

Foundations of Computer Science

Lecture 12:

Recapping and Real World Use!

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1st Nov 2023

Goals of Programming

- to **describe a computation** so that it can be done *mechanically*:
 - *expressions* compute *values*
 - *commands* cause *effects*
- to do so **efficiently and correctly**, giving right answers *quickly*
- to allow **easy modification** as our needs change
 - through an orderly *structure* based on *abstraction* principles
 - programmer should be able to predict effects of changes

Why Program in OCaml?

- It is **interactive**.
- It has a flexible notion of **data type**.
- It hides the underlying hardware: **no crashes**.
- Programs can easily be **understood mathematically**.
- It **distinguishes naming** from updating memory.
- It **manages storage** in memory for us.

Language

Static type
checking

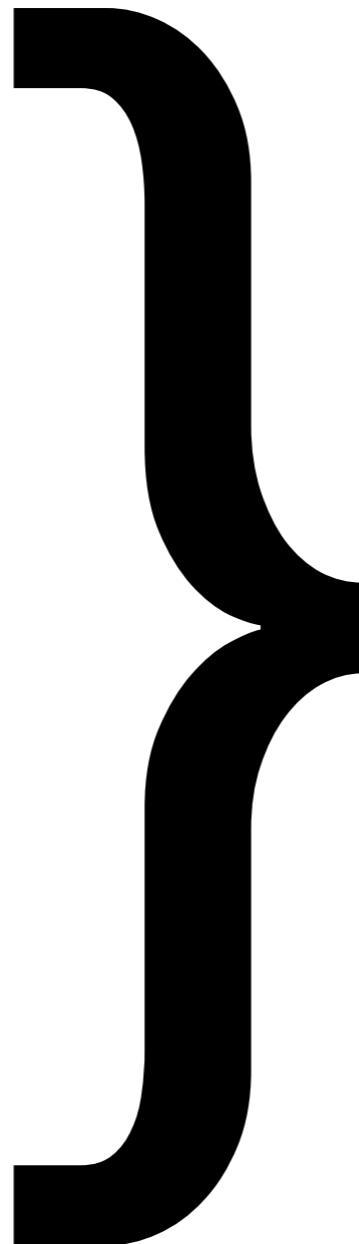
Parametric
Polymorphism

Type Inference

Algebraic Data
Types

Pattern Matching

First Class
Functions



Abstraction

Language

Static type
checking

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Polymorphism

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Functions

```
# let x = "1" + 1 ;;
```

```
Error: This expression has type string but  
an expression was expected of type int
```

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```
# let x = "1" + 1 ;;
```

```
Error: This expression has type string but  
an expression was expected of type int
```

1A Object Oriented Programming

Prof Rob Harle

Language

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```
# type 'a tree =  
  | Lf  
  | Br of 'a * 'a tree * 'a tree
```

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```
# let fn l = List.map (fun (a,b) ->  
    string_of_int a ^ b) l;;
```

```
val fn : (int * string) list -> string list  
= <fun>
```


Language

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1B Concepts in Programming Languages

1B Further Java

II Types

Language

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Functions

```
# type vehicle =  
  | Car of bool  
  | Motorbike of int  
  | Bicycle
```

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```
# type vehicle =  
  | Car of bool  
  | Motorbike of int  
  | Bicycle  
  
# match v with  
  | Car false -> "car"  
  | Car true  -> "reliant robin"  
  ...
```

Language

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1B Semantics of Programming Languages

```
# type vehicle =  
  | Car of bool  
  | Motorbike of int  
  | Bicycle  
  
# match v with  
  | Car false -> "car"  
  | Car true  -> "reliant robin"  
  ...
```

Language

Static type
checking

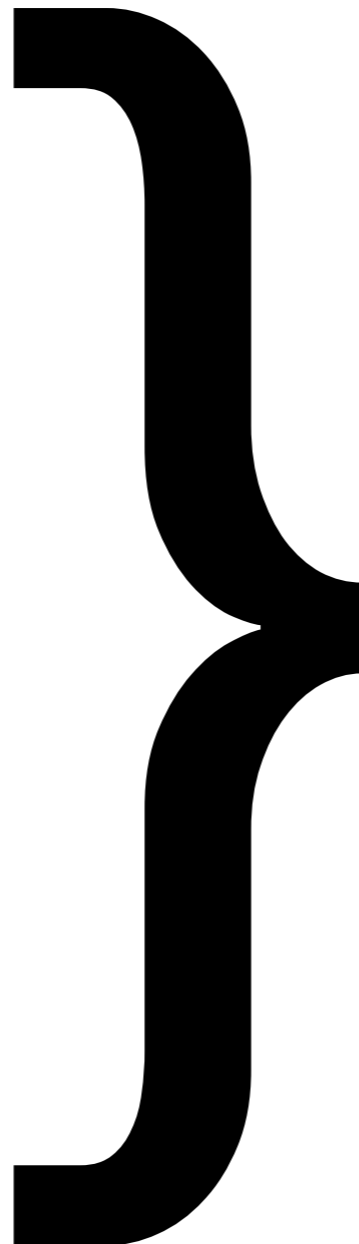
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Abstraction

Runtime

Fast Foreign
Functions

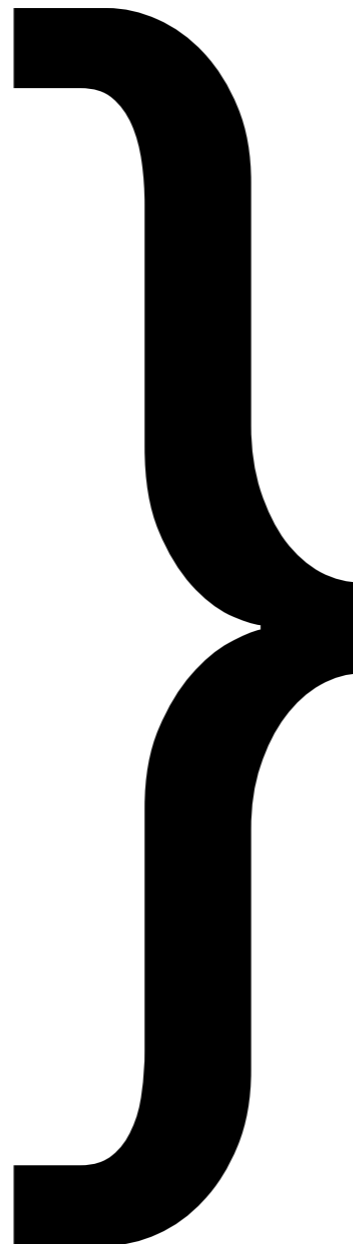
Static Linking

Garbage
Collection

Fast Native Code

Multiarchitecture

Portable Bytecode



Execution

Runtime

Fast Foreign
Functions

Static Linking

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Multiarchitecture

Portable Bytecode

Upcoming Courses:

1A Operating Systems

1B Compiler Construction

1B Programming in C/C++

OCaml: a system



Runtime

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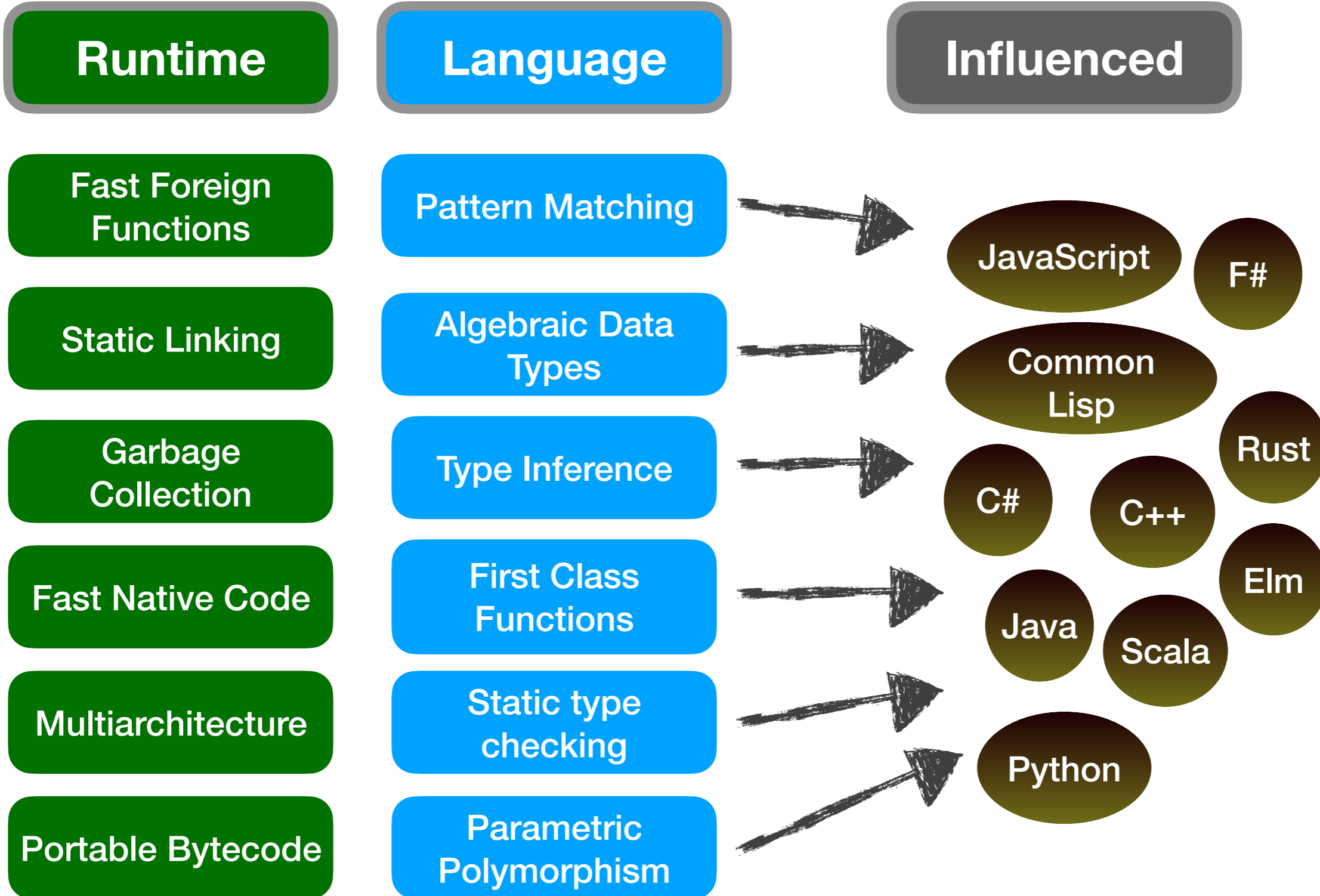
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OCaml (& ML): Influences



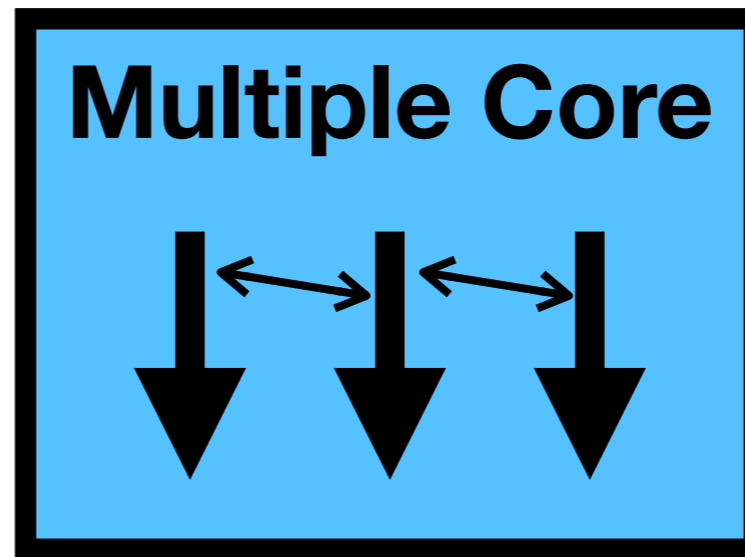
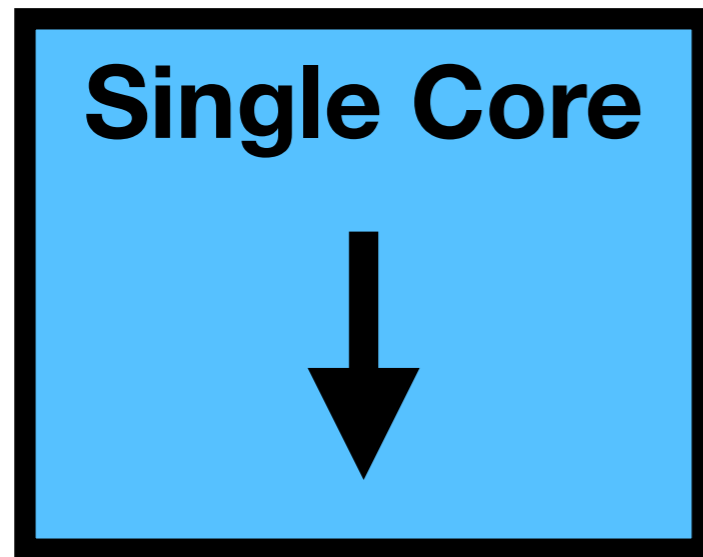
OCaml: scaling

Single Core



Execution sequential.
Why bother with
immutable values?

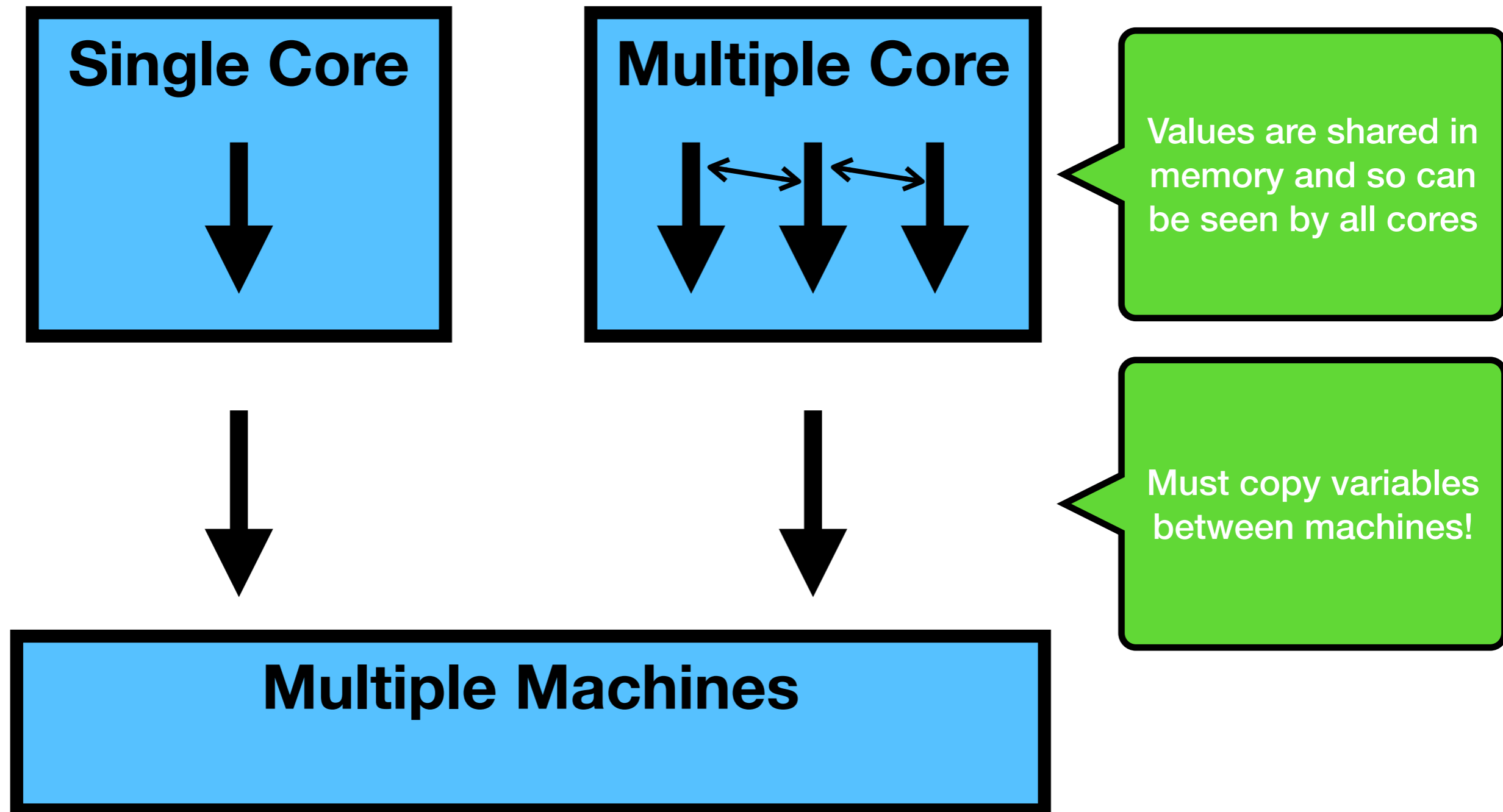
OCaml: scaling



Values are shared in memory and so can be seen by all cores

OCaml: scaling

1B Concurrent & Distributed Systems



OCaml: Applications



Runtime

Language

Flexibility

Fast Foreign
Functions

Pattern Matching

JavaScript

Wasm

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FPGAs

Microcontrollers

Garbage
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Unix

Mobile

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OCaml: Web Programming



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Parametric Polymorphism

JavaScript

Wasm



<https://rescript-lang.org>

ReScript is a robustly typed language that compiles to efficient and human-readable JavaScript. It comes with a lightning fast compiler toolchain that scales to any codebase size.

OCaml: Building Hardware



Runtime

Language

Flexibility



OCaPIC: PIC microcontrollers programmed in OCaml

Static Linking

Algebraic Data Types



FPGAs

Microcontrollers

Garbage Collect

Type Inference



Fast Native



ORCONF2015

**Writing hardware in OCaml,
Running OCaml in hardware**

Andrew Ray

Multiarchit

Portable By

HardCaml is a structural hardware design DSL embedded in OCaml. The library can be used for front end design tasks up to the synthesis stage where a VHDL or Verilog netlist is generated. Libraries for fast simulation using LLVM, waveform viewing and co-simulation with Icarus Verilog are provided.

HardCaml-RiscV is a simple pipelined RV32I core, targetted towards a FPGA implementation and built with HardCaml.

Jane Street

Been using OCaml for twenty years or so, with ~30 million lines of code.

~2000 employees, many of whom code in OCaml, with ~600 fulltime developers.

Much of the core source code is available as open source code: realworldocaml.org

**And a really fun podcast at:
<https://signalsandthreads.com/>**

Portable Bytecode

Parametric
Polymorphism

OCaml: Operating Systems



Runtime

Language

Flexibility

MIRAGE OS

Blog

Docs

API

Canopy

Community

A programming framework for building type-safe, modular systems

MirageOS is a library operating system that constructs [unikernels](#) for secure, high-performance network applications across a variety of cloud computing and mobile platforms. Code can be developed on a normal OS such as Linux or MacOS X, and then compiled into a fully-standalone, specialised unikernel that runs under a [Xen](#) or [KVM](#)

Recent Updates *all*

- [MirageOS running on the ESP32 embedded chip \(26 Jan 2018\)](#)
- [MirageOS Winter 2017 hack retreat roundup \(23 Dec 2017\)](#)

Fast Native Code

First Class Functions

Unix

Mobile

Unikernels

Containers



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Parametric Polymorphism

<https://mirage.io>

Docker

The most popular way to share and extend software distributions.

13m+ developers use Docker for Desktop daily.

7m+ applications developed.

13 billion monthly image downloads.

At the heart of desktop integration on Windows and Mac, there are services written in OCaml that process every byte of traffic.

<https://github.com/moby/vpnkit>

Find out more in Part II Cloud Computing!

OCaml: Safety Critical



Runtime

Lang

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Pattern M

Static Linkin



ebra
Typ

flow Getting Started Docs Try Blog

FLOW IS A STATIC TYPE CHECKER FOR JAVASCRIPT.

GET STARTED INSTALL FLOW Star

Current Version: [v0.66.0](#)

Garbage
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Type Inference



Fast Native Co

The Coq Proof Assistant

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<https://coq.inria.fr>

Proof
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Static
Analysis

OCaml: Predictable Robots!



Run

Creating safe robots with Imandra



Kostya Kanishev [Follow](#)

Jul 9, 2018 · 3 min read

Fast
Fun

From self-driving cars to medical surgeons, robots have become ubiquitous. Ensuring they operate safely and correctly is evermore important. The most popular middleware for robotics is the open-sourced Robot OS. We have begun work on developing an Imandra interface to Robot OS, opening up the world of robotics to the latest advancements in automated reasoning. In this post, we showcase our early results, discuss our roadmap and our submission for a talk at the upcoming ROSCon 2018 (Madrid, Spain).

Static

Game
Code

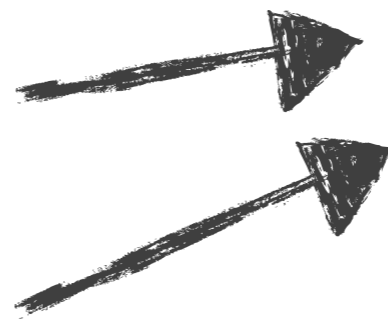
Fast N

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www.imandra.ai

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OCaml: Data Science



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ocaml.xyz



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