

Massive Graph Triangulation

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Takeaway Messages

- ▶ Triangle listing important input for graph properties
- ▶ I/O becomes bottleneck for massive graphs
 - ▶ Obvious approach doesn't work
- ▶ MGT algorithm
 - ▶ Total order of vertices guarantees unique triangle orientation
 - ▶ Near optimal asymptotic I/O + CPU performance
 - ▶ Much faster than alternatives in practice

Definition

Given a graph $G = (V, E)$, list exactly once all
 $\Delta_{v_1 v_2 v_3} = \{v_1, v_2, v_3\}$ such that $v_i \in V$ and $(v_i, v_j) \in E$

Motivation

- ▶ Triangle = shortest non-trivial cycle and clique
- ▶ Various metrics
 - ▶ Dense neighborhood discovery
 - ▶ Triangular connectivity
 - ▶ k -truss
 - ▶ Clustering coefficient

The Algorithm

```
procedure LIST( $G$ )
     $\Delta(G) \leftarrow \emptyset$ 
    loop  $u \in V$ 
        loop  $v \in adj_G(u)$  &  $v > u$ 
            loop  $w \in adj_G(u) \cap adj_G(v)$  &  $w > v$ 
                 $\Delta(G) \leftarrow \Delta(G) \cup \{\Delta_{uvw}\}$ 
    return  $\Delta(G)$ 
```

The Problem

- ▶ Random access to $adj_G(v)$ for $v \in adj_G(u)$
- ▶ $\mathcal{O}(|E| \cdot scan(d_{max}))$ I/Os in the worst case
 - ▶ When it doesn't fit in the memory of size M
 - ▶ Recall: $scan(N) = \Theta(N/B)$ where B is the disk block size

Previous Approaches

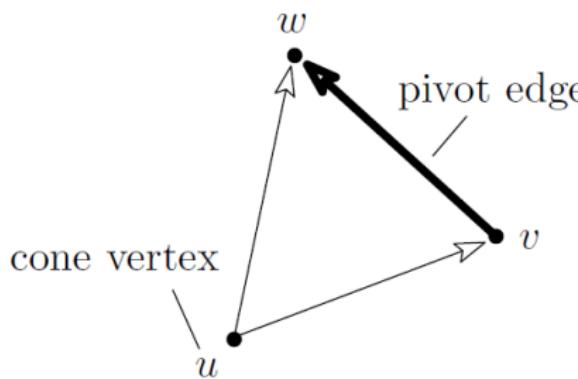
- ▶ External Memory Compact Forward (EM-CF)
 - ▶ $\mathcal{O}(|E| + |E|^{1.5}/B)$ I/Os
 - ▶ $|E|$ I/O reads
 - ▶ Output insensitive
- ▶ External Memory Node Iterator (EM-NI)
 - ▶ $\mathcal{O}\left(|E|^{1.5}/B \cdot \log_{M/B}(|E|/B)\right)$ I/Os
 - ▶ Almost insensitive to M
 - ▶ Output insensitive
- ▶ Graph Partition [CC12]
 - ▶ $\mathcal{O}(|E|^2/(MB) + K/B)$ I/Os where K triangles
 - ▶ In practice, $M > \sqrt{|E|}$
 - ▶ If $M = c|E|$, asymptotically optimal
 - ▶ But under a set of assumptions...

This Approach

- ▶ $\mathcal{O}(|E|^2/(MB) + K/B)$ I/Os in all settings
- ▶ $\mathcal{O}(|E| \log |E| + |E|^2/M + \alpha|E|)$ CPU time
 - ▶ α is the arboricity of the graph
- ▶ Both optimal up to constants
- ▶ Key idea: total order for unique triangle orientation
- ▶ Side note: also improves analysis of previous work

Defining G^*

- ▶ Define \prec on V by $u \prec v$ iff
 - ▶ $d(u) < d(v)$ or $d(u) = d(v)$ and $id(u) < id(v)$
 - ▶ Is a total order
- ▶ G^* is G with edges oriented by \prec
 - ▶ Takes $\mathcal{O}(\text{sort}(|E|))$ I/Os
 - ▶ Recall: $\text{sort}(N) = \Theta(N/B \log_{M/B} N/B)$
- ▶ Every triangle $\{u, v, w\}$ has unique orientation $u \prec v \prec w$



Initial Idea

1. Load next cM edges of G^* into memory (E_{mem})
 - ▶ All-or-nothing requirement (small-degree assumption)
2. Find all triangle with pivot edges in E_{mem}

The Algorithm

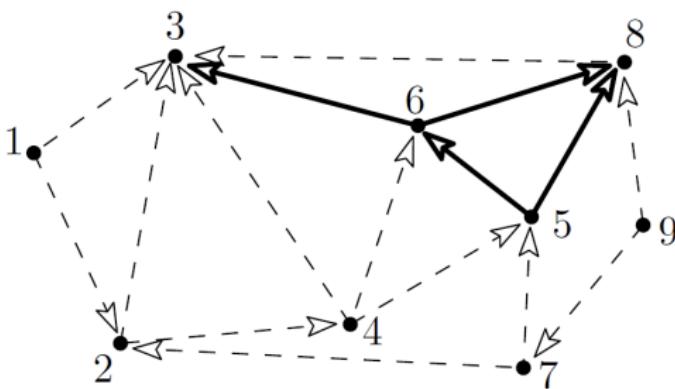
Step 2 (Initial)

```
procedure LIST( $G, E_{mem}$ )
```

```
loop  $u \in V$ 
```

```
 $V_{mem}(u) \leftarrow N^+(u) \cap V_{mem}$ 
```

```
Find triangles with  $u$  cone in  $E_{mem}(u) \cup E_{mem}$ 
```



Step 2 (Details)

procedure LIST(G^*, E_{mem})

 Build hash structures

loop $u \in V$

$V_{mem}(u) \leftarrow N^+(u) \cap V_{mem}$

loop $v \in V_{mem}^+(u)$

loop $w \in V_{mem}(u)$

if $v \neq w \text{ & } (v, w) \in E_{mem}$ **then**

 Output Δ_{uvw}

Analysis

- ▶ $\mathcal{O}(|E|^2/(MB) + K/B)$ I/O
 - ▶ $\Theta(|E|/M)$ iterations
 - ▶ $\mathcal{O}(|E|/B)$ I/Os for scanning
 - ▶ $\mathcal{O}(K/B)$ for listing
- ▶ $\mathcal{O}(|E| \log |E| + |E|^2/M + \alpha|E|)$ CPU
 - ▶ $\mathcal{O}(|E| \log |E|)$ for G^* sorting
 - ▶ $\Theta(|E|/M)$ iterations
 - ▶ $\mathcal{O}(|N^+(u)| + |N^+(u)| \cdot |V_{mem}^+(u)|)$
 - ▶ $\sum |N^+(u)| = |E|$
 - ▶ $\sum_{v \in V} d^+(v)^2 = \mathcal{O}(\alpha|E|)$
- ▶ Optimality comes from considering the complete graph

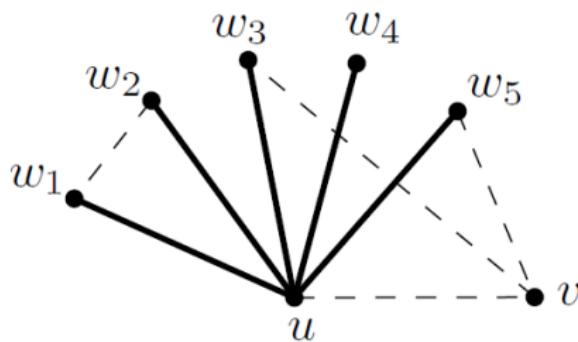
Small-Degree Assumption

- ▶ What if $\exists v$ such that $d^+(v) > cM/2$?
 1. Find one
 2. Load a set S of $cM/2$ of its out-edges
 3. Report all triangles involving one of the edges in S
 4. Remove S from the graph
 5. Repeat

Small-Degree Assumption

- ▶ How to implement step 3

- ▶ Create hash table of loaded vertices
- ▶ Scan all $|E|$ edges
- ▶ Also scan $N(v)$ for each $v \neq u$ with $u \in N(v)$
- ▶ Does not change complexity

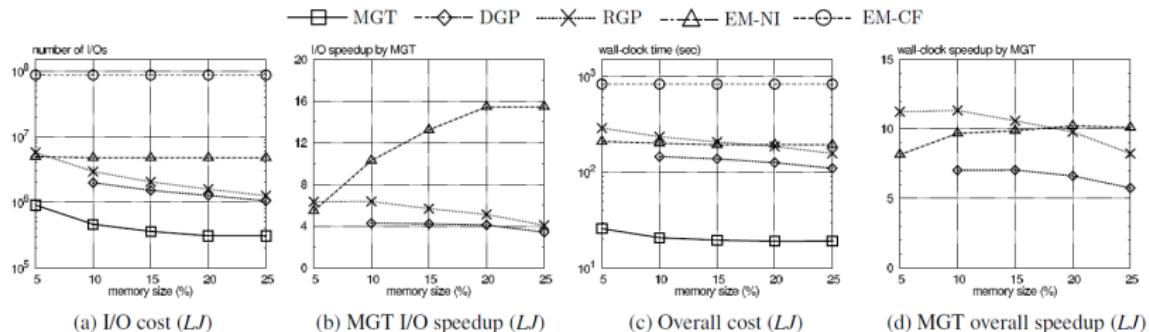


Experimental Setup

- ▶ 8GB memory (but memory conscious)
- ▶ Graphs unoriented
- ▶ Real data
 - ▶ 364MB to 7.5GB
 - ▶ 4.8 to 165 million vertices
 - ▶ 28 to 938 million edges
 - ▶ $|E|/|V|$ from 1.2 to 15.1
 - ▶ Varied M from 5% to 25% of disk size
- ▶ Synthetic data
 - ▶ Random, Recursive Matrix, Small World
 - ▶ $m = 16n$, n from 16 to 80 million
 - ▶ 2.1GB to 10.6GB

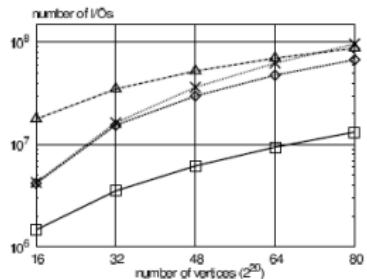
Real Data

- ▶ MGT always better for CPU
- ▶ MGT almost always better for I/O
- ▶ RGP higher hidden constant in complexity!

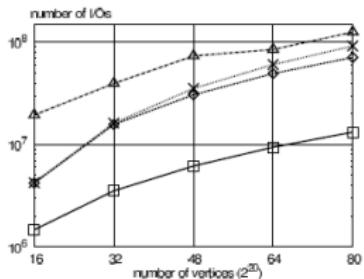


Evaluation

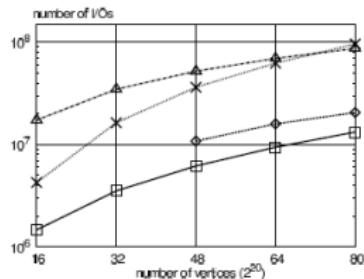
—□— MGT -◇- DGP ×--- RGP ▲--- EM-NI



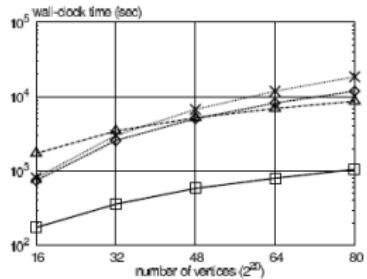
(a) I/O cost (RAND)



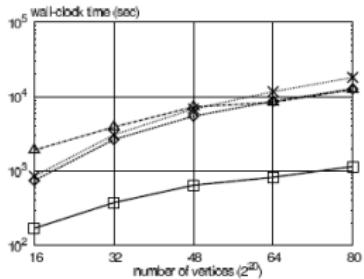
(b) I/O cost (R-MAT)



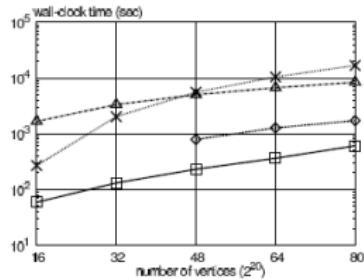
(c) I/O cost (S-WORLD)



(d) Overall cost (RAND)



(e) Overall cost (R-MAT)



(f) Overall cost (S-WORLD)

Criticism

- ▶ I/O analysis excludes cost of sorting
- ▶ Algorithm does not exploit parallelism
 - ▶ Is inherently sequential
 - ▶ Not applicable to distributed environment
 - ▶ Or across cores
 - ▶ RGP ideas applied in this case [PC13]
- ▶ Block I/O model for SSDs and parallel environment?
- ▶ Behavior for large-degree vertices
- ▶ Experiments lacking when M bigger percentage of graph

Key Insights

- ▶ Total order of vertices guarantees unique triangle orientation
- ▶ Key idea simple, but multiple tricks
- ▶ Near optimal asymptotic I/O + CPU performance
- ▶ Much faster than alternatives in practice

Key Questions

- ▶ Can you parallelize the algorithms non-trivially on a single PC?
- ▶ How can you extend the I/O model to different environments?
- ▶ How can you minimize data transfers in a distr. environment?
- ▶ Your questions?

Bibliography I

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