

Definability of Linear Programming Problems

Anuj Dawar

University of Cambridge Computer Laboratory

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Recapitulation

Descriptive Complexity provides an alternative perspective on Computational Complexity.

For a first-order sentence φ , the class of its finite models can be decided in *polynomial time* and *logarithmic space*.

Existential second-order logic captures exactly the complexity class **NP**.

The search for a logic for **P** focusses on logics intermediate between first and second-order logic.

Recapitulation II

FP is a logic that extends first-order logic by means of *inductive definitions*.

On *linearly ordered structures*, FP exactly captures the complexity class P

In the absence of order, FP cannot express *evenness*. This is proved through a pebble game for L^k , first-order logic with k variables.

FPC is the extension of FP with a mechanism for *counting*. Its expressive power can be analyzed through a connection with C^k , first-order logic with k variables and *counting quantifiers*.

We aim to use this to show that solvability of linear systems of equations over \mathbb{Z}_2 is not definable in FPC..

Undefinability in FPC

To show that the *satisfiability* of systems of equations is not definable in FPC it suffices to show that for each k , we can construct two systems of equations

$$E_k \text{ and } F_k$$

such that:

- E_k is satisfiable;
- F_k is unsatisfiable; and
- $E_k \equiv^{C^k} F_k$

Constructing systems of equations

Take \mathcal{G} a 3-regular, connected graph.

Define equations $\mathbf{E}_{\mathcal{G}}$ with two variables x_0^e, x_1^e for each edge e .

For each vertex v with edges e_1, e_2, e_3 incident on it, we have eight equations:

$$E_v : \quad x_a^{e_1} + x_b^{e_2} + x_c^{e_3} \equiv a + b + c \pmod{2}$$

$\tilde{\mathbf{E}}_{\mathcal{G}}$ is obtained from $\mathbf{E}_{\mathcal{G}}$ by replacing, for exactly one vertex v , E_v by:

$$E'_v : \quad x_a^{e_1} + x_b^{e_2} + x_c^{e_3} \equiv a + b + c + 1 \pmod{2}$$

We can show: $\mathbf{E}_{\mathcal{G}}$ is satisfiable; $\tilde{\mathbf{E}}_{\mathcal{G}}$ is unsatisfiable.

Satisfiability

Lemma \mathbf{E}_G is satisfiable.

by setting the variables x_i^e to i .

Lemma $\tilde{\mathbf{E}}_G$ is unsatisfiable.

Consider the subsystem consisting of equations involving only the variables x_0^e .

*The sum of all **left-hand sides** is*

$$2 \sum_e x_0^e \equiv 0 \pmod{2}$$

*However, the sum of **right-hand sides** is 1.*

Now we show that, for each k , we can find a graph G such that $\mathbf{E}_G \equiv^{C^k} \tilde{\mathbf{E}}_G$.

Counting Game

Immerman and Lander (1990) defined a *pebble game* for C^k .

This is again played by *Spoiler* and *Duplicator* using k pairs of pebbles $\{(a_1, b_1), \dots, (a_k, b_k)\}$ on a pair of structures \mathbb{A} and \mathbb{B}

At each move, *Spoiler* picks i and a set of elements of one structure (say $X \subseteq B$)

Duplicator responds with a set of vertices of the other structure (say $Y \subseteq A$) of the same *size*.

Spoiler then places a_i on an element of Y and *Duplicator* must place b_i on an element of X .

Spoiler wins at any stage if the partial map from \mathbb{A} to \mathbb{B} defined by the pebble pairs is not a partial isomorphism

If *Duplicator* has a winning strategy for p moves, then \mathbb{A} and \mathbb{B} agree on all sentences of C^k of quantifier rank at most p .

Bijection Games

\equiv^{C^k} is also characterised by a k -pebble *bijection game*. **(Hella 96)**.
The game is played on graphs \mathbb{A} and \mathbb{B} with pebbles a_1, \dots, a_k on \mathbb{A} and b_1, \dots, b_k on \mathbb{B} .

- *Spoiler* chooses a pair of pebbles a_i and b_i ;
- *Duplicator* chooses a bijection $h : A \rightarrow B$ such that for pebbles a_j and $b_j (j \neq i)$, $h(a_j) = b_j$;
- *Spoiler* chooses $a \in A$ and places a_i on a and b_i on $h(a)$.

Duplicator loses if the partial map $a_i \mapsto b_i$ is not a partial isomorphism.

Duplicator has a strategy to play forever if, and only if, $\mathbb{A} \equiv^{C^k} \mathbb{B}$.

Equivalence of Games

It is easy to see that a winning strategy for *Duplicator* in the bijection game yields a winning strategy in the counting game:

Respond to a set $X \subseteq A$ (or $Y \subseteq B$) with $h(X)$ ($h^{-1}(Y)$), respectively).

For the other direction, consider the partition induced by the equivalence relation

$$\{(a, a') \mid (\mathbb{A}, \mathbf{a}[a/a_i]) \equiv^{C^k} (\mathbb{A}, \mathbf{a}[a'/a_i])\}$$

and for each of the parts X , take the response Y of *Duplicator* to a move where *Spoiler* would choose X .

Stitch these together to give the bijection h .

Cops and Robbers

A game played on an undirected graph $G = (V, E)$ between a player controlling k cops and another player in charge of a robber.

At any point, the cops are sitting on a set $X \subseteq V$ of the nodes and the robber on a node $r \in V$.

A move consists in the cop player removing some cops from $X' \subseteq X$ nodes and announcing a new position Y for them. The robber responds by moving along a path from r to some node s such that the path does not go through $X \setminus X'$.

The new position is $(X \setminus X') \cup Y$ and s . If a cop and the robber are on the same node, the robber is caught and the game ends.

Cops and Robbers on the Grid

If G is the $k \times k$ toroidal grid, then the *robber* has a winning strategy in the *k-cops and robbers* game played on G .

To show this, we note that for any set X of at most k vertices, the graph $G \setminus X$ contains a connected component with at least half the vertices of G .

If all vertices in X are in distinct rows then $G \setminus X$ is connected. Otherwise, $G \setminus X$ contains an entire row and column and in its connected component there are at least $k - 1$ vertices from at least $k/2$ columns.

Robber's strategy is to stay in the large component.

Cops, Robbers and Bijections

Suppose G is such that the *robber* has a winning strategy in the *k-cops and robbers* game played on G .

We use this to construct a winning strategy for Duplicator in the k -pebble bijection game on \mathbf{E}_G and $\tilde{\mathbf{E}}_G$.

- A bijection $h : \mathbf{E}_G \rightarrow \tilde{\mathbf{E}}_G$ is *good bar v* if it is an isomorphism everywhere except at the variables x_a^e for edges e incident on v .
- If h is good bar v and there is a path from v to u , then there is a bijection h' that is good bar u such that h and h' differ only at vertices corresponding to the path from v to u .
- Duplicator plays bijections that are good bar v , where v is the robber position in G when the cop position is given by the currently pebbled elements.

Computational Problems from Linear Algebra

Linear Algebra is a testing ground for exploring the boundary of the expressive power of FPC.

It may also be a possible source of new operators to extend the logic.

For a set I , and binary relation $A \subseteq I \times I$, take the matrix M over the two element field \mathbb{Z}_2 :

$$M_{ij} = 1 \quad \Leftrightarrow \quad (i, j) \in A.$$

Most interesting properties of M are invariant under permutations of I .

Matrix Multiplication

We can write a formula $\text{prod}(x, y, A, B)$ that defines the *product* of two matrices:

$$(\exists \nu_2 < t)(t = 2 \cdot \nu_2 + 1) \quad \text{for} \quad t = \#z(A(x, z) \wedge B(z, y))$$

A simple application of **ifp** then allows us to define $\text{upower}(x, y, \nu, A)$ which gives the matrix A^ν :

$$[\text{ifp}_{R, uv\mu} (\mu = 0 \wedge u = v \vee (\exists \mu' < \mu) (\mu = \mu' + 1 \wedge \text{prod}(u, v, B/R(\mu'), A)))](x, y, \nu),$$

where $\text{prod}(u, v, B/R(\mu'), A)$ is obtained from $\text{prod}(u, v, A, B)$ by replacing the occurrence of $B(z, v)$ by $R(z, v, \mu')$.

Matrix Exponentiation

We can, instead, represent numbers up to $2^{|A|}$ in *binary*.

That is, a unary relation Γ interpreted over the number domain (using numbers up to $|A|$) codes the number $\sum_{\gamma \in \Gamma} 2^\gamma$.

Repeated squaring then allows us to define $\text{power}(x, y, \Gamma, A)$ giving A^N where Γ codes a value N which may be exponential.

Non-Singularity

(Blass-Gurevich 04) show that *non-singularity* of a matrix over \mathbb{Z}_2 can be expressed in FPC.

$GL(n, \mathbb{Z}_2)$ —the *general linear group* of degree n over \mathbb{Z}_2 —is the group of non-singular $n \times n$ matrices over \mathbb{Z}_2 .

The order of $GL(n, \mathbb{Z}_2)$ divides

$$N = \prod_{i=0}^{n-1} (2^n - 2^i).$$

Thus, A is *non-singular* if, and only if, $A^N = \mathbf{I}$.
Moreover, the inverse A^{-1} is given by A^{N-1} .

Representing Finite Fields

We can represent matrices M over a finite field \mathbb{F}_q by taking, for each $a \in \mathbb{F}_q$ a binary relation $A_a \subseteq I \times I$ with

$$M_{ij} = a \quad \Leftrightarrow \quad (i, j) \in A_a.$$

Alternatively, we could have the elements of \mathbb{F}_q (along with the field operations) as a *separate sort* and include a ternary relation R

$$M_{ij} = a \quad \Leftrightarrow \quad (i, j, a) \in R.$$

These two representations are inter-definable.

FPC over Finite Fields

More generally, over the finite field \mathbb{F}_q , *matrix multiplication*; *non-singularity* of matrices; the *inverse* of a matrix; are all definable in FPC.

determinants and more generally, the coefficients of the *characteristic polynomial* can be expressed FPC.

(D., Grohe, Holm, Laubner, 2009)

solvability of systems of equations is *undefinable*.

the *rank* of a matrix is *undefinable*.

Linear Algebra over the Rational Field

Over the rational field \mathbb{Q} , we can also define *matrix multiplication*; *non-singularity* of matrices; the *inverse* of a matrix in FPC

Moreover, we can also define the coefficients of the *characteristic polynomial*

and, we can define the *rank* of a matrix and the *solvability* of systems of equations.

(Holm 2010)

The last result also follows from the stronger result that *optimization of linear programs* is expressible in FPC.

(Anderson, D., Holm 2015)

Representing Rational Numbers

We can take the rational number

$$q = s \frac{n}{d}$$

where $s \in \{1, -1\}$ and $n, d \in \mathbb{N}$
to be given by a structure

$$(B, <, S, N, D)$$

where $<$ is a linear order on the domain B and S , N and D are unary relations.

$S = \emptyset$ iff $s = 1$ and N and D code the binary representation of n and d .

Since the domain is ordered, it is straightforward to see that arithmetic, in the form of addition and multiplication of numbers is definable in **FPC**

Representing Rational Vectors and Matrices

A *rational vector* indexed by a set I :

$$v : I \rightarrow \mathbb{Q}$$

is represented by a structure over domain $I \cup B$ with relations:

- $<$ an order on B ;
- $S, N, D \subseteq I \times B$

Similarly, a *rational matrix* $M \in \mathbb{Q}^{I \times J}$ is given by a structure over domain $I \cup J \cup B$ with relations:

- $<$ an order on B ;
- $S, N, D \subseteq I \times J \times B$

Weighted Graphs

We use a similar encoding to represent problems over *weighted graphs* where the weights may be integer or rational.

For example, a graph with vertex set V with *non-negative rational* weights might be considered as a relational structure over universe $V \cup B$ where B is bigger than the number of bits required to represent any of the rational weights and we have

- $<$ an order on B ;
- *weight relations* $W_n, W_d \subseteq V \times V \times B$

Linear Programming

Linear Programming is an important algorithmic tool for solving a large variety of optimization problems.

It was shown by **(Khachiyan 1980)** that linear programming problems can be solved in polynomial time.

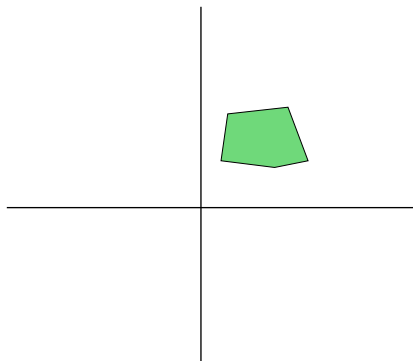
We have a set C of *constraints* over a set V of *variables*. Each $c \in C$ consists of $a_c \in \mathbb{Q}^V$ and $b_c \in \mathbb{Q}$.

Feasibility Problem: Given a linear programming instance, determine if there is an $x \in \mathbb{Q}^V$ such that:

$$a_c^T x \leq b_c \quad \text{for all } c \in C$$

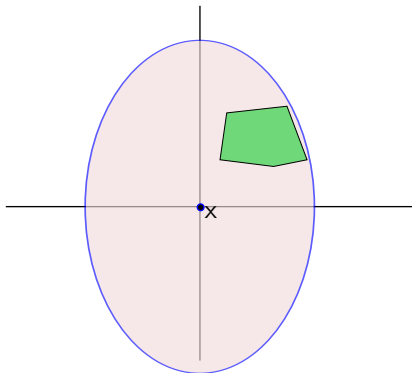
In **Anderson, D., Holm (2013)** we show that this, and the corresponding *optimization problem* are expressible in **FPC**.

Ellipsoid Method



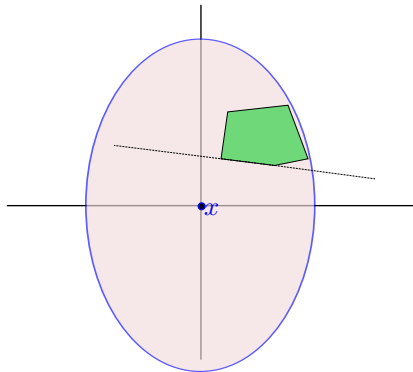
The set of constraints determines a *polytope*

Ellipsoid Method



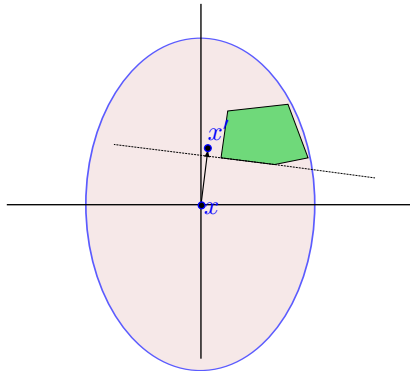
Start at the origin and calculate an *ellipsoid* enclosing it.

Ellipsoid Method



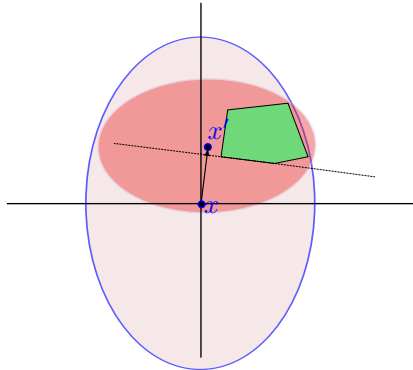
If the centre is not in the polytope, choose a constraint it *violates*.

Ellipsoid Method



Calculate a new *centre*.

Ellipsoid Method



And a new ellipsoid around the centre of at most *half* the volume.

Ellipsoid Method in FPC

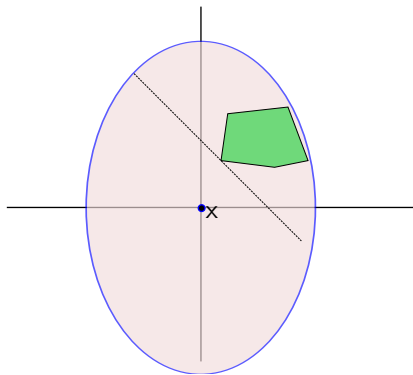
We can encode all the calculations involved in FPC.

This relies on expressing algebraic manipulations of *unordered* matrices.

What is not obvious is how to *choose* the violated constraint on which to project.

However, the ellipsoid method works as long as we can find, at each step, some *separating hyperplane*.

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However, the ellipsoid method works as long as we can find, at each step, some *separating hyperplane*.

So, we can take:

$$\left(\sum_{c \in S} a_c\right)^T x \leq \sum_{c \in S} b_c$$

where S is the *set* of all violated constraints.

Separation Oracle

More generally, the ellipsoid method can be used, even when the *constraint matrix* is not given explicitly, as long as we can always determine a *separating hyperplane*.

In particular, the polytope represented may have *exponentially many* facets.

Anderson, D., Holm (2013) shows that as long as the *separation oracle* can be defined in FPC, the corresponding *optimization problem* can be solved in FPC.

Representations of Polytopes

A *representation* of a class \mathcal{P} of *polytopes* is a *relational vocabulary* τ along with a surjective function ν taking τ -structures to polytopes in \mathcal{P} , which is isomorphism invariant.

A *separation oracle* for a representation ν, \mathcal{P} is definable in FPC if there is an FPC formula that given a τ -structure \mathbb{A} and a vector $v \in \mathbb{Q}^V$ either

- determines that $v \in \nu(\mathbb{A})$; or
- defines a hyperplane separating v from $\nu(\mathbb{A})$.

Folding Polytopes

We use the separation oracle to define an *ordered equivalence relation* on the set V of variables.

We also define a *projection* operation on polytopes which either

- preserves feasibility; or
- refines the equivalence relation further.

Graph Matching

Recall, in a *graph* $G = (V, E)$ a matching $M \subset E$ is a set of edges such that each vertex is incident on *at most* one edge in M .

We saw that the existence of a *perfect matching* is not definable in **FP**.

(Blass, Gurevich, Shelah 1999) showed that for *bipartite* graphs this is definable in **FPC**.

They conjectured that this was *not* the case for general graphs.

We consider the more general problem of determining the *maximum weight* of a matching in a *weighted graph*:

$$G = (V, E) \quad w : E \rightarrow \mathbb{Q}_{\geq 0}$$

The Matching Polytope

(Edmonds 1965) showed that the problem of finding a *maximum weight matching* in $G = (V, E)$ $w : \mathbb{Q}_{\geq 0}^E$ can be expressed as the following linear programming problem

$$\begin{aligned} \max w^\top y \quad & \text{subject to} \\ Ay &\leq 1^V, \\ y_e &\geq 0, \quad \forall e \in E, \\ \sum_{e \in E \cap W^2} y_e &\leq \frac{1}{2}(|W| - 1), \quad \forall W \subseteq V \text{ with } |W| \text{ odd}, \end{aligned} \tag{1}$$

Matching in FPC

We show that a *separation oracle* for this polytope is definable by an FPC formula interpreted in the weighted graph G .

As a consequence, there is an FPC formula defining the *size* of the maximum matching in G .

Note that this does not allow us to define an *actual* matching.