

# Nominal System T

Andrew Pitts



**Primitive Recursion:** recursive definitions of (total) functions where value at a *structure* is a given function of its value at *immediate substructures*.

- ▶ Gödel (Tate) System T — **structure** = numbers.
- ▶ Burstall, Martin-Löf *et al* generalized this to **abstract syntax trees**.

Primitive Recursion: recursive definitions of (total) functions where value at a *structure* is a given function of its value at *immediate substructures*.

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- ▶ **Nominal System T** (NST): generalizes to **abstract syntax trees quotiented by  $\alpha$ -equivalence** via Odersky-style local names + name-permutations.

NST formalizes common practice with bound names, e.g. . . .

$\lambda$ -terms  $t = \lambda$ -trees mod  $\alpha$ -equivalence

$a \mapsto V a$	variables
$t, t' \mapsto A t t'$	application terms
$a, t \mapsto L a. t$	$\lambda$ -abstraction terms

Typical e.g. of “not quite” primitive recursion:

$$f = (-)[t_1/a_1]$$

(capture-avoiding substitution)

is well-(and totally-)defined by:

$$\begin{aligned} f(\forall a) &= \text{if } a = a_1 \text{ then } t_1 \text{ else } \forall a \\ f(\Lambda t t') &= \Lambda (f t) (f t') \\ f(\text{L } a. t) &= \text{L } a. (f t) \quad \text{if } a \# a_1, t_1 \end{aligned}$$

In general:

$$\begin{aligned} f(\vee a) &= f_1 a \\ f(\wedge t t') &= f_2 t t' (f t) (f t') \\ f(\text{L } a . t) &= f_3 a t (f t) \end{aligned} \quad \text{if } a \# f_1, f_2, f_2$$

In general:

$$\begin{aligned} f(\forall a) &= f_1 a \\ f(\text{A } t t') &= f_2 t t' (f t) (f t') \\ f(\text{L } a. t) &= f_3 a t (f t) \quad \text{if } a \# f_1, f_2, f_2 \end{aligned}$$

$$\begin{aligned} &= \text{L } a'. t' && = f_3 a' t' (f t') \end{aligned}$$

Q: how to get rid of this inconvenient proof obligation?

In general:

$$\begin{aligned} f(V a) &= f_1 a \\ f(A t t') &= f_2 t t' (f t) (f t') \\ f(L a. t) &= \nu a. f_3 a t (f t) \quad [ a \# f_1, f_2, f_2 ] \end{aligned}$$

$= L a'. t'$

$= \nu a'. f_3 a' t' (f t')$  OK!

Q: how to get rid of this inconvenient proof obligation?

A: use a local scoping construct  $\nu a. (-)$  for names



In general:

$$\begin{aligned} f(\mathbb{V} a) &= f_1 a \\ f(\mathbb{A} t t') &= f_2 t t' (f t) (f t') \\ f(\mathbb{L} a. t) &= \mathbf{va.} f_3 a t (f t) \quad [ a \# f_1, f_2, f_2 ] \end{aligned}$$

A: use **a** local scoping construct  $\mathbf{va.}(-)$  for names

which one?!

# Dynamic allocation

- ▶ Familiar—widely used in practice.
- ▶ Stateful:  $va.e$  means “add a fresh name  $a'$  to the current state and return  $e[a'/a]$ ”

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- ▶ Familiar—widely used in practice.
- ▶ Stateful:  $\nu a. e$  means “add a fresh name  $a'$  to the current state and return  $e[a'/a]$ ”
- ▶ Disrupts familiar mathematical properties of pure datatypes. E.g. tuples do not behave extensionally:

	$\text{fst}(\nu a a'. (a, a')) \approx \text{fst}(\nu a. (a, a))$
and	$\text{snd}(\nu a a'. (a, a')) \approx \text{snd}(\nu a. (a, a))$
but	$\nu a a'. (a, a') \not\approx \nu a. (a, a)$
	(consider case $[-]$ of $(x, x') \rightarrow x = x'$ )

(and similar nasties for functions).

So we reject it in favour of...

# Odersky's *va.* (—) [POPL'94]

- ▶ Unfamiliar—apparently not used in practice (so far).
- ▶ Pure equational calculus.
- ▶ Tuples and functions obey familiar mathematical laws, because

$$\begin{aligned}va.(\lambda x.e) &\approx \lambda x.(va.e) \\va.(e, e') &\approx (va.e, va.e')\end{aligned}$$

so e.g. unlike for dynamic allocation, one has

$$\begin{aligned}va a'.(a, a') &\approx (va a'.a, va a'.a') \\ &\approx (va.a, va.a) \\ &\approx va.(a, a)\end{aligned}$$

# Name-permutation expressions

Expression  $(a \ a') * e$  denotes the result of swapping names  $a$  and  $a'$  in the structure denoted by the expression  $e$ .

Gives rise to a form of **non-binding abstraction**

$$L(a, e) \triangleq L a'. (a' \ a) * e \quad [a' \# a, e]$$

$a$  is free in this expression



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$$L(a, e) \triangleq L a'. (a' \ a) * e \quad [a' \# a, e]$$

Makes NST's form of primitive recursion sufficiently expressive.

$$\begin{aligned} f(\mathbb{V} a) &= f_1 a \\ f(\mathbb{A} t t') &= f_2 t t' (f t) (f t') \\ f(\mathbb{L} a. t) &= \nu a. f_3 a t (f t) \quad a \# f_1, f_2, f_3 \end{aligned}$$

e.g. for capture-avoiding substitution  $f_3 a t x \triangleq L(a, x)$

# Main results

A new model of Odersky's *va.* (—)  
using Gabbay-Pitts **nominal sets**



Decidability of the NST conversion relation  
proved by a normalization-by-evaluation argument



All  **$\alpha$ -structurally recursive functions** [JACM 53(2006)]  
can be adequately represented in Nominal System T.

# Future work

- ▶ **Dependent Types**

Extend NST's primitive recursion to encompass structural **induction mod  $\alpha$**  in versions of

Agda [Martin-Löf TT]

Coq [Calculus of Inductive Constructions]

with Odersky- $\nu$  + name-permutations.



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- ▶ **(Pure) Functional Programming**

Operational semantics: Odersky- $\nu$  + name-permutations

- + call-by-value/name functions... OK

- + call-by-need functions... ???

Relationship of Odersky- $\nu$  with dynamic allocation?