Introduction to Probability

Lecture 1: Conditional probabilities and Bayes' theorem Mateja Jamnik, Thomas Sauerwald

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Outline

Logistics, motivation, background

Conditional probability

Bayes' Theorem

Independence

Lecturers







Thomas Sauerwald

Course logistics

Rough syllabus:

- Introduction to probability: 1 lecture
- Discrete and continuous random variables: 6 lectures
- Moments and limit theorems: 3 lectures
- Applications/statistics: 2 lectures

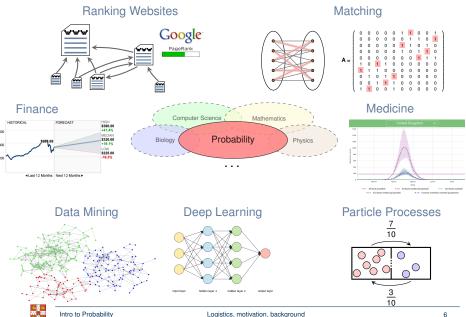
Recommended reading:

- Ross, S.M. (2014). A First course in probability. Pearson (9th ed.).
- Dekking, F.M., et. al. (2005) A modern introduction to probability and statistics. Springer.
- Bertsekas, D.P. & Tsitsiklis, J.N. (2008). Introduction to probability. Athena Scientific.
- Grimmett, G. & Welsh, D. (2014). Probability: an Introduction. Oxford University Press (2nd ed.).

Why probability?

- Gives us mathematical tools to deal with uncertain events.
- It is used everywhere, especially in applications of machine learning.
- Machine learning: use probability to compute predictions about and from data.
- Probability is not statistics:
 - Both about random processes.
 - Probability: logically self-contained, few rules for computing, one correct answer.
 - Statistics: messier, more art, get experimental data and try to draw probabilistic conclusions, no single correct answer.

Applications of probability



Prerequisite background

- Set theory
- Counting: product rule, sum rule, inclusion-exclusion
- Combinatorics: permutations
- Probability space: sample space, event space
- Axioms
- Union bound

Look for revision material of above on the course website:

https://www.cl.cam.ac.uk/teaching/2425/IntroProb/

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Definition

Conditional probability

Consider an experiment with sample space S, and two events E and F. Then, the (conditional) probability of event E given F has occurred (denoted P[E|F]) with P[F] > 0 is defined by

$$P[E|F] = \frac{P[E \cap F]}{P[F]} = \frac{P[EF]}{P[F]}$$

Sample space: all possible outcomes consistent with F (i.e., $S \cap F = F$) Event space: all outcomes in E consistent with F (i.e., $E \cap F$) Note: we assume that all outcomes are equally likely

$$\mathbf{P}[E|F] = \frac{\text{\# outcomes in } E \cap F}{\text{\# outcomes in } F} = \frac{\text{\# outcomes in } E \cap F}{\text{\# outcomes in } S} = \frac{\mathbf{P}[E \cap F]}{\mathbf{P}[F]}$$

Example

Example

Two dice are rolled yielding value D_1 and D_2 . Let E be event that $D_1 + D_2 = 4$.

- 1. What is **P**[*E*]?
- 2. Let event F be $D_1 = 2$. What is P[E|F]?

Answer

Rules revisited

Chain rule ———

Rearranging the definition of conditional probability gives us:

$$P[EF] = P[E|F]P[F]$$

Generalisation of the Chain rule:

Multiplication rule _____

$$\mathbf{P}[E_1 E_2 \cdots E_n] = \mathbf{P}[E_1] \mathbf{P}[E_2 | E_1] \mathbf{P}[E_3 | E_2 E_1] \cdots \mathbf{P}[E_n | E_1 \cdots E_{n-1}]$$

Example

Example

An ordinary deck of 52 playing cards is randomly divided into 4 piles of 13 cards each. What is the probability that each pile has exactly 1 ace?

Define:

E₁= ace♥ is in any one pile

 E_2 = ace \heartsuit and ace \spadesuit are in different piles

E₃= ace♥, ace♠ and ace♣ are in different piles

 E_4 = all aces are in different piles

$$P[E_1E_2E_3E_4] = P[E_1]P[E_2|E_1]P[E_3|E_1E_2]P[E_4|E_1E_2E_3]$$

We have $P[E_1] = 1$. For rest we consider complement of next ace being in the same pile and thus have:

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Law of total probability

The law of total probability (a.k.a. Partition theorem) -

For events E and F where P[F] > 0, then for any event E

$$P[E] = P[EF] + P[EF^c] = P[E|F]P[F] + P[E|F^c]P[F^c]$$

In general, for disjoint events $F_1, F_2, \dots F_n$ s.t. $F_1 \cup F_2 \cup \dots \cup F_n = S$,

$$\mathbf{P}[E] = \sum_{i=1}^{n} \mathbf{P}[E|F_{i}] \mathbf{P}[F_{i}]$$

Intuition:

Want to know probability of E. There are two scenarios, F and F^c . If we know these and the probability of E conditioned on each scenario, we can compute the probability of E.

Lightbulb example

Example

There are 3 boxes each containing a different number of light bulbs. The first box has 10 bulbs of which 4 are dead, the second has 6 bulbs of which 1 is dead, and the third box has 8 bulbs of which 3 are dead. What is the probability of a dead bulb being selected when a bulb is chosen at random from one of the 3 boxes (each box has equal chance of being picked)?

Answer

Let event E = "dead bulb is picked", and F_1 = "bulb is picked from first box", F_2 = "bulb is picked from second box" and F_3 = "bulb is picked from third box". We know:

$$P[E|F_1] = \frac{4}{10}, P[E|F_2] = \frac{1}{6}, P[E|F_3] = \frac{3}{8}$$

We need to compute P[E], and we know that $P[F_i] = \frac{1}{3}$:

Bayes' theorem

How many spam emails contain the word "Dear"?

$$P[E|F] = P["Dear"|spam]$$

But how about what is the probability that an email containing "Dear" is spam?

$$P[F|E] = P[spam|"Dear"]$$

- Bayes' theorem -

For any events E and F where P[E] > 0 and P[F] > 0,

$$\mathbf{P}[F|E] = \frac{\mathbf{P}[E|F]\mathbf{P}[F]}{\mathbf{P}[E]}$$

and in expanded form,

$$\mathbf{P}[F|E] = \frac{\mathbf{P}[E|F]\mathbf{P}[F]}{\mathbf{P}[E|F]\mathbf{P}[F] + \mathbf{P}[E|F^c]\mathbf{P}[F^c]} = \frac{\mathbf{P}[E|F]\mathbf{P}[F]}{\sum_{i=1}^{n} \mathbf{P}[E|F_i]\mathbf{P}[F_i]}$$

using the Law of Total Probability. Note that all events F_i must be mutually exclusive (non-overlapping) and exhaustive (their union is the complete sample space) .

Example

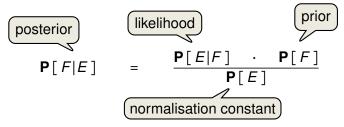
Example

60% of all email in 2022 is spam. 20% of spam contains the word "Dear". 1% of non-spam contains the word "Dear". What is the probability that an email is spam given it contains the word "Dear"?

Answer

■ Let event *E* ="Dear", event *F* = spam.

Bayes' terminology



F: hypothesis, E: evidence

P[F]: "prior probability" of hypothesis

P[E|F]: probability of evidence given hypothesis (likelihood)

P[*E*]: calculated by making sure that probabilities of all outcomes sum to 1 (they are "normalised")

Confusion matrix (error matrix)

Used in classification tasks for predicting output error.

		True condition	
	Total population	Condition positive <i>F</i>	Condition negative F^c
Predicted condition	Predicted condition pos-itive E	True positive P [<i>E</i> <i>F</i>]	False positive P[E F ^c]
	Predicted condition negative E^c	False negative $P[E^c F]$	True negative $P[E^c F^c]$

Medical testing example

Example

- A test is 98% effective at detecting the disease COVID-19 ("true positive").
- The test has a "false positive" rate of 1%.
- 0.5% of the population has COVID-19.
- What is the likelihood you have COVID-19 if you test positive?

Answer

- Let E: test positive, F: actually have COVID-19.
- Need to find P[F|E].

Bayesian intuition

- 33% chance of having COVID-19 after testing positive may seem surprising.
- But the space of facts is now conditioned on a positive test result (people who test positive and have COVID-19 and people who test positive and don't have COVID-19).

	F yes disease	F^c no disease
E test+	True positive	False positive
	P[E F] = 0.98	$P[E F^c] = 0.01$
E ^c test-	False negative	True negative
	$\mathbf{P}[E^c F] = 0.02$	$\mathbf{P}\left[E^{c} F^{c}\right] = 0.99$

But what is a chance of having COVID-19 if you test and it comes back negative?

$$\mathbf{P}[F|E^c] = \frac{\mathbf{P}[E^c|F]\mathbf{P}[F]}{\mathbf{P}[E^c|F]\mathbf{P}[F] + \mathbf{P}[E^c|F^c]\mathbf{P}[F^c]} \approx 0.000$$

- We update our beliefs with Bayes' theorem: I have 0.5% chance of having COVID-19. I take the test:
 - Test is positive: I now have 33% chance of having COVID-19.
 - Test is negative: I now have 0.01% chance of having COVID-19.
- So it makes sense to take the test.

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Independence

Independent events

Independence

Two events E and F are independent if and only if

$$P[EF] = P[E]P[F]$$

Otherwise, they are called dependent events.

In general, n events E_1, E_2, \ldots, E_n are mutually independent if for every subset of these events with r elements (where $r \le n$) it holds that

$$\mathbf{P}[E_aE_b\cdots E_r] = \mathbf{P}[E_a]\mathbf{P}[E_b]\cdots \mathbf{P}[E_r]$$

Therefore for 3 events E, F, G to be independent, we must have

Independence of complement

Notice an equivalent definition for independent events E and F (P[F] > 0)

$$P[E|F] = P[E]$$

Proof:

Independence of complement -

If events E and F are independent, then E and F^c are independent:

$$\mathbf{P}[EF^c] = \mathbf{P}[E]\mathbf{P}[F^c]$$

Proof:

Example

Example

Each roll of a die is an independent trial. We have two rolls of D_1 and D_2 . Let event $E: D_1 = 1$, $F: D_2 = 6$ and event $G: D_1 + D_2 = 7$ (thus $G = \{(1,6), (2,5), (3,4), (4,3), (5,2), (6,1)\}$).

- 1. Are *E* and *F* independent?
- 2. Are E and G independent?
- 3. Are E, F, G independent?

Answer

Conditional independence

Conditional independence -

Two events E and F are called conditionally independent given a third event G if

$$P[EF|G] = P[E|G]P[F|G]$$

Or equivalently,

$$P[E|FG] = P[E|G]$$

Notice that:

- Dependent events can become conditionally independent.
- Independent events can become conditionally dependent.
- Knowing when conditioning breaks or creates independence is a big part of building complex probabilistic models.

Example revisited

Example

Each roll of a die is an independent trial. We have two rolls of D_1 and D_2 . Let event $E: D_1 = 1$, $F: D_2 = 6$ and event $G: D_1 + D_2 = 7$ (thus $G = \{(1,6), (2,5), (3,4), (4,3), (5,2), (6,1)\}$).

- 1. Are *E* and *F* independent?
- 2. Are E and F independent given G?

Answer

Conditioning on event G:

Name of rule	Original rule	Conditional rule
1st axiom of probability	0 ≤ P [<i>E</i>] ≤ 1	$0 \le \mathbf{P}[E G] \le 1$
Complement	$P[E] = 1 - P[E^c]$	$P[E G] = 1 - P[E^c G]$
Chain rule	P[EF] = P[E F]P[F]	P[EF G] = P[E FG]P[F G]
Bayes' theorem	$P[F E] = \frac{P[E F]P[F]}{P[E]}$	$P[F EG] = \frac{P[E FG]P[F G]}{P[E G]}$