

# Optimising Compilers

Computer Science Tripos Part II

Tobias Grosser

# Questions?

- Please ask any you like during the lecture
- Or you can come talk to me afterwards
- Or you can drop by my office when I'm in
- Or you can email me any time you like

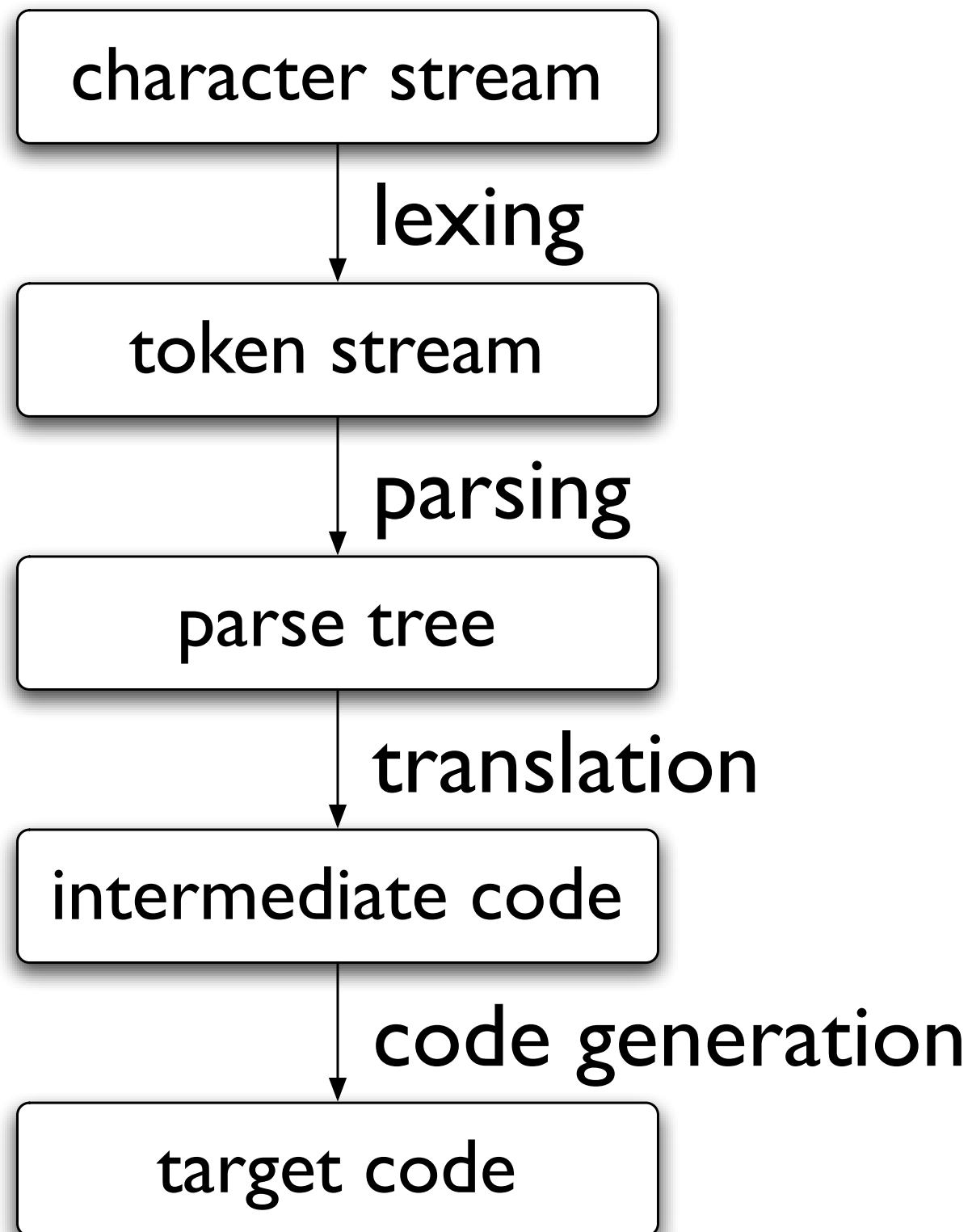
Office - SCI2

Email - [tobias.grosser@cst.cam.ac.uk](mailto:tobias.grosser@cst.cam.ac.uk)

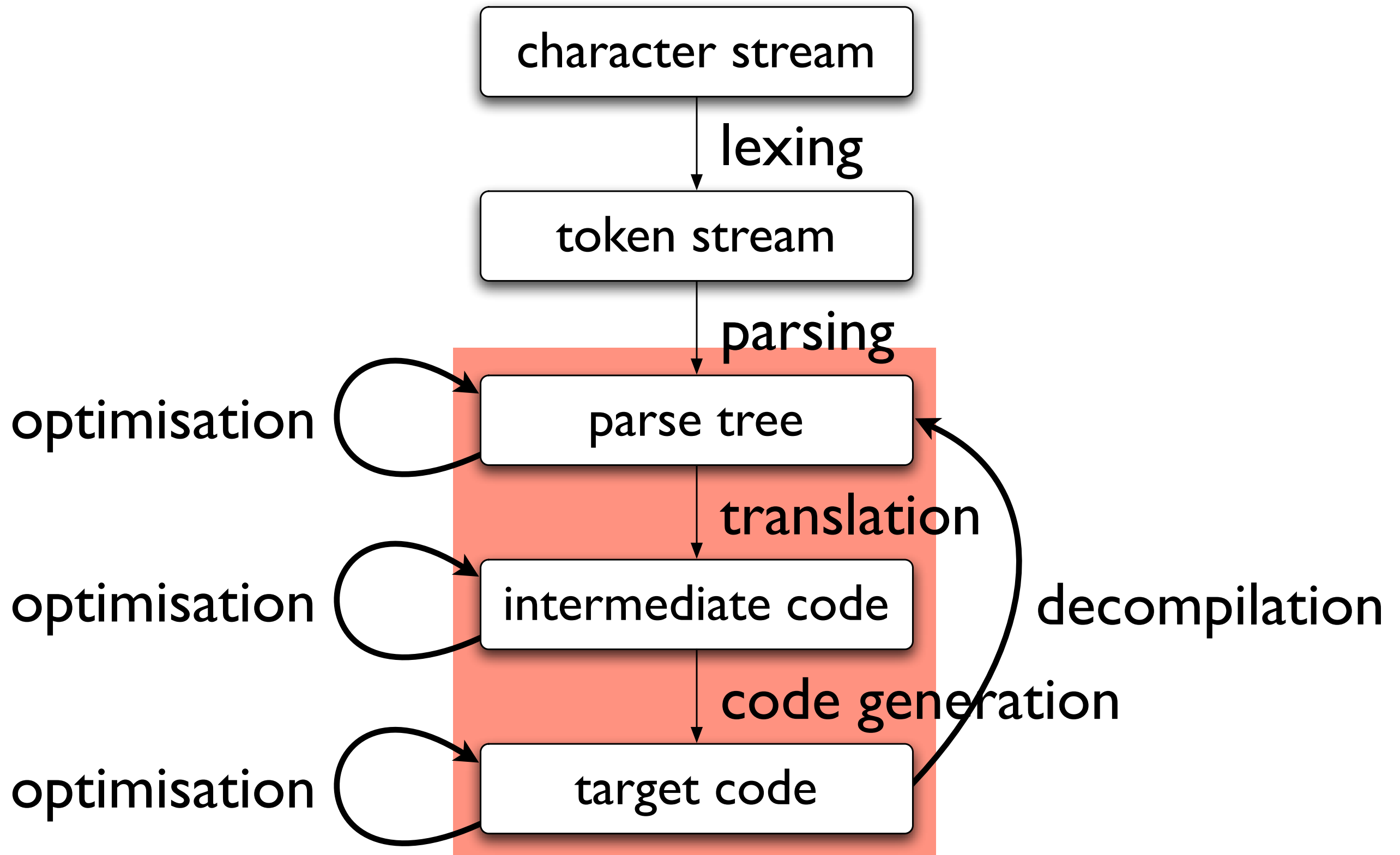
# Lecture I

# Introduction

# A non-optimising compiler



# An optimising compiler



# Optimisation

(really “amelioration”!)

Good humans write simple, maintainable, *general* code.

Compilers should then *remove unused generality*,  
and hence hopefully make the code:

- Smaller
- Faster
- Cheaper (e.g. lower power consumption)

Optimisation

=

Analysis

+

Transformation

# Analysis + Transformation

- Transformation *does something dangerous*.
- Analysis determines *whether it's safe*.



# Analysis + Transformation

- An analysis shows that your program has some property...
- ...and the transformation is designed to be safe for all programs with that property...
- ...so it's safe to do the transformation.

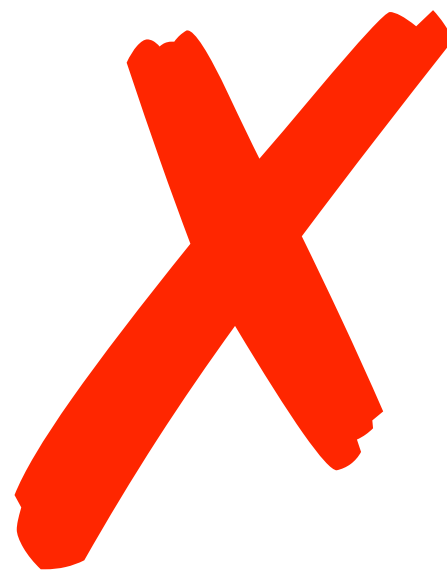
# Analysis + Transformation

```
int main(void)
{
    return 42;
}
```



# Analysis + Transformation

```
int main(void)
{
    return f(21);
}
```



# Analysis + Transformation

```
int t = k * 2;  
while (i <= k*2) {  
    j = j * i;  
    i = i + 1;  
}
```

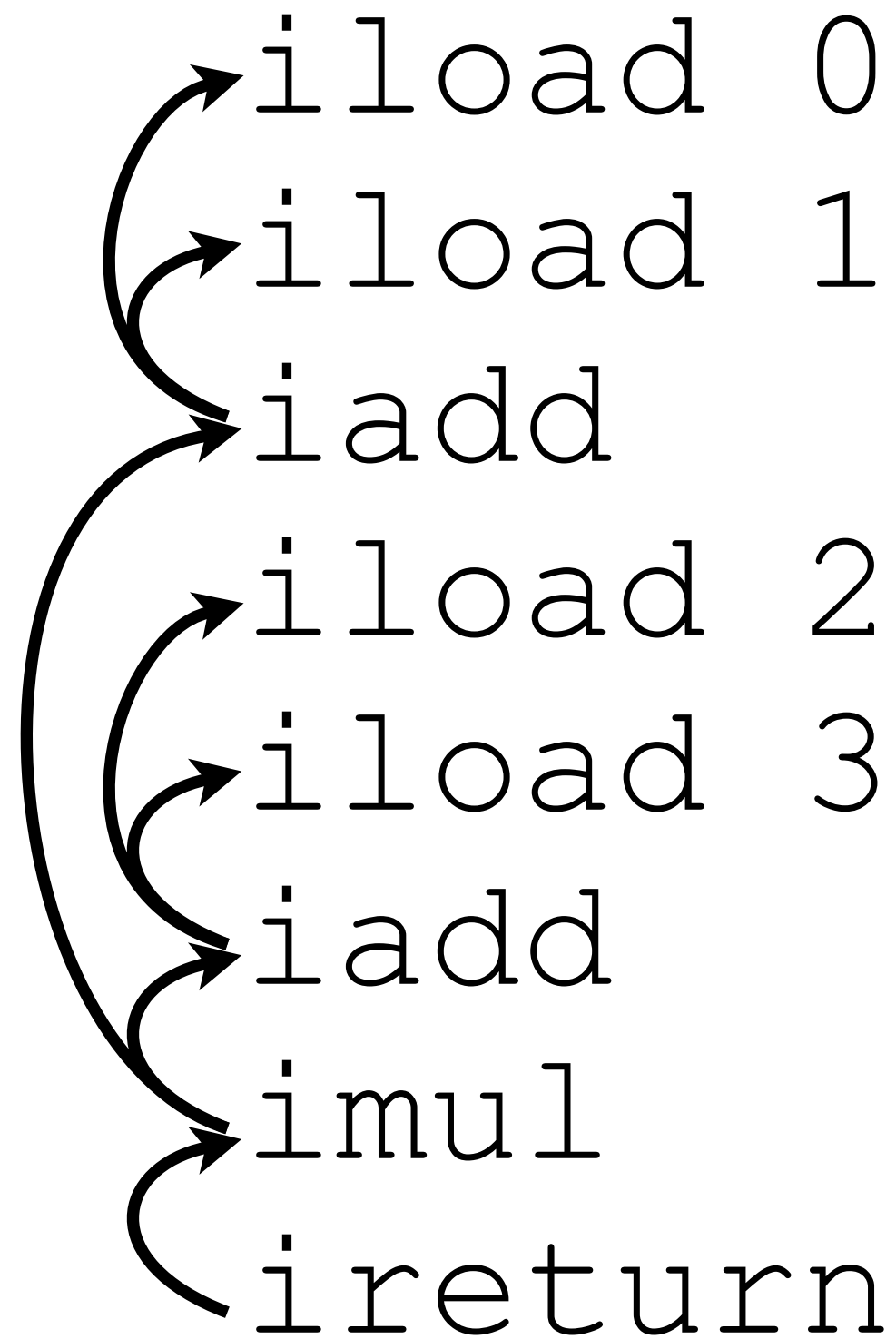


# Analysis + Transformation

```
int t = k * 2;  
while (i <= k * 2) {  
    k = k - i;  
    i = i + 1;  
}
```

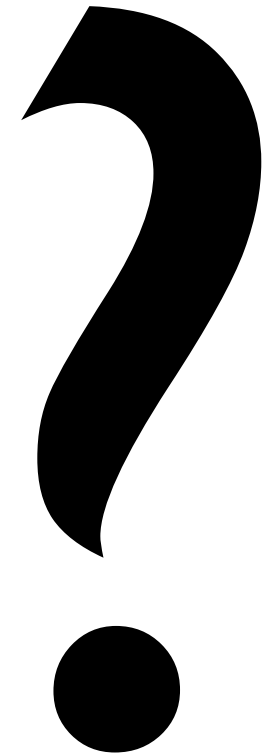


# Stack-oriented code

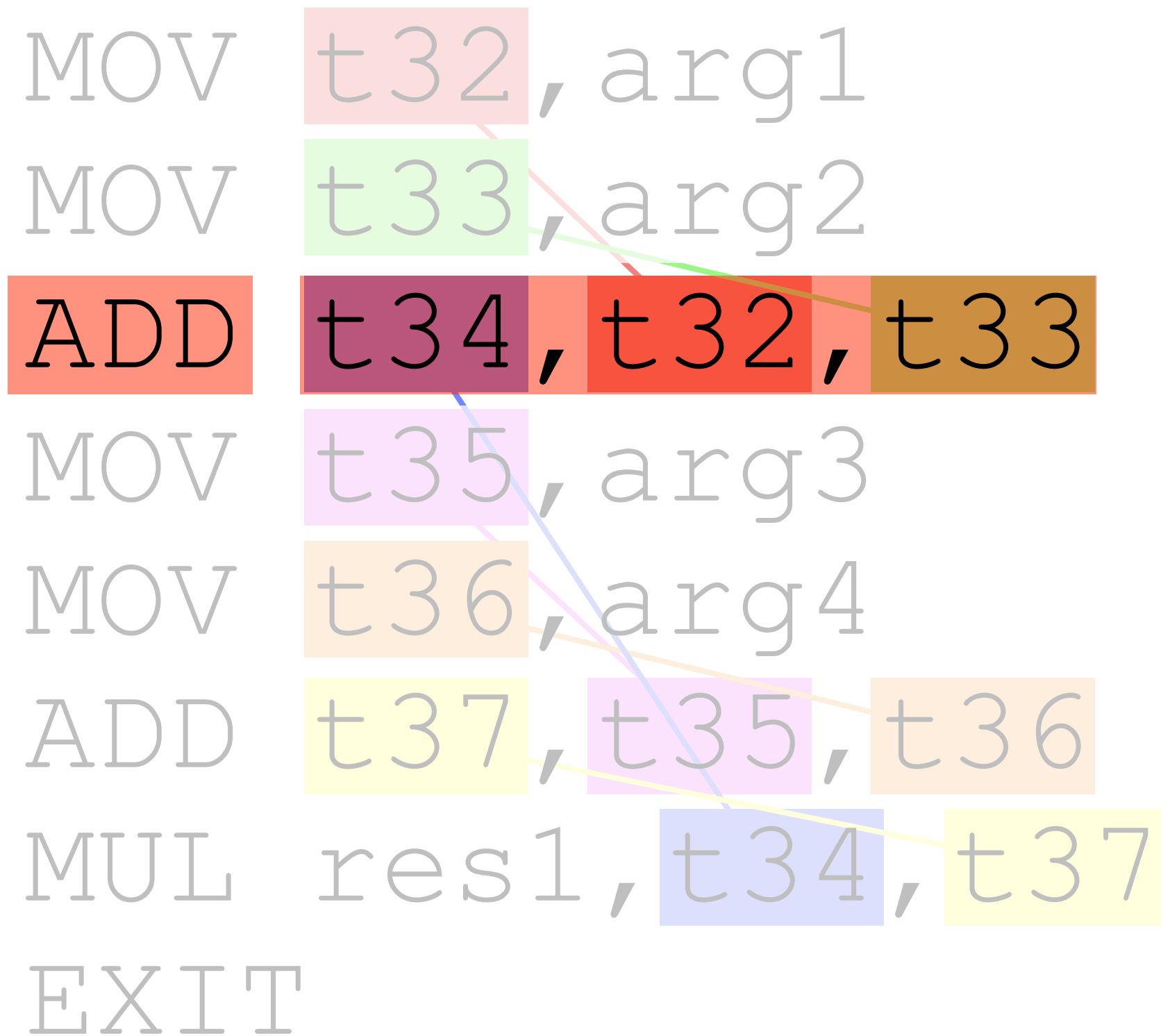


A diagram illustrating the execution flow of stack-oriented code. The code consists of eight instructions: `iload 0`, `iload 1`, `iadd`, `iload 2`, `iload 3`, `iadd`, `imul`, and `ireturn`. Curved arrows on the left side of the code indicate the flow of execution from one instruction to the next, starting from `iload 0` and ending at `ireturn`.

```
iload 0
iload 1
iadd
iload 2
iload 3
iadd
imul
ireturn
```



# 3-address code



# C into 3-address code

```
int fact (int n) {  
    if (n == 0) {  
        return 1;  
    } else {  
        return n * fact(n-1);  
    }  
}
```



# C into 3-address code

```
ENTRY fact
```

```
MOV t32, arg1
```

```
CMPEQ t32, #0, lab1
```

```
SUB arg1, t32, #1
```

```
CALL fact
```

```
MUL res1, t32, res1
```

```
EXIT
```

```
lab1: MOV res1, #1
```

```
EXIT
```

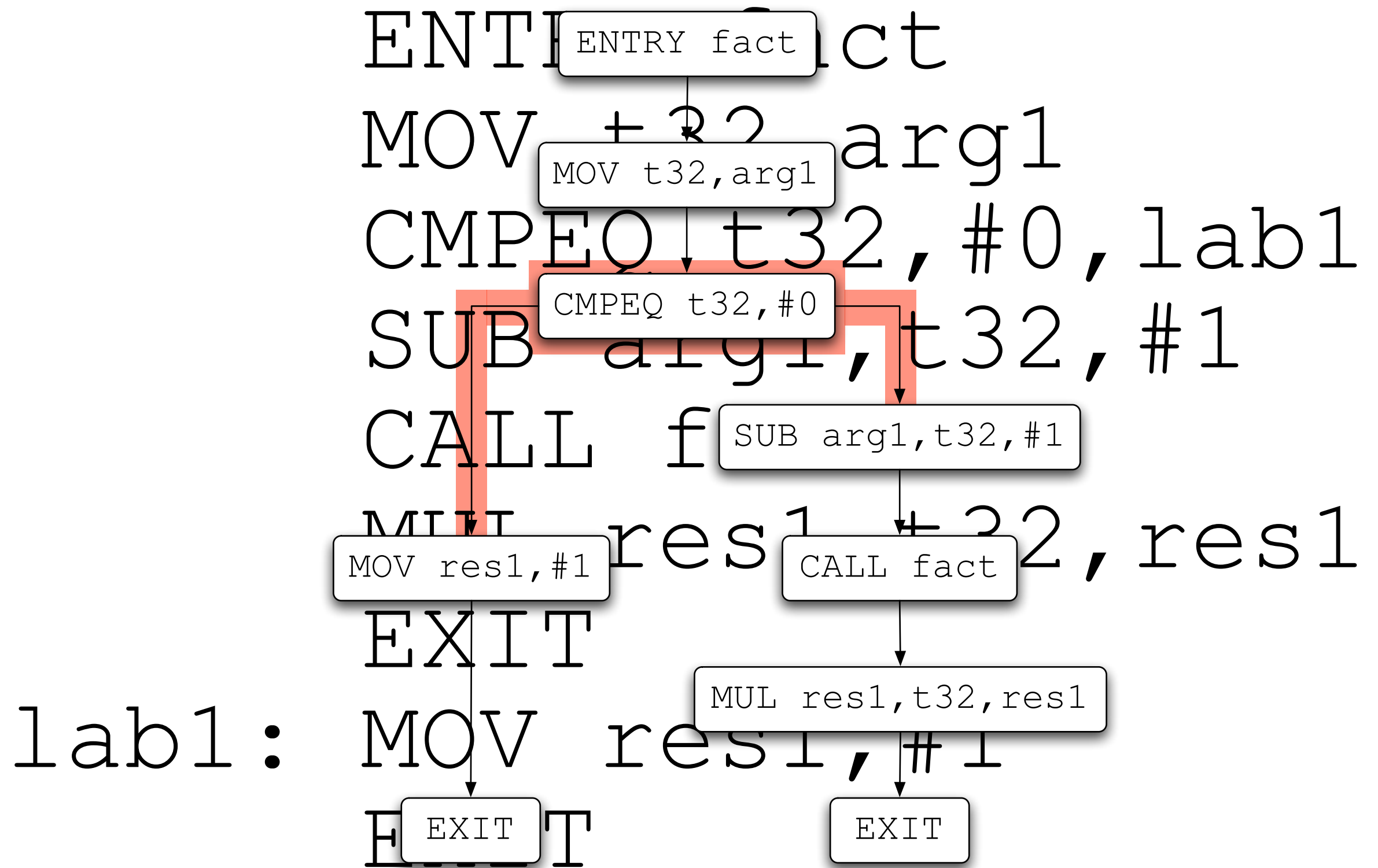
# Flowgraphs

- A graph representation of a program
- Each node stores 3-address instruction(s)
- Each edge represents (potential) control flow:

$$pred(n) = \{n' \mid (n', n) \in edges(G)\}$$

$$succ(n) = \{n' \mid (n, n') \in edges(G)\}$$

# Flowgraphs

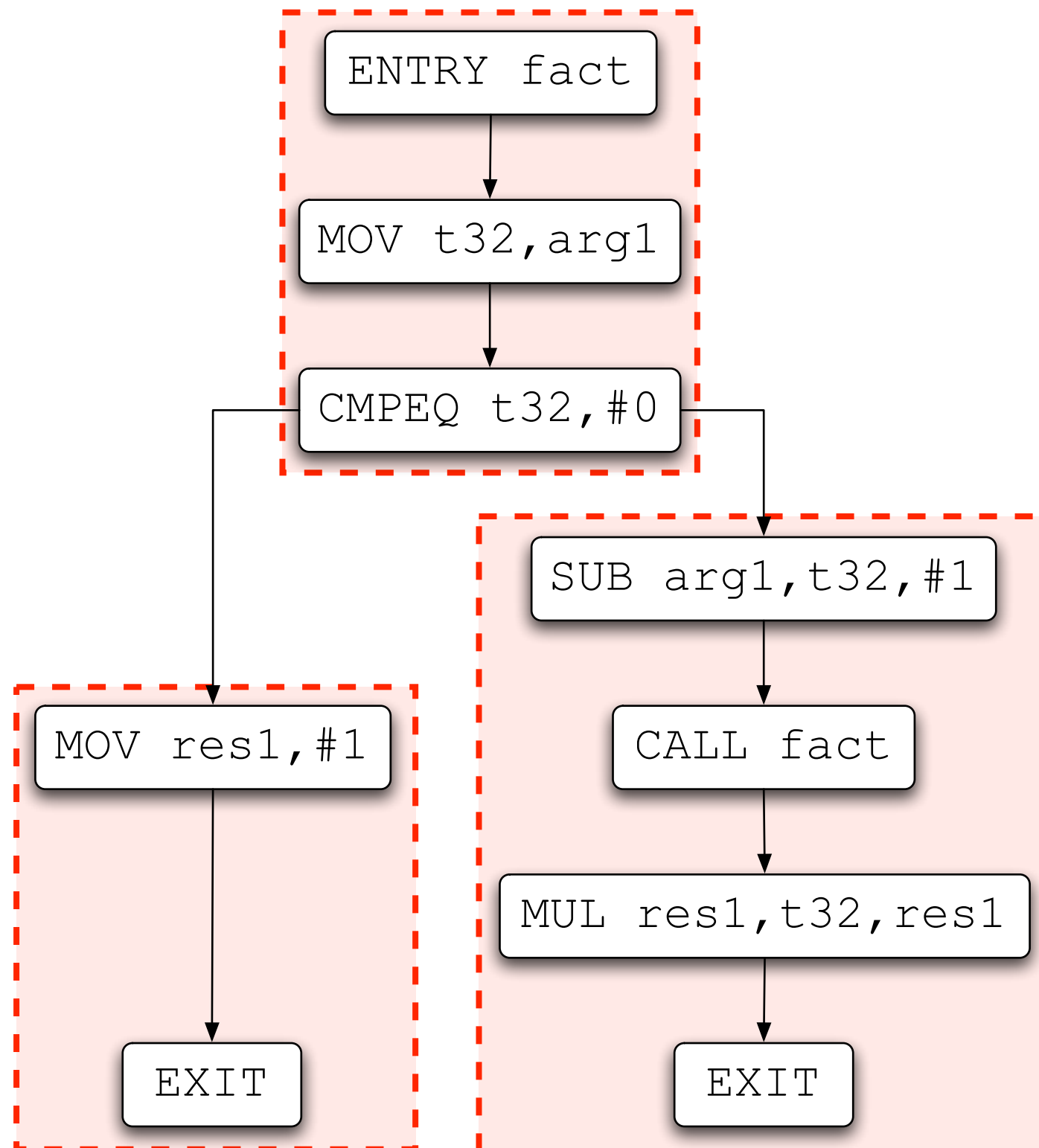


# Basic blocks

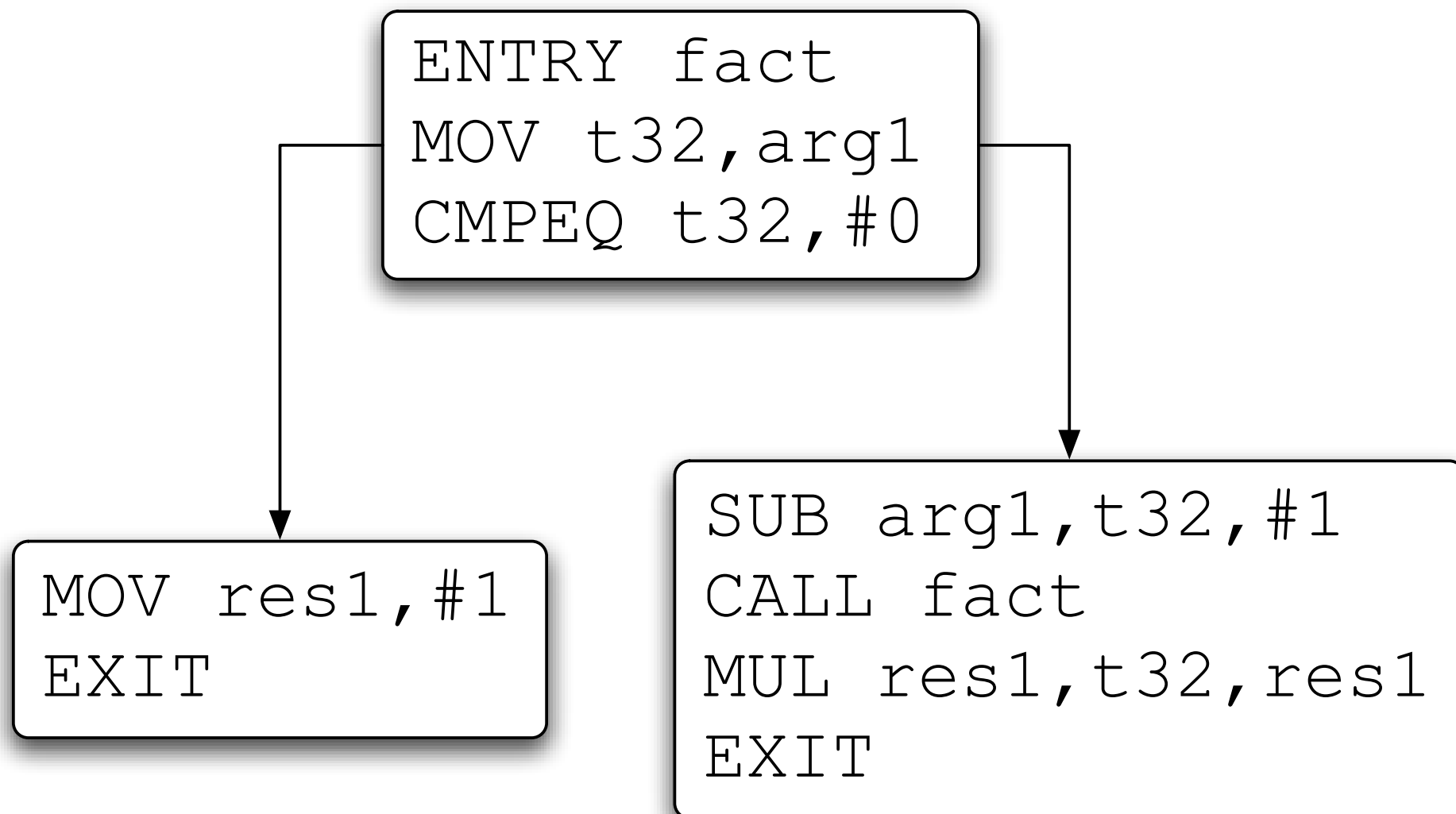
A maximal sequence of instructions  $n_1, \dots, n_k$  which have

- exactly one predecessor (except possibly for  $n_1$ )
- exactly one successor (except possibly for  $n_k$ )

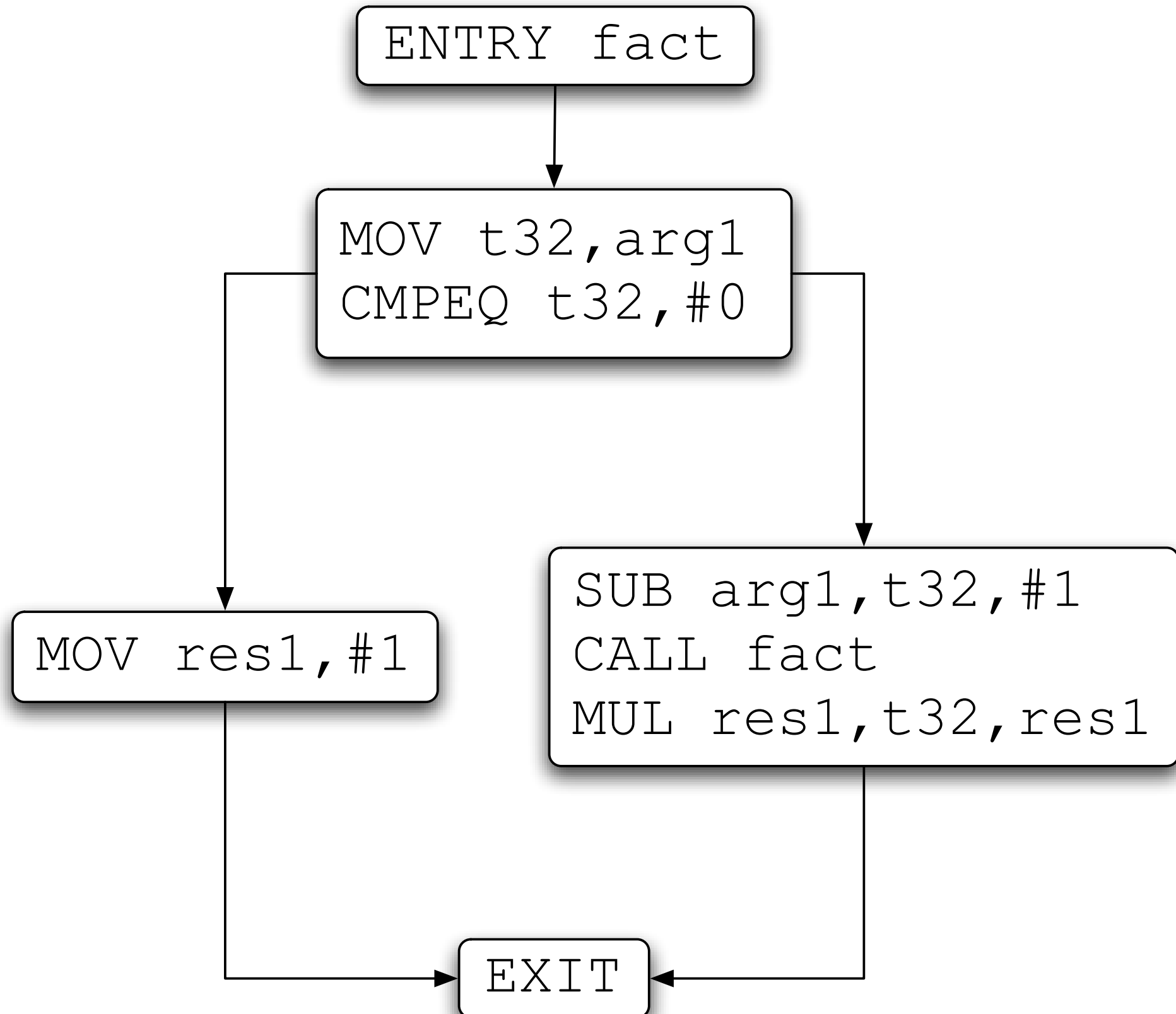
# Basic blocks



# Basic blocks



# Basic blocks



# Basic blocks

A basic block doesn't contain any interesting control flow.



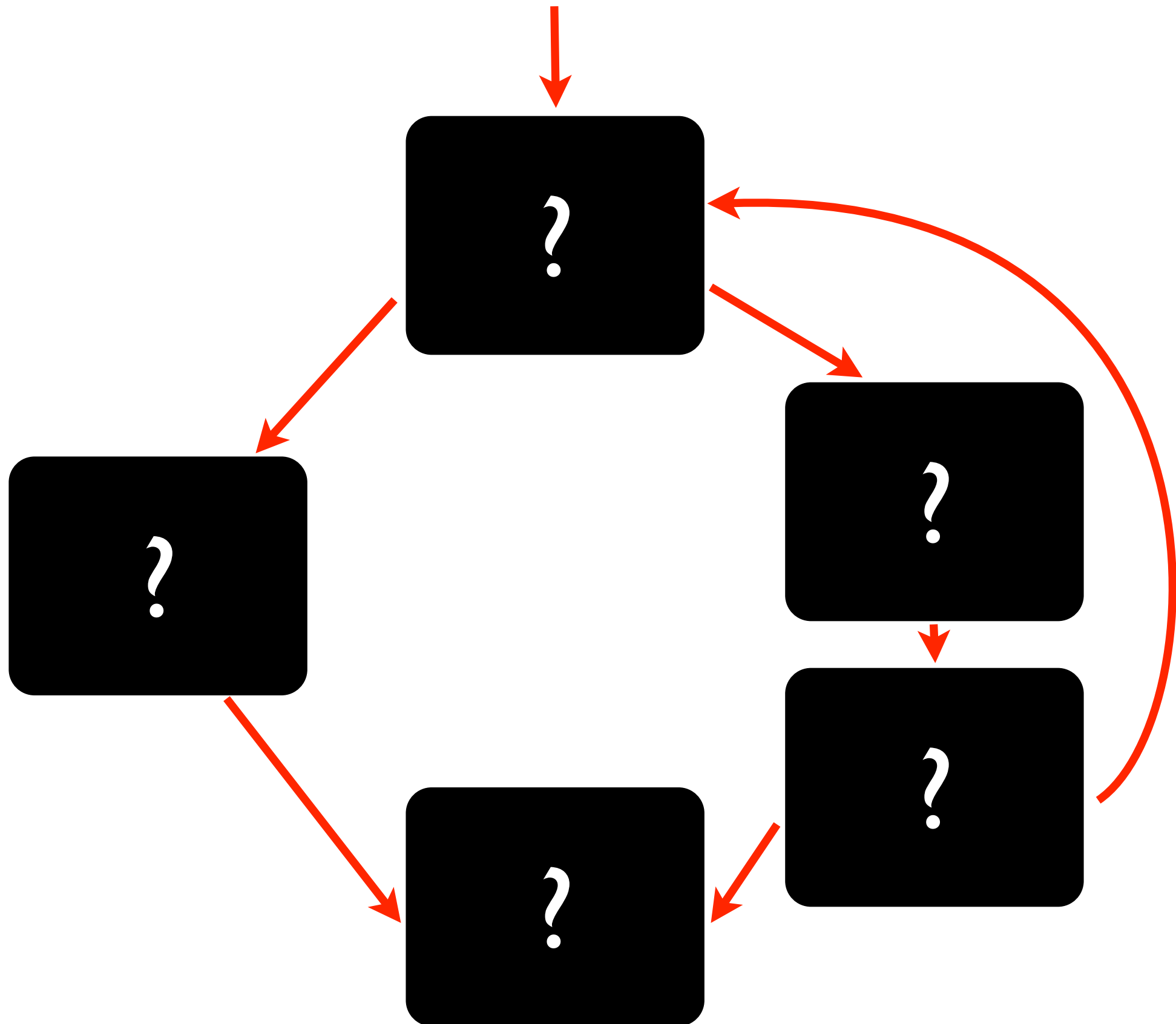
# Basic blocks

Reduce time and space requirements  
for analysis algorithms  
by calculating and storing data flow information  
**once per block**  
(and recomputing within a block if required)  
instead of  
**once per instruction.**

# Basic blocks



# Basic blocks



# Types of analysis

(and hence optimisation)

## Scope:

- Within basic blocks (“local” / “peephole”)
- Between basic blocks (“global” / “intra-procedural”)
  - e.g. live variable analysis, available expressions
- Whole program (“inter-procedural”)
  - e.g. unreachable-procedure elimination

# Peephole optimisation

```
ADD  t32, arg1, #1
MOV  r0, r1
MOV  r1, r0
MUL  t33, r0, t32
```

matches

↓

```
ADD  t32, arg1, #1
MOV  r0, r1
MUL  t33, r0, t32
```

replace

```
MOV  x, y
MOV  y, x
```

with

```
MOV  x, y
```

# Types of analysis

(and hence optimisation)

Type of information:

- Control flow
  - Discovering control structure (basic blocks, loops, calls between procedures)
- Data flow
  - Discovering data flow structure (variable uses, expression evaluation)

# Finding basic blocks

1. Find all the instructions which are *leaders*:
  - the first instruction is a leader;
  - the target of any branch is a leader; and
  - any instruction immediately following a branch is a leader.
2. For each leader, its basic block consists of itself and all instructions up to the next leader.

# Finding basic blocks

```
ENTRY fact
```

```
MOV t32, arg1
```

```
CMPEQ t32, #0, lab1
```

```
SUB arg1, t32, #1
```

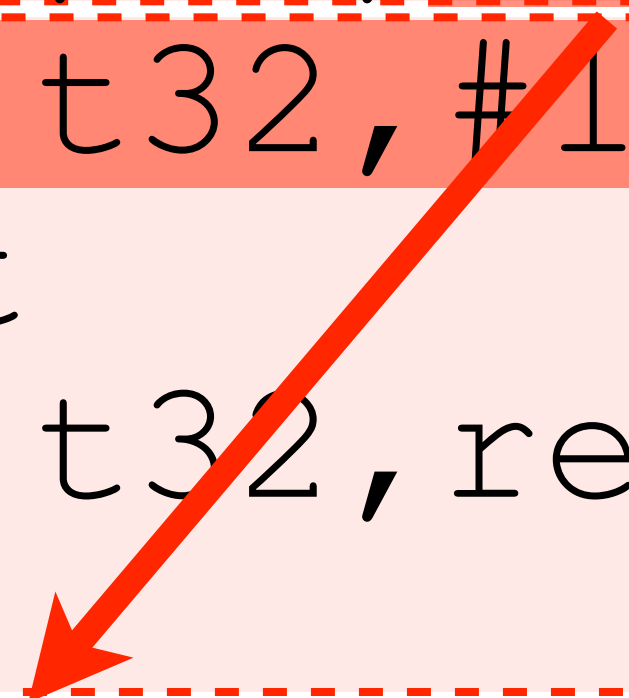
```
CALL fact
```

```
MUL res1, t32, res1
```

```
EXIT
```

```
lab1: MOV res1, #1
```

```
EXIT
```





# Summary

- Structure of an optimising compiler
- Why optimise?
- Optimisation = Analysis + Transformation
- 3-address code
- Flowgraphs
- Basic blocks
- Types of analysis
- Locating basic blocks