



OpenTuner

An Extensible Framework for Program Autotuning

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Jeffrey Bosboom, Una-May O'Reilly, and Saman Amarasinghe

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Goal

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Modify configuration → tune software heuristic, e.g.,

Goal

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 Program size

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 Program size

 Time

Goal

Modify configuration → tune software heuristic, e.g.,

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 Time

 Resource usage (e.g., memory)

Goal

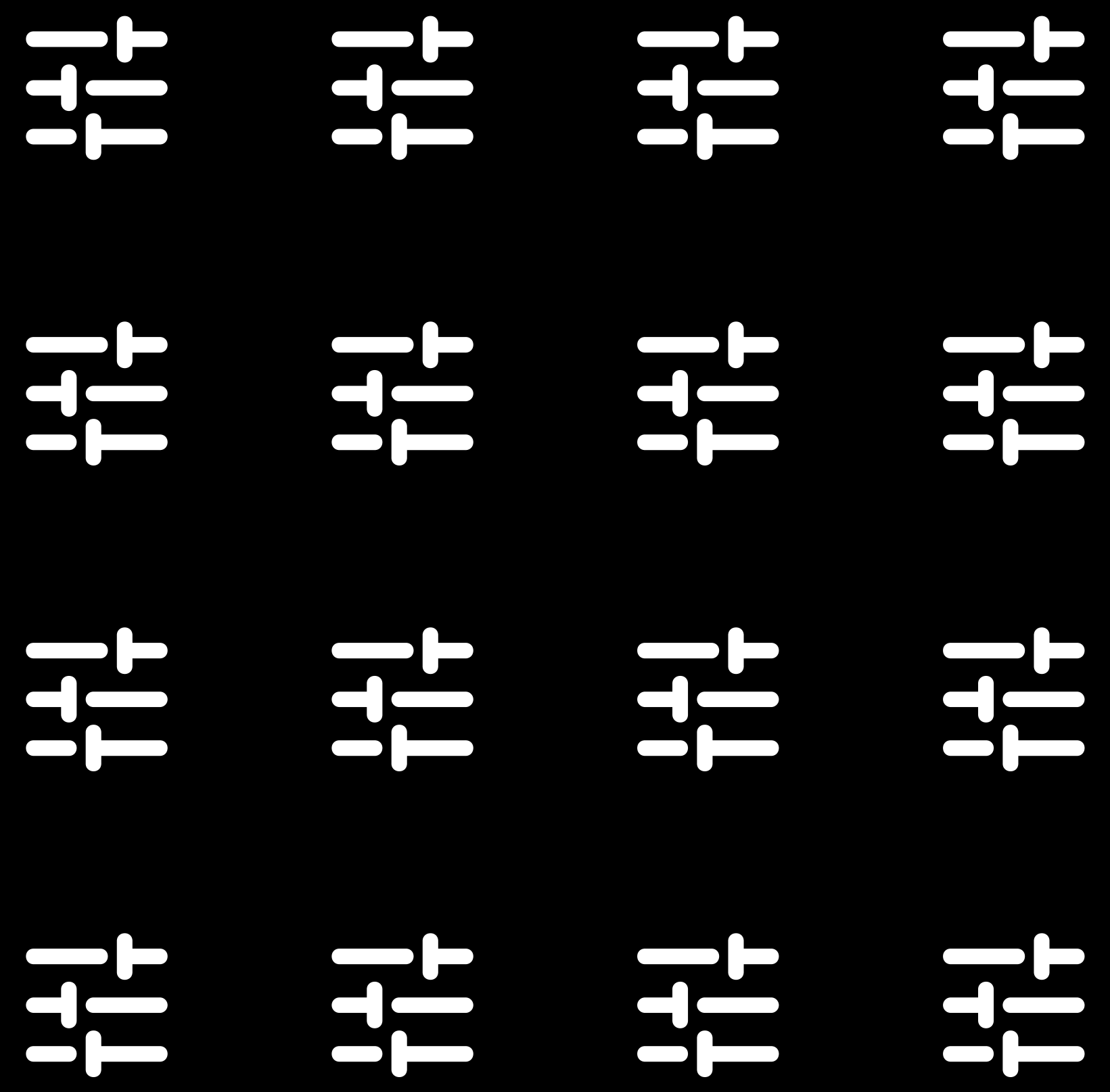
Modify configuration → tune software heuristic, e.g.,

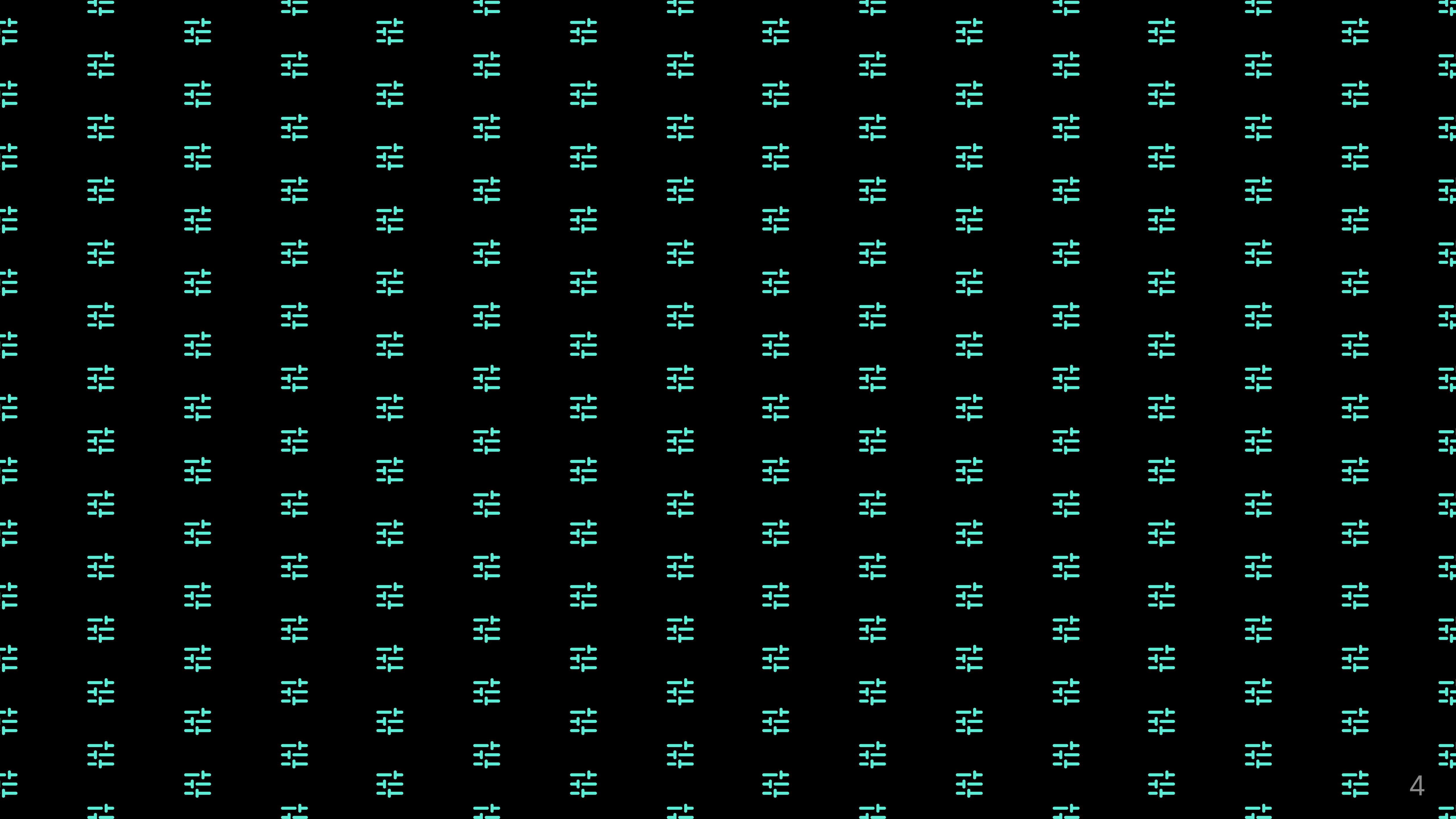
 Program size

 Time

 Resource usage (e.g., memory)

 Energy consumption





10²⁰

Possible configurations

➤ 10 3600
Possible configurations

Autotuning

Autotuning

Challenges

Autotuning

Challenges

1 Configuration Representation

Need domain-informed configuration space representation

Autotuning

Challenges

1 Configuration Representation

Need domain-informed configuration space representation

2 Configuration Space Size

Need search technique

Autotuning

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1 Configuration Representation

Need domain-informed configuration space representation

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3 Configuration Space Landscape

Continuity? Dimensionality? Coupled parameters?

Autotuning

Challenges

1 Configuration Representation

Need domain-informed configuration space representation

2 Configuration Space Size

Need search technique

3 Configuration Space Landscape

Continuity? Dimensionality? Coupled parameters?

? Effect on search techniques?

Configuration Space Landscape

Technique – Hill Climber Optimisation



Configuration Space Landscape

Technique – Hill Climber Optimisation

Configuration Space Landscape

Discontinuities, Smaller Hills, Plateaus, Coupling

Configuration Space Landscape

Discontinuities, Smaller Hills, Plateaus, Coupling

Project ①

Configuration Space Landscape

Different project – different technique

Project

Configuration Space Landscape

Different project – different technique

Project ②

Autotuning

Challenges

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Autotuning

Challenges

1 Configuration Representation

Need domain-informed configuration space representation

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Need search technique

3 Configuration Space Landscape

Continuity? Dimensionality? Coupled parameters?

? Search technique efficacy depends heavily on landscape (→ on project)

Previous work: Custom representations & techniques for specific problem

OpenTuner

Search

OpenTuner

Search

Use multiple search techniques
("Ensemble") simultaneously

OpenTuner

Search

Use multiple search techniques
("Ensemble") simultaneously



Nelder-Mead
Hill Climber



Differential
Evolution



Random
Search



Greedy
Mutation



Torczon Hill
Climber



Particle Swarm
Optimisation

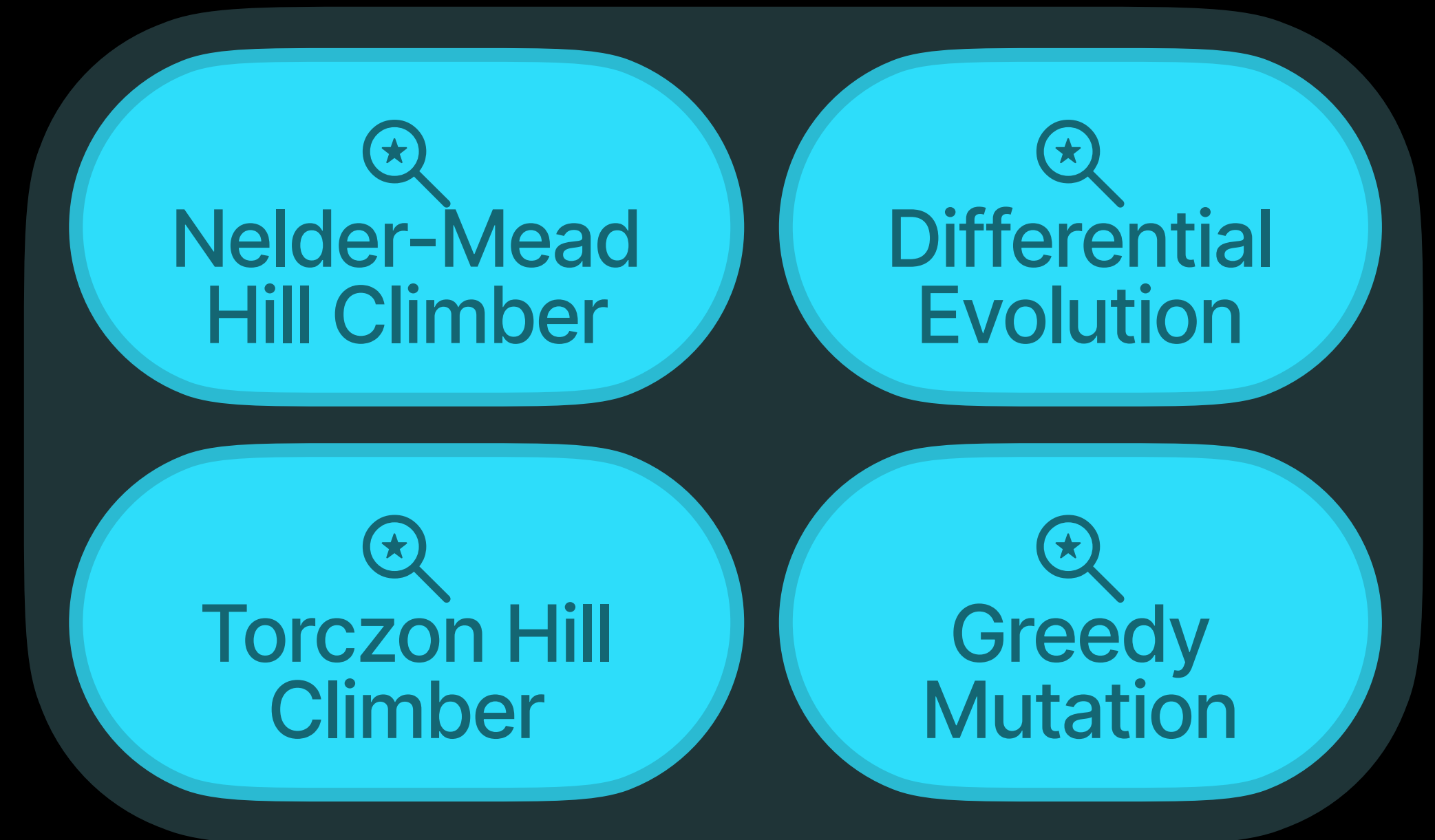


Pattern
Search

OpenTuner

Search

Use multiple search techniques
("Ensemble") simultaneously

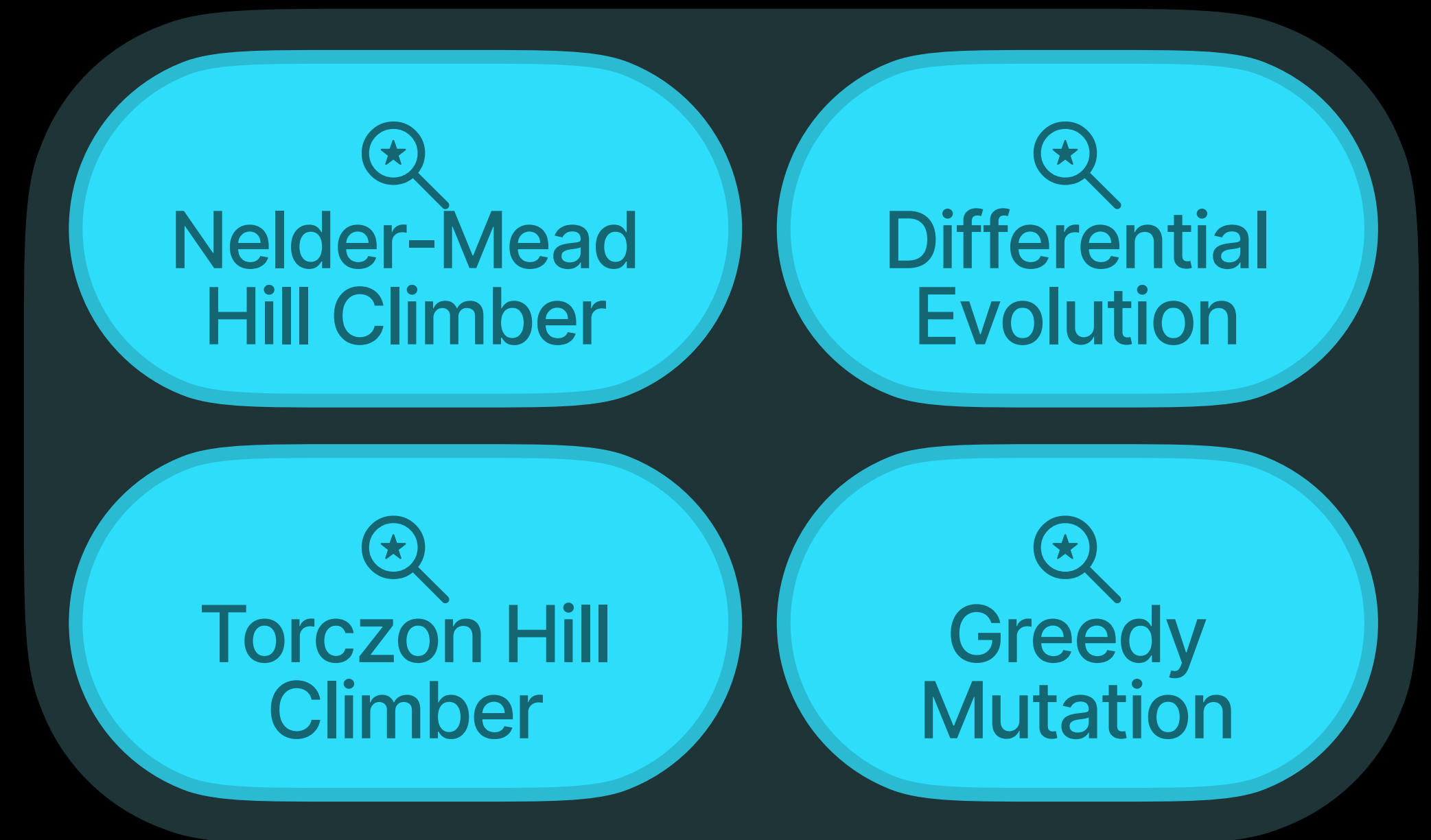


OpenTuner

Search

Use multiple search techniques
("Ensemble") simultaneously

Meta techniques group techniques



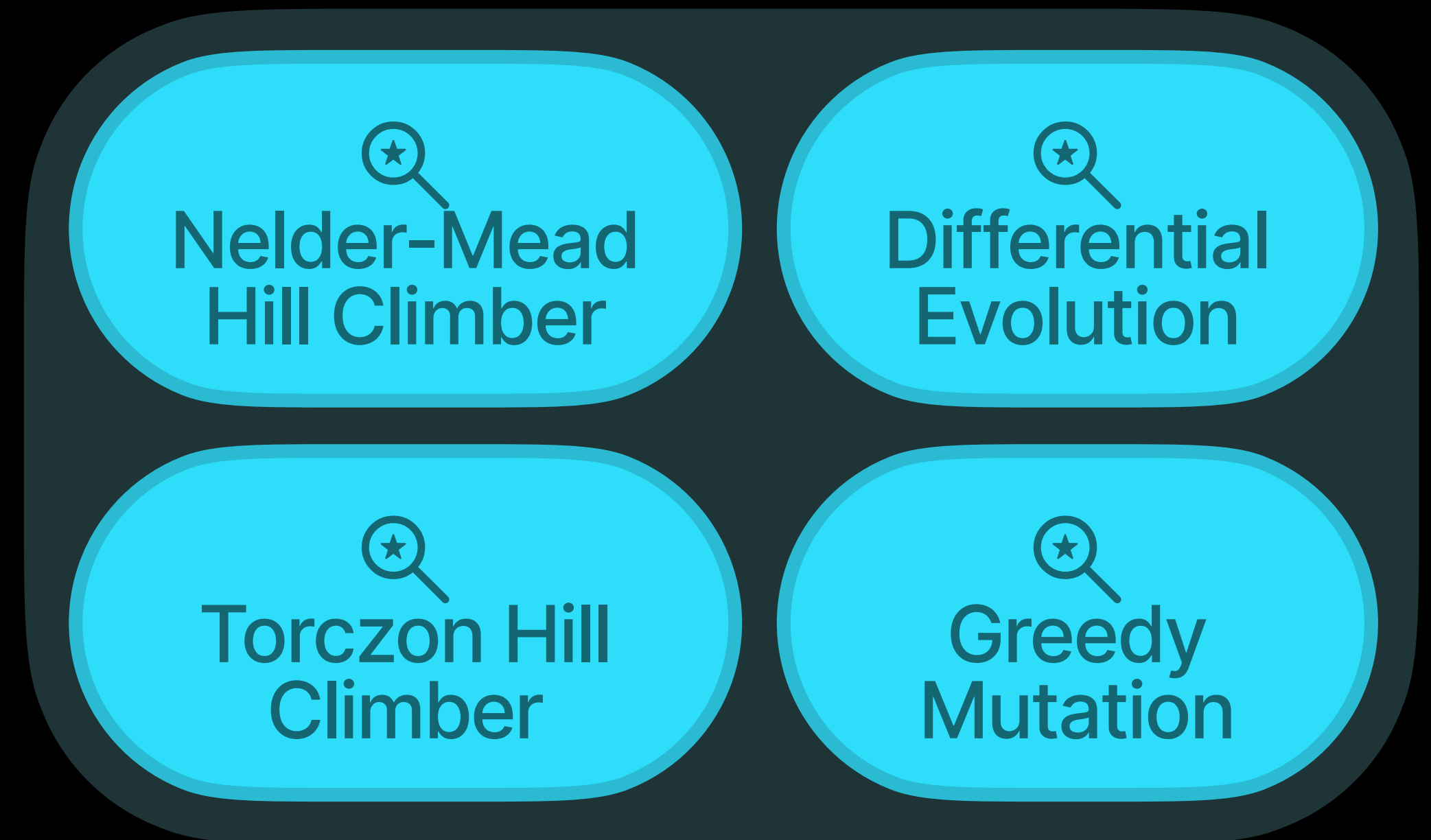
OpenTuner

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Use multiple search techniques
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Meta techniques group techniques

Can nest (meta) techniques



OpenTuner

Search

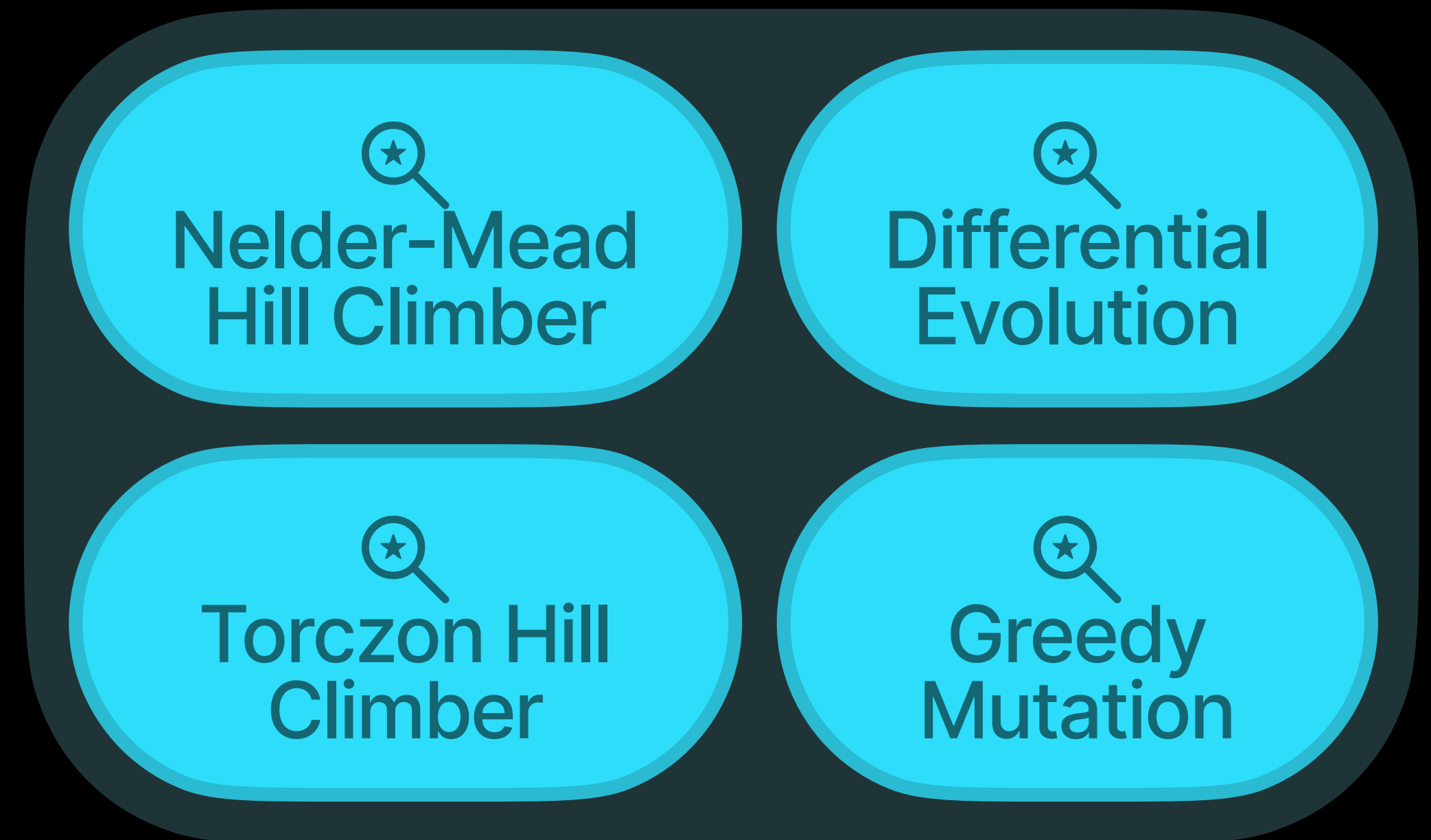
Use multiple search techniques
("Ensemble") simultaneously

Meta techniques group techniques

Can nest (meta) techniques

Dynamically allocate test runs to
sub-techniques

(e.g., Round Robin, Multi-armed bandit)



OpenTuner

Search

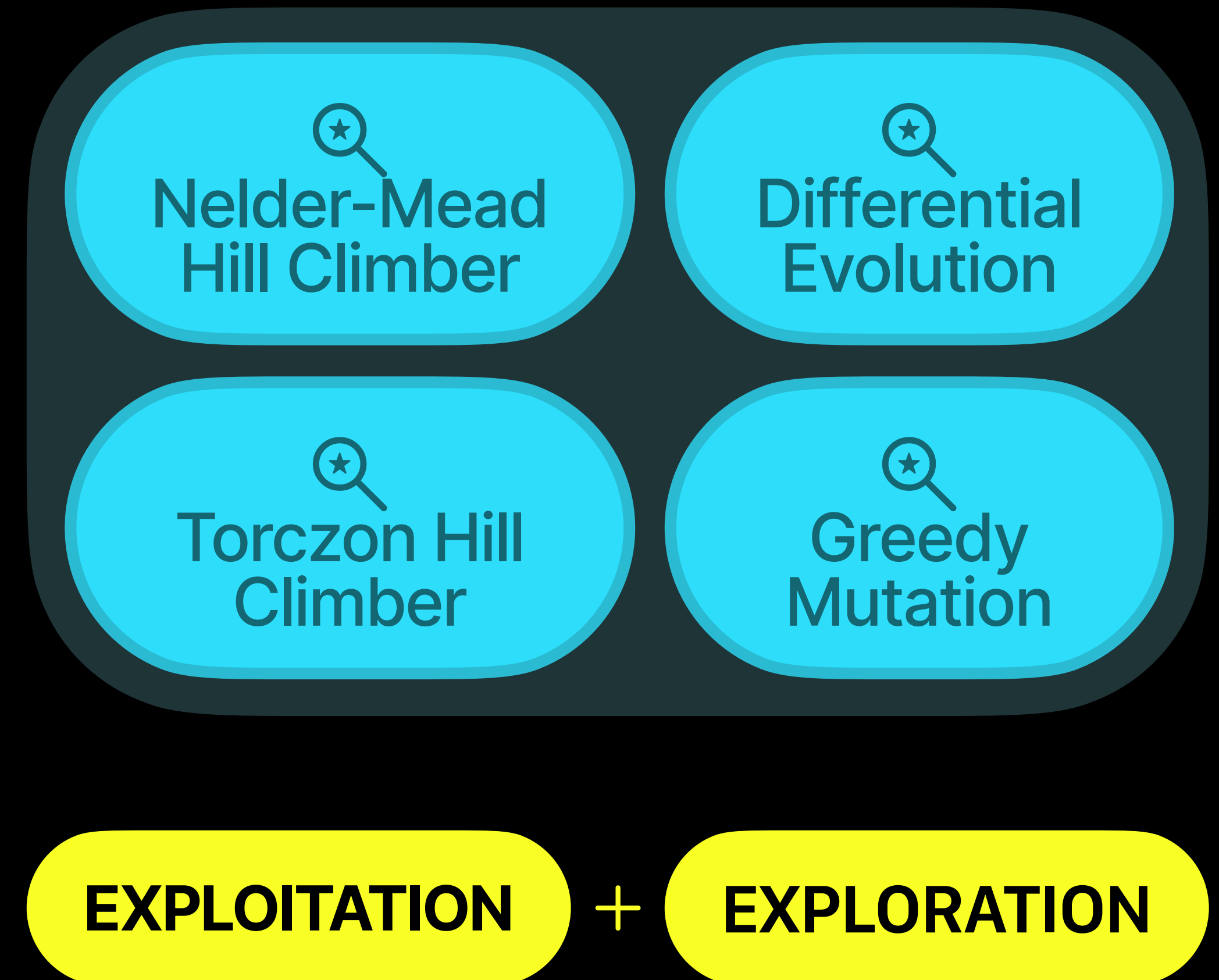
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OpenTuner

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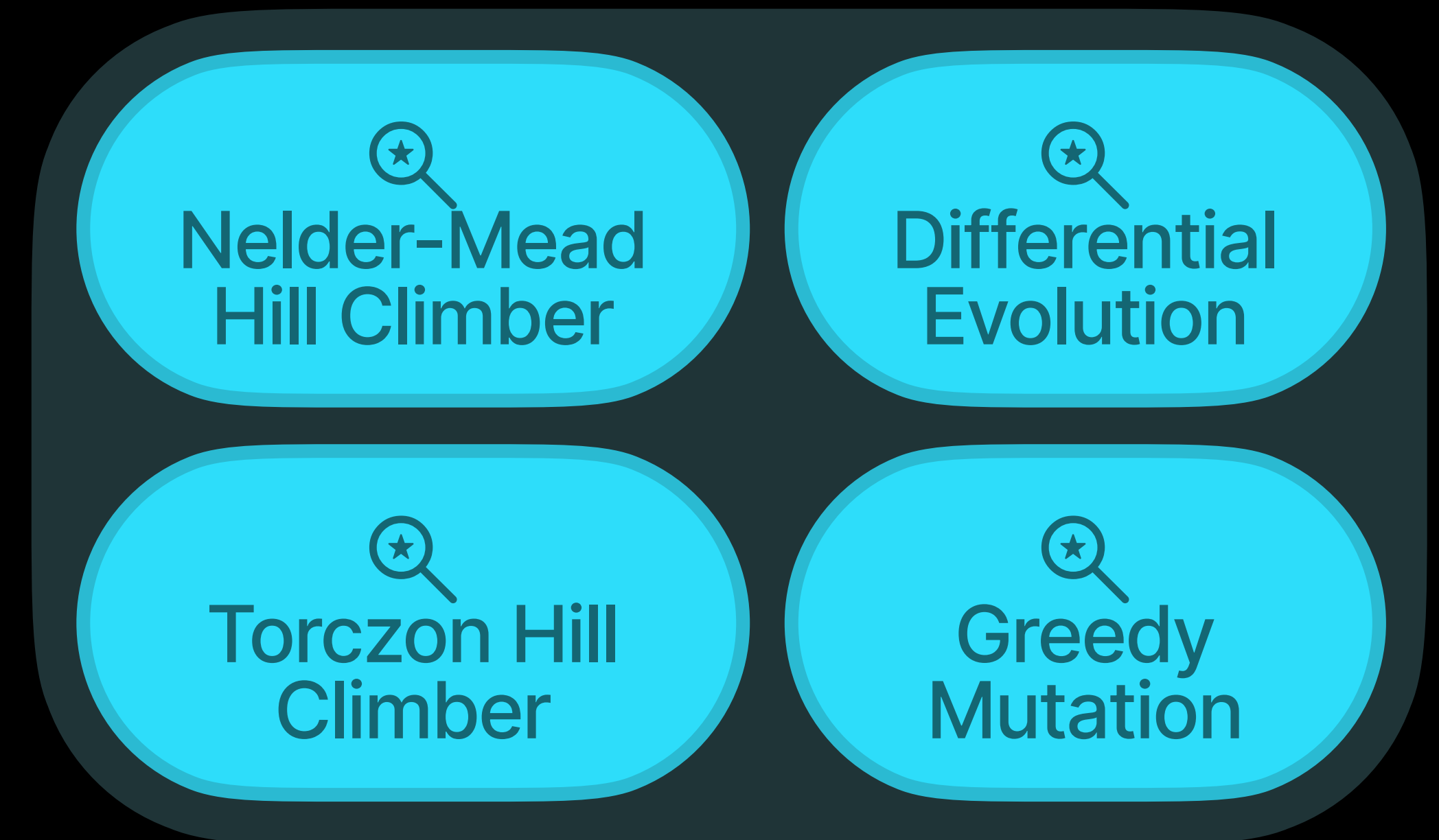
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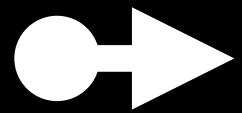
$$\operatorname{argmax}_{\mathbf{T}} \left(\frac{2}{|\mathbf{V}_{\mathbf{T}}|(|\mathbf{V}_{\mathbf{T}}| + 1)} \sum_{i=0}^{|\mathbf{V}_{\mathbf{T}}|} i V_{i,\mathbf{T}} + C \sqrt{\frac{2 \lg |H|}{|\mathbf{V}_{\mathbf{T}}|}} \right)$$

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Components

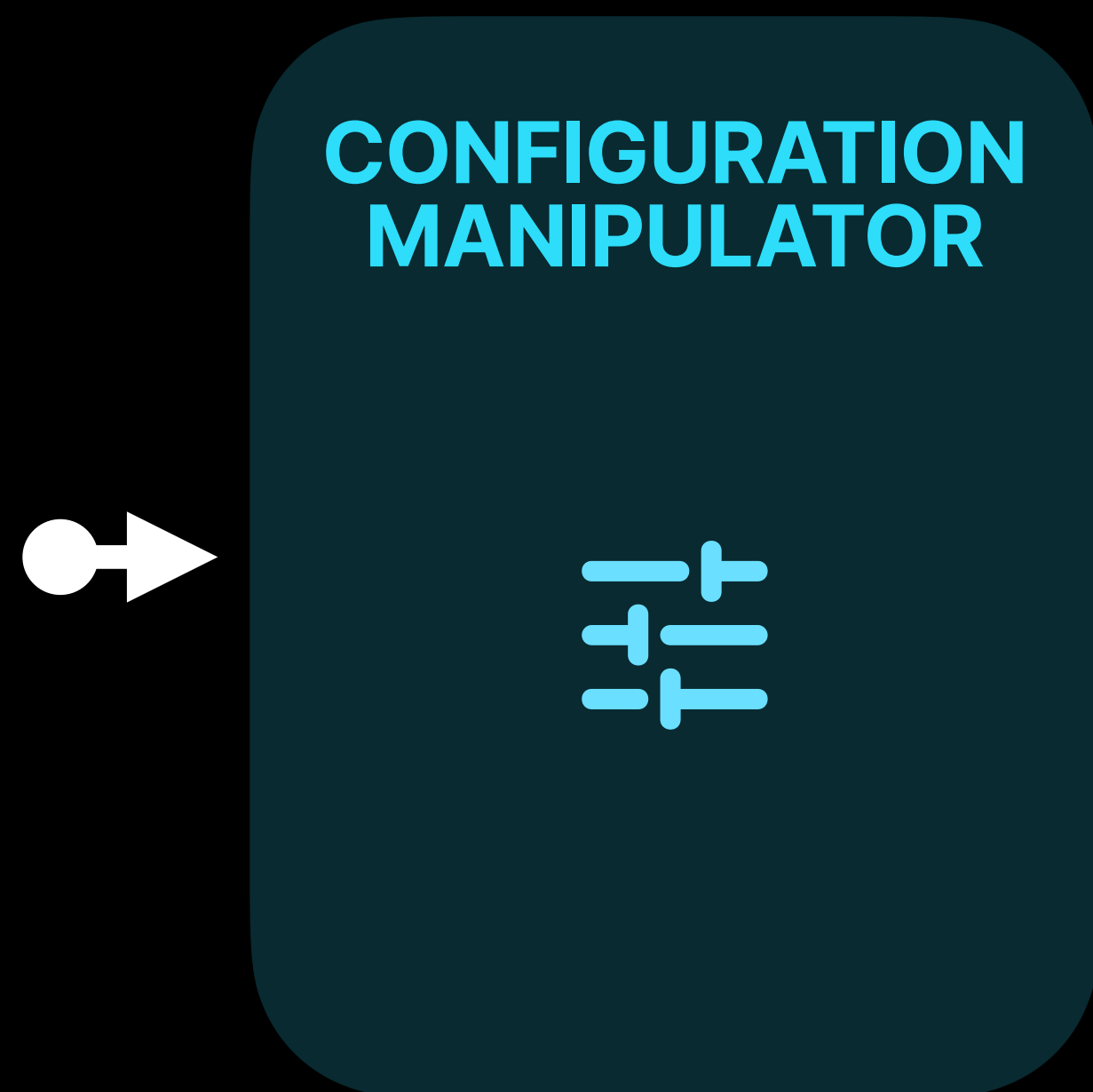
OpenTuner

Components



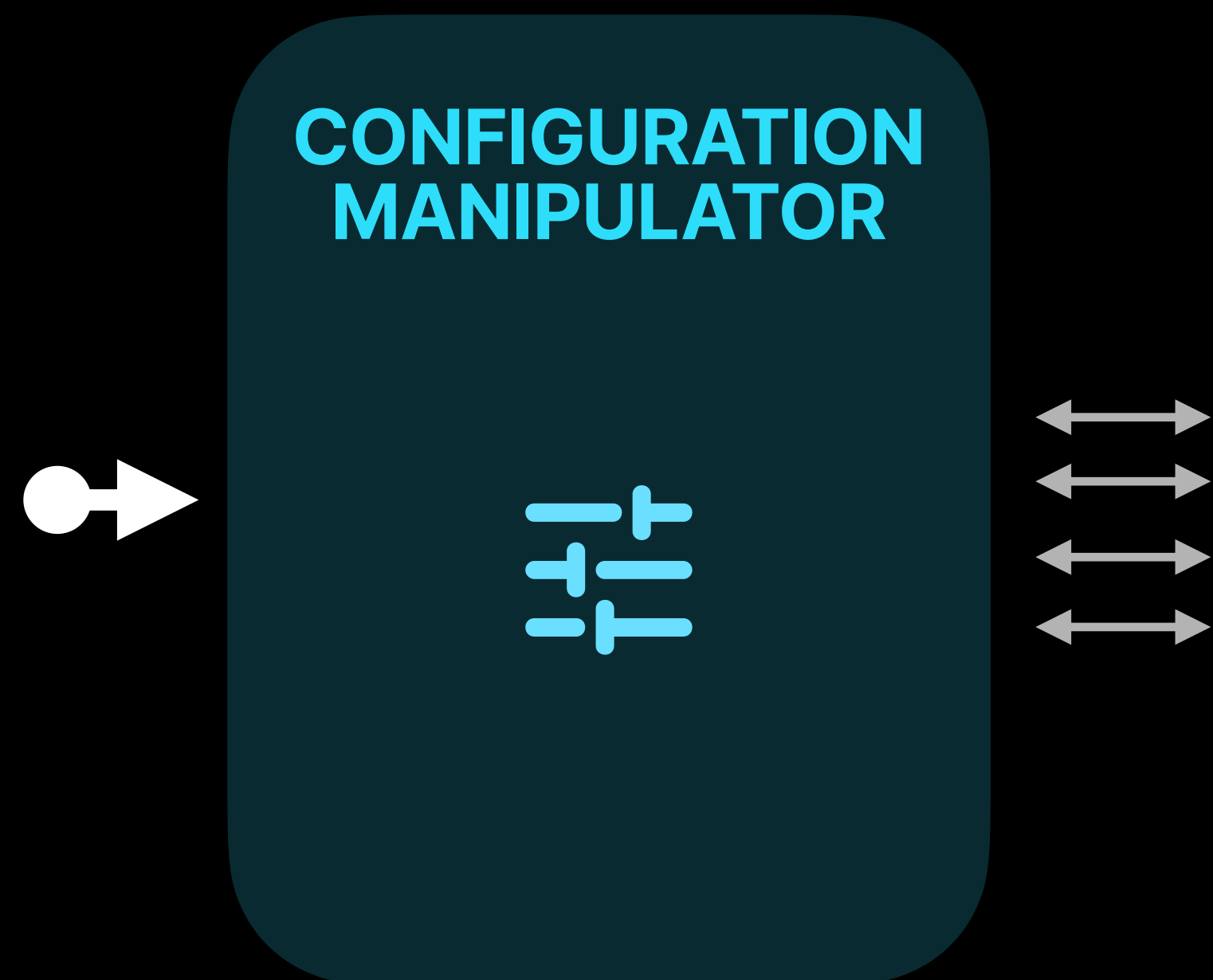
OpenTuner

Components



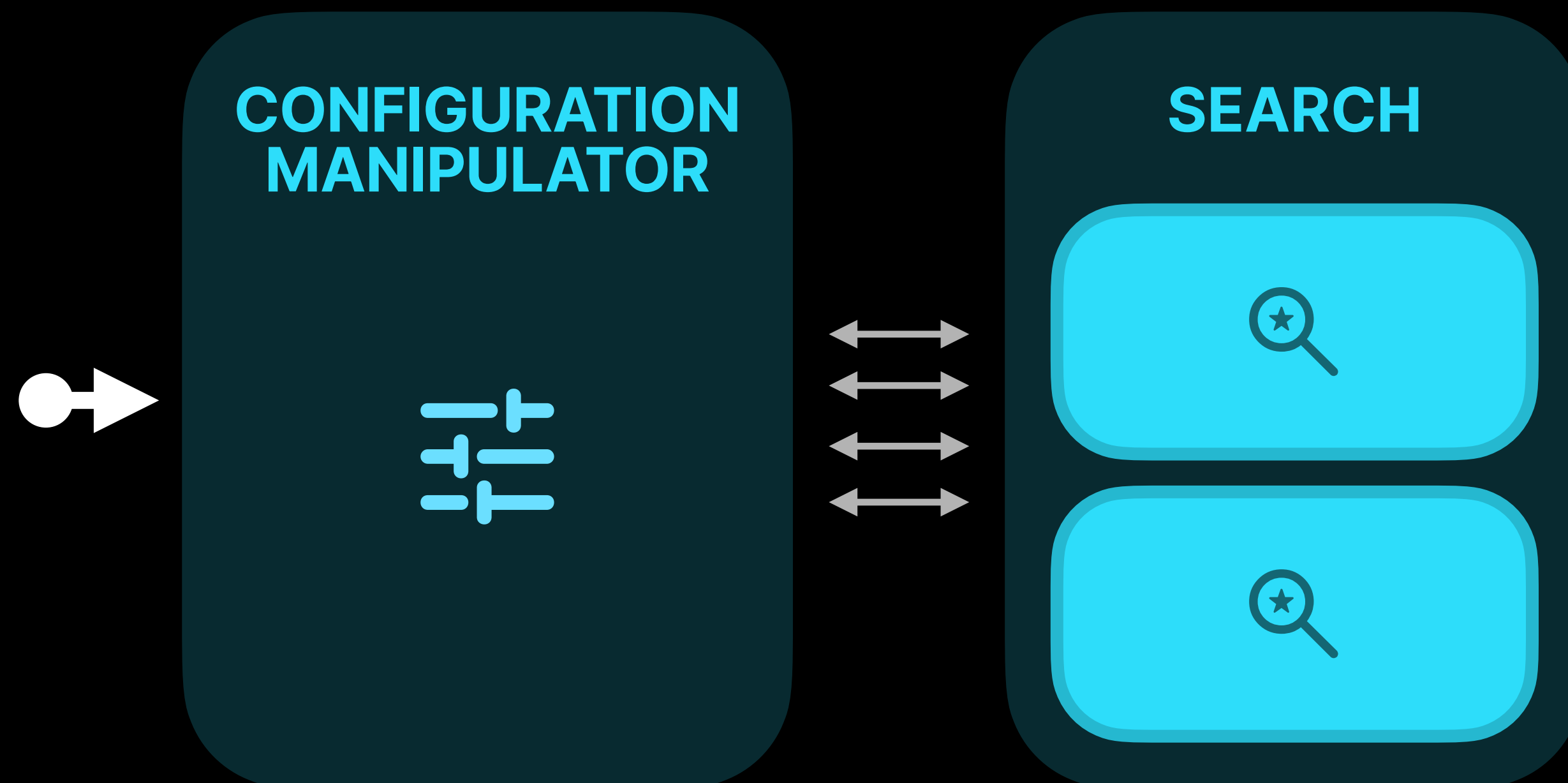
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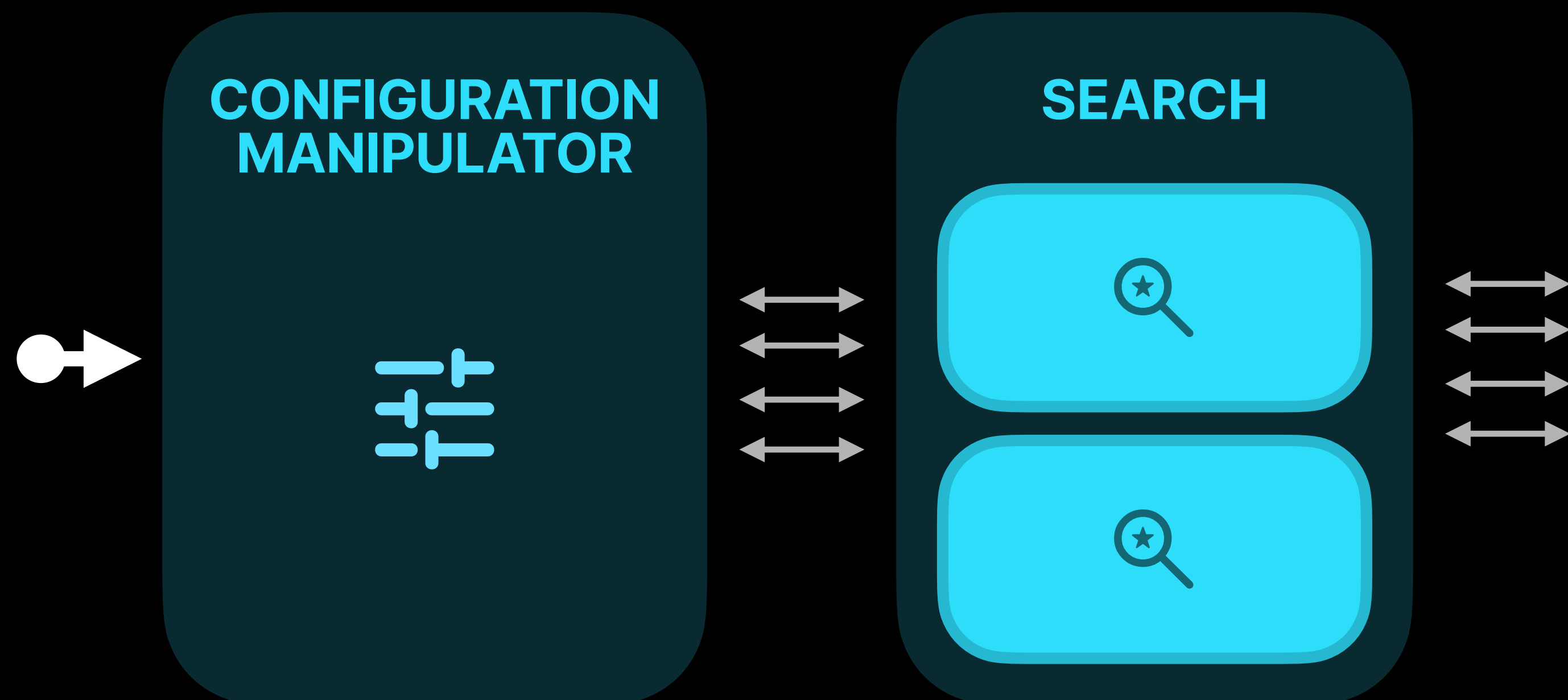
OpenTuner

Components



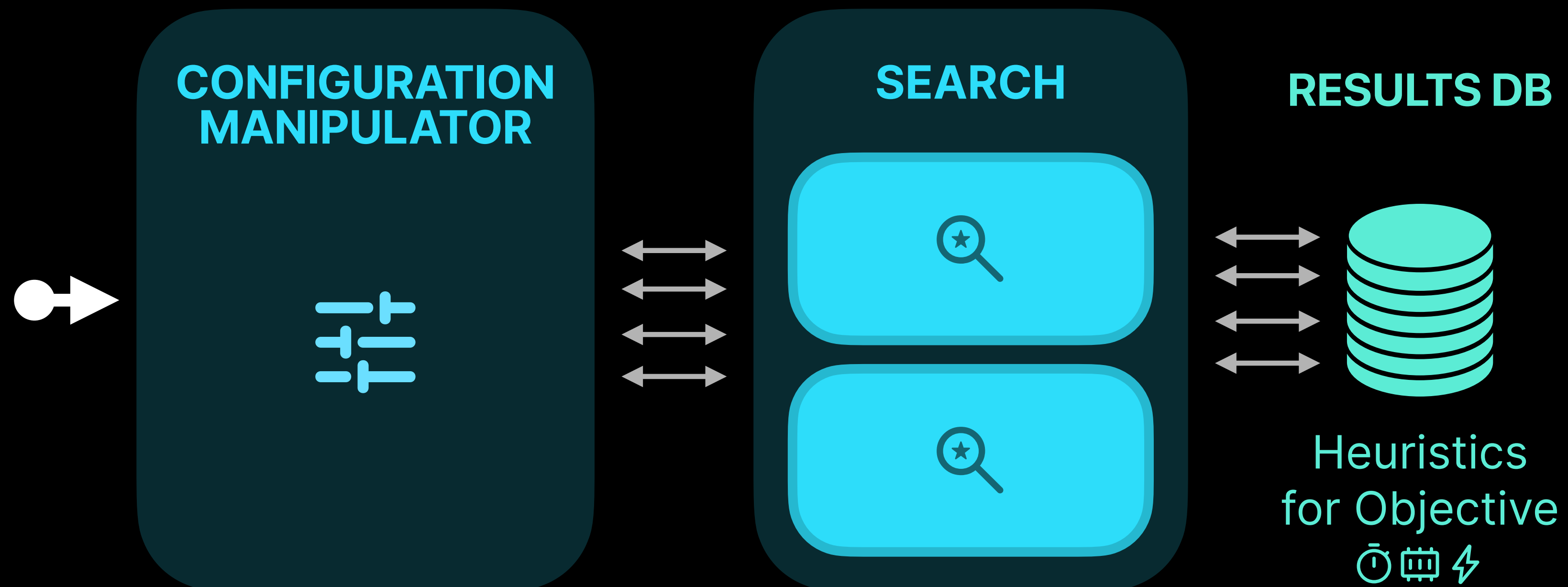
OpenTuner

Components



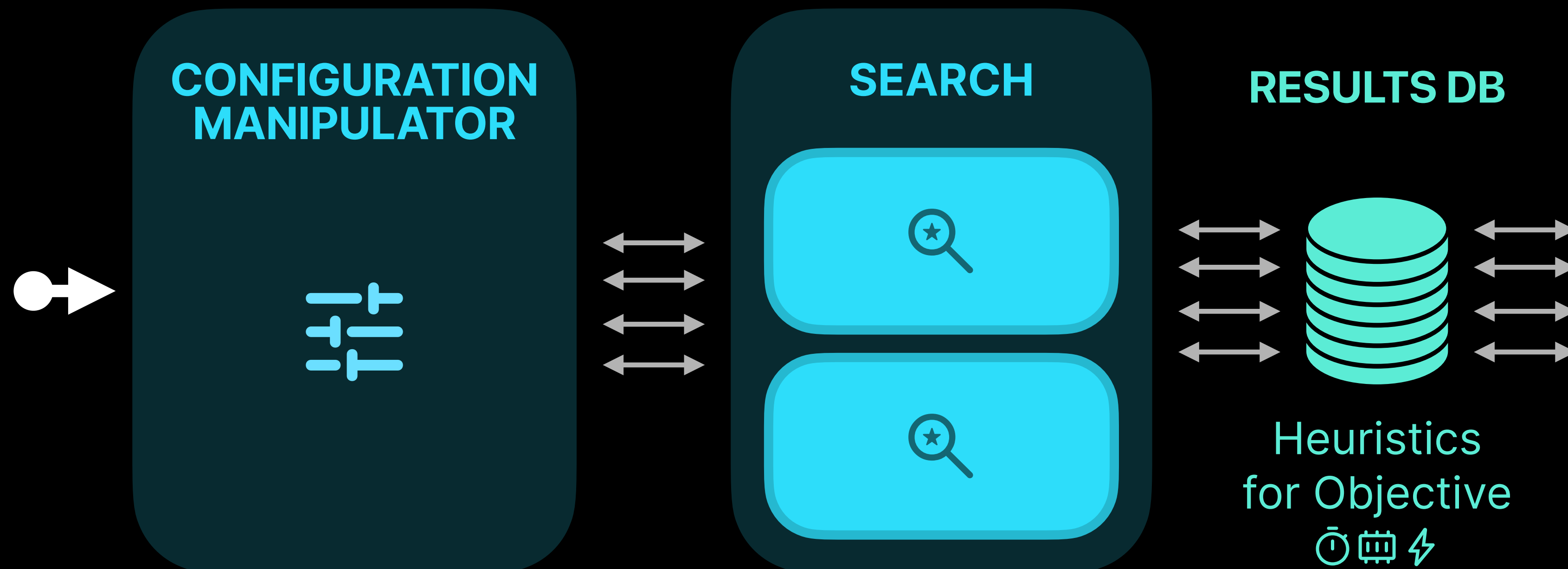
OpenTuner

Components



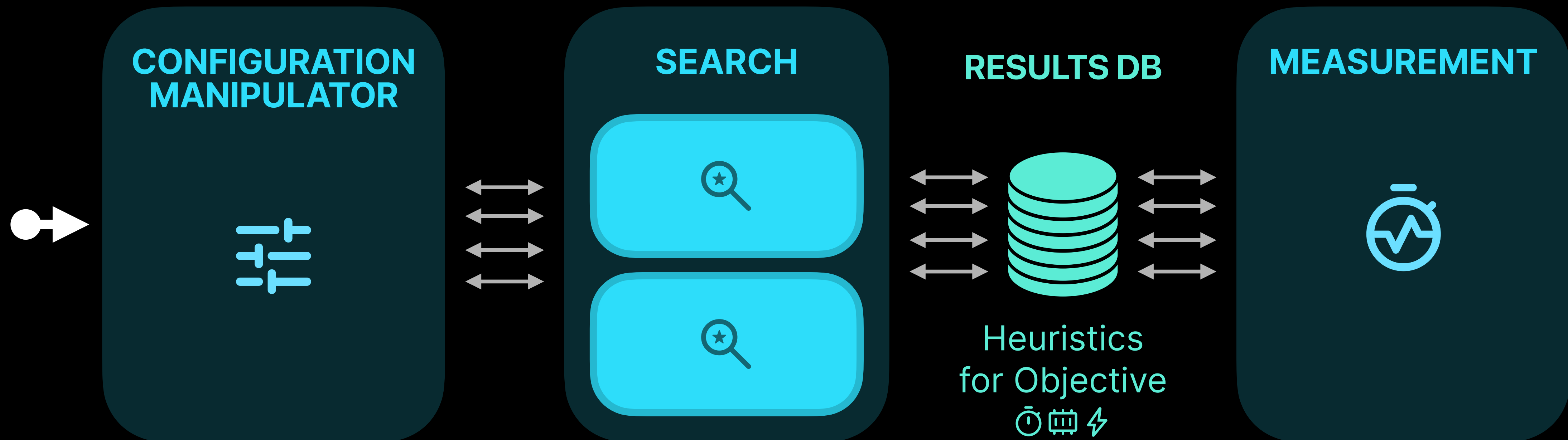
OpenTuner

Components



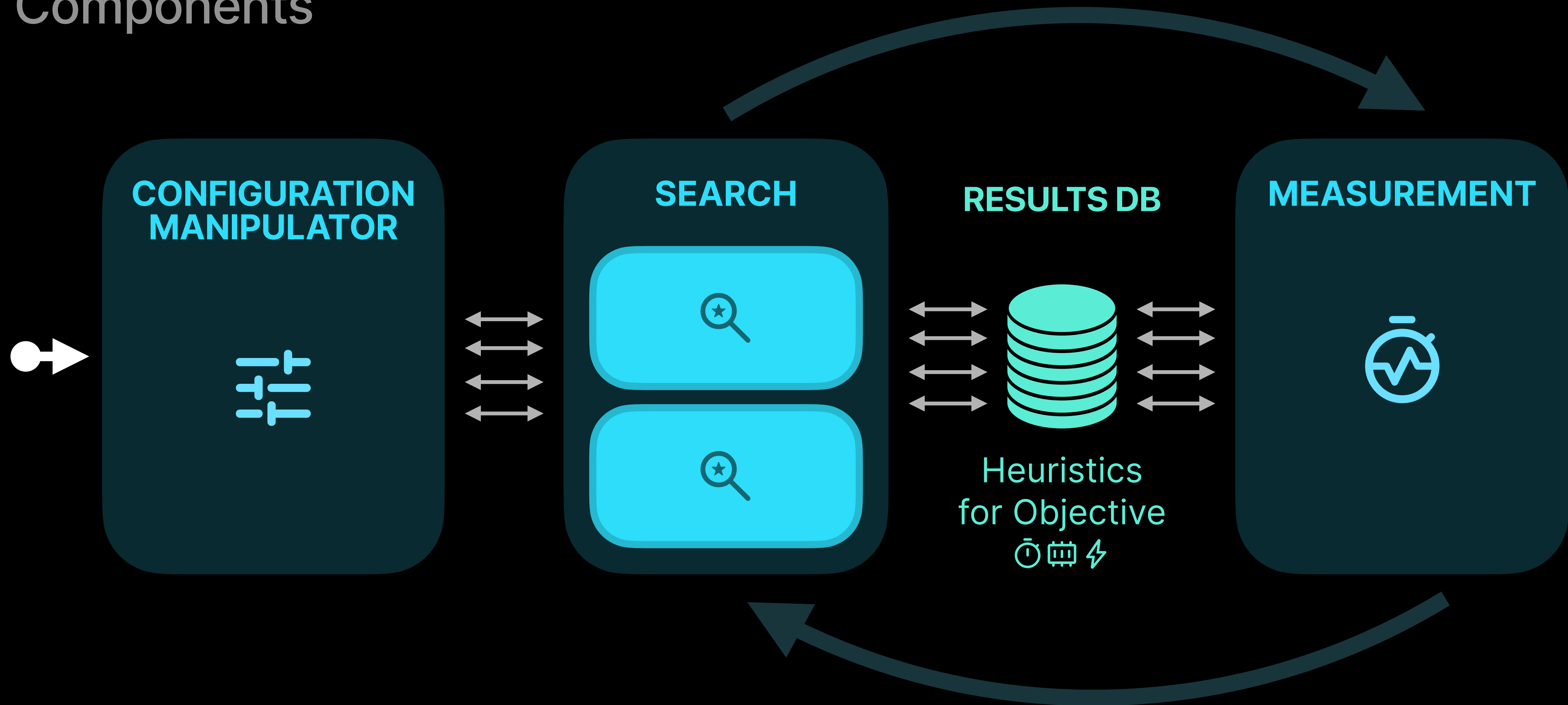
OpenTuner

Components



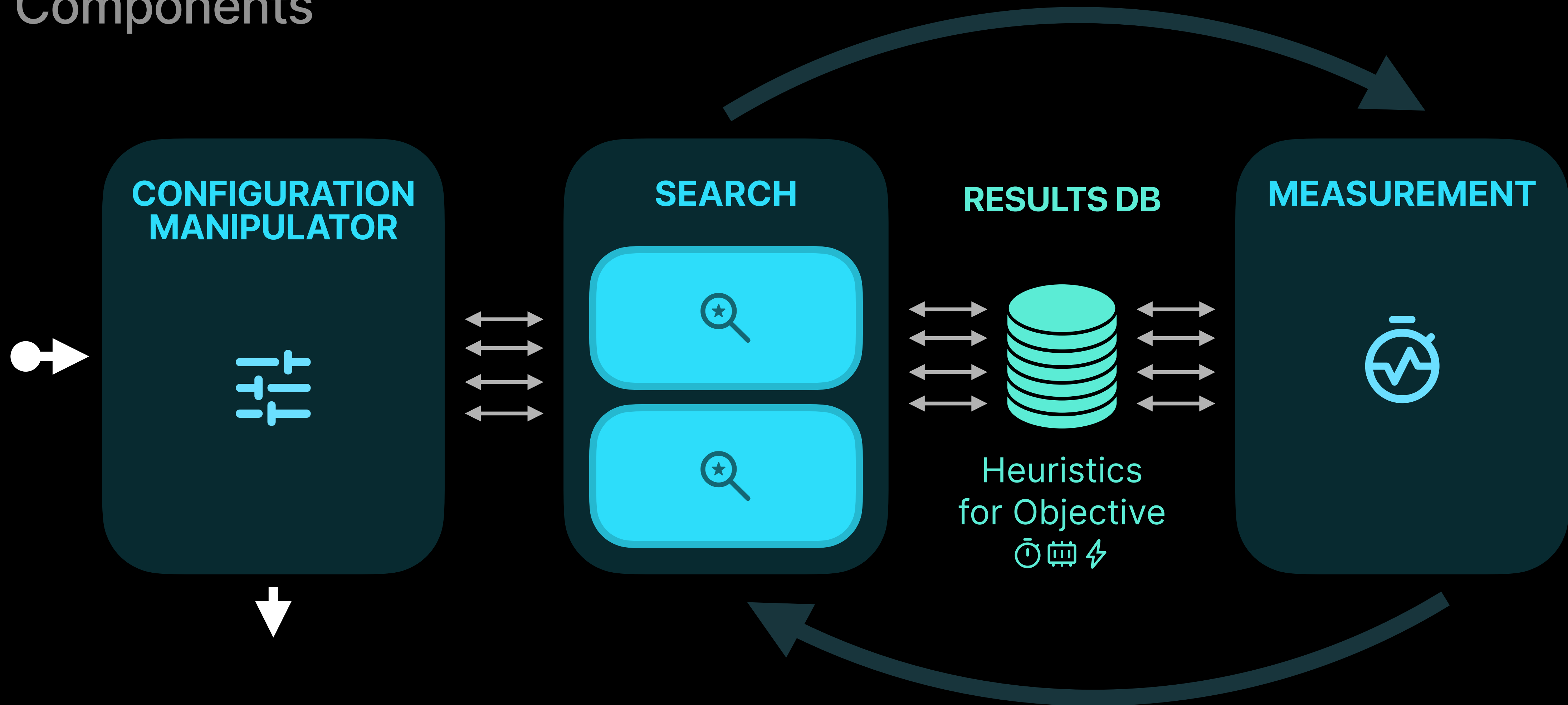
OpenTuner

Components



OpenTuner

Components



OpenTuner

Solutions

- 1 Configuration Representation
- 2 Configuration Space Size
- 3 Configuration Space Landscape

OpenTuner

Solutions

1 Configuration Representation

Python abstraction (API): primitive, complex, custom data types

2 Configuration Space Size

3 Configuration Space Landscape

OpenTuner

Solutions

1 Configuration Representation

Python abstraction (API): primitive, complex, custom data types

2 Configuration Space Size

3 Configuration Space Landscape

Ensemble of search techniques:

concurrent, dynamic evaluation budget allocation, cooperative

Evaluation

Evaluation

- ☑ 7 different project with different configuration representations

Evaluation

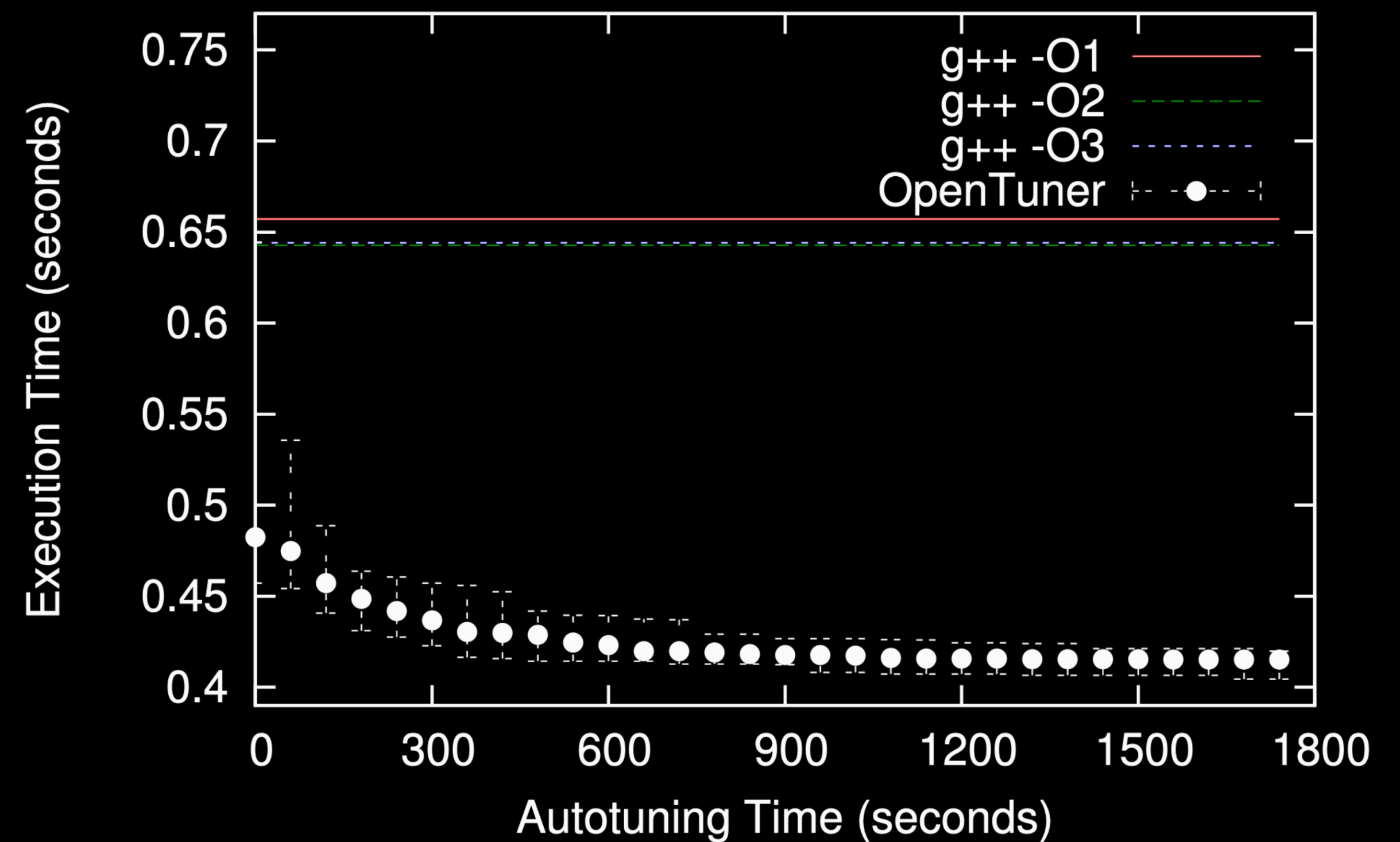
- ☑ 7 different project with different configuration representations
- ☑ Heuristic tuned to manual equivalent or optimum

Evaluation

- ☑ 7 different project with different configuration representations
- ☑ Heuristic tuned to manual equivalent or optimum
- ☑ Domain-specific success

Evaluation

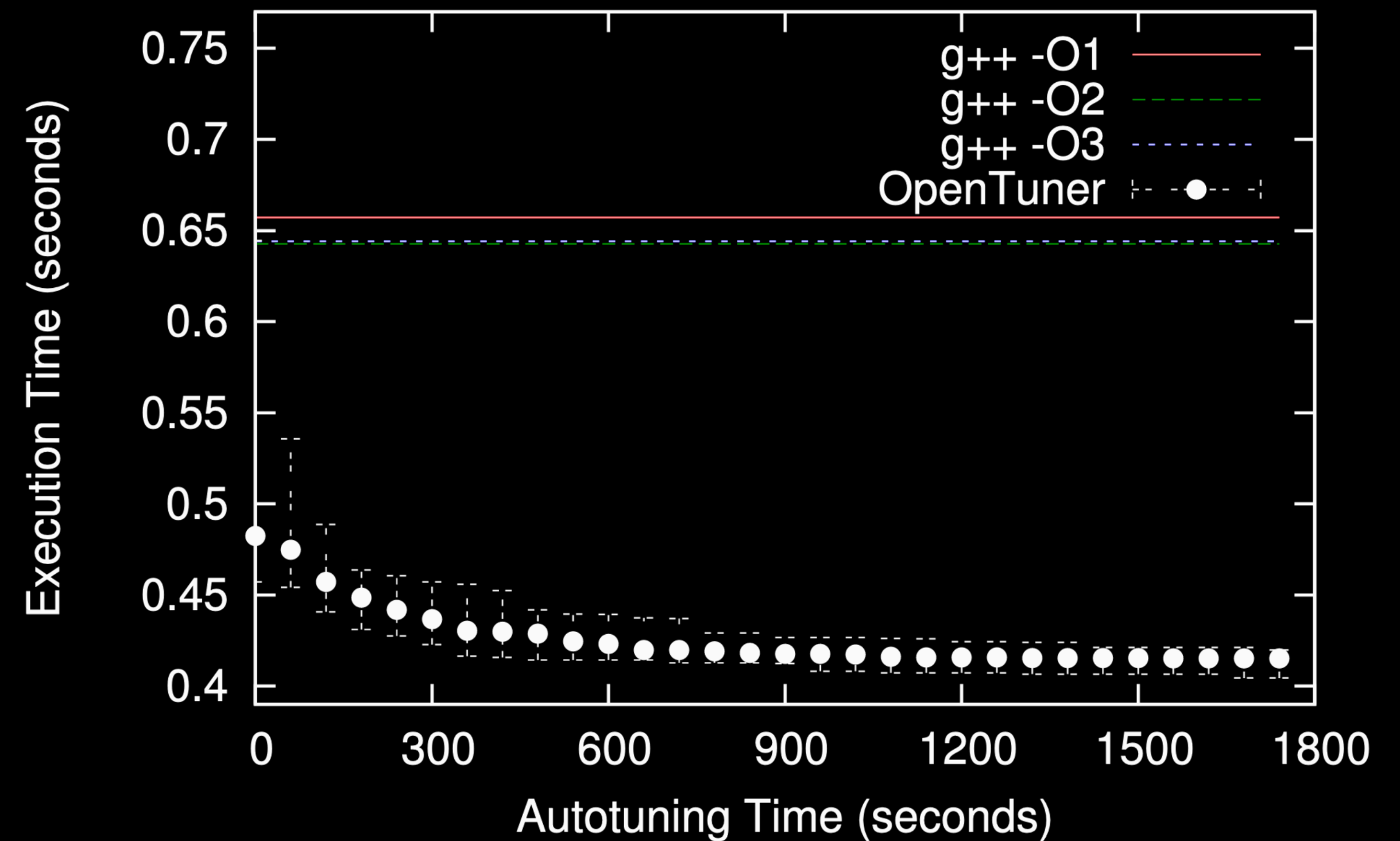
Experiment – GCC Flags



Evaluation

Experiment – GCC Flags

CONFIGURATION

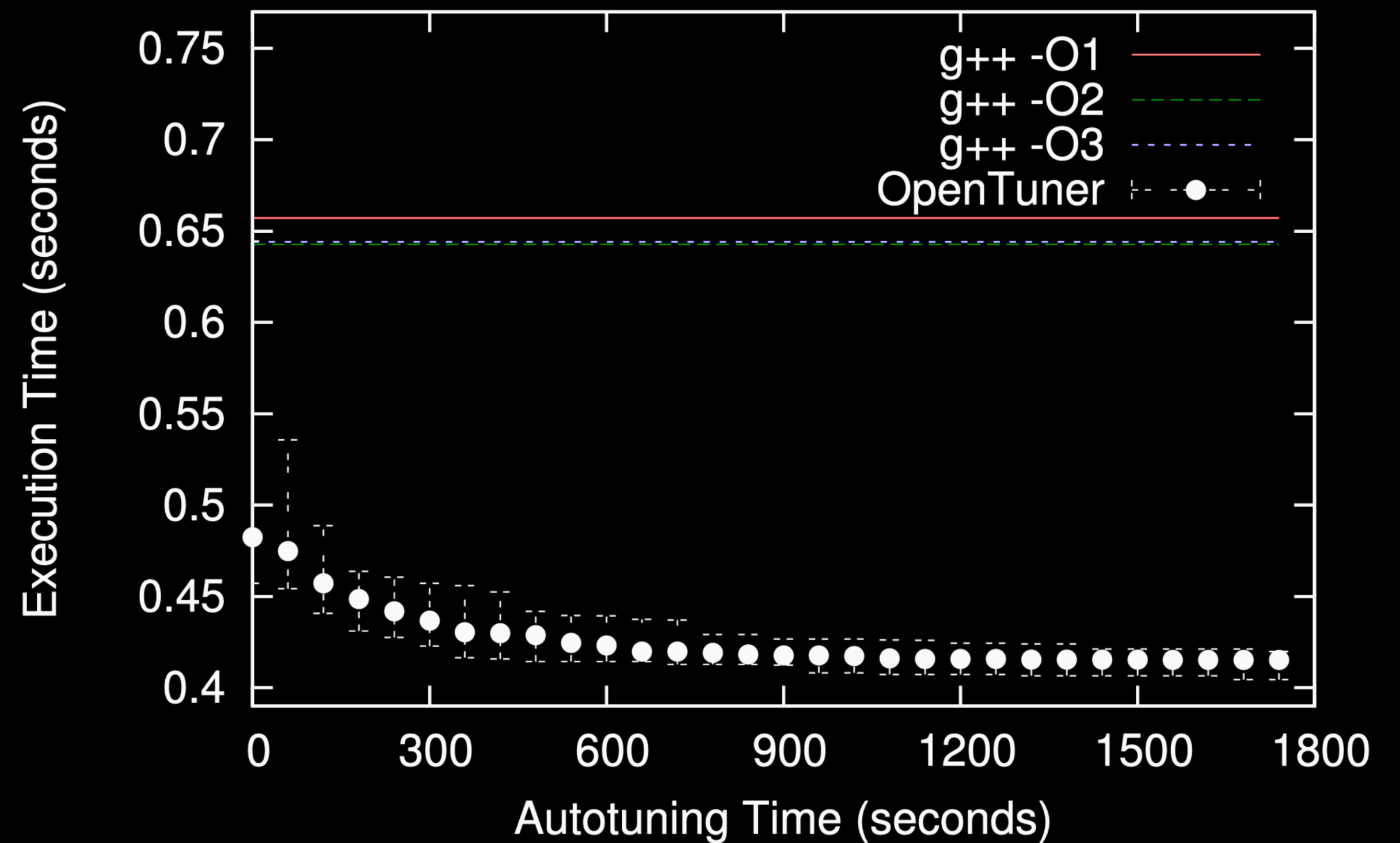


Evaluation

Experiment – GCC Flags

CONFIGURATION

Compiler flags



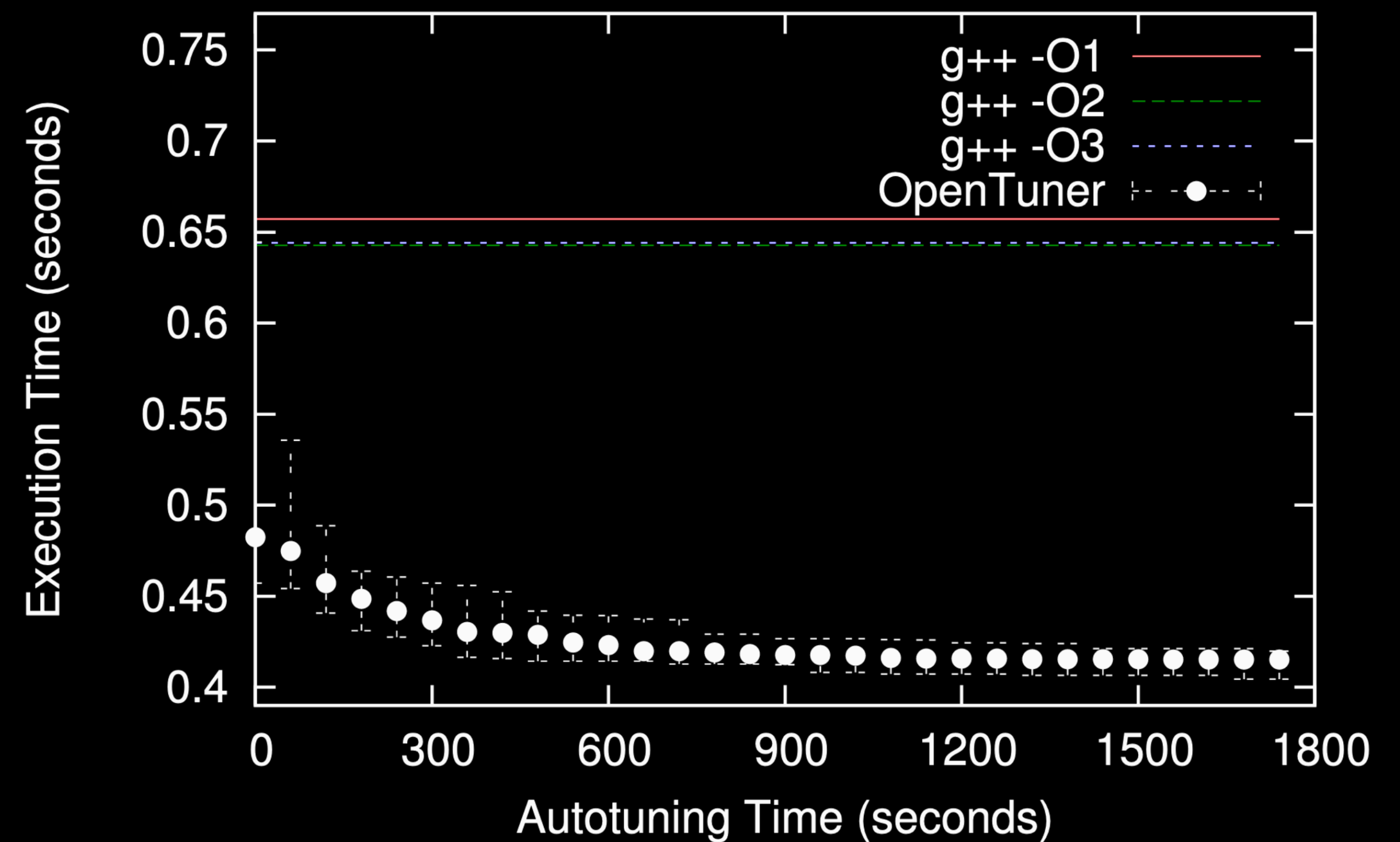
Evaluation

Experiment – GCC Flags

CONFIGURATION

Compiler flags

OBJECTIVE



Evaluation

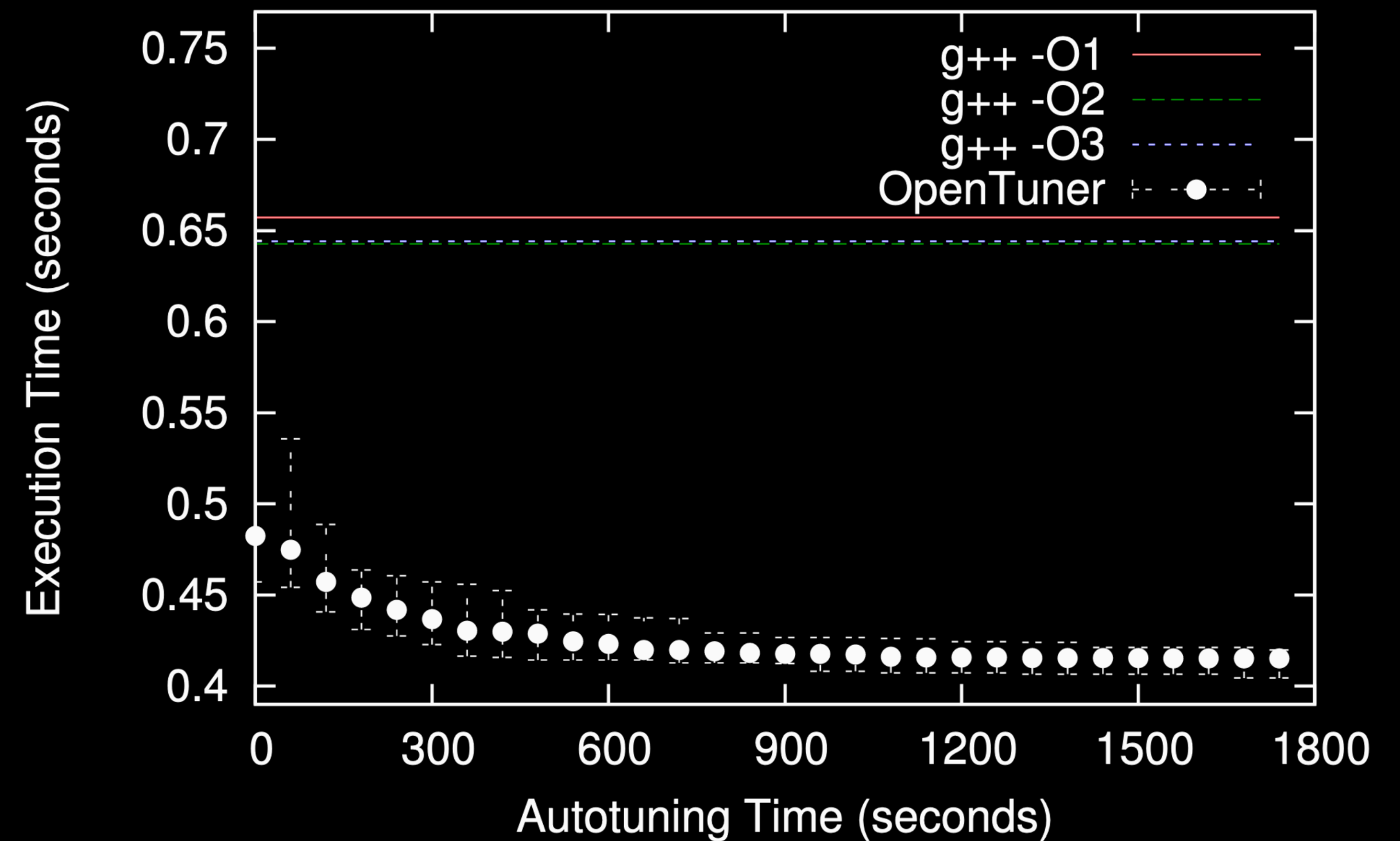
Experiment – GCC Flags

CONFIGURATION

Compiler flags

OBJECTIVE

⌚ Execution Time



Evaluation

Experiment – GCC Flags

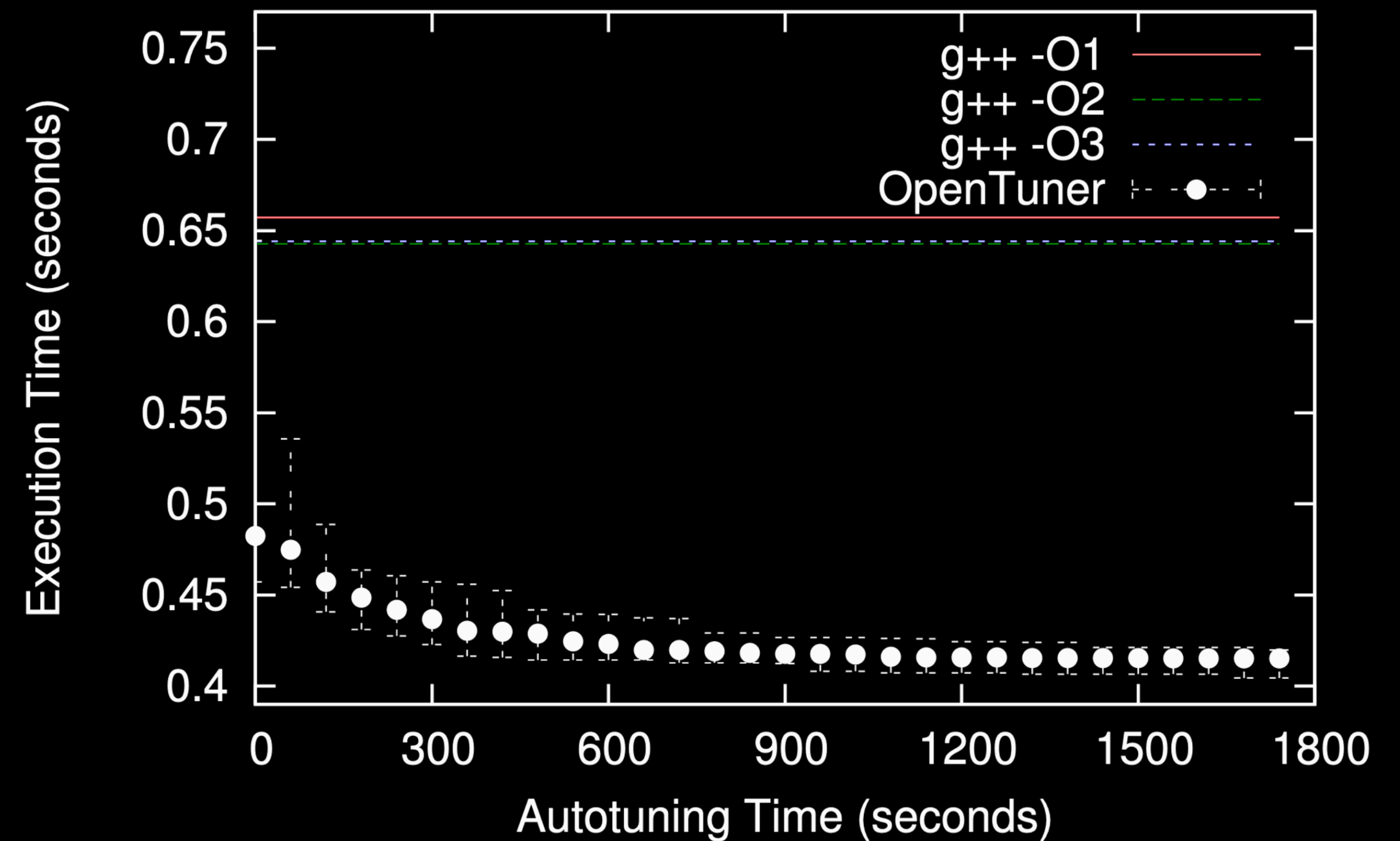
CONFIGURATION

Compiler flags

OBJECTIVE

⌚ Execution Time

RESULTS



Evaluation

Experiment – GCC Flags

CONFIGURATION

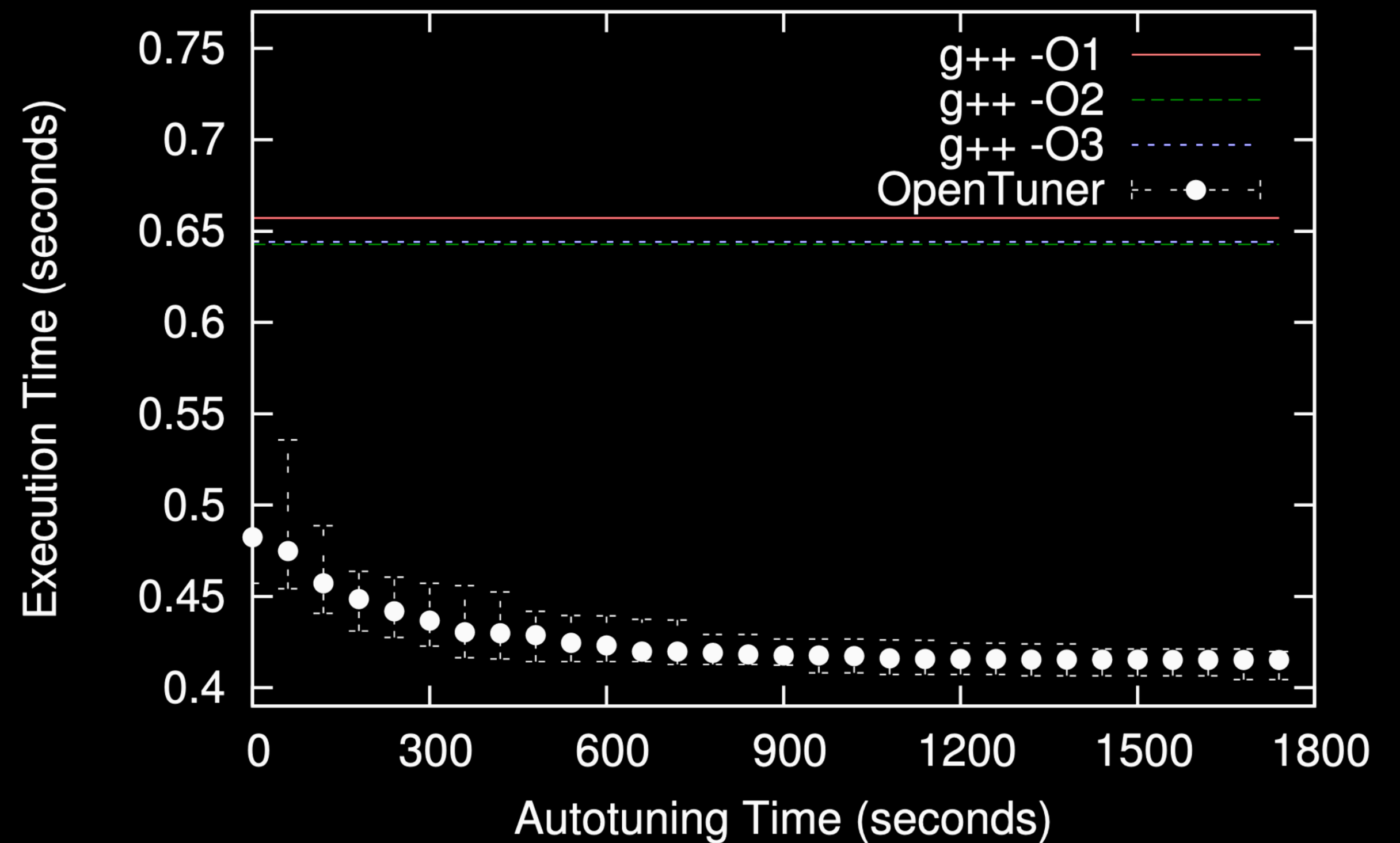
Compiler flags

OBJECTIVE

⌚ Execution Time

RESULTS

Raytracing
≈ −30%



Evaluation

Experiment – GCC Flags

CONFIGURATION

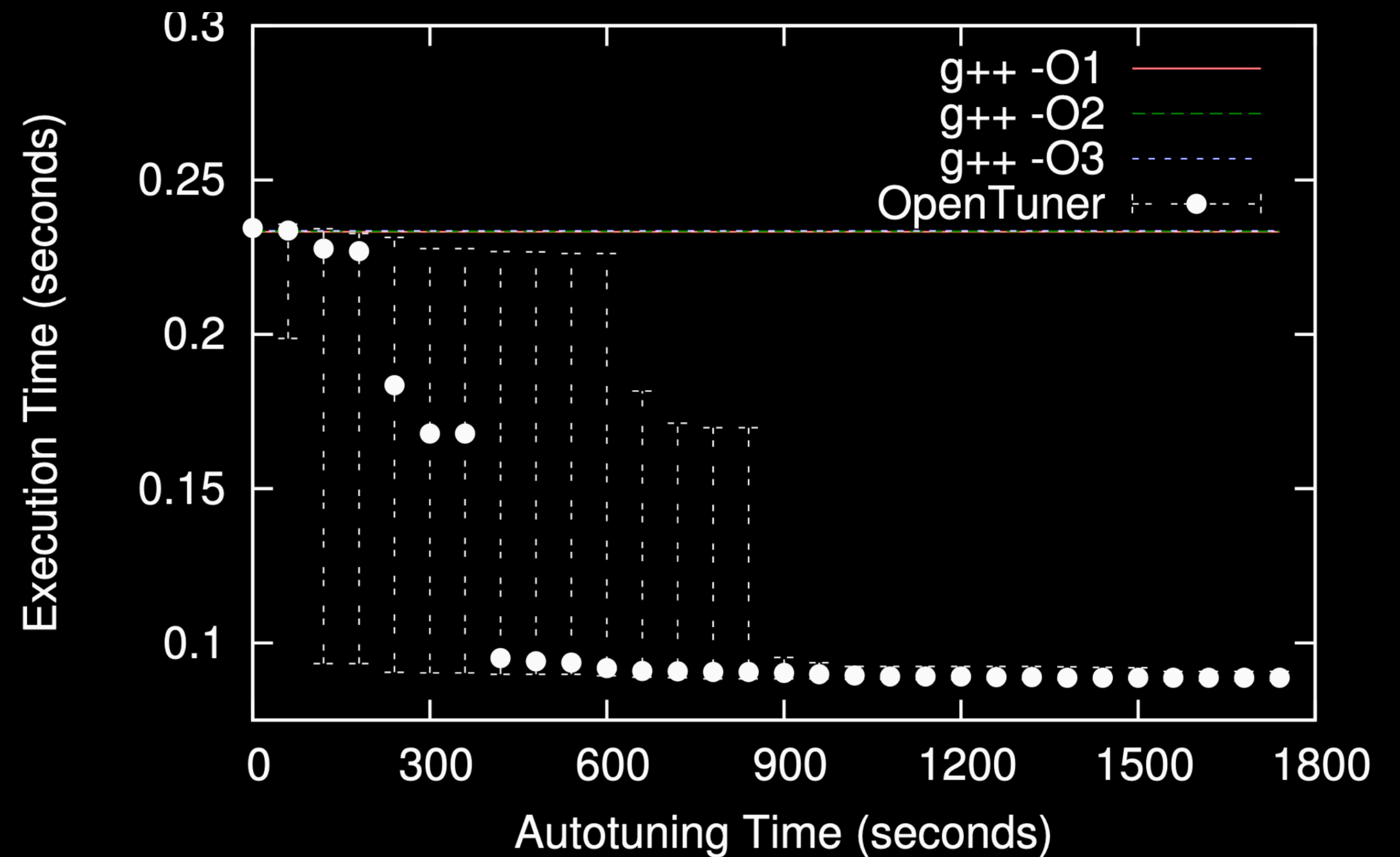
Compiler flags

OBJECTIVE

⌚ Execution Time

RESULTS

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≈ −30%



Evaluation

Experiment – GCC Flags

CONFIGURATION

Compiler flags

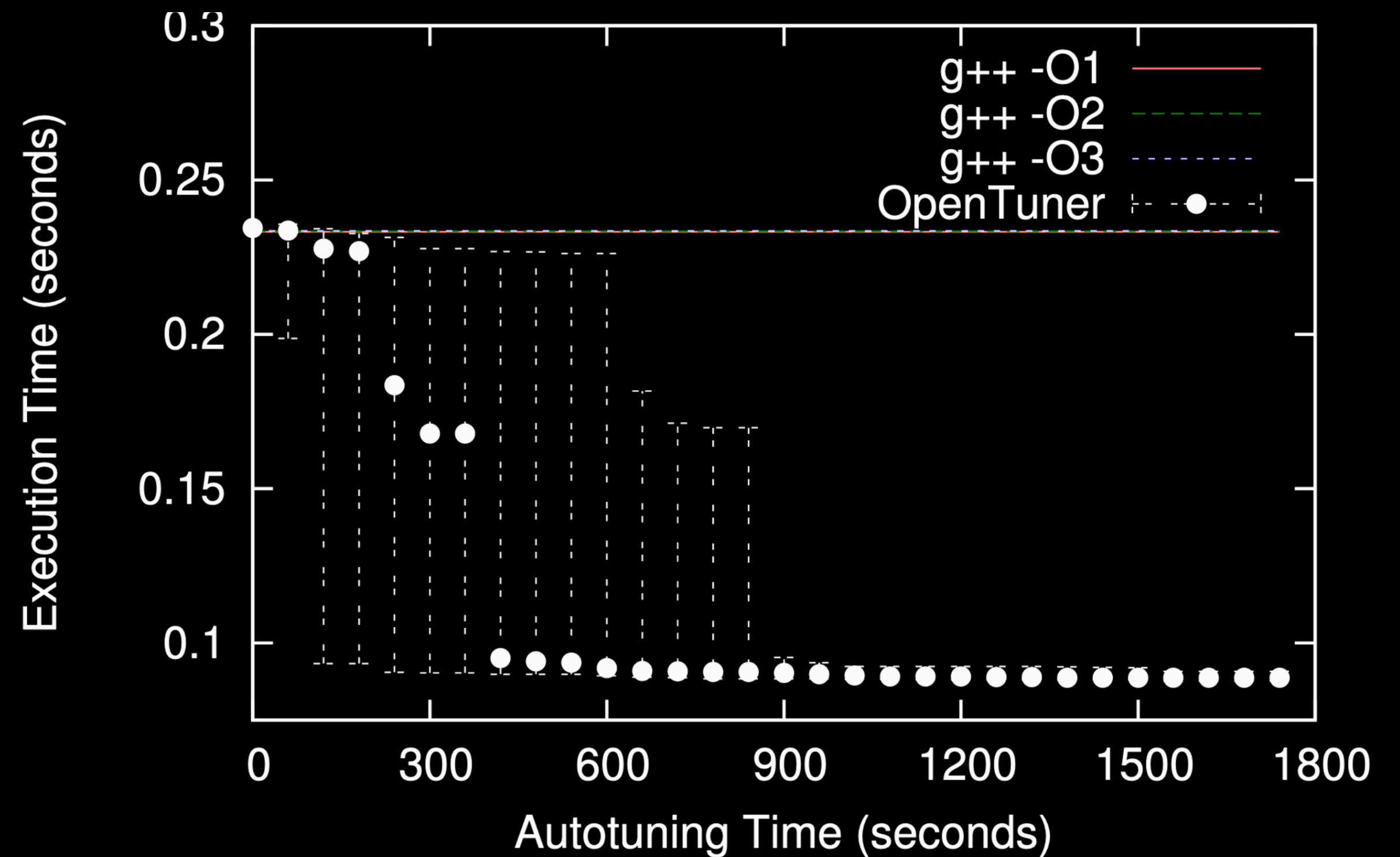
OBJECTIVE

⌚ Execution Time

RESULTS

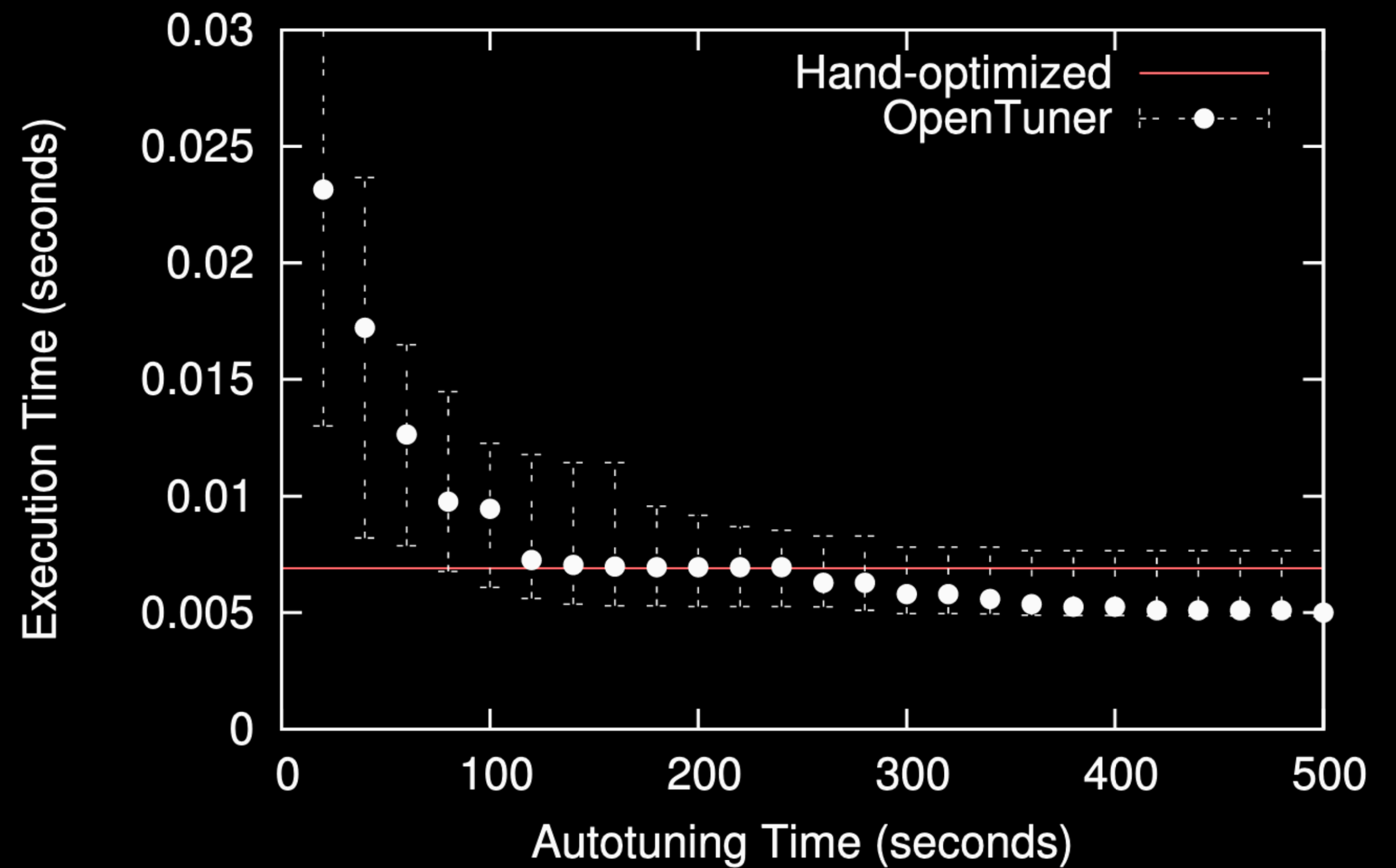
Raytracing
≈ −30%

Matrix Multiplication
≈ −60%



Evaluation

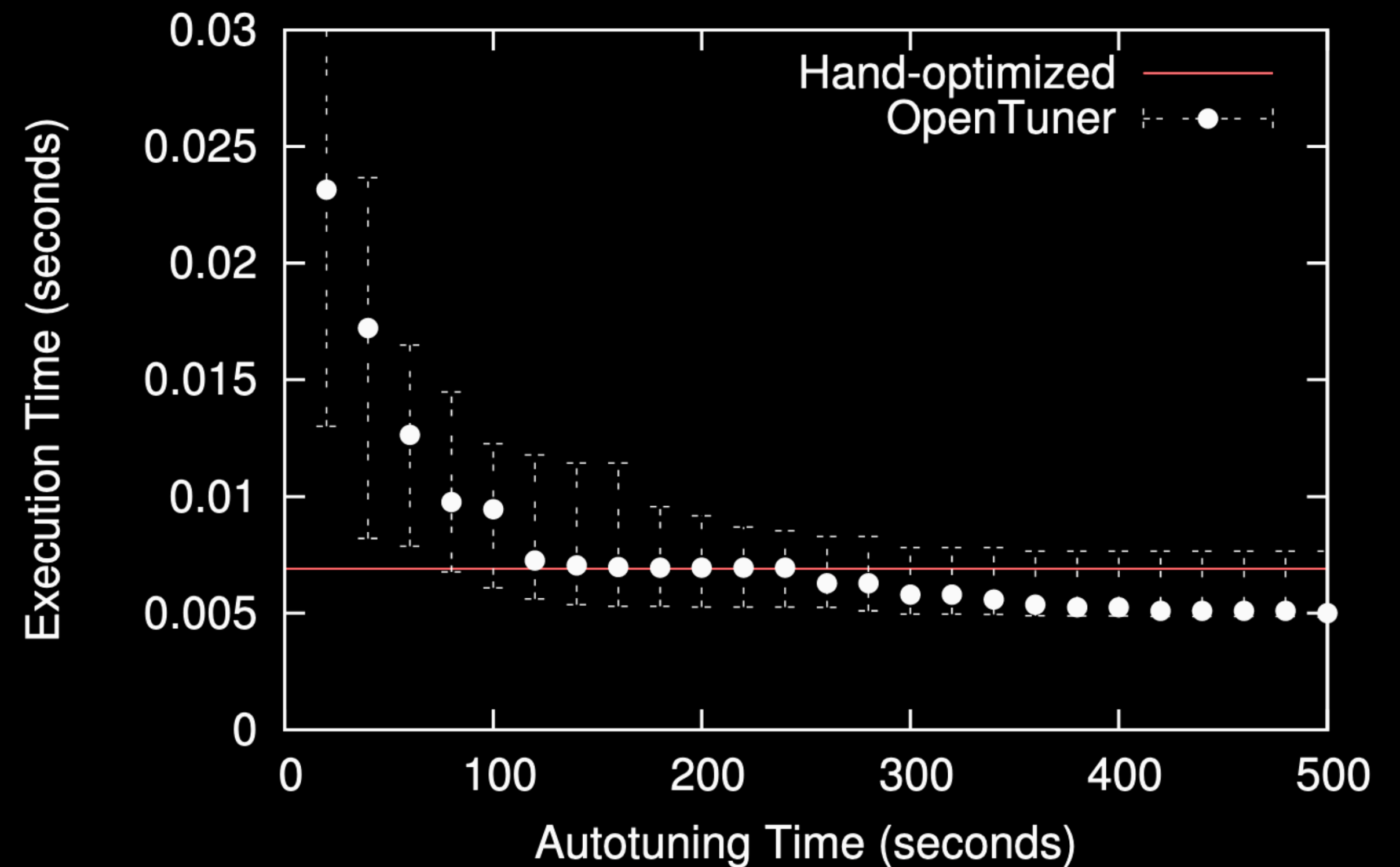
Experiment – Halide Graphics Processing Pipeline Schedule



Evaluation

Experiment – Halide Graphics Processing Pipeline Schedule

CONFIGURATION

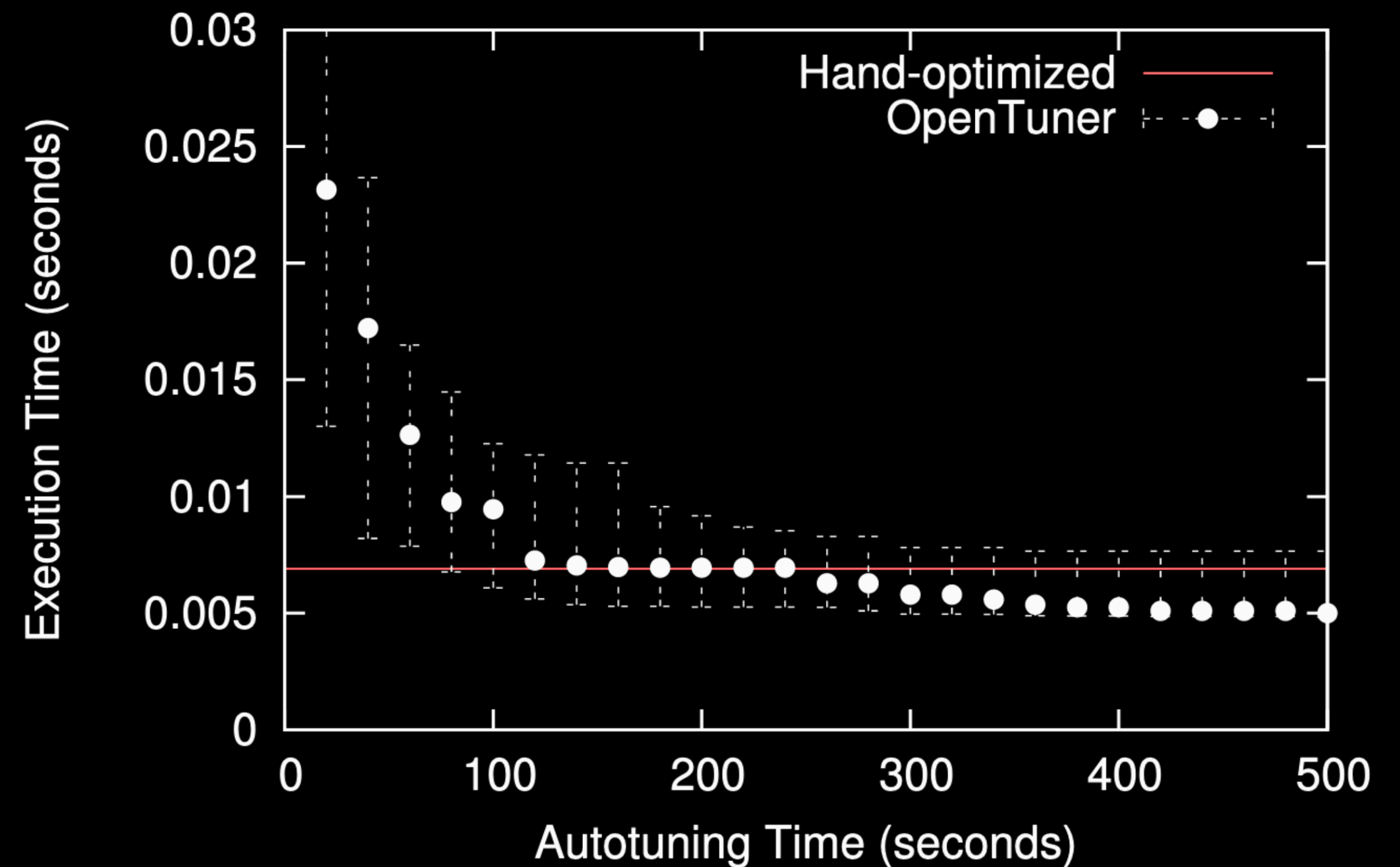


Evaluation

Experiment – Halide Graphics Processing Pipeline Schedule

CONFIGURATION

Pipeline schedule order



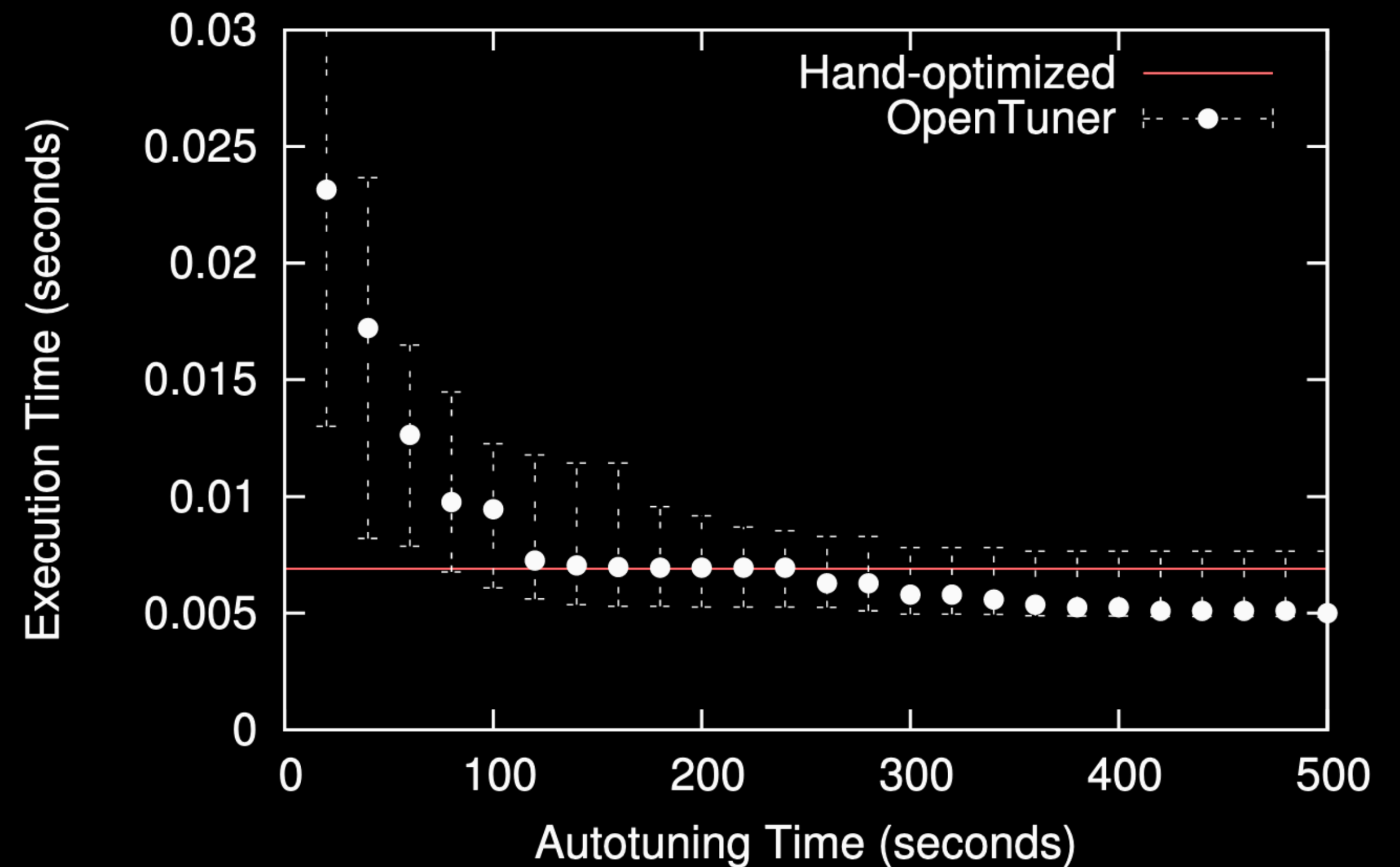
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CONFIGURATION

Pipeline schedule order

OBJECTIVE



Evaluation

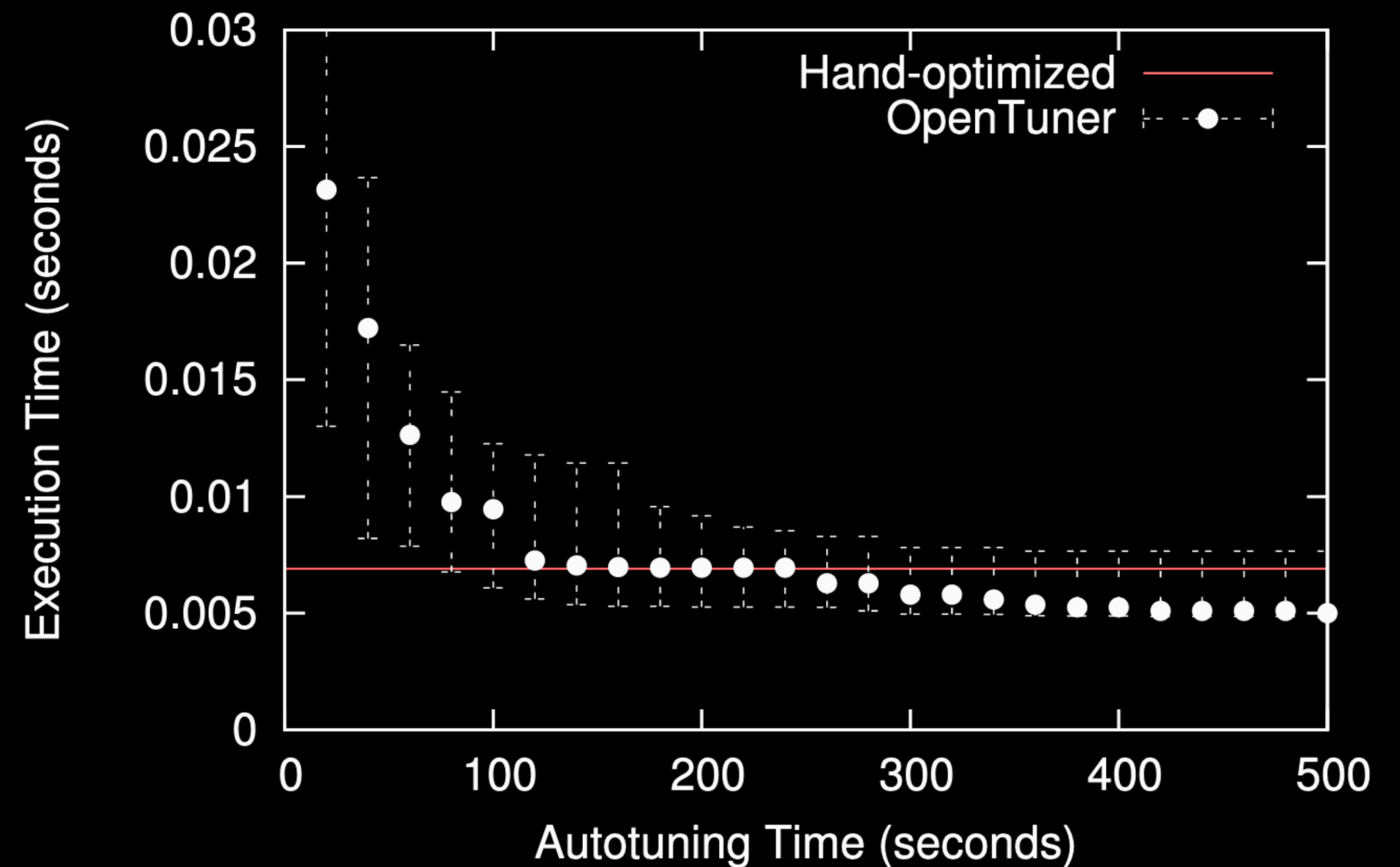
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CONFIGURATION

Pipeline schedule order

OBJECTIVE

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Evaluation

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CONFIGURATION

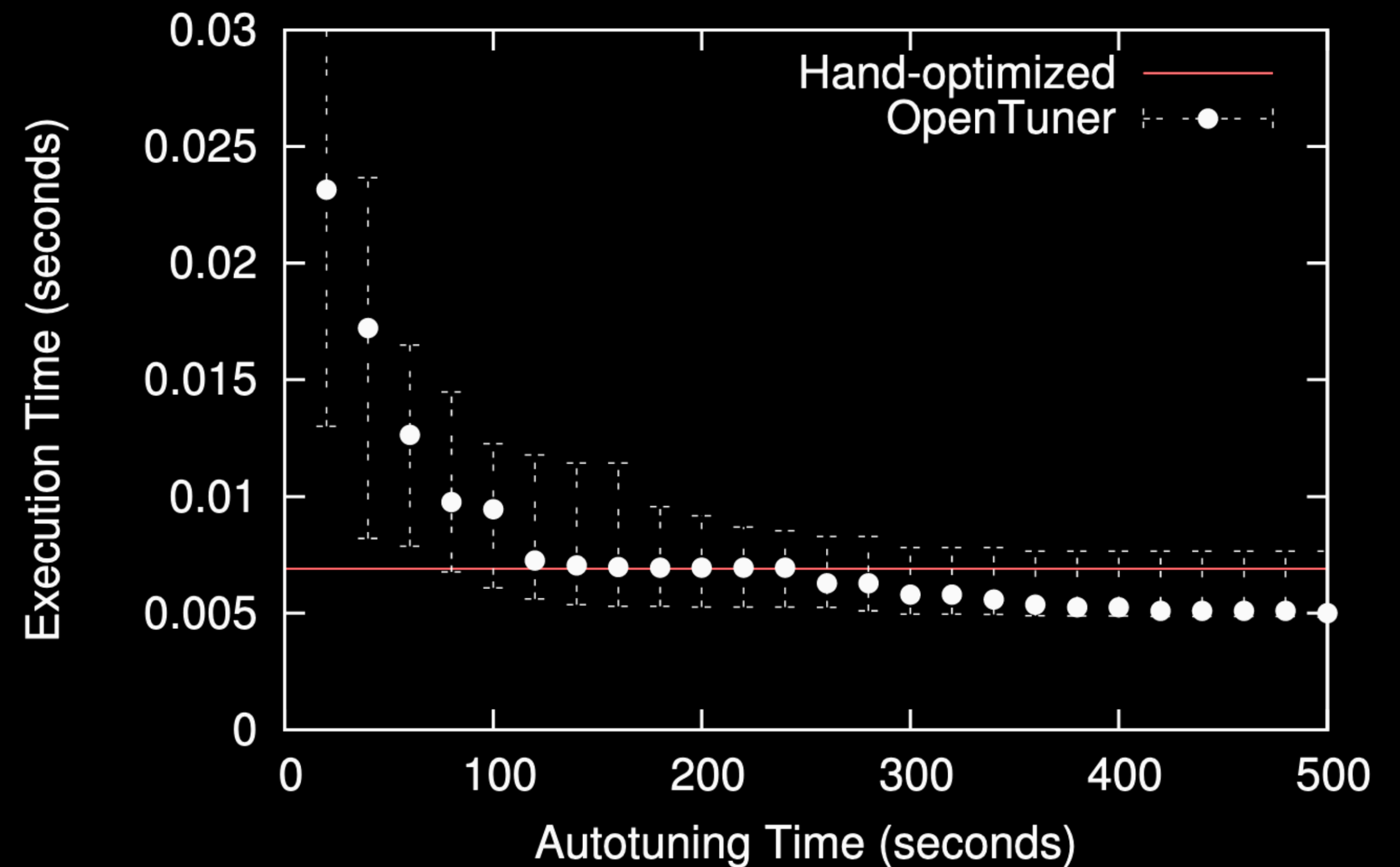
Pipeline schedule order

OBJECTIVE

⌚ Execution Time

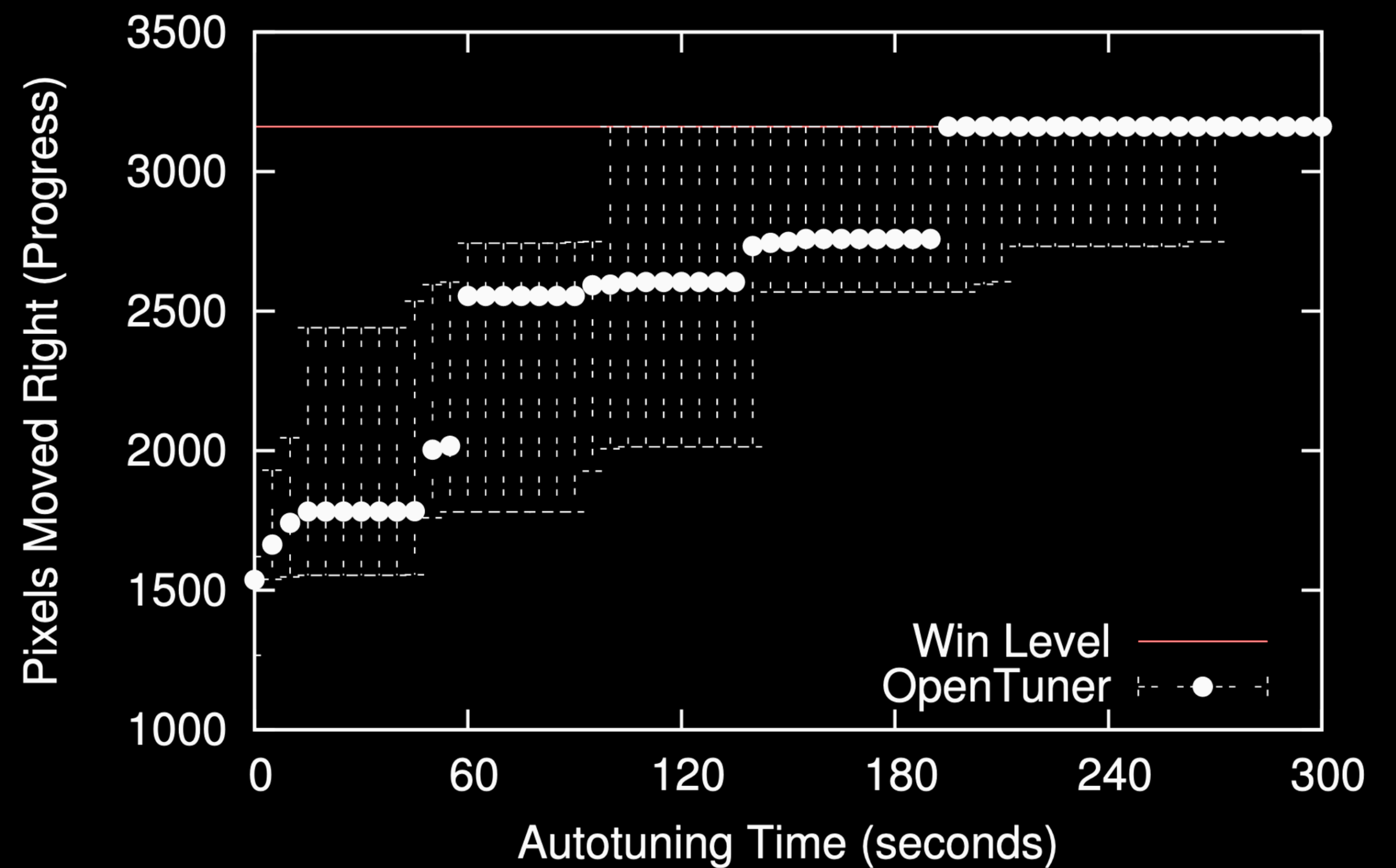
RESULTS

Blur Pipeline
reaches hand-optimized
performance



Evaluation

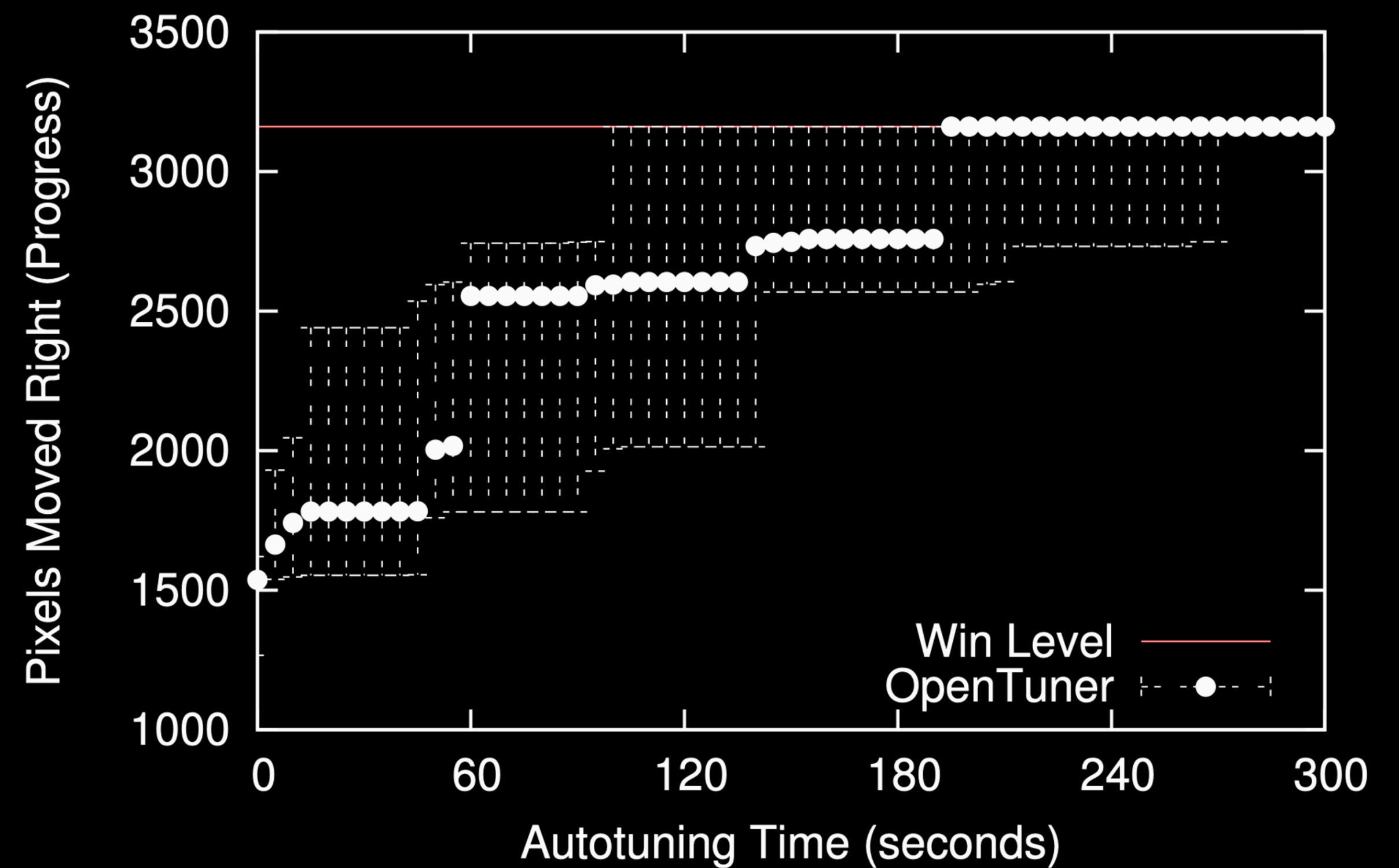
Experiment – Super Mario Bros.



Evaluation

Experiment – Super Mario Bros.

CONFIGURATION

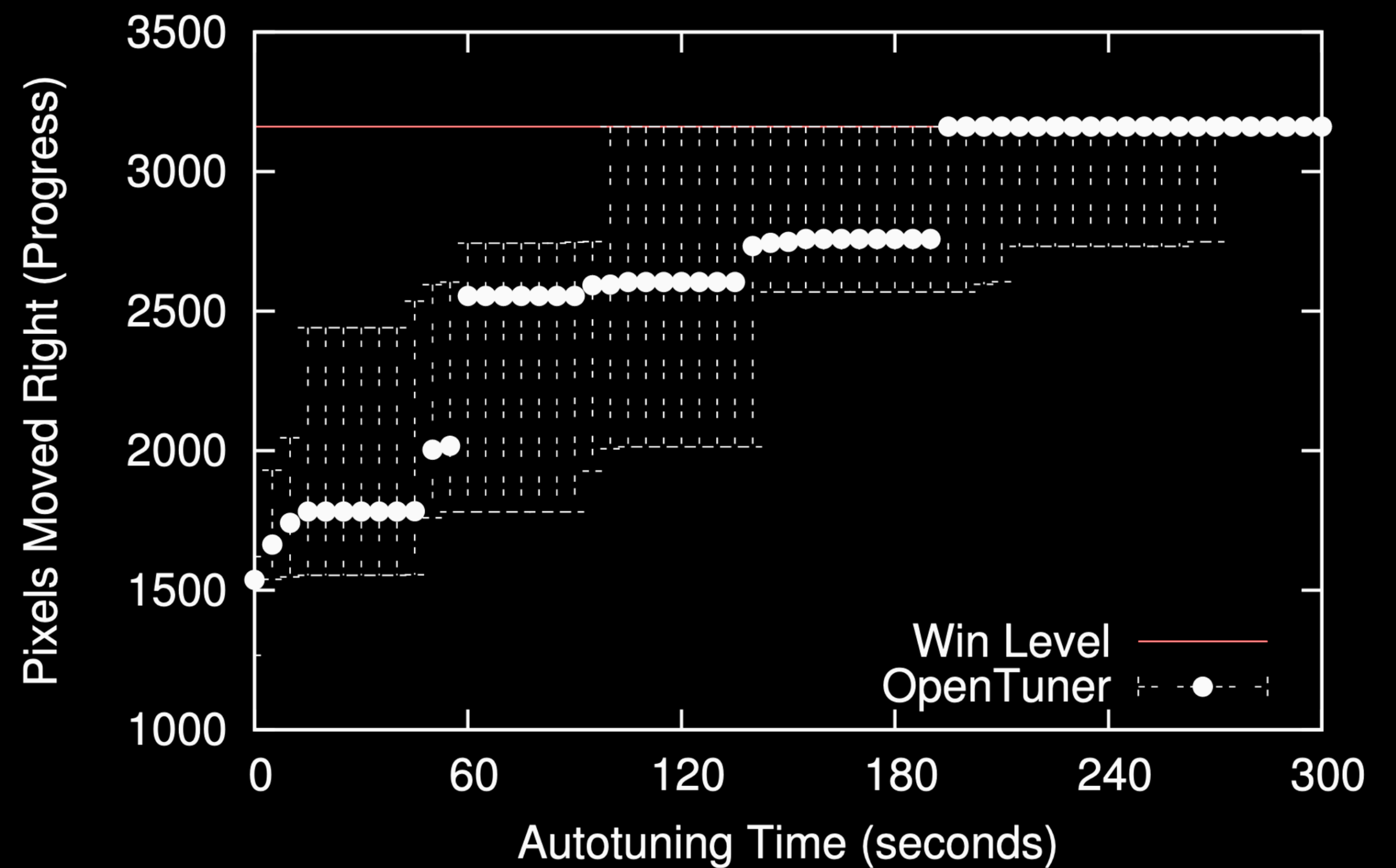


Evaluation

Experiment – Super Mario Bros.

CONFIGURATION

Sequence of button presses



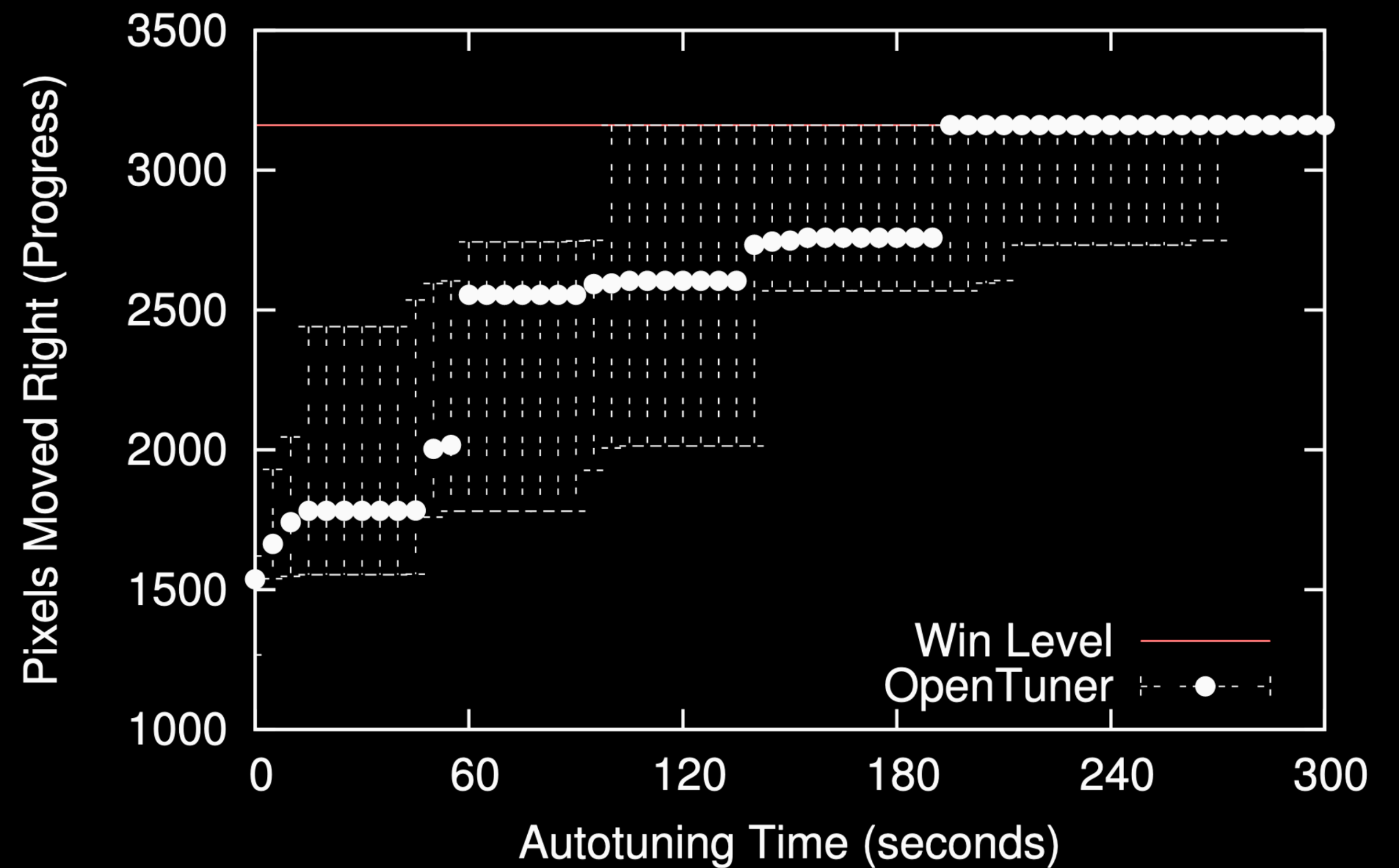
Evaluation

Experiment – Super Mario Bros.

CONFIGURATION

Sequence of button presses

OBJECTIVE



Evaluation

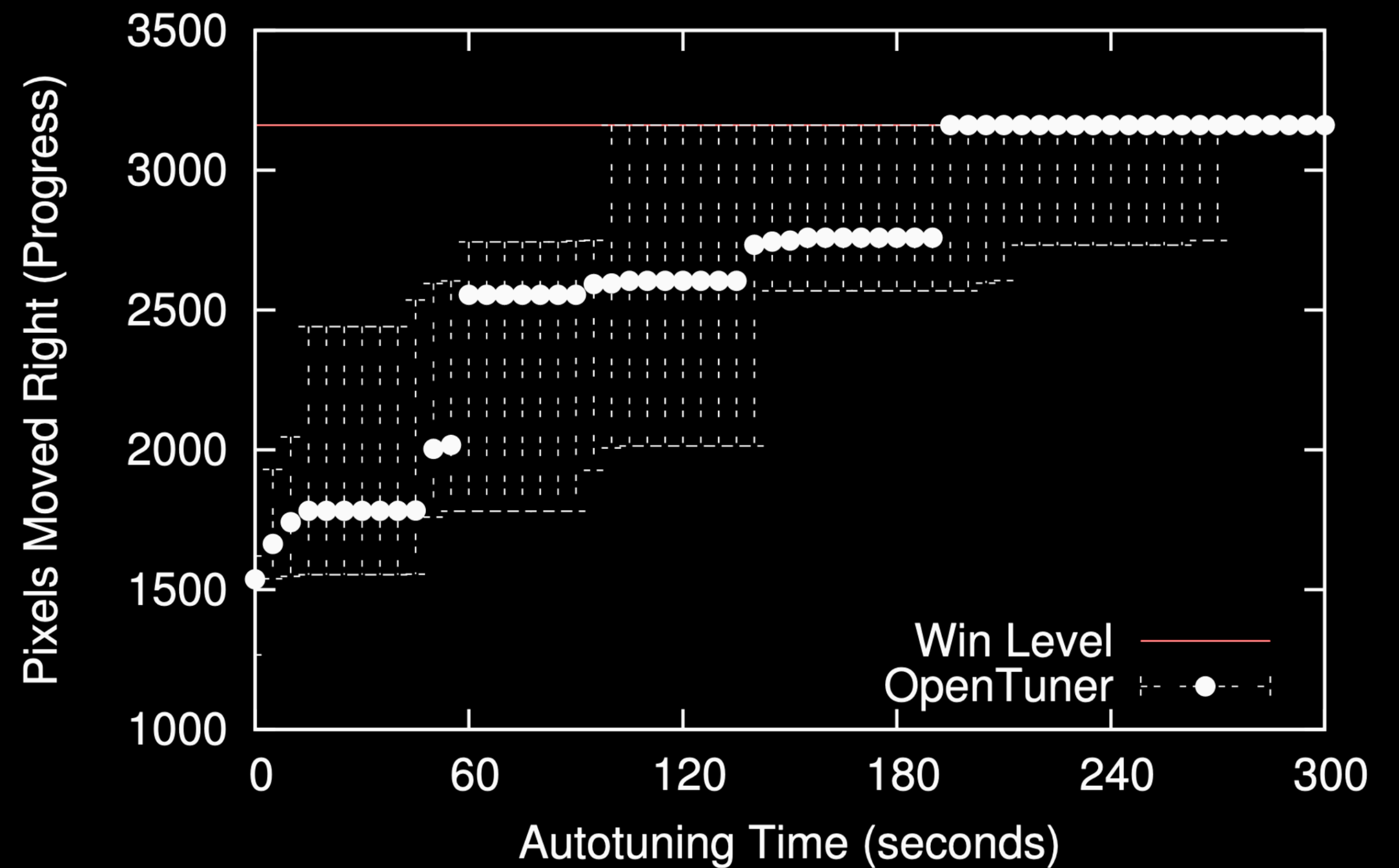
Experiment – Super Mario Bros.

CONFIGURATION

Sequence of button presses

OBJECTIVE

⌘ Execution Time



Evaluation

Experiment – Super Mario Bros.

CONFIGURATION

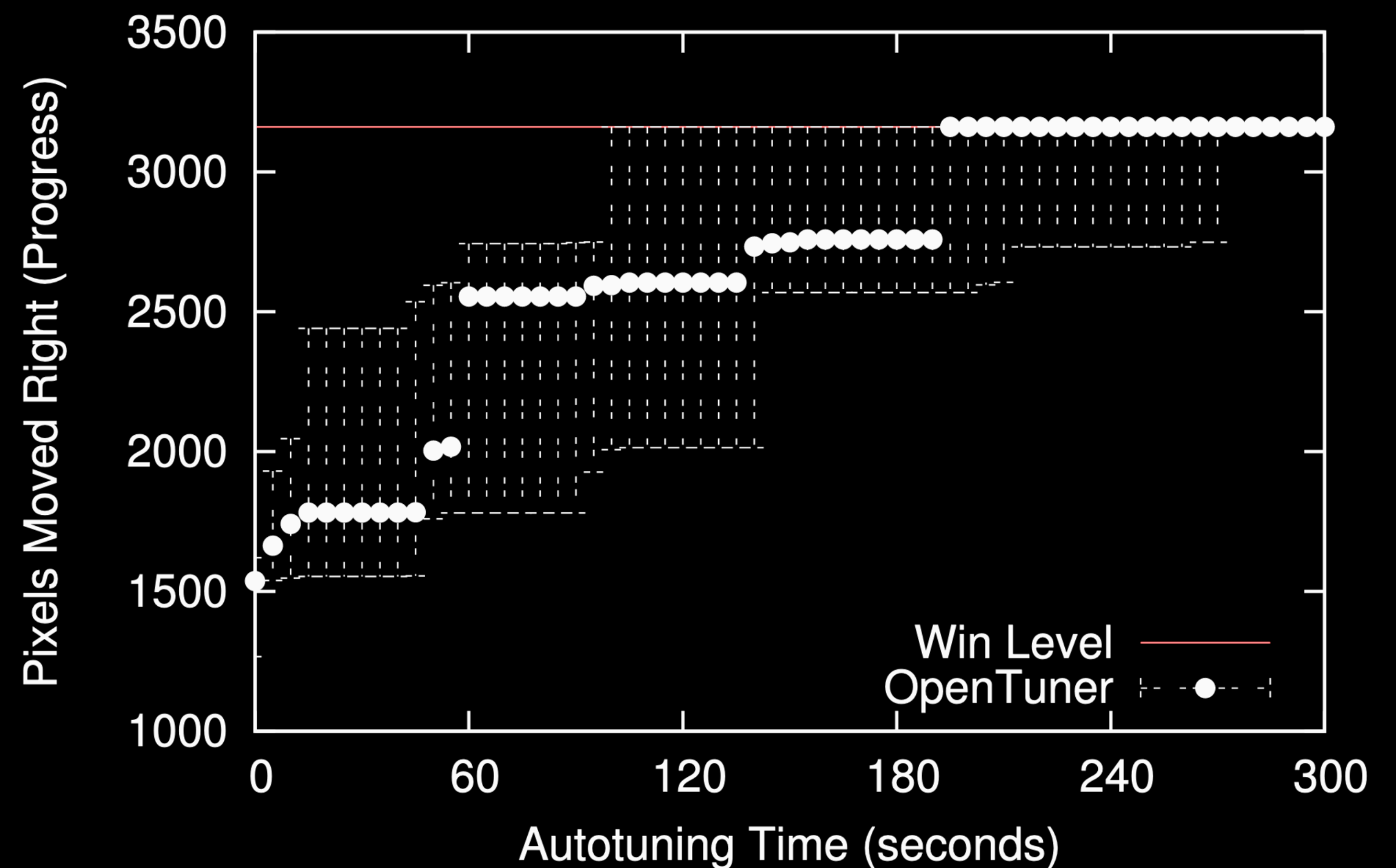
Sequence of button presses

OBJECTIVE

⌘ Execution Time

RESULTS

Successful coordination of jump:
right moment, duration, speed,
return on pit



Conclusions

[28] J. Ansel et al.: Petabricks: A language and compiler for algorithmic choice. In Proceedings of the 2009 ACM SIGPLAN Conference on Programming Language Design and Implementation, PLDI, 2009.

Conclusions

Motivated by *PetaBricks*^[28]

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Motivated by *PetaBricks*^[28]

Configuration representation + search techniques
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Extensible configuration abstraction

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FLOSS software

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Extensible configuration abstraction

FOSS software

→ **Portable autotuner**

Thoughts...

[7] V. Dalibard, M. Schaarschmidt, and E. Yoneki: BOAT: Building Auto-Tuners with Structured Bayesian Optimization, WWW, 2017.

[32] S. Cereda, S. Valladares, P. Cremonesi and S. Doni: CGPTuner: a Contextual Gaussian Process Bandit Approach for the Automatic Tuning of IT Configurations Under Varying Workload Conditions, VLDB, 2021.

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+ Extensibility + Abstractions

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