

# Optimising Compilers

Computer Science Tripos Part II

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# Questions?

- Please ask any you like during the lecture
- Or you can come talk to me afterwards
- Or you can drop by my office when I'm in
- Or you can email me any time you like

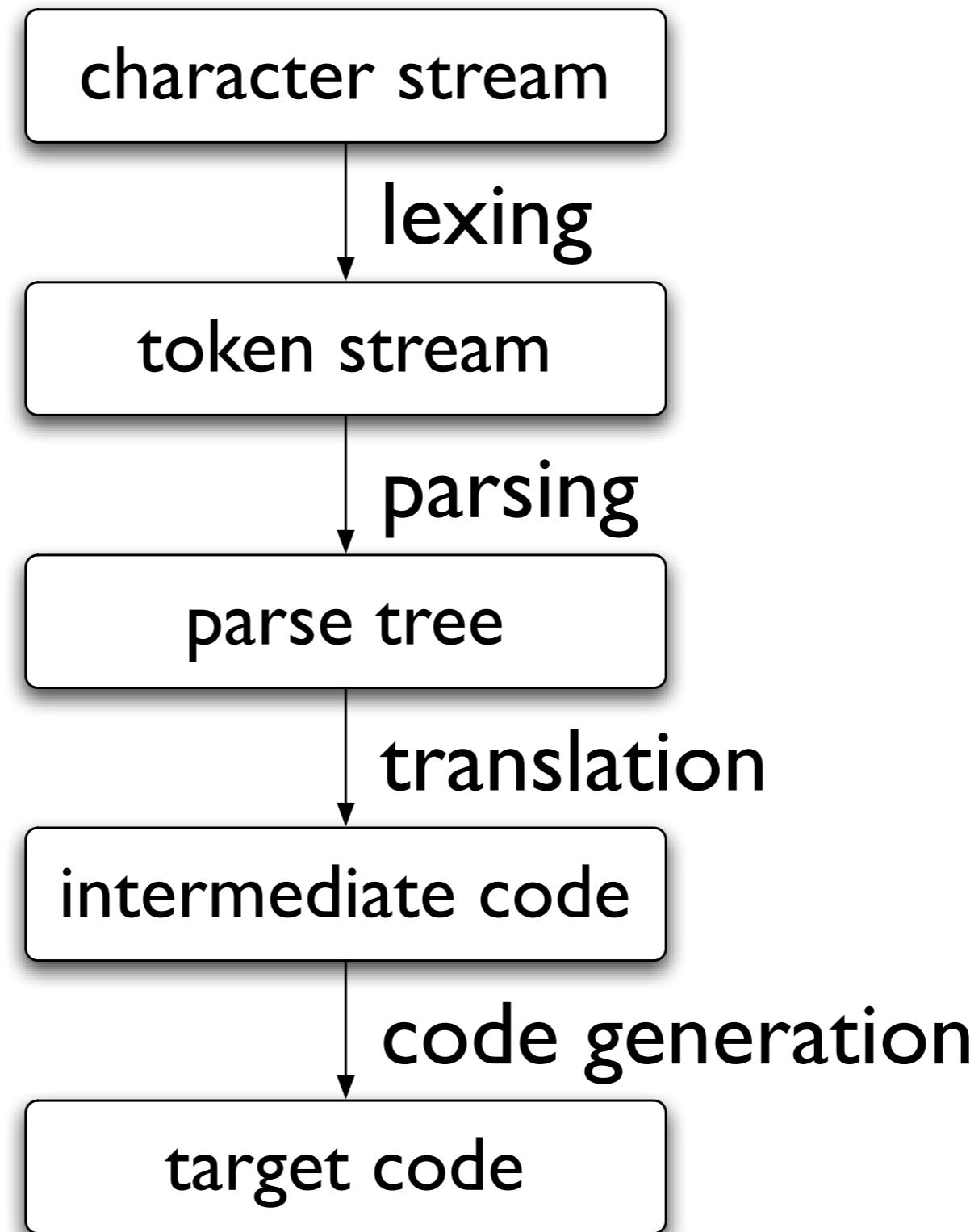
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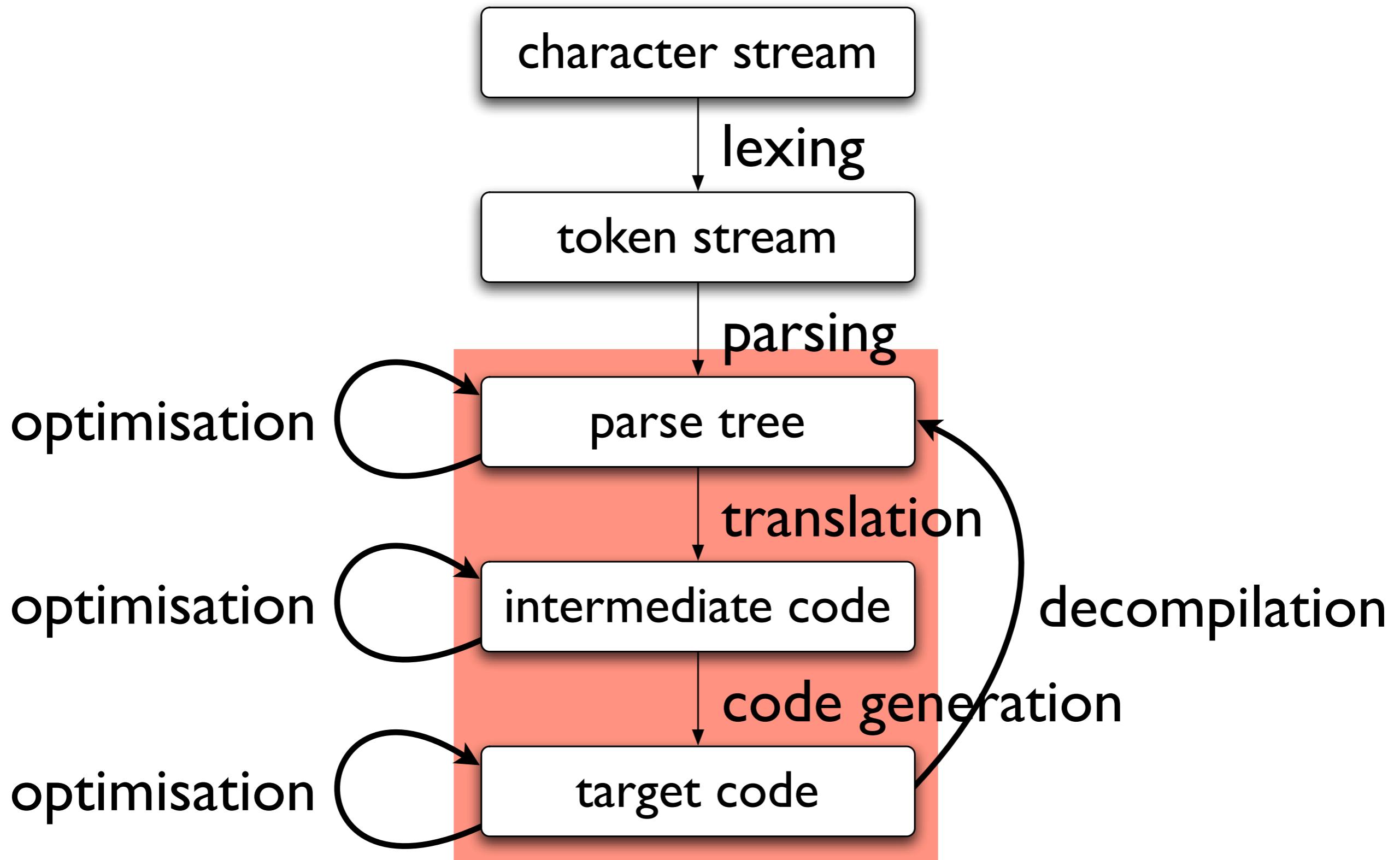
# Lecture I

# Introduction

# A non-optimising compiler



# An optimising compiler



# Optimisation

(really “amelioration”!)

Good humans write simple, maintainable, general code.

Compilers should then *remove unused generality*,  
and hence hopefully make the code:

- Smaller
- Faster
- Cheaper (e.g. lower power consumption)

# Optimisation

=

# Analysis

+

# Transformation

# Analysis + Transformation

- Transformation *does something dangerous.*
- Analysis determines *whether it's safe.*

# Analysis + Transformation

- An analysis shows that your program has some property...
- ...and the transformation is designed to be safe for all programs with that property...
- ...so it's safe to do the transformation.

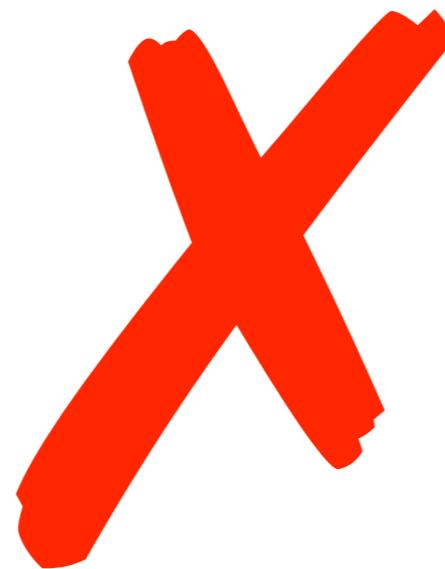
# Analysis + Transformation

```
int main(void)
{
    return 42;
}
```



# Analysis + Transformation

```
int main(void)
{
    return f(21);
}
```



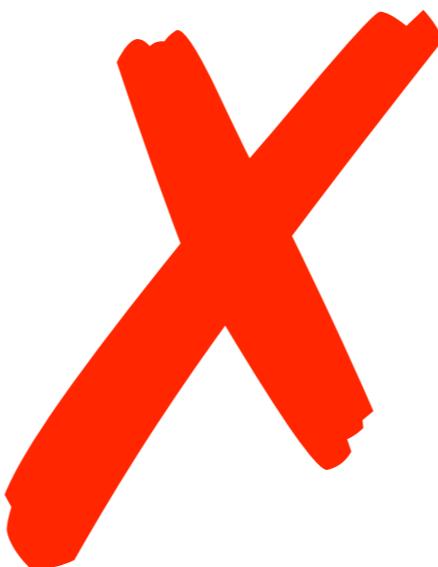
# Analysis + Transformation

```
int t = k * 2;  
while (i <= k*2){  
    j = j * i;  
    i = i + 1;  
}
```

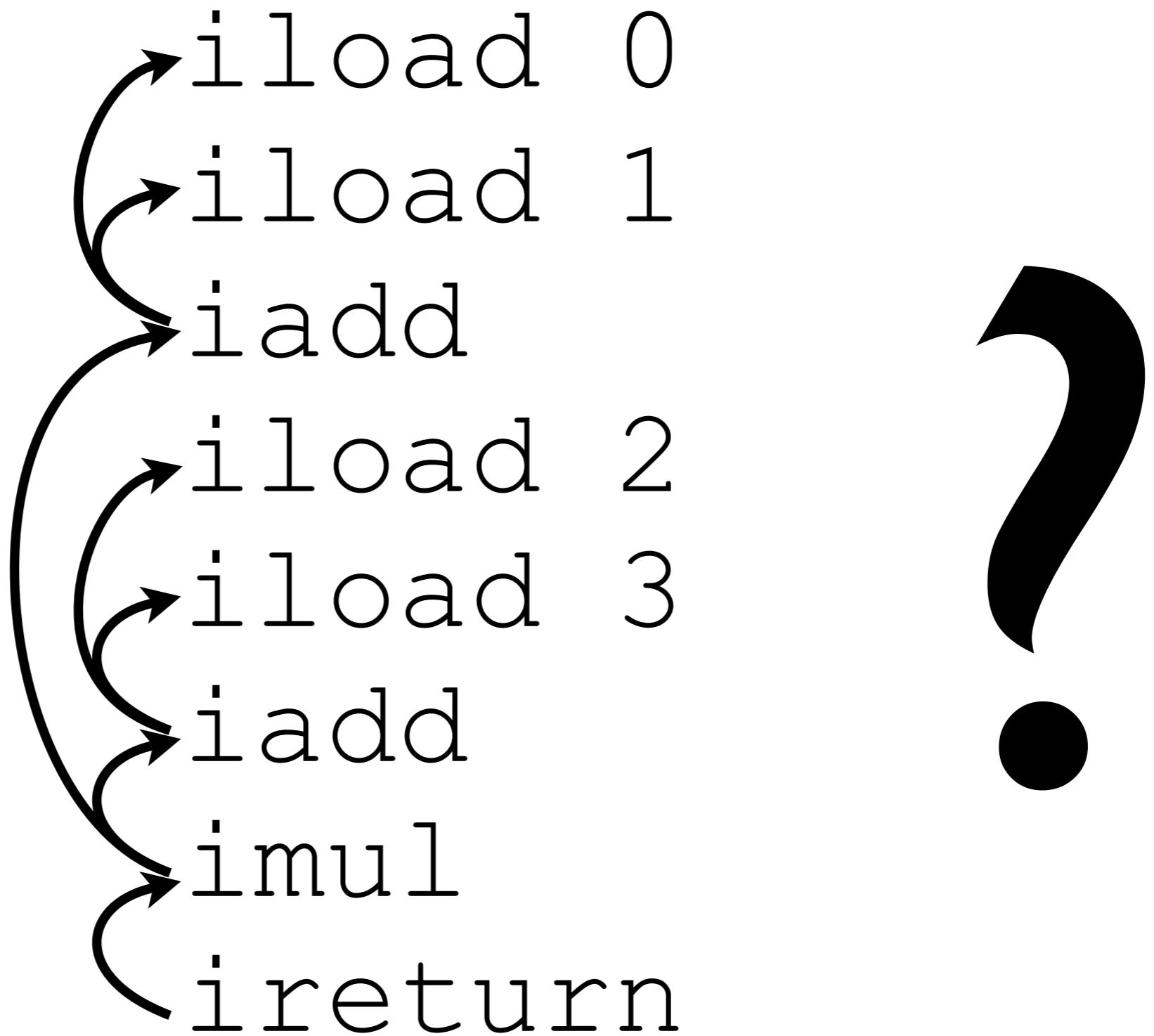


# Analysis + Transformation

```
int t = k * 2;  
while (i <= k*2){  
    k = k - i;  
    i = i + 1;  
}
```



# Stack-oriented code



# 3-address code

|      |                |
|------|----------------|
| MOV  | t32, arg1      |
| MOV  | t33, arg2      |
| ADD  | t34, t32, t33  |
| MOV  | t35, arg3      |
| MOV  | t36, arg4      |
| ADD  | t37, t35, t36  |
| MUL  | res1, t34, t37 |
| EXIT |                |

The diagram illustrates the flow of temporary variables in 3-address code. Each instruction is shown with its operation code (MOV, ADD, MUL) and its three addresses. The values are highlighted with colored boxes, and colored lines connect the values from one instruction to the next, showing the flow of data.

- MOV t32, arg1
- MOV t33, arg2
- ADD t34, t32, t33
- MOV t35, arg3
- MOV t36, arg4
- ADD t37, t35, t36
- MUL res1, t34, t37
- EXIT

# C into 3-address code

```
int fact (int n) {  
    if (n == 0) {  
        return 1;  
    } else {  
        return n * fact (n-1);  
    }  
}
```

# C into 3-address code

```
ENTRY fact
      MOV t32, arg1
      CMPEQ t32, #0, lab1
      SUB arg1, t32, #1
      CALL fact
      MUL res1, t32, res1
      EXIT
lab1:   MOV res1, #1
      EXIT
```

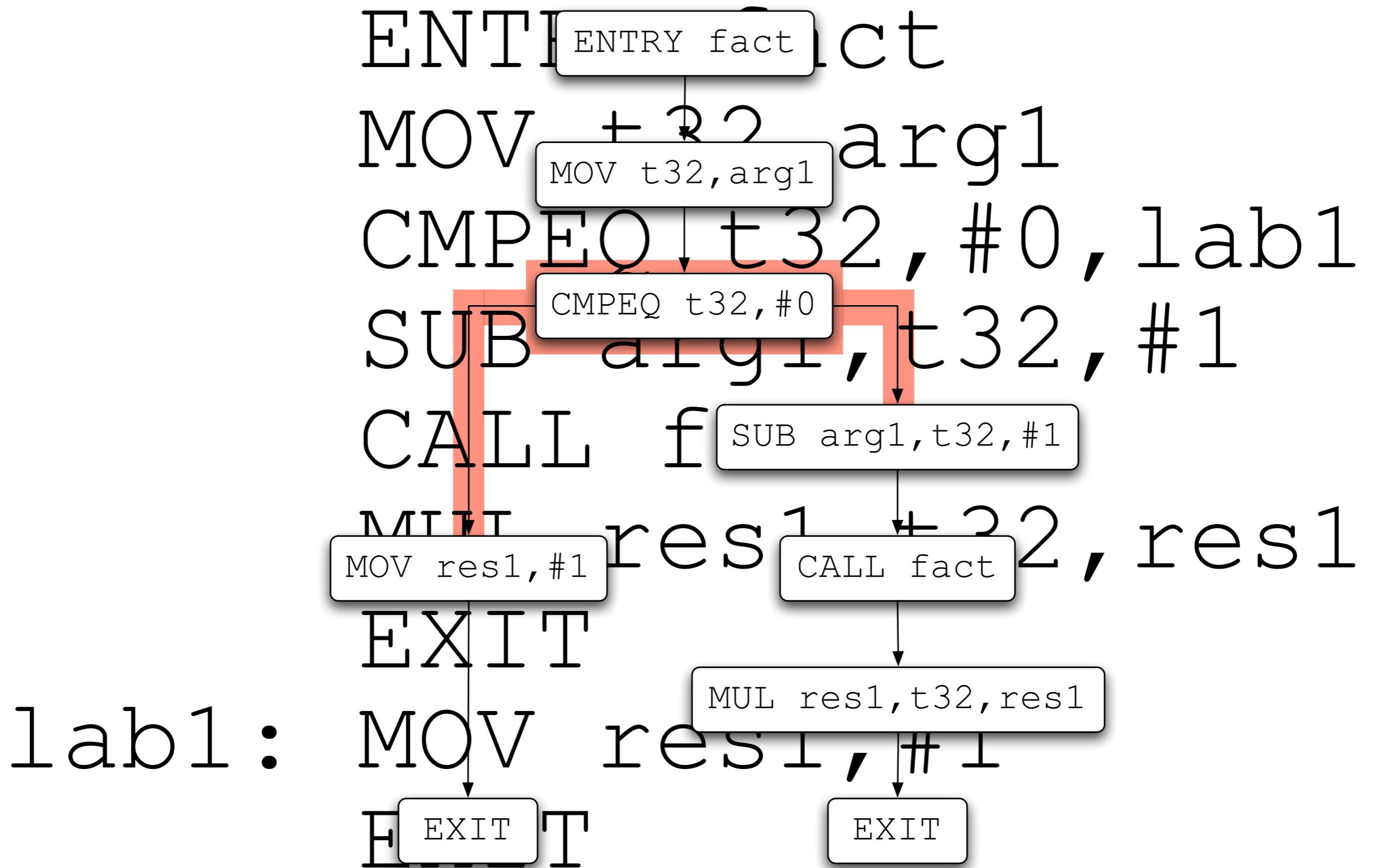
# Flowgraphs

- A graph representation of a program
- Each node stores 3-address instruction(s)
- Each edge represents (potential) control flow:

$$pred(n) = \{n' \mid (n', n) \in edges(G)\}$$

$$succ(n) = \{n' \mid (n, n') \in edges(G)\}$$

# Flowgraphs

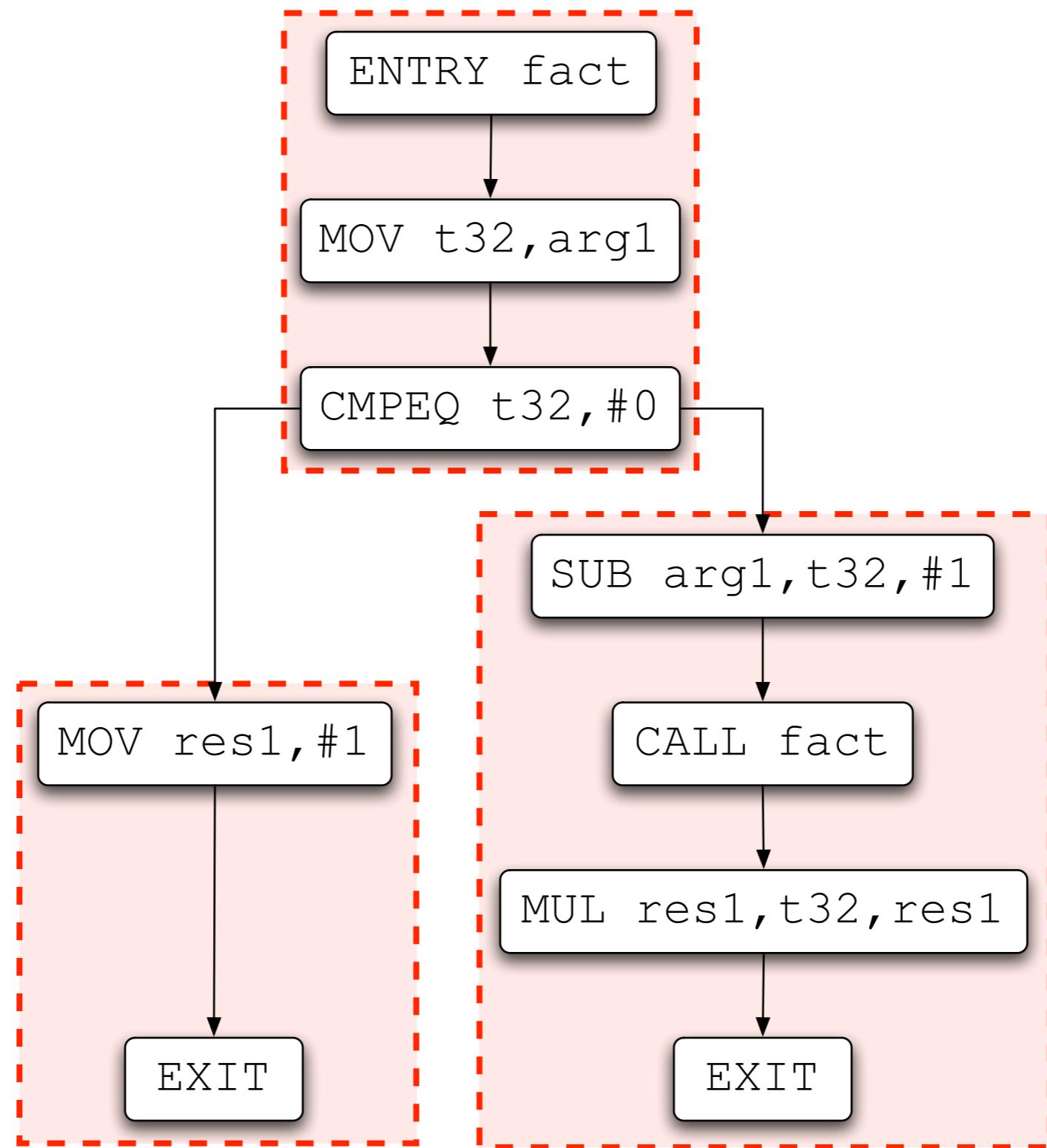


# Basic blocks

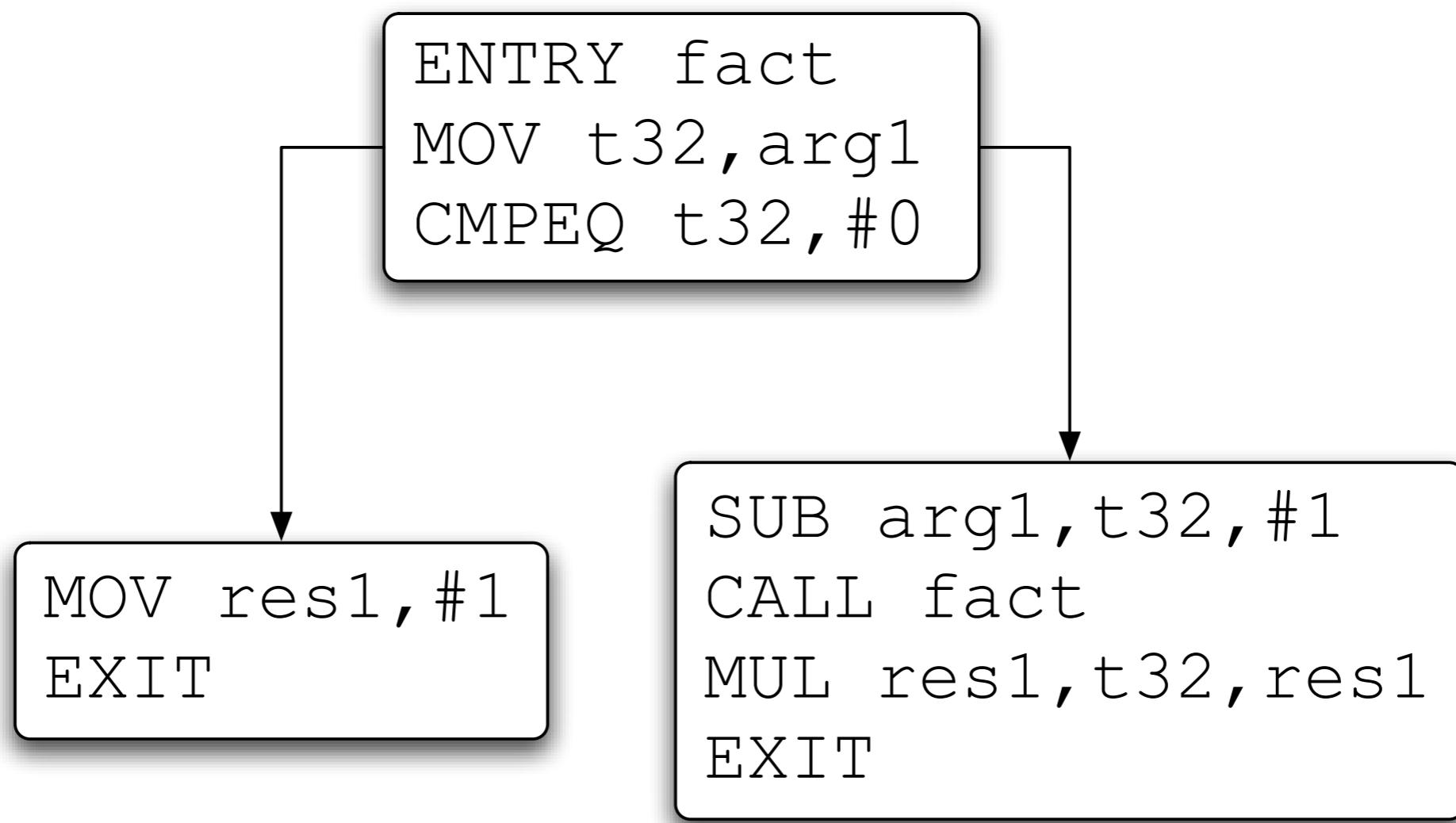
A maximal sequence of instructions  $n_1, \dots, n_k$  which have

- exactly one predecessor (except possibly for  $n_1$ )
- exactly one successor (except possibly for  $n_k$ )

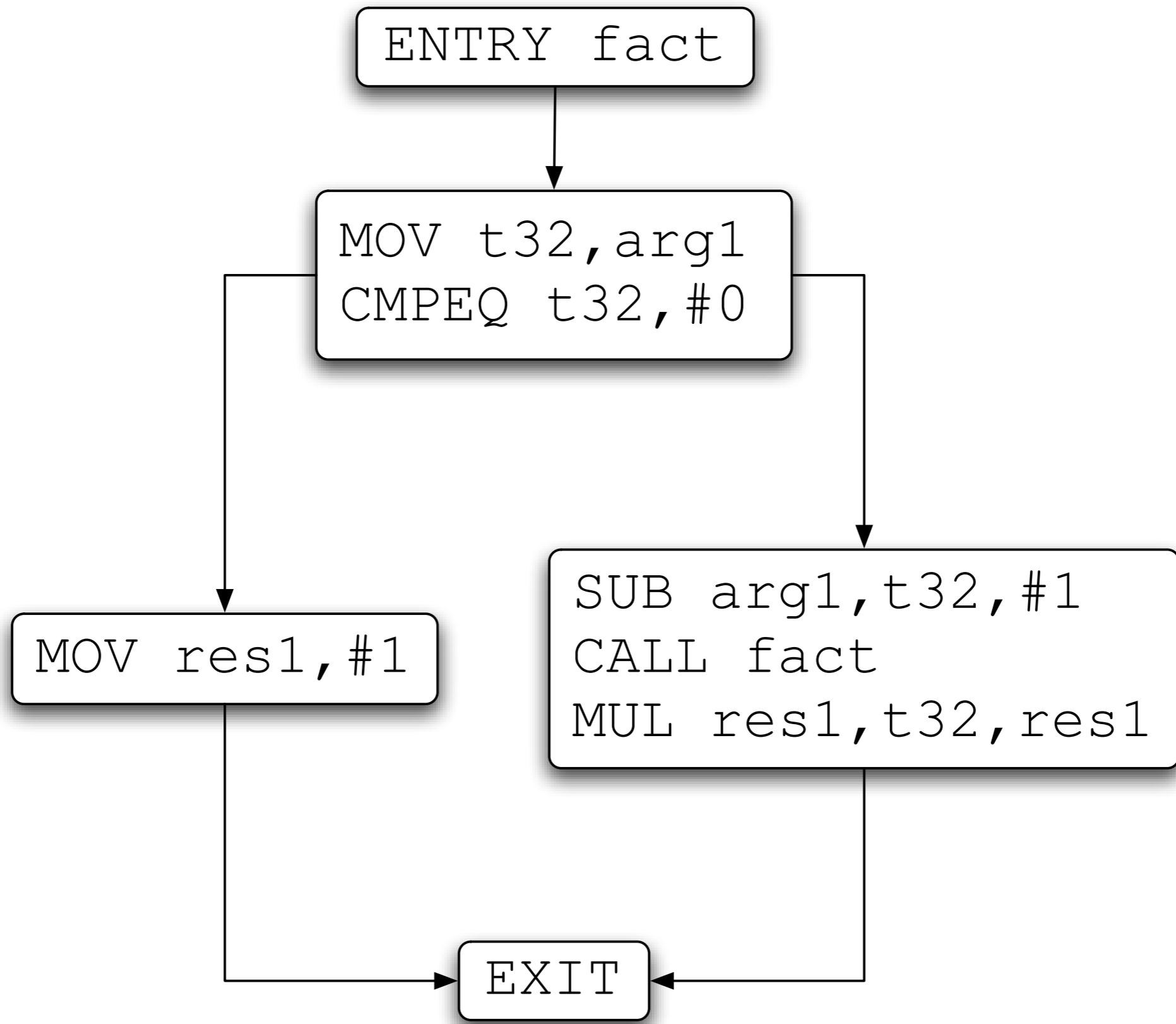
# Basic blocks



# Basic blocks



# Basic blocks



# Basic blocks

A basic block doesn't contain any interesting control flow.

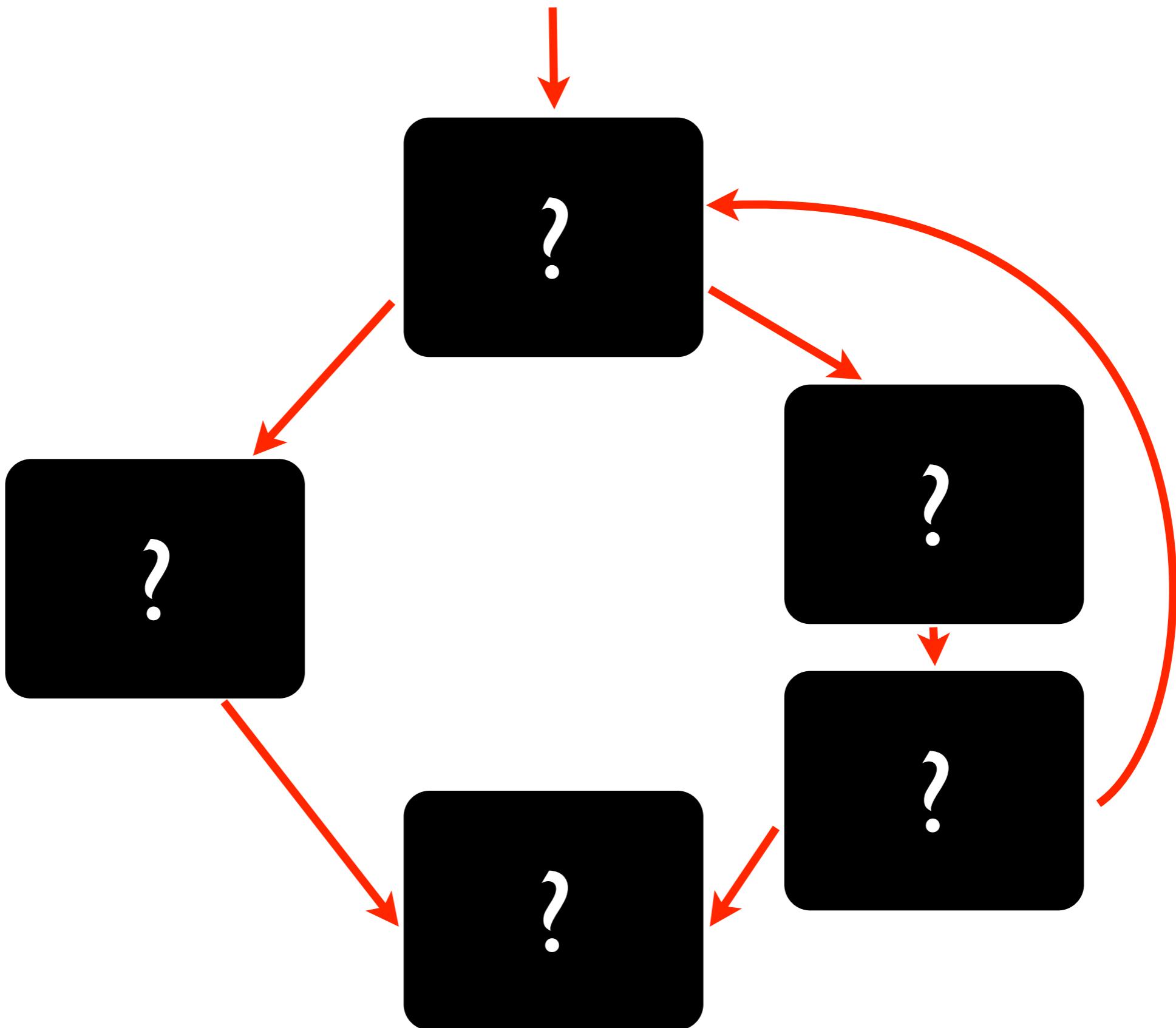
# Basic blocks

Reduce time and space requirements  
for analysis algorithms  
by calculating and storing data flow information  
once per block  
(and recomputing within a block if required)  
instead of  
once per instruction.

# Basic blocks



# Basic blocks



# Types of analysis

(and hence optimisation)

Scope:

- Within basic blocks (“local” / “peephole”)
- Between basic blocks (“global” / “intra-procedural”)
  - e.g. live variable analysis, available expressions
- Whole program (“inter-procedural”)
  - e.g. unreachable-procedure elimination

# Peephole optimisation

```
ADD t32, arg1, #1
MOV r0, r1
MOV r1, r0
MUL t33, r0, t32
```

matches



```
ADD t32, arg1, #1
MOV r0, r1
MUL t33, r0, t32
```

replace  
MOV x, y  
MOV y, x  
with  
MOV x, y

# Types of analysis

(and hence optimisation)

Type of information:

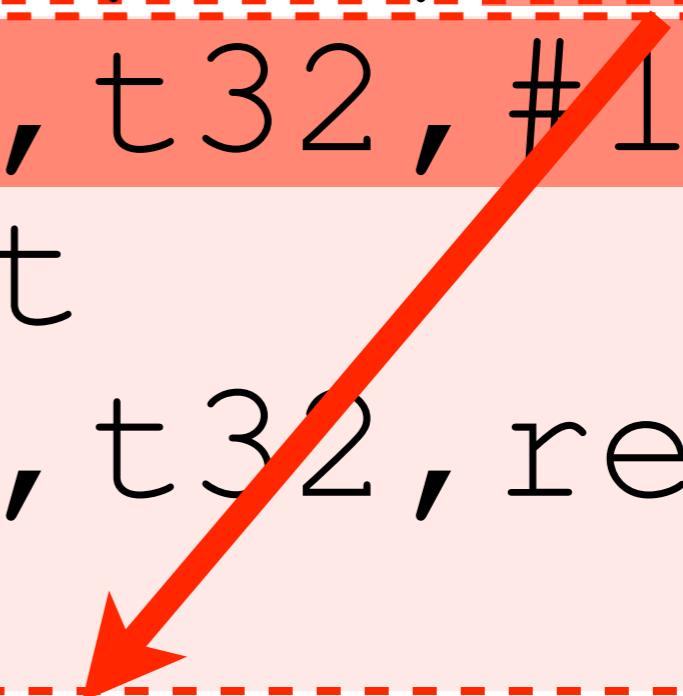
- Control flow
  - Discovering control structure (basic blocks, loops, calls between procedures)
- Data flow
  - Discovering data flow structure (variable uses, expression evaluation)

# Finding basic blocks

- I. Find all the instructions which are *leaders*:
  - the first instruction is a leader;
  - the target of any branch is a leader; and
  - any instruction immediately following a branch is a leader.
2. For each leader, its basic block consists of itself and all instructions up to the next leader.

# Finding basic blocks

```
ENTRY fact
      MOV t32, arg1
      CMPEQ t32, #0, lab1
      SUB arg1, t32, #1
      CALL fact
      MUL res1, t32, res1
      EXIT
lab1:  MOV res1, #1
      EXIT
```



# Summary

- Structure of an optimising compiler
- Why optimise?
- Optimisation = Analysis + Transformation
- 3-address code
- Flowgraphs
- Basic blocks
- Types of analysis
- Locating basic blocks