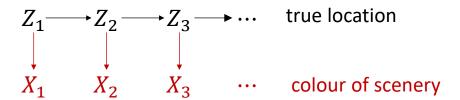
Challenge.

Our friend Data Stoat has gone missing!

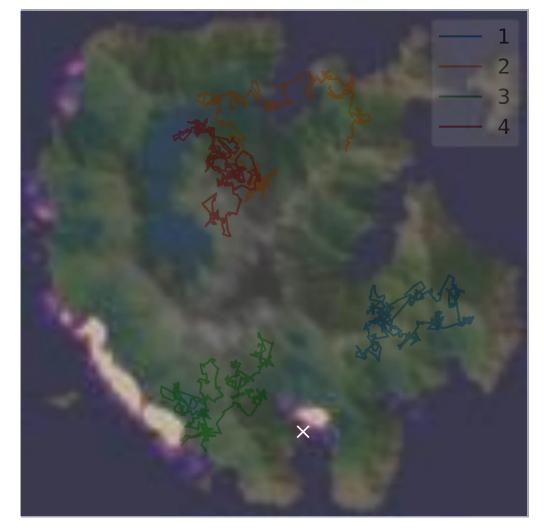
The GPS sensor that they normally carry has stopped working. But they still have a low-res camera with mobile uplink, so we know what sort of scenery they're in.

Can you help find Data Stoat?

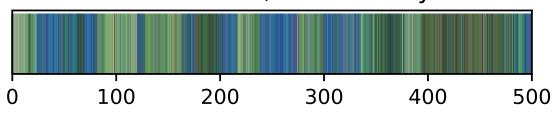


- Use data from animals 1–4 (for which we know both z and x) to learn the probability model.
- Use computational Bayes to find the distribution of \underline{Z} given X = x, and submit your answer as a heatmap.
- Your score will be the probability you assign to Data Stoat's actual location.

Animals 1--4, GPS tracks



Animal id=0, camera only



§11.3 – §11.6 Behaviour of Markov chains

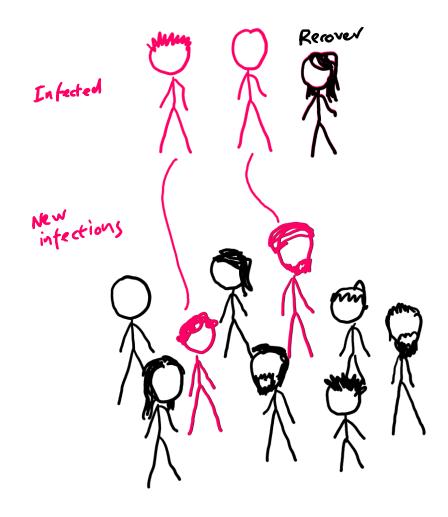
Example 11.1.2: epidemic model

Let $X_n \in \mathbb{N}$ be the number of infected people on day n, and let it evolve according to

$$X_{n+1} = X_n - \text{Recoveries}_n + \text{Infections}_n$$

(We'll let the distributions of Recoveries_n and Infections_n depend only on X_n , making this a Markov model.)

Day 21: ##infracted =33+2-1=4



Example 11.1.2: epidemic model

Let $X_n \in \mathbb{N}$ be the number of infected people on day n, and let it evolve according to

$$X_{n+1} = X_n - \text{Recoveries}_n + \text{Infections}_n$$

(We'll let the distributions of Recoveries_n and Infections_n depend only on X_n , making this a Markov model.)

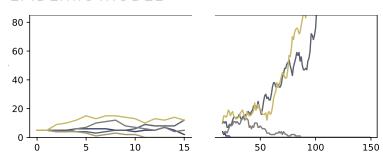
Example 11.1.3 (active users)

Let $X_n \in \mathbb{N}$ be the number of users currently using an online platform at timestep n, and let it evolve according to

$$X_{n+1} = X_n + \text{Newusers}_n - \text{Departures}_n$$

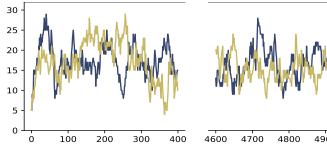
(We'll let the distributions of Newusers_n and Departures_n depend only on X_n , making this a Markov model.)

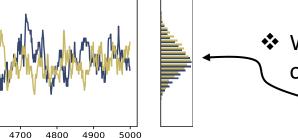
EPIDEMIC MODEL



- How likely is it that the epidemic dies out? §11.3 "Hitting probabilities" (* non-examinable)
- If it doesn't die out, what's the growth rate? §11.6 "Drift models" (* non-examinable)

ACTIVE USERS MODEL

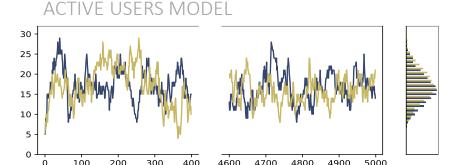




What's the average number
 of active users?
 How can we learn this
 distribution? §11.4, 11.5 "Stationarity"

Needed for Part II Machine Learning & Bayesian Inference

How can we tell which of these two behaviours we'll see? §11.4.2 "Existence and uniqueness" (* non-examinable)



It looks like this distribution is **stable**

i.e. unchanging over time

$$X_i \sim \pi$$
 means: $\mathbb{P}(X_i = x) = \pi_x$ for all x in the state space

Can we find a stable probability distribution π , i.e. a distribution such that $X_0 \sim \pi \Rightarrow X_1 \sim \pi$? (If so, and if $X_0 \sim \pi$, then $X_i \sim \pi$ for all i > 0. We then say the chain is *stationary*.)

A distribution π over the state space is called a *stationary distribution* or equilibrium distribution if

$$X_0 \sim \pi \implies X_1 \sim \pi$$

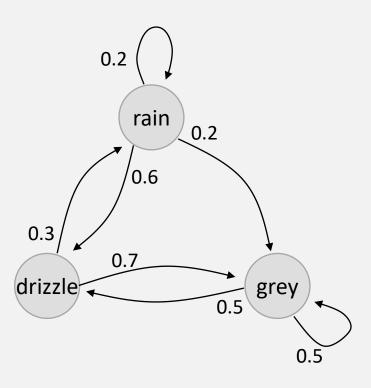
by time spent in state &

§11.5. What does stationarity have to do with the histogram above, which shows time-averages? If $X_i \sim \pi$ for all i, then the time-averages are given by π , because

$$\mathbb{E}\left(\frac{1}{n}\sum_{i=1}^{n} 1_{X_i = x}\right) = \frac{1}{n}\sum_{i} \mathbb{E}(1_{X_i = x}) = \frac{1}{n}\sum_{i} \mathbb{P}(X_i = x) = \frac{1}{n}\sum_{i} \pi_x = \pi_x$$

Example 11.4.1 (Stationary distribution)

Find the stationary distribution of Cambridge weather.



let's suppose that a stationary dist. exists, call i'v IT.

Suppose Xo N IT.

Then XINIT by definition of stationarily.

But also

$$P(X_1 = x) = \sum_{y} P(X_1 = x \mid X_0 = y) P(X_0 = y) by (aTP)$$

$$P(X_1 = x \mid X_0 = y) P(X_0 = y) by (aTP)$$

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$$P(X_1 = x \mid X_0 = y) P(X_1 = x \mid X_0 = y) P(X_0 = y) P(X_$$

x = rain: $\Pi_{rain} = 0.2 \Pi_{rain} + 0.3 \Pi_{drizzle}$ x = drizzle: $\Pi_{drizzle} = 0.6 \Pi_{rain} + 0.5 \Pi_{grey}$

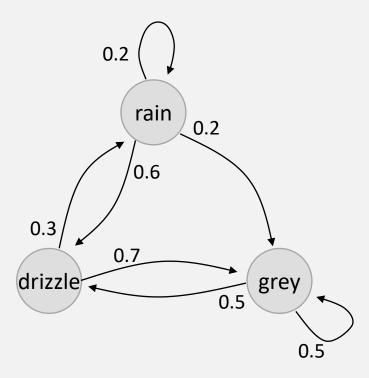
x = grey: Tigrey = 0.2 Train +0.7 Trainzle + 0.5 Tigrey

Also: Mrain + Marizzle > Myrey = 1. because we've assumed si is a disc.

Can solve for IT.

Example 11.4.1 (Stationary distribution)

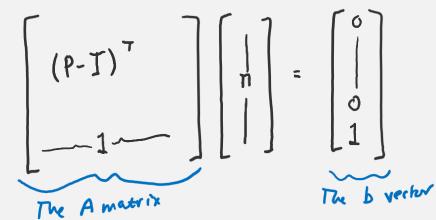
Find the stationary distribution of Cambridge weather.



In matrix notation,

$$\pi = \pi P$$
 or equivalently $(P - I)^{\mathsf{T}} \pi = 0$
 $\pi \cdot 1 = 1$

Or, putting these two together, $A\pi = b$



```
# let states be rain=0, drizzle=1, grey=2
P = np.array([[.2,.6,.2], [.3,0,.7], [0,.5,.5]])
A = np.concatenate([(P-numpy.eye(3)).T, [[1,1,1]]])
```

- $\pi = \text{np.linalg.lstsq(A, [0,0,0,1])[0]}$
- np.linalg.lstsq(A,b) seeks $\min_{x} |Ax b|^2$. If Ax = b can be solved, it will find a solution. It doesn't care about redundant equations.
- np.linalg.solve(A,b) solves Ax = b. It requires an exact system of equations, i.e. A square with no redundant equations.

Stationarity equations

If π is a stationary distribution, then it solves

$$\pi = \pi P$$
, $\pi \cdot 1 = 1$

Conversely, if π is a distribution that solves $\pi = \pi P$ then π is a stationary distribution.

But does this help us to find a stationary distribution? Can these equations even be solved?

- ❖ What if there's no solution?
- What if there are multiple solutions?

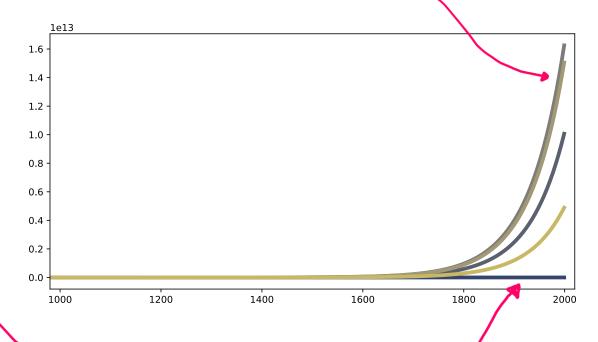
§11.4.2 "Existence and uniqueness" (* non-examinable)

Existence and uniqueness

Suppose (1) the state space is finite, and (2) the state space is *irreducible* i.e. there's a path from any state to any other

Then there is a unique stationary distribution, and it specifies the long-run time-average distribution.

If the state space is infinite, the Markov chain might 'explode'



If there are 'absorbing' states, the Markov chain might get stuck

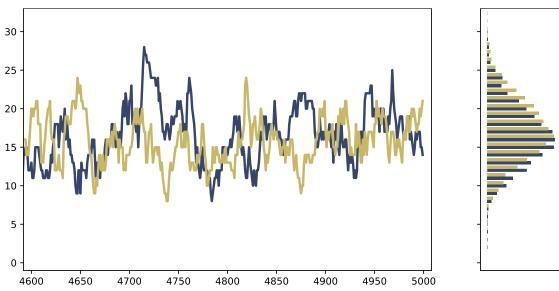
This epidemic model *does* have a unique stationary distribution (namely the "stuck at zero" distribution), but the epidemic may nonetheless explode in which case long-run time-averages aren't equal to stationary.

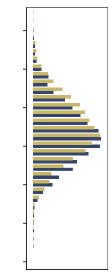
Existence and uniqueness

Suppose (1) the state space is finite, and (2) the state space is irreducible i.e. there's a path from any state to any other

Then there is a unique stationary distribution, and it specifies the longrun time-average distribution.

Even if the state space is infinite, there might still be a stationary distribution





In practice, just go ahead and solve $\pi = \pi P$. (This can always be solved.)

- If there's a unique solution and it can be normalized to sum to 1, then it's the unique stationary distribution.
- Otherwise, we have to work harder to classify the Markov chain's behaviour.

Stationarity equations

If π is a stationary distribution, then it solves

$$\pi = \pi P$$
, $\pi \cdot 1 = 1$

Conversely, if π is a distribution that solves $\pi = \pi P$ then π is a stationary distribution.

Detailed balance equations

Lemma. If π is a vector that satisfies

$$\pi_x P_{xy} = \pi_y P_{yx}$$
 for all x, y
then π solves $\pi = \pi P$.

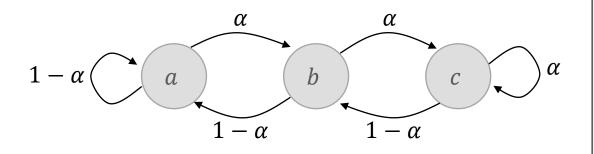
It doesn't hurt to try to solve detailed balance!

- If we're lucky, it tells us the stationary distribution
- If not, we just have to slog through solving $\pi = \pi P$

Example 11.4.4

(Stationary distribution via detailed balance)

Find the stationary distribution of the Markov chain



let's see it we can solve the detailed balance equations:

$$z = a, y = b$$
.

 $z = b, y = \alpha$.

 $z = a, y = c$.

 $z = a, y = c$.

 $z = a, y = c$.

 $z = b, y = c$.

 $z = c$.

$$|T_b| = |T_a| |T_{\alpha}| = |T_{\alpha}| \left(\frac{\alpha}{1-\alpha}\right)^{\frac{1}{2}}$$

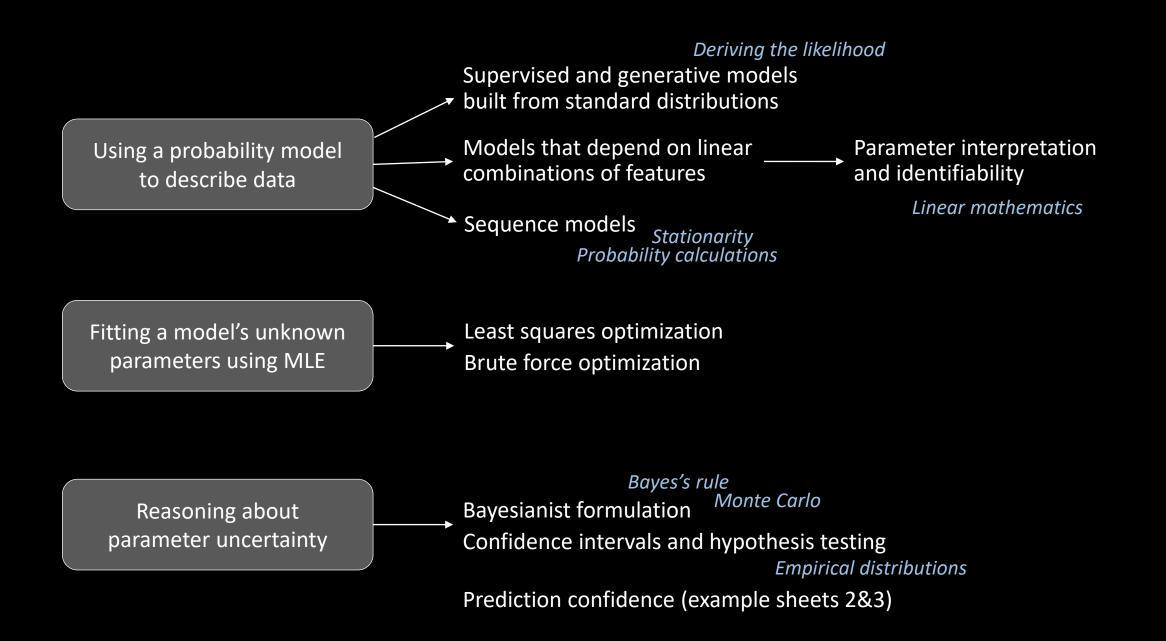
$$|T_c| = |T_b| |T_{\alpha}| = |T_{\alpha}| \left(\frac{\alpha}{1-\alpha}\right)^{\frac{1}{2}}$$

$$|T_{\alpha}| + |T_{\alpha}| + |T_{c}| = 1$$

and we get a stat. dist.

Also, since this chain is finite and irreducible, then there is a unique stationary distribution.
The TT we have just found must be it.

IB Data Science syllabus



Probability modelling is a great way to approach machine learning

Why don't more people adopt it? Because it's unnatural!

If you don't get this elementary, but mildly unnatural, mathematics of elementary probability into your repertoire, then you go through a long life like a one-legged man in an ass kicking contest.

MACHINE LEARNING

Supervised Learning

Data: $\{(x_1, y_1), (x_2, y_2), ..., (x_n, y_n)\}$

Labels: y_1, y_2, \dots, y_n

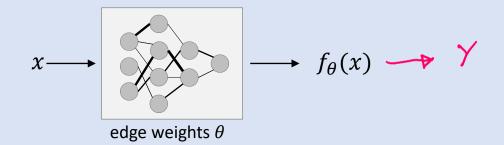
Task: Predict the label Model $Pr_{y}(y_{i}; z_{i})$ $y_{i} \approx f_{\theta}(x_{i})$

Holdout Invent a prediction loss function e.g. evaluation: $L(v, f_{\theta}(x)) = |v - f_{\theta}(x)|^2$

 $L(y, f_{\theta}(x)) = |y - f_{\theta}(x)|^{2}$ and measure the prediction loss

on a holdout dataset

holdort loglik



Generative Modelling

Data: $\{x_1, x_2, ..., x_n\}$

Task: learn to synthesize new values

similar (but not identical) to those

in the dataset, ... Model Pix (x;)

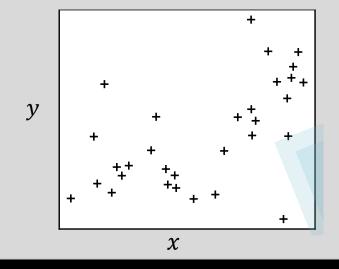
Holdout ??? there is no prediction, so we evaluation: ean't measure prediction loss ???

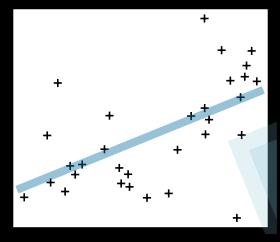
holdout log lik

The real strength of probability modelling is for the generative case, where the algorithmic approach just doesn't have the tools we need.

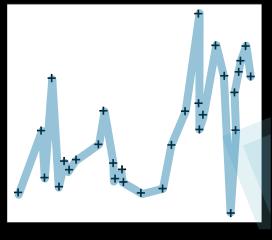
Exercise

I have a labelled dataset of (x, y) pairs and I want to predict y given x. Which of these three models is best?

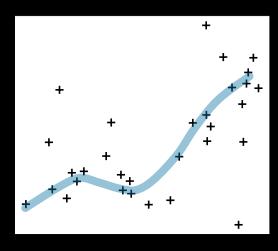




prediction loss: bad



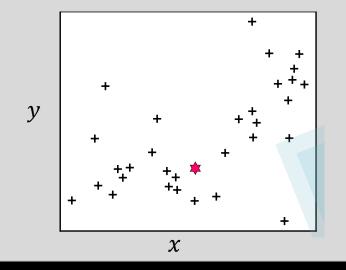
prediction loss: great



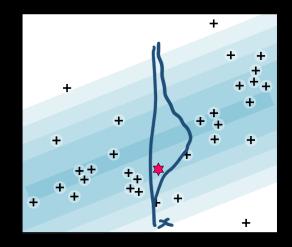
prediction loss: ok

Exercise

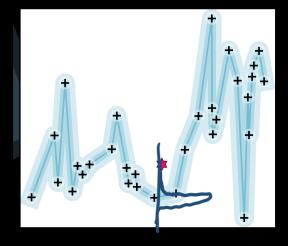
I have a labelled dataset of (x, y) pairs and I want to model y given x. Which of these three probability models is best?



- + training data
- holdout data



log lik: bad holdout log lik: bad UNDERFIT



log lik: great
holdout log lik: terrible
OVERFIT

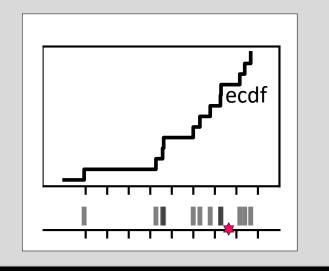


log lik: ok holdout log lik: ok GOLDILOCKS FIT

Holdout log likelihood is a sensible way to evaluate a probability model. It's the natural way to generalize holdout prediction loss.

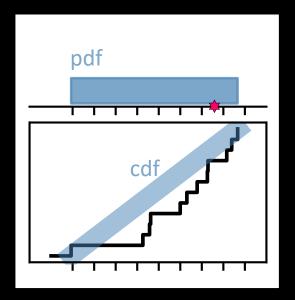
Exercise

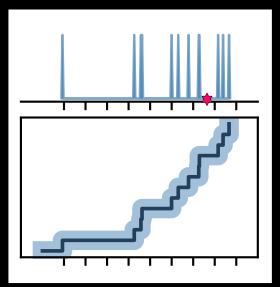
I have an unlabelled dataset $\{x_1, x_2, ..., x_n\}$ and I want to fit a generative model. Which model is best?

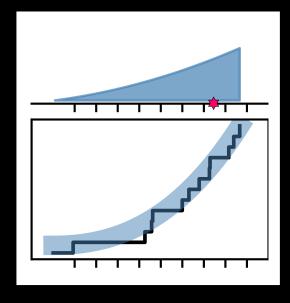


training data

holdout data







fit to data: bad

holdout log lik: bad

UNDERFIT

fit to data: great

holdout log lik: terrible

OVERFIT

fit to data: ok

holdout log lik: ok

GOLDILOCKS FIT

Holdout log likelihood is a perfect way to evaluate generative models.

"The job of my code is to make predictions.

"Evaluate my code by how close its predictions are to the ground truth."

There are many different ways to measure prediction accuracy, for different types of data:

 R^2 mean square hinge loss for error regression margin Cohen's κ ranking loss mean absolute error classification accuracy for area classification under F1 curve score

algorithmic ML

probabilistic ML, generative Al /

"The job of my code is to propose a probability model.

"Evaluate my code by the likelihood it assigns to the ground truth."

log Pr (dataset)

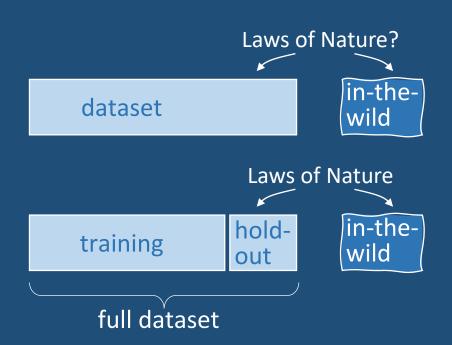
though it's known by different names in different fields:

- perplexity in NLP
- *KL divergence* in ML
- likelihood ratio in statistics
- ignorance score in sports betting

and inside every sane algorithmic ML procedure there's a probability model struggling to get out!

We model because we want to make inductive claims

How will my model perform in the wild?



Every genuine scientific theory must be falsifiable.

It is easy to obtain evidence in support of virtually any theory; the evidence only counts if it is the positive result of a genuinely risky prediction.

Why does Popper not believe in supporting evidence?

HYPOTHESIS

All swans are white, i.e.

 $\forall x \ \text{IsSwan}(x) \Rightarrow \text{IsWhite}(x)$



ANALYSIS

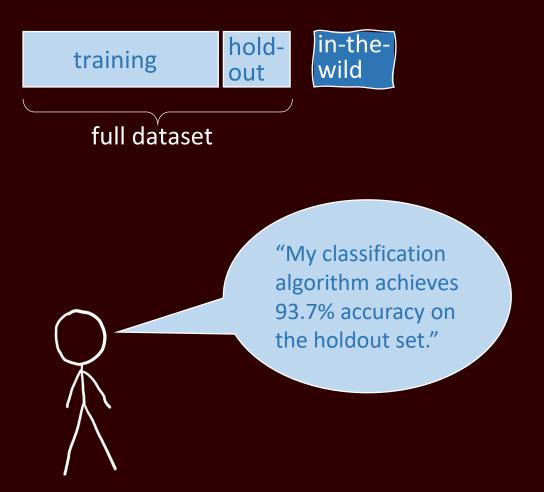
The hypothesis is logically equivalent to

 $\forall x \neg IsWhite(x) \Rightarrow \neg IsSwan(x)$

SUPPORTING EVIDENCE

My pot plant isn't white, and it isn't a swan.

Limitations of current ML: it makes weak inductive claims



What the end-users think (and want):

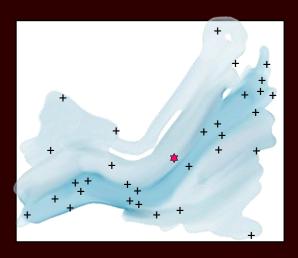
For a new in-the-wild datapoint x, $\mathbb{P}(\text{classify } x \text{ correctly}) = 93.7\%$

What you actually meant:

When I take a big bunch of new in-the-wild datapoints* then, averaged across this bunch, fraction classified correctly = 93.7%

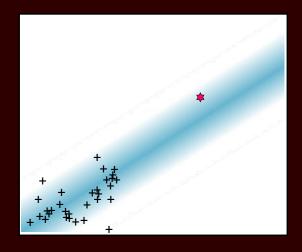
^{*} assuming that this bunch matches the composition of my holdout set

Limitations of current ML: it has trouble with generalization



Machine learning approach

"The job of a model is to **generalize to new data.** I'll split my data into
training + holdout, and measure how
accurate it is on the holdout set."



Scientist's approach

"The job of a model is to **generalize to novel situations.** Any model that's not based on well-grounded scientific concepts will not align with the Laws of Nature, so it will probably make bad predictions."

Limitations of current ML: logical learning



You

Bleen is an adjective, meaning "if the year is before 2000 then blue, otherwise green". I have a bleen car, and the year is 2023. What colour is my car?



ChatGPT

Your car, described as "bleen" and given the year 2023, would be green. The definition of "bleen" you provided changes the color based on the year: blue for years before 2000 and green for years from 2000 onwards. Since 2023 is after 2000, the color of your car would be green.



Did you know that there is no country in Africa that starts with the letter "k"?



ChatGPT:

Yes, that's correct! While there are 54 recognized countries in Africa, none of them begin with the letter "K". The closest is Kenya, which starts with a "K" sound, but is actually spelled with a "K" sound. It's always interesting to learn new trivia facts like this.

Current AI does some amazing things with one-shot learning, but it's still missing the picture.

When you study IB Artificial Intelligence, think hard about why old-school AI can do things that modern Al can't.