

# The HOL Light formalization of Euclidean space

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JMM special session on Formal Mathematics for Mathematicians

January 8th, 2011 (09:30–10:00)

## Summary

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- History of this formalization
- Encoding trick for  $\mathbb{R}^n$
- Vectors, matrices and linear algebra
- Topology, convexity and polyhedra
- Analysis, integration and measure
- Complex analysis

## History of this formalization

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This formalization began following a discussion at NYU in February 2004, in an attempt to answer the question

**How to formalize Euclidean space in a natural and streamlined way in HOL Light, with the goal of supporting the Flyspeck project?**

Although Flyspeck is mainly concerned with  $\mathbb{R}^3$ , we try to work in the more general setting of  $\mathbb{R}^N$  where possible.

The general theory has also been applied to the special case of  $\mathbb{R}^2$  and used in a further development of complex analysis.

## Authorship and acknowledgements

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As well as the present speaker, others have contributed substantially:

- Tom Hales and Flyspeck group: the further development and application to the Flyspeck project, as well as many lemmas here and much of the motivation.
- Lars Schewe: several results on affine dependence and convex sets, Radon's theorem.
- Marco Maggesi, Graziano Gentili and Gianni Ciolli: further development of complex analysis including higher derivatives and the first and second Cartan theorems.
- Valentina Bruno: Cauchy's inequality, analytic continuation, maximum modulus principle, open mapping theorem, Schwarz's lemma.

## The problem with simple type theory

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Can work over abstract spaces but then parametrization is heavy.

We would like each  $\mathbb{R}^n$  to be a *type* in **simple type theory**.

For any *fixed*  $n$  we can use  $n$ -tuples, e.g.  $\mathbb{R} \times \mathbb{R}$  for  $\mathbb{R}^2$ .

For general  $n$ , using a *set/predicate* is OK, but then the type system isn't helping us much.

Yet we have no dependent types so we can't have a *type*  $\mathbb{R}^n$  depend on a *term*  $n$ .

## A parochial problem

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Defining spaces such as  $\mathbb{R}^n$  presents no problem for many foundational systems.

- Untyped systems such as set theory (ACL2, B prover, Mizar, ...)
- Richer dependent type theories (Coq, MetaPRL, PVS, ...)

However, there are reasons to stick to simple type theory.

Several highly developed provers based on simple type theory (HOL4, HOL Light, IMPS, Isabelle/HOL, ...)

## Our solution

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For  $\mathbb{R}^n$  use the function space  $\tau \rightarrow \mathbb{R}$  where  $|\tau| = n$ .

With some technical groundwork, this gives quite a nice solution:

- Operations can be defined generically with no parametrization
- Use polymorphic type variables in place of numeric parameters
- Use constructors like disjoint sum for "arithmetic" on indices
- Theorems about  $\mathbb{R}^2$  etc. are really *instances* of results for  $\mathbb{R}^\alpha$

Main downside: types are still not completely 'first class', so can't trivially do induction on dimension etc.

## Gory details

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Define a binary type constructor ‘^’.

Second argument is coerced to size 1 if infinite.

Indexing function ( \$ ) :  $A^N \rightarrow \text{num} \rightarrow A$ .

Components are  $x\$1$ ,  $x\$2$ ,  $x\$3$  etc.

Special notion of lambda-binding for componentwise expressions so that  $(\text{lambda } i. t[i])\$j = t[j]$ .



## Basic definitions

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|-  $x + y = \text{lambda } i. x\$\$i + y\$\$i$

|-  $c \% x = \text{lambda } i. c * x\$\$i$

|-  $\text{vec } n = \text{lambda } i. \&n$

For summations, looks similar to  $x \cdot y = \sum_{i=1}^n x_i y_i$ :

|-  $(x:\text{real}^N) \text{ dot } (y:\text{real}^N) =$   
 $\text{sum}(1..\text{dimindex}(:N)) (\lambda i. x\$\$i * y\$\$i)$

## Norms etc.

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Define some of the usual vector notions:

$$|- \text{ norm } x = \text{sqrt}(x \text{ dot } x)$$

$$|- \text{ dist}(x,y) = \text{norm}(x - y)$$

$$|- \text{ orthogonal } x \ y \Leftrightarrow (x \text{ dot } y = 0)$$

and linear functions:

$$\begin{aligned} |- \text{ linear } (f:\text{real}^M \rightarrow \text{real}^N) \Leftrightarrow \\ (\forall x \ y. f(x + y) = f(x) + f(y)) \wedge \\ (\forall c \ x. f(c \% x) = c \% f(x)) \end{aligned}$$

## Matrices

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Encode  $M \times N$  matrices by  $(\mathbb{R}^N)^M$ . Multiplication:

```
|- (A:real^N^M) ** (B:real^P^N) =  
    lambda i j. sum (1..dimindex(UNIV:N->bool))  
        (lambda k. A$i$k * B$k$j)
```

Types give a natural way of enforcing dimensional compatibility in matrix multiplication.

```
|- forall A:real^N^M. linear(lambda x. A ** x)
```

```
|- forall f:real^M->real^N.  
    linear f => forall x. matrix f ** x = f(x)
```

```
|- forall f g. linear f & linear g  
    => (matrix(g o f) = matrix g ** matrix f)
```

## Topology

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Induction over dimension in Heine-Borel and Brouwer are OK:

| - compact  $s \Leftrightarrow$   
     $\forall f: \text{num} \rightarrow \text{real}^{\mathbb{N}}.$   
         $(\forall n. f(n) \text{ IN } s)$   
         $\Rightarrow \exists l \ r. l \text{ IN } s \wedge (\forall m \ n. m < n \Rightarrow r(m) < r(n))$   
             $((f \circ r) \dashrightarrow l) \text{ sequentially}$

| - compact  $s \Leftrightarrow \text{bounded } s \wedge \text{closed } s$

| -  $\forall f: \text{real}^{\mathbb{N}} \rightarrow \text{real}^{\mathbb{N}}.$   
    compact  $s \wedge \text{convex } s \wedge \neg(s = \{\}) \wedge$   
     $f \text{ continuous\_on } s \wedge \text{IMAGE } f \ s \text{ SUBSET } s$   
     $\Rightarrow \exists x. x \text{ IN } s \wedge f \ x = x$

## Convex sets and polyhedra

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Classic properties of convex sets such as Radon's theorem

| -  $\forall c. \text{affine\_dependent } c$   
     $\Rightarrow \exists m \ p. m \text{ SUBSET } c \wedge p \text{ SUBSET } c \wedge \text{DISJOINT } m \ p$   
         $\neg(\text{DISJOINT } (\text{convex hull } m) (\text{convex hull } p))$

and results about polytopes and polyhedra, their faces etc.

| -  $\text{polytope } s \iff \exists v. \text{FINITE } v \wedge s = \text{convex hull } v$

| -  $\text{polyhedron } s \iff$   
     $\exists f. \text{FINITE } f \wedge s = \text{INTERS } f \wedge$   
     $\forall h. h \text{ IN } f \Rightarrow \exists a \ b. \neg(a = \text{vec } 0) \wedge$   
         $h = \{x \mid a \text{ dot } x \leq b\}$

| -  $\forall s. \text{polytope } s \iff \text{polyhedron } s \wedge \text{bounded } s$

## Analysis

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Usual Fréchet derivative:

```
|- (f has_derivative f') (at x) ⇔  
  linear f' ∧  
  ((λy. inv(norm(y - x)) % (f(y) - (f(x) + f'(y -  
    --> vec 0)  
  (at x)
```

and typical theorems:

```
|- (f has_derivative f') (at x) ∧  
  (g has_derivative g') (at (f x))  
⇒ ((g o f) has_derivative (g' o f')) (at x)
```

## Integration and measure

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Kurzweil-Henstock gauge integral for functions  $\mathbb{R}^M \rightarrow \mathbb{R}^N$ :

```
|-  $\forall f\ g\ h\ s.$   
  ( $\forall k. (f\ k)\ \text{integrable\_on}\ s$ )  $\wedge$   $h\ \text{integrable\_on}\ s$   
  ( $\forall k\ x. x\ \text{IN}\ s \Rightarrow \text{norm}(f\ k\ x) \leq \text{drop}(h\ x)$ )  $\wedge$   
  ( $\forall x. x\ \text{IN}\ s \Rightarrow ((\lambda k. f\ k\ x) \dashrightarrow g\ x)$  sequentially  
   $\Rightarrow g\ \text{integrable\_on}\ s \wedge$   
    ( $(\lambda k. \text{integral}\ s\ (f\ k)) \dashrightarrow \text{integral}\ s\ g$ )  
    sequentially
```

and Lebesgue measure as integral of characteristic function:

```
|-  $\forall f:\text{real}^N \rightarrow \text{real}^N.$   
  linear\ f  $\wedge$  measurable\ s  
   $\Rightarrow (\text{IMAGE}\ f\ s)$  has\_measure  
    ( $\text{abs}(\text{det}(\text{matrix}\ f)) * \text{measure}\ s$ )
```

## Complex analysis (1)

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Define complex derivatives and analytic functions, and relate it to general differentiability in Euclidean space:

$$\begin{aligned} | - \forall f \ z. \ f \ \text{complex\_differentiable} \ \text{at} \ z \ \Leftrightarrow \\ & f \ \text{differentiable} \ \text{at} \ z \ \wedge \\ & (\text{jacobian} \ f \ (\text{at} \ z))_{11} = \\ & (\text{jacobian} \ f \ (\text{at} \ z))_{22} \ \wedge \\ & (\text{jacobian} \ f \ (\text{at} \ z))_{12} = \\ & \text{--}((\text{jacobian} \ f \ (\text{at} \ z))_{21}) \end{aligned}$$

Many other analytic theorems are proved.



## Complex analysis (2)

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More interesting theorems involve contour integrals, like Cauchy's integral formula:

| -  $\forall f, s, k, g, z.$

$\text{convex } s \wedge \text{FINITE } k \wedge f \text{ continuous\_on } s \wedge$

$(\forall x. x \text{ IN interior}(s) \text{ DIFF } k$

$\Rightarrow f \text{ complex\_differentiable at } x) \wedge$

$z \text{ IN interior}(s) \text{ DIFF } k \wedge$

$\text{valid\_path } g \wedge$

$(\text{path\_image } g) \text{ SUBSET } (s \text{ DELETE } z) \wedge$

$\text{pathfinish } g = \text{pathstart } g$

$\Rightarrow ((\lambda w. f(w) / (w - z)) \text{ has\_path\_integral}$

$(2 * \pi) * i * \text{winding\_number}(g, z) * f(z)$

$g$

## Automated reasoning routines

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As well as *theorems*, we have also developed a few convenient automated proof tools:

- Simple routine for automatically proving universally quantified vector formulas ‘componentwise’
- More sophisticated quantifier elimination for vectors, based on an idea of Solovay.
- ‘Without loss of generality’ tactics for exploiting symmetries and invariances, especially in geometry.

## WLOG example

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```
g `∀s a:real^N.  
  closed s ∧ ¬(s = {})  
  ⇒ ∃x. x IN s ∧  
    ∀y. y IN s ⇒ dist(a,x) <= dist(a,y)`;;
```

With a single application of our tactic, we can suppose the point in question is the origin:

```
# e(GEOM_ORIGIN_TAC `a:real^N`);;  
val it : goalstack = 1 subgoal (1 total)
```

```
`∀s. closed s ∧ ¬(s = {})  
  ⇒ ∃x. x IN s ∧  
    ∀y. y IN s ⇒ dist(vec 0,x) <= dist(vec 0,y)
```

## Summary

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- Simple but apparently effective representational trick
- Many definitions and theorems have a very natural formulation
- Some potential difficulties over induction on dimension etc.
- Has been developed into a substantial library with many classic theorems
- Supplemented with some convenient proof tools
- Seems to provide a good foundation for Flyspeck work
- Also used for a significant development of complex analysis