

A Lightweight Graph Processing Framework for Shared Memory

What's it hoping to achieve?

1. A simple, concise framework

2. High-performance for shared-memory machines



 \rightarrow An abundance of graph processing applications

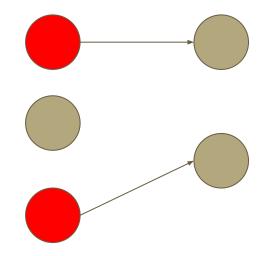
Problems with other, contemporary, graph processing applications:

- 1. Focus on the distributed case which is often
 - a. less efficient per core, per dollar, per watt, etc.
 - b. more complex
 - c. examples: Boost Graph Library, Pregel, Pegasus, PowerGraph, Knowledge Discovery Toolkit

Relevant Work: Beamer et al's fast, hybrid BFS implementation for shared memory

- 1. Combines a :

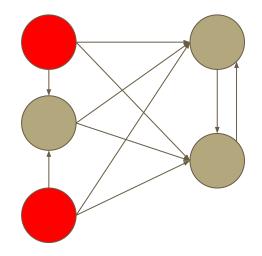
b. bottom-up approach *← dense frontiers*



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b. bottom-up approach *← dense frontiers*



Ligra

A new framework based on Beamer et al's work

Extends Beamer et al's idea of a hybrid system to more graphing applications in order to create a lightweight framework for shared memory.

A *novel* framework

Datatypes:

- 1. G = (V, E) (or G = (V, E, w(E)))
- 2. vertexSubsets : (U \subseteq V)

Functions:

- 1. **vertexMap**(U : vertexSubset, F : vertex \rightarrow bool) : vertexSubset
- 2. **edgeMap**(G : graph, U : vertexSubset, F : (vertex x vertex) \rightarrow bool, C : vertex \rightarrow bool) : vertexSubset)

Ligra: Hybridization

SPARSE:

- \rightarrow **vertices:** [0,2,3] or [3,2,0]
- \rightarrow edgeMapSparse
 - F(u,ngh) ∀ ngh ∈ neighbours
 (u)
 - $\propto |U| + \sum outdegrees(U)$

DENSE:

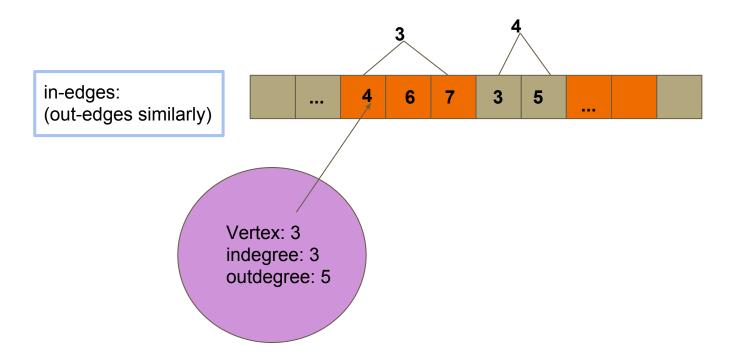
 \rightarrow **vertices**: [1,0,1,1,0,0,0,0]

$\rightarrow edgeMapDense$

- F(ngh,v) \forall ngh \in neighbours (v) where v \in U
- $\infty d |V|$

 \rightarrow Switch on $|U| + \sum outdegrees(U) > |E|/20$

Ligra: Graph Representation



An Example: BFS

Parents = {-1, ..., -1}

procedure Update(s,d)

```
return (CAS(&Parents[d],-1,s))
```

procedure Cond(i)

```
return (Parents[i] == -1)
```

procedure BFS(G,r)

```
Parents[r] = r Frontier = {r}
```

while (size(Frontier) != 0) do Frontier = edgeMap(G,Frontier,Update,Cond)

An Example: Connected Components

Algorithm 8 Connected Components 1: IDs = $\{0, \ldots, |V| - 1\}$ \triangleright initialized such that IDs[i] = i2: prevIDs = $\{0, \ldots, |V| - 1\}$ \triangleright initialized such that prevIDs[i] = i3: 4: procedure CCUPDATE(s, d) 5: origID = IDs[d]if (WRITEMIN(&IDs[d], IDs[s])) then 6: 7: **return** (origID == prevIDs[d]) return 0 8: 9: 10: procedure COPY(i) prevIDs[i] = IDs[i]11: 12: return 1 13: 14: procedure CC(G)Frontier = $\{0, ..., |V| - 1\}$ 15: \triangleright vertexSubset initialized to V 16: while (SIZE(Frontier) $\neq 0$) do Frontier = VERTEXMAP(Frontier, COPY)17: 18: Frontier = EDGEMAP(G, Frontier, CCUPDATE, C_{true}) 19: return IDs

Evaluation & Experiments

Algorithms:

- 1. Bellman-Ford
- 2. PageRank
- 3. CC, Graph Radii
- 4. Betweenness Centrality
- 5. Breadth-First Search

Datasets:

- 1. 3D-grid
- 2. random-local
- 3. rMat24, rMat27
- 4. Twitter, Yahoo

10-39x

speedup from using Ligra on a range of algorithms

Comparative Evaluation

1. Betweeness Centrality

- **a. KDT:** can traverse ~¹/₅ the number of edges as Ligra but on a graph that is smaller
- *b. problem*: KDT uses a batch processing system

2. PageRank

- **a. GPS**: running time of 1.44 min/iteration whereas **Ligra**: takes 20sec/iteration on a larger graph
- **b. Powergraph**: running time of 3.6 sec/iterations vs **Ligra**: 2.91 sec/iteration

3. Connected-Components

a. Pegasus: running time of 10min/6iterations vs **Ligra**: 10 seconds/6iterations

Problems with Evaluation

1. Comparing *similar* graphs on *similar problems*

2. The dramatic improvements are a bit suspect -- XStream paper

 Is improvement based on clever use of a poorly implemented language (e. g. the authors know lots about the programming language -- but what about the average user)?

Strengths & Weaknesses

Strengths:

• simple idea/easy to use

• can get impressive speedups

Weaknesses:

• Narrow optimisation

• Inconsistent evaluation

• Are the assumptions valid?



1. We can use a hybridization method for some optimisations

2. A focus on shared-memory