

UNIVERSITY OF  
CAMBRIDGE  
COMPUTER LABORATORY



# Display Technologies

**Advanced Graphics and Image Processing**

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# Overview

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- ▶ **Temporal aspects**
  - ▶ Latency in VR
  - ▶ Eye-movement
  - ▶ Hold-type blur
- ▶ **2D displays**
  - ▶ 2D spatial light modulators
  - ▶ High dynamic range displays

# Latency in VR

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## ▶ Sources of latency in VR

- ▶ IMU ~1 ms
  - ▶ Inertial Measurement Unit
- ▶ sensor fusion, data transfer
- ▶ rendering: depends on complexity of scene & GPU – a few ms
- ▶ data transfer again
- ▶ Display
  - ▶ 60 Hz = 16.6 ms;
  - ▶ 70 Hz = 14.3 ms;
  - ▶ 120 Hz = 8.3 ms.

## ▶ Target latency

- ▶ Maximum acceptable: 20ms
- ▶ Much smaller (5ms) desired for interactive applications

## ▶ Example

- ▶ 16 ms (display) + 16 ms (rendering) + 4 ms (orientation tracking) = 36 ms latency total
- ▶ At 60 deg/s head motion, 1Kx1K, 100deg fov display:
  - ▶ 19 pixels error
  - ▶ Too much

# Post-rendering image warp (time warp)

- ▶ To minimize end-to-end latency
- ▶ The method:
  - ▶ get current camera pose
  - ▶ render into a larger raster than the screen buffer
  - ▶ get new camera pose
  - ▶ warp rendered image using the latest pose, send to the display
    - ▶ 2D image translation
    - ▶ 2D image warp
    - ▶ 3D image warp
- ▶ Original paper from Mark et al. 1997, also Darsa et al. 1997
  - ▶ Meta: Asynchronous Time Warp



# Eye movement - basics

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Fixation

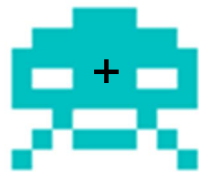


Drift: 0.15-0.8 deg/s

# Eye movement - basics

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Saccade



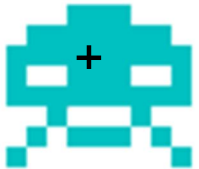
160-300 deg/s



# Eye movement - basics

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## Smooth Pursuit Eye Motion (SPEM)



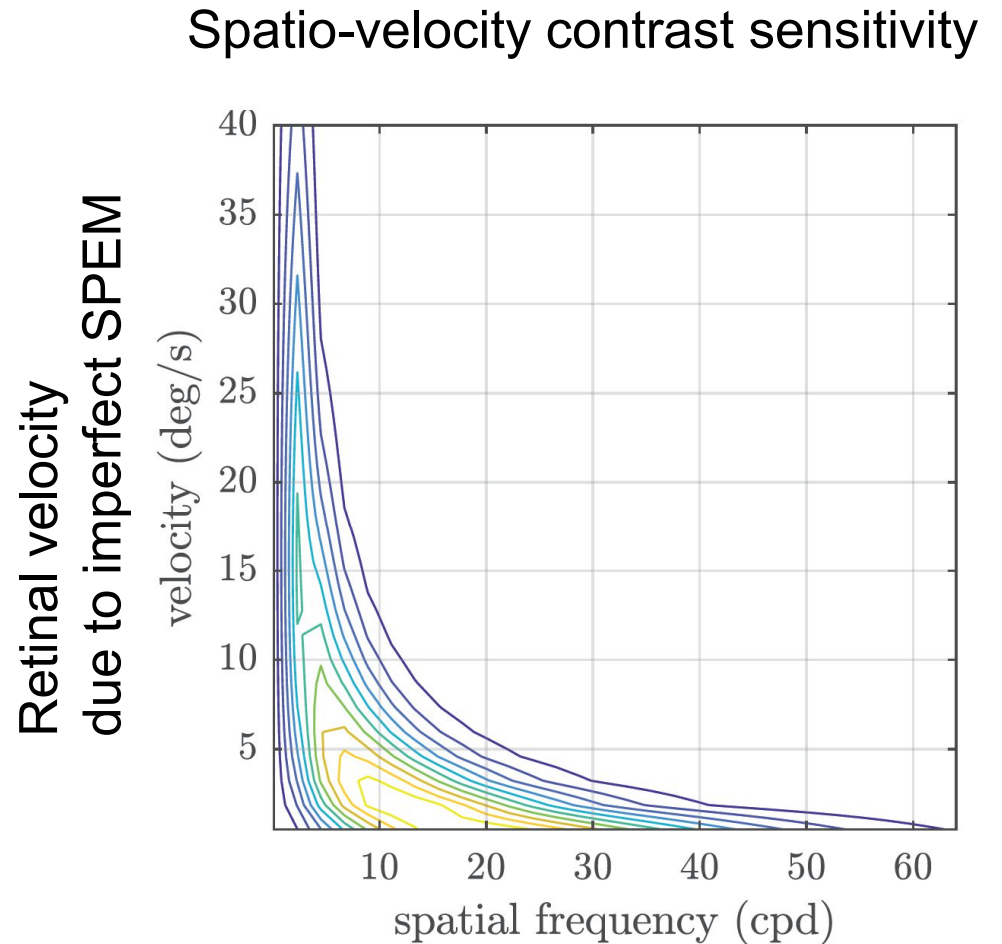
Up to 80 deg/s

The tracking is imperfect

- especially at higher velocities
- and for unpredictable motion

# Retinal velocity

- ▶ The eye tracks moving objects
  - ▶ Smooth Pursuit Eye Motion (SPEM) stabilizes images on the retina
  - ▶ But SPEM is imperfect
- ▶ Loss of sensitivity mostly caused by imperfect SPEM
  - ▶ SPEM worse at high velocities



Kelly's model [1979]



# Motion sharpening

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- ▶ The visual system “sharpens” objects moving at speeds of 6 deg/s or more

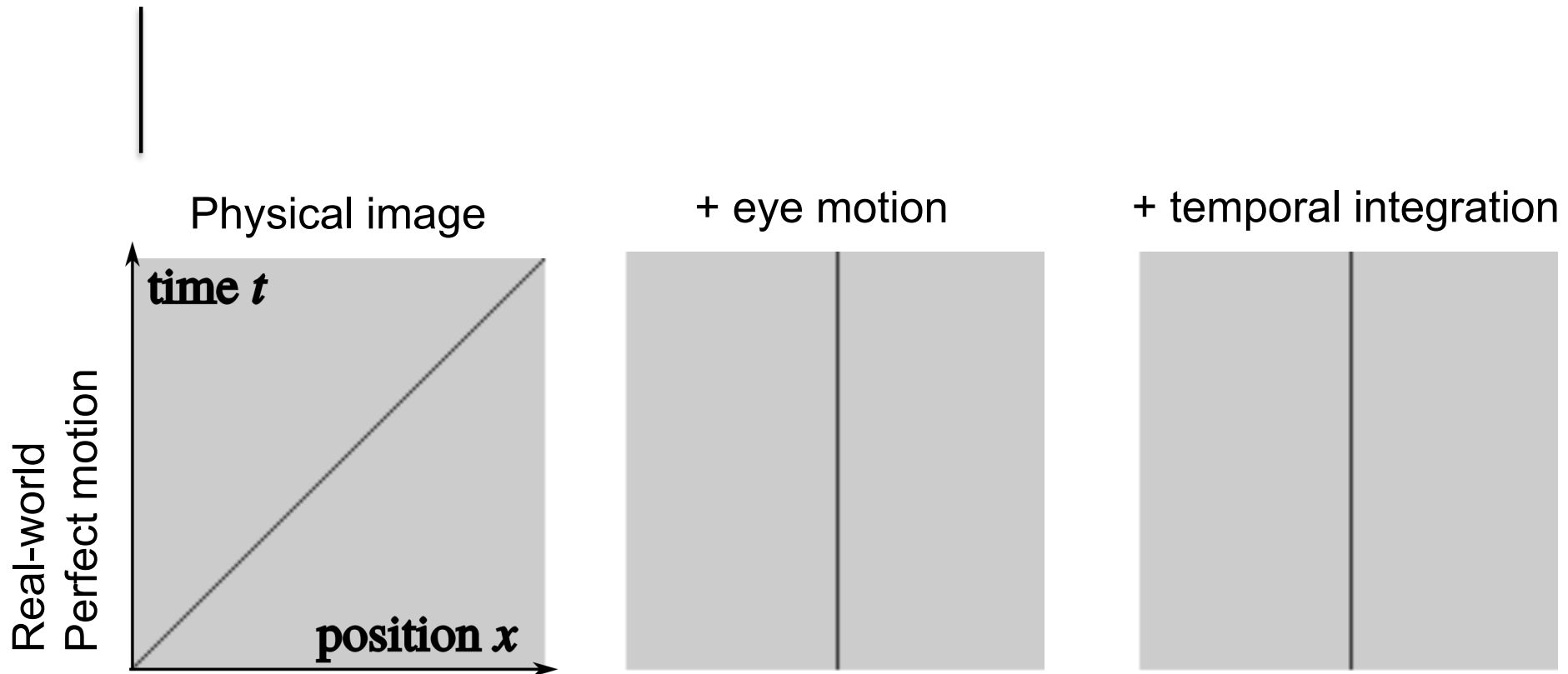


- ▶ Potentially a reason why VR appears sharper than it actually is

# Hold-type blur

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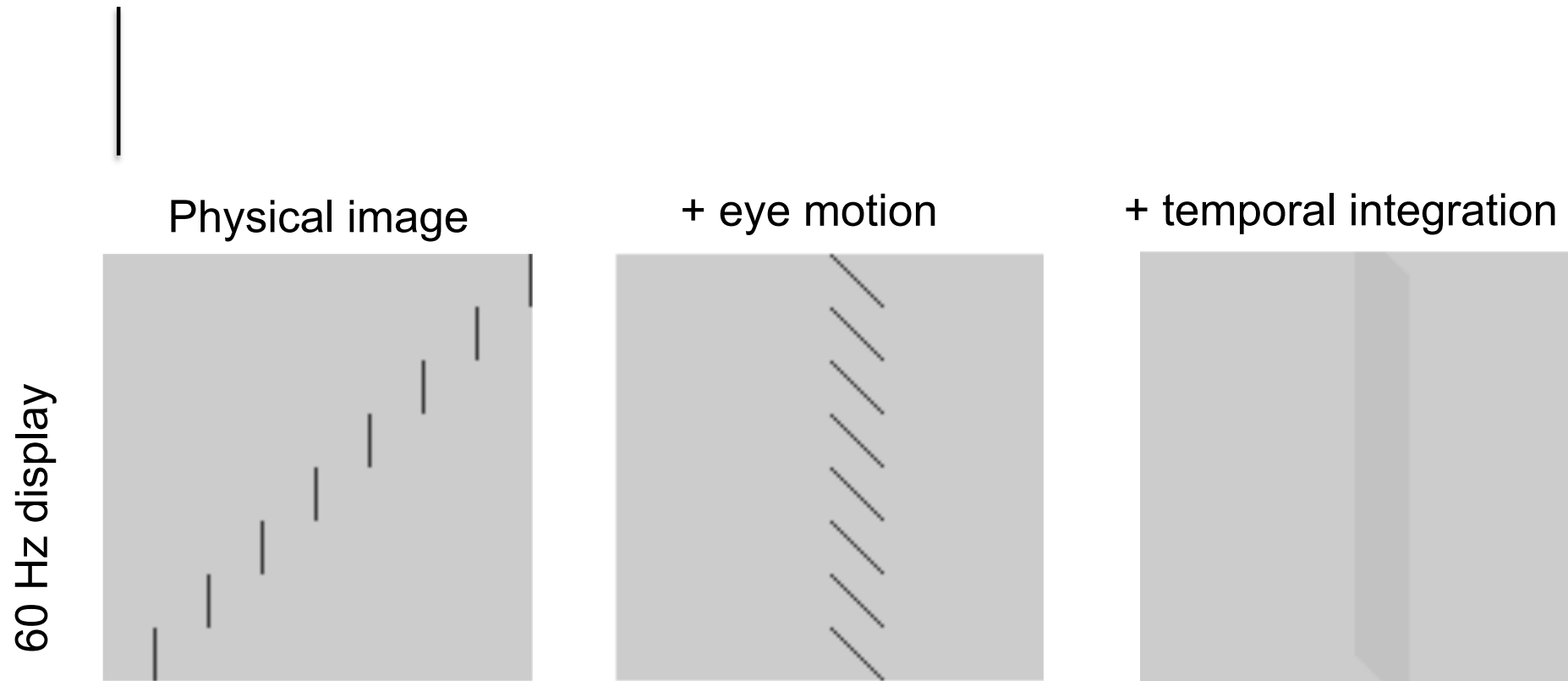
- ▶ The eye smoothly follows a moving object
- ▶ But the image on the display is “frozen” for  $1/60^{\text{th}}$  of a second



# Hold-type blur

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- ▶ The eye smoothly follows a moving object
- ▶ But the image on the display is “frozen” for 1/60<sup>th</sup> of a second






Original scene



With hold-type blur

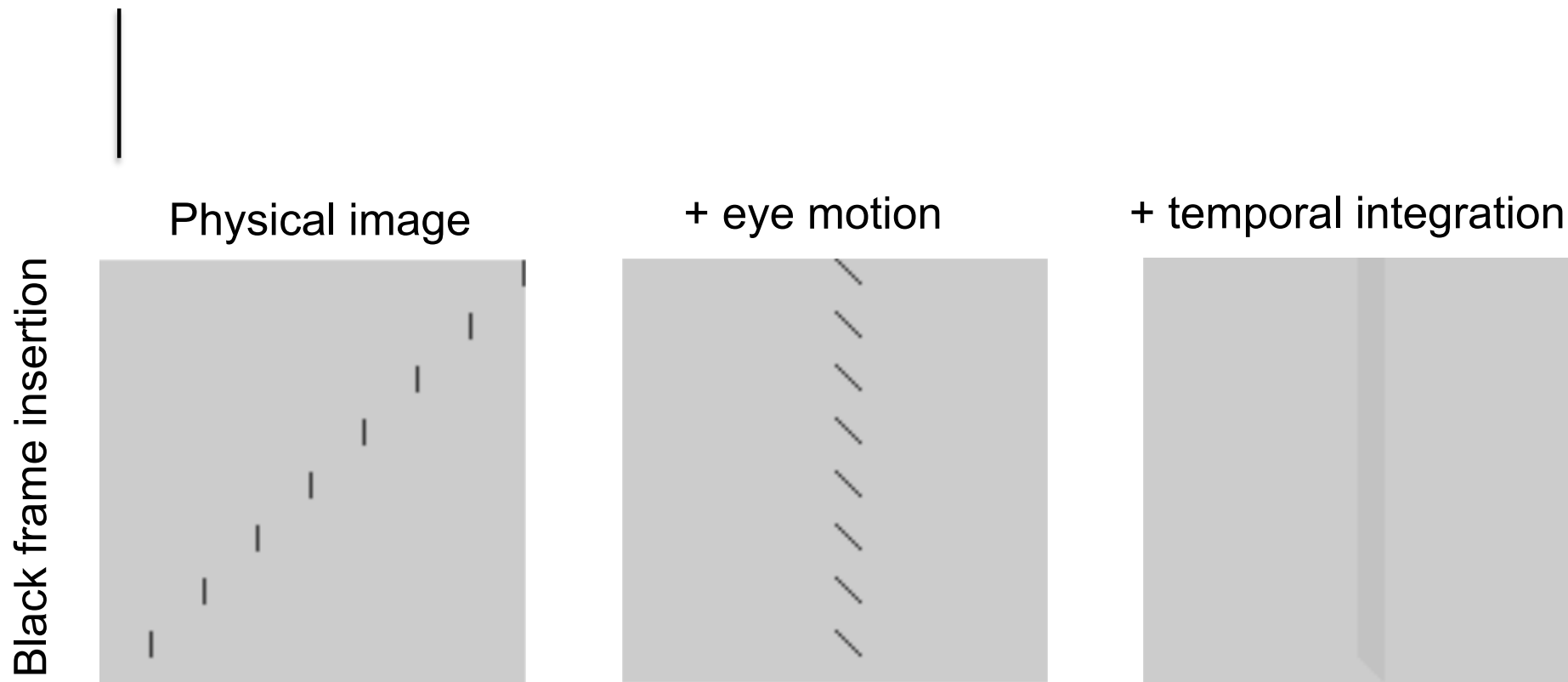
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# Hold-type blur

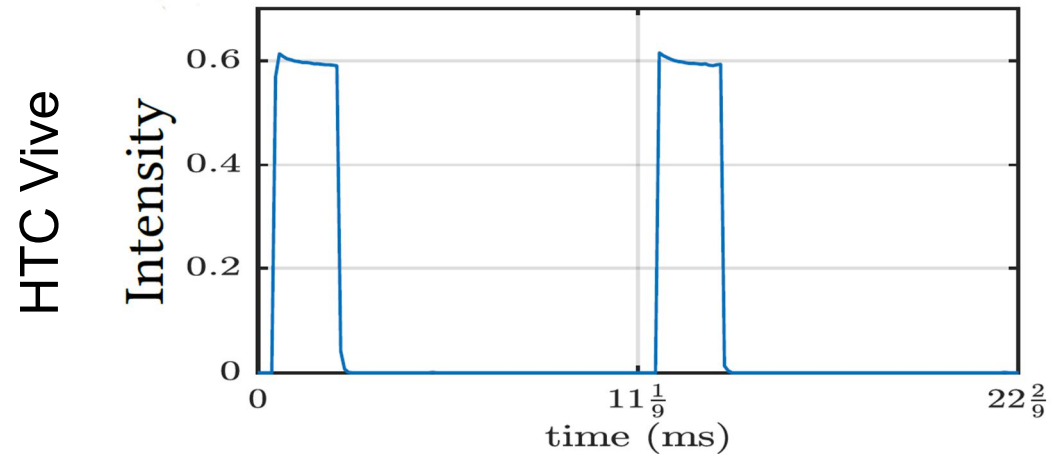
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- ▶ The eye smoothly follows a moving object
- ▶ But the image on the display is “frozen” for 1/60<sup>th</sup> of a second

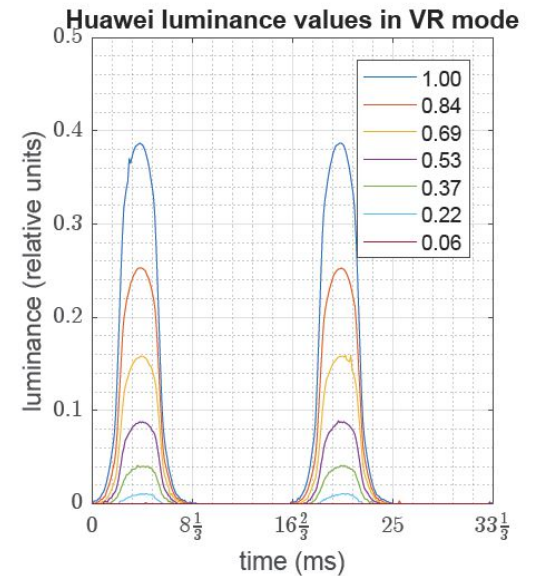
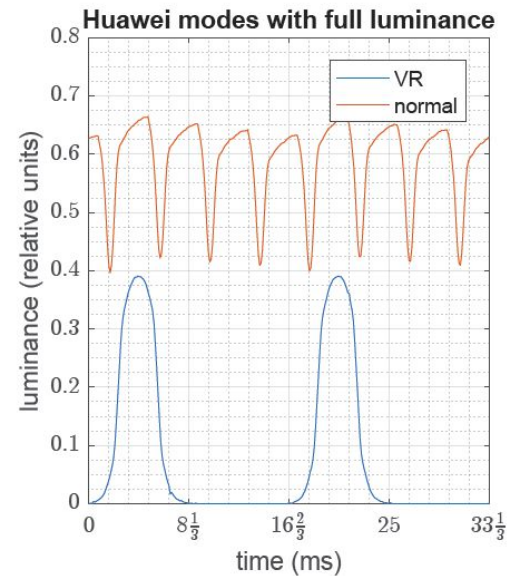


# Low persistence displays

- ▶ Most VR displays flash an image for a fraction of frame duration
- ▶ This reduces hold-type blur
- ▶ And also reduces the perceived lag of the rendering



Mate 9 Pro + DayDream



# Black frame insertion

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- ▶ Which invader appears sharper?

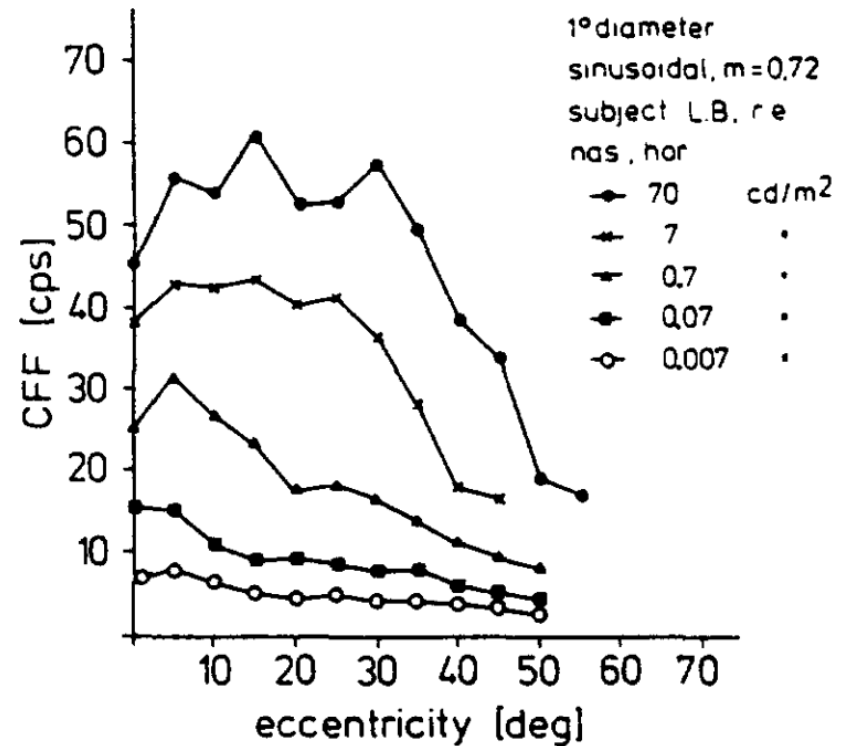


- ▶ A similar idea to low-persistence displays in VR
- ▶ Reduces hold-type blur

# Flicker

## ▶ Critical Flicker Frequency

- ▶ The lowest frequency at which flickering stimulus appears as a steady field
- ▶ Measured for full-on / off presentation
- ▶ Strongly depends on luminance – big issue for HDR VR headsets
- ▶ Varies with eccentricity and stimulus size
- ▶ It is possible to detect flicker even at 2kHz
  - ▶ For saccadic eye motion



[Hartmann et al. 1979]

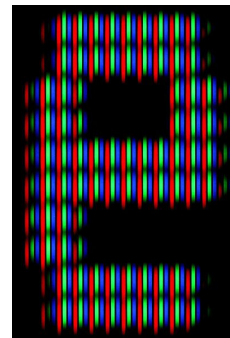
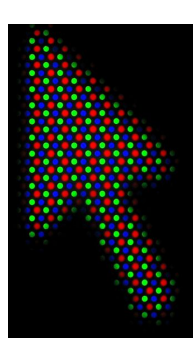
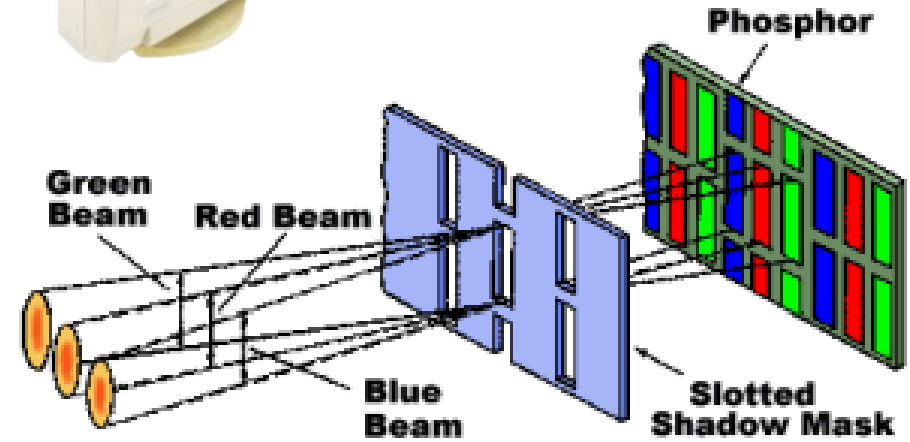
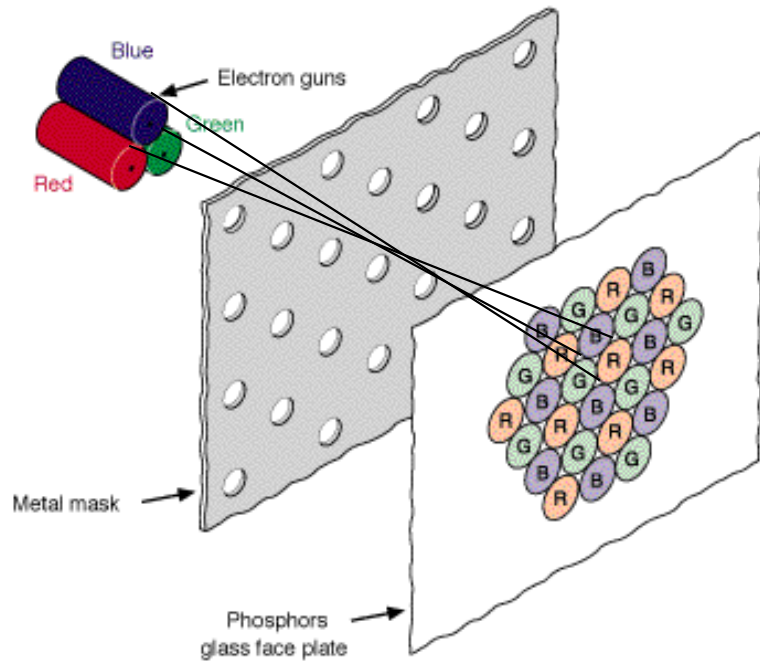


# Overview

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- ▶ **Temporal aspects**
  - ▶ Latency in VR
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- ▶ **2D displays**
  - ▶ 2D spatial light modulators
  - ▶ High dynamic range displays

# Cathode Ray Tube

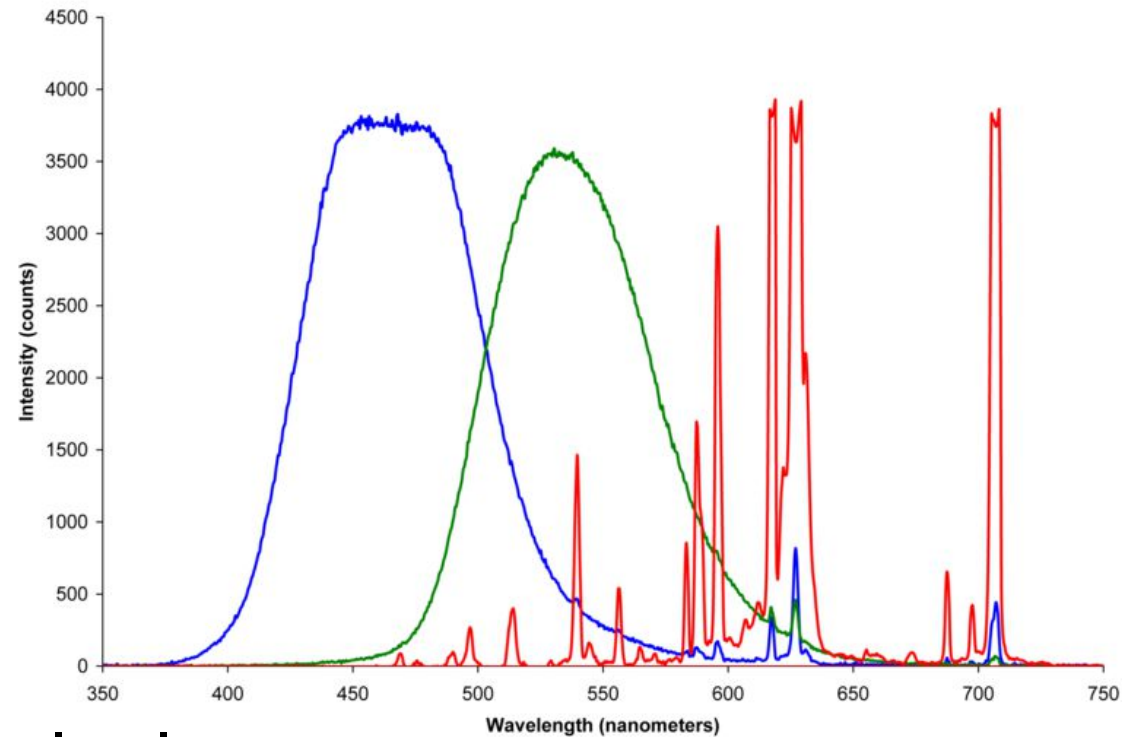


[from wikipedia]

# Spectral Composition

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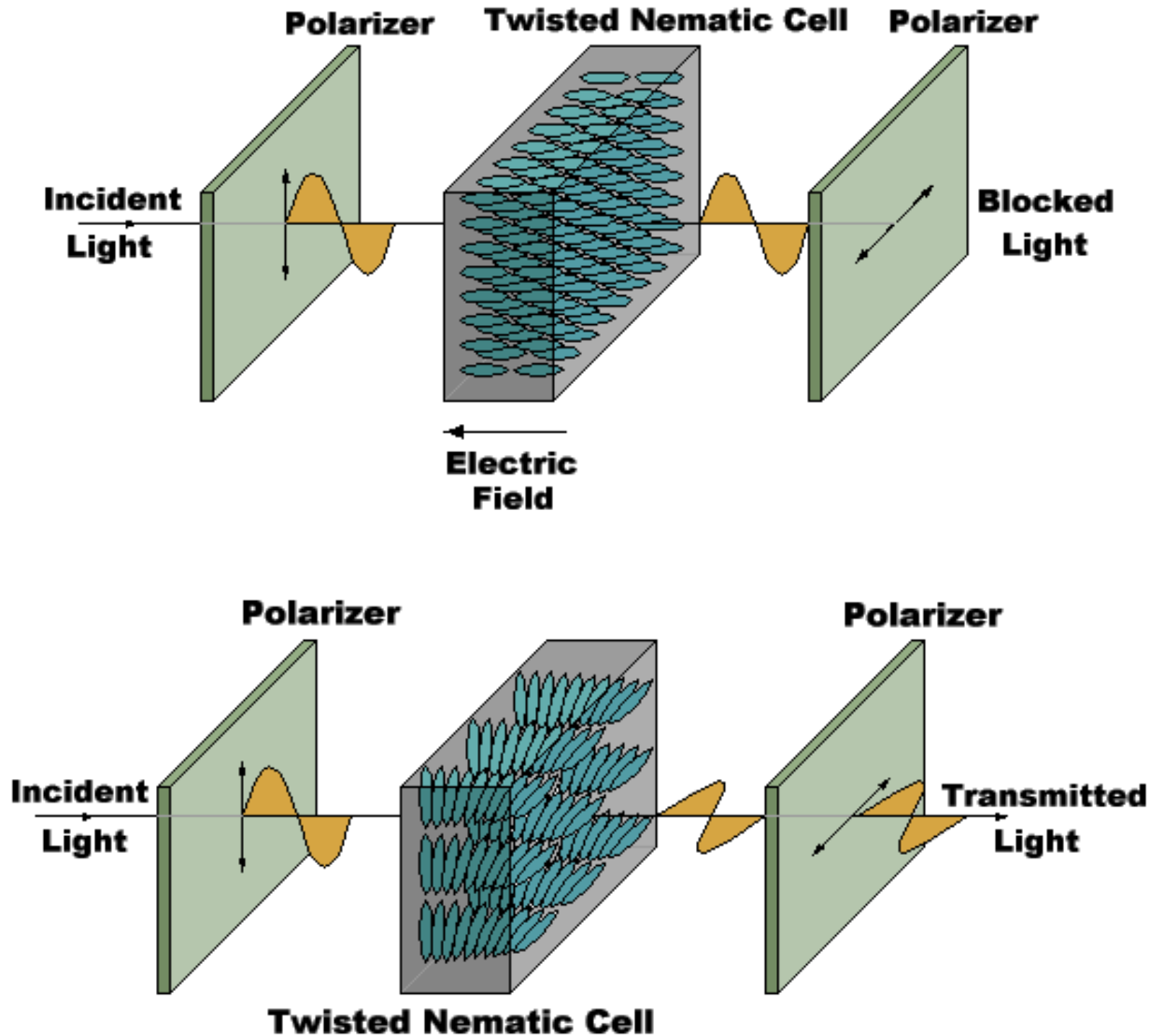
- ▶ three different phosphors



- ▶ saturated and natural colors
- ▶ inexpensive
- ▶ high contrast and brightness

[from wikipedia]

# Liquid Chrystal Displays (LCD)



# Twisted neumatic LC cell

TN Cell

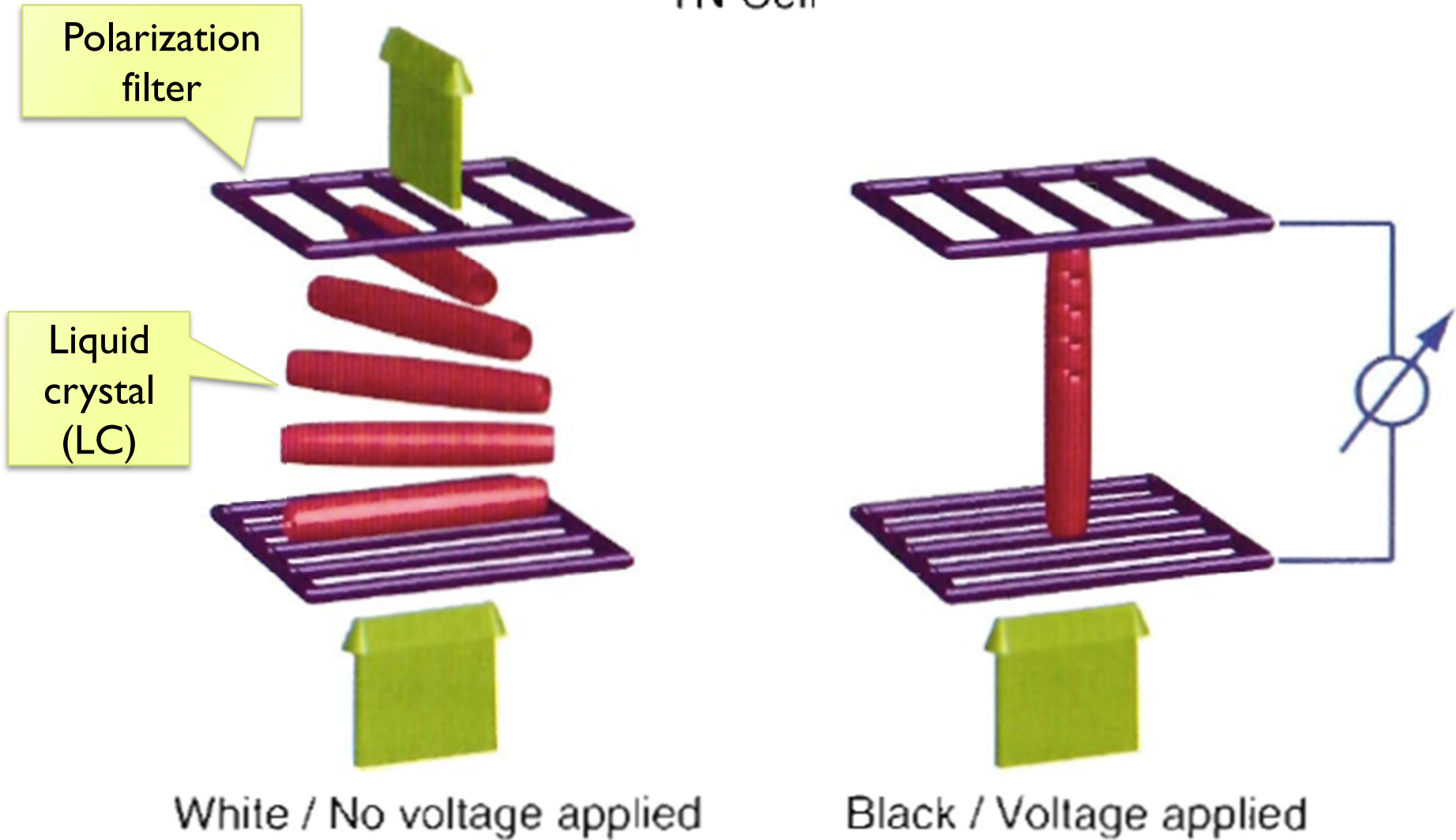


Figure from: High Dynamic Range Imaging by E. Reinhard et al.

# In-plane switching cell (IPS)

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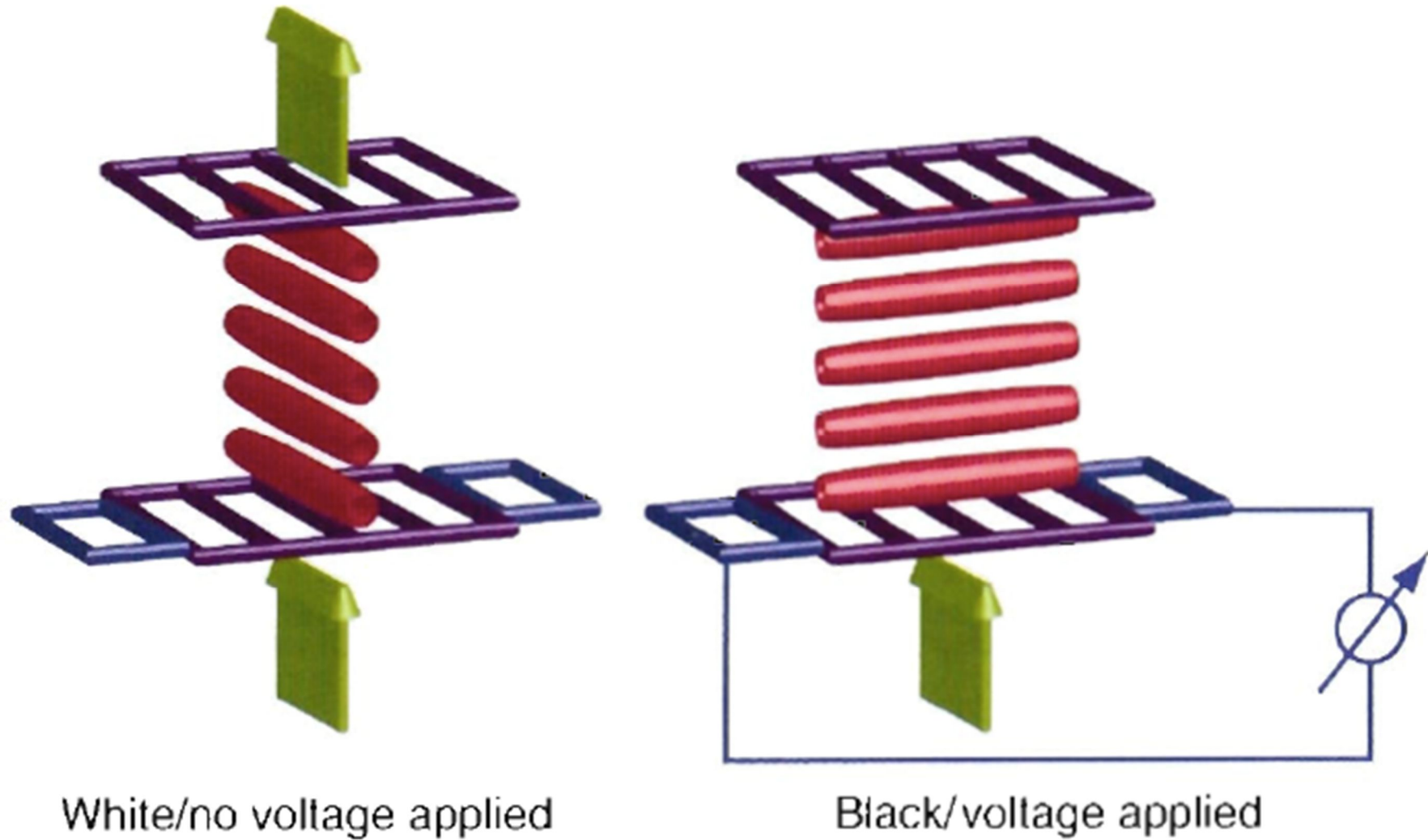
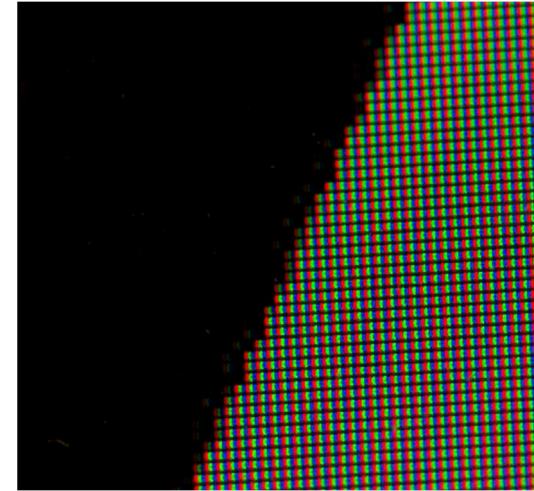
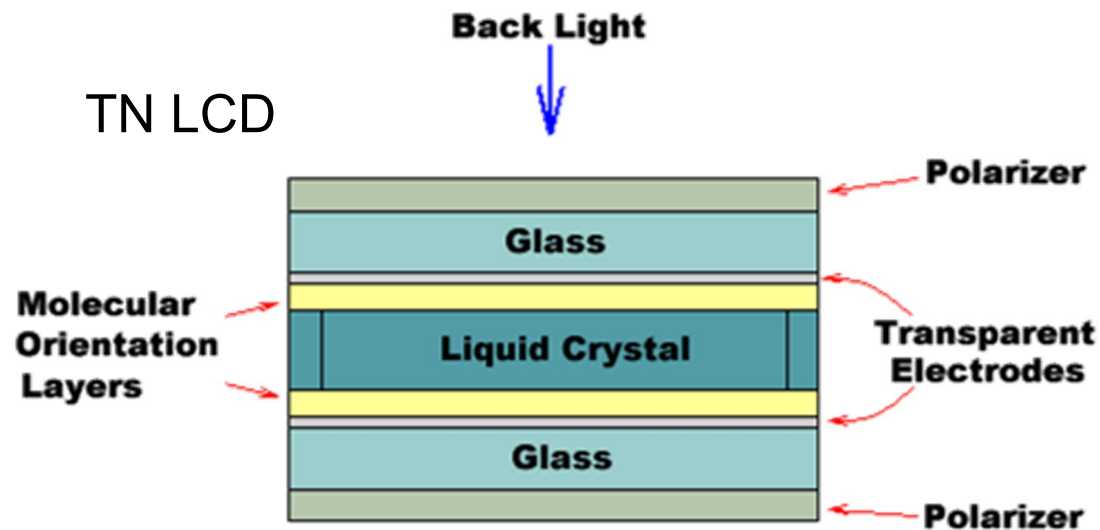


Figure from: High Dynamic Range Imaging by E. Reinhard et al.

# LCD

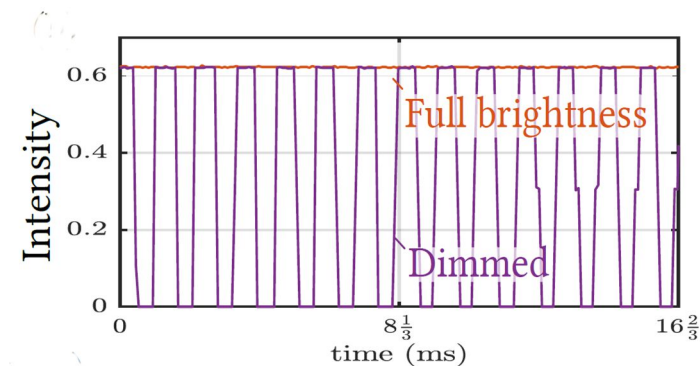
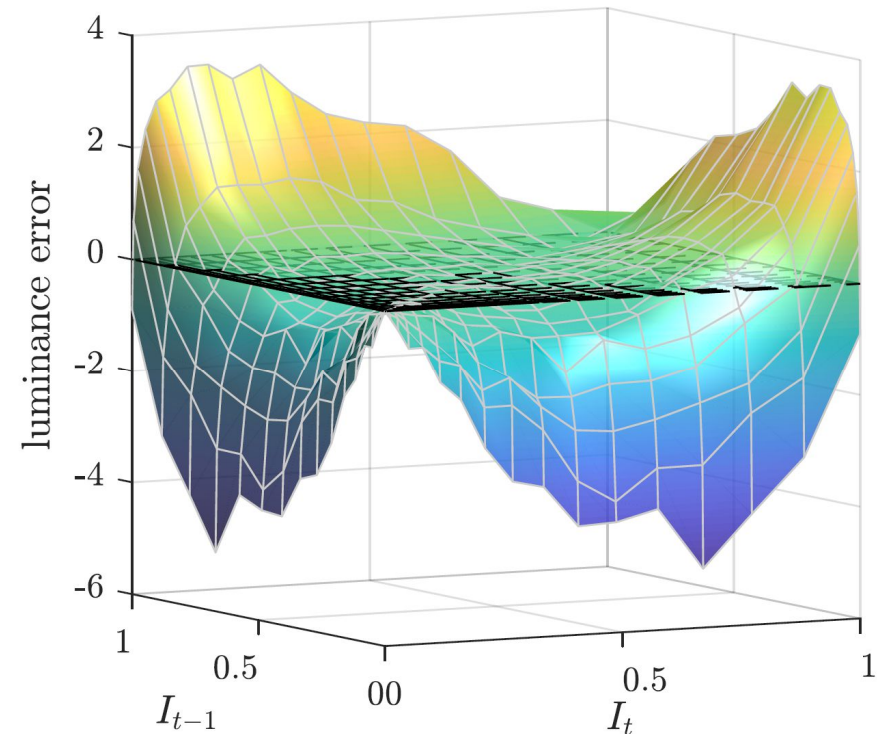


A white slanted edge (photograph)

- ▶ color may change with the viewing angle
- ▶ contrast up to 3000:1
- ▶ higher resolution results in smaller fill-factor
- ▶ color LCD transmits only up to 8% (more often close to 4-5%) light when set to full white

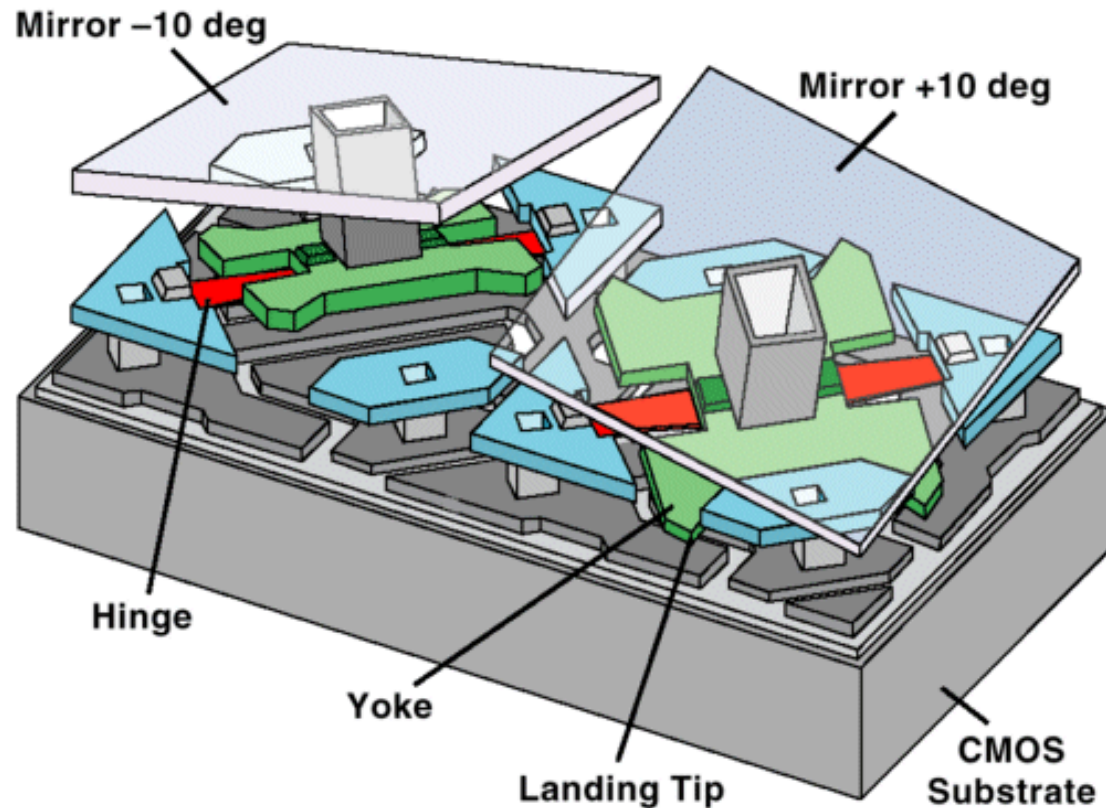
# LCD temporal response

- ▶ Experiment on an IPS LCD screen
- ▶ We rapidly switched between two intensity levels at 120Hz
- ▶ Measured luminance integrated over  $I_s$
- ▶ The top plot shows the difference between expected ( $\frac{I_{t-1}+I_t}{2}$ ) and measured luminance
- ▶ The bottom plot: intensity measurement for the full brightness and half-brightness display settings
  - ▶ Pulse-Width Modulation controls brightness of the backlight



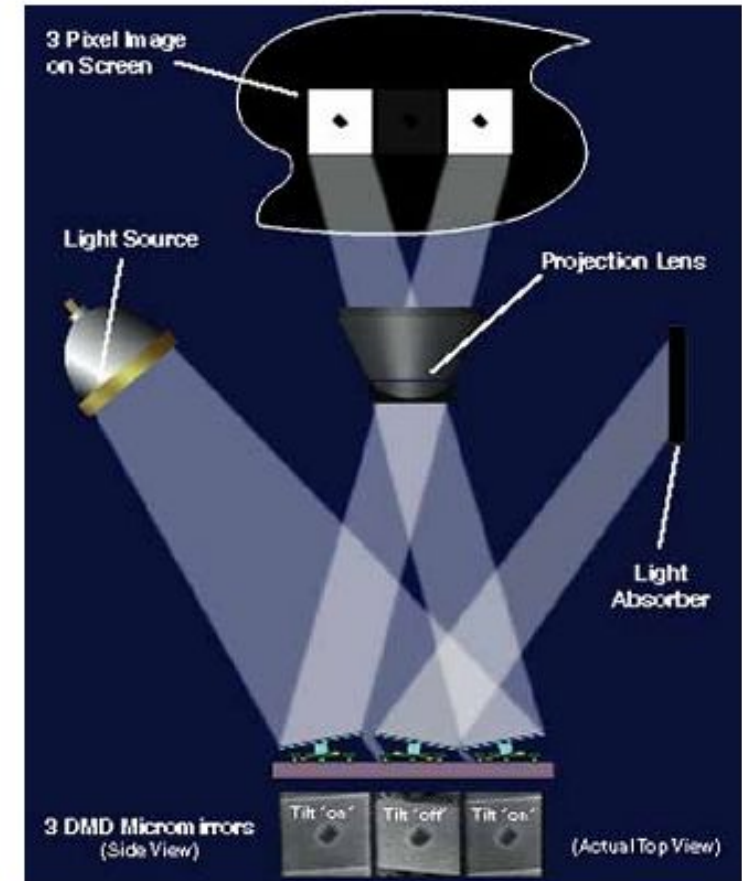


# Digital Micromirror Devices (DMDs/DLP)



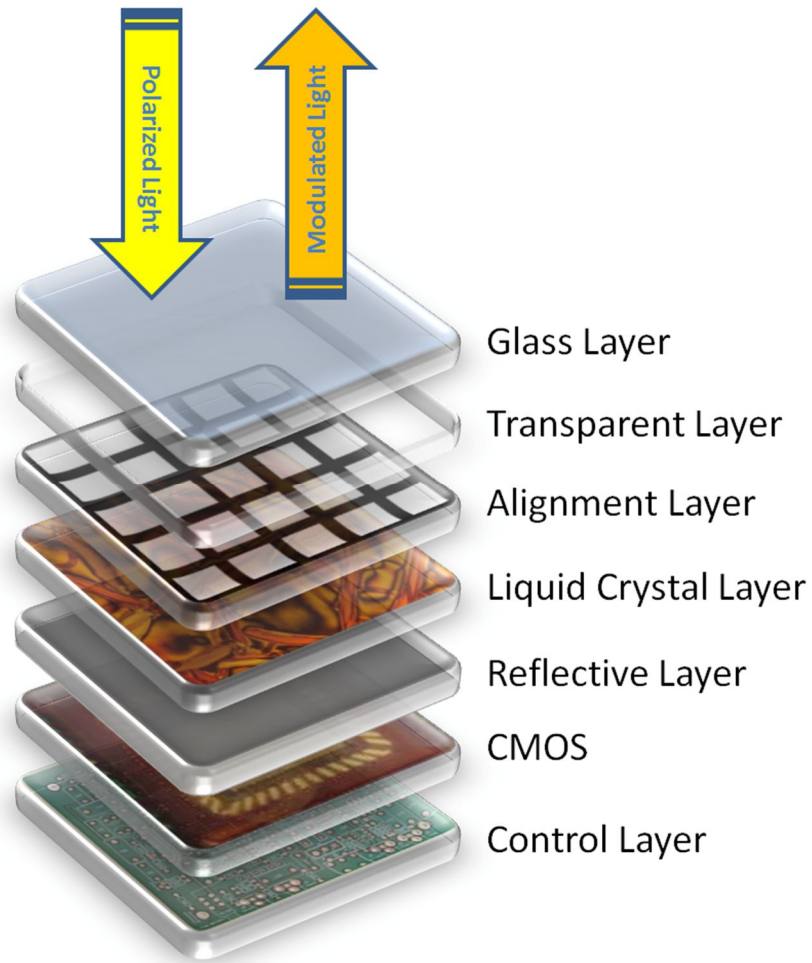
[Texas Instruments](#)

- ▶ 2-D array of mirrors
- ▶ Truly digital pixels
- ▶ Grey levels via Pulse-Width Modulation



# Liquid Crystal on Silicon (LCoS)

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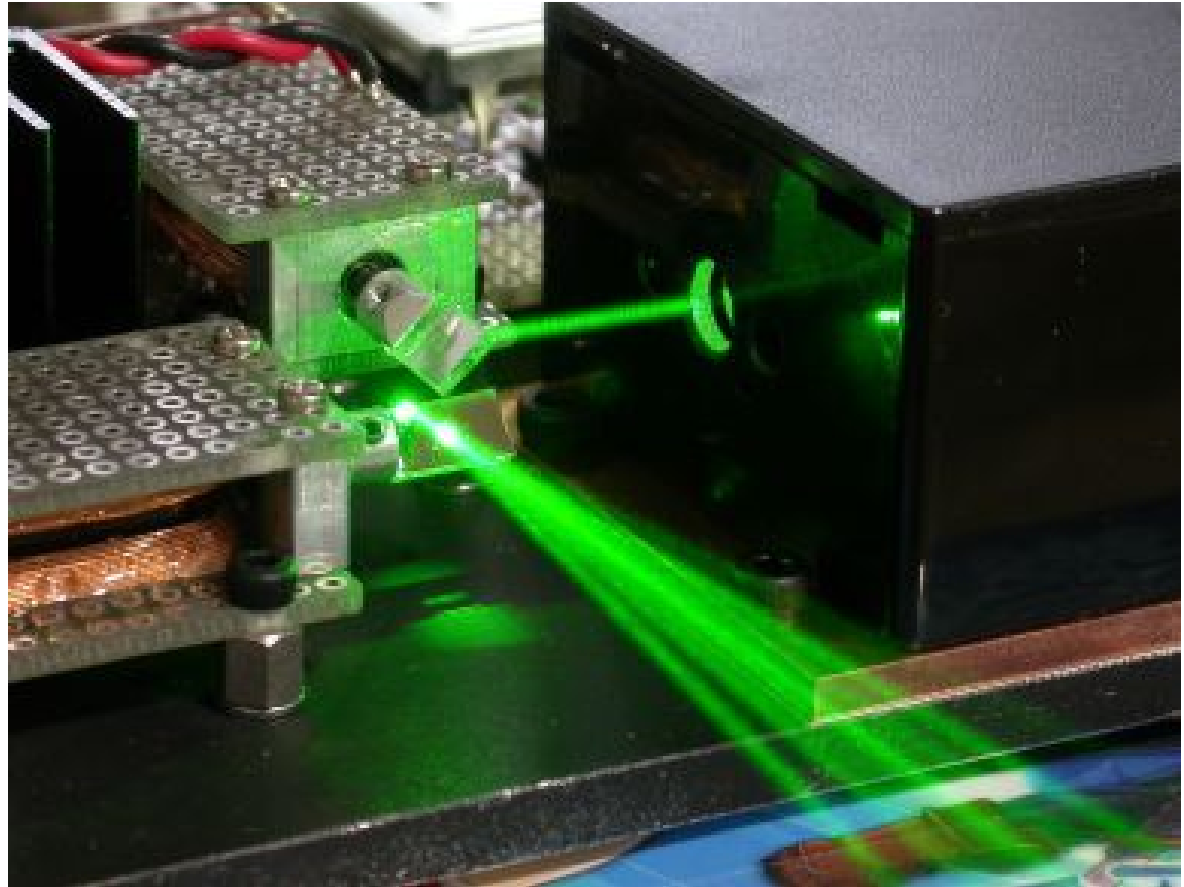


- ▶ basically a reflective LCD
- ▶ standard component in projectors and head mounted displays
- ▶ used e.g. in Google Glass

# Scanning Laser Projector

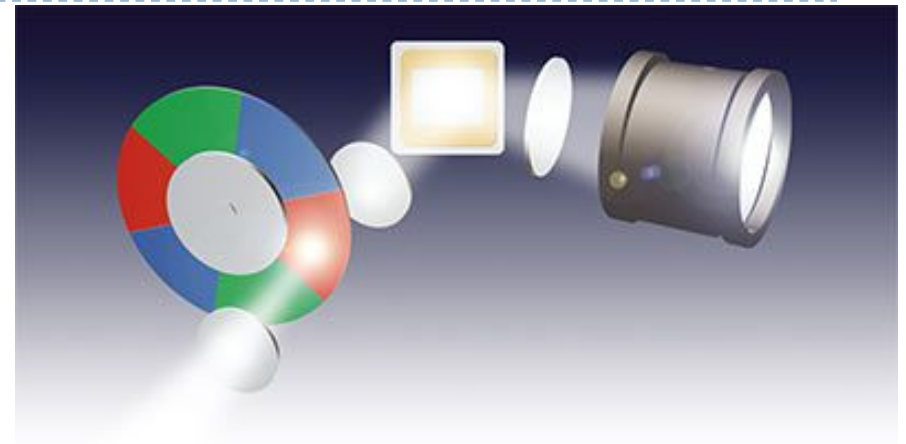
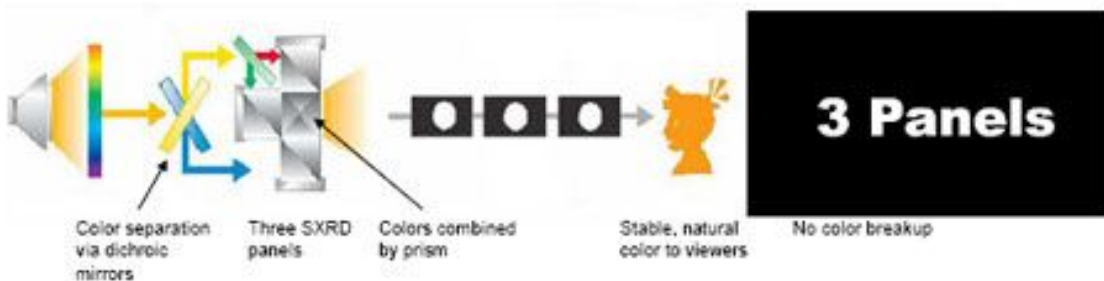
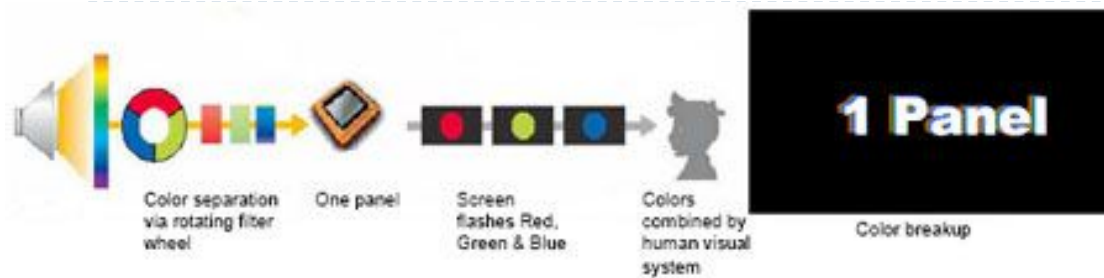
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- ▶ maximum contrast
- ▶ scanning rays
  
- ▶ very high power lasers needed for high brightness

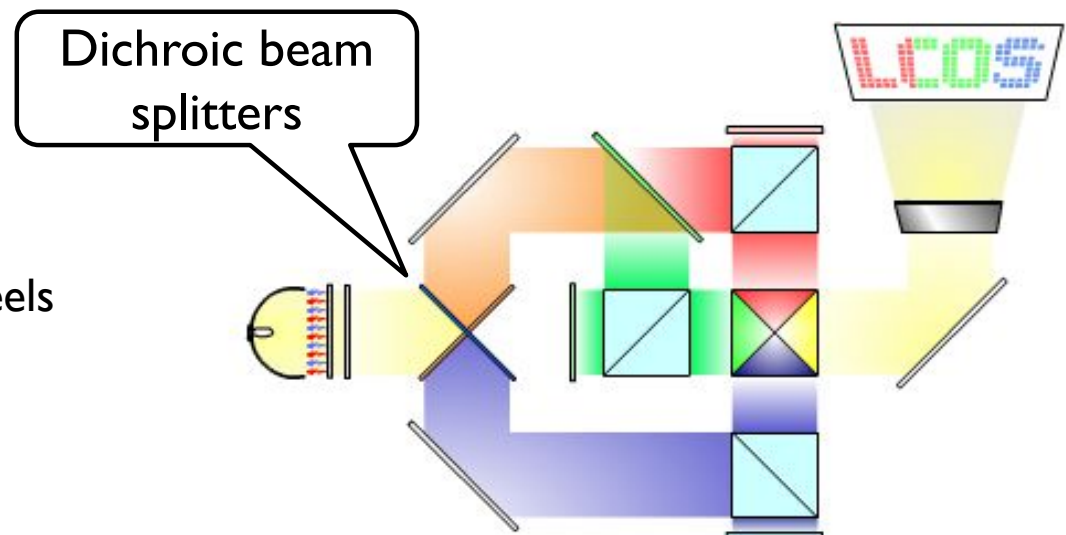


[http://elm-chan.org/works/vlp/report\\_e.html](http://elm-chan.org/works/vlp/report_e.html)

# 3-chip vs. Color Wheel Display

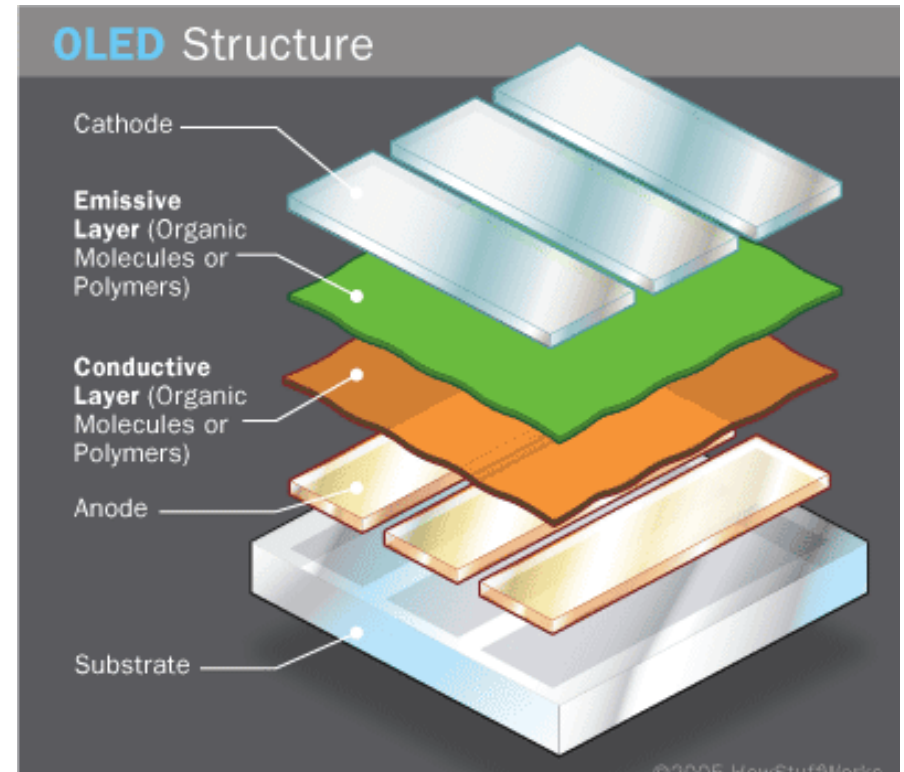


- ▶ color wheel
  - ▶ cheap
  - ▶ time sequenced colors
  - ▶ color fringes with motion/video
    - ▶ mitigated with advanced colour wheels
- ▶ 3-chip
  - ▶ complicated setup
  - ▶ no color fringes



# OLED

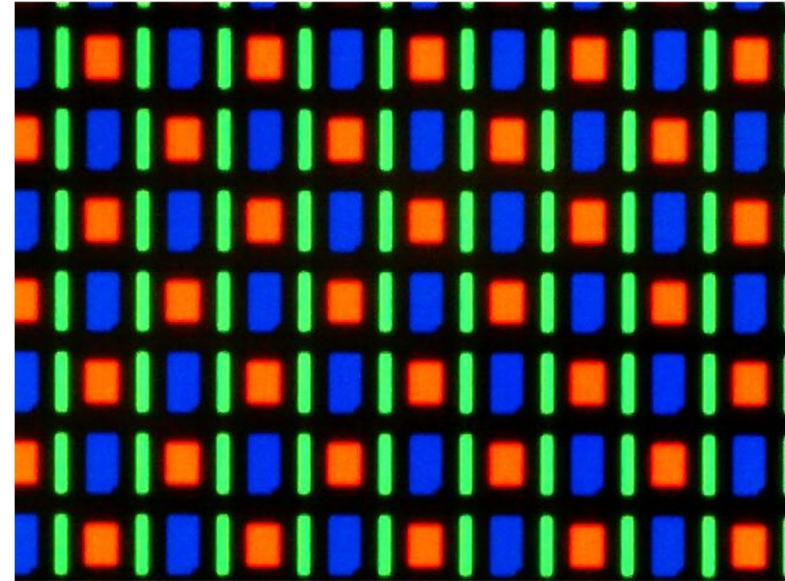
- ▶ based on electrophosphorescence
  - ▶ large viewing angle
  - ▶ the power consumption varies with the brightness of the image
  - ▶ fast ( $< 1$  microsec)
  - ▶ arbitrary sizes
- 
- ▶ life-span can be short
    - ▶ Worst for blue OLEDs



# Active matrix OLED

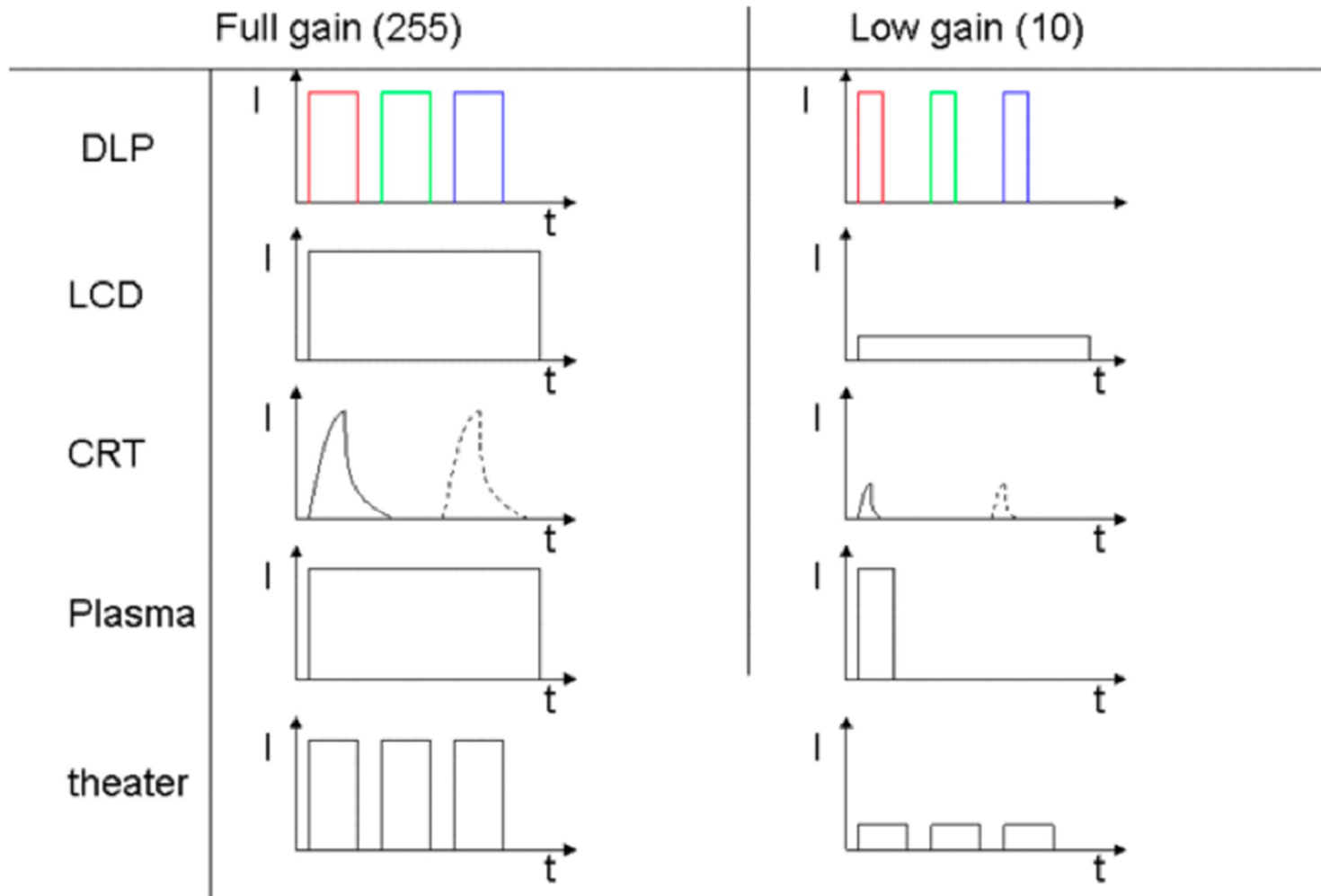
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- ▶ Commonly used in mobile phones (AMOLED)
- ▶ Very good contrast
  - ▶ But the screen more affected by glare than LCD
- ▶ But limited brightness
  - ▶ The brighter is OLED, the shorter is its live-span



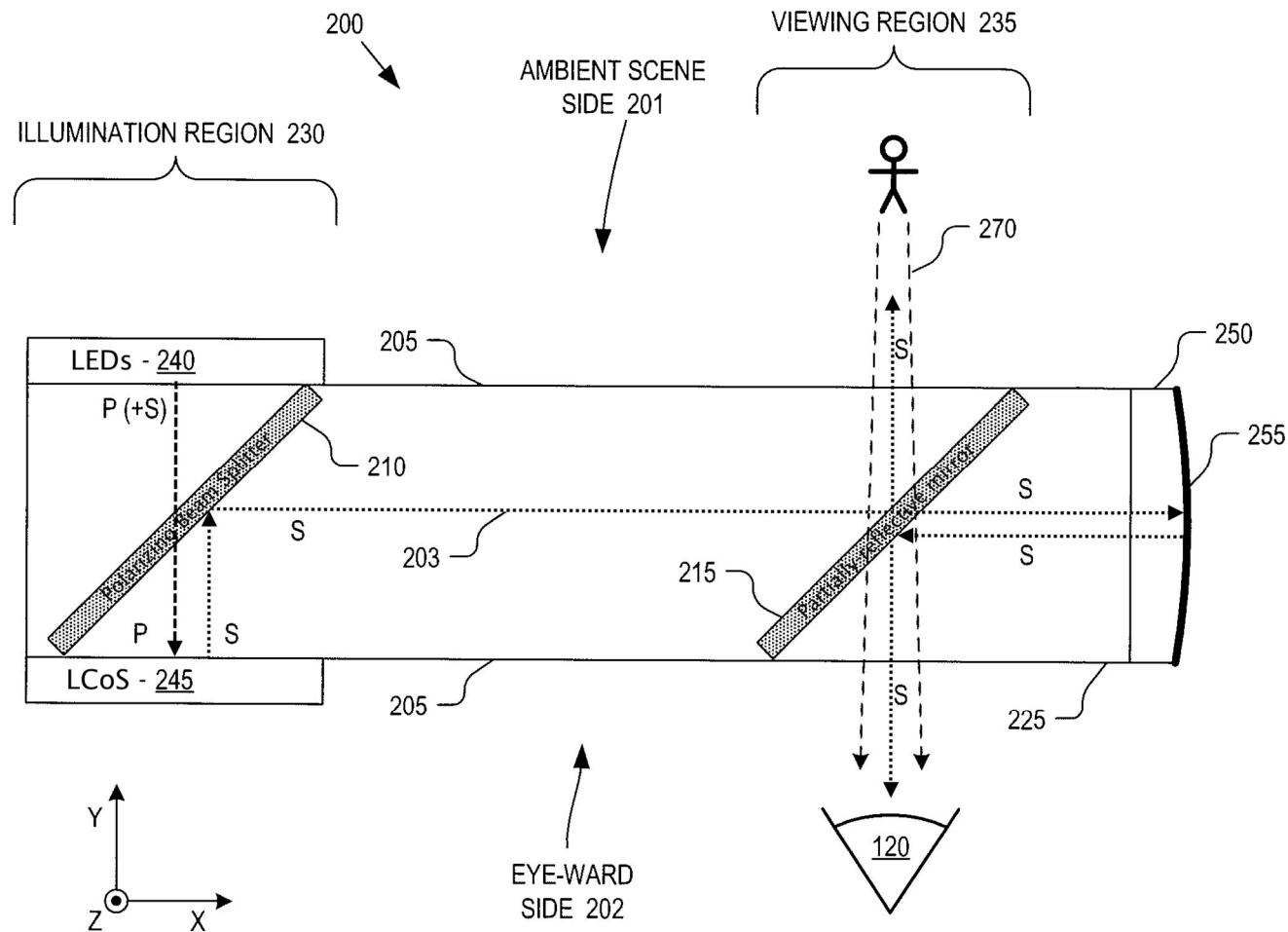
# Temporal characteristic

A single uniform white frame @24/25/30 Hz





# Bird-bath optics for near-eye displays



Google Glass

Pros:

- Simple, efficient design

Cons:

- Cannot be scaled up easily

More reading: <https://kgutttag.com/2017/03/03/near-eye-bird-bath-optics-pros-and-cons-and-immys-different-approach/>



# Diffraction waveguides

US 2016/0116739

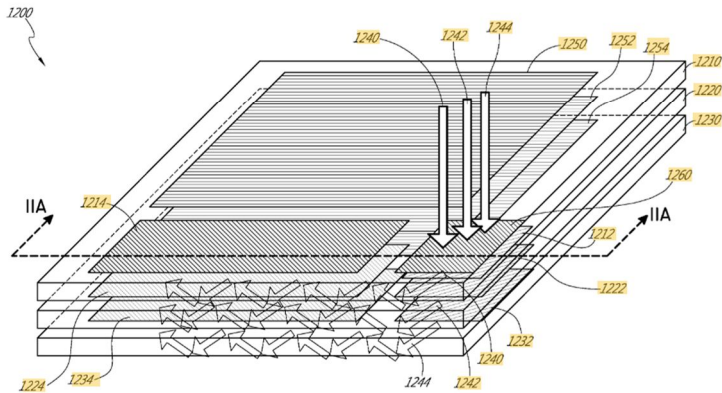
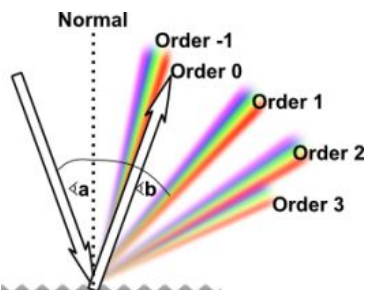
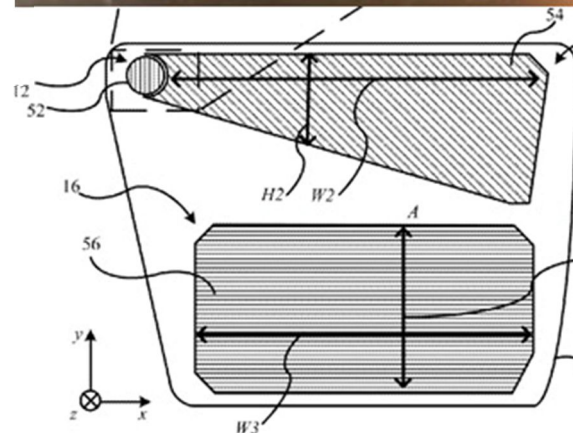
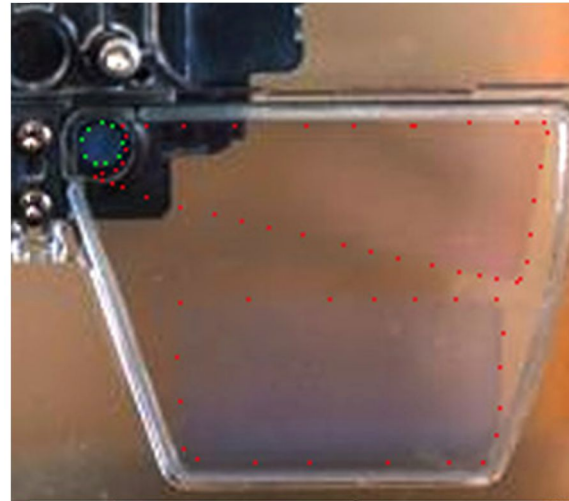


FIG. IIB

Magic Leap



[http://www.fdu.edu/~photonics/experiments\\_new/Sem001\\_Hydrogen/02TheoreticalBackground.html](http://www.fdu.edu/~photonics/experiments_new/Sem001_Hydrogen/02TheoreticalBackground.html)



US 2016/0231568

Fig. 3B

Microsoft HoloLens



US 20160231568A1

(19) **United States**

(12) **Patent Application Publication** (10) **Pub. No.:** US 2016/0231568 A1  
 Saarikko et al. (43) **Pub. Date:** Aug. 11, 2016

(54) **WAVEGUIDE** (52) **U.S. CL.**  
 CPC ..... G02B 27/0172 (2013.01); G02B 6/0035 (2013.01); G02B 5/1842 (2013.01); G02B 2027/011 (2013.01); G02B 2027/0178 (2013.01)

(71) Applicant: **Microsoft Technology Licensing, L.L.C.**, Redmond, WA (US)

(72) Inventors: **Pasi Saarikko**, Espoo (FI); **Pasi Kostamo**, Espoo (FI)

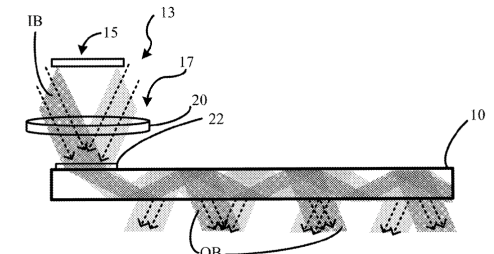
(21) Appl. No.: **14/617,697**

(22) Filed: **Feb. 9, 2015**

**Publication Classification**

(51) **Int. Cl.**  
 G02B 27/01 (2006.01)  
 G02B 5/18 (2006.01)  
 F21V 8/00 (2006.01)

(57) **ABSTRACT**  
 A waveguide has a front and a rear surface, the waveguide for a display system and arranged to guide light from a light engine onto an eye of a user to make an image visible to the user, the light guided through the waveguide by reflection at the front and rear surfaces. A first portion of the front or rear surface has a structure which causes light to change phase upon reflection from the first portion by a first amount. A second portion of the same surface has a different structure which causes light to change phase upon reflection from the second portion by a second amount different from the first amount. The first portion is offset from the second portion by a distance which substantially matches the difference between the second amount and the first amount.

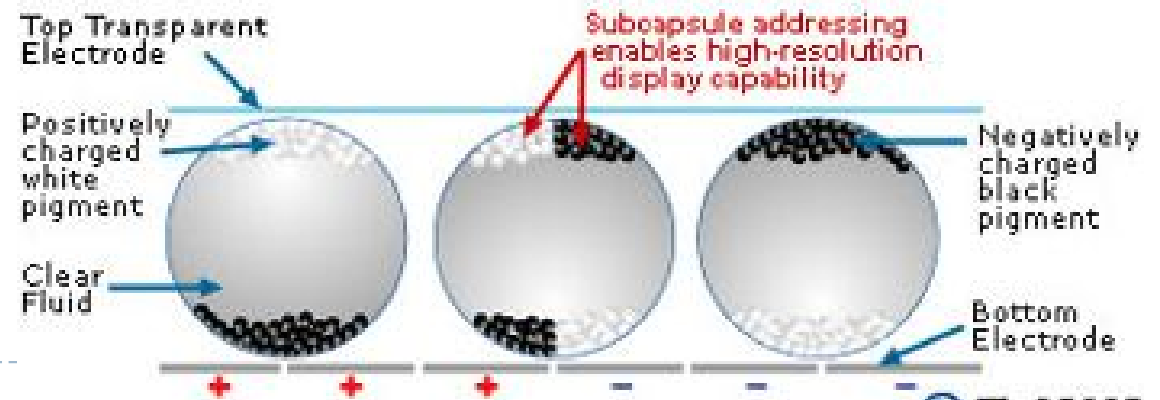


# Electronic Paper

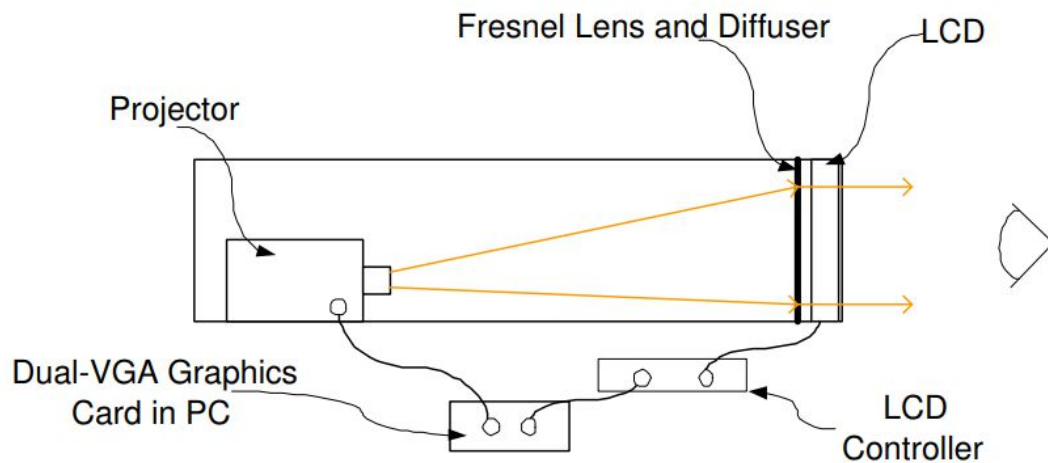
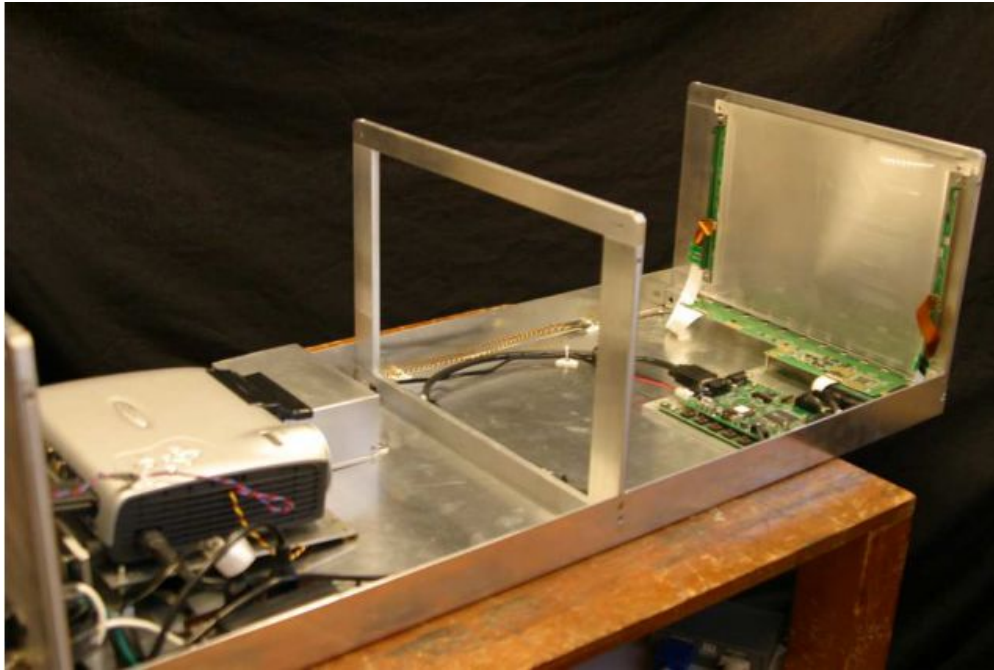


[www.eink.com](http://www.eink.com)

## Cross Section of Electronic-Ink Microcapsules



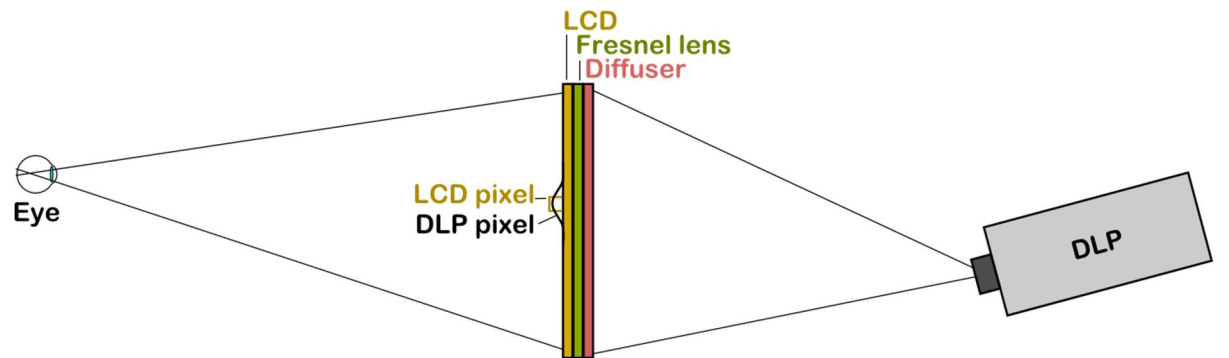
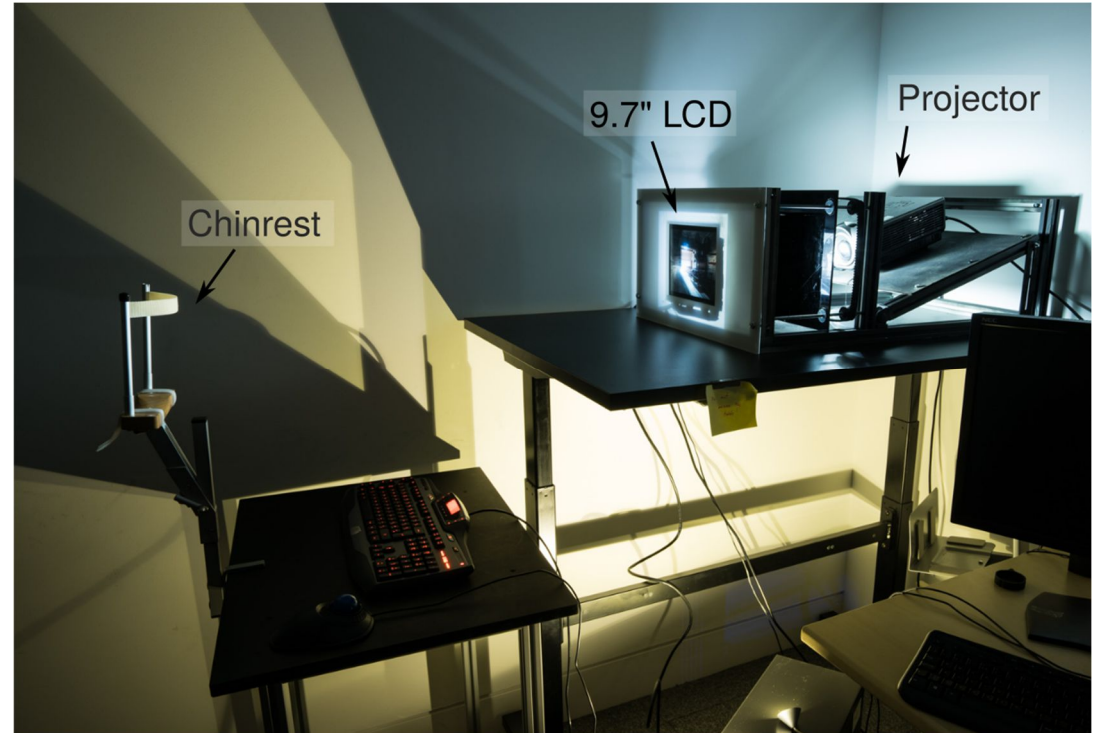
# Prototype HDR display (2004)



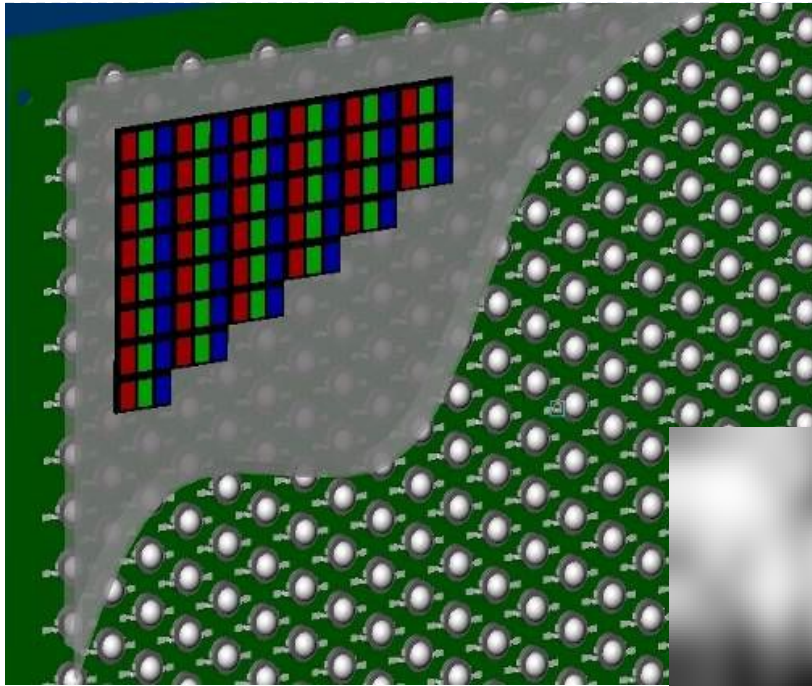
From [Seetzen et al. SIGGRAPH 2004]

# Cambridge experimental HDR display

- ▶ 35,000 cd/m<sup>2</sup> peak luminance
- ▶ 0.01 cd/m<sup>2</sup> black level
- ▶ LCD resolution: 2048x1536
- ▶ Backlight (DLP) resolution: 1024x768
- ▶ Geometric-calibration with a DSLR camera
- ▶ Display uniformity compensation
- ▶ Bit-depth of DLP and LCD extended to 10 bits using spatio-temporal dithering



# Modern HDR displays



- Modulated LED array
- Conventional LCD
- Image compensation

$$\text{Low resolution LED Array} \times \text{High resolution Colour Image} = \text{High Dynamic Range Display}$$

# HDR Display

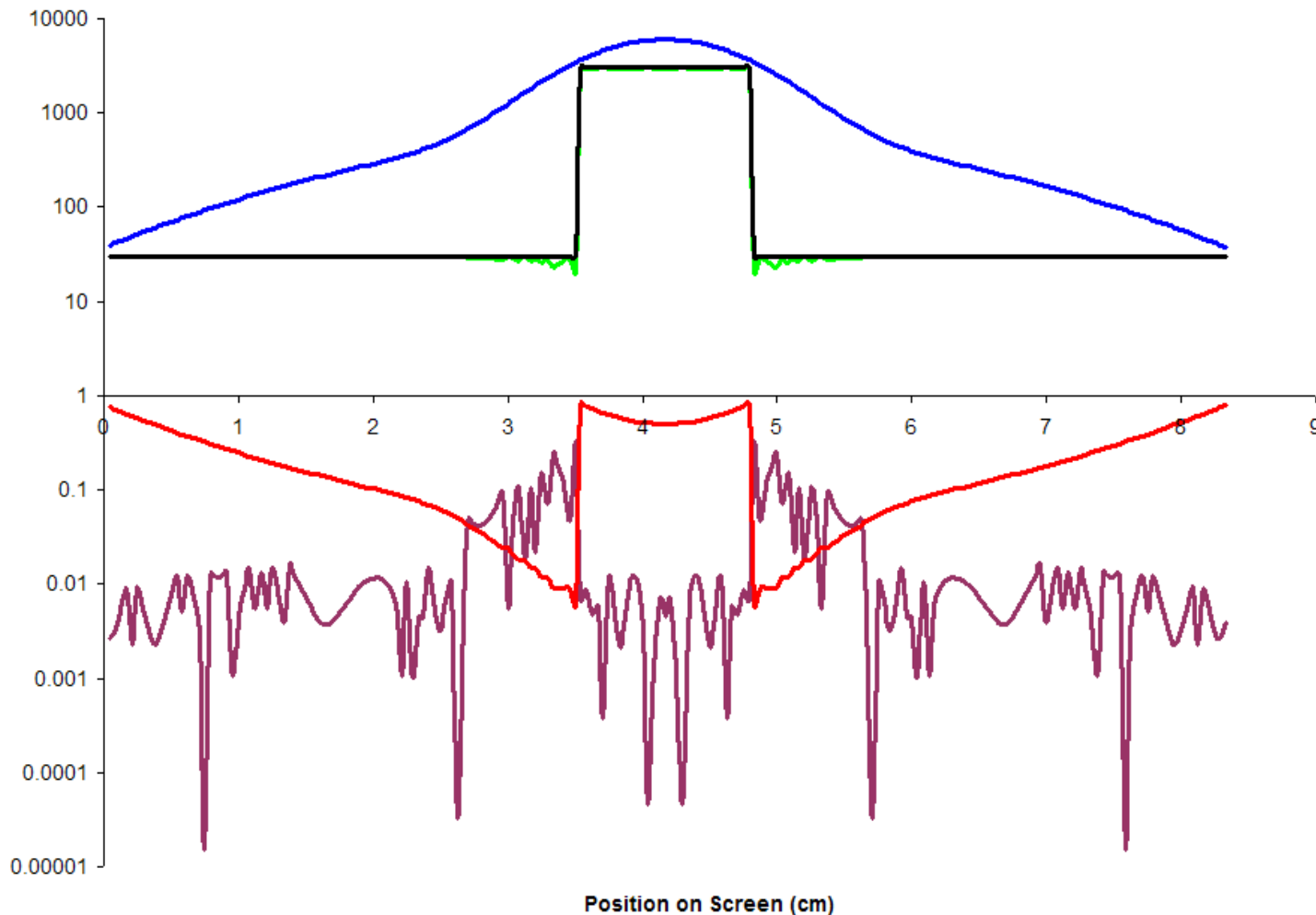
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- ▶ **Two spatial modulators**
  - ▶ 1st modulator contrast 1000:1
  - ▶ 2nd modulator contrast 1000:1
  - ▶ Combined contrast 1000,000:1
- ▶ **Idea: Replace constant backlight of LCD panels with an array of LEDs**
  - ▶ Very few (about 1000) LEDs sufficient
  - ▶ Every LED intensity can be set individually
  - ▶ Very flat form factor (fits in standard LCD housing)
- ▶ **Issue:**
  - ▶ LEDs larger than LCD pixels
  - ▶ This limits maximum local contrast



# Veiling Luminance

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Receive Image

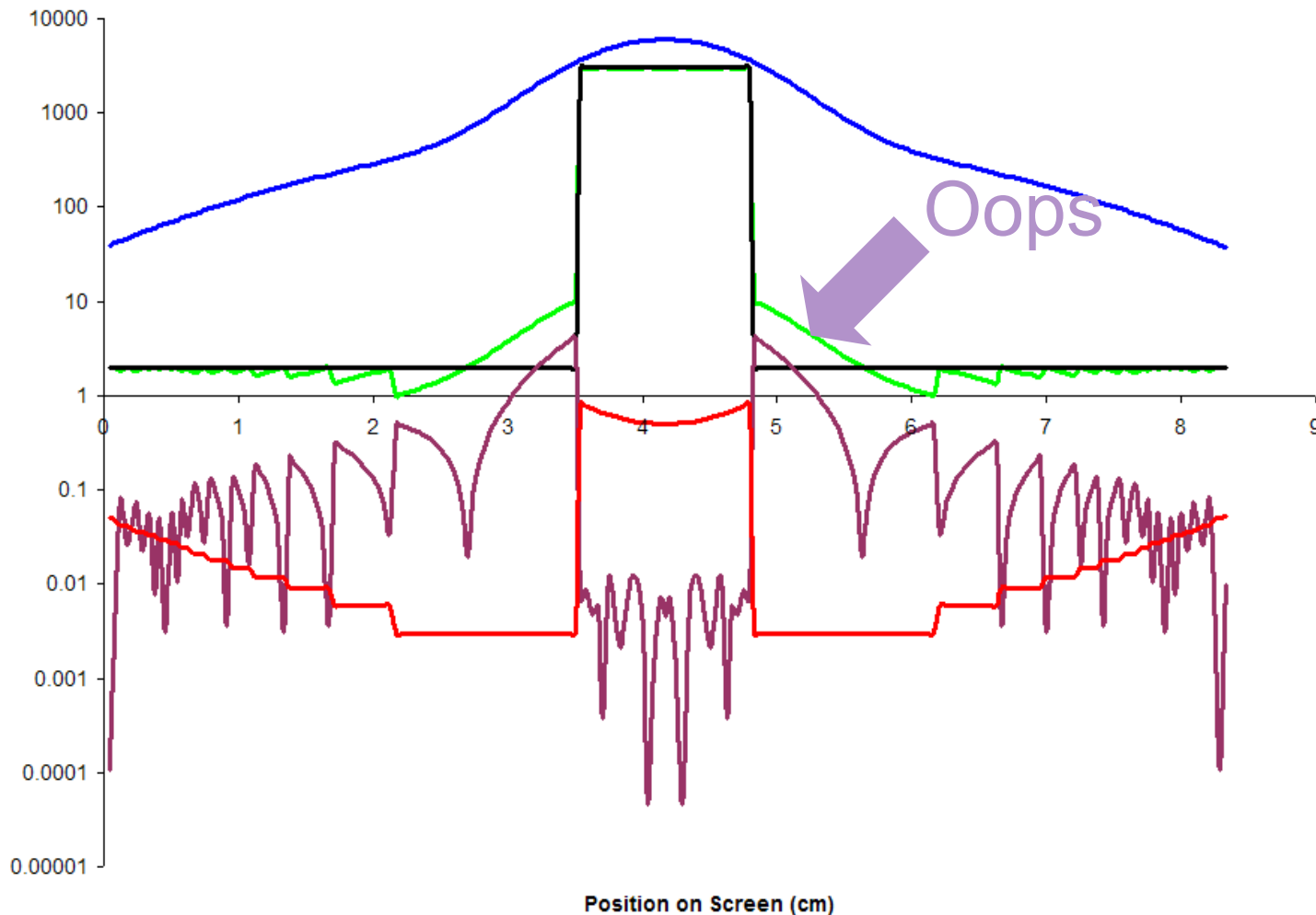
Drive LED

Divide Image by  
LED light field to  
obtain LCD values

Output Luminance  
is the product of  
LED light field and  
LCD transmission  
(modest error)

# Veiling Luminance

---



Receive Image

Drive LED

Divide Image by  
LED light field to  
obtain LCD values

Output Luminance  
is the product of  
LED light field and  
LCD transmission  
(Problematic error)

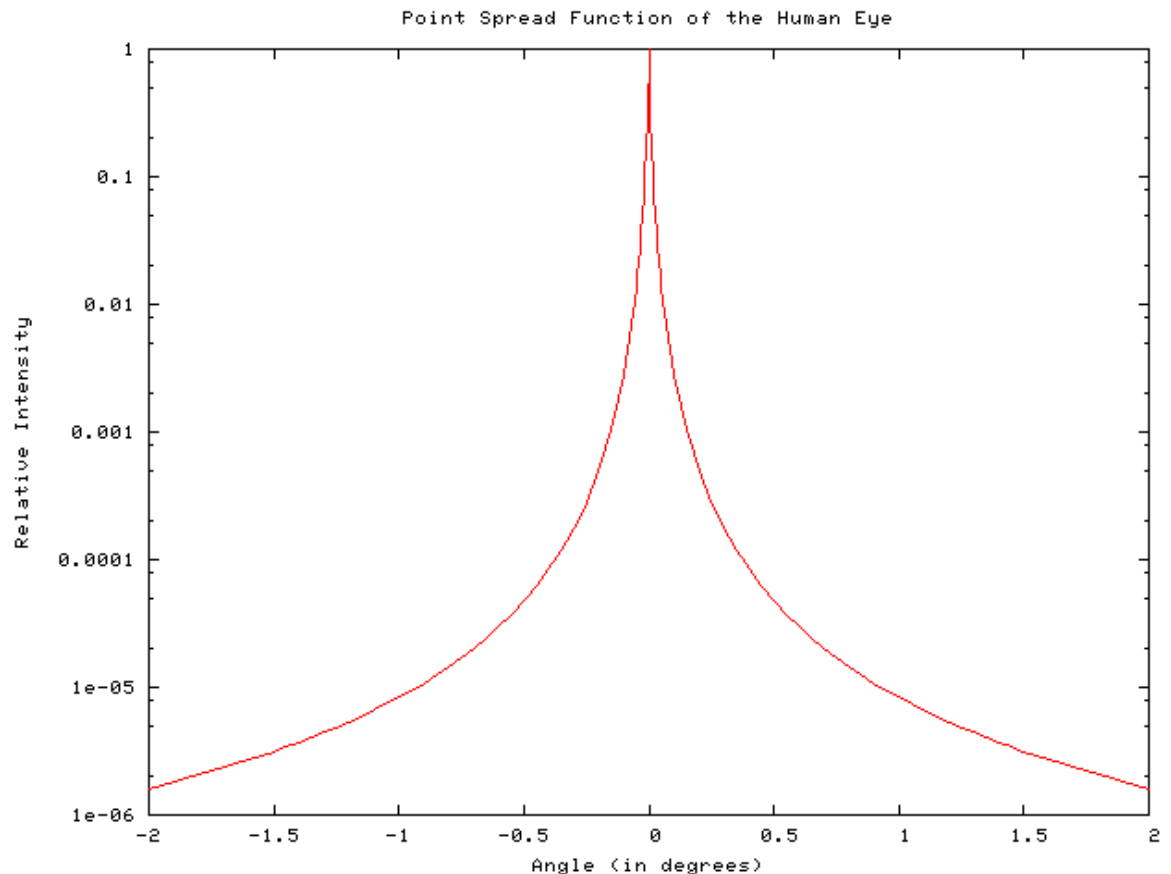
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# Veiling Luminance

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- ▶ **Maximum perceivable contrast**
  - ▶ Globally very high (5-6 orders of magnitude)
    - ▶ That is why we create these displays!
  - ▶ Locally can be low: 150:1
- ▶ **Point-spread function of human eye**
  - ▶ Refer to „HDR and tone mapping” lecture
  - ▶ Consequence: high contrast edges cannot be perceived at full contrast

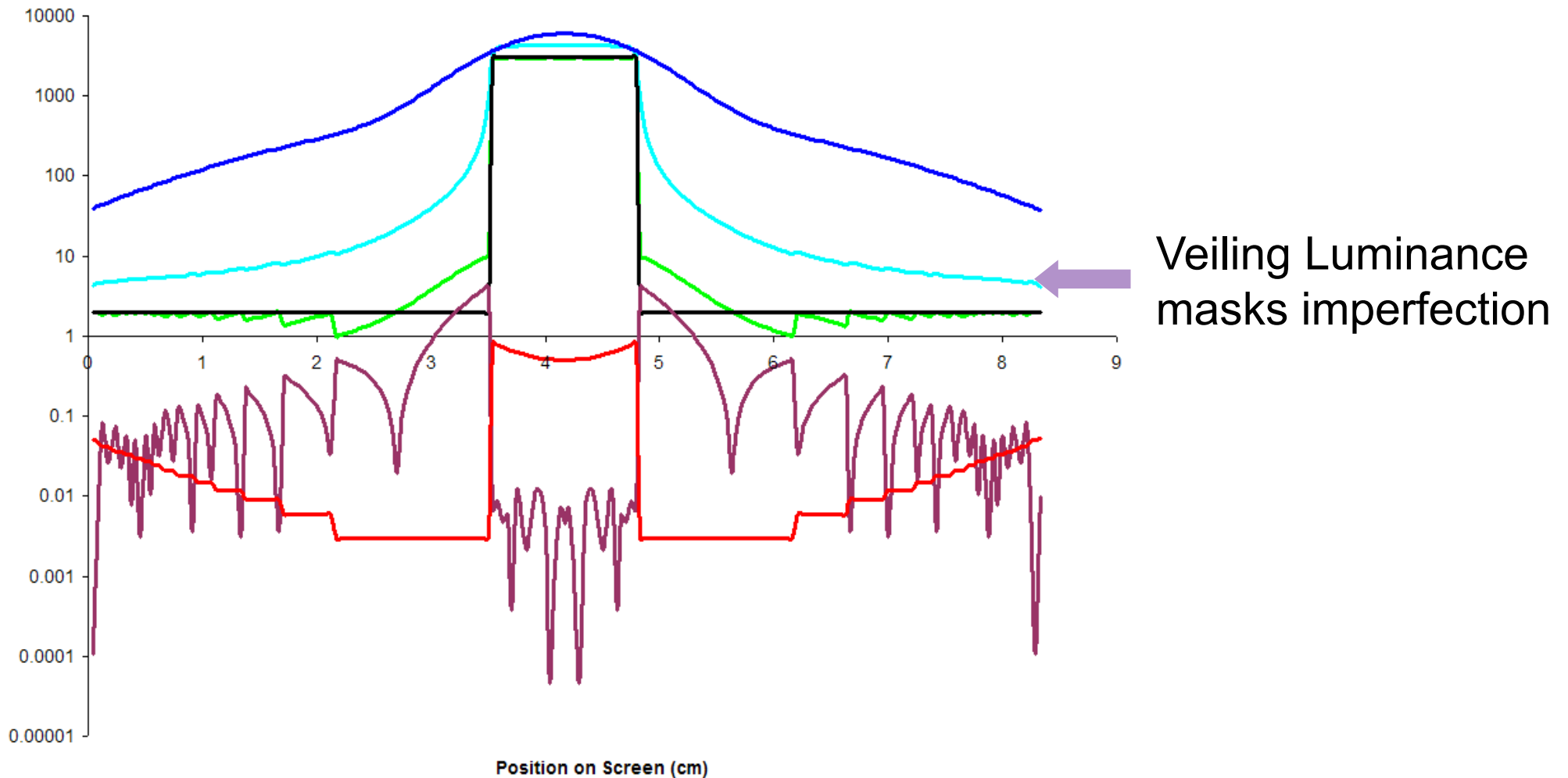


# Veiling Glare (Camera)

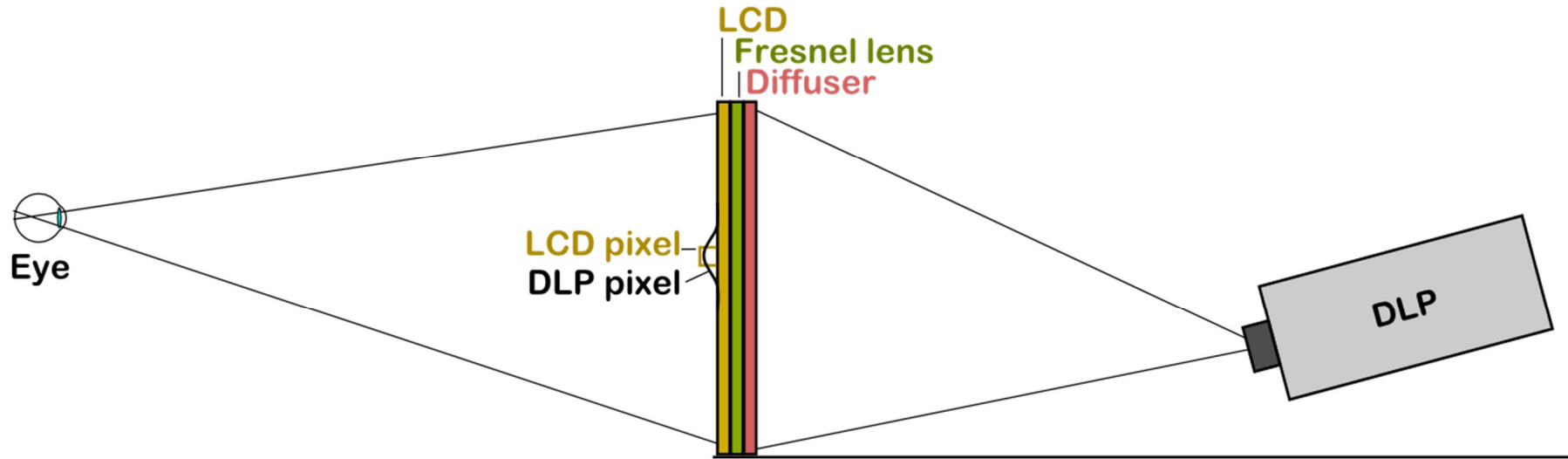


# Veiling Luminance

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# HDR rendering algorithm - high level



Desired image

DLP blur (PSF)

$$\operatorname{argmin}_{L,D} \|I(x,y) - g * D(x,y)L(x,y)\|_2$$

DLP image

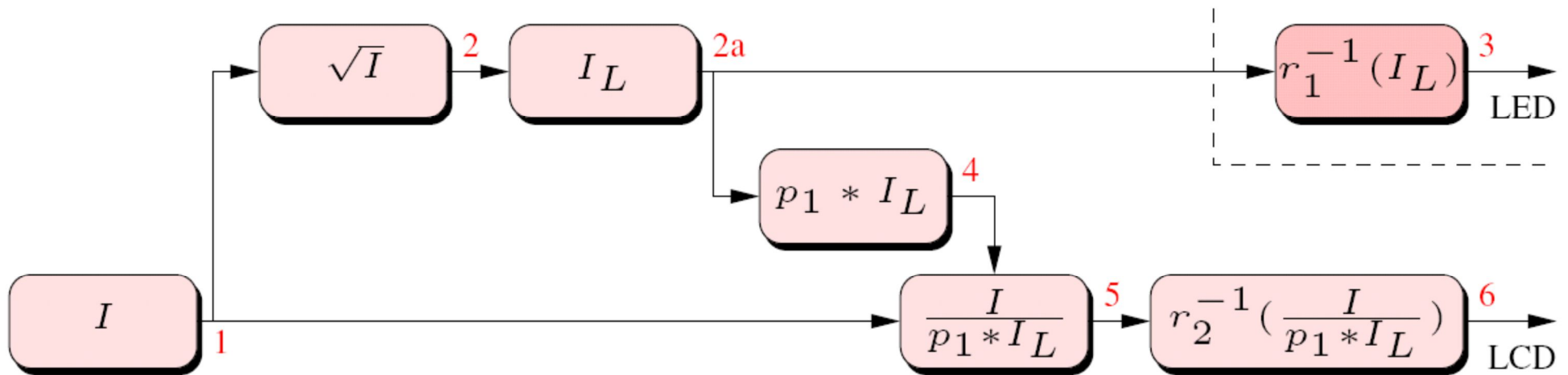
LCD image

Subject to:

$$\forall(x,y) \quad L_{min} \leq L(x,y) \leq L_{max}$$

$$\forall(x,y) \quad D_{min} \leq D(x,y) \leq D_{max}$$

# Simplified HDR rendering algorithm



# Rendering Algorithm

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# References

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- ▶ HAINICH, R.R.AND BIMBER, O. 2011. *Displays: Fundamentals and Applications*. CRC Press.
- ▶ SEETZEN, H., HEIDRICH, W., STUERZLINGER, W., ET AL. 2004. High dynamic range display systems. *ACM Transactions on Graphics* 23, 3, 760.
- ▶ Visual motion test for high-frame-rate monitors:
  - ▶ <https://www.testufo.com/>