

Nominal Sets

Andrew Pitts



Mathematics of syntax

- ▶ Seems of little interest to mathematicians and of only slight interest to logicians. (?)
- ▶ Vital for computer science — because of *symbolic computation* and *automated reasoning*.
- ▶ Has yet to reach an intellectual fixed point for syntax involving scope, binding and freshness of **names**.

Nominal sets

- ▶ Mathematical theory of names: **scope**, **binding**, **freshness**.
- ▶ Simple math to do with **properties invariant under permuting names**.
- ▶ Originally introduced by Gabbay & AMP circa 2000, but the math goes back to 1930's set theory & logic (Fraenkel & Mostowski).

Nominal sets

- ▶ Mathematical theory of names: scope, binding, freshness.
- ▶ Simple math to do with properties invariant under permuting names.
- ▶ Originally introduced by Gabbay & AMP circa 2000, but the math goes back to 1930's set theory & logic (Fraenkel & Mostowski).
- ▶ Applications: theorem-proving tools for **PL semantics**; metaprogramming (within functional programming, mainly); verification.

Outline

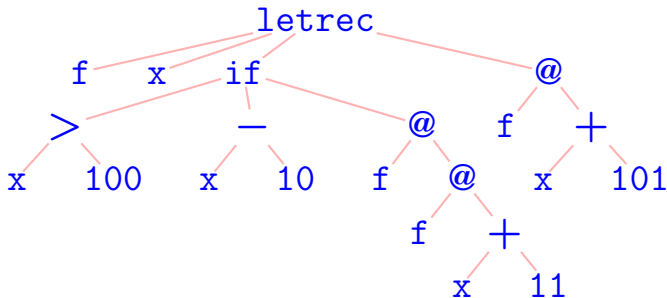
- ▶ **Lecture 1.** Structural recursion and induction in the presence of name-binding operations.
- ▶ **Lecture 2.** Introducing the category of nominal sets.
[Notes, chapters 1–3 +exercises]
- ▶ **Lecture 3.** Nominal algebraic data types and α -structural recursion.
[Notes, chapters 4–5 +exercises]
- ▶ **Lecture 4.** Simply typed λ -calculus with local names and name-abstraction.
[www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

Lecture 1

For semantics, concrete syntax

```
letrec f x = if x > 100 then x - 10
else f ( f ( x + 11 ) ) in f ( x + 100 )
```

is unimportant compared to **abstract syntax** (ASTs):



We should aim for **compositional semantics** of program constructions, rather than of whole programs. (Why?)

ASTs enable two fundamental (and inter-linked) tools in programming language semantics:

- ▶ Definition of functions on syntax by **recursion on its structure**.
- ▶ Proof of properties of syntax by **induction on its structure**.

Structural recursion

Recursive definitions of functions whose values at a *structure* are given functions of their values at *immediate substructures*.

- ▶ Gödel System T (1958):

structure = numbers
structural recursion = primitive recursion for \mathbb{N} .

- ▶ Burstall, Martin-Löf *et al* (1970s) generalized this to ASTs.

Running example

Set of ASTs for λ -terms

$$\mathbf{Tr} \triangleq \{t ::= V a \mid A(t, t) \mid L(a, t)\}$$

where $a \in \mathbb{A}$, fixed infinite set of names of variables.

Operations for constructing these ASTs:

$$V : \mathbb{A} \rightarrow \mathbf{Tr}$$

$$A : \mathbf{Tr} \times \mathbf{Tr} \rightarrow \mathbf{Tr}$$

$$L : \mathbb{A} \times \mathbf{Tr} \rightarrow \mathbf{Tr}$$

Structural recursion for Tr

Theorem.

$$\begin{array}{l} \text{Given} \\ f_1 \in \mathbb{A} \rightarrow X \\ f_2 \in X \times X \rightarrow X \\ f_3 \in \mathbb{A} \times X \rightarrow X \end{array}$$

exists unique $\hat{f} \in Tr \rightarrow X$ satisfying

$$\begin{aligned} \hat{f}(\vee a) &= f_1 a \\ \hat{f}(A(t, t')) &= f_2(\hat{f} t, \hat{f} t') \\ \hat{f}(L(a, t)) &= f_3(a, \hat{f} t) \end{aligned}$$

Structural recursion for Tr

E.g. the finite set $\mathbf{var} t$ of variables occurring in $t \in Tr$:

$$\begin{aligned}\mathbf{var}(\forall a) &= \{a\} \\ \mathbf{var}(A(t, t')) &= (\mathbf{var} t) \cup (\mathbf{var} t') \\ \mathbf{var}(L(a, t)) &= (\mathbf{var} t) \cup \{a\}\end{aligned}$$

is defined by structural recursion using

- ▶ $X = \mathbf{P}_f(\mathbb{A})$ (finite sets of variables)
- ▶ $f_1 a = \{a\}$
- ▶ $f_2(S, S') = S \cup S'$
- ▶ $f_3(a, S) = S \cup \{a\}$.

Structural recursion for Tr

E.g. swapping: $(a\ b) \cdot t =$ result of transposing all occurrences of a and b in t

For example

$$(a\ b) \cdot L(a, A(V\ b, V\ c)) = L(b, A(V\ a, V\ c))$$

Structural recursion for Tr

E.g. swapping: $(a\ b) \cdot t =$ result of transposing all occurrences of a and b in t

$$(a\ b) \cdot \forall c = \text{if } c = a \text{ then } \forall b \text{ else} \\ \text{if } c = b \text{ then } \forall a \text{ else } \forall c$$

$$(a\ b) \cdot A(t, t') = A((a\ b) \cdot t, (a\ b) \cdot t')$$

$$(a\ b) \cdot L(c, t) = \text{if } c = a \text{ then } L(b, (a\ b) \cdot t) \\ \text{else if } c = b \text{ then } L(a, (a\ b) \cdot t) \\ \text{else } L(c, (a\ b) \cdot t)$$

is defined by structural recursion using. . .

Structural recursion for Tr

Theorem.

$$\begin{array}{l} \text{Given} \\ f_1 \in \mathbb{A} \rightarrow X \\ f_2 \in X \times X \rightarrow X \\ f_3 \in \mathbb{A} \times X \rightarrow X \end{array}$$

exists unique $\hat{f} \in Tr \rightarrow X$ satisfying

$$\begin{aligned} \hat{f}(\vee a) &= f_1 a \\ \hat{f}(A(t, t')) &= f_2(\hat{f} t, \hat{f} t') \\ \hat{f}(L(a, t)) &= f_3(a, \hat{f} t) \end{aligned}$$

Structural recursion for Tr

Theorem.

Given $f_1 \in A \rightarrow X$
 $f_2 \in X \times X \rightarrow X$
 $f_3 \in X \times A \rightarrow X$

exists unique $\hat{a} : A \rightarrow X$ satisfying

$$\begin{aligned} \hat{a} a &= f_1 a \\ \hat{a} (L(a, t)) &= f_2(\hat{a} t, \hat{a} t') \\ \hat{a} (R(a, t)) &= f_3(a, \hat{a} t) \end{aligned}$$

Doesn't take binding into account!

Alpha-equivalence

Smallest binary relation $=_\alpha$ on Tr closed under the rules:

$$\frac{a \in \mathbb{A}}{\forall a =_\alpha \forall a} \quad \frac{t_1 =_\alpha t'_1 \quad t_2 =_\alpha t'_2}{A(t_1, t_2) =_\alpha A(t'_1, t'_2)}$$

$$\frac{(a \ b) \cdot t =_\alpha (a' \ b) \cdot t' \quad b \notin \{a, a'\} \cup \text{var}(t \ t')}{L(a, t) =_\alpha L(a', t')}$$

E.g. $A(L(a, A(\forall a, \forall b))), \forall c) =_\alpha A(L(c, A(\forall c, \forall b))), \forall c)$
 $\neq_\alpha A(L(b, A(\forall b, \forall b))), \forall c)$

Fact: $=_\alpha$ is transitive (and reflexive & symmetric).

ASTs mod alpha equivalence

Dealing with issues to do with **binders** and **alpha equivalence** is

- ▶ pervasive (very many languages involve binding operations)
- ▶ difficult to formalise/mechanise without losing sight of common informal practice:

ASTs mod alpha equivalence

Dealing with issues to do with **binders** and **alpha equivalence** is

- ▶ pervasive (very many languages involve binding operations)
- ▶ difficult to formalise/mechanise without losing sight of common informal practice:

“We identify expressions up to alpha-equivalence” . . .

ASTs mod alpha equivalence

Dealing with issues to do with **binders** and **alpha equivalence** is

- ▶ pervasive (very many languages involve binding operations)
- ▶ difficult to formalise/mechanise without losing sight of common informal practice:

“We identify expressions up to alpha-equivalence” . . .
. . . and then forget about it, referring to
alpha-equivalence classes $[t]_{\alpha}$ only via representatives t .

ASTs mod alpha equivalence

Dealing with issues to do with **binders** and **alpha equivalence** is

- ▶ pervasive (very many languages involve binding operations)
- ▶ difficult to formalise/mechanise without losing sight of common informal practice:

E.g. notation for λ -terms:

$$\Lambda \triangleq \{[t]_\alpha \mid t \in Tr\}$$

a	means	$[V a]_\alpha$ ($= \{V a\}$)
$e e'$	means	$[A(t, t')]_\alpha$, where $e = [t]_\alpha$ and $e' = [t']_\alpha$
$\lambda a.e$	means	$[L(a, t)]_\alpha$ where $e = [t]_\alpha$

Informal structural recursion

E.g. capture-avoiding substitution:

$$f = (-)[e_1/a_1] : \Lambda \rightarrow \Lambda$$

$$f a = \text{if } a = a_1 \text{ then } e_1 \text{ else } a$$

$$f (e e') = (f e) (f e')$$

$$f(\lambda a. e) = \text{if } a \notin \text{fv}(a_1, e_1) \text{ then } \lambda a. (f e) \\ \text{else don't care!}$$

Not an instance of structural recursion for **Tr**.

Why is f well-defined and total?

Informal structural recursion

E.g. denotation of λ -term in a **suitable** domain D :

$$\llbracket - \rrbracket : \Lambda \rightarrow ((A \rightarrow D) \rightarrow D)$$

$$\llbracket a \rrbracket \rho = \rho a$$

$$\llbracket e e' \rrbracket \rho = \text{app}(\llbracket e \rrbracket \rho, \llbracket e' \rrbracket \rho)$$

$$\llbracket \lambda a. e \rrbracket \rho = \text{fun}(\lambda(d \in D) \rightarrow \llbracket e \rrbracket (\rho[a \rightarrow d]))$$

where $\begin{cases} \text{app} \in D \times D \rightarrow_{cts} D \\ \text{fun} \in (D \rightarrow_{cts} D) \rightarrow_{cts} D \end{cases}$
are continuous functions satisfying...

Informal structural recursion

E.g. denotation of λ -term in a suitable domain D :

$$\llbracket - \rrbracket : \Lambda \rightarrow ((A \rightarrow D) \rightarrow D)$$

$$\llbracket a \rrbracket \rho = \rho a$$

$$\llbracket e e' \rrbracket \rho = \text{app}(\llbracket e \rrbracket \rho, \llbracket e' \rrbracket \rho)$$

$$\llbracket \lambda a. e \rrbracket \rho = \text{fun}(\lambda(d \in D) \rightarrow \llbracket e \rrbracket (\rho[a \rightarrow d]))$$

why is this very standard
definition independent of the
choice of bound variable a ?

Is there a recursion principle for Λ that legitimises these
'definitions' of $(-)[e_1/a_1] : \Lambda \rightarrow \Lambda$ and $\llbracket - \rrbracket : \Lambda \rightarrow \mathcal{D}$
(and many other e.g.s)?

Is there a recursion principle for Λ that legitimises these
'definitions' of $(-)[e_1/a_1] : \Lambda \rightarrow \Lambda$ and $\llbracket - \rrbracket : \Lambda \rightarrow \mathcal{D}$
(and many other e.g.s)?

Yes! — α -structural recursion.

Is there a recursion principle for Λ that legitimises these 'definitions' of $(-)[e_1/a_1] : \Lambda \rightarrow \Lambda$ and $\llbracket - \rrbracket : \Lambda \rightarrow \mathcal{D}$ (and many other e.g.s)?

Yes! — α -structural recursion.

What about other languages with binders?

Is there a recursion principle for Λ that legitimises these 'definitions' of $(-)[e_1/a_1] : \Lambda \rightarrow \Lambda$ and $\llbracket - \rrbracket : \Lambda \rightarrow D$ (and many other e.g.s)?

Yes! — α -structural recursion.

What about other languages with binders?

Yes! — available for any nominal signature.

Is there a recursion principle for Λ that legitimises these 'definitions' of $(-)[e_1/a_1] : \Lambda \rightarrow \Lambda$ and $\llbracket - \rrbracket : \Lambda \rightarrow D$ (and many other e.g.s)?

Yes! — α -structural recursion.

What about other languages with binders?

Yes! — available for any nominal signature.

Great. What's the catch?

Is there a recursion principle for Λ that legitimises these 'definitions' of $(-)[e_1/a_1] : \Lambda \rightarrow \Lambda$ and $\llbracket - \rrbracket : \Lambda \rightarrow D$ (and many other e.g.s)?

Yes! — α -structural recursion.

What about other languages with binders?

Yes! — available for any nominal signature.

Great. What's the catch?

Need to learn a bit of possibly unfamiliar math, to do with permutations and support.

Lecture 2

Outline

- ▶ **Lecture 1.** Structural recursion and induction in the presence of name-binding operations.
- ▶ **Lecture 2.** Introducing the category of nominal sets.

[Notes, chapters 1–3 +exercises]

- ▶ **Lecture 3.** Nominal algebraic data types and α -structural recursion.

[Notes, chapters 4–5 +exercises]

- ▶ **Lecture 4.** Simply typed λ -calculus with local names and name-abstraction.

[www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

Preliminaries on name-permutations

- ▶ A = fixed countably infinite set of names (a, b, \dots)

Preliminaries on name-permutations

- ▶ \mathbb{A} = fixed countably infinite set of names (a, b, \dots)
- ▶ $\text{Perm } \mathbb{A}$ = **group** of **finite** permutations of \mathbb{A}
(π, π', \dots)
 - ▶ π **finite** means: $\{a \in \mathbb{A} \mid \pi(a) \neq a\}$ is finite.
 - ▶ **group**: multiplication is composition of functions $\pi' \circ \pi$; identity is identity function ι .

Preliminaries on name-permutations

- ▶ \mathbb{A} = fixed countably infinite set of names (a, b, \dots)
- ▶ $\text{Perm } \mathbb{A}$ = group of finite permutations of \mathbb{A}
(π, π', \dots)
 - ▶ π finite means: $\{a \in \mathbb{A} \mid \pi(a) \neq a\}$ is finite.
 - ▶ group: multiplication is composition of functions $\pi' \circ \pi$; identity is identity function ι .
- ▶ **swapping**: $(a\ b) \in \text{Perm } \mathbb{A}$ is the function mapping a to b , b to a and fixing all other names.

Fact: every $\pi \in \text{Perm } \mathbb{A}$ is equal to
 $(a_1\ b_1) \circ \dots \circ (a_n\ b_n)$
for some a_i & b_i (with $\pi a_i \neq a_i \neq b_i \neq \pi b_i$).

Preliminaries on name-permutations

- ▶ \mathbb{A} = fixed countably infinite set of names (a, b, \dots)
- ▶ $\text{Perm } \mathbb{A}$ = group of finite permutations of \mathbb{A}
(π, π', \dots)
- ▶ **action** of $\text{Perm } \mathbb{A}$ on a set X is a function

$$(-) \cdot (-) : \text{Perm } \mathbb{A} \times X \rightarrow X$$

satisfying for all $x \in X$

- ▶ $\pi' \cdot (\pi \cdot x) = (\pi' \circ \pi) \cdot x$
- ▶ $\iota \cdot x = x$

Running example

Action of **Perm** \mathbb{A} on set of ASTs for λ -terms

$$Tr \triangleq \{t ::= V a \mid A(t, t) \mid L(a, t)\}$$

$$\begin{aligned}\pi \cdot V a &= V(\pi a) \\ \pi \cdot A(t, t') &= A(\pi \cdot t, \pi \cdot t') \\ \pi \cdot L(a, t) &= L(\pi a, \pi \cdot t)\end{aligned}$$

This respects α -equivalence and so induces an action on set of λ -terms $\Lambda = \{[t]_\alpha \mid t \in Tr\}$:

$$\pi \cdot [t]_\alpha = [\pi \cdot t]_\alpha$$

Nominal sets

are sets X with with a $\text{Perm } \mathbb{A}$ -action satisfying

Finite support property: for each $x \in X$, there is a finite subset $\bar{a} \subseteq \mathbb{A}$ that supports x , in the sense that for all $\pi \in \text{Perm } \mathbb{A}$

$$((\forall a \in \bar{a}) \pi a = a) \Rightarrow \pi \cdot x = x$$

Fact: in a nominal set every $x \in X$ possesses a *smallest* finite support, written $\text{supp } x$.

Nominal sets

are sets X with with a $\text{Perm } \mathbb{A}$ -action satisfying

Finite support property: for each $x \in X$, there is a finite subset $\bar{a} \subseteq \mathbb{A}$ that supports x , in the sense that for all $\pi \in \text{Perm } \mathbb{A}$

$$((\forall a \in \bar{a}) \pi a = a) \Rightarrow \pi \cdot x = x$$

Fact: in a nominal set every $x \in X$ possesses a *smallest* finite support, written $\text{supp } x$.

E.g. Tr and Λ are nominal sets—any \bar{a} containing all the variables occurring (free, binding, or bound) in $t \in \text{Tr}$ supports t and (hence) $[t]_\alpha$.

Fact: for $e \in \Lambda$, $\text{supp } e = \text{fv } e$. (See Notes, p28.)

Further examples of support

[**Perm** \mathbb{A} acts of sets of names $S \subseteq \mathbb{A}$ pointwise:

$$\pi \cdot S \triangleq \{\pi a \mid a \in S\}.$$

What is a support for the following sets of names?

▶ $S_1 \triangleq \{a\}$

▶ $S_2 \triangleq \mathbb{A} - \{a\}$

▶ $S_3 \triangleq \{a_0, a_2, a_4, \dots\}$, where $\mathbb{A} = \{a_0, a_1, a_2, \dots\}$

Further examples of support

[**Perm** \mathbb{A} acts of sets of names $S \subseteq \mathbb{A}$ pointwise:

$$\pi \cdot S \triangleq \{\pi a \mid a \in S\}.$$

What is a support for the following sets of names?

▶ $S_1 \triangleq \{a\}$

Answer: $\{a\}$ is smallest support.

▶ $S_2 \triangleq \mathbb{A} - \{a\}$

▶ $S_3 \triangleq \{a_0, a_2, a_4, \dots\}$, where $\mathbb{A} = \{a_0, a_1, a_2, \dots\}$

Further examples of support

[**Perm** \mathbb{A} acts of sets of names $S \subseteq \mathbb{A}$ pointwise:

$$\pi \cdot S \triangleq \{\pi a \mid a \in S\}.$$

What is a support for the following sets of names?

▶ $S_1 \triangleq \{a\}$

Answer: $\{a\}$ is smallest support.

▶ $S_2 \triangleq \mathbb{A} - \{a\}$

Answer: $\{a\}$ is smallest support.

▶ $S_3 \triangleq \{a_0, a_2, a_4, \dots\}$, where $\mathbb{A} = \{a_0, a_1, a_2, \dots\}$

Further examples of support

[**Perm** \mathbb{A} acts of sets of names $S \subseteq \mathbb{A}$ pointwise:

$$\pi \cdot S \triangleq \{\pi a \mid a \in S\}.$$

What is a support for the following sets of names?

▶ $S_1 \triangleq \{a\}$

Answer: $\{a\}$ is smallest support.

▶ $S_2 \triangleq \mathbb{A} - \{a\}$

Answer: $\{a\}$ is smallest support.

▶ $S_3 \triangleq \{a_0, a_2, a_4, \dots\}$, where $\mathbb{A} = \{a_0, a_1, a_2, \dots\}$

Answer: $\{a_0, a_2, a_4, \dots\}$ is a support

Further examples of support

[Perm \mathbb{A} acts of sets of names $S \subseteq \mathbb{A}$ pointwise:

$$\pi \cdot S \triangleq \{\pi a \mid a \in S\}.$$

What is a support for the following sets of names?

▶ $S_1 \triangleq \{a\}$

Answer: $\{a\}$ is smallest support.

▶ $S_2 \triangleq \mathbb{A} - \{a\}$

Answer: $\{a\}$ is smallest support.

▶ $S_3 \triangleq \{a_0, a_2, a_4, \dots\}$, where $\mathbb{A} = \{a_0, a_1, a_2, \dots\}$

Answer: $\{a_0, a_2, a_4, \dots\}$ is a support, and so is

$\{a_1, a_3, a_5, \dots\}$ —but there is no finite support. S_3 does not exist in the ‘world of nominal sets’—in that world \mathbb{A} is infinite, but not enumerable.

Category of nominal sets, **Nom**

- ▶ objects are nominal sets
- ▶ morphisms are functions $f \in X \rightarrow Y$ that are **equivariant**:

$$\pi \cdot (f x) = f(\pi \cdot x)$$

for all $\pi \in \mathbf{Perm} \mathbb{A}$, $x \in X$.

Category of nominal sets, **Nom**

Fact. **Nom** is equivalent to the **Schanuel topos**, a well-known Grothendieck topos classifying the geometric theory of an infinite decidable object.

So in particular **Nom** is a model of **classical higher-order logic**.

Category of nominal sets, **Nom**

Fact. **Nom** is equivalent to the **Schanuel topos**, a well-known Grothendieck topos classifying the geometric theory of an infinite decidable object.

Finite products: $X_1 \times \cdots \times X_n$ is cartesian product of sets with **Perm** \mathbb{A} -action

$$\pi \cdot (x_1, \dots, x_n) \triangleq (\pi \cdot x_1, \dots, \pi \cdot x_n)$$

which satisfies

$$\text{supp}(x, \dots, x_n) = (\text{supp } x_1) \cup \cdots \cup (\text{supp } x_n)$$

Category of nominal sets, **Nom**

Fact. **Nom** is equivalent to the **Schanuel topos**, a well-known Grothendieck topos classifying the geometric theory of an infinite decidable object.

Coproducts are given by disjoint union.

Natural number object: $\mathbb{N} = \{0, 1, 2, \dots\}$ with trivial **Perm** \mathbb{A} -action: $\pi \cdot n \triangleq n$ (so $\text{supp } n = \emptyset$).

Category of nominal sets, **Nom**

Fact. **Nom** is equivalent to the **Schanuel topos**, a well-known Grothendieck topos classifying the geometric theory of an infinite decidable object.

Exponentials: $X \rightarrow_{\text{fs}} Y$ is the set of functions $f \in Y^X$ that are finitely supported w.r.t. the **Perm A**-action

$$\pi \cdot f \triangleq \lambda(x \in X) \rightarrow \pi \cdot (f(\pi^{-1} \cdot x))$$

(Can be tricky to see when $f \in Y^X$ is in $X \rightarrow_{\text{fs}} Y$.)

Category of nominal sets, **Nom**

Fact. **Nom** is equivalent to the **Schanuel topos**, a well-known Grothendieck topos classifying the geometric theory of an infinite decidable object.

Subobject classifier: $\Omega = \{\text{true}, \text{false}\}$ with trivial **Perm** \mathbb{A} -action: $\pi \cdot b \triangleq b$ (so $\text{supp } b = \emptyset$).

(**Nom** is a Boolean topos: $\Omega = 1 + 1$.)

Power objects: $X \rightarrow_{\text{fs}} \Omega \cong \mathbf{P}_{\text{fs}} X$, the set of subsets $S \subseteq X$ that are finitely supported w.r.t. the **Perm** \mathbb{A} -action

$$\pi \cdot S \triangleq \{\pi \cdot x \mid x \in S\}$$

The nominal set of names

\mathbb{A} is a nominal set once equipped with the action

$$\pi \cdot a = \pi(a)$$

which satisfies $\text{supp } a = \{a\}$.

N.B. \mathbb{A} is not \mathbb{N} ! Although $\mathbb{A} \in \mathbf{Set}$ is a countable, any $f \in \mathbb{N} \rightarrow_{\text{fs}} \mathbb{A}$ has to satisfy

$$\{f n\} = \text{supp}(f n) \subseteq \text{supp } f \cup \text{supp } n = \text{supp } f$$

for all $n \in \mathbb{N}$, and so f cannot be surjective.

Nom \neq choice

Nom models classical higher-order logic, but not Hilbert's ε -operation, $\varepsilon x. \varphi(x)$ satisfying

$$(\forall x : X) \varphi(x) \Rightarrow \varphi(\varepsilon x. \varphi(x))$$

Theorem. There is no equivariant function $c : \{S \in \mathbf{P}_{fs} \mathbb{A} \mid S \neq \emptyset\} \rightarrow \mathbb{A}$ satisfying $c(S) \in S$ for all non-empty $S \in \mathbf{P}_{fs} \mathbb{A}$.

Proof. Suppose there were such a c . Putting $a \triangleq c \mathbb{A}$ and picking some $b \in \mathbb{A} - \{a\}$, we get a contradiction to $a \neq b$:

$$a = c \mathbb{A} = c((a \ b) \cdot \mathbb{A}) = (a \ b) \cdot c \mathbb{A} = (a \ b) \cdot a = b$$

Nom $\not\models$ choice

Nom models classical higher-order logic, but not Hilbert's ε -operation, $\varepsilon x. \varphi(x)$ satisfying

$$(\forall x : X) \varphi(x) \Rightarrow \varphi(\varepsilon x. \varphi(x))$$

In fact **Nom** does not model even very weak forms of choice, such as Dependent Choice.

Freshness

For each nominal set X , we can define a relation $\# \subseteq A \times X$ of **freshness**:

$$a \# x \triangleq a \notin \text{supp } x$$

Freshness

For each nominal set X , we can define a relation $\# \subseteq \mathbb{A} \times X$ of **freshness**:

$$a \# x \triangleq a \notin \text{supp } x$$

- ▶ In \mathbb{N} , $a \# n$ always.
- ▶ In \mathbb{A} , $a \# b$ iff $a \neq b$.
- ▶ In Λ , $a \# t$ iff $a \notin \text{fv } t$.
- ▶ In $X \times Y$, $a \# (x, y)$ iff $a \# x$ and $a \# y$.
- ▶ In $X \rightarrow_{\text{fs}} Y$, $a \# f$ can be subtle!
(and hence ditto for $\mathbf{P}_{\text{fs}} X$)

Lecture 3

Outline

- ▶ **Lecture 1.** Structural recursion and induction in the presence of name-binding operations.
- ▶ **Lecture 2.** Introducing the category of nominal sets.

[Notes, chapters 1–3 +exercises]

- ▶ **Lecture 3.** Nominal algebraic data types and α -structural recursion.

[Notes, chapters 4–5 +exercises]

- ▶ **Lecture 4.** Simply typed λ -calculus with local names and name-abstraction.

[www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

Alpha-equivalence

Smallest binary relation $=_\alpha$ on \mathbf{Tr} closed under the rules:

$$\frac{a \in \mathbb{A}}{\forall a =_\alpha \forall a} \quad \frac{t_1 =_\alpha t'_1 \quad t_2 =_\alpha t'_2}{A(t_1, t_2) =_\alpha A(t'_1, t'_2)}$$

$$\frac{(a \ b) \cdot t =_\alpha (a' \ b) \cdot t' \quad b \notin \{a, a'\} \cup \text{var}(t \ t')}{L(a, t) =_\alpha L(a', t')}$$

E.g. $A(L(a, A(\forall a, \forall b)), \forall c) =_\alpha A(L(c, A(\forall c, \forall b)), \forall c)$
 $\neq_\alpha A(L(b, A(\forall b, \forall b)), \forall c)$

Fact: $=_\alpha$ is transitive (and reflexive & symmetric).

Name abstraction

Each $X \in \mathbf{Nom}$ yields a nominal set $[A]X$ of

name-abstractions $\langle a \rangle x$ are \sim -equivalence classes of pairs $(a, x) \in A \times X$, where

$$(a, x) \sim (a', x') \Leftrightarrow \exists b \# (a, x, a', x') \\ (b \ a) \cdot x = (b \ a') \cdot x'$$

The **Perm** A -action on $[A]X$ is well-defined by

$$\pi \cdot \langle a \rangle x = \langle \pi(a) \rangle (\pi \cdot x)$$

Fact: $\text{supp}(\langle a \rangle x) = \text{supp } x - \{a\}$, so that

$$b \# \langle a \rangle x \Leftrightarrow b = a \vee b \# x$$

(See Notes, p40.)

Name abstraction

Each $X \in \mathbf{Nom}$ yields a nominal set $[A]X$ of

name-abstractions $\langle a \rangle x$ are \sim -equivalence classes of pairs $(a, x) \in A \times X$, where

$$(a, x) \sim (a', x') \Leftrightarrow \exists b \# (a, x, a', x') \\ (b a) \cdot x = (b a') \cdot x'$$

We get a functor $[A](-) : \mathbf{Nom} \rightarrow \mathbf{Nom}$ sending $f \in \mathbf{Nom}(X, Y)$ to $[A]f \in \mathbf{Nom}([A]X, [A]Y)$ where

$$[A]f(\langle a \rangle x) = \langle a \rangle (f x)$$

Name abstraction

$[A](-) : \mathbf{Nom} \rightarrow \mathbf{Nom}$ is a kind of (affine) function space—it is right adjoint to the functor $A \otimes (-) : \mathbf{Nom} \rightarrow \mathbf{Nom}$ sending X to $A \otimes X = \{(a, x) \mid a \# x\}$.

Name abstraction

That explains what morphisms *into* $[\mathbb{A}]X$ look like.
More important is the following characterization of morphisms *out of* $[\mathbb{A}]X$.

Theorem. $f \in (\mathbb{A} \times X) \rightarrow_{fs} Y$ factors through the subquotient $\{(a, x) \mid a \# f\} \subseteq \mathbb{A} \times X \rightarrow [\mathbb{A}]X$ to give a unique element of $\bar{f} \in ([\mathbb{A}]X) \rightarrow_{fs} Y$ satisfying

$$\bar{f}(\langle a \rangle x) = f(a, x) \quad \text{if } a \# f$$

iff $(\forall a \in \mathbb{A}) a \# f \Rightarrow (\forall x \in X) a \# f(a, x)$

iff $(\exists a \in \mathbb{A}) a \# f \wedge (\forall x \in X) a \# f(a, x)$.

Initial algebras

- ▶ $[A](-)$ has excellent exactness properties. It can be combined with \times , $+$ and $X \rightarrow_{fs} (-)$ to give functors $\mathbf{T} : \mathbf{Nom} \rightarrow \mathbf{Nom}$ that have **initial algebras** $I : \mathbf{T}D \rightarrow D$

$$\begin{array}{ccc} \mathbf{T}D & & \mathbf{T}X \\ \downarrow I & & \downarrow F \\ D & & X \end{array}$$

for all F

Initial algebras

- ▶ $[A](-)$ has excellent exactness properties. It can be combined with \times , $+$ and $X \rightarrow_{fs} (-)$ to give functors $T : \mathbf{Nom} \rightarrow \mathbf{Nom}$ that have **initial algebras** $I : TD \rightarrow D$

$$\begin{array}{ccc} TD & \xrightarrow{\quad T\hat{F} \quad} & TX \\ \downarrow I & & \downarrow F \\ D & \xrightarrow[\hat{f}]{\text{exists unique}} & X \end{array}$$

Initial algebras

- ▶ $[A](-)$ has excellent exactness properties. It can be combined with \times , $+$ and $X \rightarrow_{fs} (-)$ to give functors $\mathbf{T} : \mathbf{Nom} \rightarrow \mathbf{Nom}$ that have **initial algebras** $I : \mathbf{T}D \rightarrow D$
- ▶ For a wide class of such functors (**nominal algebraic functors**) the initial algebra D coincides with ASTs/ α -equivalence.
E.g. Λ is the initial algebra for

$$\mathbf{T}(-) \triangleq \mathbf{A} + (- \times -) + [A](-)$$

Nominal algebraic signatures

- Sorts $S ::=$
 - N name-sort (here just one, for simplicity)
 - D data-sorts
 - 1 unit
 - S, S pairs
 - $N.S$ name-binding
- Typed operations $op : S \rightarrow D$

Signature Σ is specified by the stuff in red.

Nominal algebraic signatures

Example: λ -calculus

name-sort **Var** for variables, data-sort **Term** for terms,
and operations

$V : \text{Var} \rightarrow \text{Term}$

$A : \text{Term}, \text{Term} \rightarrow \text{Term}$

$L : \text{Var} . \text{Term} \rightarrow \text{Term}$

Nominal algebraic signatures

Example: π -calculus

name-sort **Chan** for channel names, data-sorts **Proc**, **Pre** and **Sum** for processes, prefixed processes and summations, and operations

$S : \text{Sum} \rightarrow \text{Proc}$

$\text{Comp} : \text{Proc}, \text{Proc} \rightarrow \text{Proc}$

$\text{Nu} : \text{Chan}. \text{Proc} \rightarrow \text{Proc}$

$! : \text{Proc} \rightarrow \text{Proc}$

$P : \text{Pre} \rightarrow \text{Sum}$

$0 : 1 \rightarrow \text{Sum}$

$\text{Plus} : \text{Sum}, \text{Sum} \rightarrow \text{Sum}$

$\text{Out} : \text{Chan}, \text{Chan}, \text{Proc} \rightarrow \text{Pre}$

$\text{In} : \text{Chan}, (\text{Chan}. \text{Proc}) \rightarrow \text{Pre}$

$\text{Tau} : \text{Proc} \rightarrow \text{Pre}$

$\text{Match} : \text{Chan}, \text{Chan}, \text{Pre} \rightarrow \text{Pre}$

Nominal algebraic signatures

Closely related notions:

- ▶ *binding signatures* of Fiore, Plotkin & Turi (LICS 1999)
- ▶ *nominal algebras* of Honsell, Miculan & Scagnetto (ICALP 2001)

N.B. all these notions of signature restrict attention to iterated, but *unary* name-binding—there are other kinds of lexically scoped binder (e.g. see Pottier's `Caml` language.)

$\Sigma(S)$ = raw terms over Σ of sort S

$$\frac{a \in \mathbb{A}}{a \in \Sigma(N)} \quad \frac{t \in \Sigma(S) \quad \text{op} : S \rightarrow D}{\text{op } t \in \Sigma(D)} \quad \frac{}{() \in \Sigma(1)}$$

$$\frac{t_1 \in \Sigma(S_1) \quad t_2 \in \Sigma(S_2)}{t_1, t_2 \in \Sigma(S_1, S_2)} \quad \frac{a \in \mathbb{A} \quad t \in \Sigma(S)}{a . t \in \Sigma(N . S)}$$

Each $\Sigma(S)$ is a nominal set once equipped with the obvious **Perm** \mathbb{A} -action—any finite set of atoms containing all those occurring in t supports $t \in \Sigma(S)$.

Alpha-equivalence

$$=_{\alpha} \subseteq \Sigma(S) \times \Sigma(S)$$

$$\frac{a \in \mathbb{A}}{a =_{\alpha} a}$$

$$\frac{t =_{\alpha} t'}{\text{op } t =_{\alpha} \text{op } t'}$$

$$\frac{}{() =_{\alpha} ()}$$

$$\frac{t_1 =_{\alpha} t'_1 \quad t_2 =_{\alpha} t'_2}{t_1, t_2 =_{\alpha} t'_1, t'_2}$$

$$\frac{(a_1 \ a) \cdot t_1 =_{\alpha} (a_2 \ a) \cdot t_2 \quad a \# (a_1, t_1, a_2, t_2)}{a_1 \cdot t_1 =_{\alpha} a_2 \cdot t_2}$$

Alpha-equivalence

$$=_{\alpha} \subseteq \Sigma(S) \times \Sigma(S)$$

Fact: $=_{\alpha}$ is equivariant ($t_1 =_{\alpha} t_2 \Rightarrow \pi \cdot t_1 =_{\alpha} \pi \cdot t_2$)
and each quotient

$$\Sigma_{\alpha}(S) \triangleq \{[t]_{\alpha} \mid t \in \Sigma(S)\}$$

is a nominal set with

$$\begin{aligned} \pi \cdot [t]_{\alpha} &= [\pi \cdot t]_{\alpha} \\ \text{supp } [t]_{\alpha} &= \text{fn } t \end{aligned}$$

where

$$\begin{aligned} \text{fn}(a \cdot t) &= \text{fn } t - \{a\} \\ \text{fn}(t_1, t_2) &= \text{fn } t_1 \cup \text{fn } t_2 \end{aligned}$$

etc.

Theorem. Given a nominal algebraic signature Σ
(for simplicity, assume Σ has a single data-sort D as well as a single
name-sort N)
 $\Sigma_\alpha(D)$ is an initial algebra for the
associated functor $T_\Sigma : \mathbf{Nom} \rightarrow \mathbf{Nom}$.

(Notes, p61.)

Theorem. Given a nominal algebraic signature Σ
(for simplicity, assume Σ has a single data-sort D as well as a single
name-sort N)

$\Sigma_\alpha(D)$ is an initial algebra for the
associated functor $T_\Sigma : \mathbf{Nom} \rightarrow \mathbf{Nom}$.

$$T_\Sigma(-) = \llbracket S_1 \rrbracket(-) + \dots + \llbracket S_n \rrbracket(-)$$

where Σ has operations $op_i : S_i \rightarrow D$ ($i = 1..n$)

and $\llbracket S \rrbracket(-) : \mathbf{Nom} \rightarrow \mathbf{Nom}$ is defined by:

$$\begin{aligned}\llbracket N \rrbracket(-) &= A \\ \llbracket D \rrbracket(-) &= (-) \\ \llbracket 1 \rrbracket(-) &= 1 \\ \llbracket S_1, S_2 \rrbracket(-) &= \llbracket S_1 \rrbracket(-) \times \llbracket S_2 \rrbracket(-) \\ \llbracket N.S \rrbracket(-) &= [A](\llbracket S \rrbracket(-))\end{aligned}$$

Theorem. Given a nominal algebraic signature Σ
(for simplicity, assume Σ has a single data-sort D as well as a single
name-sort N)

$\Sigma_\alpha(D)$ is an initial algebra for the
associated functor $T_\Sigma : \mathbf{Nom} \rightarrow \mathbf{Nom}$.

E.g. for the λ -calculus signature with operations

$V : \text{Var} \rightarrow \text{Term}$

$A : \text{Term}, \text{Term} \rightarrow \text{Term}$

$L : \text{Var} . \text{Term} \rightarrow \text{Term}$

we have

$T_\Sigma(-) = A + (- \times -) + [A](-)$

Theorem. Given a nominal algebraic signature Σ
(for simplicity, assume Σ has a single data-sort D as well as a single
name-sort N)

$\Sigma_\alpha(D)$ is an initial algebra for the
associated enriched functor $T_\Sigma : \mathbf{Nom} \rightarrow \mathbf{Nom}$.

T_Σ not only acts on equivariant (=emptily supported)
functions, but also on finitely supported functions:

$$\begin{aligned} (X \rightarrow_{\text{fs}} Y) &\rightarrow (T_\Sigma X \rightarrow_{\text{fs}} T_\Sigma Y) \\ F &\mapsto T_\Sigma F \end{aligned}$$

α -Structural recursion

For λ -terms:

Theorem.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \mathbb{A} \rightarrow_{\text{fs}} X \\ f_2 \in X \times X \rightarrow_{\text{fs}} X \\ f_3 \in [\mathbb{A}]X \rightarrow_{\text{fs}} X \end{cases}$

$\exists! \hat{f} \in \Lambda \rightarrow_{\text{fs}} X$ s.t. $\begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a.e) = f_3(\langle a \rangle(\hat{f} e)) \end{cases}$ if $a \# (f_1, f_2, f_3)$

The **enriched** functor $[\mathbb{A}](-) : \mathbf{Nom} \rightarrow \mathbf{Nom}$ sends $f \in X \rightarrow_{\text{fs}} Y$ to $[\mathbb{A}]f \in [\mathbb{A}]X \rightarrow_{\text{fs}} [\mathbb{A}]Y$ where

$$[\mathbb{A}]f (\langle a \rangle x) = \langle a \rangle (f x) \quad \text{if } a \# f$$

α -Structural recursion

For λ -terms:

Theorem.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \mathbb{A} \rightarrow_{fs} X \\ f_2 \in X \times X \rightarrow_{fs} X \\ f_3 \in \mathbb{A} \times X \rightarrow_{fs} X \end{cases}$ s.t.

$$(\forall a) a \# (f_1, f_2, f_3) \Rightarrow (\forall x) a \# f_3(a, x) \quad (\text{FCB})$$

$$\exists! \hat{f} \in \mathbb{A} \rightarrow_{fs} X \quad \begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a. e) = f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_3) \end{cases}$$

Name abstraction

Recall:

Theorem. $f \in (\mathbb{A} \times X) \rightarrow_{\text{fs}} Y$ factors through the subquotient $\{(a, x) \mid a \# f\} \subseteq \mathbb{A} \times X \twoheadrightarrow [\mathbb{A}]X$ to give a unique element of $\bar{f} \in ([\mathbb{A}]X) \rightarrow_{\text{fs}} Y$ satisfying

$$\bar{f}(\langle a \rangle x) = f(a, x) \quad \text{if } a \# f$$

iff $(\forall a \in \mathbb{A}) a \# f \Rightarrow (\forall x \in X) a \# f(a, x)$

iff $(\exists a \in \mathbb{A}) a \# f \wedge (\forall x \in X) a \# f(a, x)$.

α -Structural recursion

For λ -terms:

Theorem.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \Lambda \rightarrow_{fs} X \\ f_2 \in X \times X \rightarrow_{fs} X \\ f_3 \in \Lambda \times X \rightarrow_{fs} X \end{cases}$ s.t.

$$(\forall a) a \# (f_1, f_2, f_3) \Rightarrow (\forall x) a \# f_3(a, x) \quad (\text{FCB})$$

$$\exists! \hat{f} \in \Lambda \rightarrow_{fs} X \quad \text{s.t.} \quad \begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a.e) = f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_3) \end{cases}$$

E.g. capture-avoiding substitution $(-)[e'/a'] : \Lambda \rightarrow \Lambda$ is the \hat{f} for

$$\begin{aligned} f_1 a &\triangleq \text{if } a = a' \text{ then } e' \text{ else } a \\ f_2(e_1, e_2) &\triangleq e_1 e_2 \\ f_3(a, e) &\triangleq \lambda a.e \end{aligned}$$

for which (FCB) holds, since $a \# \lambda a.e$

α -Structural recursion

For λ -terms:

Theorem.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \Lambda \rightarrow_{fs} X \\ f_2 \in X \times X \rightarrow_{fs} X \\ f_3 \in \Lambda \times X \rightarrow_{fs} X \end{cases}$ s.t.

$$(\forall a) a \# (f_1, f_2, f_3) \Rightarrow (\forall x) a \# f_3(a, x) \quad (\text{FCB})$$

$$\exists! \hat{f} \in \Lambda \rightarrow_{fs} X \quad \begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a. e) = f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_3) \end{cases}$$

E.g. size function $\Lambda \rightarrow \mathbb{N}$ is the \hat{f} for

$$\begin{aligned} f_1 a &\triangleq 0 \\ f_2(n_1, n_2) &\triangleq n_1 + n_2 \\ f_3(a, n) &\triangleq n + 1 \end{aligned}$$

for which (FCB) holds, since $a \# (n + 1)$

α -Structural recursion

For λ -terms:

Theorem.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \mathbb{A} \rightarrow_{fs} X \\ f_2 \in X \times X \rightarrow_{fs} X \\ f_3 \in \mathbb{A} \times X \rightarrow_{fs} X \end{cases}$ s.t.

$$(\forall a) a \# (f_1, f_2, f_3) \Rightarrow (\forall x) a \# f_3(a, x) \quad (\text{FCB})$$

$$\exists! \hat{f} \in \Lambda \rightarrow_{fs} X \quad \begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a.e) = f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_3) \end{cases}$$

Non-example: trying to list the bound variables of a λ -term

$$\begin{aligned} f_1 a &\triangleq \mathbf{nil} \\ f_2(l_1, l_2) &\triangleq l_1 @ l_2 \\ f_3(a, l) &\triangleq a :: l \end{aligned}$$

for which (FCB) does not hold, since $a \in \mathit{supp}(a :: l)$.

α -Structural recursion

For λ -terms:

Theorem.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \mathbb{A} \rightarrow_{fs} X \\ f_2 \in X \times X \rightarrow_{fs} X \\ f_3 \in \mathbb{A} \times X \rightarrow_{fs} X \end{cases}$ s.t.

$$(\forall a) a \# (f_1, f_2, f_3) \Rightarrow (\forall x) a \# f_3(a, x) \quad (\text{FCB})$$

$$\exists! \hat{f} \in \Lambda \rightarrow_{fs} X \quad \begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a. e) = f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_3) \end{cases}$$

Similar results hold for any nominal algebraic signature—see J ACM 53(2006)459–506.

Implemented in Urban & Berghofer's Nominal package for Isabelle/HOL (classical higher-order logic).

Seems to capture informal usage well, but (FCB) can be tricky...

Counting bound variables

For each $e \in \Lambda$, $\text{cbv } e \triangleq f e \rho_0 \in \mathbb{N}$

where we want $f \in \Lambda \rightarrow_{\text{fs}} X$ with
 $X = (\mathbb{A} \rightarrow_{\text{fs}} \mathbb{N}) \rightarrow_{\text{fs}} \mathbb{N}$ to satisfy

$$\begin{aligned} f a \rho &= \rho a \\ f (e_1 e_2) \rho &= (f e_1 \rho) + (f e_2 \rho) \\ f (\lambda a. e) \rho &= f e (\rho[a \mapsto \mathbf{1}]) \end{aligned}$$

and where $\rho_0 \in \mathbb{A} \rightarrow_{\text{fs}} \mathbb{N}$ is $\lambda(a \in \mathbb{A}) \rightarrow \mathbf{0}$.

Counting bound variables

For each $e \in \Lambda$, $\text{cbv } e \triangleq f e \rho_0 \in \mathbb{N}$

where we want $f \in \Lambda \rightarrow_{\text{fs}} X$ with
 $X = (\mathbb{A} \rightarrow_{\text{fs}} \mathbb{N}) \rightarrow_{\text{fs}} \mathbb{N}$ to satisfy

$$\begin{aligned} f a \rho &= \rho a \\ f (e_1 e_2) \rho &= (f e_1 \rho) + (f e_2 \rho) \\ f (\lambda a. e) \rho &= f e (\rho[a \mapsto 1]) \end{aligned}$$

and where $\rho_0 \in \mathbb{A} \rightarrow_{\text{fs}} \mathbb{N}$ is $\lambda(a \in \mathbb{A}) \rightarrow 0$.

Looks like we should take

$$f_3(a, x) = \lambda(\rho \in \mathbb{A} \rightarrow_{\text{fs}} \mathbb{N}) \rightarrow x(\rho[a \mapsto 1]),$$

but this does not satisfy (FCB). Solution: take X to be a certain nominal subset of $(\mathbb{A} \rightarrow_{\text{fs}} \mathbb{N}) \rightarrow_{\text{fs}} \mathbb{N}$. (See Notes, p67.)

Lecture 4

Outline

- ▶ **Lecture 1.** Structural recursion and induction in the presence of name-binding operations.
- ▶ **Lecture 2.** Introducing the category of nominal sets.

[Notes, chapters 1–3 +exercises]

- ▶ **Lecture 3.** Nominal algebraic data types and α -structural recursion.

[Notes, chapters 4–5 +exercises]

- ▶ **Lecture 4.** Simply typed λ -calculus with local names and name-abstraction.

[www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

α -Structural recursion

For λ -terms:

Theorem.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \mathbb{A} \rightarrow_{\mathbf{fs}} X \\ f_2 \in X \times X \rightarrow_{\mathbf{fs}} X \\ f_3 \in \mathbb{A} \times X \rightarrow_{\mathbf{fs}} X \end{cases}$ s.t.

$$(\forall a) a \# (f_1, f_2, f_3) \Rightarrow (\forall x) a \# f_3(a, x) \quad (\text{FCB})$$

$$\exists! \hat{f} \in \Lambda \rightarrow_{\mathbf{fs}} X \quad \begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a. e) = f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_3) \end{cases}$$

Can we avoid explicit reasoning about finite support, $\#$ and (FCB) when computing 'mod α '?

Want definition/computation to be separate from proving.

$$\begin{aligned} \hat{f} &= f_1 a \\ \hat{f}(e_1 e_2) &= f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f}(\lambda a.e) &= f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_2) \end{aligned}$$

$$\begin{aligned} &= \lambda a'.e' && = f_3(a', \hat{f} e') \end{aligned}$$

Q: how to get rid of this inconvenient proof obligation?

$$\begin{aligned} \hat{f} &= f_1 a \\ \hat{f}(e_1 e_2) &= f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f}(\lambda a. e) &= \nu a. f_3(a, \hat{f} e) \quad [a \# (f_1, f_2, f_3)] \end{aligned}$$

$$= \lambda a'. e'$$

$$= \nu a'. f_3(a', \hat{f} e') \quad \text{OK!}$$

Q: how to get rid of this inconvenient proof obligation?

A: use a local scoping construct $\nu a. (-)$ for names

$$\begin{aligned} \hat{f} &= f_1 a \\ \hat{f}(e_1 e_2) &= f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f}(\lambda a. e) &= \mathbf{va.} f_3(a, \hat{f} e) \quad [a \# (f_1, f_2, f_3)] \end{aligned}$$

$$= \lambda a'. e'$$

$$= \mathbf{va'.} f_3(a', \hat{f} e') \quad \text{OK!}$$

Q: how to get rid of this inconvenient proof obligation?

A: use **a** local scoping construct $\mathbf{va.} (-)$ for names

which one?!

Dynamic allocation

- ▶ Stateful: $va.t$ means “add a fresh name a' to the current state and return $t[a'/a]$ ”.
 - ▶ Used in Shinwell's **Fresh OCaml** = OCaml +
 - ▶ name types and name-abstraction type former
 - ▶ **name-abstraction patterns**
—matching involves dynamic allocation of fresh names
- [www.fresh-ocaml.org].

Sample Fresh OCaml code

```
(* syntax *)
type t;;
type var = t name;;
type term = Var of var | Lam of <var>term | App of term*term;;

(* semantics *)
type sem = L of ((unit -> sem) -> sem) | N of neu
and neu = V of var | A of neu*sem;;

(* reify : sem -> term *)
let rec reify d =
  match d with L f -> let x = fresh in Lam(<x>(reify(f(function () -> N(V x)))))
    | N n -> reifyn n
and reifyn n =
  match n with V x -> Var x
    | A(n',d') -> App(reifyn n', reify d');;

(* evals : (var * (unit -> sem))list -> term -> sem *)
let rec evals env t =
  match t with Var x -> (match env with [] -> N(V x)
    | (x',v)::env -> if x=x' then v() else evals env (Var x))
  | Lam(<x>t) -> L(function v -> evals ((x,v)::env) t)
  | App(t1,t2) -> (match evals env t1 with L f -> f(function () -> evals env t2)
    | N n -> N(A(n,evals env t2))));;

(* eval : term -> sem *)
let rec eval t = evals [] t;;

(* norm : lam -> lam *)
let norm t = reify(eval t);;
```

Dynamic allocation

- ▶ Stateful: $va.t$ means “add a fresh name a' to the current state and return $t[a'/a]$ ”.
- ▶ Used in Shinwell's Fresh OCaml = OCaml +
 - ▶ name types and name-abstraction type former
 - ▶ name-abstraction patterns
 - matching involves dynamic allocation of fresh names

[\[www.fresh-ocaml.org\]](http://www.fresh-ocaml.org).

Dynamic allocation

- ▶ **Stateful**: $va.t$ means “add a fresh name a' to the current state and return $t[a'/a]$ ”.

Statefulness disrupts familiar mathematical properties of pure datatypes. So we will try to reject it in favour of...

Odersky's $\nu a. (-)$

[M. Odersky, *A Functional Theory of Local Names*, POPL'94]

- ▶ Unfamiliar—apparently not used in practice (so far).
- ▶ Pure equational calculus, in which local scopes 'intrude' rather than extrude (as per dynamic allocation):

$$\begin{aligned} \nu a. (\lambda x \rightarrow t) &\approx \lambda x \rightarrow (\nu a. t) && [a \neq x] \\ \nu a. (t, t') &\approx (\nu a. t, \nu a. t') \end{aligned}$$

- ▶ **New:** a straightforward semantics using nominal sets equipped with a 'name-restriction operation'...

Name-restriction

A **name-restriction** operation on a nominal set X is a morphism $(-)\backslash(-) \in \mathbf{Nom}(\mathbb{A} \times X, X)$ satisfying

- ▶ $a \# a \backslash x$
- ▶ $a \# x \Rightarrow a \backslash x = x$
- ▶ $a \backslash (b \backslash x) = b \backslash (a \backslash x)$

Equivalently, a morphism $\rho : [\mathbb{A}]X \rightarrow X$ making

$$\begin{array}{ccc}
 X & \xrightarrow{\kappa} & [\mathbb{A}]X \\
 & \searrow \text{id}_X & \downarrow \rho \\
 & & X
 \end{array}
 \qquad
 \begin{array}{ccc}
 [\mathbb{A}][\mathbb{A}]X & \xrightarrow{\delta} & [\mathbb{A}][\mathbb{A}]X \\
 [\mathbb{A}]\rho \downarrow & & \downarrow [\mathbb{A}]\rho \\
 [\mathbb{A}]X & & [\mathbb{A}]X \\
 & \searrow \rho & \swarrow \rho \\
 & X &
 \end{array}$$

commute, where $\kappa x = \langle a \rangle x$ for some (or indeed any) $a \# x$; and where $\delta(\langle a \rangle \langle a' \rangle x) = \langle a' \rangle \langle a \rangle x$.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \Lambda \rightarrow_{fs} X \\ f_2 \in X \times X \rightarrow_{fs} X \\ f_3 \in \Lambda \times X \rightarrow_{fs} X \end{cases}$ s.t.

$$(\forall a) a \# (f_1, f_2, f_3) \Rightarrow (\forall x) a \# f_3(a, x) \quad (\text{FCB})$$

$$\exists! \hat{f} \in \Lambda \rightarrow_{fs} X \quad \begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a. e) = f_3(a, \hat{f} e) \quad \text{if } a \# (f_1, f_2, f_3) \end{cases}$$

If X has a name restriction operation $(-)\backslash(-)$, we can trivially satisfy (FCB) by using $a \backslash f_3(a, x)$ in place of $f_3(a, x)$.

Given any $X \in \mathbf{Nom}$ and $\begin{cases} f_1 \in \Lambda \rightarrow_{fs} X \\ f_2 \in X \times X \rightarrow_{fs} X \\ f_3 \in \Lambda \times X \rightarrow_{fs} X \end{cases}$

and a restriction operation $(-)\backslash(-)$ on X ,

$\exists! \hat{f} \in \Lambda \rightarrow_{fs} X$ s.t. $\begin{cases} \hat{f} a = f_1 a \\ \hat{f} (e_1 e_2) = f_2(\hat{f} e_1, \hat{f} e_2) \\ \hat{f} (\lambda a.e) = a \backslash f_3(a, \hat{f} e) \end{cases}$

Is requiring X to carry a name-restriction operation much of a hindrance for applications?

Not much...

Examples of name-restriction

► For \mathbb{N} :

$$a \setminus n \triangleq n$$

Examples of name-restriction

- ▶ For \mathbb{N} :

$$a \setminus n \triangleq n$$

- ▶ For $\mathbb{A}' \triangleq \mathbb{A} \uplus \{\mathbf{anon}\}$:

$$\begin{aligned} a \setminus a &\triangleq \mathbf{anon} \\ a \setminus a' &\triangleq a' \quad \text{if } a' \neq a \\ a \setminus \mathbf{anon} &\triangleq \mathbf{anon} \end{aligned}$$

Examples of name-restriction

- ▶ For \mathbb{N} :

$$a \setminus n \triangleq n$$

- ▶ For $\mathbb{A}' \triangleq \mathbb{A} \uplus \{\mathbf{anon}\}$:

$$a \setminus t \triangleq t[\mathbf{anon}/a]$$

- ▶ For $\Lambda' \triangleq \{t ::= \forall a \mid A(t, t) \mid L(a . t) \mid \mathbf{anon}\} / =_{\alpha}$:

$$a \setminus [t]_{\alpha} \triangleq [t[\mathbf{anon}/a]]_{\alpha}$$

Examples of name-restriction

► For \mathbb{N} : $a \setminus n \triangleq n$

► For $\mathbb{A}' \triangleq \mathbb{A} \uplus \{\mathbf{anon}\}$:

$$a \setminus t \triangleq t[\mathbf{anon}/a]$$

► For $\Lambda' \triangleq \{t ::= \forall a \mid \mathbb{A}(t, t) \mid \mathbb{L}(a . t) \mid \mathbf{anon}\} / =_{\alpha}$:

$$a \setminus [t]_{\alpha} \triangleq [t[\mathbf{anon}/a]]_{\alpha}$$

► Nominal sets with name-restriction are closed under products, coproducts, name-abstraction and exponentiation by a nominal set.

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011,
www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

- ▶ type of **names**, **Name**

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011, www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

- ▶ type of **names**, **Name**, with terms for
 - ▶ names, $a : \text{Name}$ ($a \in \mathbb{A}$)

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011, www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

- ▶ type of **names**, \mathbf{Name} , with terms for
 - ▶ names, $a : \mathbf{Name}$ ($a \in \mathbf{A}$)
 - ▶ equality test, $= : \mathbf{Name} \rightarrow \mathbf{Name} \rightarrow \mathbf{Bool}$

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011, www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

- ▶ type of **names**, **Name**, with terms for
 - ▶ names, $a : \text{Name}$ ($a \in \mathbb{A}$)
 - ▶ equality test, $= : \text{Name} \rightarrow \text{Name} \rightarrow \text{Bool}$
 - ▶ name-swapping, $\frac{t : T}{(a \ \lambda \ a')t : T}$

with type-directed computation rules, e.g.

$$(a \ \lambda \ b)(\lambda x \rightarrow t) = \lambda x \rightarrow (a \ \lambda \ b)(t[(a \ \lambda \ b)x / x])$$

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011, www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

- ▶ type of **names**, Name , with terms for

- ▶ names, $a : \text{Name}$ ($a \in \mathbb{A}$)

- ▶ equality test, $= : \text{Name} \rightarrow \text{Name} \rightarrow \text{Bool}$

- ▶ name-swapping,
$$\frac{t : T}{(a \ \lambda a')t : T}$$

- ▶ locally scoped names
$$\frac{t : T}{\nu a. t : T}$$
 (binds a)

with Odersky-style computation rules, e.g.

$$\nu a. \lambda x \rightarrow t = \lambda x \rightarrow \nu a. t$$

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011,
www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

- ▶ type of **names**, **Name**
- ▶ **name-abstraction** types, **Name . T**

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011, www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

- ▶ type of **names**, \mathbf{Name}
- ▶ **name-abstraction** types, $\mathbf{Name} . T$, with terms for
 - ▶ name-abstraction, $\frac{t : T}{\alpha a . t : \mathbf{Name} . T}$ (binds a)

$\lambda\alpha\nu$ -Calculus

[AMP, *Structural Recursion with Locally Scoped Names*, preprint 2011, www.cl.cam.ac.uk/users/amp12/papers/strrls/strrls.pdf]

is standard simply-typed λ -calculus with booleans and products, extended with:

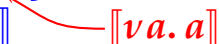
- ▶ type of **names**, Name
- ▶ **name-abstraction** types, $\text{Name} . T$, with terms for
 - ▶ name-abstraction, $\frac{t : T}{\alpha a . t : \text{Name} . T}$ (binds a)
 - ▶ unbinding, $\frac{t : \text{Name} . T \quad t' : T'}{\text{let } a . x = t \text{ in } t' : T'}$ (binds a & x in t')

with computation rule that uses **local scoping**

$$\text{let } a . x = \alpha a . t \text{ in } t' = \nu a . (t' [t/x])$$

$\lambda\alpha\nu$ -Calculus

Denotational semantics. $\lambda\alpha\nu$ -calculus has a straightforward interpretation in **Nom** that is sound for the computation rules—types denote nominal sets equipped with a name-restriction operation:

$$\begin{aligned} \llbracket \text{Bool} \rrbracket &= \{\text{true}, \text{false}\} \\ \llbracket \text{Name} \rrbracket &= \mathbb{A} \uplus \{\text{anon}\} \\ \llbracket T \times T' \rrbracket &= \llbracket T \rrbracket \times \llbracket T' \rrbracket \\ \llbracket T \rightarrow T' \rrbracket &= \llbracket T \rrbracket \rightarrow_{\text{fs}} \llbracket T' \rrbracket \\ \llbracket \text{Name} . T \rrbracket &= [\mathbb{A}] \llbracket T \rrbracket \end{aligned}$$


$\lambda\alpha\nu$ -Calculus

Normalization. Terms possess normal forms with respect to the computation rules that are unique up to a simple **structural congruence** relation generated by:

$$\begin{aligned} \nu a.t &\equiv t && \text{if } a \notin \text{fn}(t) \\ \nu a.\nu b.t &\equiv \nu b.\nu a.t \end{aligned}$$

(Proof in the paper *Structural Recursion with Locally Scoped Names* uses Coquand's technique of evaluation to weak head normal form (whnf) combined with a 'readback' of whnfs to normal forms.)

$\lambda\alpha\nu$ -Calculus

Nominal datatypes. E.g. add type `Lam` with

constructors $\left\{ \begin{array}{l} V : \text{Name} \rightarrow \text{Lam} \\ A : (\text{Lam} \times \text{Lam}) \rightarrow \text{Lam} \\ L : (\text{Name} . \text{Lam}) \rightarrow \text{Lam} \end{array} \right.$

iterator $\frac{t_1 : \text{Name} \rightarrow T \quad t_2 : (T \times T) \rightarrow T \quad t_3 : (\text{Name} . T) \rightarrow T}{\text{lrec } t_1 t_2 t_3 : \text{Lam} \rightarrow T}$

computation rules (writing f for $\text{lrec } t_1 t_2 t_3$)

$$\left\{ \begin{array}{l} f(V t) = t_1 t \\ f(A(t, t')) = t_2(f t, f t') \\ f(L \alpha a . t) = t_3(\alpha a . f t) \quad \text{if } a \notin \text{fn}(t_1, t_2, t_3) \end{array} \right.$$

$\lambda\alpha\nu$ -Calculus

Nominal datatypes. E.g. add type `Lam` with computation rules (writing f for `lrec t1 t2 t3`)

$$\left\{ \begin{array}{l} f(\mathbf{V} t) = t_1 t \\ f(\mathbf{A}(t, t')) = t_2(f t, f t') \\ f(\mathbf{L} \alpha a. t) = t_3(\alpha a. f t) \quad \text{if } a \notin \text{fn}(t_1, t_2, t_3) \end{array} \right.$$

Theorem. Computation of normal forms in this extension of $\lambda\alpha\nu$ -calculus adequately represents α -structurally recursive functions on Λ .

$\lambda\alpha\nu$ -Calculus

Nominal datatypes. E.g. add type `Lam` with computation rules (writing f for `lrec t1 t2 t3`)

$$\left\{ \begin{array}{l} f(\mathbf{V} t) = t_1 t \\ f(\mathbf{A}(t, t')) = t_2(f t, f t') \\ f(\mathbf{L} \alpha a. t) = t_3(\alpha a. f t) \quad \text{if } a \notin \text{fn}(t_1, t_2, t_3) \end{array} \right.$$

Theorem. Computation of normal forms in this extension of $\lambda\alpha\nu$ -calculus adequately represents α -structurally recursive functions on Λ .

E.g. capture-avoiding substitution of t for a is represented by `lrec t1 t2 t3` with

$$\begin{array}{l} t_1 \triangleq \text{if } x = a \text{ then } t \text{ else } \mathbf{V} x \\ t_2 \triangleq \lambda x \rightarrow \text{let } (y, z) = x \text{ in } \mathbf{A} y z \\ t_3 \triangleq \lambda x \rightarrow \text{let } a. y = x \text{ in } \mathbf{L} a b. (a \setminus b) y \end{array}$$

$\lambda\alpha\nu$ -calculus as a FP language

To do: revisit FreshML using Odersky-style local names rather than dynamic allocation

```
names Var : Set
```

```
data Term : Set where
  V : Var -> Term           --(possibly open)  $\lambda$ -terms mod  $\alpha$ 
  A : (Term  $\times$  Term)-> Term --variable
  L : (Var . Term) -> Term  --application term
                               -- $\lambda$ -abstraction

_/_ : Term -> Var -> Term -> Term  --capture-avoiding substitution
(t / x)(V x') = if x = x' then t else V x'
(t / x)(A(t' , t'')) = A((t / x)t' , (t / x)t'')
(t / x)(L(x' . t')) = L(x' . (t / x)t')
```

'Nominal Agda' (???)

```
names Var : Set

data Term : Set where
  V : Var -> Term           --(possibly open)  $\lambda$ -terms mod  $\alpha$ 
  A : (Term  $\times$  Term)-> Term --variable
  L : (Var . Term) -> Term  --application term
                               -- $\lambda$ -abstraction

_/_ : Term -> Var -> Term -> Term           --capture-avoiding substitution
(t / x)(V x') = if x = x' then t else V x'
(t / x)(A(t' , t'')) = A((t / x)t' , (t / x)t'')
(t / x)(L(x' . t')) = L(x' . (t / x)t')

data _==_ (t : Term) : Term -> Set where   --intensional equality
  Refl : t == t
```

'Nominal Agda' (???)

```
names Var : Set
```

```
data Term : Set where
  V : Var -> Term           --(possibly open)  $\lambda$ -terms mod  $\alpha$ 
  A : (Term  $\times$  Term)-> Term --variable
  L : (Var . Term) -> Term  --application term
                               -- $\lambda$ -abstraction
```

```
_/_ : Term -> Var -> Term -> Term           --capture-avoiding substitution
(t / x)(V x') = if x = x' then t else V x'
(t / x)(A(t' , t'')) = A((t / x)t' , (t / x)t'')
(t / x)(L(x' . t')) = L(x' . (t / x)t')
```

```
data _==_ (t : Term) : Term -> Set where
  Refl : t == t           --intensional equality
                               --is term equality mod  $\alpha$ 
```

```
eg : (x x' : Var) ->
  ((V x) / x')(L(x . V x')) == L(x' . V x)   --( $\lambda x.x'$ )[ $x/x'$ ] =  $\lambda x'.x$ 
eg x x' = {! !}
```

Dependent types

- ▶ Can the $\lambda\alpha\nu$ -calculus be extended from simple to dependent types?

At the moment I do not see how to do this, because. . .

$$\frac{\Gamma, a : \text{Name} \vdash e : T \quad a \notin \text{fn}(T)}{\Gamma \vdash \text{va}.e : T}$$

$$\frac{\Gamma, a : \text{Name} \vdash e : T \quad a \notin \text{fn}(T)}{\Gamma \vdash \nu a. e : T}$$

$$\nu a. (e_1, e_2) \stackrel{?}{=} (\nu a. e_1, \nu a. e_2)$$

$e_1 : T_1$

$e_2 : T_2[e_1]$

$$\frac{\Gamma, a : \text{Name} \vdash e : T \quad a \notin \text{fn}(T)}{\Gamma \vdash va.e : T}$$

$$va.(e_1, e_2) \stackrel{?}{=} (va.e_1, va.e_2)$$

$e_1 : T_1$
 $e_2 : T_2[e_1]$

$va.(e_1, e_2) : (x : T_1) \times T_2[x]$
 if $a \notin \text{fn}(T_1, T_2)$

$$\frac{\Gamma, a : \text{Name} \vdash e : T \quad a \notin \text{fn}(T)}{\Gamma \vdash va.e : T}$$

$$va.(e_1, e_2) \stackrel{?}{=} (va.e_1, va.e_2)$$

$e_1 : T_1$ $va.e_1 : T_1$
 $e_2 : T_2[e_1]$

$va.(e_1, e_2) : (x : T_1) \times T_2[x]$
 if $a \notin \text{fn}(T_1, T_2)$

$$\frac{\Gamma, a : \text{Name} \vdash e : T \quad a \notin \text{fn}(T)}{\Gamma \vdash va.e : T}$$

$$va.(e_1, e_2) \stackrel{?}{=} (va.e_1, va.e_2)$$

$e_1 : T_1$ $va.e_1 : T_1$
 $e_2 : T_2[e_1]$ $va.e_2 : T_2[va.e_1]???$

$va.(e_1, e_2) : (x : T_1) \times T_2[x]$
 if $a \notin \text{fn}(T_1, T_2)$

Dependent types

- ▶ Can the $\lambda\alpha\nu$ -calculus be extended from simple to dependent types?

At the moment I do not see how to do this, because. . .

- ▶ In any case, is there a useful/expressive form of **indexed structural induction mod α** , whether or not we try to use Odersky-style locally scoped names?

(Recent work of Cheney on DNTT is interesting, but probably not sufficiently expressive.)