

Randomised Algorithms

Lecture 5: Random Walks, Hitting Times and Application to 2-SAT

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UNIVERSITY OF
CAMBRIDGE

Application 3: Ehrenfest Chain and Hypercubes

Random Walks on Graphs, Hitting Times and Cover Times

Random Walks on Paths and Grids

SAT and a Randomised Algorithm for 2-SAT

The Ehrenfest Markov Chain

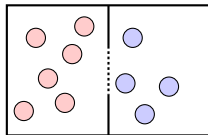
Ehrenfest Model

- A simple model for the exchange of molecules between two boxes

The Ehrenfest Markov Chain

Ehrenfest Model

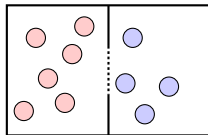
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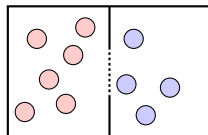
- A simple model for the exchange of molecules between two boxes
- We have d particles



The Ehrenfest Markov Chain

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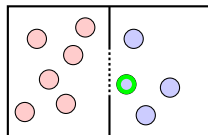
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- At each step a particle is selected **uniformly at random** and switches to the other box



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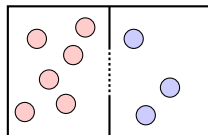
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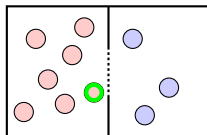
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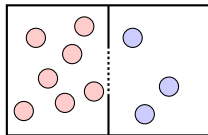


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- A simple model for the exchange of molecules between two boxes
- We have d particles
- At each step a particle is selected **uniformly at random** and switches to the other box
- If $\Omega = \{0, 1, \dots, d\}$ denotes the **number of particles** in the red box, then:

$$P_{x,x-1} = \frac{x}{d} \quad \text{and} \quad P_{x,x+1} = \frac{d-x}{d}.$$

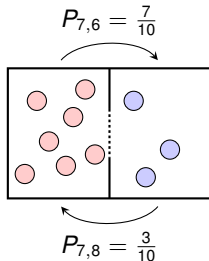


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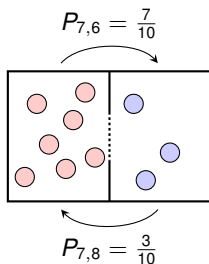


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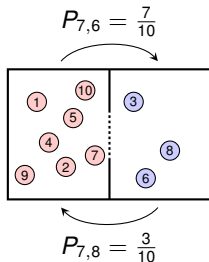
Let us now enlarge the state space by looking at each particle **individually**!

The Ehrenfest Markov Chain

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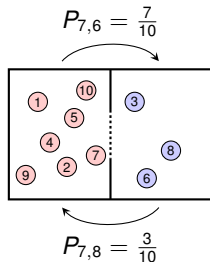
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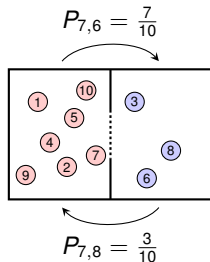
Random Walk on the Hypercube

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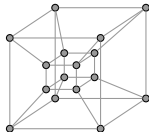
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- For each particle an indicator variable $\Rightarrow \Omega = \{0, 1\}^d$

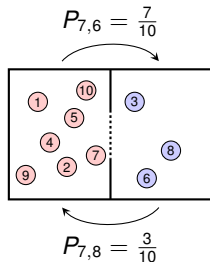


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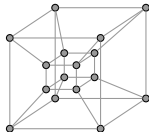
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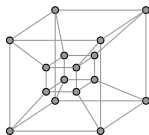
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Analysis of the Mixing Time

(Non-Lazy) Random Walk on the Hypercube

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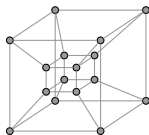


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Problem: This Markov Chain is **periodic**, as the number of ones always switches between odd to even!



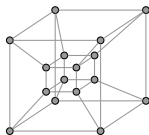
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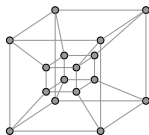
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Lazy Random Walk (1st Version)

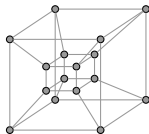
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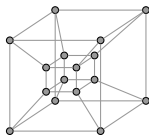
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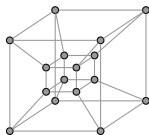
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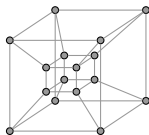
Lazy Random Walk (1st Version)

- At each step $t = 0, 1, 2, \dots$
 - Pick a **random** coordinate in $[d]$
 - With prob. $1/2$ **flip** coordinate.

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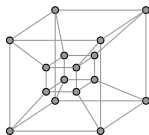
Lazy Random Walk (2nd Version)

- At each step $t = 0, 1, 2 \dots$
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Analysis of the Mixing Time

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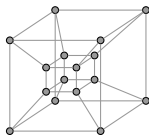
Lazy Random Walk (2nd Version)

- At each step $t = 0, 1, 2 \dots$
 - Pick a **random** coordinate in $[d]$
 - Set coordinate to $\{0, 1\}$ **uniformly**.

Analysis of the Mixing Time

(Non-Lazy) Random Walk on the Hypercube

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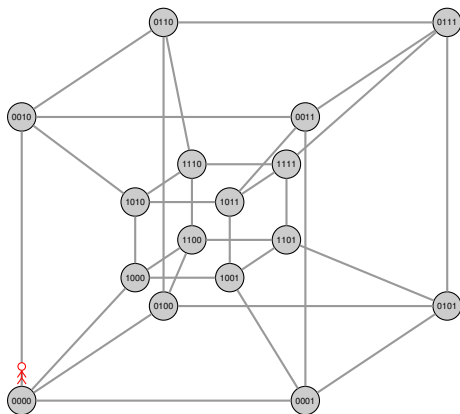
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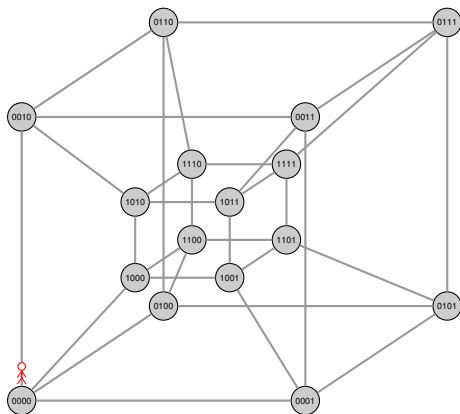
These two chains are equivalent!

Example of a Random Walk on a 4-Dimensional Hypercube



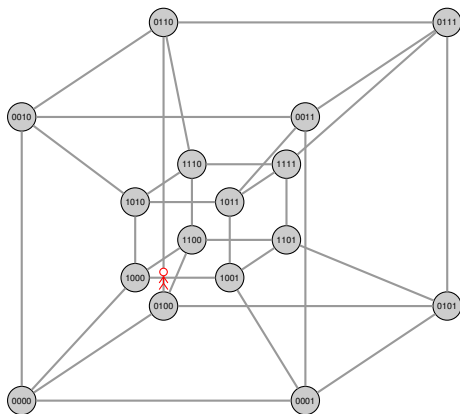
t	Coord.	X_t			
0		0	0	0	0

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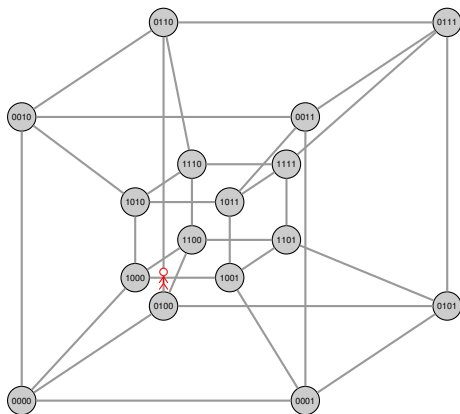
t	Coord.	X_t			
0	2	0	0	0	0
1		0	?	0	0

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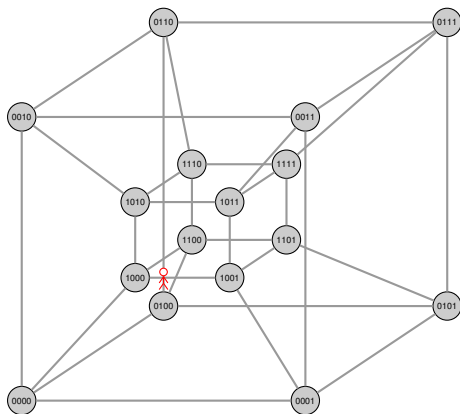
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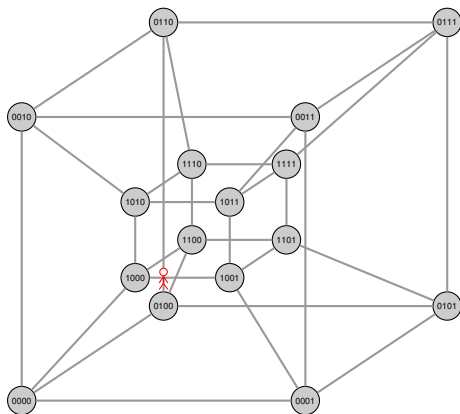
t	Coord.	X_t			
0	2	0	0	0	0
1	3	0	1	0	0
2		0	1	?	0

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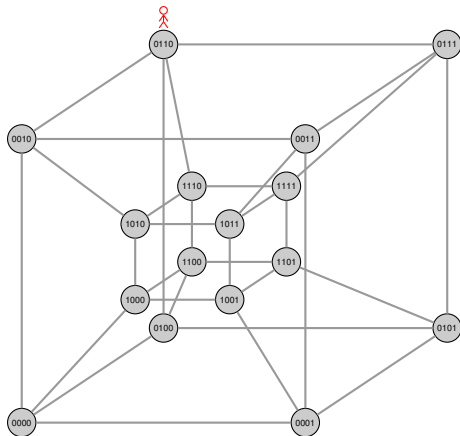
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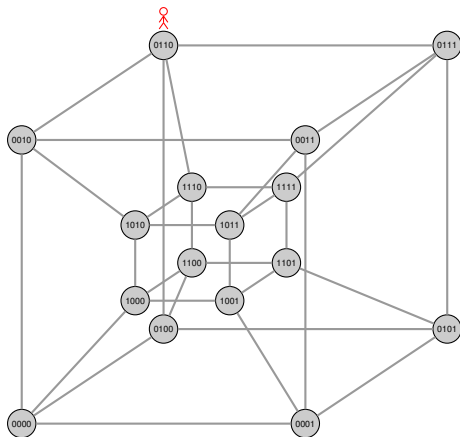
t	Coord.	X_t			
0	2	0	0	0	0
1	3	0	1	0	0
2	3	0	1	0	0
3		0	1	?	0

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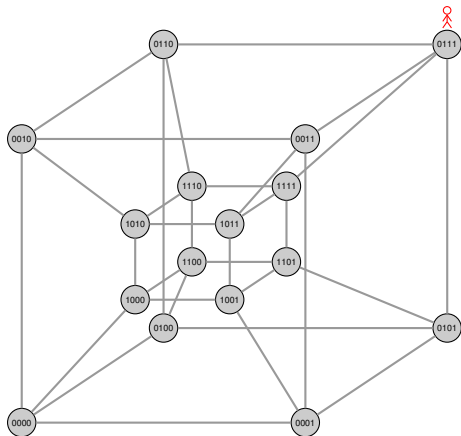
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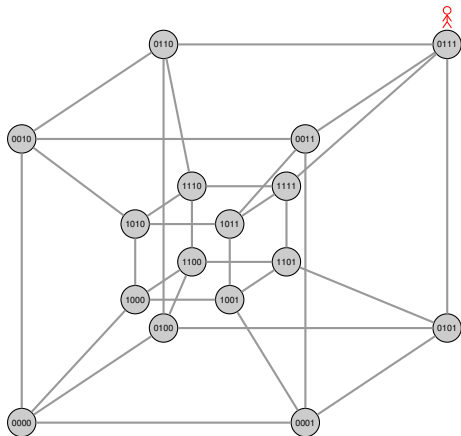
t	Coord.	X_t			
0	2	0	0	0	0
1	3	0	1	0	0
2	3	0	1	0	0
3	4	0	1	1	0
4		0	1	1	?

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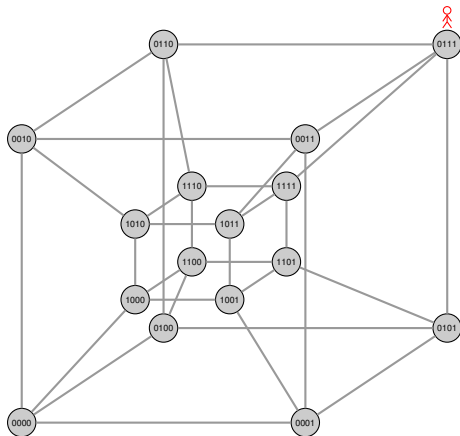
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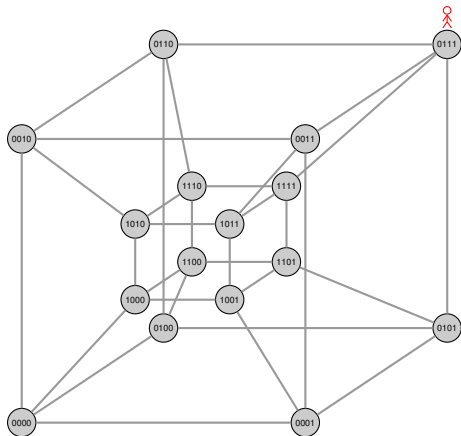
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2	3	0	1	0	0
3	4	0	1	1	0
4	2	0	1	1	1
5		0	?	1	1

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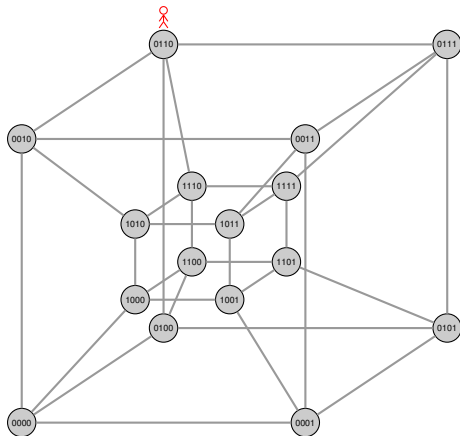
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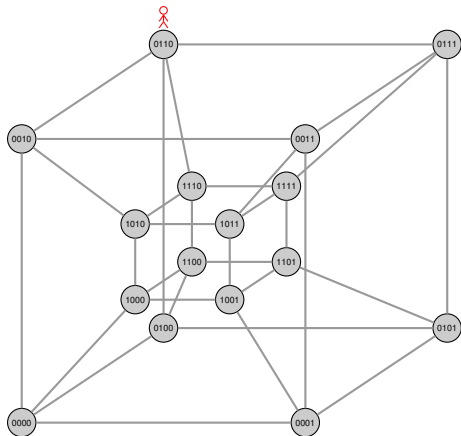
t	Coord.	X_t			
0	2	0	0	0	0
1	3	0	1	0	0
2	3	0	1	0	0
3	4	0	1	1	0
4	2	0	1	1	1
5	4	0	1	1	1
6		0	1	1	?

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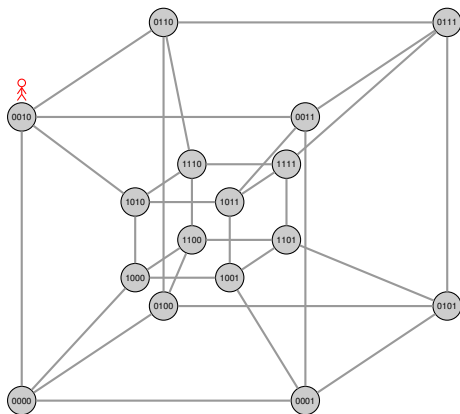
t	Coord.	X_t			
0	2	0	0	0	0
1	3	0	1	0	0
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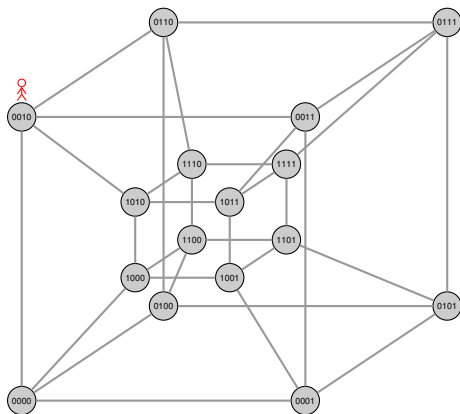
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6	2	0	1	1	0
7		0	?	1	0

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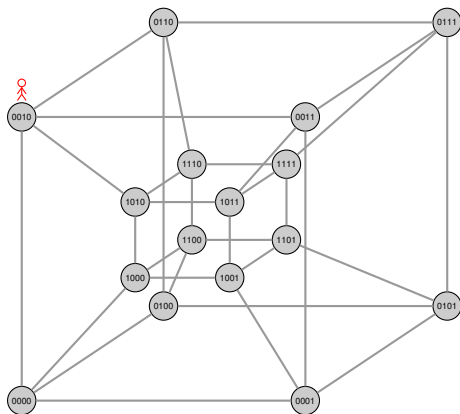
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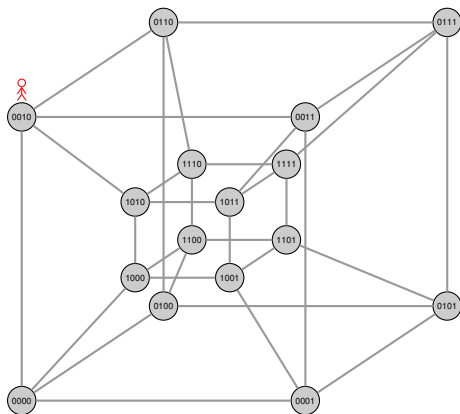
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5	4	0	1	1	1
6	2	0	1	1	0
7	4	0	0	1	0
8		0	0	1	?

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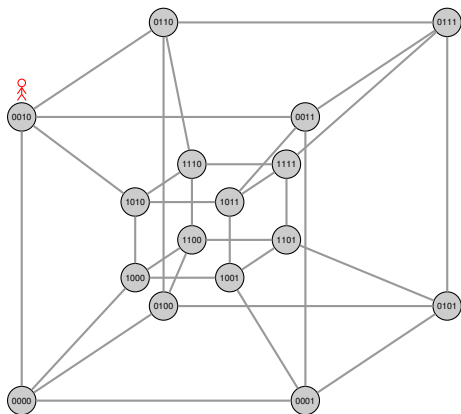
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4	2	0	1	1	1
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6	2	0	1	1	0
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8		0	0	1	0

Example of a Random Walk on a 4-Dimensional Hypercube



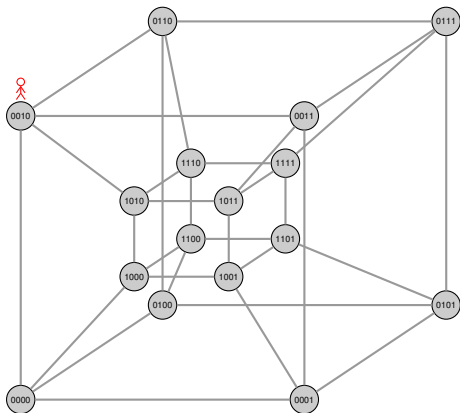
t	Coord.	X_t			
0	2	0	0	0	0
1	3	0	1	0	0
2	3	0	1	0	0
3	4	0	1	1	0
4	2	0	1	1	1
5	4	0	1	1	1
6	2	0	1	1	0
7	4	0	0	1	0
8	3	0	0	1	0
9		0	0	?	0

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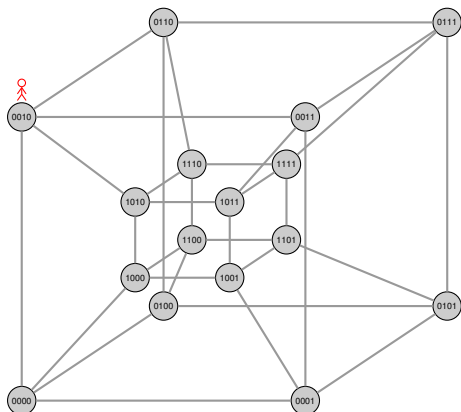
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2	3	0	1	0	0
3	4	0	1	1	0
4	2	0	1	1	1
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8	3	0	0	1	0
9	1	0	0	1	0
10	done!	?	0	1	0

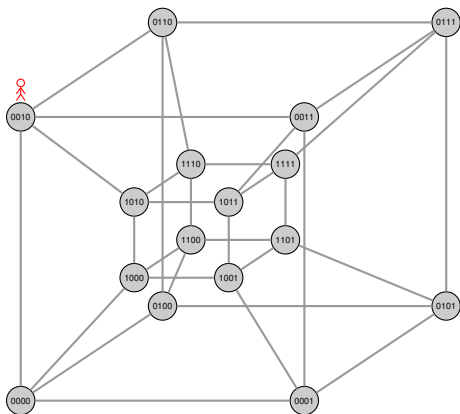
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Once **all coordinates** have been **picked** at least once, the state is uniformly at random in $\{0, 1\}^d$.

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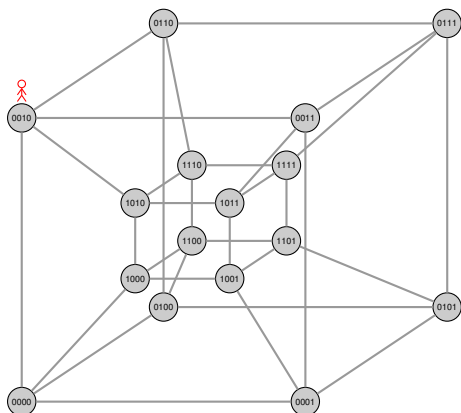


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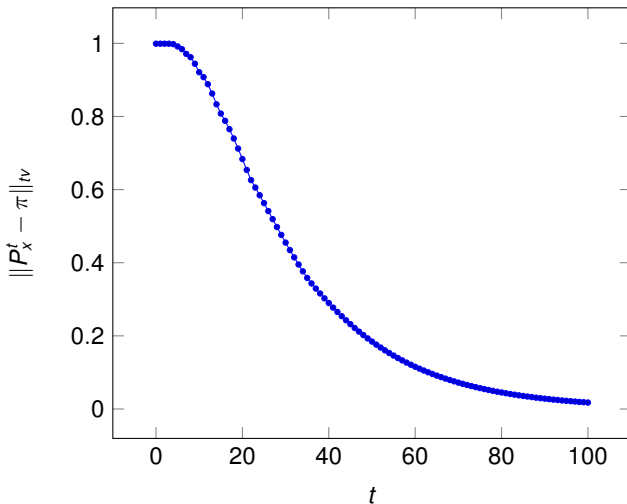
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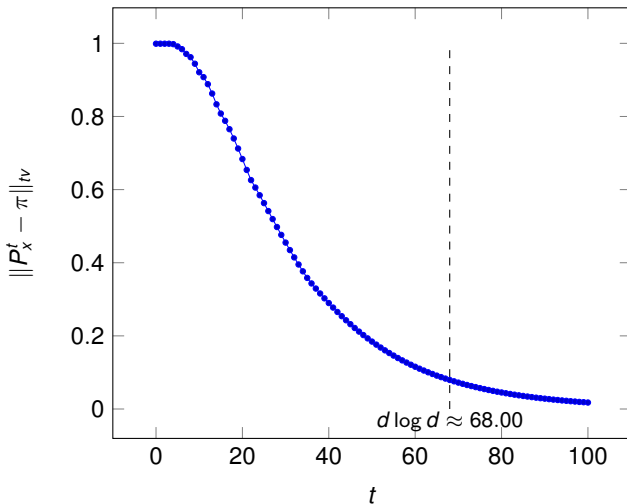
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We won't formalise this argument here (see [\[Ex. 4/5.11\]](#))

Total Variation Distance of Random Walk on Hypercube ($d = 22$)



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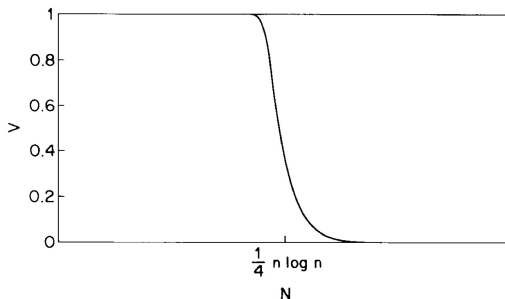


Fig. 1. The variation distance V as a function of N , for $n = 10^{12}$.

Source: "Asymptotic analysis of a random walk on a hypercube with many dimensions", P. Diaconis, R.L. Graham, J.A. Morrison; Random Structures & Algorithms, 1990.

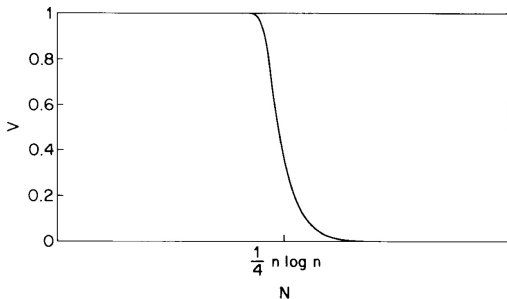


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- This is a numerical plot of a **theoretical bound**, where $d = 10^{12}$
(Minor Remark: This random walk is with a loop probability of $1/(d + 1)$)
- The variation distance exhibits a so-called **cut-off** phenomena:

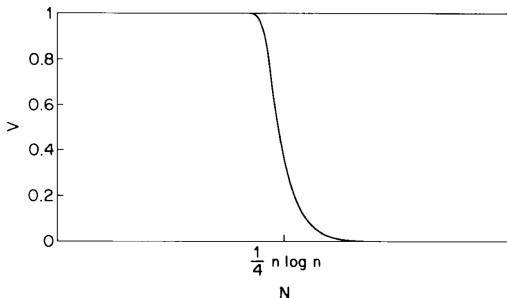


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 - Distance remains close to its maximum value 1 until step $\frac{1}{4}n \log n - \Theta(n)$
 - Then distance moves close to 0 before step $\frac{1}{4}n \log n + \Theta(n)$

Application 3: Ehrenfest Chain and Hypercubes

Random Walks on Graphs, Hitting Times and Cover Times

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Stopping and Hitting Times

A non-negative integer random variable τ is a **stopping time** for $(X_t)_{t \geq 0}$ if for every $s \geq 0$ the event $\{\tau = s\}$ depends only on X_0, \dots, X_s .

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Some distinguish between $\tau_y^+ = \min\{t \geq 1 : X_t = y\}$ and $\tau_y = \min\{t \geq 0 : X_t = y\}$

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— A Useful Identity —

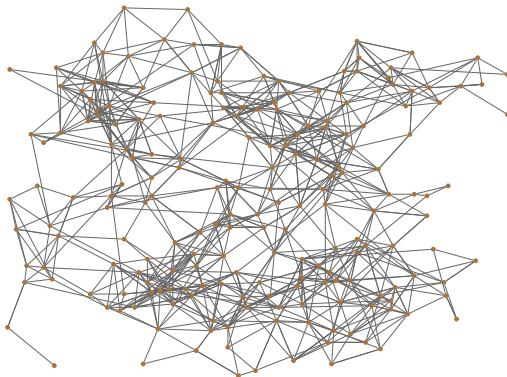
Hitting times are the solution to a **set of linear equations**:

$$h(x, y) \stackrel{\text{Markov Prop.}}{=} 1 + \sum_{z \in \Omega \setminus \{y\}} P(x, z) \cdot h(z, y) \quad \forall x, y \in \Omega.$$

Random Walks on Graphs

A **Simple Random Walk (SRW)** on a graph G is a Markov chain on $V(G)$ with

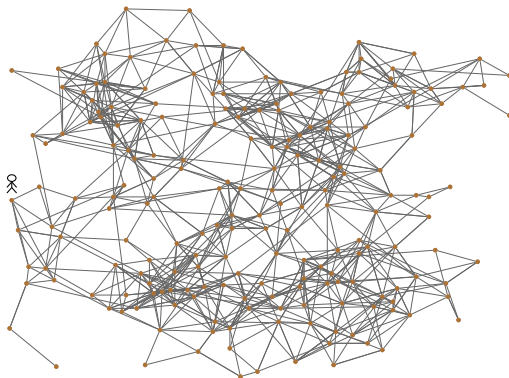
$$P(u, v) = \begin{cases} \frac{1}{\deg(u)} & \text{if } \{u, v\} \in E, \\ 0 & \text{if } \{u, v\} \notin E. \end{cases}, \quad \text{and} \quad \pi(u) = \frac{\deg(u)}{2|E|}$$



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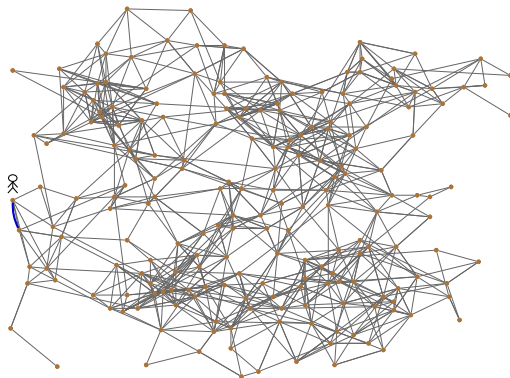
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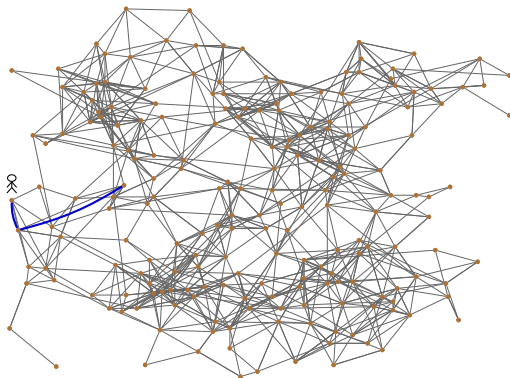
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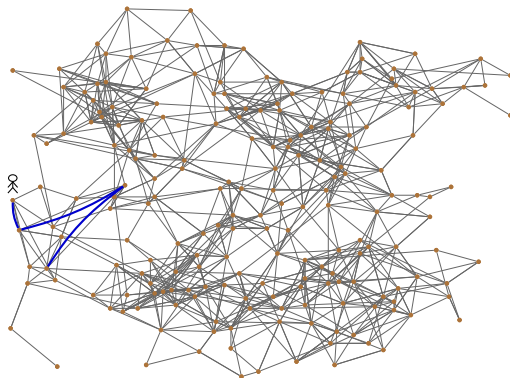
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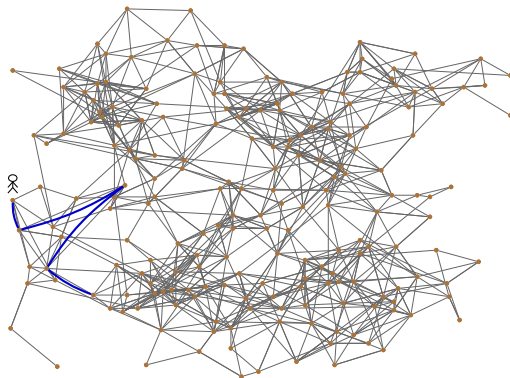
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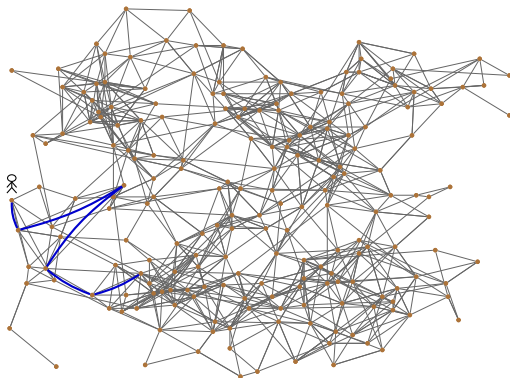
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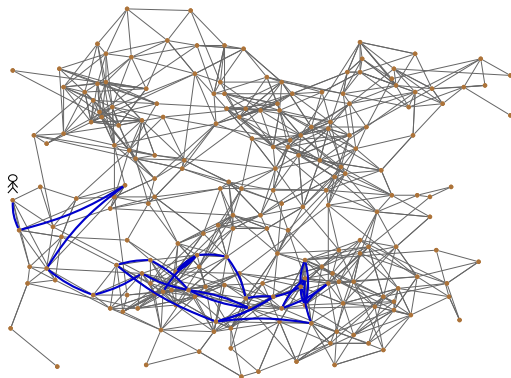
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Fact: For any graph G the LRW on G is **aperiodic**.

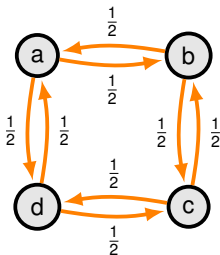
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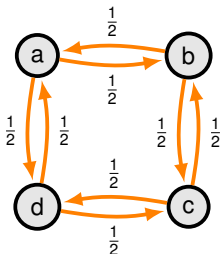
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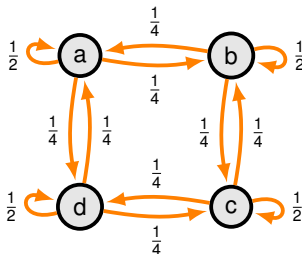
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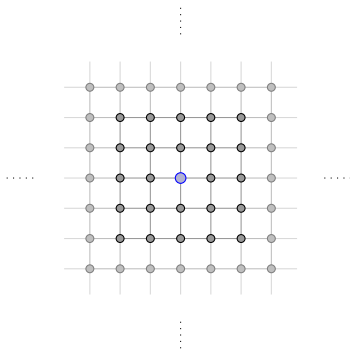
1921: The Birth of Random Walks on (Infinite) Graphs (Polyá)

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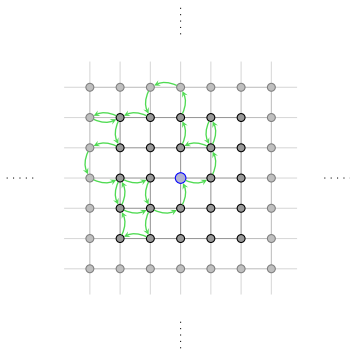
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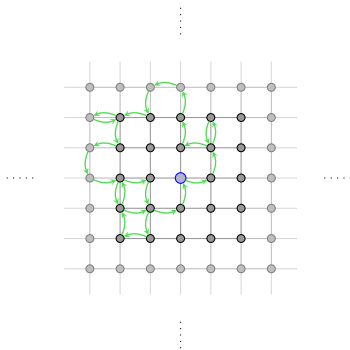
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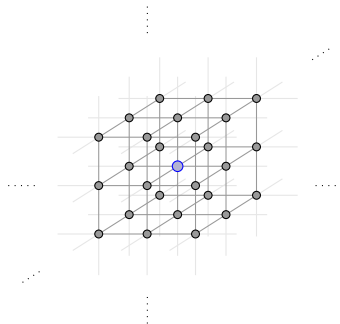
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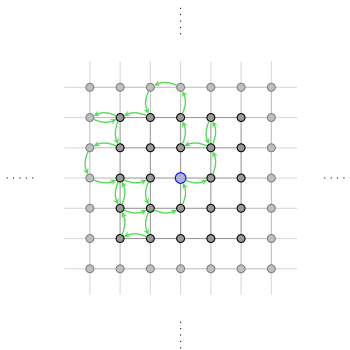
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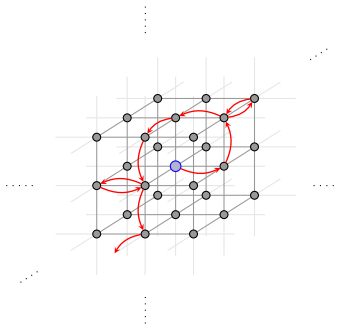
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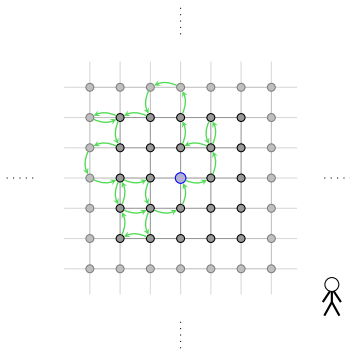
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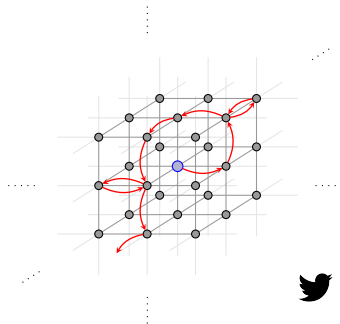
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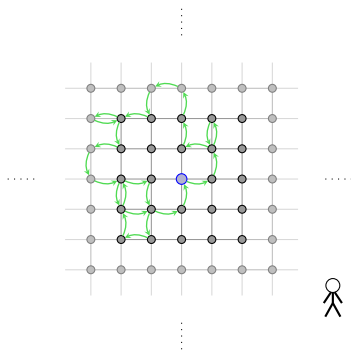


“A drunk man will find his way home, but a drunk bird may get lost forever.”

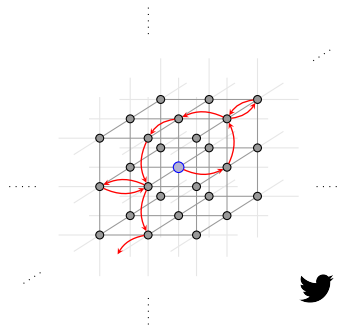
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But for any regular (finite) graph, the **expected return time** to u is $1/\pi(u) = n$

SRW Random Walk on Two-Dimensional Grids: Animation

Random Walk on a Path (1/2)

The n -path P_n is the graph with $V(P_n) = [0, n]$, $E(P_n) = \{\{i, j\} : j = i + 1\}$.



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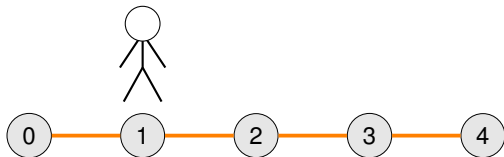


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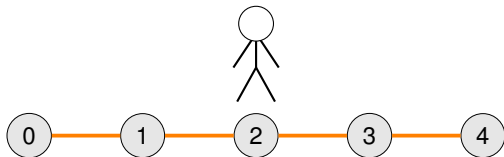


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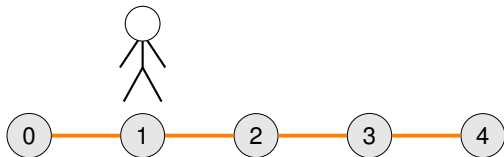


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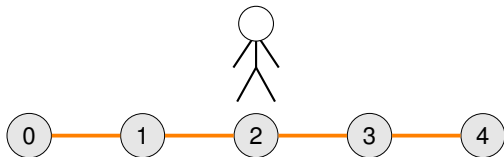


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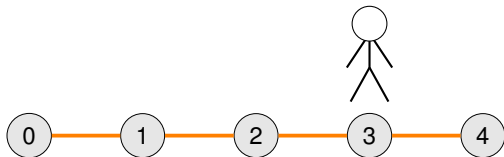


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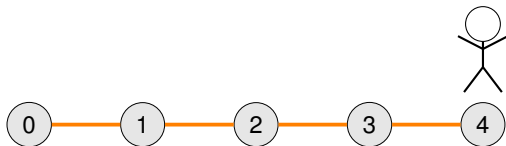


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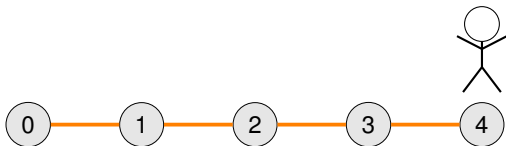


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Exercise: [\[Exercise 4/5.15\]](#) What happens for the LRW on P_n ?

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Application 3: Ehrenfest Chain and Hypercubes

Random Walks on Graphs, Hitting Times and Cover Times

Random Walks on Paths and Grids

SAT and a Randomised Algorithm for 2-SAT

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2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

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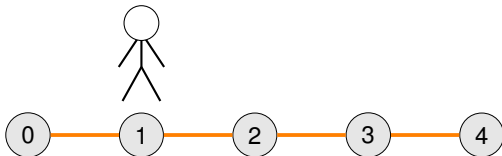
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F T T T F F F T F T

$$\alpha = (T, T, F, T).$$



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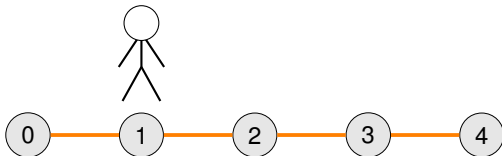
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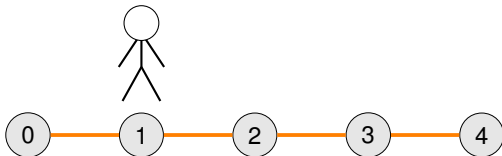
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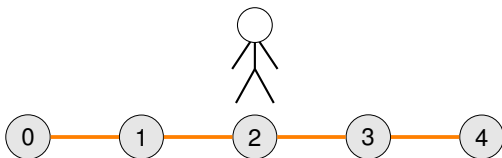
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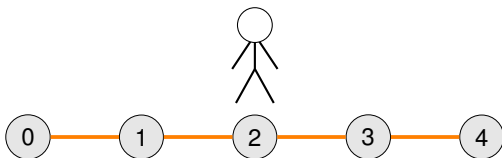
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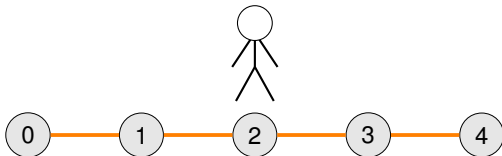
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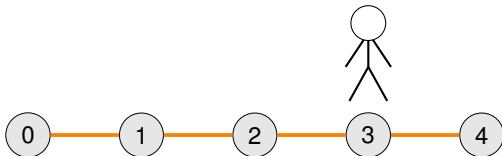
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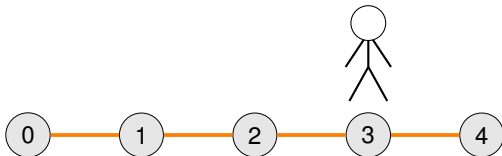
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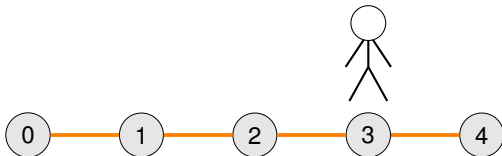
- 1: Start with an arbitrary truth assignment
 - 2: **Repeat up to $2n^2$ times**
 - 3: Pick an **arbitrary** unsatisfied clause
 - 4: Choose a random **literal** and **switch** its value
 - 5: **If** formula is satisfied **then return** "Satisfiable"
 - 6: **return** "Unsatisfiable"
- Call each loop of (2) a **step**. Let A_i be the variable assignment at step i .
 - Let α be **any solution** and $X_i = |\text{variable values shared by } A_i \text{ and } \alpha|$.

Example 1 :

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (x_4 \vee \overline{x_3}) \wedge (x_4 \vee \overline{x_1})$$

T F F T T T F T **F** F

$$\alpha = (T, T, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	T	F	F
2	T	T	F	F

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

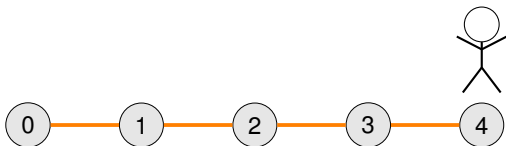
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T F F T T T T T T F

$$\alpha = (T, T, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	T	F	F
2	T	T	F	F
3	T	T	F	T

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

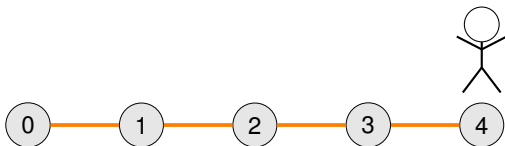
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 - Let α be **any solution** and $X_i = |\text{variable values shared by } A_i \text{ and } \alpha|$.

Example 1 : Solution Found

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (x_4 \vee \overline{x_3}) \wedge (x_4 \vee \overline{x_1})$$

T F F T T T T T T F

$$\alpha = (T, T, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	T	F	F
2	T	T	F	F
3	T	T	F	T

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

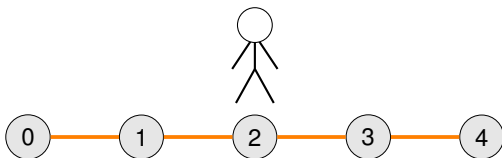
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 - Let α be any solution and $X_i = |\text{variable values shared by } A_i \text{ and } \alpha|$.

Example 2 :

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (x_4 \vee x_3) \wedge (x_4 \vee \overline{x_1})$$

F T T T F F F F F T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

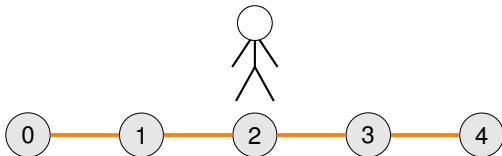
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Example 2 :

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (x_4 \vee x_3) \wedge (x_4 \vee \overline{x_1})$$

F T T T F F F F F T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F

2-SAT

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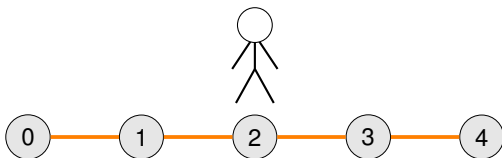
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Example 2 :

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (x_4 \vee x_3) \wedge (x_4 \vee \overline{x_1})$$

F T T T F F F F F T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F

2-SAT

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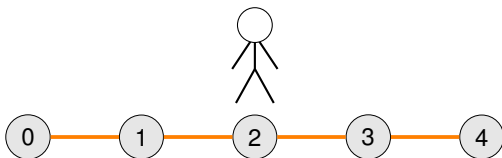
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Example 2 :

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F T T T F F **F** F F T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

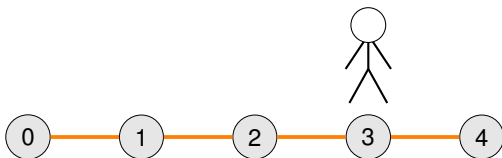
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F T T T F F T F T T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	F	F	T

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

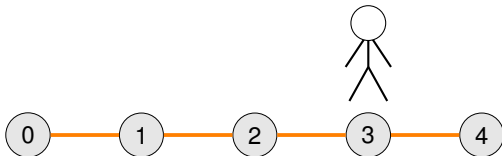
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 - Let α be any solution and $X_i = |\text{variable values shared by } A_i \text{ and } \alpha|$.

Example 2 :

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (\textcolor{red}{x_1} \vee \textcolor{red}{x_2}) \wedge (x_4 \vee x_3) \wedge (x_4 \vee \overline{x_1})$$

F T T T F F T F T T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	F	F	T

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

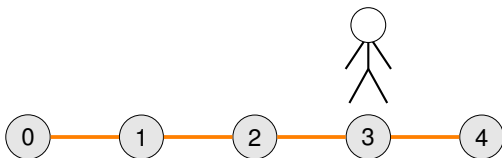
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Example 2 :

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F T T T F **F** T F T T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	F	F	T

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

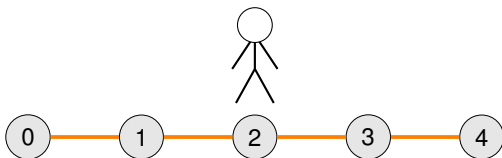
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F F T T F T T F T T

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t	x_1	x_2	x_3	x_4
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1	F	F	F	T
2	F	T	F	T

2-SAT

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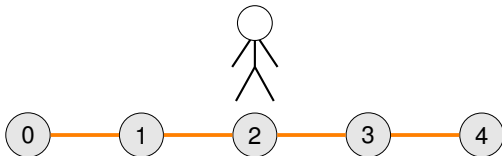
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F F T T F T T F T T

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	F	F	T
2	F	T	F	T

2-SAT

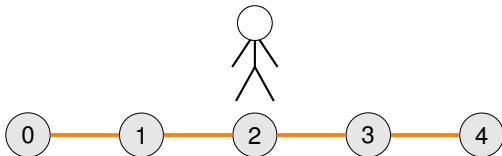
RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

- 1: Start with an arbitrary truth assignment
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 - 3: Pick an **arbitrary** unsatisfied clause
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Example 2 :

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (x_4 \vee x_3) \wedge (x_4 \vee \overline{x_1})$$

F F T T F T T F T T



$$\alpha = (T, F, F, T).$$

t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	F	F	T
2	F	T	F	T

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

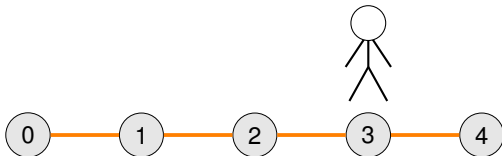
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T F F T T T T F T F

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	F	F	T
2	F	T	F	T
3	T	T	F	T

2-SAT

RANDOMISED-2-SAT (Input: a 2-SAT-Formula)

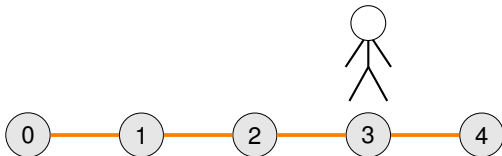
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- Call each loop of (2) a **step**. Let A_i be the variable assignment at step i .
 - Let α be any solution and $X_i = |\text{variable values shared by } A_i \text{ and } \alpha|$.

Example 2 : (Another) Solution Found

$$(x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (x_4 \vee x_3) \wedge (x_4 \vee \overline{x_1})$$

T F F T T T T F T F

$$\alpha = (T, F, F, T).$$



t	x_1	x_2	x_3	x_4
0	F	F	F	F
1	F	F	F	T
2	F	T	F	T
3	T	T	F	T

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

Proof: Fix any solution α , then for any $i \geq 0$ and $1 \leq k \leq n - 1$,

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

Proof: Fix any solution α , then for any $i \geq 0$ and $1 \leq k \leq n - 1$,

(i) $\mathbf{P}[X_{i+1} = 1 \mid X_i = 0] = 1$

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

Proof: Fix any solution α , then for any $i \geq 0$ and $1 \leq k \leq n - 1$,

- (i) $\mathbf{P}[X_{i+1} = 1 \mid X_i = 0] = 1$
- (ii) $\mathbf{P}[X_{i+1} = k + 1 \mid X_i = k] \geq 1/2$

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

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- (iii) $\mathbf{P}[X_{i+1} = k - 1 \mid X_i = k] \leq 1/2$.

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

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- (iii) $\mathbf{P}[X_{i+1} = k - 1 \mid X_i = k] \leq 1/2$.

Notice that if $X_i = n$ then $A_i = \alpha$ thus **solution** found (may find another first).

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

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Notice that if $X_i = n$ then $A_i = \alpha$ thus **solution** found (may find another first).

Assume (pessimistically) that $X_0 = 0$ (none of our initial guesses is right).

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

Proof: Fix any solution α , then for any $i \geq 0$ and $1 \leq k \leq n - 1$,

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The process X_i is complicated to describe in full; however by (i) – (iii) we can **bound** it by Y_i (SRW on the n -path from 0).

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

Proof: Fix any solution α , then for any $i \geq 0$ and $1 \leq k \leq n - 1$,

- (i) $\mathbf{P}[X_{i+1} = 1 \mid X_i = 0] = 1$
- (ii) $\mathbf{P}[X_{i+1} = k + 1 \mid X_i = k] \geq 1/2$
- (iii) $\mathbf{P}[X_{i+1} = k - 1 \mid X_i = k] \leq 1/2$.

Notice that if $X_i = n$ then $A_i = \alpha$ thus **solution** found (may find another first).

Assume (pessimistically) that $X_0 = 0$ (none of our initial guesses is right).

The process X_i is complicated to describe in full; however by (i) – (iii) we can **bound** it by Y_i (SRW on the n -path from 0). This gives (see also [Ex 4/5.17])

$$\mathbf{E}[\text{time to find sol}] \leq \mathbf{E}_0[\min\{t : X_t = n\}] \leq \mathbf{E}_0[\min\{t : Y_t = n\}] = h(0, n) = n^2.$$

□

2-SAT and the SRW on the Path

Expected iterations of (2) in RANDOMISED-2-SAT

If the formula is **satisfiable**, then the **expected number of steps** before RANDOMISED-2-SAT outputs a valid solution is at most n^2 .

Proof: Fix any solution α , then for any $i \geq 0$ and $1 \leq k \leq n-1$,

- (i) $\mathbf{P}[X_{i+1} = 1 \mid X_i = 0] = 1$
- (ii) $\mathbf{P}[X_{i+1} = k+1 \mid X_i = k] \geq 1/2$
- (iii) $\mathbf{P}[X_{i+1} = k-1 \mid X_i = k] \leq 1/2$.

Notice that if $X_i = n$ then $A_i = \alpha$ thus **solution** found (may find another first).

Assume (pessimistically) that $X_0 = 0$ (none of our initial guesses is right).

The process X_i is complicated to describe in full; however by (i) – (iii) we can **bound** it by Y_i (SRW on the n -path from 0). This gives (see also [Ex 4/5.17])

$\mathbf{E}[\text{time to find sol}] \leq \mathbf{E}_0[\min\{t : X_t = n\}] \leq \mathbf{E}_0[\min\{t : Y_t = n\}] = h(0, n) = n^2$.

Running for $2n^2$ steps and using Markov's inequality yields: □

2-SAT and the SRW on the Path

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Proposition

If the formula is **satisfiable**, RANDOMISED-2-SAT will return a valid solution in $O(n^2)$ steps with probability at least $1/2$.

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Exercise: (difficult, beyond this course) What happens to the above analysis if we apply the same algorithm to 3-SAT?

Boosting Success Probabilities

Boosting Lemma

Suppose a randomised algorithm succeeds with probability (at least) p . Then for any $C \geq 1$, $\lceil \frac{C}{p} \cdot \log n \rceil$ repetitions are sufficient to succeed (in at least one repetition) with probability at least $1 - n^{-C}$.

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Proof: Recall that $1 - p \leq e^{-p}$ for all real p . Let $t = \lceil \frac{C}{p} \log n \rceil$ and observe

$$\begin{aligned} \mathbf{P}[t \text{ runs all fail}] &\leq (1 - p)^t \\ &\leq e^{-pt} \\ &\leq n^{-C}, \end{aligned}$$

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RANDOMISED-2-SAT

There is a $O(n^2 \log n)$ -step algorithm for 2-SAT which succeeds w.h.p.