# Complexity Theory 

Lecture 6: NP-Complete Problems

## Tom Gur

http://www.cl.cam.ac.uk/teaching/2324/Complexity

## Preface: What do professors do all day?

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- In fact, so is CNF-SAT.
- And CNF-SAT is reducible to 3SAT: $\left(x_{1} \vee x_{2} \vee x_{3} \vee x_{4}\right) \rightarrow\left(x_{1} \vee x_{2} \vee z_{1}\right) \wedge\left(\neg z_{1} \vee x_{3} \vee z_{2}\right) \wedge\left(\neg z_{2} \vee x_{4}\right)$


## Composing Reductions

Polynomial time reductions are clearly closed under composition.
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Hence $A$ is also NP-complete.

Let's see some reductions!

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To turn this optimisation problem into a decision problem, we define IS as:

The set of pairs $(G, K)$, where $G$ is a graph, and $K$ is an integer, such that $G$ contains an independent set with $K$ or more vertices.

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IS is clearly in NP. We now show it is NP-complete.

## Reduction

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A Boolean expression $\phi$ in 3CNF with $m$ clauses is mapped by the reduction to the pair ( $G, m$ ), where $G$ is the graph obtained from $\phi$ as follows:
$G$ contains $m$ triangles, one for each clause of $\phi$, with each node representing one of the literals in the clause.
Additionally, there is an edge between two nodes in different triangles if they represent literals where one is the negation of the other.

Example

$$
\left(x_{1} \vee x_{2} \vee \neg x_{3}\right) \wedge\left(x_{3} \vee \neg x_{2} \vee \neg x_{1}\right)
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As with IS, we can define a decision problem:
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CLIQUE is NP-complete, since

## IS $\leq_{p}$ CLIQUE

by the reduction that maps the pair $(G, K)$ to $(\bar{G}, K)$, where $\bar{G}$ is the complement graph of $G$.

## k-Colourability

A graph $G=(V, E)$ is $k$-colourable, if there is a function

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\chi: V \rightarrow\{1, \ldots, k\}
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such that, for each $u, v \in V$, if $(u, v) \in E$,

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For all $k>2$, $k$-colourability is NP-complete.

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In addition, for each clause containing the literals $I_{1}, l_{2}$ and $I_{3}$ we have a gadget.

## Gadget



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With a further edge from $a$ to $b$.

## Hamiltonian Graphs

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The language HAM is the set of encodings of Hamiltonian graphs.

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This reduction is much more intricate than the one for IND.

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The problem TSP consists of the set of triples

$$
(V, c: V \times V \rightarrow \mathbb{N}, t)
$$

such that there is a tour of the set of vertices $V$, which under the cost matrix $c$, has cost $t$ or less.

## Reduction

There is a simple reduction from HAM to TSP, mapping a graph ( $V, E$ ) to the triple $(V, c: V \times V \rightarrow \mathbb{N}, n)$, where

$$
c(u, v)= \begin{cases}1 & (u, v) \in E \\ 2 & (u, v) \notin E\end{cases}
$$

and $n$ is the size of $V$.

## Bonus: Randomness and BPP

