

# **Model-Checking First-Order Logic**

## **Automata and Locality**

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## The Model-Checking Problem

We are interested in the computational complexity of the following decision problem:

Given: a first-order formula  $\varphi$  and a structure  $\mathbb{A}$

Decide: if  $\mathbb{A} \models \varphi$

*Or*, what is the complexity of the *satisfaction relation* for first-order logic?

For the rest of the talk,

We assume that  $\mathbb{A}$  is finite and given explicitly in the input.

We generally write  $l$  for the length of  $\varphi$  and  $n$  for the size of  $\mathbb{A}$ .

We assume  $\mathbb{A}$  is a *directed, coloured graph*—i.e., a structure interpreting one binary relation  $E$ , some unary relations and some constants. We write  $G\mathbb{A}$  for the underlying undirected graph.

## Naïve Algorithm

The straightforward algorithm proceeds recursively on the structure of  $\varphi$ :

- Atomic formulas by direct lookup.
- Boolean connectives are easy.
- If  $\varphi \equiv \exists x \psi$  then for each  $a \in \mathbb{A}$  check whether

$$(\mathbb{A}, c \mapsto a) \models \psi[c/x],$$

where  $c$  is a new constant symbol.

This shows that the model-checking problem can be solved in time  $O(ln^m)$  and  $O(m \log n)$  space, where  $m$  is the nesting depth of quantifiers in  $\varphi$  (or by a more careful accounting, the number of distinct variables occurring in  $\varphi$ ).

## Complexity

This shows that the model checking problem is in **PSpace** and for a fixed sentence  $\varphi$ , the problem of deciding membership in the class

$$\text{Mod}(\varphi) = \{\mathbb{A} \mid \mathbb{A} \models \varphi\}$$

is in *logarithmic space* and *polynomial time*.

**QBF**—satisfiability of quantified Boolean formulas can be easily reduced to the model checking problem with  $\mathbb{A}$  a fixed two-element structure.

Thus, the problem is **PSpace**-complete, even for fixed  $\mathbb{A}$ .

## Is FO contained in an initial segment of PTime?

Question posed in the title of a paper by **Stolboushkin and Taitlin (CSL 1994)**.

Is there a fixed  $c$  such that for every first-order  $\varphi$ ,  $\text{Mod}(\varphi)$  is decidable in time  $O(n^c)$ ?

If  $\text{PTime} = \text{PSpace}$ , then the answer is yes, as the satisfaction relation is then itself decidable in time  $O(n^c)$  and this bounds the time for all formulas  $\varphi$ .

Thus, though we expect the answer is no, this would be difficult to prove.

A more uniform version of their question is:

Is there a constant  $c$  and a computable function  $f$  so that the satisfaction relation for first-order logic is decidable in time  $O(f(l)n^c)$ ?

## Fixed Parameter Tractability

If  $\text{Mod}(\varphi)$  is decidable in time  $O(n^c)$  and the constants involved are bounded by some computable function of  $l$ , then the model-checking problem is *fixed-parameter tractable* (FPT) with the formula length as parameter.

The parameterised model-checking problem is  $AW[\star]$ -complete.

The parameterised model-checking problem restricted to  $\Pi_t$  formulas is hard for the class  $W[t]$ .

Thus, the whole edifice of parameterized intractability would collapse.

## Restricted Classes of Structures

One way to get a handle on the complexity of first-order model checking is to consider restricted classes of structures.

Given: a first-order formula  $\varphi$  and a structure  $\mathbb{A} \in \mathcal{C}$

Decide: if  $\mathbb{A} \models \varphi$

For many classes  $\mathcal{C}$ , this problem has been shown to be **FPT**.

1. Every first-order (or even **MSO**) definable class of strings is a regular language and so decidable in linear time.
2.  $\mathcal{T}_k$ —the class of structures of tree-width at most  $k$ .

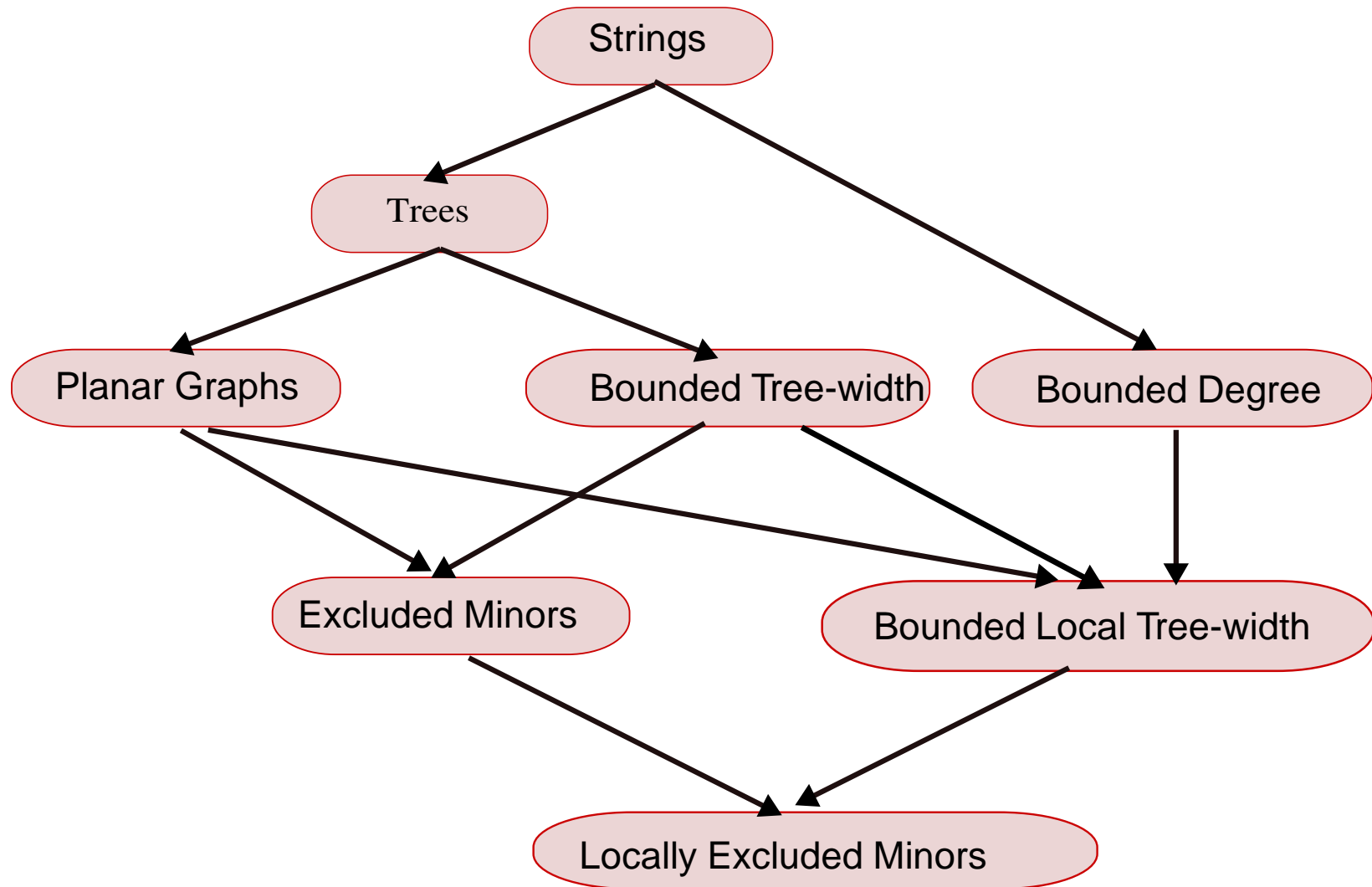
**Courcelle (1990)** shows that every **MSO** definable property is decidable in linear time on this class.

## Restricted Classes of Structures

3.  $\mathcal{D}_k$ —the class of structures of *degree* bounded by  $k$ .  
**Seese (1996)** shows that every FO definable property is decidable in linear time.
4.  $\text{LTW}_t$ —the class of structures of *local tree-width* bounded by a function  $t$ .  
**Frick and Grohe (2001)** show that every FO definable property is decidable in quadratic time.
5.  $\mathcal{M}_k$ —the class of structures *excluding  $K_k$  as a minor*.  
**Flum and Grohe (2001)** show that every FO definable property is decidable in time  $O(n^5)$ .
6.  $\text{LEM}_t$ —the class of structures with *locally excluded minors* given by  $t$ .  
**D., Grohe and Kreutzer (2007)** show that every FO definable property is decidable in time  $O(n^6)$ .



## Map of Restrictions



## Automata and Locality

The methods of proof for the results are combinations of two general techniques:

- Methods of *automata* or *decompositions*; and
- Methods based on the *locality* of first-order logic.

In the rest of this talk, we first review these two methods using the results on

*strings*;

graphs of *bounded tree-width*; and

graphs of *bounded degree*.

We then show how the methods combine in the other cases.

## Strings

Structures  $\mathbb{A}$  where the binary relation  $E$  forms a connected graph, with each node having *in-degree* and *out-degree* at most 1, can be viewed as words over the alphabet  $\mathcal{P}(\mathcal{U})$ , where  $\mathcal{U}$  is the collection of unary relation symbols.

### Theorem (Büchi, Elgot, Trakhtenbrot)

For any sentence  $\varphi$  of MSO, the language  $L_\varphi = \{s \mid s \text{ a string and } s \models \varphi\}$  is regular.

A particularly perspicuous proof of this is obtained by using the *Myhill-Nerode theorem*.

## Myhill-Nerode Theorem

### Theorem (Myhill-Nerode)

A language  $L$  is regular *if, and only if*, there is an equivalence relation  $\sim$  on strings such that:

1.  $\sim$  has finite index on the set of all strings;
2.  $\sim$  is a congruence for string concatenation, i.e.

$$s_1 \sim t_1 \text{ and } s_2 \sim t_2 \Rightarrow s_1 \cdot s_2 \sim t_1 \cdot t_2;$$

and

3.  $L$  is the union of some number of  $\sim$ -equivalence classes.

## MSO Languages

$\varphi$ —an MSO sentence of quantifier rank  $m$ .

$A \equiv_m^{(\text{MSO})} B$  if they cannot be distinguished by any first-order (MSO) sentence of quantifier rank  $m$ .

- $\equiv_m^{\text{MSO}}$  has finite index since there are, up to logical equivalence, only finitely many MSO sentences of quantifier rank at most  $m$ .
- $\equiv_m^{\text{MSO}}$  is a congruence for concatenation by an easy argument using *Ehrenfeucht-Fraïssé games* (a special case of the *Feferman-Vaught theorem*).
- It is immediate that  $L_\varphi$  is closed under  $\equiv_m^{\text{MSO}}$ .

## Tree-Width

Tree-width is a measure of how *tree-like* a structure is.

For a graph  $G = (V, E)$ , a *tree decomposition* of  $G$  is a relation  $D \subset V \times T$  with a tree  $T$  such that:

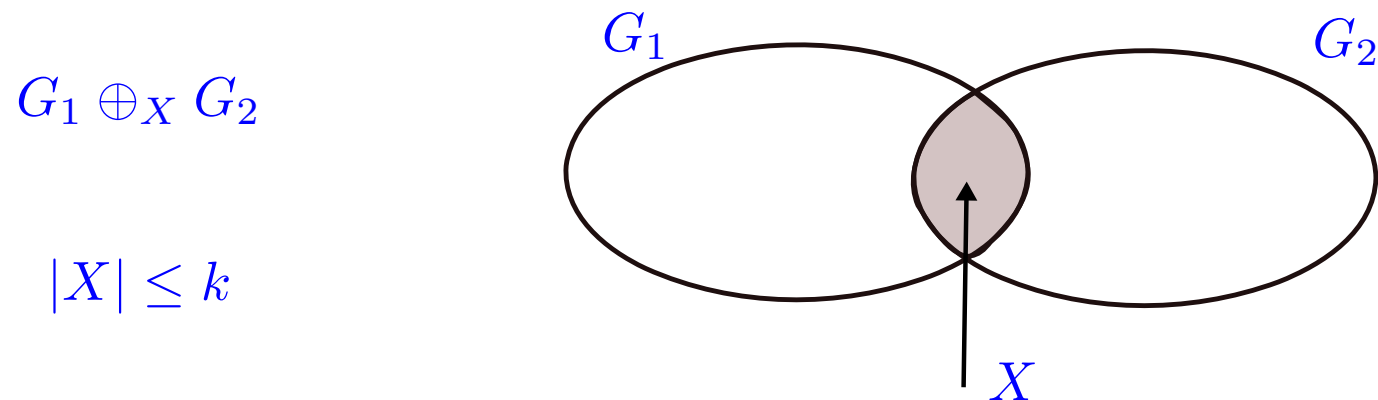
- for each  $v \in V$ , the set  $\{t \mid (v, t) \in D\}$  forms a connected subtree of  $T$ ;  
and
- for each edge  $(u, v) \in E$ , there is a  $t \in T$  such that  $(u, t), (v, t) \in D$ .

The *tree-width* of  $G$  is the least  $k$  such that there is a tree  $T$  and a tree decomposition  $D \subset V \times T$  such that for each  $t \in T$ ,

$$|\{v \in V \mid (v, t) \in D\}| \leq k + 1.$$

## Tree-Width

Looking at the decomposition *bottom-up*, a graph of tree-width  $k$  is obtained from graphs with at most  $k + 1$  nodes through a finite sequence of applications of the operation of taking *sums over sets* of at most  $k$  elements.



We let  $\mathcal{T}_k$  denote the class of structures  $\mathbb{A}$  such that  $\text{tw}(G\mathbb{A}) \leq k$ .

## Courcelle's Theorem

### Theorem (Courcelle)

For any MSO sentence  $\varphi$  and any  $k$  there is a linear time algorithm that decides, given  $\mathbb{A} \in \mathcal{T}_k$  whether  $\mathbb{A} \models \varphi$ .

A proof relies on the fact (proved by **Bodlaender**) that there is an algorithm (linear in  $n$ , exponential in  $k$ ) that given a graph  $G \in \mathcal{T}_k$  computes a tree decomposition of  $G$  of width  $k$ .

Given  $\mathbb{A} \in \mathcal{T}_k$  and  $\varphi$ , compute:

- from  $\mathbb{A}$  a labelled tree  $T$ ; and
- from  $\varphi$  a bottom-up tree automaton  $\mathcal{A}$

such that  $\mathcal{A}$  accepts  $T$  if, and only if,  $\mathbb{A} \models \varphi$ .



## The Labelled Tree

$C = \{c_0, \dots, c_k\}$  a set of  $k + 1$  new constants.

$(\mathbb{A}, \rho)$ —expansion of  $\mathbb{A}$  with  $\rho : C \rightarrow V$ , a partial map interpreting some of the constants in  $C$ .

Let

- $\mathcal{B}_k$ —the collection of  $(\mathbb{A}, \rho)$  such that  $\mathbb{A}$  has at most  $k + 1$  elements.
- $\text{erase}_i$ —an operation which takes  $(\mathbb{A}, \rho)$  to  $(\mathbb{A}, \rho')$ , where  $\rho'$  is as  $\rho$  but without  $c_i$ .
- a binary operation of union disjoint over  $C$ :

$$(\mathbb{A}_1, \rho_1) \oplus_C (\mathbb{A}_1, \rho_2)$$

## Congruence

- Any  $\mathbb{A} \in \mathcal{T}_k$  is obtained from  $\mathcal{B}_k$  by finitely many applications of the operations  $\text{erase}_i$  and  $\oplus_C$ .
- If  $\mathbb{A}_1, \rho_1 \equiv_m^{\text{MSO}} \mathbb{A}_2, \rho_2$ , then

$$\text{erase}_i(\mathbb{A}_1, \rho_1) \equiv_m^{\text{MSO}} \text{erase}_i(\mathbb{A}_2, \rho_2)$$

- If  $\mathbb{A}_1, \rho_1 \equiv_m^{\text{MSO}} \mathbb{A}_2, \rho_2$ , and  $\mathbb{B}_1, \sigma_1 \equiv_m^{\text{MSO}} \mathbb{B}_2, \sigma_2$  then

$$(\mathbb{A}_1, \rho_1) \oplus_C (\mathbb{B}_1, \sigma_1) \equiv_m^{\text{MSO}} (\mathbb{A}_2, \rho_2) \oplus_C (\mathbb{B}_2, \sigma_2)$$

## Model-Checking on $\mathcal{T}_k$

Any  $\mathbb{A} \in \mathcal{T}_k$  can be represented as a finite tree, with leaves labelled by elements of  $\mathcal{B}_k$ , internal nodes labelled by operations  $\text{erase}_i$  and  $\oplus_C$ .

We can then compute the  $\equiv_m^{\text{MSO}}$  type of  $\mathbb{A}$  bottom-up.

This establishes the following:

The model-checking problem for **MSO** is decidable in time  $f(l, k)n$ , where

- $f$  is some computable function
- $l$  is the length of the input formula
- $k$  is the tree-width of the input structure
- $n$  is the size of the input structure.

## The Method of Automata

Suppose  $\mathcal{C}$  is a class of structures such that there is a finite class  $\mathcal{B}$  and a finite collection  $\text{Op}$  of operations such that:

- $\mathcal{C}$  is contained in the closure of  $\mathcal{B}$  under the operations in  $\text{Op}$ ;
- there is a polynomial-time algorithm which computes, for any  $\mathbb{A} \in \mathcal{C}$ , an  $\text{Op}$ -decomposition of  $\mathbb{A}$  over  $\mathcal{B}$ ; and
- for each  $m$ , the equivalence class  $\equiv_m^{(\text{MSO})}$  is an *effective* congruence with respect to to all operations  $o \in \text{Op}$  (i.e., the  $\equiv_m^{(\text{MSO})}$ -type of  $o(\mathbb{A}_1, \dots, \mathbb{A}_s)$  can be computed from the  $\equiv_m^{(\text{MSO})}$ -types of  $\mathbb{A}_1, \dots, \mathbb{A}_s$ ).

Then, **FO (MSO)** model-checking is fixed-parameter tractable on  $\mathcal{C}$ .

## Relaxations of the Method

1. Instead of requiring  $\mathcal{B}$  be finite, require that *model-checking is in FPT over  $\mathcal{B}$* .
2. In place of  $\equiv_m^{(\text{MSO})}$ , we can take any sequence of equivalence relations  $\sim_m$  ( $m \in \mathbb{N}$ ) satisfying
  - for every  $\varphi$  there is an  $m$  such that models of  $\varphi$  are closed under  $\sim_m$ ;
  - and
  - for all  $m$ ,  $\sim_m$  has finite index.

**Note:** letting  $\mathbb{A} \sim_m \mathbb{B}$  if  $\mathbb{A}, \mathbb{B}$  cannot be distinguished by a formula of *length  $m$* , does not yield a congruence with respect to disjoint union.

There is no elementary function  $e$  such that  $\mathbb{A}_1 \sim_{e(m)} \mathbb{B}_1$  and  $\mathbb{A}_2 \sim_{e(m)} \mathbb{B}_2$  implies  $\mathbb{A}_1 \oplus \mathbb{A}_2 \sim_m \mathbb{B}_1 \oplus \mathbb{B}_2$ .

**(D.,Grohe, Kreutzer, Schweikardt 2007)**

## Bounded Degree

$\mathcal{D}_k$ —the class of structures  $\mathbb{A}$  in which every element has degree (in-degree + out-degree) at most  $k$ .

### Theorem (Seese)

For every sentence  $\varphi$  of FO and every  $k$  there is a linear time algorithm which, given a structure  $\mathbb{A} \in \mathcal{D}_k$  determines whether  $\mathbb{A} \models \varphi$ .

**Note:** this is not true for MSO unless  $P = NP$ .

The proof is based on *locality* of first-order logic. Specifically, *Hanf's theorem*.

## Hanf Types

For an element  $a$  in a structure  $\mathbb{A}$ , define

$N_r^{\mathbb{A}}(a)$ —the substructure of  $\mathbb{A}$  generated by the elements whose distance from  $a$  (in  $G\mathbb{A}$ ) is at most  $r$ .

We say  $\mathbb{A}$  and  $\mathbb{B}$  are *Hanf equivalent* with radius  $r$  and threshold  $q$  ( $\mathbb{A} \simeq_{r,q} \mathbb{B}$ ) if, for every  $a \in A$  the two sets

$$\{a' \in A \mid N_r^{\mathbb{A}}(a) \cong N_r^{\mathbb{A}}(a')\} \quad \text{and} \quad \{b \in B \mid N_r^{\mathbb{A}}(a) \cong N_r^{\mathbb{B}}(b)\}$$

either have the same size or both have size greater than  $q$ ;

and, similarly for every  $b \in B$ .

## Hanf Locality Theorem

### Theorem (Hanf)

For every vocabulary  $\sigma$  and every  $m$  there are  $r \leq 3^m$  and  $q \leq m$  such that for any  $\sigma$ -structures  $\mathbb{A}$  and  $\mathbb{B}$ : if  $\mathbb{A} \simeq_{r,q} \mathbb{B}$  then  $\mathbb{A} \equiv_m \mathbb{B}$ .

In other words, if  $r \geq 3^m$ , the equivalence relation  $\simeq_{r,m}$  is a refinement of  $\equiv_m$ .

For  $\mathbb{A} \in \mathcal{D}_k$ :

$N_r^{\mathbb{A}}(a)$  has at most  $k^r + 1$  elements

each  $\simeq_{r,m}$  has finite index.

Each  $\simeq_{r,m}$ -class  $t$  can be characterised by a finite table,  $I_t$ , giving isomorphism types of neighbourhoods and numbers of their occurrences up to threshold  $m$ .



## Model-Checking on $\mathcal{D}_k$

For a sentence  $\varphi$  of FO, we can compute a set of tables  $\{I_1, \dots, I_s\}$  describing  $\simeq_{r,m}$ -classes consistent with it.

This computation is independent of any structure  $\mathbb{A}$ .

Given a structure  $\mathbb{A} \in \mathcal{D}_k$ ,

for each  $a$ , determine the isomorphism type of  $N_r^{\mathbb{A}}(a)$

construct the table describing the  $\simeq_{r,m}$ -class of  $\mathbb{A}$ .

compare against  $\{I_1, \dots, I_s\}$  to determine whether  $\mathbb{A} \models \varphi$ .

For fixed  $k, r, m$ , this requires time *linear* in the size of  $\mathbb{A}$ .

**Note:** model-checking for FO is in  $O(f(l, k)n)$ .

## Local Tree-Width

Let  $t : \mathbb{N} \rightarrow \mathbb{N}$  be a non-decreasing function.

$\text{LTW}_t$ —the class of structures  $\mathbb{A}$  such that for every  $a \in A$ :

$GN_r^{\mathbb{A}}(a)$  has tree-width at most  $t(r)$ . **(Eppstein; Frick-Grohe).**

We say that  $\mathcal{C}$  has *bounded local tree-width* if there is some function  $t$  such that  $\mathcal{C} \subseteq \text{LTW}_t$ .

*Examples:*

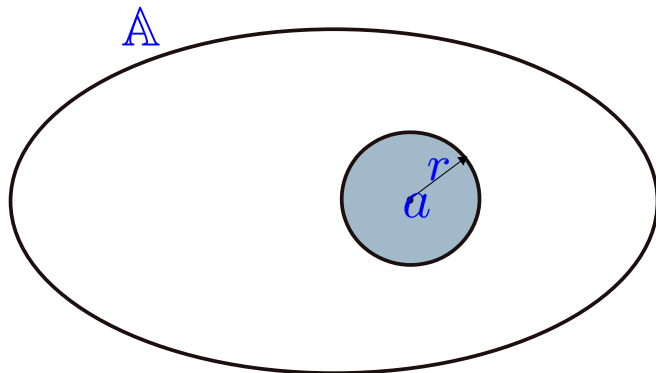
1.  $\mathcal{T}_k$  has local tree-width bounded by the constant function  $t(r) = k$ .
2.  $\mathcal{D}_k$  has local tree-width bounded by  $t(r) = k^r + 1$ .
3. Planar graphs have local tree-width bounded by  $t(r) = 3r$ .

## Bounded Local Tree-Width

### Theorem (Frick-Grohe)

For any class  $\mathcal{C}$  of bounded local tree-width and any  $\varphi \in \text{FO}$ , there is a *quadratic* time algorithm that decides, given  $\mathbb{A} \in \mathcal{C}$ , whether  $\mathbb{A} \models \varphi$ .

The idea:



For each  $a$ , the structure  $N_r^{\mathbb{A}}(a)$  has tree-width bounded by  $t(r)$ .

Use the linear time algorithm on  $T_{t(r)}$  to determine  $\equiv_m$ -type of  $N_r^{\mathbb{A}}(a)$ .

Hanf's theorem uses *isomorphism types* of  $N_r^{\mathbb{A}}(a)$ . We use *Gaifman's locality theorem* instead.

## Gaifman's Theorem

We write  $\delta(x, y) > d$  for the formula of FO that says that the distance between  $x$  and  $y$  is greater than  $d$ .

We write  $\psi^N(x)$  to denote the formula obtained from  $\psi(x)$  by relativising all quantifiers to the set  $N$ .

A *basic local sentence* is a sentence of the form

$$\exists x_1 \cdots \exists x_s \left( \bigwedge_{i \neq j} \delta(x_i, x_j) > 2r \wedge \bigwedge_i \psi^{N_r(x_i)}(x_i) \right)$$

### Theorem (Gaifman)

Every first-order sentence is equivalent to a Boolean combination of basic local sentences.

## Using Gaifman's Theorem

How do we evaluate a basic local sentence

$\exists x_1 \cdots \exists x_s \left( \bigwedge_{i \neq j} \delta(x_i, x_j) > 2r \wedge \bigwedge_i \psi^{N_r(x_i)}(x_i) \right)$  in a structure  $\mathbb{A}$ ?

For each  $a \in A$ , determine whether

$$N_r^{\mathbb{A}}(a) \models \psi[a]$$

using the linear time model-checking algorithm on  $\mathcal{T}_{t(r)}$ .

Label  $a$  **red** if so.

We now want to know whether there exists a  $2r$ -**scattered** set of **red** vertices of size  $s$ .

## Finding a Scattered Set

Choose red vertices from  $\mathbb{A}$  in some order, removing the  $2r$ -neighbourhood of each chosen vertex.

$$\begin{aligned} a_1 &\in \mathbb{A}, \\ a_2 &\in \mathbb{A} \setminus N_{2r}^{\mathbb{A}}(a_1), \\ a_3 &\in \mathbb{A} \setminus (N_{2r}^{\mathbb{A}}(a_1) \cup N_{2r}^{\mathbb{A}}(a_2)), \dots \end{aligned}$$

If the process continues for  $s$  steps, we have found a  $2r$ -scattered set of size  $s$ .

Otherwise, for some  $u < s$  we have found  $a_1, \dots, a_u$  such that all red vertices are contained in

$$N_{2r}^{\mathbb{A}}(a_1, \dots, a_u)$$

This is a structure of tree-width at most  $t(2rs)$  and the property of containing a  $2r$ -scattered set of *red* vertices of size  $s$  can be stated in FO.

## Method of Locality

- Suppose we have a function, associating a parameter  $k_{\mathbb{A}} \in \mathbb{N}$  with each structure  $\mathbb{A}$ .
- Suppose we have an algorithm which, given  $\mathbb{A}$  and  $\varphi$  decides  $\mathbb{A} \models \varphi$  in time

$$g(l, k_{\mathbb{A}})n^c$$

for some computable function  $g$  and some constant  $c$ .

- Let  $\mathcal{C}$  be a class of structures of *bounded local  $k$* , i.e.

there is a computable function  $t : \mathbb{N} \rightarrow \mathbb{N}$  such that for every  $\mathbb{A} \in \mathcal{C}$  and  $a \in \mathbb{A}$ ,  $k_{N_r^{\mathbb{A}}(a)} < t(r)$ .

Then, there is an algorithm which, given  $\mathbb{A} \in \mathcal{C}$  and  $\varphi$  decides whether  $\mathbb{A} \models \varphi$  in time

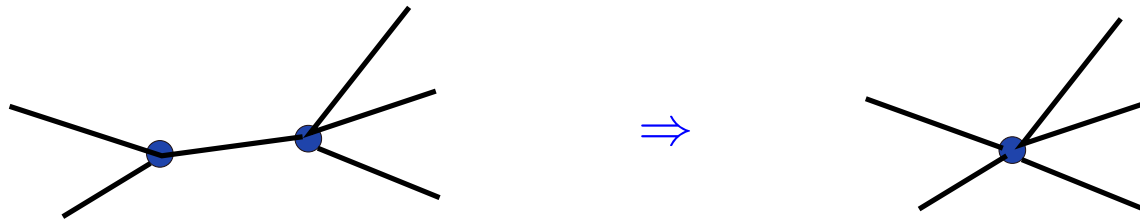
$$f(l)n^{c+1}$$

for some computable function  $f$ .

## Graph Minors

We say that a graph  $G$  is a minor of graph  $H$  (written  $G \prec H$ ) if  $G$  can be obtained from  $H$  by repeated applications of the operations:

- *delete an edge*;
- *delete a vertex* (and all incident edges); and
- *contract an edge*

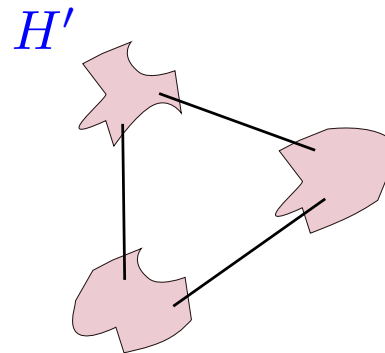
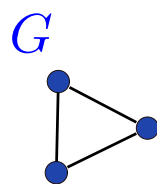




## Graph Minors

Alternatively,  $G = (V, E)$  is a minor of  $H = (U, F)$ , if there is a graph  $H' = (U', F')$  with  $U' \subseteq U$  and  $F' \subseteq F$  and a surjective map  $M : U' \rightarrow V$  such that

- for each  $v \in V$ ,  $M^{-1}(v)$  is a connected subgraph of  $H'$ ; and
- for each edge  $(u, v) \in E$ , there is an edge in  $F'$  between some  $x \in M^{-1}(u)$  and some  $y \in M^{-1}(v)$ .



## Facts about Graph Minors

- $G$  is planar if, and only if,  $K_5 \not\prec G$  and  $K_{3,3} \not\prec G$ .
- If  $G \subset H$  then  $G \prec H$ .
- The relation  $\prec$  is transitive.
- If  $G \prec H$ , then  $\text{tw}(G) \leq \text{tw}(H)$ .
- If  $\text{tw}(G) < k - 1$ , then  $K_k \not\prec G$ .

Say that a class of structures  $\mathcal{C}$  *excludes  $H$  as a minor* if  $H \not\prec G\mathbb{A}$  for all  $\mathbb{A} \in \mathcal{C}$ .

$\mathcal{C}$  has *excluded minors* if it excludes some  $H$  as a minor (equivalently, it excludes some  $K_k$  as a minor).

- $\mathcal{T}_k$  excludes  $K_{k+2}$  as a minor.

## More Facts about Graph Minors

### Theorem (Robertson-Seymour)

In any infinite collection  $\{G_i \mid i \in \omega\}$  of graphs, there are  $i, j$  with  $G_i \prec G_j$ .

### Corollary

For any class  $\mathcal{C}$  *closed under minors*, there is a finite collection  $\mathcal{F}$  of graphs such that  $G \in \mathcal{C}$  *if, and only if,*  $F \not\prec G$  for all  $F \in \mathcal{F}$ .

### Theorem (Robertson-Seymour)

For any  $G$  there is an  $O(n^3)$  algorithm for deciding, given  $H$ , whether  $G \prec H$ .

### Corollary

Any class  $\mathcal{C}$  closed under minors is decidable in *cubic time*.

## Decomposing Graphs with Excluded Minors

Write  $\mathcal{M}_k$  for the class of graphs  $G$  such that  $K_k \not\prec G$ .

from now on, we elide the distinction between restrictions on  $\mathbb{A}$  and  $G\mathbb{A}$ .

**Robertson and Seymour** show how to obtain a decomposition of graphs in  $\mathcal{M}_k$ .

**Grohe** shows that this can be done over graphs of *almost bounded local tree-width*.

Let

$$\mathcal{L}_\lambda = \{G \mid \forall H \prec G : \text{ltw}_r(H) \leq \lambda r\}$$

$$\mathcal{L}_{\lambda,\mu} = \{G \mid \exists v_1, \dots, v_\mu : G \setminus \{v_1, \dots, v_\mu\} \in \mathcal{L}_\lambda\}$$

## Almost Bounded Local Tree-width

Classes  $\mathcal{L}_\lambda$  and  $\mathcal{L}_{\lambda,\mu}$  are *minor-closed* and so decidable in cubic time.

Given  $G \in \mathcal{L}_{\lambda,\mu}$ , we can find  $v_1, \dots, v_\mu$  witnessing this in time  $O(n^4)$ .

For each  $v$ , check if  $G - v$  is in  $\mathcal{L}_{\lambda,\mu-1}$ .

If so, add  $v$  to the list and proceed with  $G - v$  and  $\mathcal{L}_{\lambda,\mu-1}$ .

**Question:** Is this algorithm in time  $O(f(\lambda, \mu)n^4)$  for a *computable* function  $f$ ?

There is a polynomial-time computable map taking a structure  $\mathbb{A} \in \mathcal{L}_{\lambda,\mu}$  to  $\mathbb{A}' \in \mathcal{L}_\lambda$  so that the FO-type of  $\mathbb{A}$  is determined by that of  $\mathbb{A}'$ .

$\mathbb{A}'$  is obtained from  $\mathbb{A} \setminus \{v_1, \dots, v_\mu\}$  by adding new relations  $S_1, \dots, S_\mu$  interpreted by the neighbours of  $v_1, \dots, v_\mu$ .

## Decomposition Theorem

$\forall k \exists \lambda \exists \mu$

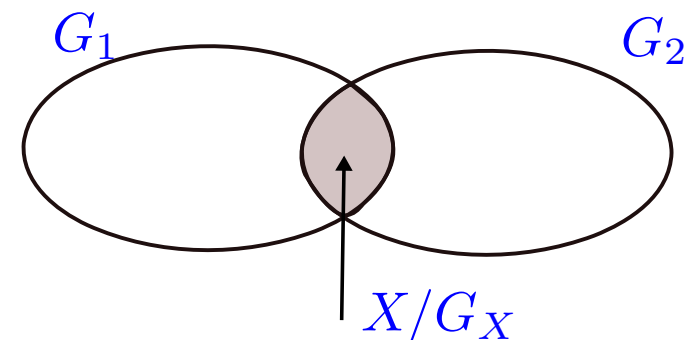
Any  $G \in \mathcal{M}_k$  can be obtained from graphs in  $\mathcal{L}_{\lambda, \mu}$  by a finite sequence of *clique sum* operations.

And the decomposition can be computed in time  $O(n^4)$

*Clique Sum:*  $G_1, G_2$  graphs with  $X \subseteq G_1 \cap G_2$  a set of vertices that induces a clique in each of  $G_1$  and  $G_2$ .

$$G_1 \oplus_{X, G_X} G_2$$

Take the disjoint sum of  $G_1$  and  $G_2$ , identifying the two copies of  $X$  and replacing the clique by the graph  $G_X$ .



## Congruences

For graphs  $G \in \mathcal{L}_{\lambda, \mu}$ , if  $X$  is a clique in  $G$ ,

$$|X| < \lambda + \mu + 1$$

Thus, there are only finitely many operations of the form  $\oplus_{X, G_X}$ .

We have nearly satisfied the requirements for an application of the *automata-theoretic method*, but . . . .

If  $X = x_1, \dots, x_s$ , the  $\equiv_m$ -type of  $(G, x_1, \dots, x_s)$ , where

$$G = G_1 \oplus_{X, G_X} G_2,$$

is given by the  $\equiv_m$ -types of  $(G_1, x_1, \dots, x_s)$  and  $(G_2, x_1, \dots, x_s)$ .

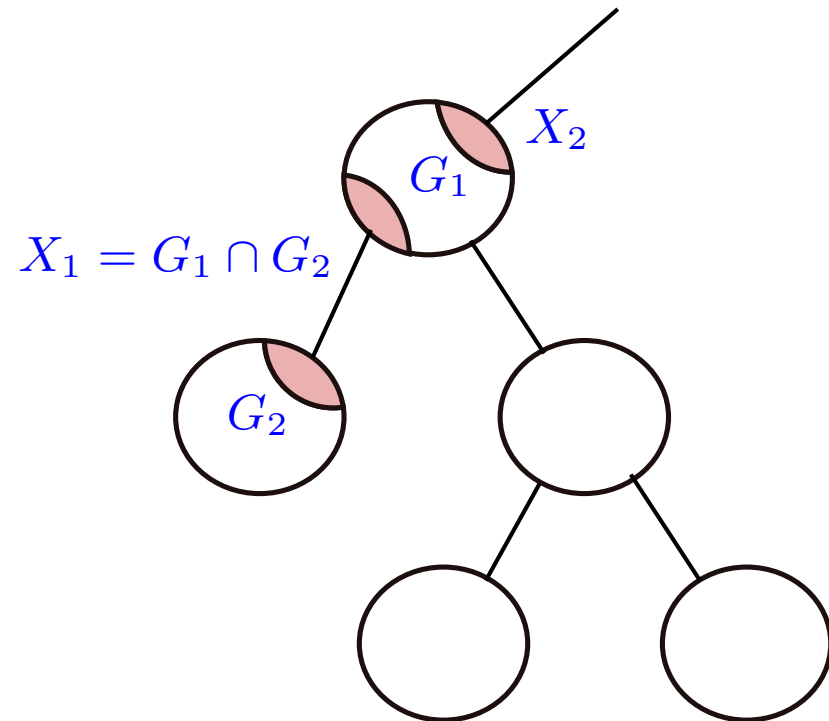
However, different clique-sum operations may apply to different cliques  $X$ .

## Bounding decompositions

While in a *bounded-width* tree-decomposition of  $G$ , the size of the individual bags is bounded, here we only have a bound on the size of the *intersections* between bags.

What we do have is a bound on the *local tree-width* of the bags  $G_1$  (by replacing structures in  $\mathcal{L}_{\lambda,\mu}$  by their encodings in  $\mathcal{L}_\lambda$ ).

*Idea:* the type of  $X_2$  in  $G_1 \oplus_X G_2$  is determined by the type of  $(G_1, \bar{x}_2)$ , the type of  $(G_2, \bar{x}_1)$  and the *local neighbourhood* of the clique  $X_1$  in  $G_1$ .





## Typing the Sum

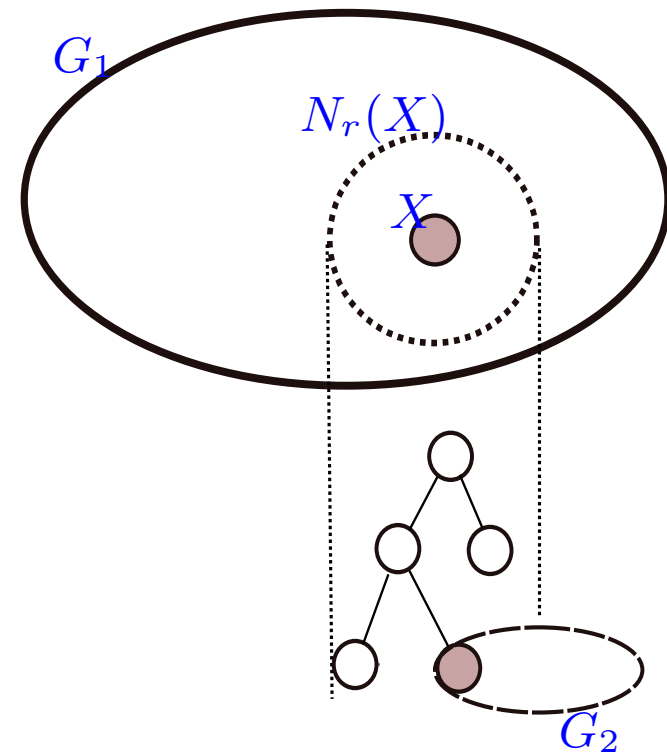
The tree-decomposition of  $N_r^{G_1}(X)$  determines a function  $\theta$  that takes the  $\equiv_m$ -type of  $(G_2, \bar{x}_2)$  to the  $\equiv_m$ -type of  $N_r^{G_1}(X) \oplus_X (G_2, \bar{x}_2)$

There are only finitely many such functions  $\theta$ .

Define the asymmetric clique-sum *of type  $\theta$* :

$$(G_1, \bar{y}) \oplus_{X, G_X}^{\theta} (G_2, \bar{x})$$

of taking the clique-sum of the two graphs, joining  $\bar{x}$  to a clique in  $G_1$  whose neighbourhood has type  $\theta$ .



## Automata on $\mathcal{M}_k$

Given a first-order sentence  $\varphi$ , it determines a radius of locality  $r$  and quantifier rank  $m$ .

- We have a finite collection of operations  $\oplus_{X, G_X}^\theta$  (depending on  $r$  and  $m$ ).
- We have structures  $(\mathbb{A}, \bar{x})$ , where the length of  $x$  is bounded by  $s$  (depending only on  $k$ ).

Thus, there are only finitely many  $\equiv_m$  classes.

- $\equiv_m$  is a congruence for each operation  $\oplus_{X, G_X}^\theta$ .

Thus, *first-order logic* is *fixed-parameter tractable* on  $\mathcal{M}_k$ .

**(Flum-Grohe)**

## Locally Excluded Minors

Let  $t : \mathbb{N} \rightarrow \mathbb{N}$  be a non-decreasing function.

$\text{LEM}_t$ —the class of structures  $\mathbb{A}$  such that for every  $a \in A$ :

$$K_{t(r)} \not\prec GN_r^{\mathbb{A}}(a)$$

We say that  $\mathcal{C}$  *locally excludes minors* if there is some function  $t$  such that  $\mathcal{C} \subseteq \text{LEM}_t$ .

### Theorem (D., Grohe, Kreutzer)

First-order logic is fixed-parameter tractable on every class  $\mathcal{C}$  that locally excludes minors.

## Application of Locality Method?

The result would be an easy application of the *locality method* if we had established:

There is an algorithm deciding  $\mathbb{A} \models \varphi$  in time  $f(l, k)n^c$   
 where  $k$  is the least value such that  $K_k \not\leq GA$

While the **Flum-Grohe** theorem does give a  $O(n^5)$  algorithm for the class of structures that exclude  $K_k$  as a minor, *it is not clear if the constants are bounded by a computable function of  $k$ .*

## Potential Sources of Uncomputability

1. The algorithm decomposing a graph in  $\mathcal{M}_k$  over the class  $\mathcal{L}_{\lambda,\mu}$  relies on a membership test in a *minor-closed superclass* of  $\mathcal{M}_k$ . It is not known whether the excluded minors for this class are given by a computable function of  $k$ .
2. The algorithm for reducing structures in  $\mathcal{L}_{\lambda,\mu}$  to  $\mathcal{L}_\lambda$  relies on membership tests for  $\mathcal{L}_{\lambda,\mu'}$  (for  $\mu' \leq \mu$ ) and it is not known if the excluded minors for these classes are given by a computable function of  $k$ .

**(D., Grohe, Kreutzer)** gives constructive solutions to both these problems.

## Constructive Decomposition

There is a *uniform in  $k$*  algorithm which computes a decomposition of a graph  $G \in \mathcal{M}_k$  over  $\mathcal{L}_{\lambda, \mu}$  in time  $O(n^4)$ .

Instead of *clique-sums*, the decomposition uses *neighbourhood-sums*.

$$(G_1, x) \odot_x (G_2, x)$$

is the graph obtained by taking the *disjoint sum* of  $G_1$  and  $G_2$  while identifying  $N_1(x)$  and *deleting  $x$* .

It is also shown that given  $G \in \mathcal{L}_{\lambda, \mu}$ , we can effectively find  $v_1, \dots, v_\mu$  such that  $G \setminus \{v_1, \dots, v_\mu\} \in \mathcal{L}_{\lambda'}$  for some  $\lambda'$  computable from  $\lambda$ .

## Review

We have gone from graphs of *bounded size* to *locally excluded minors* in four steps, alternating decomposition steps with localisation steps.

In general, these steps may be carried out for logics more expressive than first-order logic.

- Each decomposition gives rise to a notion of automata. What is the full power of these automata?
- Locality steps would work, not just for first-order logic, but the “Gaifman closure” of the logic. What is its power?

