

Introduction to Probability

Lecture 11: Estimators (Part II)

Mateja Jamnik, [Thomas Sauerwald](#)

University of Cambridge, Department of Computer Science and Technology
email: {mateja.jamnik,thomas.sauerwald}@cl.cam.ac.uk

Easter 2025



UNIVERSITY OF
CAMBRIDGE

Estimating Population Size (First Model)

Mean Squared Error

Estimating Population Size (Second Model)

Estimating Population Size (First Model)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
- Each of the IDs is drawn **without replacement** from the **discrete uniform distribution** over $\{1, 2, \dots, N\}$

Estimating Population Size (First Model)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
- Each of the IDs is drawn **without replacement** from the **discrete uniform distribution** over $\{1, 2, \dots, N\}$
- This is also known as **Tank Estimation Problem** or **(Discrete) Taxi Problem**

Estimating Population Size (First Model)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
- Each of the IDs is drawn **without replacement** from the **discrete uniform distribution** over $\{1, 2, \dots, N\}$
- This is also known as **Tank Estimation Problem** or **(Discrete) Taxi Problem**

7, 3, 10, 46, 14

Estimating Population Size (First Model)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
- Each of the IDs is drawn **without replacement** from the **discrete uniform distribution** over $\{1, 2, \dots, N\}$
- This is also known as **Tank Estimation Problem** or **(Discrete) Taxi Problem**

7, 3, 10, 46, 14



Warning

- As before, we denote the samples X_1, X_2, \dots, X_n

Estimating Population Size (First Model)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
- Each of the IDs is drawn without replacement from the **discrete uniform distribution** over $\{1, 2, \dots, N\}$
- This is also known as **Tank Estimation Problem** or **(Discrete) Taxi Problem**

7, 3, 10, 46, 14



Warning

- As before, we denote the samples X_1, X_2, \dots, X_n
- Since sampling is without replacement:

Estimating Population Size (First Model)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
- Each of the IDs is drawn without replacement from the **discrete uniform distribution** over $\{1, 2, \dots, N\}$
- This is also known as **Tank Estimation Problem** or **(Discrete) Taxi Problem**

7, 3, 10, 46, 14



Warning

- As before, we denote the samples X_1, X_2, \dots, X_n
- Since sampling is without replacement:
 - they are not independent! (but identically distributed)

Estimating Population Size (First Model)

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an **unknown parameter** N (so $N = \theta$)
- Each of the IDs is drawn without replacement from the **discrete uniform distribution** over $\{1, 2, \dots, N\}$
- This is also known as **Tank Estimation Problem** or **(Discrete) Taxi Problem**

7, 3, 10, 46, 14



Warning

- As before, we denote the samples X_1, X_2, \dots, X_n
- Since sampling is without replacement:
 - they are **not independent!** (but identically distributed)
 - their number must satisfy $n \leq N$

First Estimator Based on Sample Mean

Example 1

Construct an unbiased estimator T_1 using the sample mean.

Answer

First Estimator Based on Sample Mean

Example 1

Construct an unbiased estimator T_1 using the sample mean.

Answer

- The sample mean is

$$\bar{X}_n =$$

First Estimator Based on Sample Mean

Example 1

Construct an unbiased estimator T_1 using the sample mean.

Answer

- The sample mean is

$$\bar{X}_n = \frac{X_1 + X_2 + \cdots + X_n}{n}.$$

First Estimator Based on Sample Mean

Example 1

Construct an unbiased estimator T_1 using the sample mean.

Answer

- The sample mean is

$$\bar{X}_n = \frac{X_1 + X_2 + \cdots + X_n}{n}.$$

- Linearity of expectation applies (even for dependent random var.!):

First Estimator Based on Sample Mean

Example 1

Construct an unbiased estimator T_1 using the sample mean.

Answer

- The sample mean is

$$\bar{X}_n = \frac{X_1 + X_2 + \cdots + X_n}{n}.$$

- Linearity of expectation applies (even for dependent random var.!):

$$\mathbf{E}[\bar{X}_n] = \frac{n \cdot \mathbf{E}[X_1]}{n} = \mathbf{E}[X_1]$$

First Estimator Based on Sample Mean

Example 1

Construct an unbiased estimator T_1 using the sample mean.

Answer

- The sample mean is

$$\bar{X}_n = \frac{X_1 + X_2 + \cdots + X_n}{n}.$$

- Linearity of expectation applies (even for dependent random var.!):

$$\begin{aligned}\mathbf{E}[\bar{X}_n] &= \frac{n \cdot \mathbf{E}[X_1]}{n} = \mathbf{E}[X_1] \\ &= \sum_{i=1}^N i \cdot \frac{1}{N}\end{aligned}$$

First Estimator Based on Sample Mean

Example 1

Construct an unbiased estimator T_1 using the sample mean.

Answer

- The sample mean is

$$\bar{X}_n = \frac{X_1 + X_2 + \cdots + X_n}{n}.$$

- Linearity of expectation applies (even for dependent random var.!):

$$\begin{aligned}\mathbf{E}[\bar{X}_n] &= \frac{n \cdot \mathbf{E}[X_1]}{n} = \mathbf{E}[X_1] \\ &= \sum_{i=1}^N i \cdot \frac{1}{N} = \frac{N+1}{2}.\end{aligned}$$

First Estimator Based on Sample Mean

Example 1

Construct an **unbiased estimator** T_1 using the **sample mean**.

Answer

- The sample mean is

$$\bar{X}_n = \frac{X_1 + X_2 + \cdots + X_n}{n}.$$

- Linearity of expectation applies (even for **dependent** random var.!):

$$\begin{aligned}\mathbf{E}[\bar{X}_n] &= \frac{n \cdot \mathbf{E}[X_1]}{n} = \mathbf{E}[X_1] \\ &= \sum_{i=1}^N i \cdot \frac{1}{N} = \frac{N+1}{2}.\end{aligned}$$

- Thus we obtain an **unbiased estimator** by

$$T_1 := 2 \cdot \bar{X}_n - 1.$$

Example: Odd Behaviour of T_1

- Suppose $n = 5$

Example: Odd Behaviour of T_1

- Suppose $n = 5$
- Let the sample be

7, 3, 10, 46, 14

Example: Odd Behaviour of T_1

- Suppose $n = 5$
- Let the sample be

7, 3, 10, 46, 14

- The estimator returns:

$$T_1 = 2 \cdot \bar{X}_n - 1 =$$

Example: Odd Behaviour of T_1

- Suppose $n = 5$
- Let the sample be

7, 3, 10, 46, 14

- The estimator returns:

$$T_1 = 2 \cdot \bar{X}_n - 1 = 2 \cdot \frac{80}{5} - 1 =$$

Example: Odd Behaviour of T_1

- Suppose $n = 5$
- Let the sample be

7, 3, 10, 46, 14

- The estimator returns:

$$T_1 = 2 \cdot \bar{X}_n - 1 = 2 \cdot \frac{80}{5} - 1 = 31 \text{ ☹}$$

Example: Odd Behaviour of T_1

- Suppose $n = 5$
- Let the sample be

7, 3, 10, 46, 14

- The estimator returns:

$$T_1 = 2 \cdot \bar{X}_n - 1 = 2 \cdot \frac{80}{5} - 1 = 31 \text{ ☹}$$

This estimator will often unnecessarily **underestimate** the true value N .

Example: Odd Behaviour of T_1

- Suppose $n = 5$
- Let the sample be

7, 3, 10, 46, 14

- The estimator returns:

$$T_1 = 2 \cdot \bar{X}_n - 1 = 2 \cdot \frac{80}{5} - 1 = 31 \quad \text{☹}$$

This estimator will often unnecessarily **underestimate** the true value N .

Challenging exercise: Find a lower bound on $\mathbf{P} [T_1 < \max(X_1, X_2, \dots, X_n)]$

Example: Odd Behaviour of T_1

- Suppose $n = 5$
- Let the sample be

7, 3, 10, 46, 14

- The estimator returns:

$$T_1 = 2 \cdot \bar{X}_n - 1 = 2 \cdot \frac{80}{5} - 1 = 31 \quad \text{☹}$$

This estimator will often unnecessarily **underestimate** the true value N .

Challenging exercise: Find a lower bound on $\mathbf{P} [T_1 < \max(X_1, X_2, \dots, X_n)]$

- Achieving **unbiasedness** alone is not a good strategy
- **Improvement:** find an estimator which always returns a value at least $\max(X_1, X_2, \dots, X_n)$

Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$

Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55



Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the maximum?



Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the maximum?

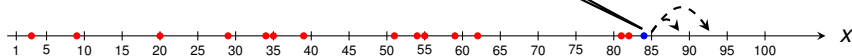


Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the maximum?

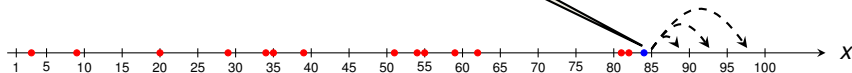


Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the maximum?

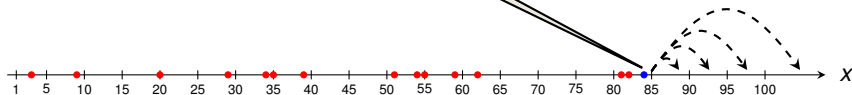


Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the maximum?

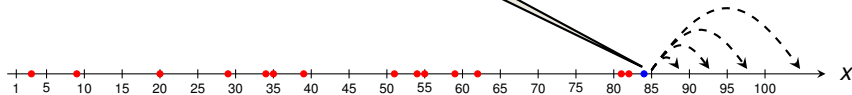


Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the **maximum**?



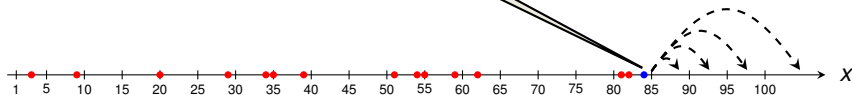
Rearrange the other 14 points equi-spaced between 0 and 84.

Intuition: Constructing an Estimator based on Maximum Sample

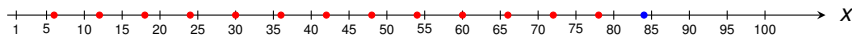
- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the **maximum**?



Rearrange the other 14 points equi-spaced between 0 and 84.

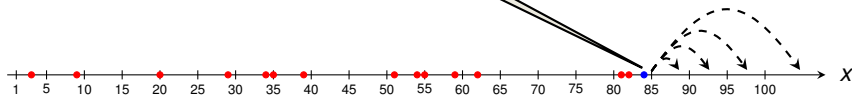


Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the maximum?



Rearrange the other 14 points equi-spaced between 0 and 84.

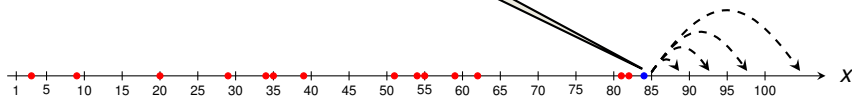


Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the **maximum**?



Rearrange the other 14 points equi-spaced between 0 and 84.



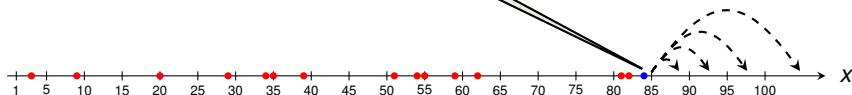
This suggests $84 + 6 = 90$ as the estimate!

Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the **maximum**?



Rearrange the other 14 points equi-spaced between 0 and 84.



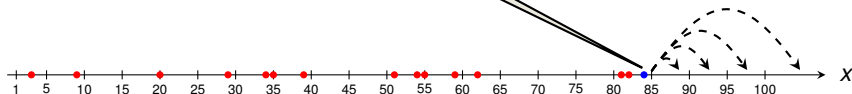
This suggests $84 + 6 = 90$ as the estimate!

Intuition: Constructing an Estimator based on Maximum Sample

- Suppose $n = 15$
- Our samples are:

9, 82, 39, 35, 20, 51, 54, 62, 81, 29, 84, 59, 3, 34, 55

How much should we add to the maximum?



Rearrange the other 14 points equi-spaced between 0 and 84.



$$\max(X_1, \dots, X_n) + \frac{\max(X_1, \dots, X_n)}{n-1}$$

This suggests $84 + 6 = 90$ as the estimate!

Deriving the Estimator Based on Maximum Sample

Example 2

Construct an unbiased estimator T_2 using $\max(X_1, \dots, X_n)$

Answer

Deriving the Estimator Based on Maximum Sample

Example 2

Construct an unbiased estimator T_2 using $\max(X_1, \dots, X_n)$

Answer

- Calculate expectation of the maximum (for details see Dekking et al.)

$$\mathbf{E} [\max(X_1, \dots, X_n)] =$$

Deriving the Estimator Based on Maximum Sample

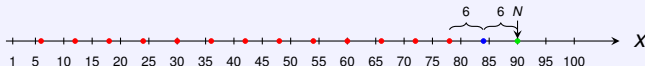
Example 2

Construct an unbiased estimator T_2 using $\max(X_1, \dots, X_n)$

Answer

- Calculate expectation of the maximum (for details see Dekking et al.)

$$\mathbf{E}[\max(X_1, \dots, X_n)] =$$



Deriving the Estimator Based on Maximum Sample

Example 2

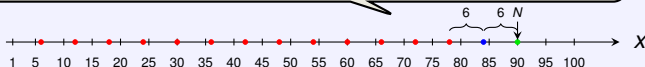
Construct an **unbiased estimator** T_2 using $\max(X_1, \dots, X_n)$

Answer

- Calculate expectation of the maximum (for details see Dekking et al.)

$$\mathbf{E}[\max(X_1, \dots, X_n)] =$$

Equi-spaced configuration would suggest $\max(X_1, \dots, X_n) \approx \frac{n-1}{n} \cdot N$



Deriving the Estimator Based on Maximum Sample

Example 2

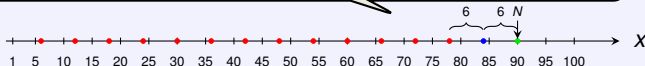
Construct an **unbiased estimator** T_2 using $\max(X_1, \dots, X_n)$

Answer

- Calculate expectation of the maximum (for details see Dekking et al.)

$$\mathbf{E}[\max(X_1, \dots, X_n)] = \dots = \frac{n}{n+1} \cdot N + \frac{n}{n+1} = \frac{n}{n+1} \cdot (N+1).$$

Equi-spaced configuration would suggest $\max(X_1, \dots, X_n) \approx \frac{n-1}{n} \cdot N$



Deriving the Estimator Based on Maximum Sample

Example 2

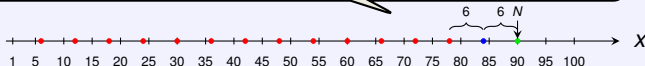
Construct an **unbiased estimator** T_2 using $\max(X_1, \dots, X_n)$

Answer

- Calculate expectation of the maximum (for details see Dekking et al.)

$$\mathbf{E}[\max(X_1, \dots, X_n)] = \dots = \frac{n}{n+1} \cdot N + \frac{n}{n+1} = \frac{n}{n+1} \cdot (N+1).$$

Equi-spaced configuration would suggest $\max(X_1, \dots, X_n) \approx \frac{n-1}{n} \cdot N$



- Hence we obtain an **unbiased estimator** by

$$T_2 := \frac{n+1}{n} \cdot \max(X_1, \dots, X_n) - 1.$$

Deriving the Estimator Based on Maximum Sample

Example 2

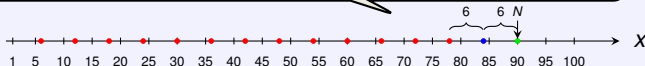
Construct an **unbiased estimator** T_2 using $\max(X_1, \dots, X_n)$

Answer

- Calculate expectation of the maximum (for details see Dekking et al.)

$$\mathbf{E}[\max(X_1, \dots, X_n)] = \dots = \frac{n}{n+1} \cdot N + \frac{n}{n+1} = \frac{n}{n+1} \cdot (N+1).$$

Equi-spaced configuration would suggest $\max(X_1, \dots, X_n) \approx \frac{n-1}{n} \cdot N$

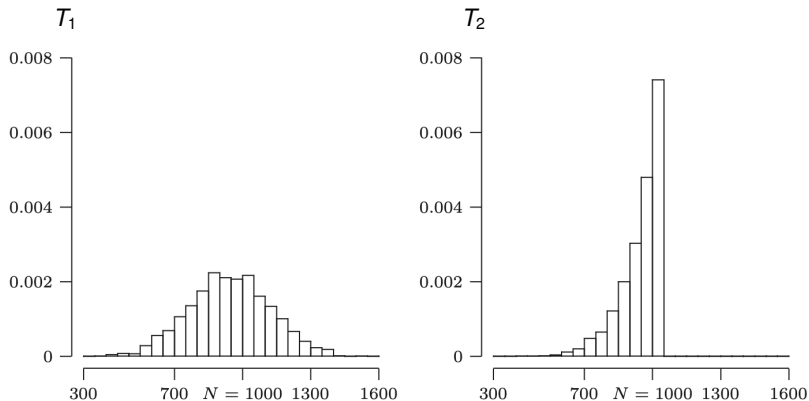


- Hence we obtain an **unbiased estimator** by

$$T_2 := \frac{n+1}{n} \cdot \max(X_1, \dots, X_n) - 1.$$

- For our samples before, we get $t_2 = \frac{16}{15} \cdot 84 - 1 = 88.6$.

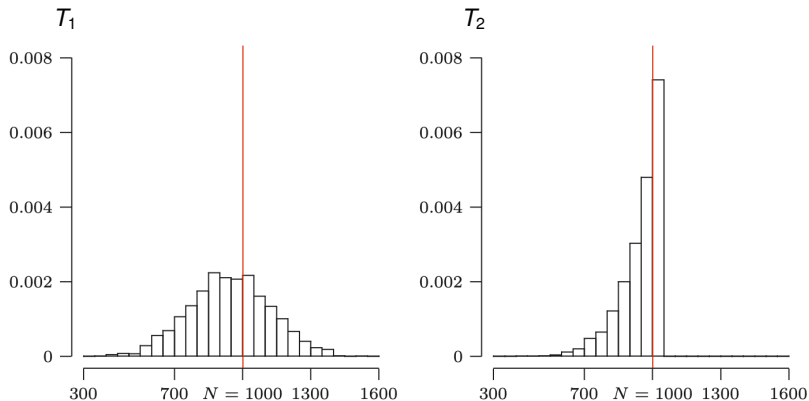
Empirical Analysis of the two Estimators



Source: Modern Introduction to Statistics

Figure: Histogram of 2000 values for T_1 and T_2 , when $N = 1000$ and $n = 10$.

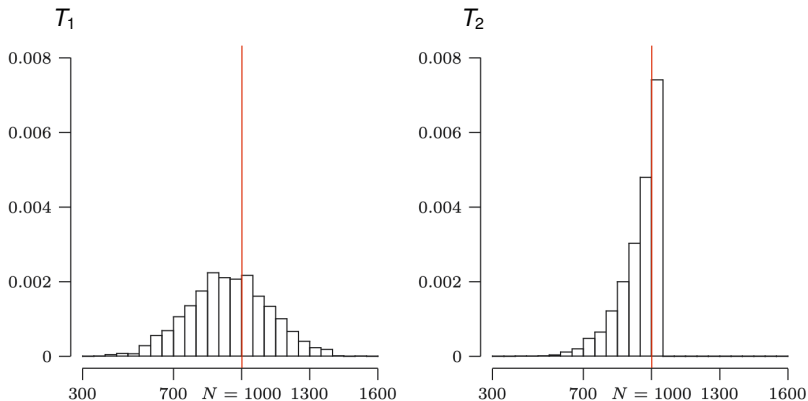
Empirical Analysis of the two Estimators



Source: Modern Introduction to Statistics

Figure: Histogram of 2000 values for T_1 and T_2 , when $N = 1000$ and $n = 10$.

Empirical Analysis of the two Estimators



Source: Modern Introduction to Statistics

Figure: Histogram of 2000 values for T_1 and T_2 , when $N = 1000$ and $n = 10$.

Can we find a quantity that captures the superiority of T_2 over T_1 ?

Estimating Population Size (First Model)

Mean Squared Error

Estimating Population Size (Second Model)

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The mean squared error of T is

$$\mathbf{MSE} [T] = \mathbf{E} \left[(T - \theta)^2 \right].$$

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The **mean squared error** of T is

$$\mathbf{MSE} [T] = \mathbf{E} \left[(T - \theta)^2 \right].$$

- According to this, estimator T_1 **better** than T_2 if $\mathbf{MSE} [T_1] < \mathbf{MSE} [T_2]$.

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The **mean squared error** of T is

$$\mathbf{MSE} [T] = \mathbf{E} \left[(T - \theta)^2 \right].$$

- According to this, estimator T_1 **better** than T_2 if $\mathbf{MSE} [T_1] < \mathbf{MSE} [T_2]$.

Bias-Variance Decomposition

The **mean squared error** can be decomposed into:

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The **mean squared error** of T is

$$\mathbf{MSE} [T] = \mathbf{E} \left[(T - \theta)^2 \right].$$

- According to this, estimator T_1 **better** than T_2 if $\mathbf{MSE} [T_1] < \mathbf{MSE} [T_2]$.

Bias-Variance Decomposition

The **mean squared error** can be decomposed into:

$$\mathbf{MSE} [T] = (\mathbf{E} [T] - \theta)^2 + \mathbf{V} [T]$$

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The **mean squared error** of T is

$$\mathbf{MSE} [T] = \mathbf{E} [(T - \theta)^2].$$

- According to this, estimator T_1 **better** than T_2 if $\mathbf{MSE} [T_1] < \mathbf{MSE} [T_2]$.

Bias-Variance Decomposition

The **mean squared error** can be decomposed into:

$$\mathbf{MSE} [T] = \underbrace{(\mathbf{E} [T] - \theta)^2}_{= \text{Bias}^2} + \mathbf{V} [T]$$

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The **mean squared error** of T is

$$\mathbf{MSE} [T] = \mathbf{E} \left[(T - \theta)^2 \right].$$

- According to this, estimator T_1 **better** than T_2 if $\mathbf{MSE} [T_1] < \mathbf{MSE} [T_2]$.

Bias-Variance Decomposition

The **mean squared error** can be decomposed into:

$$\mathbf{MSE} [T] = \underbrace{(\mathbf{E} [T] - \theta)^2}_{= \text{Bias}^2} + \underbrace{\mathbf{V} [T]}_{= \text{Variance}}$$

Mean Squared Error

Mean Squared Error Definition

Let T be an estimator for a parameter θ . The **mean squared error** of T is

$$\mathbf{MSE} [T] = \mathbf{E} [(T - \theta)^2].$$

- According to this, estimator T_1 **better** than T_2 if $\mathbf{MSE} [T_1] < \mathbf{MSE} [T_2]$.

Bias-Variance Decomposition

The **mean squared error** can be decomposed into:

$$\mathbf{MSE} [T] = \underbrace{(\mathbf{E} [T] - \theta)^2}_{= \text{Bias}^2} + \underbrace{\mathbf{V} [T]}_{= \text{Variance}}$$

- If T_1 and T_2 are both **unbiased**, T_1 is **better** than T_2 iff $\mathbf{V} [T_1] < \mathbf{V} [T_2]$.

Bias-Variance Decomposition: Derivation

Example 3

We need to prove: $\mathbf{MSE}[T] = (\mathbf{E}[T] - \theta)^2 + \mathbf{V}[T]$.

Answer

Bias-Variance Decomposition: Derivation

Example 3

We need to prove: $\mathbf{MSE} [T] = (\mathbf{E} [T] - \theta)^2 + \mathbf{V} [T]$.

Answer

$$\mathbf{MSE} [T] = \mathbf{E} [(T - \theta)^2]$$

Example 3

We need to prove: $\mathbf{MSE} [T] = (\mathbf{E} [T] - \theta)^2 + \mathbf{V} [T]$.

Answer

$$\begin{aligned}\mathbf{MSE} [T] &= \mathbf{E} [(T - \theta)^2] \\ &= \mathbf{E} [T^2 - 2T\theta + \theta^2]\end{aligned}$$

Example 3

We need to prove: $\mathbf{MSE}[T] = (\mathbf{E}[T] - \theta)^2 + \mathbf{V}[T]$.

Answer

$$\begin{aligned}\mathbf{MSE}[T] &= \mathbf{E}[(T - \theta)^2] \\ &= \mathbf{E}[T^2 - 2T\theta + \theta^2] \\ &= \mathbf{E}[T]^2 - 2 \cdot \mathbf{E}[T] \cdot \theta + \theta^2 + \mathbf{E}[T^2] - \mathbf{E}[T]^2\end{aligned}$$

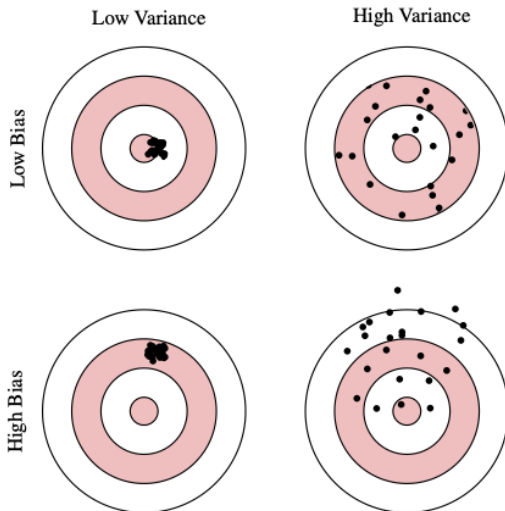
Example 3

We need to prove: $\mathbf{MSE}[T] = (\mathbf{E}[T] - \theta)^2 + \mathbf{V}[T]$.

Answer

$$\begin{aligned}\mathbf{MSE}[T] &= \mathbf{E}[(T - \theta)^2] \\ &= \mathbf{E}[T^2 - 2T\theta + \theta^2] \\ &= \mathbf{E}[T]^2 - 2 \cdot \mathbf{E}[T] \cdot \theta + \theta^2 + \mathbf{E}[T^2] - \mathbf{E}[T]^2 \\ &= (\mathbf{E}[T] - \theta)^2 + \mathbf{V}[T].\end{aligned}$$

Bias-Variance Decomposition: Illustration



Source: Edwin Leuven (Point Estimation)

Example 4

It holds that **MSE** [T_1] = $\Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

Example 4

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

Example 4

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

$$\mathbf{V} [T_1] = \mathbf{V} [2 \cdot \bar{X}_n - 1] = 4 \cdot \mathbf{V} [\bar{X}_n] = \frac{4}{n^2} \cdot \mathbf{V} [X_1 + \dots + X_n]$$

Example 4

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

$$\mathbf{V} [T_1] = \mathbf{V} [2 \cdot \bar{X}_n - 1] = 4 \cdot \mathbf{V} [\bar{X}_n] = \frac{4}{n^2} \cdot \mathbf{V} [X_1 + \dots + X_n]$$

- Note:** The X_i 's are **not independent**!

Example 4

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

$$\mathbf{V} [T_1] = \mathbf{V} [2 \cdot \bar{X}_n - 1] = 4 \cdot \mathbf{V} [\bar{X}_n] = \frac{4}{n^2} \cdot \mathbf{V} [X_1 + \dots + X_n]$$

- Note:** The X_i 's are **not independent**!
- Use generalisation of $\mathbf{V} [X_1 + X_2] = \mathbf{V} [X_1] + \mathbf{V} [X_2] + 2 \cdot \mathbf{Cov} [X_1, X_2]$ (Exercise Sheet) to n r.v.'s, and then that the X_i 's are **identically distributed**, and also the (X_i, X_j) , $i \neq j$:

Example 4

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

$$\mathbf{V} [T_1] = \mathbf{V} [2 \cdot \bar{X}_n - 1] = 4 \cdot \mathbf{V} [\bar{X}_n] = \frac{4}{n^2} \cdot \mathbf{V} [X_1 + \dots + X_n]$$

- Note:** The X_i 's are **not independent**!
- Use generalisation of $\mathbf{V} [X_1 + X_2] = \mathbf{V} [X_1] + \mathbf{V} [X_2] + 2 \cdot \mathbf{Cov} [X_1, X_2]$ (Exercise Sheet) to n r.v.'s, and then that the X_i 's are **identically distributed**, and also the (X_i, X_j) , $i \neq j$:

$$\begin{aligned} \mathbf{V} [X_1 + \dots + X_n] &= \sum_{i=1}^n \mathbf{V} [X_i] + 2 \sum_{i=1}^n \sum_{j=i+1}^n \mathbf{Cov} [X_i, X_j] \\ &= n \cdot \mathbf{V} [X_1] + 2 \binom{n}{2} \cdot \mathbf{Cov} [X_1, X_2]. \end{aligned}$$

Example 4

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

$$\mathbf{V} [T_1] = \mathbf{V} [2 \cdot \bar{X}_n - 1] = 4 \cdot \mathbf{V} [\bar{X}_n] = \frac{4}{n^2} \cdot \mathbf{V} [X_1 + \dots + X_n]$$

- Note:** The X_i 's are **not independent**!
- Use generalisation of $\mathbf{V} [X_1 + X_2] = \mathbf{V} [X_1] + \mathbf{V} [X_2] + 2 \cdot \mathbf{Cov} [X_1, X_2]$ (Exercise Sheet) to n r.v.'s, and then that the X_i 's are **identically distributed**, and also the (X_i, X_j) , $i \neq j$:

$$\begin{aligned} \mathbf{V} [X_1 + \dots + X_n] &= \sum_{i=1}^n \mathbf{V} [X_i] + 2 \sum_{i=1}^n \sum_{j=i+1}^n \mathbf{Cov} [X_i, X_j] \\ &= n \cdot \mathbf{V} [X_1] + 2 \binom{n}{2} \cdot \mathbf{Cov} [X_1, X_2]. \end{aligned}$$

- By definition of the discrete uniform distribution, $\mathbf{V} [X_1] = \frac{(N+1)(N-1)}{12}$

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

$$\mathbf{V} [T_1] = \mathbf{V} [2 \cdot \bar{X}_n - 1] = 4 \cdot \mathbf{V} [\bar{X}_n] = \frac{4}{n^2} \cdot \mathbf{V} [X_1 + \dots + X_n]$$

- Note:** The X_i 's are **not independent**!
- Use generalisation of $\mathbf{V} [X_1 + X_2] = \mathbf{V} [X_1] + \mathbf{V} [X_2] + 2 \cdot \mathbf{Cov} [X_1, X_2]$ (Exercise Sheet) to n r.v.'s, and then that the X_i 's are **identically distributed**, and also the (X_i, X_j) , $i \neq j$:

$$\begin{aligned} \mathbf{V} [X_1 + \dots + X_n] &= \sum_{i=1}^n \mathbf{V} [X_i] + 2 \sum_{i=1}^n \sum_{j=i+1}^n \mathbf{Cov} [X_i, X_j] \\ &= n \cdot \mathbf{V} [X_1] + 2 \binom{n}{2} \cdot \mathbf{Cov} [X_1, X_2]. \end{aligned}$$

- By definition of the discrete uniform distribution, $\mathbf{V} [X_1] = \frac{(N+1)(N-1)}{12}$
- Intuitively, X_1 and X_2 are negatively correlated, which would be sufficient to complete the proof. For a more rigorous and precise derivation (see Dekking et al.):

$$\mathbf{Cov} [X_1, X_2] = -\frac{1}{12} (N+1).$$

Example 4

It holds that $\mathbf{MSE} [T_1] = \Theta \left(\frac{N^2}{n} \right)$, where $T_1 = 2 \cdot \bar{X}_n - 1$.

Answer

- Since T_1 is unbiased, $\mathbf{MSE} [T_1] = (\mathbf{E} [T_1] - \theta)^2 + \mathbf{V} [T_1] = \mathbf{V} [T_1]$, and

$$\mathbf{V} [T_1] = \mathbf{V} [2 \cdot \bar{X}_n - 1] = 4 \cdot \mathbf{V} [\bar{X}_n] = \frac{4}{n^2} \cdot \mathbf{V} [X_1 + \dots + X_n]$$

- Note:** The X_i 's are **not independent**!
- Use generalisation of $\mathbf{V} [X_1 + X_2] = \mathbf{V} [X_1] + \mathbf{V} [X_2] + 2 \cdot \mathbf{Cov} [X_1, X_2]$ (Exercise Sheet) to n r.v.'s, and then that the X_i 's are **identically distributed**, and also the (X_i, X_j) , $i \neq j$:

$$\begin{aligned} \mathbf{V} [X_1 + \dots + X_n] &= \sum_{i=1}^n \mathbf{V} [X_i] + 2 \sum_{i=1}^n \sum_{j=i+1}^n \mathbf{Cov} [X_i, X_j] \\ &= n \cdot \mathbf{V} [X_1] + 2 \binom{n}{2} \cdot \mathbf{Cov} [X_1, X_2]. \end{aligned}$$

- By definition of the discrete uniform distribution, $\mathbf{V} [X_1] = \frac{(N+1)(N-1)}{12}$
- Intuitively, X_1 and X_2 are negatively correlated, which would be sufficient to complete the proof. For a more rigorous and precise derivation (see Dekking et al.):

$$\mathbf{Cov} [X_1, X_2] = -\frac{1}{12} (N+1).$$

- Rearranging and simplifying gives

$$\mathbf{V} [T_1] = \frac{(N+1)(N-n)}{3n}.$$

Analysis of the MSE for T_2 (non-examinable)

Example 5

It holds that $\mathbf{MSE} [T_2] = \Theta \left(\frac{N^2}{n^2} \right)$, where $T_2 = \frac{n+1}{n} \cdot \max(X_1, \dots, X_n) - 1$.

Answer

Analysis of the MSE for T_2 (non-examinable)

Example 5

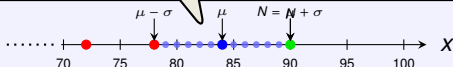
It holds that $\mathbf{MSE}[T_2] = \Theta\left(\frac{N^2}{n^2}\right)$, where $T_2 = \frac{n+1}{n} \cdot \max(X_1, \dots, X_n) - 1$.

Answer

- T_2 is unbiased \Rightarrow need $\mathbf{V}[T_2]$ which reduces to $\mathbf{V}[\max(X_1, \dots, X_n)]$
- One can prove: For details see Dekking et al.

$$\mathbf{V}[\max(X_1, \dots, X_n)] = \dots = \frac{n(N+1)(N-n)}{(n+2)(n+1)^2} = \Theta\left(\frac{N^2}{n^2}\right)$$

Equi-spaced (idealised) configuration suggests a standard deviation of $\sigma \approx \frac{N}{n}$



Maximum could have equally likely taken any value between 79 and 90

Analysis of the MSE for T_2 (non-examinable)

Example 5

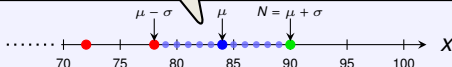
It holds that $\mathbf{MSE}[T_2] = \Theta\left(\frac{N^2}{n^2}\right)$, where $T_2 = \frac{n+1}{n} \cdot \max(X_1, \dots, X_n) - 1$.

Answer

- T_2 is unbiased \Rightarrow need $\mathbf{V}[T_2]$ which reduces to $\mathbf{V}[\max(X_1, \dots, X_n)]$
- One can prove: For details see Dekking et al.

$$\mathbf{V}[\max(X_1, \dots, X_n)] = \dots = \frac{n(N+1)(N-n)}{(n+2)(n+1)^2} = \Theta\left(\frac{N^2}{n^2}\right)$$

Equi-spaced (idealised) configuration suggests a standard deviation of $\sigma \approx \frac{N}{n}$



Maximum could have equally likely taken any value between 79 and 90

- $\mathbf{MSE}[T_2]$ is much lower than $\mathbf{MSE}[T_1] = \Theta\left(\frac{N^2}{n}\right)$, i.e., $\frac{\mathbf{MSE}[T_1]}{\mathbf{MSE}[T_2]} = \frac{n+2}{3}$
- \Rightarrow confirms **simulations** suggesting that T_2 is better than T_1 !
- can be shown T_2 is the **best unbiased estimator**, i.e., it minimises MSE.

Estimating Population Size (First Model)

Mean Squared Error

Estimating Population Size (Second Model)

A New Estimation Problem

— Previous Model —

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- **Goal:** Find estimator for N

A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- **Goal:** Find estimator for N

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S with replacement
- **Goal:** Find estimator for N

A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- Goal:** Find estimator for N

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S with replacement
- Goal:** Find estimator for N

- Suppose $n = 6$, $N = 11$, $S = \{3, 4, 7, 8, 10, 15.83356, 20, 21, 56, 81, 10000\}$

A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- Goal:** Find estimator for N

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S with replacement
- Goal:** Find estimator for N

- Suppose $n = 6$, $N = 11$, $S = \{3, 4, 7, 8, 10, 15.83356, 20, 21, 56, 81, 10000\}$
- Let the sample be

10, 81, 20, 3, 81, 10000

A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- Goal:** Find estimator for N

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S with replacement
- Goal:** Find estimator for N

- Suppose $n = 6$, $N = 11$, $S = \{3, 4, 7, 8, 10, 15.83356, 20, 21, 56, 81, 10000\}$
- Let the sample be

10, **81**, 20, 3, **81**, 10000

A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- Goal:** Find estimator for N

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S with replacement
- Goal:** Find estimator for N

- Suppose $n = 6$, $N = 11$, $S = \{3, 4, 7, 8, 10, 15.83356, 20, 21, 56, 81, 10000\}$
- Let the sample be

10, **81**, 20, 3, **81**, 10000

As we do not know S , our only clue are elements that **were sampled twice**.

A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- Goal:** Find estimator for N

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S with replacement
- Goal:** Find estimator for N

- Suppose $n = 6$, $N = 11$, $S = \{3, 4, 7, 8, 10, 15.83356, 20, 21, 56, 81, 10000\}$
- Let the sample be

10, **81**, 20, 3, **81**, 10000

Let us call this a **collision**

As we do not know S , our only clue are elements that **were sampled twice**.

A New Estimation Problem

Previous Model

- Population/ID space $S = \{1, 2, \dots, N\}$
- We take **uniform** samples from S without replacement
- Goal:** Find estimator for N

Similar idea applies to situations where elements are not labelled before we see them first time (**Mark & Recapture Method**)

New Model

- Population/ID space of size $|S| = N$
- We take **uniform** samples from S with replacement
- Goal:** Find estimator for N

- Suppose $n = 6$, $N = 11$, $S = \{3, 4, 7, 8, 10, 15.83356, 20, 21, 56, 81, 10000\}$
- Let the sample be

10, **81**, 20, 3, **81**, 10000

Let us call this a **collision**

As we do not know S , our only clue are elements that **were sampled twice**.

Birthday Problem

Birthday Problem: Given a set of k people

Birthday Problem

Birthday Problem: Given a set of k people

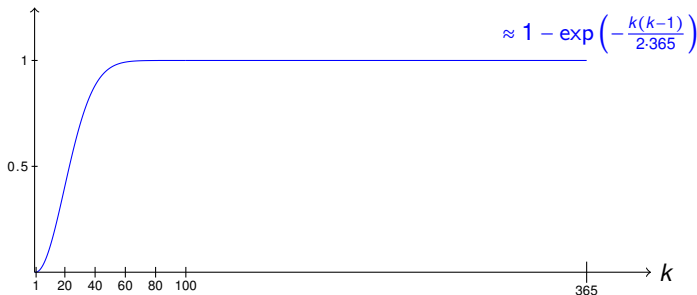
- What is the **probability** of having two with the same birthday (i.e., having at least one collision)?

Birthday Problem

Birthday Problem: Given a set of k people

- What is the **probability** of having two with the same birthday (i.e., having at least one collision)?

$P[\text{collision}]$

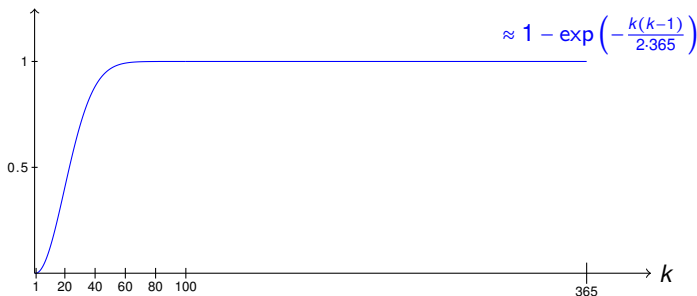


Birthday Problem

Birthday Problem: Given a set of k people

- What is the **probability** of having two with the same birthday (i.e., having at least one collision)?
- What is the **expected number** of people one needs to ask until the first collision occurs?

$P[\text{collision}]$

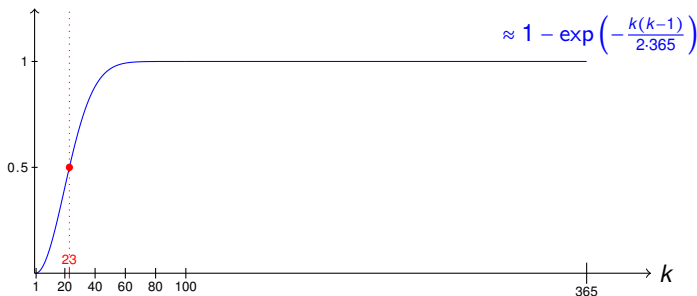


Birthday Problem

Birthday Problem: Given a set of k people

- What is the **probability** of having two with the same birthday (i.e., having at least one collision)?
- What is the **expected number** of people one needs to ask until the first collision occurs?

$P[\text{collision}]$

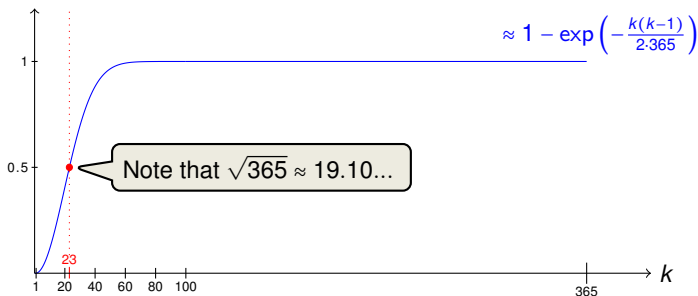


Birthday Problem

Birthday Problem: Given a set of k people

- What is the **probability** of having two with the same birthday (i.e., having at least one collision)?
- What is the **expected number** of people one needs to ask until the first collision occurs?

$P[\text{collision}]$



Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

FIND-FIRST-COLLISION(S)

- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
- 5: **else return** $T(i)$
- 6: **End For**

Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

FIND-FIRST-COLLISION(S)

- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
- 5: **else return** $T(i)$
- 6: **End For**

$T(i)$ will be the value of the estimator if algo returns after i rounds. (We want T **unbiased**)

Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

FIND-FIRST-COLLISION(S)

- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
- 5: **else return** $T(i)$
- 6: **End For**

$T(i)$ will be the value of the estimator if algo returns after i rounds. (We want T **unbiased**)

- **Running Time:** The expected time until the algorithm stops is:

Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

FIND-FIRST-COLLISION(S)

- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
- 5: **else return** $T(i)$
- 6: **End For**

$T(i)$ will be the value of the estimator if algo returns after i rounds. (We want T **unbiased**)

- **Running Time:** The expected time until the algorithm stops is:
= the expected number of samples until a **collision**...

Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

FIND-FIRST-COLLISION(S)

- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
- 5: **else return** $T(i)$
- 6: **End For**

$T(i)$ will be the value of the estimator if algo returns after i rounds. (We want T **unbiased**)

- **Running Time:** The expected time until the algorithm stops is:
= the expected number of samples until a **collision**...

Same as the birthday problem, but now with $|S| = N$ days... 😊

Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

FIND-FIRST-COLLISION(S)

- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
- 5: **else return** $T(i)$
- 6: **End For**

$T(i)$ will be the value of the estimator if algo returns after i rounds. (We want T **unbiased**)

- **Running Time:** The expected time until the algorithm stops is:
= the expected number of samples until a **collision**...

Same as the birthday problem, but now with $|S| = N$ days... ☺

Expected Running Time (Knuth, Ramanujan)

$$\sqrt{\frac{\pi N}{2}} - \frac{1}{3} + O\left(\frac{1}{\sqrt{N}}\right).$$

Estimation via Collision: The Algorithm

Recall: As we do not know S , our only information are **collisions**.

FIND-FIRST-COLLISION(S)

- 1: $C = \emptyset$
- 2: **For** $i = 1, 2, \dots$
- 3: Take next i.i.d. sample X_i from S
- 4: **If** $X_i \notin C$ **then** $C \leftarrow C \cup \{X_i\}$
- 5: **else return** $T(i)$
- 6: **End For**

$T(i)$ will be the value of the estimator if algo returns after i rounds. (We want T **unbiased**)

- **Running Time:** The expected time until the algorithm stops is:
= the expected number of samples until a **collision**...

Same as the birthday problem, but now with $|S| = N$ days... ☺

Expected Running Time (Knuth, Ramanujan)

$$\sqrt{\frac{\pi N}{2}} - \frac{1}{3} + O\left(\frac{1}{\sqrt{N}}\right).$$

Exercise: Prove a bound of $\leq 2 \cdot \sqrt{N}$

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$.

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2)$$

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

- **Case $|S| = 2$** : Algo stops after 2 or 3 rounds (w.p. 1/2 each).

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$.
We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

- **Case $|S| = 2$** : Algo stops after 2 or 3 rounds (w.p. 1/2 each).
We want

$$2 = \mathbf{E}[T] = \frac{1}{2} \cdot T(2) + \frac{1}{2} \cdot T(3)$$

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

- **Case $|S| = 2$** : Algo stops after 2 or 3 rounds (w.p. 1/2 each). We want

$$2 = \mathbf{E}[T] = \frac{1}{2} \cdot T(2) + \frac{1}{2} \cdot T(3) \quad \Rightarrow \quad T(3) = 3.$$

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$:** Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

- **Case $|S| = 2$:** Algo stops after 2 or 3 rounds (w.p. 1/2 each). We want

$$2 = \mathbf{E}[T] = \frac{1}{2} \cdot T(2) + \frac{1}{2} \cdot T(3) \quad \Rightarrow \quad T(3) = 3.$$

- **Case $|S| = 3$:** gives $3 = \mathbf{E}[T] = \frac{1}{3} \cdot T(2) + \frac{4}{9} \cdot T(3) + \frac{2}{9} \cdot T(4)$

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

- **Case $|S| = 2$** : Algo stops after 2 or 3 rounds (w.p. 1/2 each). We want

$$2 = \mathbf{E}[T] = \frac{1}{2} \cdot T(2) + \frac{1}{2} \cdot T(3) \quad \Rightarrow \quad T(3) = 3.$$

- **Case $|S| = 3$** : gives $3 = \mathbf{E}[T] = \frac{1}{3} \cdot T(2) + \frac{4}{9} \cdot T(3) + \frac{2}{9} \cdot T(4) \Rightarrow T(4) = 6$, similarly, $T(5) = 10$ etc.

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

- **Case $|S| = 2$** : Algo stops after 2 or 3 rounds (w.p. 1/2 each). We want

$$2 = \mathbf{E}[T] = \frac{1}{2} \cdot T(2) + \frac{1}{2} \cdot T(3) \quad \Rightarrow \quad T(3) = 3.$$

- **Case $|S| = 3$** : gives $3 = \mathbf{E}[T] = \frac{1}{3} \cdot T(2) + \frac{4}{9} \cdot T(3) + \frac{2}{9} \cdot T(4)$
 $\Rightarrow T(4) = 6$, similarly, $T(5) = 10$ etc.
- can continue to define $T(i)$ inductively in this way (note T is **unique**)

Estimation via Collision: Getting the Estimator Unbiased

Example 6

One can define $T(i)$, $i \in \mathbb{N}$, such that $\mathbf{E}[T] = |S|$ for any finite, non-empty set S .

Answer

- We outline a construction **by induction**.
- **Case $|S| = 1$** : Algo always stops after $i = 2$ rounds and returns $T(2)$. We want

$$1 = \mathbf{E}[T] = T(2) \quad \Rightarrow \quad T(2) = 1.$$

- **Case $|S| = 2$** : Algo stops after 2 or 3 rounds (w.p. 1/2 each). We want

$$2 = \mathbf{E}[T] = \frac{1}{2} \cdot T(2) + \frac{1}{2} \cdot T(3) \quad \Rightarrow \quad T(3) = 3.$$

- **Case $|S| = 3$** : gives $3 = \mathbf{E}[T] = \frac{1}{3} \cdot T(2) + \frac{4}{9} \cdot T(3) + \frac{2}{9} \cdot T(4)$
 $\Rightarrow T(4) = 6$, similarly, $T(5) = 10$ etc.
- can continue to define $T(i)$ inductively in this way (note T is **unique**)
(a proof that $T(i) = \binom{i}{2}$ is harder)