# Introduction to Probability

Lecture 11: Estimators (Part II) Mateja Jamnik, Thomas Sauerwald

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#### Recap

Estimating Population Size (First Version)

Mean Squared Error

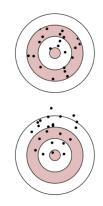
Estimating Population Size (Second Version)

Definition — An estimator T is called an unbiased estimator for a parameter  $\theta$  if

$$\mathbf{E}[T] = \theta,$$

irrespective of the value  $\theta$ . The bias is defined as

$$\mathbf{E}\left[ T\right] - \theta = \mathbf{E}\left[ T - \theta \right].$$



Source: Edwin Leuven (Point Estimation)



- How can we measure the accuracy of an estimator?
  - $\rightsquigarrow$  bias and mean-squared error
- If there are several unbiased estimators, which one to choose? → mean-squared error (or variance)

## An Unbiased Estimator may not always exist

Example 6 -

Suppose that we have one sample  $X \sim Bin(n, p)$ , where 0 is unknown but*n*is known. Prove there is no unbiased estimator for <math>1/p.

Answei

## An Unbiased Estimator may not always exist (cntd. - non-examinable)

Example 6 (cntd.)

Suppose that we have one sample  $X \sim Bin(n, p)$ , where 0 is unknown but*n*is known. Prove there is no unbiased estimator for <math>1/p.

• Suppose there exists an unbiased estimator with E[T(X)] = 1/p.

Then

$$1 = p \cdot \mathbf{E} [T(X)]$$
$$= p \cdot \sum_{k=0}^{n} \mathbf{P} [X = k] \cdot T(k)$$
$$= p \cdot \sum_{k=0}^{n} {n \choose k} p^{k} \cdot (1 - p)^{n - k} \cdot T(k)$$

• Last term is a polynomial of degree n + 1 with constant term zero  $\Rightarrow p \cdot \mathbf{E}[T(X)] - 1$  is a (non-zero) polynomial of degree  $\le n + 1$  $\Rightarrow$  this polynomial has at most n + 1 roots

 $\Rightarrow$  **E** [*T*(*X*)] can be equal to 1/*p* for at most *n* + 1 values of *p*, and thus cannot be an unbiased.

Recap

#### Estimating Population Size (First Version)

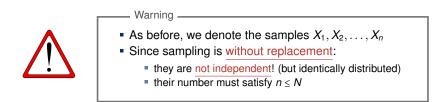
Mean Squared Error

Estimating Population Size (Second Version)

## **Estimating Population Size (First Version)**

- Suppose we have a sample of a few serial numbers (IDs) of some product
- We assume IDs are running from 1 to an unknown parameter N (so  $N = \theta$ )
- Each of the IDs is drawn without replacement from the discrete uniform distribution over {1,2,...,N}
- This is also known as Tank Estimation Problem or (Discrete) Taxi Problem

### 7, 3, 10, 46, 14



## First Estimator Based on Sample Mean

Example 1		
Construct an unbiased estimator using the sample mean.		
	Answer	

- Suppose n = 5
- Let the sample be

$$7, 3, 10, \frac{46}{14}, 14$$

The estimator returns:

$$T_1 = 2 \cdot \overline{X}_n - 1 = 2 \cdot \frac{80}{5} - 1 = 31 \quad \textcircled{0}$$
This estimator will often unnecessarily  
underestimate the true value *N*.
Ilenging exercise: Find a lower bound on **P**[ $T_1 < \max(X_1, X_2, \dots, X_n)$ ]

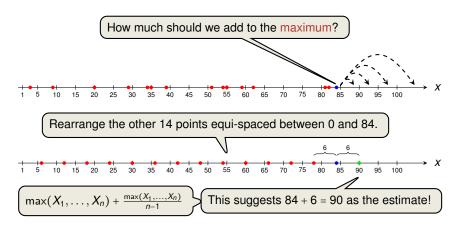
- Achieving unbiasedness alone is not a good strategy
- Improvement: find an estimator which always returns a value at least max(X<sub>1</sub>, X<sub>2</sub>,..., X<sub>n</sub>)

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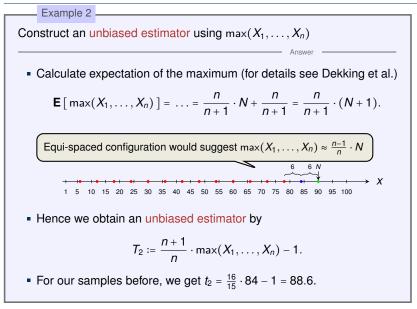
## Intuition: Constructing an Estimator based on Maximum

- Suppose *n* = 15
- Our samples are:

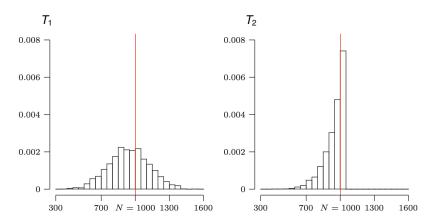
 $9, 82, 39, 35, 20, 51, 54, 62, 81, 29, {\color{red}84}, 59, 3, 34, 55$ 



## **Deriving the Estimator Based on Maximum**



### **Empirical Analysis of the two Estimators**



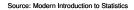


Figure: Histogram of 2000 values for  $T_1$  and  $T_2$ , when N = 1000 and n = 10.

Can we find a quantity that captures the superiority of  $T_2$  over  $T_1$ ?

Intro to Probability

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Estimating Population Size (Second Version)

## **Mean Squared Error**

#### Mean Squared Error Definition —

Let T be an estimator for a parameter  $\theta$ . The mean squared error of T is

$$\mathsf{MSE}[T] = \mathsf{E}\Big[(T-\theta)^2\Big].$$

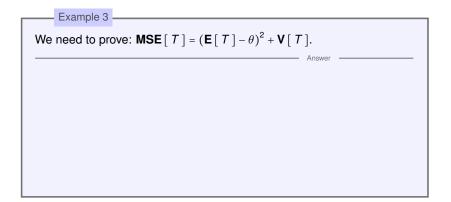
• According to this, estimator  $T_1$  better than  $T_2$  if **MSE**  $[T_1] <$ **MSE**  $[T_2]$ .

Bias-Variance Decomposition  
The mean squared error can be decomposed into:  

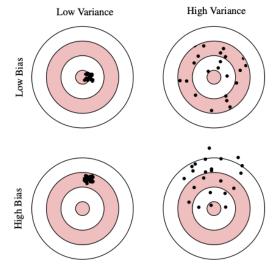
$$MSE[T] = (E[T] - \theta)^{2} + V[T]$$

$$= Bias^{2} = Variance$$

• If  $T_1$  and  $T_2$  are both unbiased,  $T_1$  is better than  $T_2$  iff  $\mathbf{V}[T_1] < \mathbf{V}[T_2]$ .



## **Bias-Variance Decomposition: Illustration**



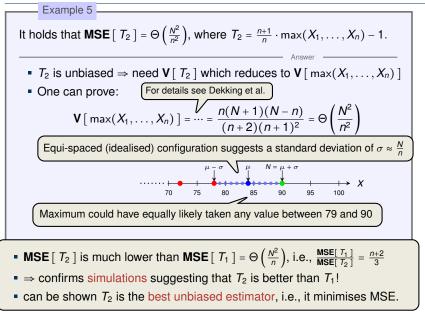
Source: Edwin Leuven (Point Estimation)

Example 4

It holds that **MSE** 
$$[T_1] = \Theta\left(\frac{N^2}{n}\right)$$
, where  $T_1 = 2 \cdot \overline{X}_n - 1$ .

Answer

## Analysis of the MSE for $T_2$ (non-examinable)



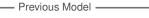
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## A New Estimation Problem



- Population/ID space S = {1, 2, ..., N}
- We take uniform samples from S without replacement
- Goal: Find estimator for N

Similar idea applies to situations where elements are not labelled before we see them first time (Mark & Recapture Method)

New Model

- Population/ID space of size |S| = N
- We take uniform samples from S with replacement
- Goal: Find estimator for N
- Suppose n = 6, N = 11, S = {3,4,7,8,10,15.83356,20,21,56,81,10000}
- Let the sample be

10, 81, 20, 3, 81, 10000

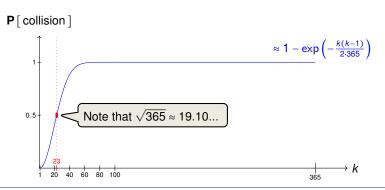
Let us call this a **collision** 

As we do not know S, our only clue are elements that were sampled twice.

## **Birthday Problem**

#### Birthday Problem: Given a set of k people

- What is the probability of having two with the same birthday (i.e., having at least one collision)?
- What is the expected number of people one needs to ask until the first collision occurs?



## Estimation via Collision: The Algorithm

Recall: As we do not know S, our only information are collisions.

FIND-FIRST-COLLISION(S)

- 1: *C* = ∅
- 2: **For** *i* = 1, 2, . . .
- 3: Take next i.i.d. sample  $X_i$  from S
- 4: If  $X_i \notin C$  then  $C \leftarrow C \cup \{X_i\}$
- 5: else return T(i)
- 6: End For

T(i) will be the value of the estimator if algo returns after *i* rounds. (We want *T* unbiased)

• Running Time: The expected time until the algorithm stops is:

= the expected number of samples until a collision...

Same as the birthday problem, but now with |S| = N days...  $\odot$ 

Expected Running Time (Knuth, Ramanujan)  

$$\sqrt{\frac{\pi N}{2}} - \frac{1}{3} + O\left(\frac{1}{\sqrt{N}}\right).$$
  
Exercise: Prove a bound of  $\leq 2 \cdot \sqrt{N}$ 

## Estimation via Collision: Getting the Estimator Unbiased

Example 6		
One can define $T(i)$ , $i \in \mathbb{N}$ , such that $\mathbf{E}[T] =  S $ for any finite, non-empty set $S$ .		
	Answer	