Randomised Algorithms

Lecture 8: Solving a TSP Instance using Linear Programming

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Lent 2024



Outline

Introduction

Examples of TSP Instances

Demonstration

Given a set of cities along with the cost of travel between them, find the cheapest route visiting all cities and returning to your starting point.

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—— Formal Definition	

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Formal Definition

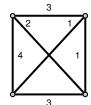
• Given: A complete undirected graph G = (V, E) with nonnegative integer cost c(u, v) for each edge $(u, v) \in E$

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- Given: A complete undirected graph G = (V, E) with nonnegative integer cost c(u, v) for each edge $(u, v) \in E$
- Goal: Find a hamiltonian cycle of G with minimum cost.

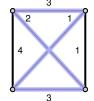
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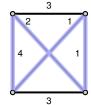
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$$3+2+1+3=9$$

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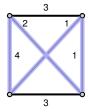
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Solution space consists of at most n! possible tours!



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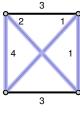
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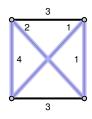
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- Special Instances

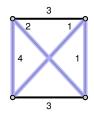
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Special Instances

Metric TSP: costs satisfy triangle inequality:

$$\forall u, v, w \in V$$
: $c(u, w) \leq c(u, v) + c(v, w)$.

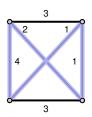
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Special Instances

■ Metric TSP: costs satisfy triangle inequality: < NP hard (Ex. 35.2-2)

Even this version is

$$\forall u, v, w \in V$$
: $c(u, w) \leq c(u, v) + c(v, w)$.

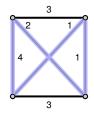
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Special Instances

 Metric TSP: costs satisfy triangle inequality:
 Even this version is NP hard (Ex. 35.2-2)

$$\forall u, v, w \in V: c(u, w) \leq c(u, v) + c(v, w).$$

 Euclidean TSP: cities are points in the Euclidean space, costs are equal to their (rounded) Euclidean distance

Outline

Introduction

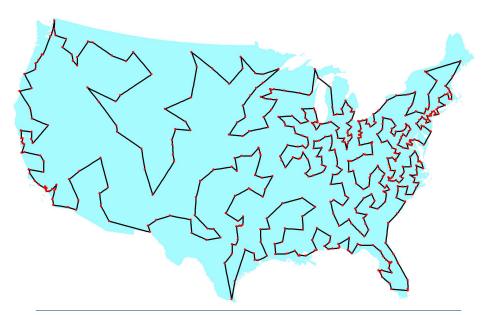
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Demonstration

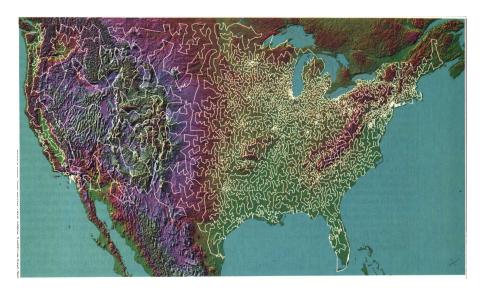
33 city contest (1964)



532 cities (1987 [Padberg, Rinaldi])



13,509 cities (1999 [Applegate, Bixby, Chavatal, Cook])



SOLUTION OF A LARGE-SCALE TRAVELING-SALESMAN PROBLEM*

G. DANTZIG, R. FULKERSON, AND S. JOHNSON

The Rand Corporation, Santa Monica, California

(Received August 9, 1954)

It is shown that a certain tour of 49 cities, one in each of the 48 states and Washington, D. C., has the shortest road distance.

THE TRAVELING-SALESMAN PROBLEM might be described as • follows: Find the shortest route (tour) for a salesman starting from a given city, visiting each of a specified group of cities, and then returning to the original point of departure. More generally, given an n by n symmetric matrix $D = (d_{IJ})$, where d_{IJ} represents the 'distance' from I to J, arrange the points in a cyclic order in such a way that the sum of the d_{IJ} between consecutive points is minimal. Since there are only a finite number of possibilities (at most $\frac{1}{2}(n-1)!$) to consider, the problem is to devise a method of picking out the optimal arrangement which is reasonably efficient for fairly large values of n. Although algorithms have been devised for problems of similar nature, e.g., the optimal assignment problem, 3,7,8 little is known about the traveling-salesman problem. We do not claim that this note alters the situation very much; what we shall do is outline a way of approaching the problem that sometimes, at least, enables one to find an optimal path and prove it so. In particular, it will be shown that a certain arrangement of 49 cities, one in each of the 48 states and Washington, D. C., is best, the d_{IJ} used representing road distances as taken from an atlas.

The 42 (49) Cities

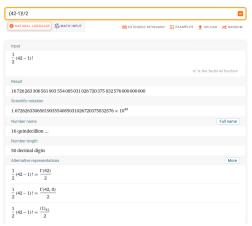
- 1. Manchester, N. H.
- 2. Montpelier, Vt.
- Detroit, Mich.
 Cleveland, Ohio
- 5. Charleston, W. Va.
- 6. Louisville, Ky.
- 7. Indianapolis, Ind.
- 8. Chicago, Ill.
- 9. Milwaukee, Wis.
- 10. Minneapolis, Minn.
- 11. Pierre, S. D.
- 12. Bismarck, N. D.
- 13. Helena, Mont.
- Helena, Mont.
 Seattle, Wash.
- 15. Portland, Ore.
- 16. Portiana, Ore
- 16. Boise, Idaho
- 17. Salt Lake City, Utah

- 18. Carson City, Nev.
- 19. Los Angeles, Calif.
- Phoenix, Ariz.
 Santa Fe, N. M.
- 22. Denver, Colo.23. Chevenne, Wyo.
- 24. Omaha, Neb.
- 25. Des Moines, Iowa
- 26. Kansas City, Mo.
- 27. Topeka, Kans.28. Oklahoma City, Okla.
- 29. Dallas, Tex.
- 30. Little Rock, Ark.
- 31. Memphis, Tenn.
- 32. Jackson, Miss.
- 33. New Orleans, La.

- 34. Birmingham, Ala.
- 35. Atlanta, Ga.
- 36. Jacksonville, Fla.
- 37. Columbia, S. C.
- 38. Raleigh, N. C. 39. Richmond, Va.
- 40. Washington, D. C.
- 41. Boston, Mass.
- 42. Portland, Me.
- A. Baltimore, Md.
- B. Wilmington, Del.
- C. Philadelphia, Penn.
- D. Newark, N. J.
- E. New York, N. Y.
- F. Hartford, Conn.
- G. Providence, R. I.

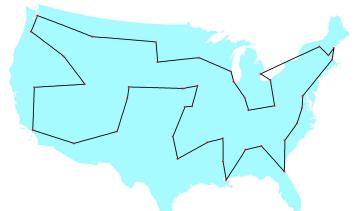
Combinatorial Explosion





Solution of this TSP problem

Dantzig, Fulkerson and Johnson found an optimal tour through 42 cities.



http://www.math.uwaterloo.ca/tsp/history/img/dantzig_big.html

TABLE I

71 65

61 61 66 84 111 113 150 186 192 166 147 180 188 167 140 124 119 90 87 90 94 107 114 77 86 92 98 80 74 77 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41

67 69

78

64

ROAD DISTANCES BETWEEN CITIES IN ADJUSTED UNITS The figures in the table are mileages between the two specified numbered cities, less 11. 50 49 21 15 divided by 17, and rounded to the nearest integer. 61 62 21 48 60 16 17 18 59 60 15 20 26 17 10 62 66 20 25 31 22 15 40 44 50 41 35 24 20 12 108 117 66 71 77 68 61 51 46 13 145 149 104 108 114 106 99 88 84 63 14 181 185 140 144 150 142 135 124 120 99 85 15 187 191 146 150 156 142 137 130 125 105 90 81 41 10 16 | 161 170 120 124 130 115 110 104 105 90 142 146 101 104 111 97 91 85 86 75 174 178 133 138 143 129 123 117 118 107 93 101 72 69 19 18 186 142 143 140 130 126 124 128 118 20 164 165 120 123 124 106 106 105 110 104 86 97 71 93 82 62 42 45 22 77 60 117 122 77 80 83 68 62 61 50 34 48 28 82 42 23 114 118 73 78 84 69 63 57 59 36 72 27 34 28 29 22 23 35 69 105 102 48 53 41 27 19 21 14 29 40 77 114 111 84 64 96 107 87 29 32 27 36 47 78 116 112 84 66 77 115 110 83 63 97 85 119 115 88 66 98 33 36 30 48 34 45 59 85 119 115 88 66 98 79 71 96 130 126 98 75 98 85 46 56 61 57 59 34 38 43 49 60 71 103 141 136 109 90 115 99 81 53 42 43 38 22 26 32 36 51 63 75 106 142 140 112 93 126 108 88 60 44 49 63 76 87 120 155 150 123 100 123 109 86 62 71 75 86 97 126 160 155 128 104 128 113 90 67 76 82 60 62 78 89 121 159 155 127 108 136 124 101 75 50 31 25 32 41 46 64 83 90 130 164 160 133 114 146 134 111 85 59 42 44 51 60 66 83 102 110 147 185 179 155 133 159 146 122 98 105 107 79 71

52 71 93 98 136 172 172 148 126 158 147 124 121 97 99

55 58 63 83 105 109 147 186 188 164 144 176 182 161 134 119 116 86

53 73 96 99 137 176 178 151 131 163 159 135 108 102 103 73

34 36 46 51 70 93 97 134 171 176 151 129 161 163 139 118 102 101 71 65 65 70 84 35 33 40 45 65 87 91 117 166 171 144 125 157 156 139 113 95 97 67 60 62 67 79

25 30 36 47

35 26 18 34 36 46 51

84 88 101 108 88 80 86 92

53 59 66 45 38 45 27 15 6

Road Distances

Hence this is an instance of the Metric TSP, but not Euclidean TSP.

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minimize
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 subject to
$$\sum_{j < i} x(i,j) + \sum_{j > i} x(j,i) = 2 \qquad \text{for each } 1 \leq i \leq 42$$

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Bound-Step: If the best known integral solution so far is better than the solution of a LP, no need to explore branch further!

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Demonstration

In the following, there are a few different runs of the demo.	

Iteration 1:

Objective value: -641.000000, 861 variables, 945 constraints, 1809 iterations



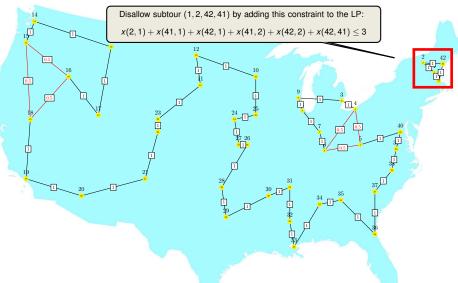
Iteration 1: Eliminate Subtour 1, 2, 41, 42

Objective value: -641.000000, 861 variables, 945 constraints, 1809 iterations



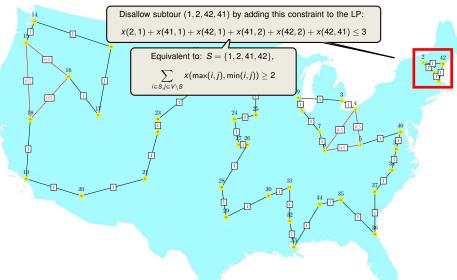
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Iteration 1: Eliminate Subtour 1, 2, 41, 42

Objective value: -641.000000, 861 variables, 945 constraints, 1809 iterations



Iteration 2:

Objective value: -676.000000, 861 variables, 946 constraints, 1802 iterations



Iteration 2: Eliminate Subtour 3 – 9

Objective value: -676.000000, 861 variables, 946 constraints, 1802 iterations



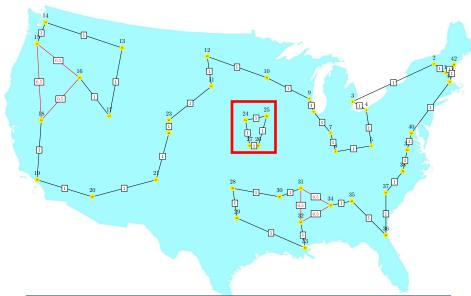
Iteration 3:

Objective value: -681.000000, 861 variables, 947 constraints, 1984 iterations



Iteration 3: Eliminate Subtour 24, 25, 26, 27

Objective value: -681.000000, 861 variables, 947 constraints, 1984 iterations



Iteration 4:

Objective value: -682.500000, 861 variables, 948 constraints, 1492 iterations



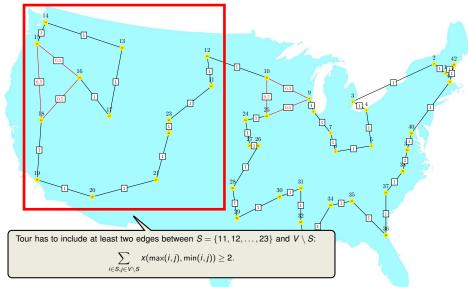
Iteration 4: Eliminate Cut 11 – 23

Objective value: -682.500000, 861 variables, 948 constraints, 1492 iterations



Iteration 4: Eliminate Cut 11 – 23

Objective value: -682.500000, 861 variables, 948 constraints, 1492 iterations



Iteration 5:

Objective value: -686.000000, 861 variables, 949 constraints, 2446 iterations



Iteration 5: Eliminate Subtour 13 – 23

Objective value: -686.000000, 861 variables, 949 constraints, 2446 iterations



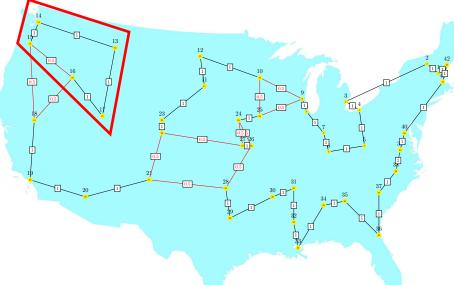
Iteration 6:

Objective value: -694.500000, 861 variables, 950 constraints, 1690 iterations



Iteration 6: Eliminate Cut 13 – 17

Objective value: -694.500000, 861 variables, 950 constraints, 1690 iterations



Iteration 7:

Objective value: -697.000000, 861 variables, 951 constraints, 2212 iterations



Iteration 7: Branch 1a $x_{18,15} = 0$

Objective value: -697.000000, 861 variables, 951 constraints, 2212 iterations



Iteration 8:

Objective value: -698.000000, 861 variables, 952 constraints, 1878 iterations



Iteration 8: Branch 2a $x_{17,13} = 0$

Objective value: -698.000000, 861 variables, 952 constraints, 1878 iterations



Iteration 9:

Objective value: -699.000000, 861 variables, 953 constraints, 2281 iterations



Iteration 9: Branch 2b $x_{17,13} = 1$

Objective value: -699.000000, 861 variables, 953 constraints, 2281 iterations



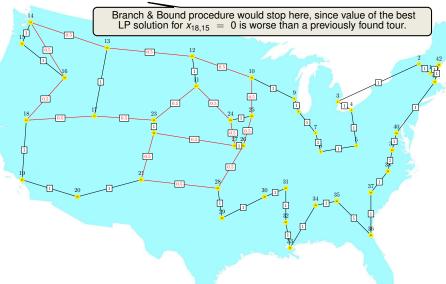
Iteration 10:

Objective value: -700.000000, 861 variables, 954 constraints, 2398 iterations



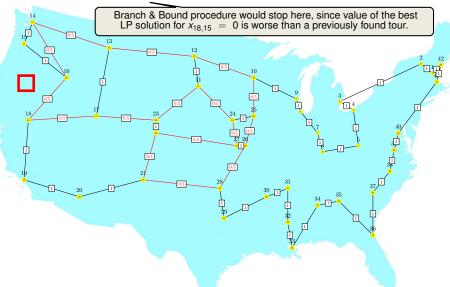
Iteration 10:

Objective value: -700.000000, 861 variables, 954 constraints, 2398 iterations



Iteration 10: Branch 1b $x_{18.15} = 1$

Objective value: -700.000000, 861 variables, 954 constraints, 2398 iterations



Iteration 11:

Objective value: -701.000000, 861 variables, 953 constraints, 2506 iterations



Iteration 11: Branch & Bound terminates

Objective value: -701.000000, 861 variables, 953 constraints, 2506 iterations



1: LP solution 641

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Eliminate Subtour 1, 2, 41, 42

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Eliminate Subtour 1, 2, 41, 42

2: LP solution 676

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Eliminate Subtour 3 – 9

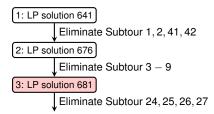
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2: LP solution 676

Eliminate Subtour 3 – 9

3: LP solution 681



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1: LP solution 641

Eliminate Subtour 1, 2, 41, 42

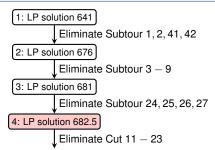
2: LP solution 676

Eliminate Subtour 3 – 9

3: LP solution 681

Eliminate Subtour 24, 25, 26, 27

4: LP solution 682.5
```



```
1: LP solution 641

Eliminate Subtour 1, 2, 41, 42

2: LP solution 676

Eliminate Subtour 3 - 9

3: LP solution 681

Eliminate Subtour 24, 25, 26, 27

4: LP solution 682.5

Eliminate Cut 11 - 23

5: LP solution 686
```

```
1: LP solution 641

Fliminate Subtour 1, 2, 41, 42

2: LP solution 676

Eliminate Subtour 3 – 9

3: LP solution 681

Eliminate Subtour 24, 25, 26, 27

4: LP solution 682.5

Eliminate Cut 11 – 23

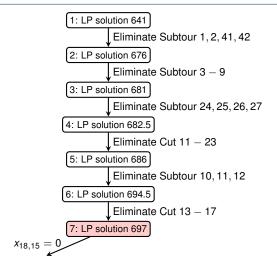
5: LP solution 686

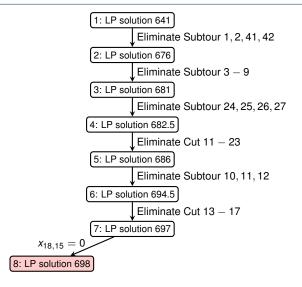
Eliminate Subtour 10, 11, 12
```

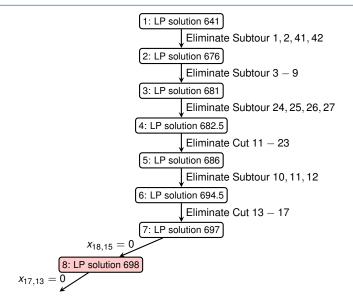
```
1: LP solution 641
          Eliminate Subtour 1, 2, 41, 42
2: LP solution 676
          Eliminate Subtour 3 – 9
3: LP solution 681
          Eliminate Subtour 24, 25, 26, 27
4: LP solution 682.5
          Eliminate Cut 11 - 23
5: LP solution 686
          Eliminate Subtour 10, 11, 12
6: LP solution 694.5
```

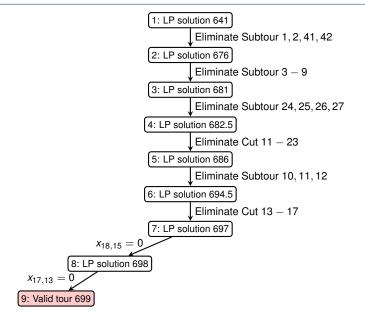
```
1: LP solution 641
          Eliminate Subtour 1, 2, 41, 42
 2: LP solution 676
          Eliminate Subtour 3 – 9
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          Eliminate Subtour 24, 25, 26, 27
4: LP solution 682.5
          Eliminate Cut 11 – 23
 5: LP solution 686
          Eliminate Subtour 10, 11, 12
6: LP solution 694.5
          Eliminate Cut 13 – 17
```

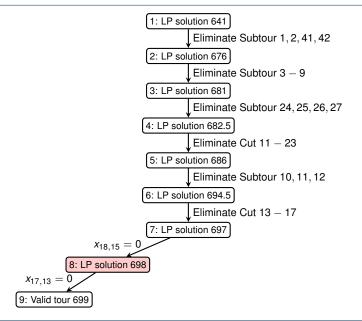
```
1: LP solution 641
          Eliminate Subtour 1, 2, 41, 42
2: LP solution 676
          Eliminate Subtour 3 – 9
3: LP solution 681
          Eliminate Subtour 24, 25, 26, 27
4: LP solution 682.5
          Eliminate Cut 11 – 23
5: LP solution 686
          Eliminate Subtour 10, 11, 12
6: LP solution 694.5
          Eliminate Cut 13 - 17
7: LP solution 697
```

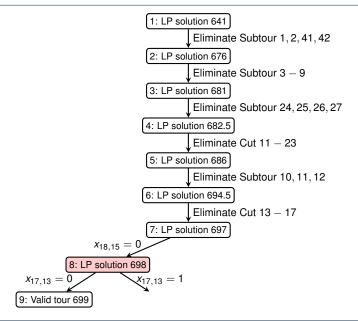


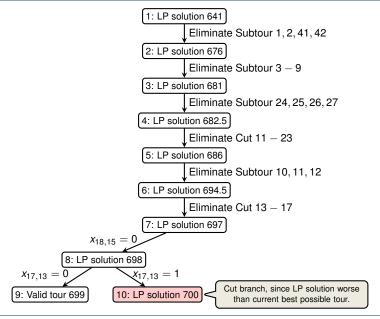


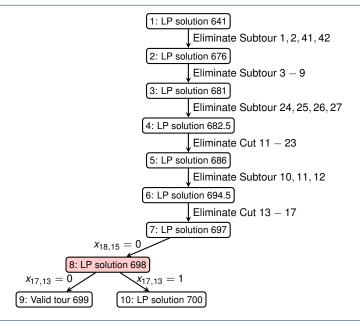


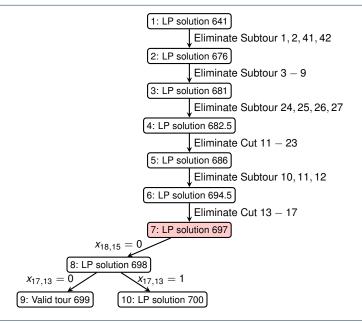


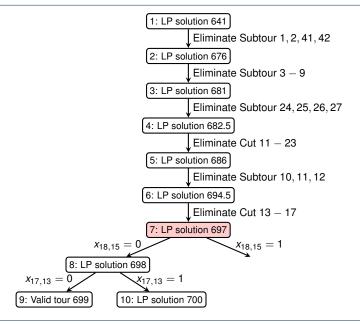


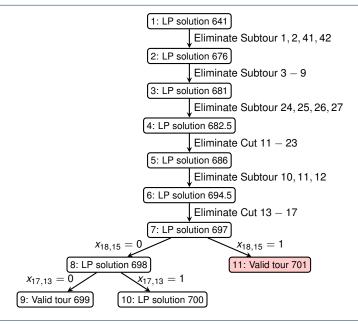


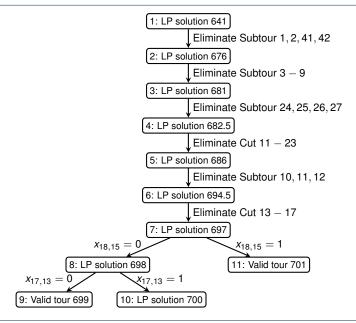




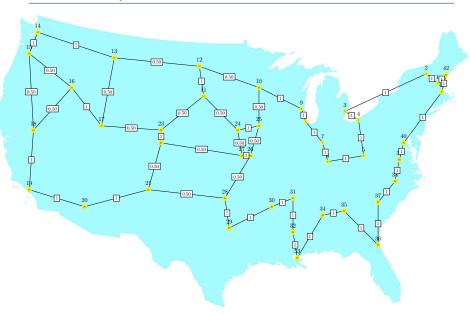




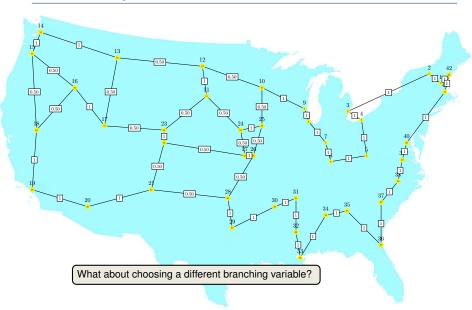




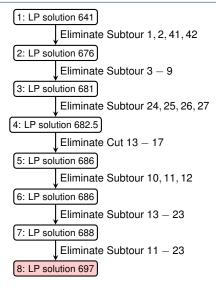
Iteration 7: Objective 697



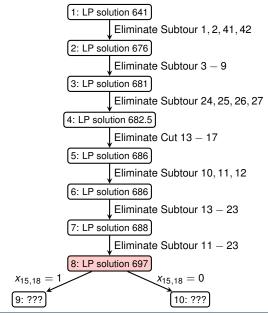
Iteration 7: Objective 697



Solving Progress (Alternative Branch 1)



Solving Progress (Alternative Branch 1)



Alternative Branch 1: $x_{18,15}$, Objective 697



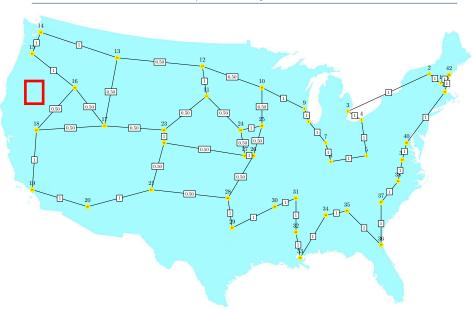
Alternative Branch 1: $x_{18,15}$, Objective 697



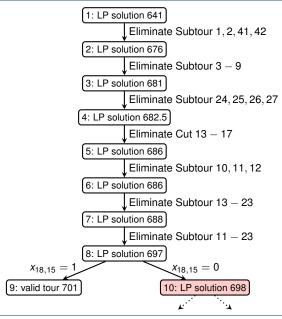
Alternative Branch 1a: $x_{18,15} = 1$, Objective 701 (Valid Tour)



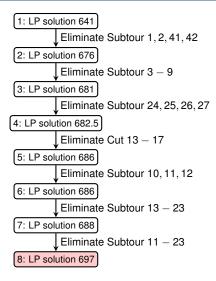
Alternative Branch 1b: $x_{18,15} = 0$, Objective 698



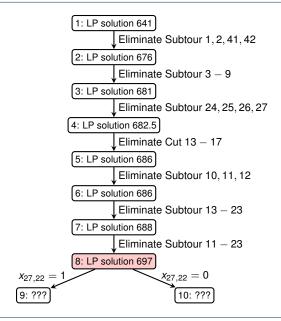
Solving Progress (Alternative Branch 1)



Solving Progress (Alternative Branch 2)



Solving Progress (Alternative Branch 2)



Alternative Branch 2: $x_{27,22}$, Objective 697



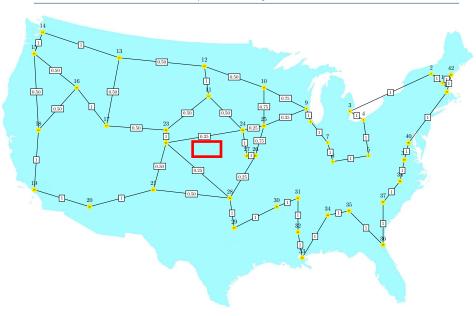
Alternative Branch 2: $x_{27,22}$, Objective 697



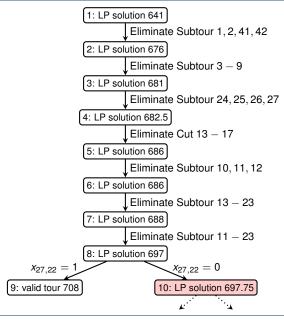
Alternative Branch 2a: $x_{27,22} = 1$, Objective 708 (Valid tour)



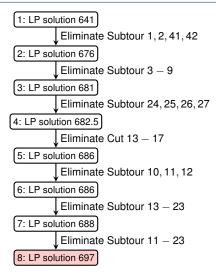
Alternative Branch 2b: $x_{27,22} = 0$, Objective 697.75



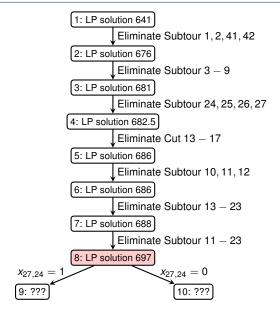
Solving Progress (Alternative Branch 2)



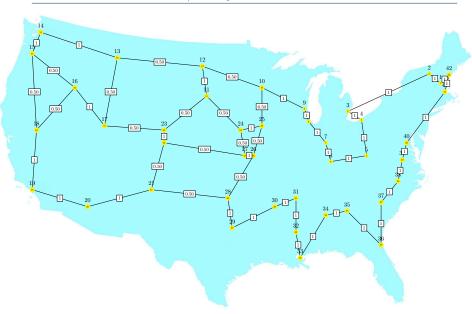
Solving Progress (Alternative Branch 3)



Solving Progress (Alternative Branch 3)



Alternative Branch 3: $x_{27,24}$, Objective 697



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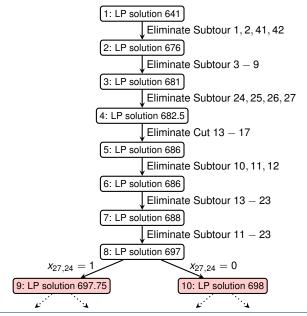
Alternative Branch 3a: $x_{27,24} = 1$, Objective 697.75



Alternative Branch 3b: $x_{27,24} = 0$, Objective 698



Solving Progress (Alternative Branch 3)



Solving Progress (Alternative Branch 3)

```
1: LP solution 641

Eliminate Subtour 1, 2, 41, 42

2: LP solution 676

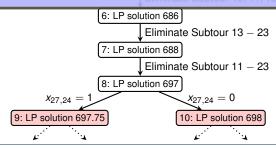
Eliminate Subtour 3 – 9

3: LP solution 681

Eliminate Subtour 24, 25, 26, 27

4: LP solution 682.5
```

Not only do we have to explore (and branch further in) both subtrees, but also the optimal tour is in the subtree with larger LP solution!



How can one generate these constraints automatically?

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 Subtour Elimination: Finding Connected Components
 Small Cuts: Finding the Minimum Cut in Weighted Graphs

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CONCLUDING REMARK

It is clear that we have left unanswered practically any question one might pose of a theoretical nature concerning the traveling-salesman problem; however, we hope that the feasibility of attacking problems involving a moderate number of points has been successfully demonstrated, and that perhaps some of the ideas can be used in problems of similar nature.

- Eliminate Subtour 1, 2, 41, 42
- Eliminate Subtour 3 9
- Eliminate Subtour 10, 11, 12
- Eliminate Subtour 11 23
- Eliminate Subtour 13 23
- Eliminate Cut 13 17
- Eliminate Subtour 24, 25, 26, 27

- Eliminate Subtour 1, 2, 41, 42
- Eliminate Subtour 3 9
- Eliminate Subtour 10, 11, 12
- Eliminate Subtour 11 23
- Eliminate Subtour 13 23
- Eliminate Cut 13 17
- Eliminate Subtour 24, 25, 26, 27

THE 49-CITY PROBLEM*

The optimal tour \bar{x} is shown in Fig. 16. The proof that it is optimal is given in Fig. 17. To make the correspondence between the latter and its programming problem clear, we will write down in addition to 42 relations in non-negative variables (2), a set of 25 relations which suffice to prove that D(x) is a minimum for \bar{x} . We distinguish the following subsets of the 42 cities:

$$\begin{array}{lll} S_1 = \{1,\,2,\,41,\,42\} & S_5 = \{13,\,14,\,\cdots,\,23\} \\ S_2 = \{3,\,4,\,\cdots,\,9\} & S_6 = \{13,\,14,\,15,\,16,\,17\} \\ S_3 = \{1,\,2,\,\cdots,\,9,\,29,\,30,\,\cdots,\,42\} & S_7 = \{24,\,25,\,26,\,27\}. \\ S_4 = \{11,\,12,\,\cdots,\,23\} & \end{array}$$



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CPLEX

From Wikipedia, the free encyclopedia

IBM ILOG CPLEX Optimization Studio (often informally referred to simply as CPLEX) is an optimization software package. In 2004, the work on CPLEX earned the first INFORMS Impact Prize.

The CPLEX Optimizer was named for the simplex method as implemented in the C programming language. although today it also supports other types of mathematical optimization and offers interfaces other than just C. It was originally developed by Robert E. Bixby and was offered commercially starting in 1988 by

CPLEX Optimization Inc., which was acquired by ILOG in 1997; ILOG was subsequently acquired by IBM in January 2009.^[1] CPLEX continues to be actively developed under IBM.

The IBM ILOG CPLEX Optimizer solves integer programming problems, very large^[2] linear programming problems using either primal or dual variants of the simplex method or the barrier interior

CPLEX

Developer(s) IRM Stable release 12.6

Development status Active

Type Technical computing License Proprietary

Website ibm.com/software

/products /ibmilogcpleoptistud/₫ Welcome to IBM(R) ILOG(R) CPLEX(R) Interactive Optimizer 12.6.1.0 with Simplex. Mixed Integer & Barrier Optimizers 5725-A06 5725-A29 5724-Y48 5724-Y49 5724-Y54 5724-Y55 5655-Y21 Copyright IBM Corp. 1988, 2014. All Rights Reserved. Type 'help' for a list of available commands. Type 'help' followed by a command name for more information on commands. CPLEX> read tsp.lp Problem 'tsp.lp' read. Read time = 0.00 sec. (0.06 ticks) CPLEX> primopt Tried aggregator 1 time. LP Presolve eliminated 1 rows and 1 columns. Reduced LP has 49 rows. 860 columns. and 2483 nonzeros. Presolve time = 0.00 sec. (0.36 ticks)Iteration log . . . Iteration: 1 Infeasibility = 33,999999 Iteration: 26 Objective 1510,000000 Objective = Iteration: 90 923,000000 Iteration: 155 Objective 711.000000 Primal simplex - Optimal: Objective = 6.9900000000e+02 Solution time = 0.00 sec. Iterations = 168 (25) Deterministic time = 1.16 ticks (288.86 ticks/sec)

CPLEX>

CPLEX> display	solut	tion	vai	riables	s -		
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x_42_1				1.6	00000		
x_3_2				1.6	909999		
x_4_3				1.6	999999		
x_5_4				1.6	90000		
x_6_5				1.6	999999		
x_7_6				1.6	99999		
x_8_7				1.6	90000		
x_9_8				1.6	999999		
x 10 9				1.6	00000		
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x_16_15				1.6	00000		
x_17_16				1.0	900000		
x_18_17				1.6	900000		
x_19_18				1.6	00000		
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x_40_39					000000		
x_41_40					000000		
x_42_41	ah1a-				1 061		
All other varia	ables	ın '	tne	range	1-861	are	υ.