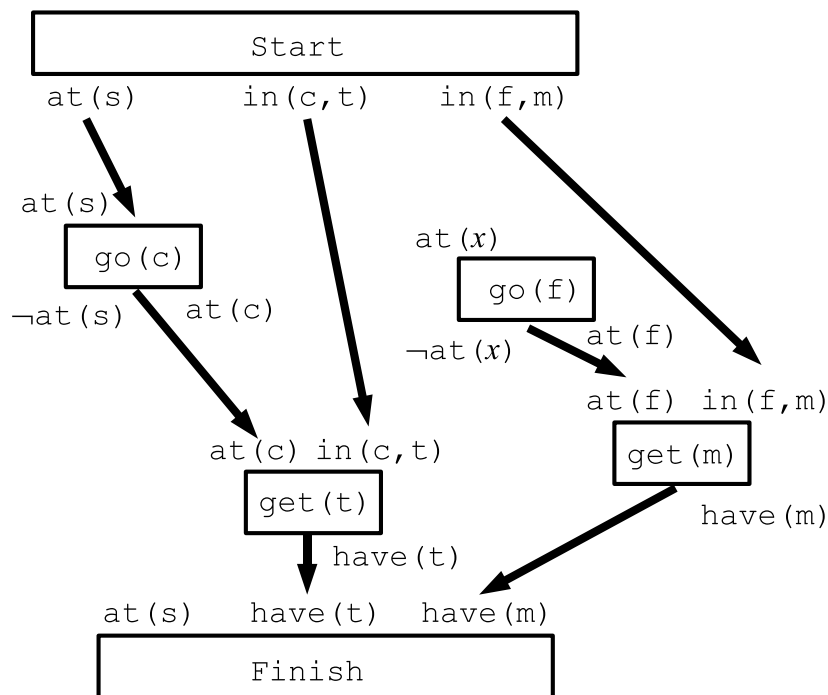


## 2008 Paper 11 Question 5

### Artificial Intelligence I

A brilliant student has finished his exams and is making a well-deserved cup of tea. He is confused, however, and is trying to use the *partial order planning* algorithm to solve part of the problem. Using the abbreviations *f* for “fridge”, *c* for “cupboard”, *s* for “sink”, *m* for “milk” and *t* for “tea”, his start state is  $\{\text{at}(s), \text{in}(c, t), \text{in}(f, m)\}$ . Using  $x$  and  $y$  to denote variables, he has two actions. The first action is  $\text{get}(y)$  having preconditions  $\text{at}(x)$  and  $\text{in}(x, y)$ , and effect  $\text{have}(y)$ . The second action is  $\text{go}(y)$  having precondition  $\text{at}(x)$  and effects  $\neg\text{at}(x)$  and  $\text{at}(y)$ . His goal is  $\{\text{at}(s), \text{have}(t), \text{have}(m)\}$ . So far he has made the following attempt at finding a plan:



In this diagram, arrows denote causal links.

- Can the  $\text{at}(x)$  precondition on  $\text{go}(f)$  be achieved by adding an ordering constraint and causal link from **Start** to  $\text{go}(f)$ , and perhaps one or more further ordering constraints, in such a way that the plan remains valid? Explain your answer. [4 marks]
- Describe a method, different from any suggested in part (a), by which the  $\text{at}(x)$  precondition on  $\text{go}(f)$  can be achieved in such a way that the plan remains valid. [8 marks]
- Describe a way in which the plan can be completed after making the addition you have described in part (b). [8 marks]