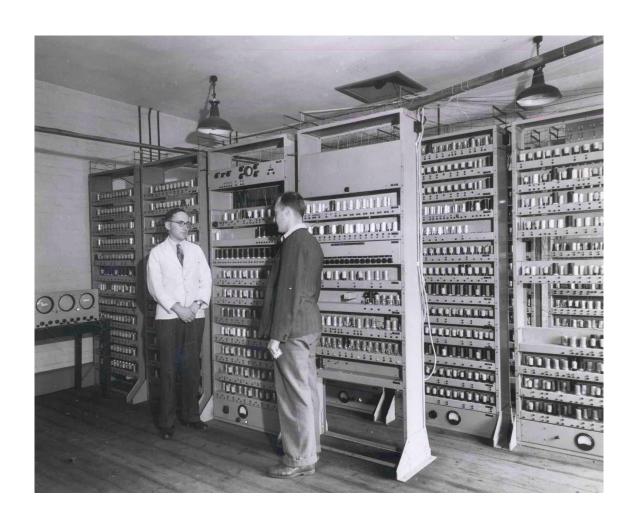
# Reliability

Advanced Topics in Computer Architecture

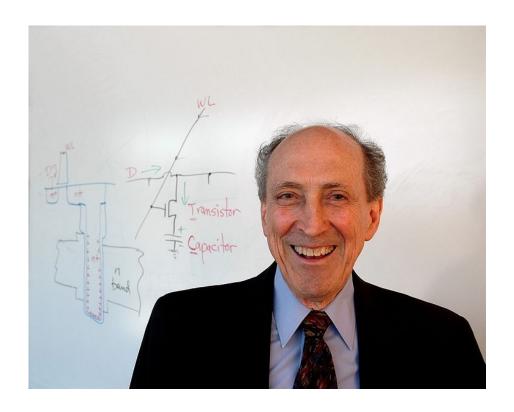
**Timothy Jones** 

# Historic reliability



# Silicon trends





# Why we care now

- Microprocessors are increasingly used in situations where we want to be sure of their correctness
  - Self-driving cars, nuclear power stations, medical devices, etc
- Many industrial sectors mandate the use of error-detection strategies
  - For example, ASIL standards in automotive
- With increased susceptibility to faults, even non-safety-critical computing starts to require fault tolerance

https://perspectives.mvdirona.com/2009/10/you-really-do-need-ecc-memory/

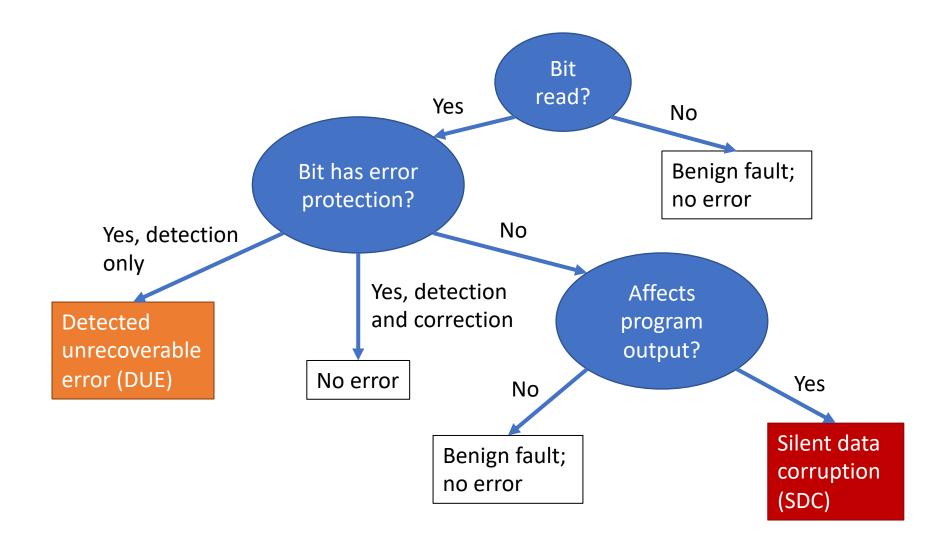
#### Hard errors

- Permanent errors that affect operation
- Caused by device wearout in-the-field
- Also can occur from manufacturing variabilities

#### Soft errors

- Transient errors that can affect operation
  - They are transient because their effects don't last
  - They are not repeatable
- Caused by
  - Alpha particle strikes
  - Cosmic rays!

### Error manifestation



# Identifying vulnerabilities

- We can perform an analysis of processor structures to identify vulnerable state
- We identify the bits that are required for architecturally correct execution (ACE)
- These bits could result in incorrect output if they were flipped
- The architectural vulnerability factor (AVF) is a useful metric

$$AVF = \frac{\sum_{i=0}^{ncycles} ACEbits}{ncycles * nbits}$$

# Identifying vulnerabilities

• Bits can be ACE in some cycles, not ACE in others

• Registers, for example Most significant bits unACE if used r0 as a 32-bit r1number 0x00000000feedcafe 0x1234567890123456 All ACE if read 0x???????????????? again, or all unACE if last All unACE until next cycle where this read has will be written to occurred and represent r2

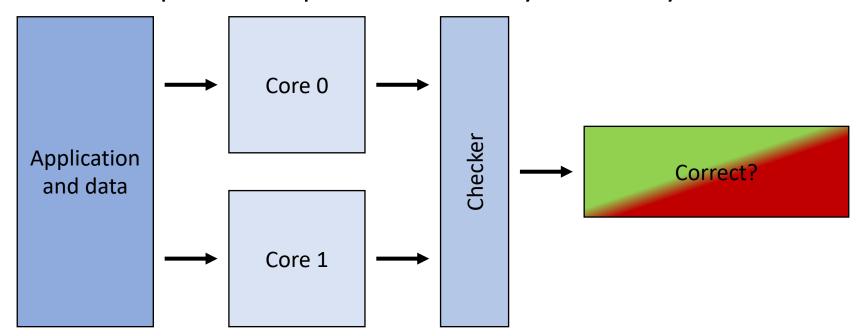
#### Metrics

- Two related metrics are often used to define reliability
- The FIT rate (failures in time)
  - Defined as the total number of errors per billion device hours
- MTTF (mean time to failure)
  - Represents the time between two errors

$$MTTF \sim \frac{1}{FIT}$$

### Dual-core lockstep

- In a system with dual-core lockstep, a program is run twice on different cores
  - Results compared at each cycle
  - Introduces temporal and spatial redundancy into the system



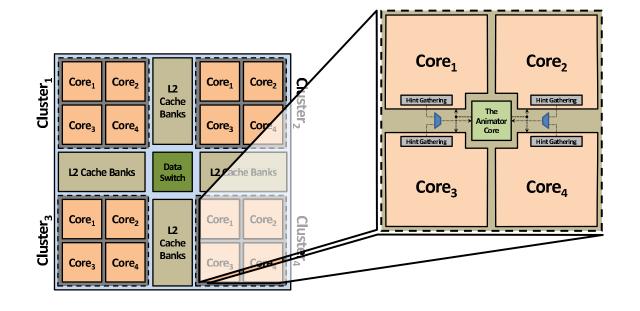
### Redundant multithreading

- Run two versions of code and compare results
  - Can be a software scheme, perhaps with some hardware support
  - Or a purely hardware approach
- Can run on different cores with one passing the other data
- Or the same core, within a different SMT context

## Taking advantage of faulty hardware

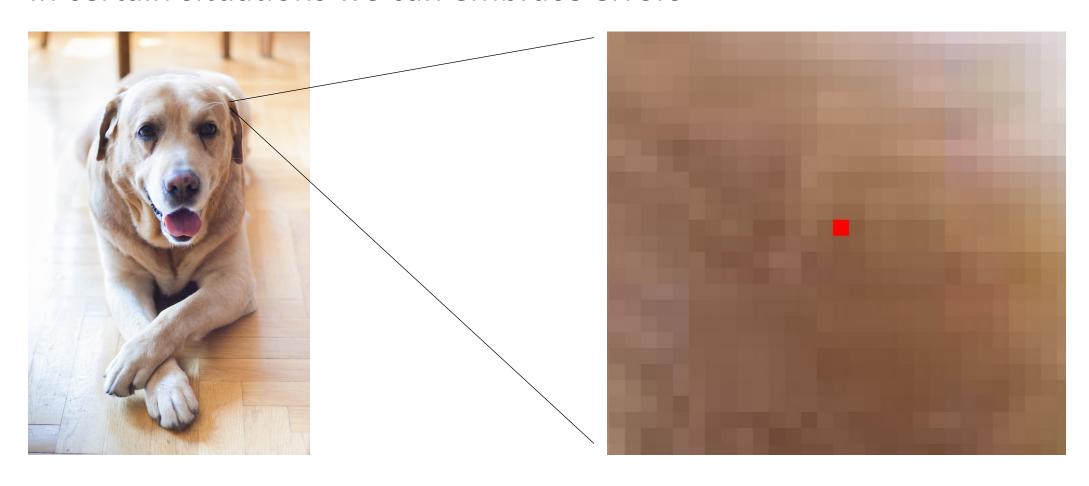
 Some systems use the faulty core to provide hints to others

 For example, Necromancer: Enhancing System Throughput by Animating Dead Cores Ansari, Feng, Gupta and Mahlke ISCA 2010



# Approximate computing

• In certain situations we can embrace errors



### Summary

Reliability is a problem that has come back to haunt us

- Required for safety-critical systems
  - Increasing needed / desired in others too

- A variety of techniques developed to
  - Identify which parts of the core are vulnerable
  - Reduce vulnerability to errors by re-executing parts of the code
  - Embrace the unreliability for performance