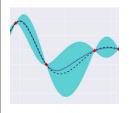


# Large-scale Data Processing and Optimisation Overview



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# Massive Data: Scale-Up vs Scale-Out

- Popular solution for massive data processing
  - → scale and build distribution, combine theoretically unlimited number of machines in single distributed storage
  - ightarrow Parallelisable data distribution and processing is key
- Scale-up: add resources to single node (many cores) in system (e.g. HPC)
- Scale-out: add more nodes to system (e.g. Amazon EC2)









# Technologies supporting Cluster Computing

#### Distributed infrastructure

Cloud (e.g. Infrastructure as a service, Amazon EC2, GCP, Azure)
 cf. Many core (parallel computing)

#### Storage

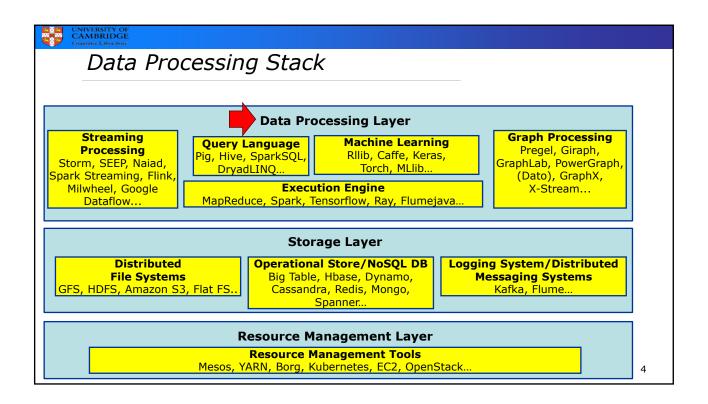
 Distributed storage (e.g. Amazon S3, Hadoop Distributed File System (HDFS), Google File System (GFS))

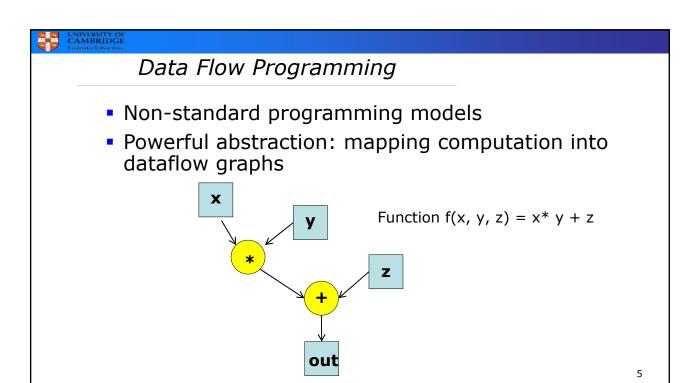
#### Data model/indexing

 High-performance schema-free database (e.g. NoSQL DB - Redis, BigTable, Hbase, Neo4J)

#### Programming model

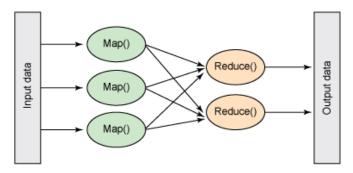
Distributed processing (e.g. MapReduce)

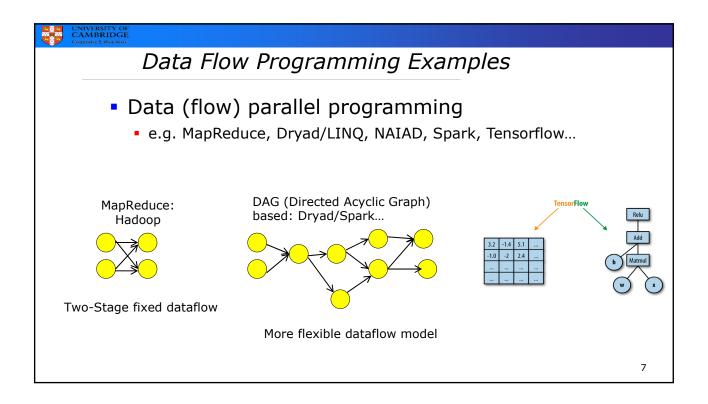


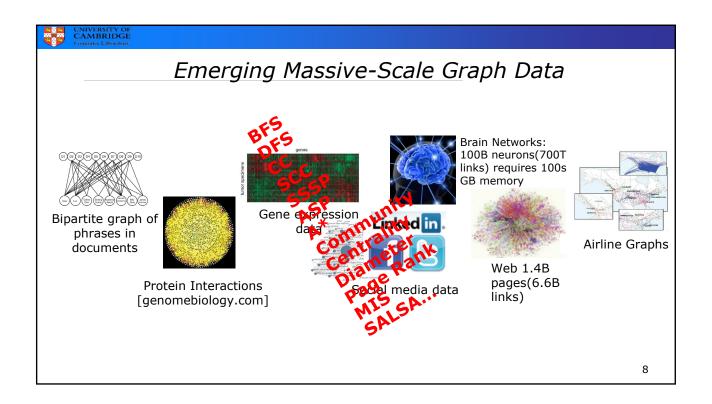


# WapReduce Programming

- Target problem needs to be parallelisable
- Split into a set of smaller code (map)
- Next small piece of code executed in parallel
- Results from map operation get synthesised into a result of original problem (reduce)









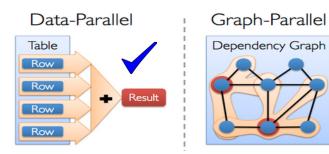
# Graph Computation Challenges

- 1. Graph algorithms (BFS, Shortest path)
- 2. Query on connectivity (Triangle, Pattern)
- 3. Structure (Community, Centrality)
- 4. ML & Optimisation (Regression, SGD)
- Data driven computation: dictated by graph's structure and parallelism based on partitioning is difficult
- Poor locality: graph can represent relationships between irregular entries and access patterns tend to have little locality
- High data access to computation ratio: graph algorithms are often based on exploring graph structure leading to a large access rate to computation ratio



#### Data-Parallel vs. Graph-Parallel

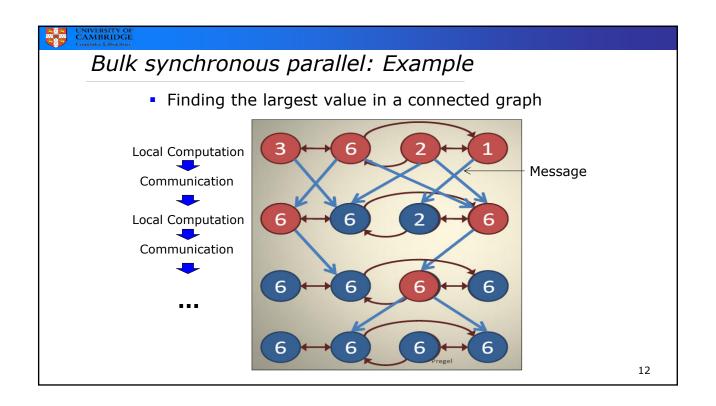
- Data-Parallel for all? Graph-Parallel is hard!
  - Data-Parallel (sort/search randomly split data to feed MapReduce)
  - Not every graph algorithm is parallelisable (interdependent computation)
  - Not much data access locality
  - High data access to computation ratio

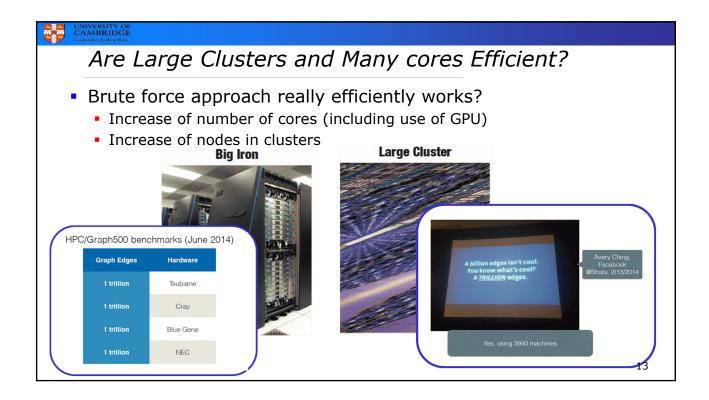


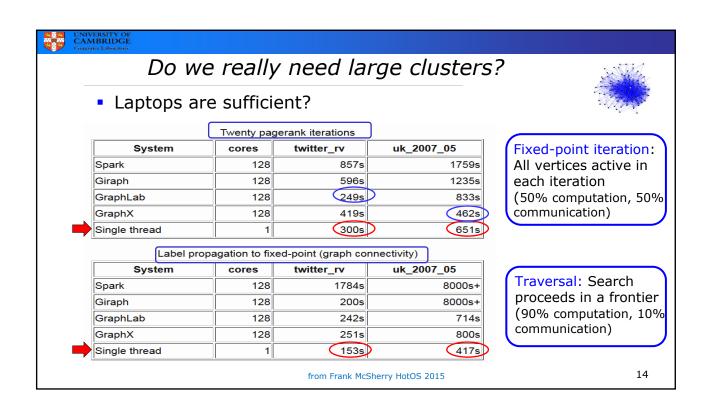


#### Graph-Parallel

- Graph-Parallel (Graph Specific Data Parallel)
  - Vertex-based iterative computation model
  - Use of iterative Bulk Synchronous Parallel Model
    - Pregel (Google), Giraph (Apache), Graphlab, GraphChi (CMU - Dato)
  - Optimisation over data parallel
    - → GraphX/Spark (U.C. Berkeley)
  - Data-flow programming more general framework
    - > NAIAD (MSR), TensorFlow...









#### Data Processing Paradigm Change

- Emergence of modern Neural Networks Applications
- Practicalities of training Neural Networks
- Leveraging heterogeneous hardware
- Traditional dataflow programming does not deal with mathematical objects (no deep learning back then), now control flow requires to be numerically differentiable (i.e. TensorFlow)

#### Image Classification



#### Reinforcement Learning





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#### Challenging: Computer Systems Optimisation

- How do we improve performance:
  - Manual tuning
  - Auto-tuning
- What is performance? objective function of optimisation
  - Resource usage (e.g. time, power)
  - Computational properties (e.g. accuracy, fairness, latency)
  - Large number of parameters
  - Evaluation is slow and expensive
- What is Optimisation Model?
  - Short-term dynamic control (e.g. stream processing: distinct workload or dynamic workload)
  - Combinatorial optimisation (e.g. indexing DB, device assignment)

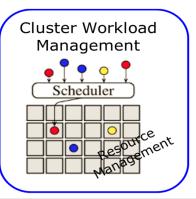
Many systems problems are combinatorial in nature

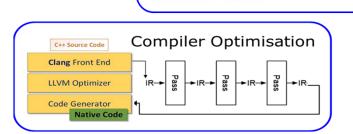


#### Use of ML based Optimisation Methods

- Increasing data volumes and high-dimension parameter space
- Expensive Objective Functions

 Hand-crafted solutions impractical, often left static or configured through extensive offline analysis
 Deep Learning





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Hyper-Parameters:
- Learning-rate
- Number of Dense Layers

Number of Dense Nodes Activation Function

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# Machine Learning and Optimisation

- Function Optimisation
  - Find the set of inputs to a target objective function that result in the minimum or maximum of the function
- Function Approximation:
  - Generalise from specific examples to a reusable mapping function for making predictions on new examples
  - ML can be described as function approximation as approximating the unknown underlying function that maps examples of inputs to outputs in order to make predictions on new data
  - Function approximation often uses function optimisation
- At the core of many ML algorithms is an optimisation algorithm!



# Optimisation: Iterative Operation

- Common to use an iterative global search algorithm for optimisation problem
- e.g. Bayesian optimisation algorithm that is capable of simultaneously approximating the target function that is being optimised while optimising it.
- Automated machine learning (AutoML) algorithms being used to choose an algorithm, an algorithm and hyperparameters, or data preparation, algorithm and hyperparameters, with very little user intervention

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#### Auto-tuning Complex Systems



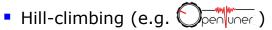
- Many dimensions
- Expensive objective function
- Hand-crafted solutions impractical (e.g. extensive offline analysis)



#### **Blackbox Optimisation**

✓ can surpass human expert-level tuning

- Grid search  $\theta \in [1, 2, 3, ...]$
- Random search
- Evolutionary approaches (e.g. PetaBricks )



Bayesian optimisation (e.g. spearmint)



1000s of evaluations of objective function

Computation more expensive

Fewer samples



#### Search Parameter Space

Random search: No risk of 'getting stuck' potentially many samples required

**Evolution strategies**: Evaluate permutations against fitness function

**Bayes Opt:** Sample efficient, requires continuous function, some configuration

Random Search	Genetic algorithm / Simulated annealing	Bayesian Optimisation
No overhead	Slight overhead	High overhead
High #evaluation	Medium-high #evaluation	Low #evaluation

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#### Bayesian Optimisation

- Iteratively builds probabilistic model of objective function
- Typically Gaussian process as probabilistic model
- Data efficient: converges quickly

**Input:** Objective function f()

Input: Surrogate function initial distribution G

**Input:** Acquisition function a()

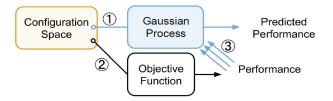
- 1: **for**  $i = 1, 2, \dots$  **do**
- 2: Sample point:  $\mathbf{x}_t \leftarrow \arg\max_{\mathbf{x}} a(G, \mathbf{x})$
- 3: Evaluate new point:  $y_t \leftarrow f(\mathbf{x}_t)$
- 4: Update surrogate distribution:  $G \leftarrow G \mid (\mathbf{x}_t, y_t)$
- 5: end for

#### **Pros:**

Data efficient: converges in few iterationsAble to deal with noisy observations

#### Cons:

X In many dimensions, model does not converge to the objective function



- ① Find promising point (high performance value in the model)
- ② Evaluate the objective function at that point
- (3) Update the model to reflect this new measurement



# Further Bayesian Optimisation...

#### BO overview/Tutorial

- https://www.cl.cam.ac.uk/~ey204/teaching/ACS/R244\_2021\_2022/aid/BO \_overview\_Archambeau.pdf
- https://www.cl.cam.ac.uk/~ey204/teaching/ACS/R244\_2021\_2022/aid/BO \_overview\_adams.pdf
- https://www.cl.cam.ac.uk/~ey204/teaching/ACS/R244\_2021\_2022/aid/BO \_overview\_gonzalez.pdf

#### Papers

- Review paper by Shahriari, et al. (2016): Taking the Human Out of the Loop: A Review of Bayesian Optimization. Proceedings of the IEEE 104(1):148-175, 2016.
- Slides by Ryan Adams (2014): A Tutorial on Bayesian Optimization for Machine Learning. CIFAR NCAP Summer School.
- Slides by Peter Frazier (2010): Tutorial: Bayesian Methods for Global and Simulation Optimization. INFORMS Annual Meeting.

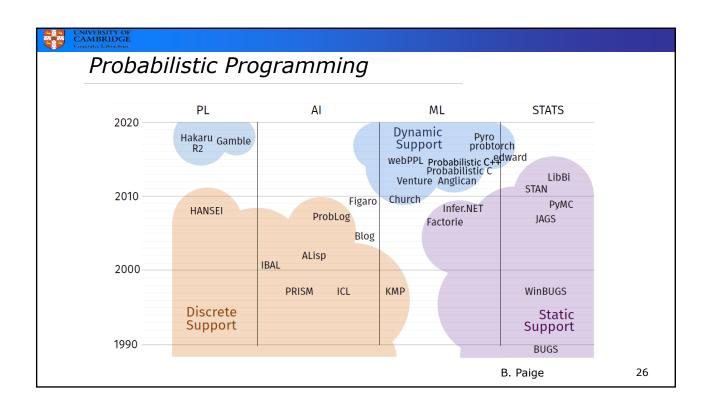
university of CAMBRIDGE Structured Bayesian Optimisation (SBO) Probabilistic Model written in Probabilistic C++ Gaussi Process del(int ygs, int sr, int mtt)(
lculate the size of the heap regions
e es = ygs \* sr / (sr + 2.0);/ Eden space's si
e ss = ygs / (sr + 2.0); // Survivor space' (1)Configuration Probabilistic Predicted Program\* Space Performance 2 Developer-specified. Objective Performance & **Function** Runtime properties model of performance from observed performance + arbitrary Better convergence runtime characteristics Use all measurements **BOAT:** a framework to build **B**esp**O**ke **A**uto-**T**uners 24

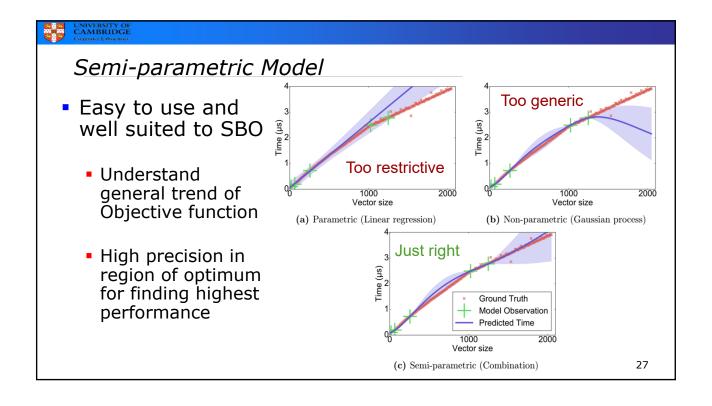


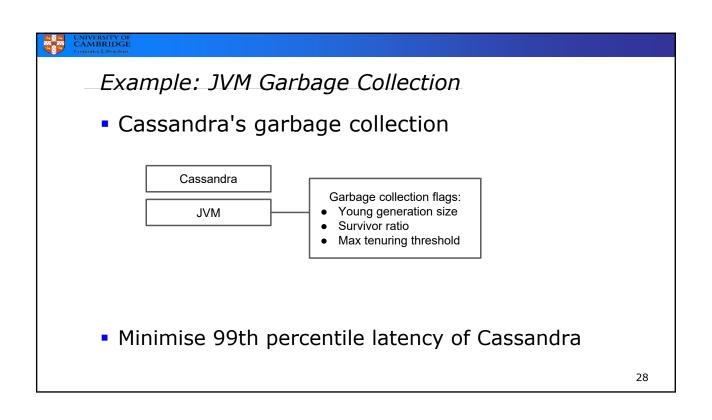
#### Probabilistic Model

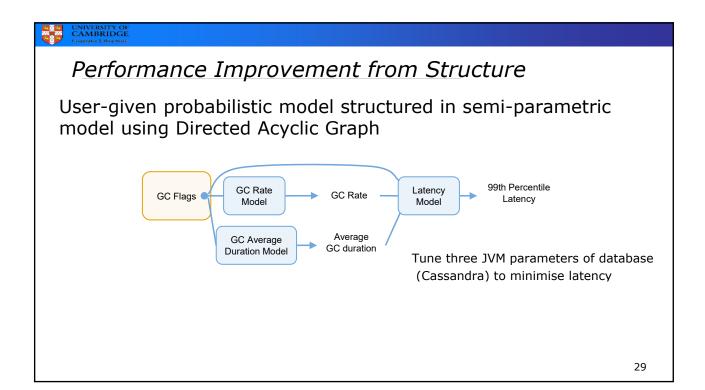
- Probabilistic models incorporate random variables and probability distributions into the model
  - Deterministic model gives a single possible outcome
  - Probabilistic model gives a probability distribution
- Used for various probabilistic logic inference (e.g. MCMCbased inference, Bayesian inference...)

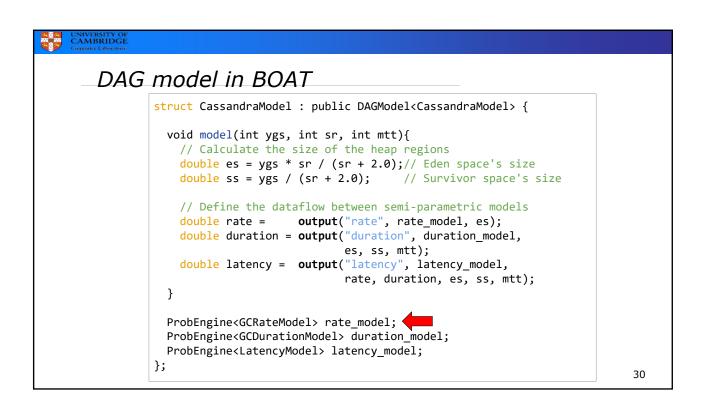
Tutorial: Session 5 - Guest Lecture by Brooks Paige











```
GC Rate Semi-parametric model

struct GCRateModel: public SemiParametricModel<GCRateModel> {

GCRateModel() {

allocated_mbs_per_sec =

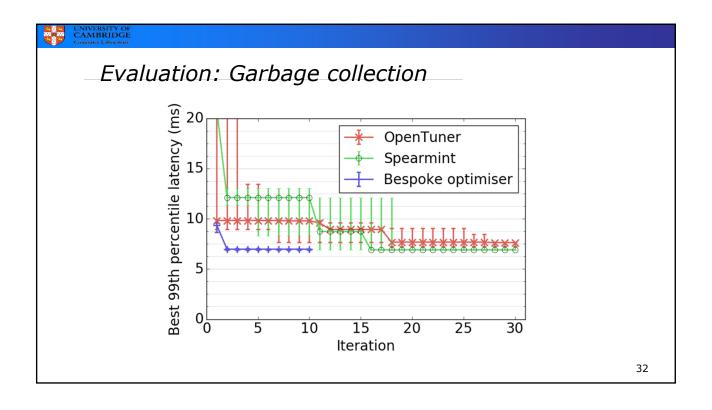
std::uniform_real_distribution<>(0.0, 5000.0)(generator);

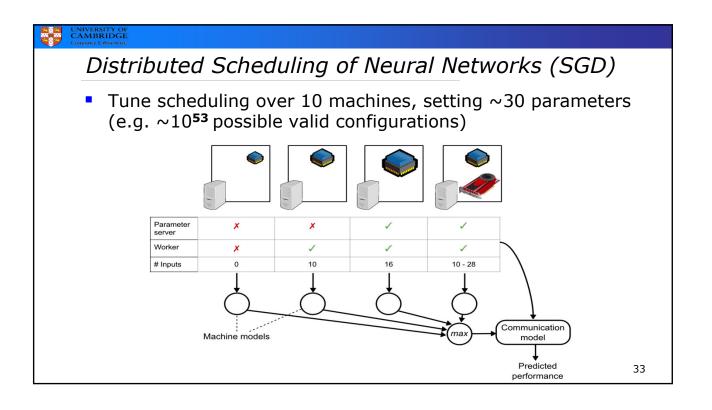
// set the GP parameters here
}

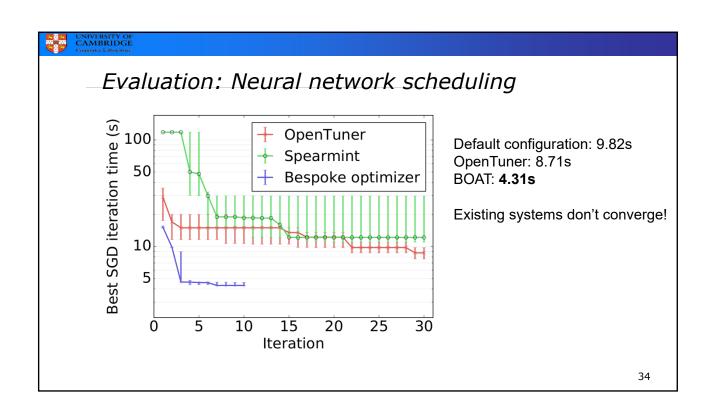
double parametric(double eden_size) const {

// Model the rate as inversely proportional to Eden's size return allocated_mbs_per_sec / eden_size;
}

double allocated_mbs_per_sec;
};
```









# Auto-Tuning

- Manual Tuning
  - User to learn expert knowledge and not transferable
  - e.g. Ottertune (manually selects limited number of parameters then use BO)
- Automated Tuning
  - Divide-and-diverge sampling to explore the configuration space
  - Use of Gaussian processes, but it struggles to make accurate performance predictions because of high dimensionality

#### → Generic Auto-Tuning with DAG models

- Use of DAG models for surrogate model, which mitigates the curse of dimensionality while also retaining all configurable variables
- Exploit data analysis to identify parameter dependencies
- Automatic building of DAG models: use of Bayesian Networks

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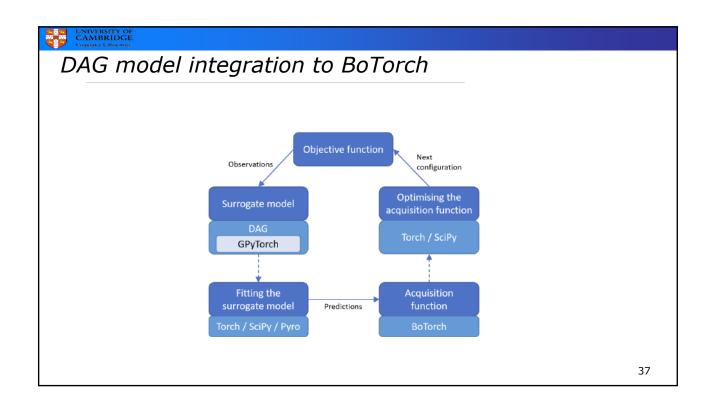


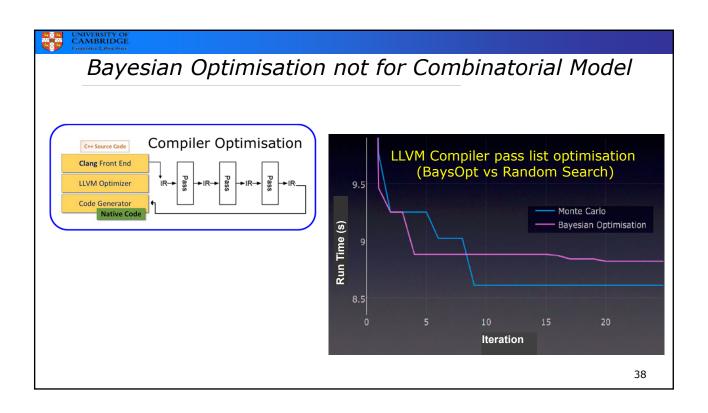
# Surrogate Model in Bayesian Optimisation

Table 2.1: Comparison of surrogate models for BO

Model	Advantages	Disadvantassa
Model	Advantages	Disadvantages
Parametric models	$\bullet$ Quickly fit long-distance trends	
Gaussian pro- cesses	Expressive	
	• Flexible	• Continuous, non-hierarchical configuration space only
Tree-Parzen estimators	$ \begin{array}{ll} \bullet & \text{Fitting is } O(n) \text{ in train-data} \\ \text{size} \\ \bullet & \text{Categorical and hierarchical} \\ \text{configuration space supported} \end{array} $	• Less sample efficient than GP
Random forests	<ul> <li>Computationally very cheap</li> <li>Categorical and hierarchical configuration space supported</li> </ul>	$\bullet$ Inaccurately extrapolates uncertainty

Structural information (e.g. DAG model) improves Optimisation.







# Reinforcement Learning in Computer Systems

- Agent interacts with Dynamic environment
- Goal: Maximise expectations over rewards in agent's lifetime
- Notion of Planning/Control, not single static configuration

#### What makes RL different from other ML paradigms?

- There is no supervisor, only a reward signal
- Feedback is delayed, not instantaneous
- Time really matters (sequential)
- Agent's actions affect the subsequent data it receives

#### **Practical Consideration:**

- Action spaces do not scale
- Exploration in production system not a good idea
- Simulations can oversimplify problem (Expensive to build)
- Online steps take too long

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Action

Agent

Environment

State +

∑ Reward



# Reinforcement Learning for Optimisation

Many problems in systems are sequential decision making and/or combinatorial problems

- Compiler Optimisation
- Chip placement
- Datacentre resource allocation
- Network congestion control with multiple connections
- Wide range of signals to make decisions (e.g., VM allocation)
- Database: Query optimiser, Dynamic indexing...



# A brief history of Deep Reinforcement Learning Tools

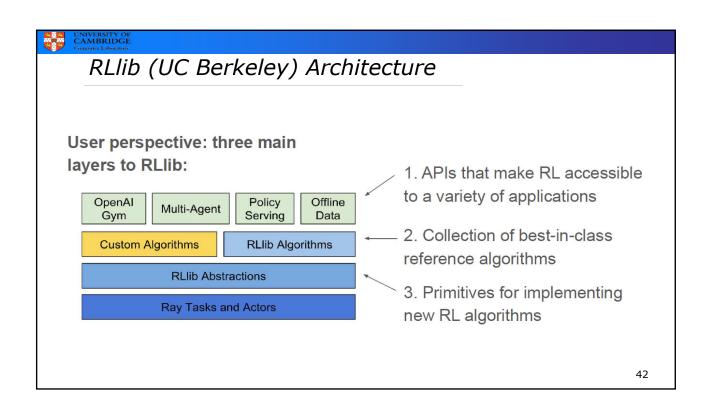
**Gen (2014-16):** Loose research scripts (e.g. DQN), high expertise required, only specific simulators

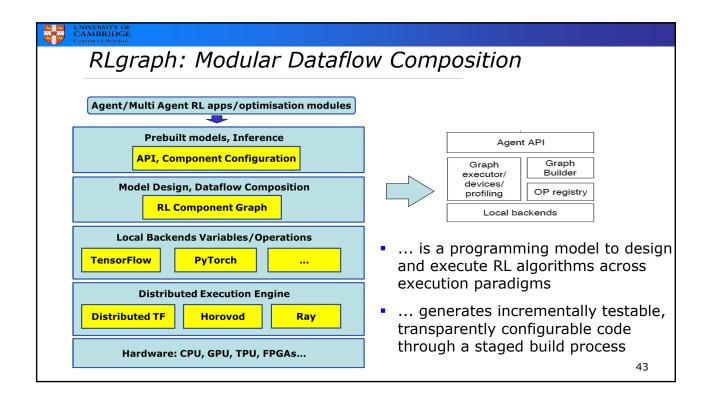
**Gen (2016-17):** OpenAI gym gives unified task interface, reference implementations

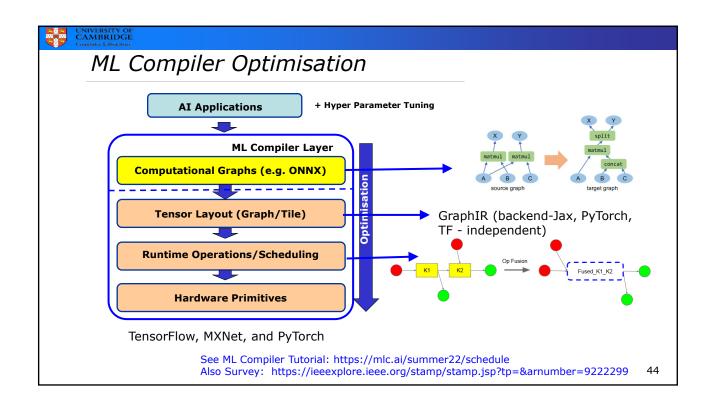
- Good results on some environments (e.g. game), difficult to retool to new domains and execution modes
- Abstractions/Libraries: not fully reusable, customised towards game simulators
- High implementation risk: lack of systematic testing, performance strongly impacted by noisy heuristics

**Gen (2017-18):** Generic declarative APIs, distributed abstractions (Ray Rllib, RLGraph), some standard *flavours* emerge

**Still Problems...** Tightly coupled execution/logic, testing, reuse...



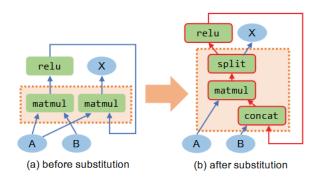






# Optimising DNN Computation with Graph Substitutions

- TASO (SOSP, 2019): Performance improvement by transformation of computation graphs
- PET (OSDI, 2021): Optimizing Tensor Programs with Partially Equivalent Transformations and Automated Corrections
- Equality Saturation for Tensor Graph Superoptimization (MLSys 2021)

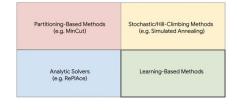


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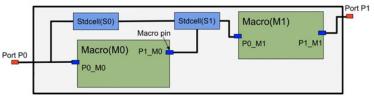
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#### Chip Placement with Reinforcement Learning

 A. Mirhoseini and A. Goldie: A graph placement methodology for fast chip design, Nature, 2021.



- A form of graph resource optimization
- Place the chip components to minimize the latency of computation, power consumption, chip area and cost, while adhering to constraints, such as congestion, cell utilization, heat profile, etc.





# Summary: Massive Data Processing and Optimisation

- → Dataflow is key element used in optimisation
- → Parameter space is complex, large and dynamic/combinatorial
- Systems are nonlinear and difficult to model manually → Exploit ML
- Reinforcement Learning to optimise dynamic combinatorial problem
- Key concept behind is Dataflow (~=Computational Graph) structural transformation/Decomposition
- → Exploit structural information for model decomposition to accelerate optimisation process and/or transform the structure
- → Bayesian Optimisation and Reinforcement Learning are key

