

# PetaBricks: A Language and Compiler for Algorithmic Choice [1]

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Michelmas 2025

# Motivation and Background

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It's a programming language and a compiler (Petabricks  $\rightarrow$  C++) and a run-time library implemented in C++.

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We need **simplicity**:

- Handle switching algorithms based on params and input data (avoids obfuscated code and manual tuning). Replace ATLAS [5] / FFTW [4] (C tuning libraries).
- 1 optimal implementation ported to different machines by re-compiling and autotuning (x86 vs Sun Niagara).

- Algorithmic choice through 1 transform with multiple rules.

```

1 transform MatrixMultiply
2 from A[c,h], B[w,c]
3 to AB[w,h]
4 {
5   // Base case, compute a single element
6   te(AB, c/h(1-x) out)
7   from(A.row(y) a, B.column(x) b) {
8     out = dot(a,b);
9   }
10 }
11 // Recursively decompose in c
12 te(AB, ab)
13 from(A, region(0, 0, c/2, h) a1,
14      A, region(c/2, 0, c, h) a2,
15      B, region(0, 0, w, c/2) b1,
16      B, region(0, c/2, w, c) b2) {
17   ab = MatrixAdd( MatrixMultiply(a1, b1),
18                  MatrixMultiply(a2, b2));
19 }
20
21 // Recursively decompose in w
22 te(AB, region(0, 0, w/2, h) ab1,
23    AB, region(w/2, 0, w, h) ab2)
24 from(A, a,
25      B, region(0, 0, w/2, c) b1,
26      B, region(w/2, 0, w, c) b2) {
27   ab1 = MatrixMultiply(a, b1);
28   ab2 = MatrixMultiply(a, b2);
29 }
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31 // Recursively decompose in h
32 te(AB, region(0, 0, w, h/2) ab1,
33    AB, region(0, h/2, w, h) ab2)
34 from(A, region(0, 0, c, h/2) a1,
35      A, region(0, h/2, c, h) a2,
36      B, b) {
37   ab1=MatrixMultiply(a1, b);
38   ab2=MatrixMultiply(a2, b);
39 }
40 }

```

Figure 1: MatrixMultiply PetaBricks source code

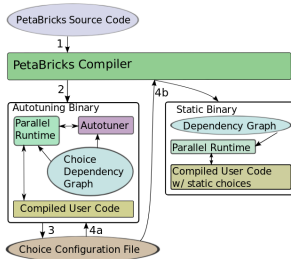


Figure 2: Interactions between compiler and output binaries.

# Features

- Algorithmic choice through 1 transform with multiple rules.
- The compilation uses a Choice Dependency Graph (CDG), nodes = transforms/rules, edges = (data) dependencies.

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1 transform MatrixMultiply
2 from A[c,h], B[w,c]
3 to AB[w,h]
4 {
5   // Base case, compute a single element
6   te(AB, c/h(1,1) out)
7   from(A.row(y) a, B.column(x) b) {
8     out = dot(a,b);
9   }
10 }
11 // Recursively decompose in c
12 te(AB, ab)
13 from(A, region(0, 0, c/2, h) a1,
14      A, region(c/2, 0, c, h) a2,
15      B, region(0, 0, w, c/2) b1,
16      B, region(0, c/2, w, c) b2) {
17   ab = MatrixAdd( MatrixMultiply(a1, b1),
18                  MatrixMultiply(a2, b2));
19 }
20
21 // Recursively decompose in w
22 te(AB, region(0, 0, w/2, h) ab1,
23    AB, region(w/2, 0, w, h) ab2) {
24   from(A, a,
25        B, region(0, 0, w/2, c) b1,
26        B, region(w/2, 0, w, c) b2) {
27     ab1 = MatrixMultiply(a, b1);
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29   }
30 }
31 // Recursively decompose in h
32 te(AB, region(0, 0, w, h/2) ab1,
33    AB, region(0, w/2, w, h) ab2) {
34   from(A, region(0, 0, c, h/2) a1,
35        A, region(0, h/2, c, h) a2,
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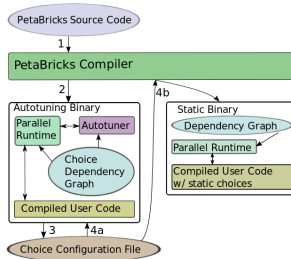


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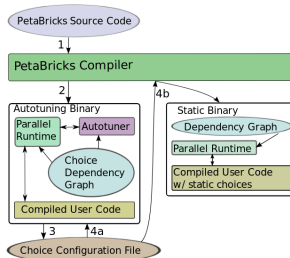


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- The compilation uses a Choice Dependency Graph (CDG), nodes = transforms/rules, edges = (data) dependencies.
- Accuracy choice with iterative and recursive methods.
- How does the autotuner select the best rule?

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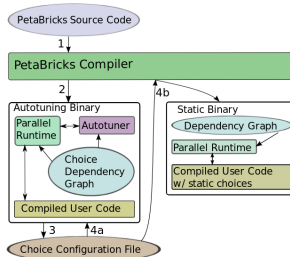


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- Evolutionary strategy: candidate  $\rightarrow$  measure runtime  $\rightarrow$  random mutation (stochastic search)  $\rightarrow$  select new 'parents'.
- Tracks performance vs accuracy (error and convergence rate).
- **Concretely**, insertion sort is introduced at  $N = 68$  instead of  $N = 15$ . Merge sort with 4 splits instead of 2.



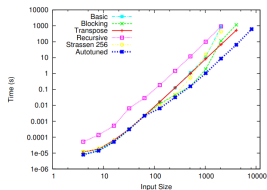


Figure 3: Matrix Multiply on 8 cores.

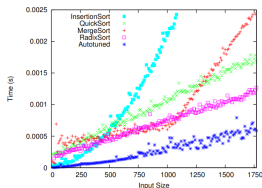


Figure 4: Sort on 8 cores.

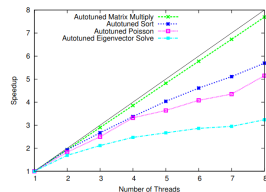


Figure 5: Parallel scalability on x86.

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# My Thoughts

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- Should we optimise for energy consumption? final binary size? robustness (average runtime on different input data)? [2]
- The core assumption is the 'Optimal Substructure Principle' [3].
- My personal bias is against general frameworks (80/20 rule).



J. Ansel, C. Chan, Y. L. Wong, M. Olszewski, Q. Zhao, A. Edelman, and S. Amarasinghe.

Petabricks: a language and compiler for algorithmic choice.

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## Q & A