

Introduction to Probability

Lecture 11: Estimators (Part II)

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Outline

Recap

Estimating Population Sizes

Mean Squared Error

Estimating Population Sizes through Collisions

Recap: Unbiased Estimators and Bias

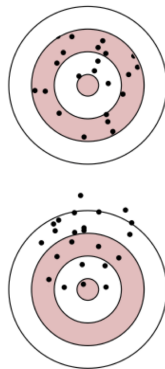
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An **estimator** T is called an **unbiased estimator** for a parameter θ if

$$\mathbf{E}[T] = \theta,$$

irrespective of the value θ . The **bias** is defined as

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Source: Edwin Leuven (Point Estimation)

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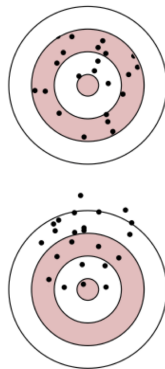
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- How can we **measure** the accuracy of an estimator?
 \leadsto bias and mean-squared error
- If there are several **unbiased** estimators, which one to choose? \leadsto mean-squared error (or variance)

Recap

Estimating Population Sizes

Mean Squared Error

Estimating Population Sizes through Collisions

Estimating Population Sizes (First Version)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
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 - their number must satisfy $n \leq N$

First Estimator Based on Sample Mean

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Construct an unbiased estimator using the sample mean.

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- The sample mean is

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

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$$T_1 := 2 \cdot \bar{X}_n - 1.$$

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- Achieving **unbiasedness** alone is not a good strategy
- **Improvement:** find an estimator which always returns a value at least $\max(X_1, X_2, \dots, X_n)$

Intuition: Constructing an Estimator based on Maximum

- Suppose $N = 100$ and $n = 15$

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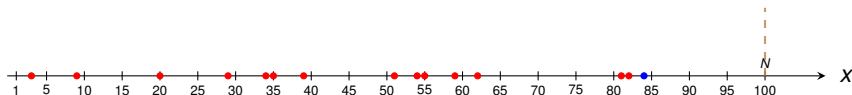
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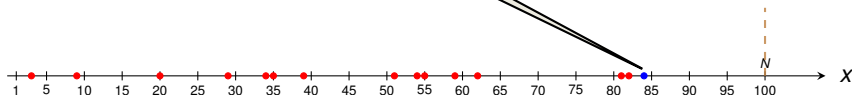


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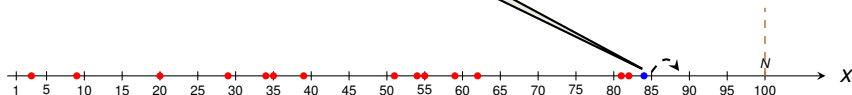


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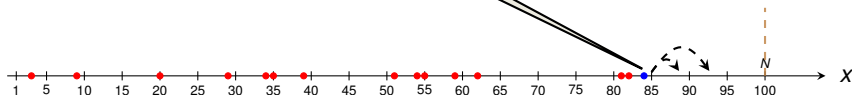


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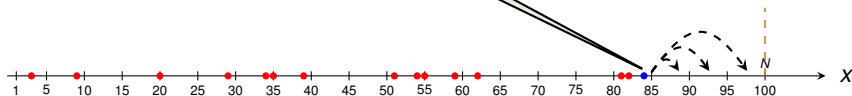


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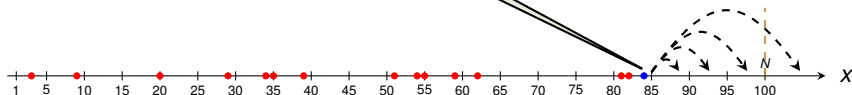


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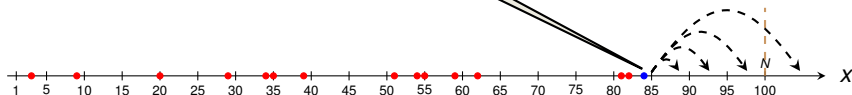


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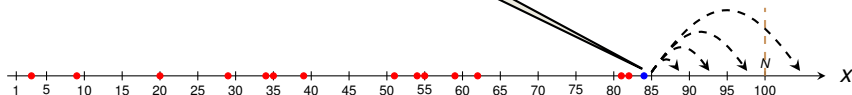
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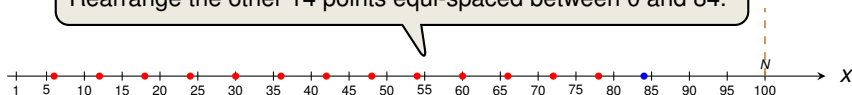
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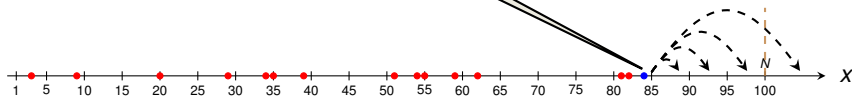


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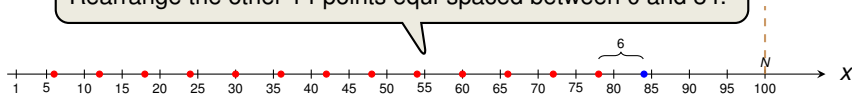
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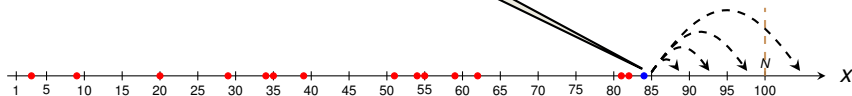


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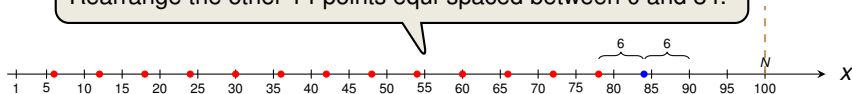
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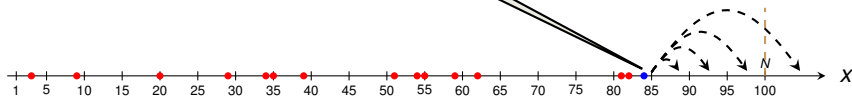
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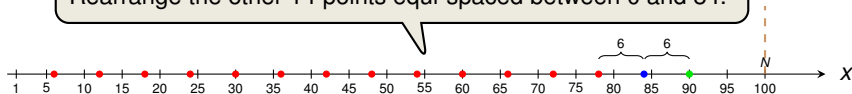
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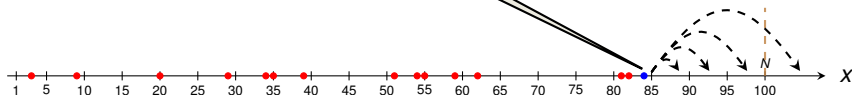
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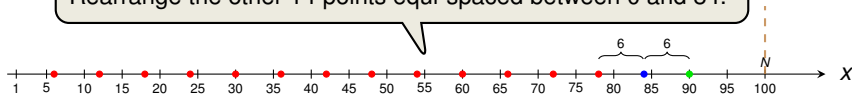
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$$\max(X_1, \dots, X_n) + \frac{\max(X_1, \dots, X_n)}{n-1}$$

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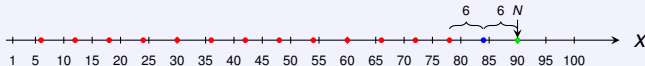
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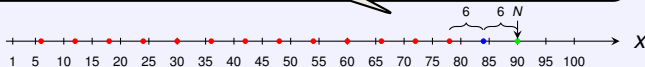
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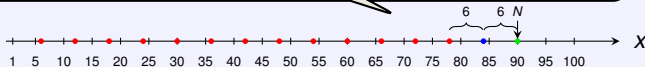
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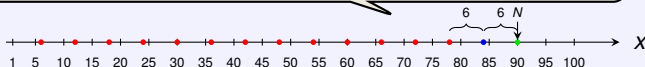
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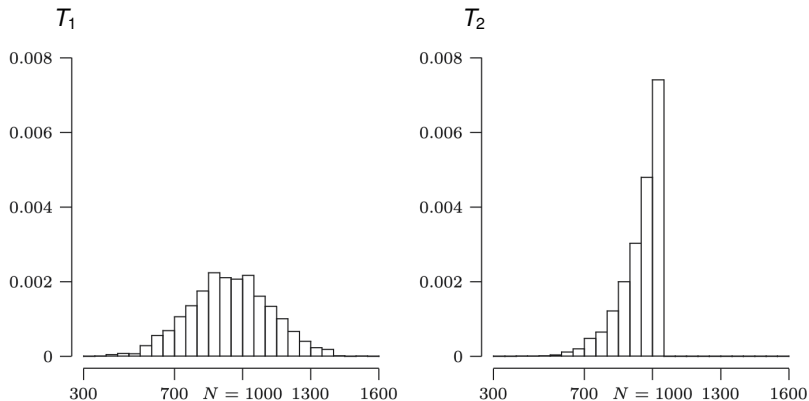
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- Hence we obtain an **unbiased estimator** by

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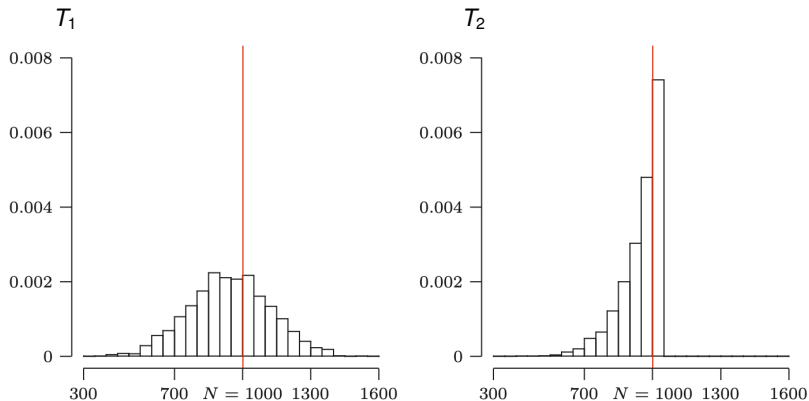
Empirical Analysis of the two Estimators



Source: Modern Introduction to Statistics

Figure: Histogram of 2000 values for T_1 and T_2 , when $N = 1000$ and $n = 10$.

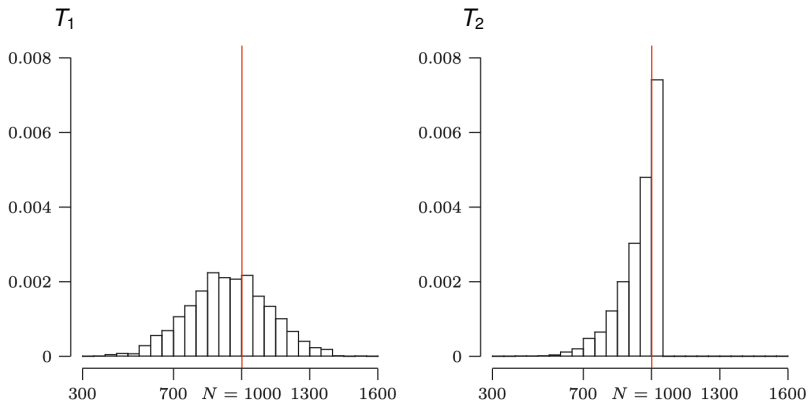
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Can we find a quantity that captures the superiority of T_2 over T_1 ?

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$$\mathbf{MSE} [T] = \underbrace{(\mathbf{E} [T] - \theta)^2}_{= \text{Bias}^2} + \underbrace{\mathbf{V} [T]}_{= \text{Variance}}$$

- If T_1 and T_2 are both **unbiased**, T_1 is **better** than T_2 iff $\mathbf{V} [T_1] < \mathbf{V} [T_2]$.

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The **mean squared error** of T is

$$\mathbf{MSE} [T] = \mathbf{E} \left[(T - \theta)^2 \right].$$

- According to this, estimator T_1 **better** than T_2 if $\mathbf{MSE} [T_1] < \mathbf{MSE} [T_2]$.

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~> **Minimum-Variance Unbiased Estimator (MVUE)**
(the unbiased estimator with the smallest variance).

Bias-Variance Decomposition: Derivation

Example 3

We need to prove: $\mathbf{MSE}[T] = (\mathbf{E}[T] - \theta)^2 + \mathbf{V}[T]$.

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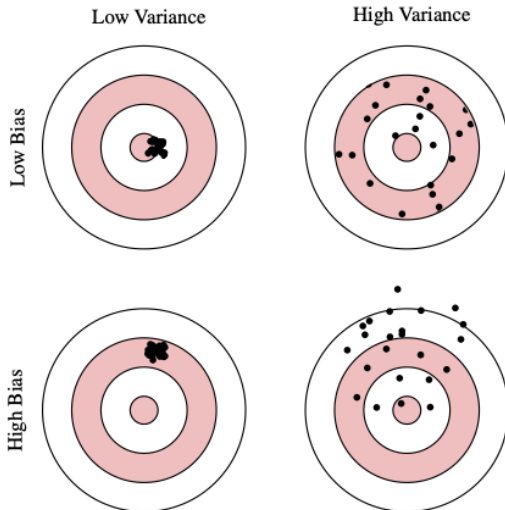
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Bias-Variance Decomposition: Illustration



Source: Edwin Leuven (Point Estimation)

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It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

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- Rearranging and simplifying gives

$$\mathbf{V} [T_1] = \frac{(N+1)(N-n)}{3n}.$$

Analysis of the MSE for T_2 (Sketch)

Example 5

It holds that $\mathbf{MSE}[T_2] = \Theta\left(\frac{N^2}{n^2}\right)$, where $T_2 = \frac{n+1}{n} \cdot \max(X_1, \dots, X_n) - 1$.

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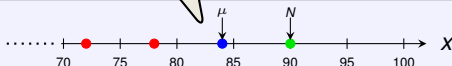
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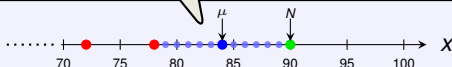
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Maximum could have equally likely taken any value between 79 and 90

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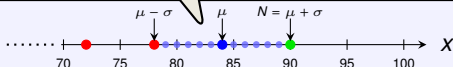
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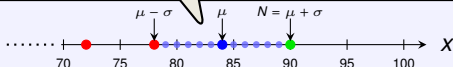
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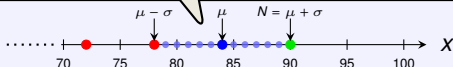
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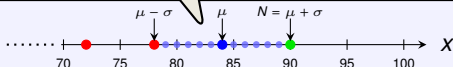
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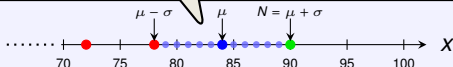
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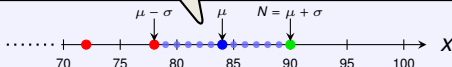
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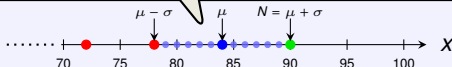
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Outline

Recap

Estimating Population Sizes

Mean Squared Error

Estimating Population Sizes through Collisions

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— Previous Model —

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- We take **uniform** samples from S **without replacement**
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Let us call this a **collision**

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A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S **without replacement**
- Goal:** Find estimator for N

This also applies to situations where elements are not labelled before we see them first time (e.g., **Mark & Recapture Method**)

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S **with replacement**
- Goal:** Find estimator for N

- Suppose $n = 6$, $N = 11$, $S = \{3, 4, 7, 8, 10, 15.83356, 20, 21, 56, 81, 10000\}$
- Let the sample be

10, **81**, 20, 3, **81**, 10000

Let us call this a **collision**

As we do not know S , our only clue are elements that **were sampled twice**.

Birthday Problem

Birthday Problem: Given a set of i people

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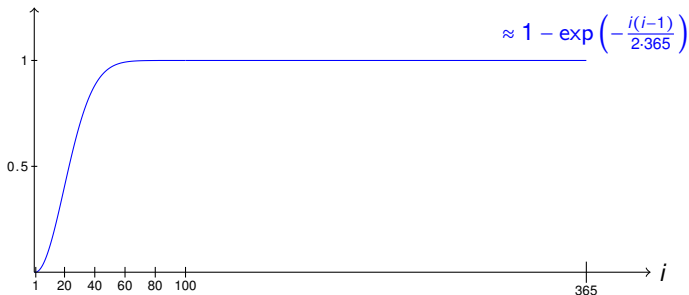
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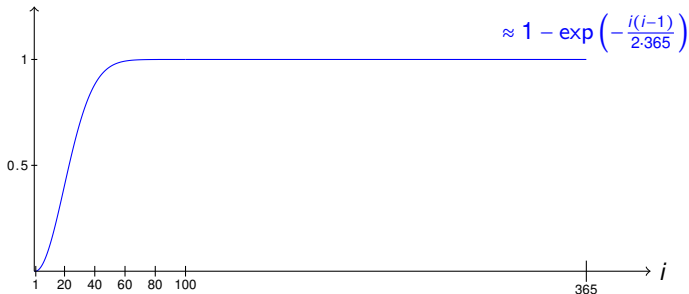


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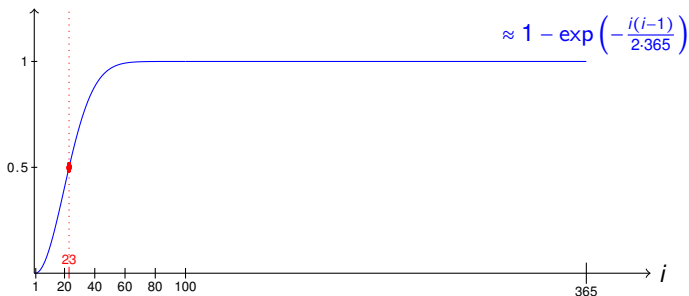


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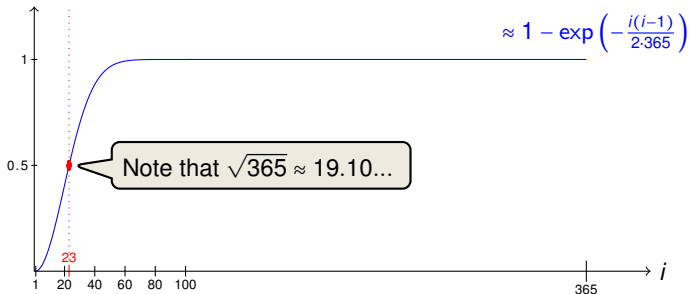


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- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
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Expected Running Time (Knuth, Ramanujan)

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Exercise: Prove a bound of $\leq 2 \cdot \sqrt{N}$

Estimation via Collision: Getting the Estimator Unbiased

Example 6

It is possible to define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any set S .

Answer

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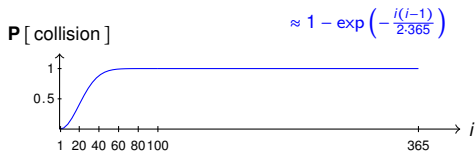
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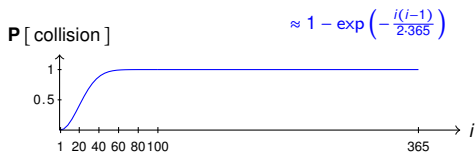
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(proof that $T(i) = \binom{i}{2}$ is harder)

Mark & Recapture Method (non-examinable)



Source: Wikipedia

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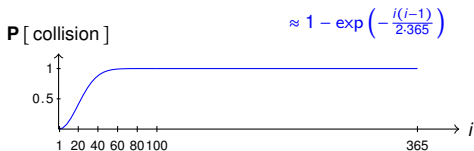


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- **First phase:** A portion of the population is captured, marked and released
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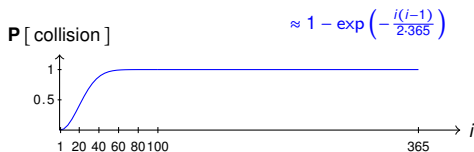
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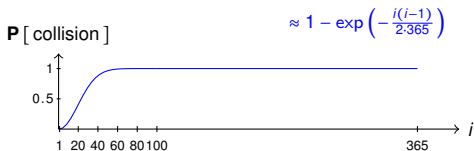
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$$\frac{k}{K} \approx \frac{n}{N} \quad \Rightarrow \quad N \approx n \cdot \frac{K}{k}.$$