

Randomised Algorithms

Lecture 7: Linear Programming: Simplex Algorithm

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Simplex Algorithm by Example

Details of the Simplex Algorithm

Finding an Initial Solution

Appendix: Cycling and Termination (non-examinable)

Simplex Algorithm: Introduction

Simplex Algorithm

- classical method for solving linear programs (Dantzig, 1947)
- usually fast in practice although worst-case runtime not polynomial
- iterative procedure somewhat similar to Gaussian elimination

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Basic Idea:

- Each iteration corresponds to a “basic solution” of the slack form
- All non-basic variables are 0, and the basic variables are determined from the equality constraints
- Each iteration converts one slack form into an equivalent one while the objective value will not decrease
- Conversion (“pivoting”) is achieved by switching the roles of one basic and one non-basic variable

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In that sense, it is a **greedy algorithm**.

Extended Example: Conversion into Slack Form

$$\begin{array}{rllllll} \text{maximise} & 3x_1 & + & x_2 & + & 2x_3 & & & & \\ \text{subject to} & & & & & & & & & \\ & x_1 & + & x_2 & + & 3x_3 & \leq & 30 & & \\ & 2x_1 & + & 2x_2 & + & 5x_3 & \leq & 24 & & \\ & 4x_1 & + & x_2 & + & 2x_3 & \leq & 36 & & \\ & & & x_1, x_2, x_3 & & & \geq & 0 & & \end{array}$$

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Conversion into slack form

$$\begin{array}{llllllll} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

Extended Example: Iteration 1

$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

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Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (0, 0, 0, 30, 24, 36)$

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This basic solution is **feasible**

Objective value is 0.

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Increasing the value of x_1 would increase the objective value.

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The third constraint is the tightest and limits how much we can increase x_1 .

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Switch roles of x_1 and x_6 :

- Solving for x_1 yields:

$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}.$$

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$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}.$$

- Substitute this into x_1 in the other three equations

Extended Example: Iteration 2

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

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Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (9, 0, 0, 21, 6, 0)$ with objective value 27

Extended Example: Iteration 2

Increasing the value of x_3 would increase the objective value.

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Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (9, 0, 0, 21, 6, 0)$ with objective value 27

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Increasing the value of x_3 would increase the objective value.

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$$x_3 = \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} - \frac{x_6}{8}.$$

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- Substitute this into x_3 in the other three equations

Extended Example: Iteration 3

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

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Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (\frac{33}{4}, 0, \frac{3}{2}, \frac{69}{4}, 0, 0)$ with objective value $\frac{111}{4} = 27.75$

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Increasing the value of x_2 would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

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The second constraint is the tightest and limits how much we can increase x_2 .

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- Solving for x_2 yields:

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3}.$$

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- Substitute this into x_2 in the other three equations

Extended Example: Iteration 4

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$

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Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (8, 4, 0, 18, 0, 0)$ with objective value 28

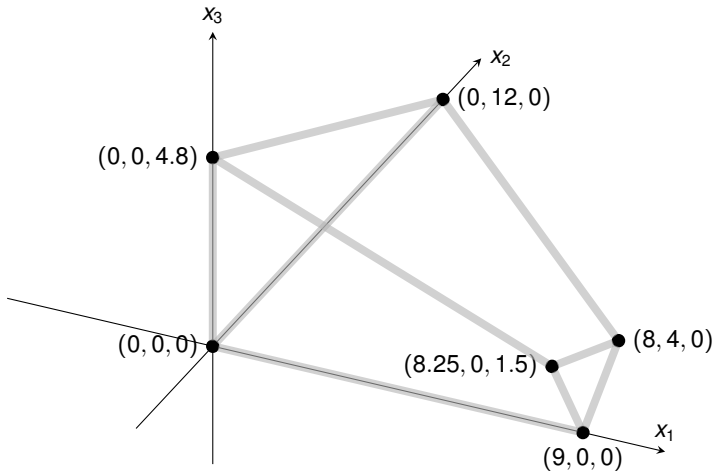
Extended Example: Iteration 4

All coefficients are negative, and hence this basic solution is **optimal!**

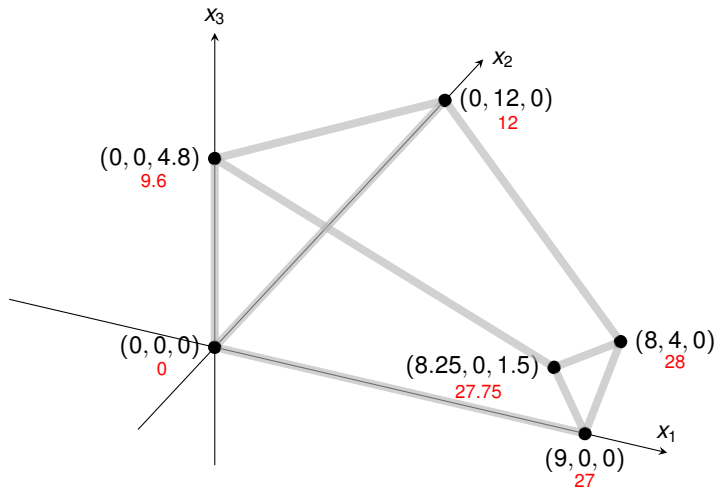
$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$

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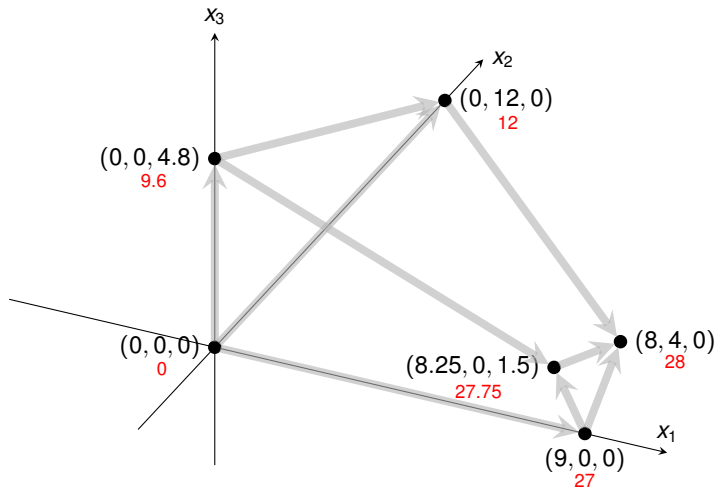
Extended Example: Visualization of SIMPLEX



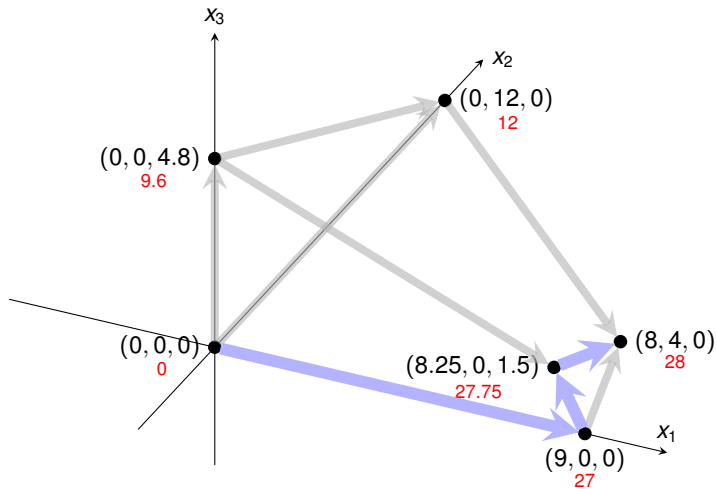
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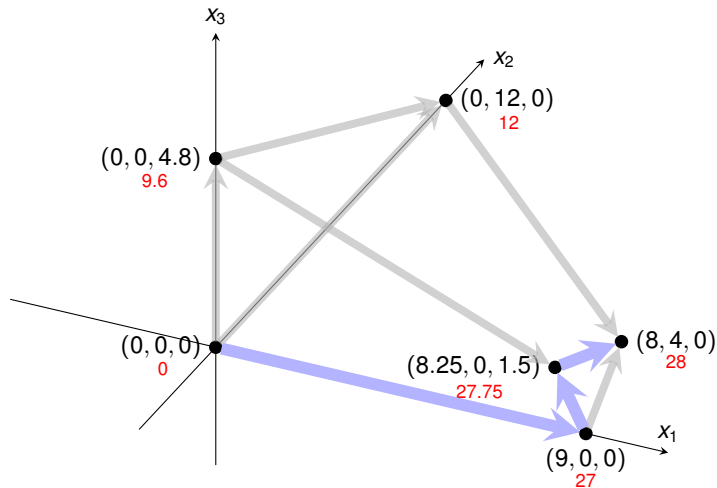
Extended Example: Visualization of SIMPLEX



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Extended Example: Visualization of SIMPLEX



Exercise: How many basic solutions (including non-feasible ones) are there?

Extended Example: Alternative Runs (1/2)

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↓ Switch roles of x_2 and x_5
▼

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Switch roles of x_2 and x_5
↓

$$\begin{aligned} z &= &12 &+& 2x_1 &-& \frac{x_3}{2} &-& \frac{x_5}{2} \\ x_2 &= &12 &-& x_1 &-& \frac{5x_3}{2} &-& \frac{x_5}{2} \\ x_4 &= &18 &-& x_2 &-& \frac{x_3}{2} &+& \frac{x_5}{2} \\ x_6 &= &24 &-& 3x_1 &+& \frac{x_3}{2} &+& \frac{x_5}{2} \end{aligned}$$

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Switch roles of x_1 and x_6
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$$\begin{array}{rcllclcl} z & = & 28 & - & \frac{x_3}{6} & - & \frac{x_5}{6} & - & \frac{2x_6}{3} \\ x_1 & = & 8 & + & \frac{x_3}{6} & + & \frac{x_5}{6} & - & \frac{x_6}{3} \\ x_2 & = & 4 & - & \frac{8x_3}{3} & - & \frac{2x_5}{3} & + & \frac{x_6}{3} \\ x_4 & = & 18 & - & \frac{x_3}{2} & + & \frac{x_5}{2} & & \end{array}$$

Extended Example: Alternative Runs (2/2)

$$\begin{array}{rcccccccc} z & = & & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

Extended Example: Alternative Runs (2/2)

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

↓ Switch roles of x_3 and x_5
↓

Extended Example: Alternative Runs (2/2)

$$\begin{aligned}z &= && 3x_1 & + & x_2 & + & 2x_3 \\x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3\end{aligned}$$

↓ Switch roles of x_3 and x_5
↓

$$\begin{aligned}z &= & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\x_4 &= & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\x_3 &= & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\x_6 &= & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}\end{aligned}$$

Extended Example: Alternative Runs (2/2)

$$\begin{aligned}z &= && 3x_1 & + & x_2 & + & 2x_3 \\x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3\end{aligned}$$

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Switch roles of x_1 and x_6

Extended Example: Alternative Runs (2/2)

$$\begin{array}{rclclcl}
 z & = & & 3x_1 & + & x_2 & + & 2x_3 \\
 x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\
 x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\
 x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3
 \end{array}$$

\downarrow Switch roles of x_3 and x_5

$$\begin{array}{rclclcl}
 z & = & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\
 x_4 & = & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\
 x_3 & = & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\
 x_6 & = & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}
 \end{array}$$

\swarrow Switch roles of x_1 and x_6

$$\begin{array}{rclclcl}
 z & = & \frac{111}{4} & + & \frac{x_2}{16} & - & \frac{x_5}{8} & - & \frac{11x_6}{16} \\
 x_1 & = & \frac{33}{4} & - & \frac{x_2}{16} & + & \frac{x_5}{8} & - & \frac{5x_6}{16} \\
 x_3 & = & \frac{3}{2} & - & \frac{3x_2}{8} & - & \frac{x_5}{4} & + & \frac{x_6}{8} \\
 x_4 & = & \frac{69}{4} & + & \frac{3x_2}{16} & + & \frac{5x_5}{8} & - & \frac{x_6}{16}
 \end{array}$$

Extended Example: Alternative Runs (2/2)

$$\begin{array}{rcl}
 z & = & 3x_1 + x_2 + 2x_3 \\
 x_4 & = & 30 - x_1 - x_2 - 3x_3 \\
 x_5 & = & 24 - 2x_1 - 2x_2 - 5x_3 \\
 x_6 & = & 36 - 4x_1 - x_2 - 2x_3
 \end{array}$$

Switch roles of x_3 and x_5

$$\begin{array}{rcl}
 z & = & \frac{48}{5} + \frac{11x_1}{5} + \frac{x_2}{5} - \frac{2x_5}{5} \\
 x_4 & = & \frac{78}{5} + \frac{x_1}{5} + \frac{x_2}{5} + \frac{3x_5}{5} \\
 x_3 & = & \frac{24}{5} - \frac{2x_1}{5} - \frac{2x_2}{5} - \frac{x_5}{5} \\
 x_6 & = & \frac{132}{5} - \frac{16x_1}{5} - \frac{x_2}{5} + \frac{2x_3}{5}
 \end{array}$$

Switch roles of x_1 and x_6

Switch roles of x_2 and x_3

$$\begin{array}{rcl}
 z & = & \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\
 x_1 & = & \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\
 x_3 & = & \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\
 x_4 & = & \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}
 \end{array}$$

Extended Example: Alternative Runs (2/2)

$$\begin{array}{rclclcl}
 z & = & & 3x_1 & + & x_2 & + & 2x_3 \\
 x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\
 x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\
 x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3
 \end{array}$$

Switch roles of x_3 and x_5

$$\begin{array}{rclclcl}
 z & = & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\
 x_4 & = & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\
 x_3 & = & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\
 x_6 & = & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}
 \end{array}$$

Switch roles of x_1 and x_6

Switch roles of x_2 and x_3

$$\begin{array}{rclclcl}
 z & = & \frac{111}{4} & + & \frac{x_2}{16} & - & \frac{x_5}{8} & - & \frac{11x_6}{16} \\
 x_1 & = & \frac{33}{4} & - & \frac{x_2}{16} & + & \frac{x_5}{8} & - & \frac{5x_6}{16} \\
 x_3 & = & \frac{3}{2} & - & \frac{3x_2}{8} & - & \frac{x_5}{4} & + & \frac{x_6}{8} \\
 x_4 & = & \frac{69}{4} & + & \frac{3x_2}{16} & + & \frac{5x_5}{8} & - & \frac{x_6}{16}
 \end{array}$$

$$\begin{array}{rclclcl}
 z & = & 28 & - & \frac{x_3}{6} & - & \frac{x_5}{6} & - & \frac{2x_6}{3} \\
 x_1 & = & 8 & + & \frac{x_3}{6} & + & \frac{x_5}{6} & - & \frac{x_6}{3} \\
 x_2 & = & 4 & - & \frac{8x_3}{3} & - & \frac{2x_5}{3} & + & \frac{x_6}{3} \\
 x_4 & = & 18 & - & \frac{x_3}{2} & + & \frac{x_5}{2} & &
 \end{array}$$

Simplex Algorithm by Example

Details of the Simplex Algorithm

Finding an Initial Solution

Appendix: Cycling and Termination (non-examinable)

The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
4 for each  $j \in N - \{e\}$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
6  $\hat{a}_{el} = 1/a_{le}$ 
7 // Compute the coefficients of the remaining constraints.
8 for each  $i \in B - \{l\}$ 
9      $\hat{b}_i = b_i - a_{ie}\hat{b}_e$ 
10    for each  $j \in N - \{e\}$ 
11         $\hat{a}_{ij} = a_{ij} - a_{ie}\hat{a}_{ej}$ 
12     $\hat{a}_{il} = -a_{ie}\hat{a}_{el}$ 
13 // Compute the objective function.
14  $\hat{v} = v + c_e\hat{b}_e$ 
15 for each  $j \in N - \{e\}$ 
16      $\hat{c}_j = c_j - c_e\hat{a}_{ej}$ 
17  $\hat{c}_l = -c_e\hat{a}_{el}$ 
18 // Compute new sets of basic and nonbasic variables.
19  $\hat{N} = N - \{e\} \cup \{l\}$ 
20  $\hat{B} = B - \{l\} \cup \{e\}$ 
21 return  $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$ 
```

The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
4 for each  $j \in N - \{e\}$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
6  $\hat{a}_{el} = 1/a_{le}$ 
7 // Compute the coefficients of the remaining constraints.
8 for each  $i \in B - \{l\}$ 
9      $\hat{b}_i = b_i - a_{ie}\hat{b}_e$ 
10    for each  $j \in N - \{e\}$ 
11         $\hat{a}_{ij} = a_{ij} - a_{ie}\hat{a}_{ej}$ 
12     $\hat{a}_{il} = -a_{ie}\hat{a}_{el}$ 
13 // Compute the objective function.
14  $\hat{v} = v + c_e\hat{b}_e$ 
15 for each  $j \in N - \{e\}$ 
16      $\hat{c}_j = c_j - c_e\hat{a}_{ej}$ 
17  $\hat{c}_l = -c_e\hat{a}_{el}$ 
18 // Compute new sets of basic and nonbasic variables.
19  $\hat{N} = N - \{e\} \cup \{l\}$ 
20  $\hat{B} = B - \{l\} \cup \{e\}$ 
21 return  $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$ 
```

Rewrite “tight” equation
for entering variable x_e .

The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
4 for each  $j \in N - \{e\}$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
6  $\hat{a}_{el} = 1/a_{le}$ 
7 // Compute the coefficients of the remaining constraints.
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```

Rewrite “tight” equation
for entering variable x_e .

Substituting x_e into
other equations.

The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

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21 return  $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$ 
```

Rewrite “tight” equation for entering variable x_e .

Substituting x_e into other equations.

Substituting x_e into objective function.

The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

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```

Rewrite “tight” equation for entering variable x_e .

Substituting x_e into other equations.

Substituting x_e into objective function.

Update non-basic and basic variables

The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
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4 for each  $j \in N - \{e\}$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
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20  $\hat{B} = B - \{l\} \cup \{e\}$ 
21 return ( $\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v}$ )
```

Need that $a_{le} \neq 0!$

Rewrite "tight" equation for entering variable x_e .

Substituting x_e into other equations.

Substituting x_e into objective function.

Update non-basic and basic variables

Effect of the Pivot Step (extra material, non-examinable)

— Lemma 29.1 —

Consider a call to $\text{PIVOT}(N, B, A, b, c, v, l, e)$ in which $a_{le} \neq 0$. Let the values returned from the call be $(\widehat{N}, \widehat{B}, \widehat{A}, \widehat{b}, \widehat{c}, \widehat{v})$, and let \bar{x} denote the basic solution after the call. Then

Effect of the Pivot Step (extra material, non-examinable)

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1. $\bar{x}_j = 0$ for each $j \in \hat{N}$.
2. $\bar{x}_e = b_l / a_{le}$.
3. $\bar{x}_i = b_i - a_{ie} \hat{b}_e$ for each $i \in \hat{B} \setminus \{e\}$.

Effect of the Pivot Step (extra material, non-examinable)

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Proof:

Effect of the Pivot Step (extra material, non-examinable)

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3. $\bar{x}_i = b_i - a_{ie}\hat{b}_e$ for each $i \in \hat{B} \setminus \{e\}$.

Proof:

1. holds since the basic solution always sets all non-basic variables to zero.
2. When we set each non-basic variable to 0 in a constraint

$$x_i = \hat{b}_i - \sum_{j \in \hat{N}} \hat{a}_{ij} x_j,$$

we have $\bar{x}_i = \hat{b}_i$ for each $i \in \hat{B}$. Hence $\bar{x}_e = \hat{b}_e = b_l/a_{le}$.

3. After substituting into the other constraints, we have

$$\bar{x}_i = \hat{b}_i = b_i - a_{ie}\hat{b}_e.$$

Effect of the Pivot Step (extra material, non-examinable)

Lemma 29.1

Consider a call to $\text{PIVOT}(N, B, A, b, c, v, l, e)$ in which $a_{le} \neq 0$. Let the values returned from the call be $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$, and let \bar{x} denote the basic solution after the call. Then

1. $\bar{x}_j = 0$ for each $j \in \hat{N}$.
2. $\bar{x}_e = b_l/a_{le}$.
3. $\bar{x}_i = b_i - a_{ie}\hat{b}_e$ for each $i \in \hat{B} \setminus \{e\}$.

Proof:

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we have $\bar{x}_i = \hat{b}_i$ for each $i \in \hat{B}$. Hence $\bar{x}_e = \hat{b}_e = b_l/a_{le}$.

3. After substituting into the other constraints, we have

$$\bar{x}_i = \hat{b}_i = b_i - a_{ie}\hat{b}_e. \quad \square$$

Questions:

- How do we determine whether a linear program is feasible?
- What do we do if the linear program is feasible, but the initial basic solution is not feasible?
- How do we determine whether a linear program is unbounded?
- How do we choose the entering and leaving variables?

Questions:

- How do we determine whether a linear program is feasible?
- What do we do if the linear program is feasible, but the initial basic solution is not feasible?
- How do we determine whether a linear program is unbounded?
- How do we choose the entering and leaving variables?

Example before was a particularly nice one!

The formal procedure SIMPLEX

SIMPLEX(A, b, c)

```
1  ( $N, B, A, b, c, v$ ) = INITIALIZE-SIMPLEX( $A, b, c$ )
2  let  $\Delta$  be a new vector of length  $m$ 
3  while some index  $j \in N$  has  $c_j > 0$ 
4      choose an index  $e \in N$  for which  $c_e > 0$ 
5      for each index  $i \in B$ 
6          if  $a_{ie} > 0$ 
7               $\Delta_i = b_i/a_{ie}$ 
8          else  $\Delta_i = \infty$ 
9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
10     if  $\Delta_l == \infty$ 
11         return “unbounded”
12     else ( $N, B, A, b, c, v$ ) = PIVOT( $N, B, A, b, c, v, l, e$ )
13 for  $i = 1$  to  $n$ 
14     if  $i \in B$ 
15          $\bar{x}_i = b_i$ 
16     else  $\bar{x}_i = 0$ 
17 return ( $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n$ )
```

The formal procedure **SIMPLEX**

SIMPLEX(A, b, c)

```
1  ( $N, B, A, b, c, v$ ) = INITIALIZE-SIMPLEX( $A, b, c$ )
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6          if  $a_{ie} > 0$ 
7               $\Delta_i = b_i/a_{ie}$ 
8          else  $\Delta_i = \infty$ 
9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
10     if  $\Delta_l == \infty$ 
11         return “unbounded”
12     else ( $N, B, A, b, c, v$ ) = PIVOT( $N, B, A, b, c, v, l, e$ )
13 for  $i = 1$  to  $n$ 
14     if  $i \in B$ 
15          $\bar{x}_i = b_i$ 
16     else  $\bar{x}_i = 0$ 
17 return ( $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n$ )
```

Returns a slack form with a feasible basic solution (if it exists)

The formal procedure SIMPLEX

SIMPLEX(A, b, c)

```
1  ( $N, B, A, b, c, v$ ) = INITIALIZE-SIMPLEX( $A, b, c$ )
2  let  $\Delta$  be a new vector of length  $m$ 
3  while some index  $j \in N$  has  $c_j > 0$ 
4      choose an index  $e \in N$  for which  $c_e > 0$ 
5      for each index  $i \in B$ 
6          if  $a_{ie} > 0$ 
7               $\Delta_i = b_i/a_{ie}$ 
8          else  $\Delta_i = \infty$ 
9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
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16     else  $\bar{x}_i = 0$ 
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Returns a slack form with a feasible basic solution (if it exists)

Main Loop:

The formal procedure SIMPLEX

SIMPLEX(A, b, c)

```
1   $(N, B, A, b, c, v) = \text{INITIALIZE-SIMPLEX}(A, b, c)$ 
2  let  $\Delta$  be a new vector of length  $m$ 
3  while some index  $j \in N$  has  $c_j > 0$ 
4      choose an index  $e \in N$  for which  $c_e > 0$ 
5      for each index  $i \in B$ 
6          if  $a_{ie} > 0$ 
7               $\Delta_i = b_i/a_{ie}$ 
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9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
10     if  $\Delta_l == \infty$ 
11         return "unbounded"
12     else  $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, e)$ 
13 for  $i = 1$  to  $n$ 
14     if  $i \in B$ 
15          $\bar{x}_i = b_i$ 
16     else  $\bar{x}_i = 0$ 
17 return  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$ 
```

Returns a slack form with a feasible basic solution (if it exists)

Main Loop:

- terminates if all coefficients in objective function are **non-positive**
- Line 4 picks entering variable x_e with **positive** coefficient
- Lines 6 – 9 pick the tightest constraint, associated with x_l
- Line 11 returns "unbounded" if there are no constraints
- Line 12 calls PIVOT, switching roles of x_l and x_e

The formal procedure SIMPLEX

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Returns a slack form with a feasible basic solution (if it exists)

Main Loop:

- terminates if all coefficients in objective function are **non-positive**
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Return corresponding solution.

The formal procedure **SIMPLEX**

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16     else  $\bar{x}_i = 0$ 
17 return ( $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n$ )
```

Returns a slack form with a feasible basic solution (if it exists)

Lemma 29.2

Suppose the call to INITIALIZE-SIMPLEX in line 1 returns a slack form for which the basic solution is feasible. Then if SIMPLEX returns a solution, it is a feasible solution. If SIMPLEX returns “unbounded”, the linear program is unbounded.

The formal procedure **SIMPLEX**

SIMPLEX(A, b, c)

```
1  ( $N, B, A, b, c, v$ ) = INITIALIZE-SIMPLEX( $A, b, c$ )
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5      for each index  $i \in B$ 
6          if  $a_{ie} > 0$ 
7               $\Delta_i = b_i / a_{ie}$ 
8          else  $\Delta_i = \infty$ 
9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
10     if  $\Delta_l == \infty$ 
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```

Returns a slack form with a feasible basic solution (if it exists)

Proof is based on the following three-part loop invariant:

Lemma 29.2

Suppose the call to INITIALIZE-SIMPLEX in line 1 returns a slack form for which the basic solution is feasible. Then if SIMPLEX returns a solution, it is a feasible solution. If SIMPLEX returns "unbounded", the linear program is unbounded.

The formal procedure **SIMPLEX**

SIMPLEX(A, b, c)

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8          else  $\Delta_i = \infty$ 
9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
10     if  $\Delta_l == \infty$ 
11     return "unbounded"
```

Returns a slack form with a feasible basic solution (if it exists)

Proof is based on the following three-part loop invariant:

1. the slack form is always equivalent to the one returned by INITIALIZE-SIMPLEX,
2. for each $i \in B$, we have $b_i \geq 0$,
3. the basic solution associated with the (current) slack form is feasible.

Lemma 29.2

Suppose the call to INITIALIZE-SIMPLEX in line 1 returns a slack form for which the basic solution is feasible. Then if SIMPLEX returns a solution, it is a feasible solution. If SIMPLEX returns "unbounded", the linear program is unbounded.

Outline

Simplex Algorithm by Example

Details of the Simplex Algorithm

Finding an Initial Solution

Appendix: Cycling and Termination (non-examinable)

Finding an Initial Solution

$$\begin{array}{llll} \text{maximise} & 2x_1 & - & x_2 \\ \text{subject to} & & & \\ & 2x_1 & - & x_2 \leq 2 \\ & x_1 & - & 5x_2 \leq -4 \\ & x_1, x_2 & & \geq 0 \end{array}$$

Finding an Initial Solution

maximise
subject to

$$2x_1 - x_2$$

$$2x_1 - x_2 \leq 2$$

$$x_1 - 5x_2 \leq -4$$

$$x_1, x_2 \geq 0$$



Conversion into slack form

Finding an Initial Solution

maximise
subject to

$$\begin{array}{rclcl} 2x_1 & - & x_2 & & \\ 2x_1 & - & x_2 & \leq & 2 \\ x_1 & - & 5x_2 & \leq & -4 \\ x_1, x_2 & & & \geq & 0 \end{array}$$

Conversion into slack form

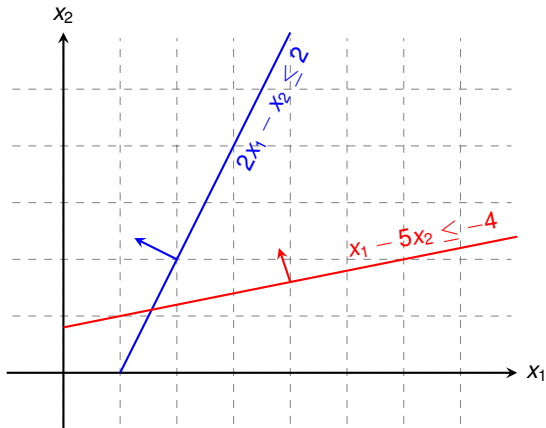
$$\begin{array}{rclcl} z & = & & 2x_1 & - & x_2 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 \end{array}$$

Basic solution $(x_1, x_2, x_3, x_4) = (0, 0, 2, -4)$ is not feasible!

Geometric Illustration

maximise
subject to

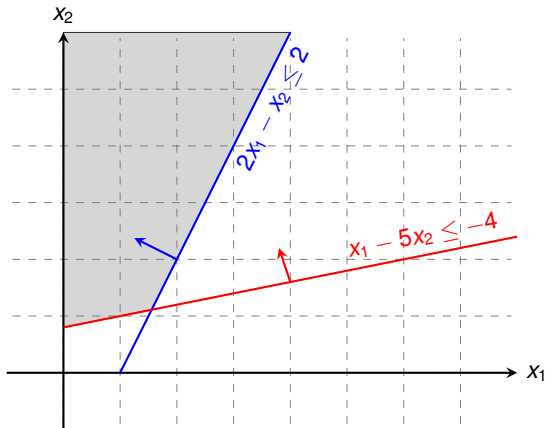
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Geometric Illustration

maximise
subject to

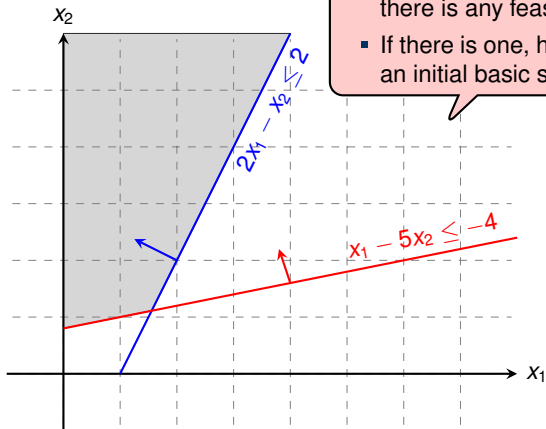
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Geometric Illustration

maximise
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$$\begin{array}{rclcl} 2x_1 & - & x_2 & & \\ 2x_1 & - & x_2 & \leq & 2 \\ x_1 & - & 5x_2 & \leq & -4 \\ x_1, x_2 & & & \geq & 0 \end{array}$$



Questions:

- How to determine whether there is any feasible solution?
- If there is one, how to determine an initial basic solution?

Formulating an Auxiliary Linear Program

maximise
subject to

$$\sum_{j=1}^n c_j x_j$$

$$\begin{aligned} \sum_{j=1}^n a_{ij} x_j &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 1, 2, \dots, n \end{aligned}$$

Formulating an Auxiliary Linear Program

maximise $\sum_{j=1}^n c_j x_j$
subject to

$$\begin{aligned}\sum_{j=1}^n a_{ij} x_j &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 1, 2, \dots, n\end{aligned}$$

↓
Formulating an [Auxiliary Linear Program](#)

Formulating an Auxiliary Linear Program

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↓
↓ Formulating an Auxiliary Linear Program

maximise $-x_0$
subject to

$$\begin{aligned} \sum_{j=1}^n a_{ij} x_j - x_0 &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 0, 1, \dots, n \end{aligned}$$

Formulating an Auxiliary Linear Program

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Lemma 29.11

Let L_{aux} be the auxiliary LP of a linear program L in standard form. Then L is feasible if and only if the optimal objective value of L_{aux} is 0.

Formulating an Auxiliary Linear Program

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Proof.

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Proof.

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Formulating an Auxiliary Linear Program

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 - $\bar{x}_0 = 0$ combined with \bar{x} is a feasible solution to L_{aux} with objective value 0.
 - Since $\bar{x}_0 \geq 0$ and the objective is to maximise $-x_0$, this is optimal for L_{aux}

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- “ \Leftarrow ”: Suppose that the optimal objective value of L_{aux} is 0
 - Then $\bar{x}_0 = 0$, and the remaining solution values $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$ satisfy L .

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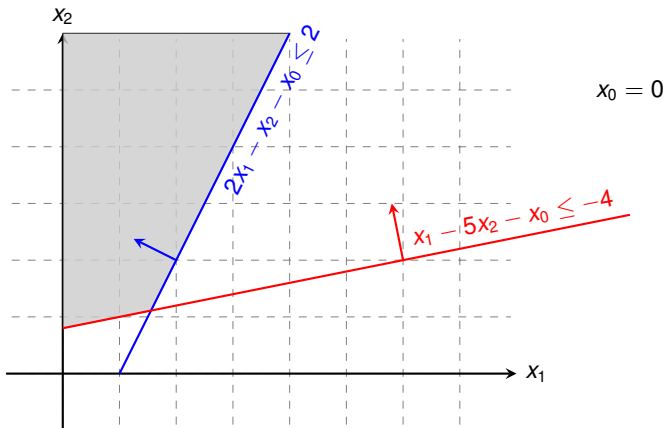
- Let us illustrate the role of x_0 as “distance from feasibility”

- Let us illustrate the role of x_0 as “distance from feasibility”
- We'll also see that increasing x_0 enlarges the feasible region

Geometric Illustration

maximise
subject to

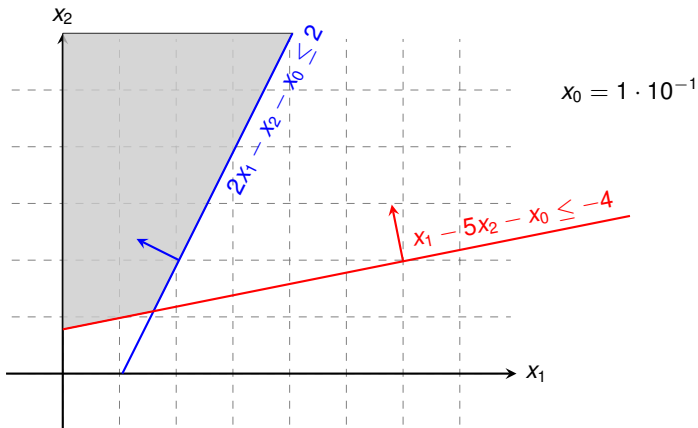
$$\begin{array}{rcllcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

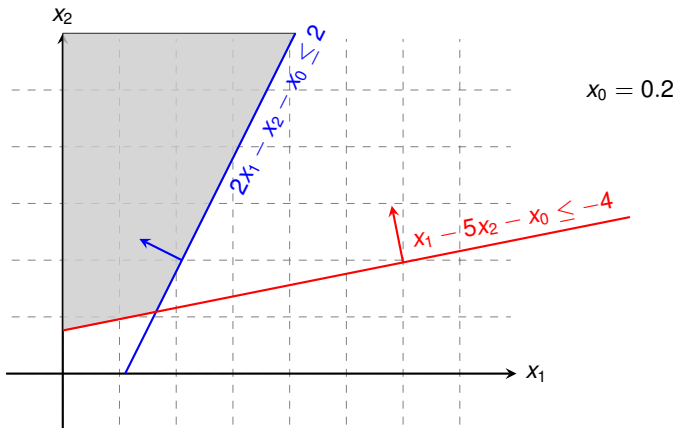
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Geometric Illustration

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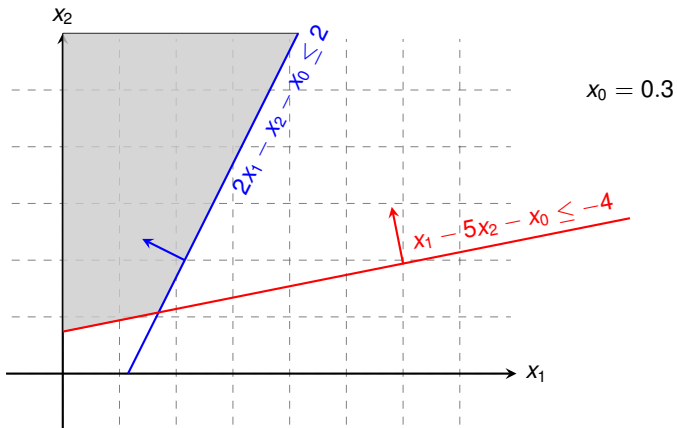
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subject to

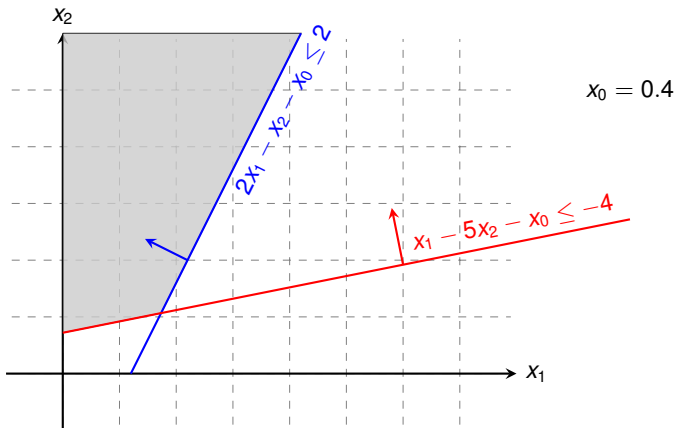
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

$$\begin{array}{rcllcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

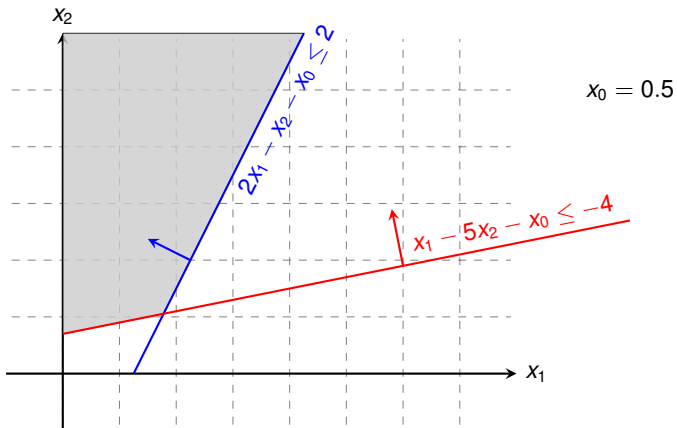
maximise
subject to

$$-x_0$$

$$2x_1 - x_2 - x_0 \leq 2$$

$$x_1 - 5x_2 - x_0 \leq -4$$

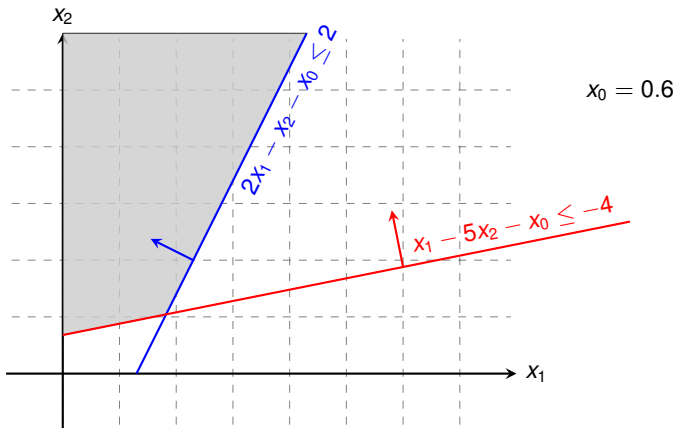
$$x_0, x_1, x_2 \geq 0$$



Geometric Illustration

maximise $-x_0$
subject to

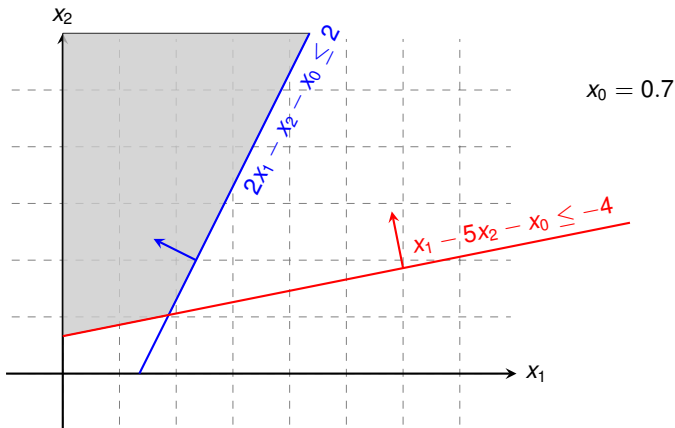
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

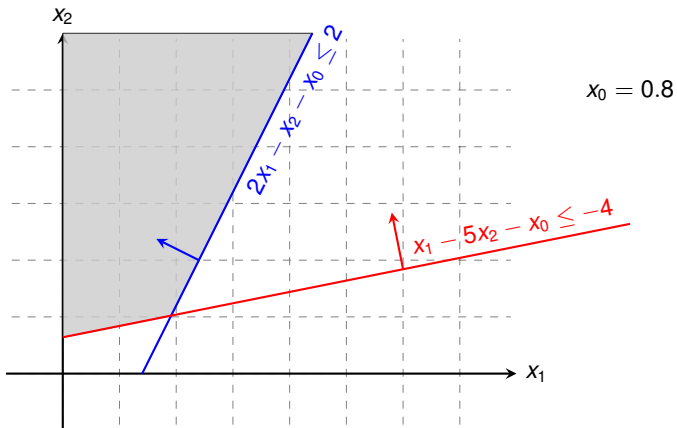
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
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$$\begin{array}{rcllcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

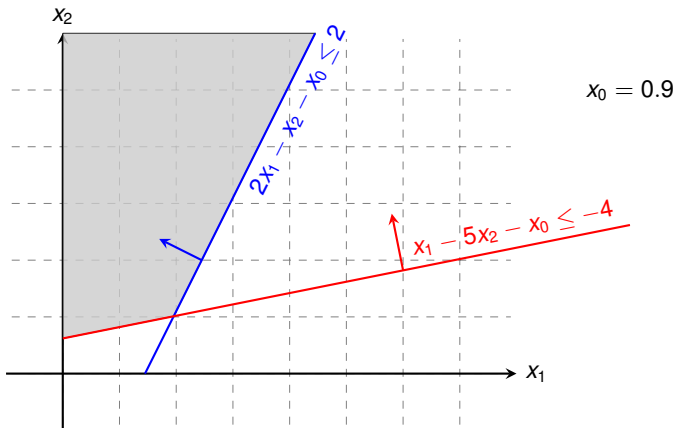
maximise
subject to

$$-x_0$$

$$2x_1 - x_2 - x_0 \leq 2$$

$$x_1 - 5x_2 - x_0 \leq -4$$

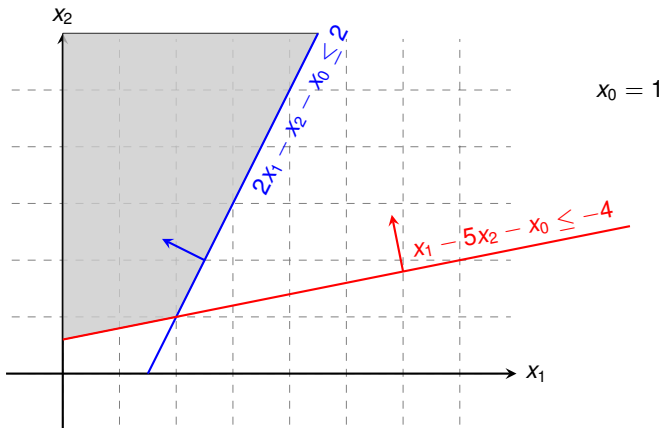
$$x_0, x_1, x_2 \geq 0$$



Geometric Illustration

maximise $-x_0$
subject to

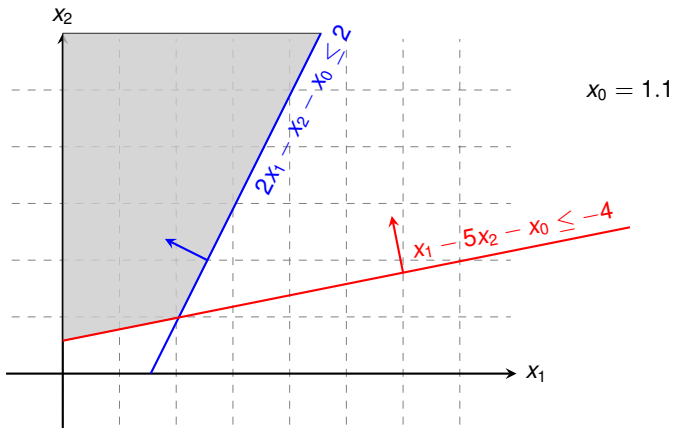
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

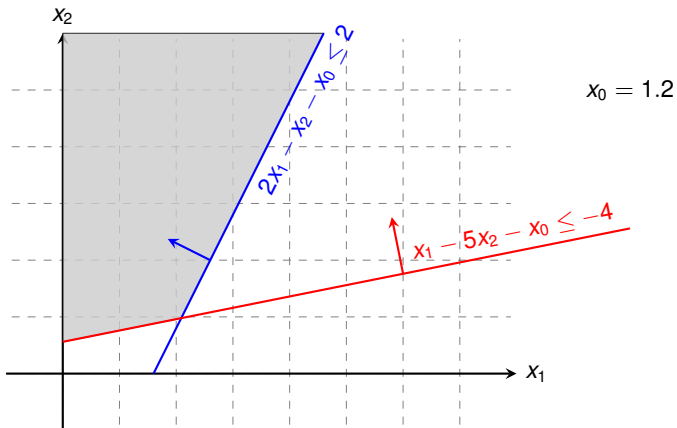
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

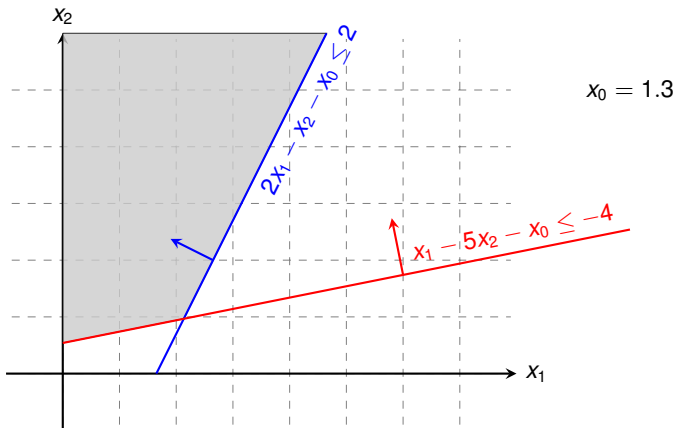
$$\begin{array}{rcllcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

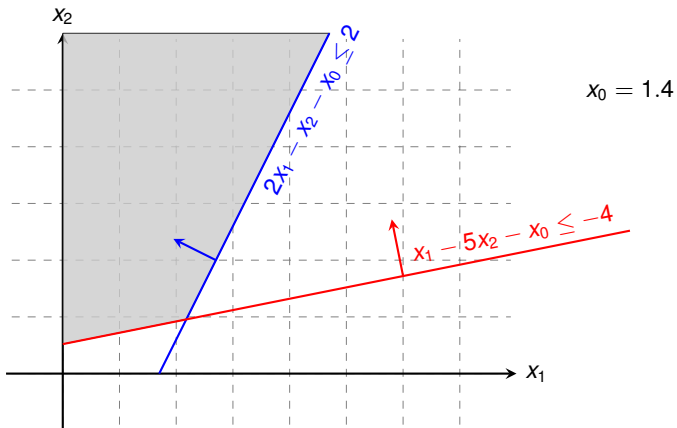
$$\begin{array}{rcllcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

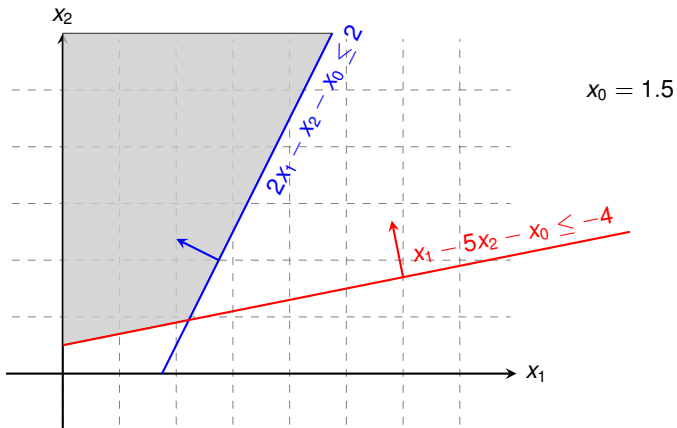
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

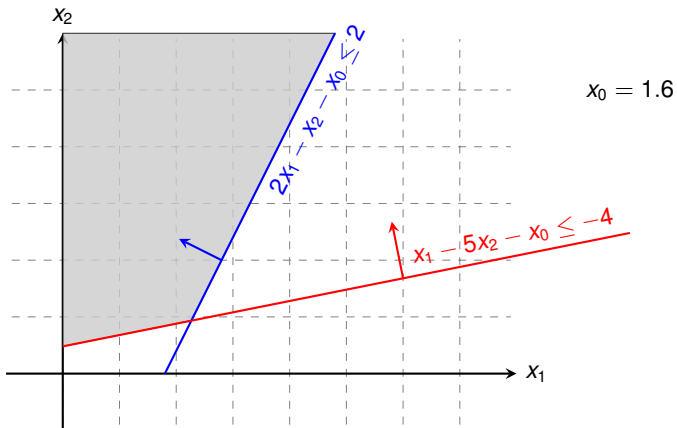
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

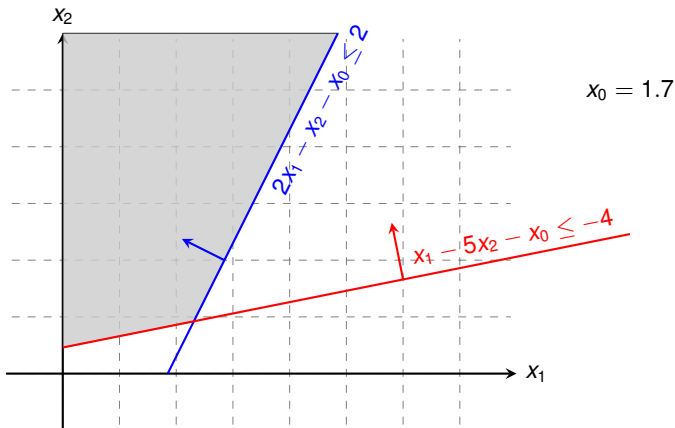
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

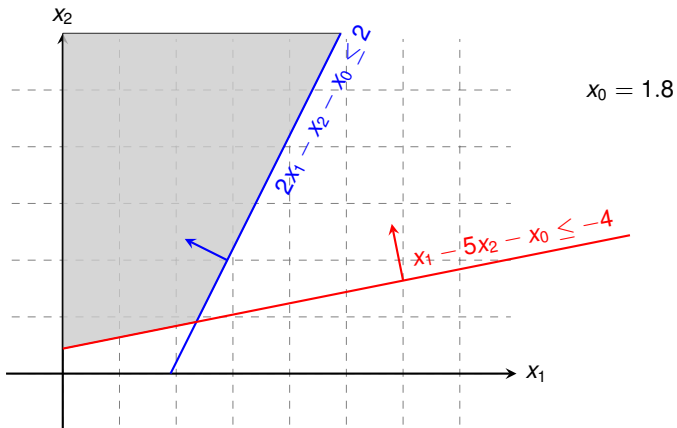
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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subject to

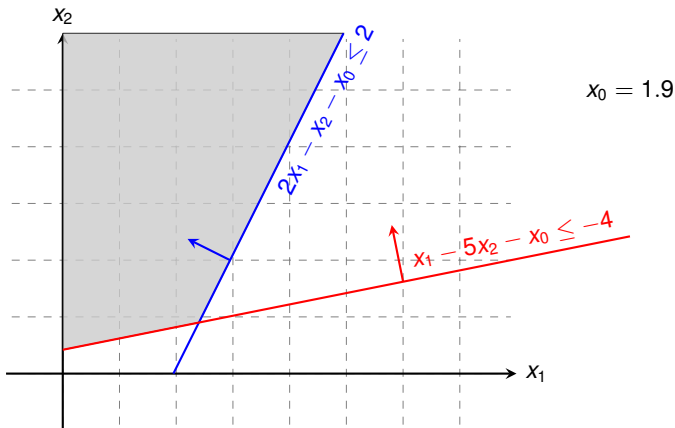
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Geometric Illustration

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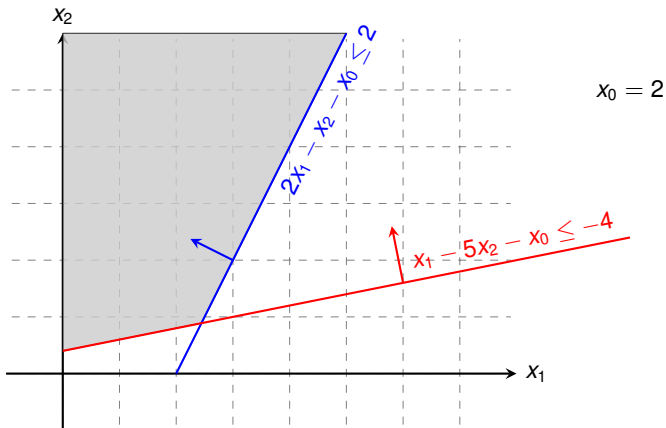
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
subject to

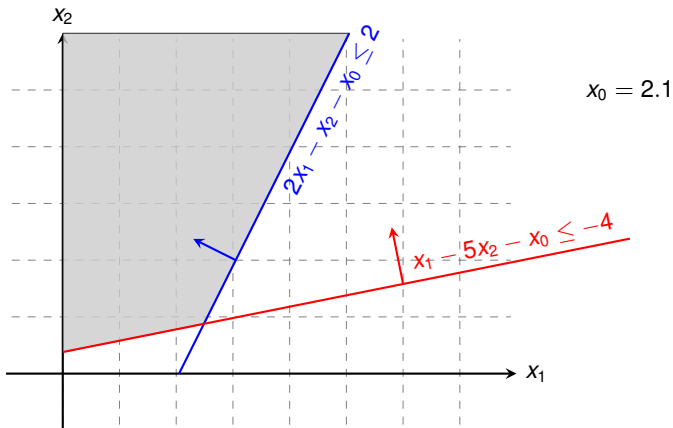
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

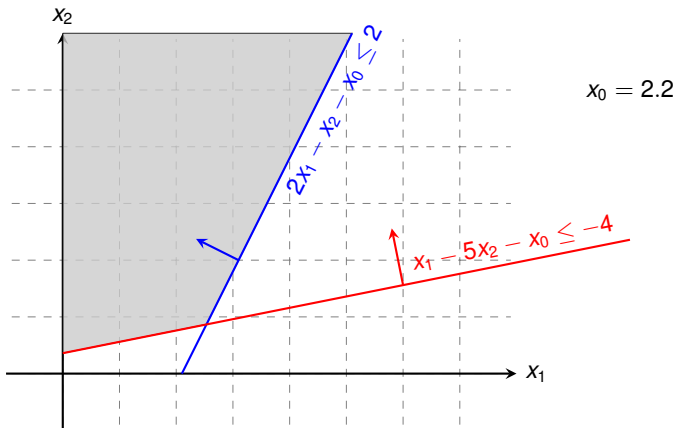
$$\begin{array}{rcllcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise $-x_0$
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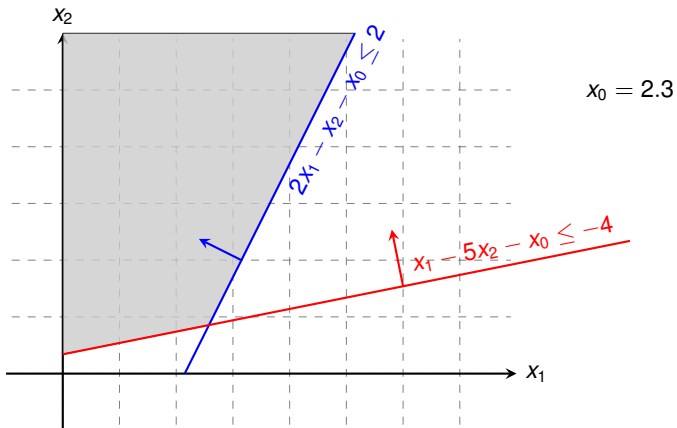
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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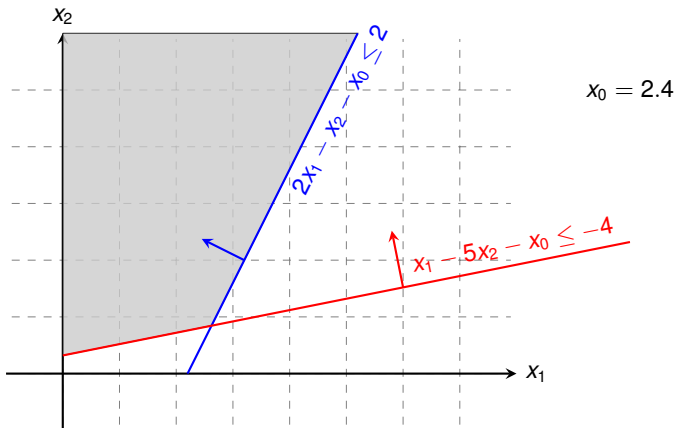
$$\begin{array}{rcllcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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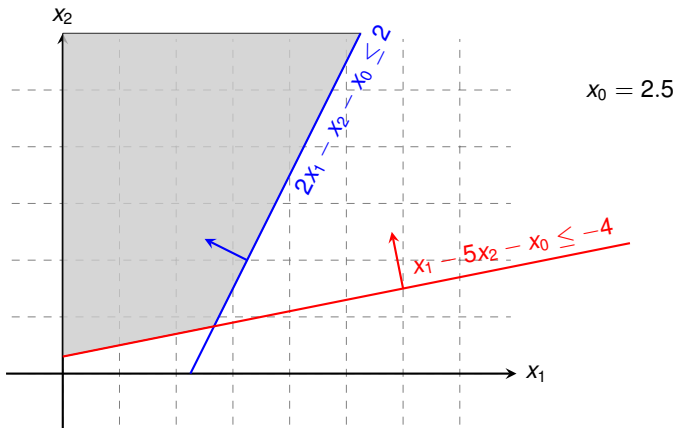
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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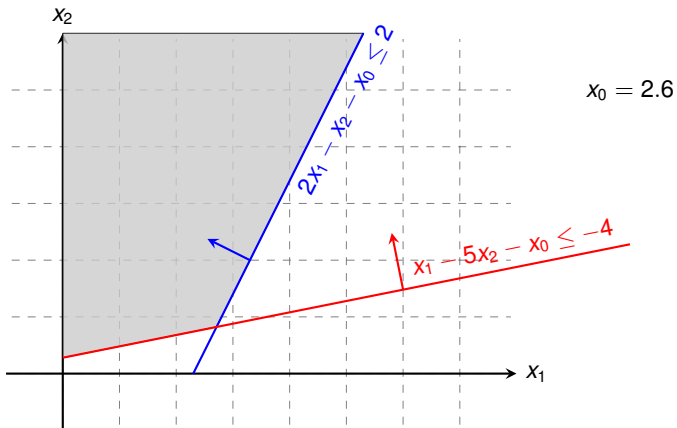
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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subject to

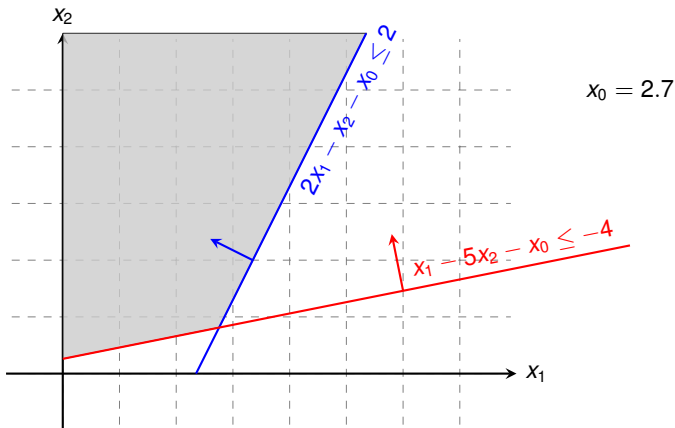
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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Geometric Illustration

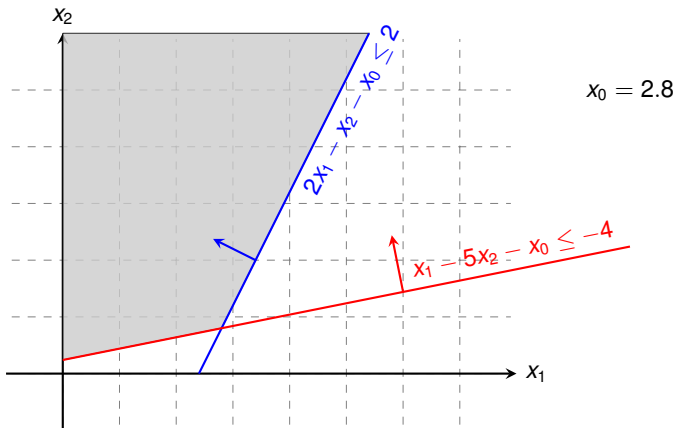
maximise
subject to

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$$2x_1 - x_2 - x_0 \leq 2$$

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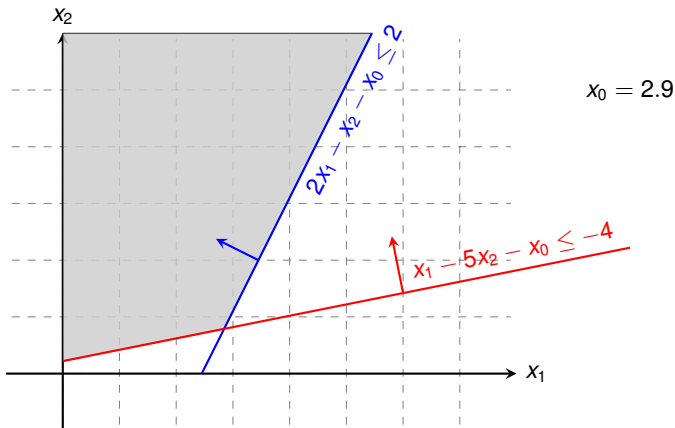
$$x_0, x_1, x_2 \geq 0$$



Geometric Illustration

maximise $-x_0$
subject to

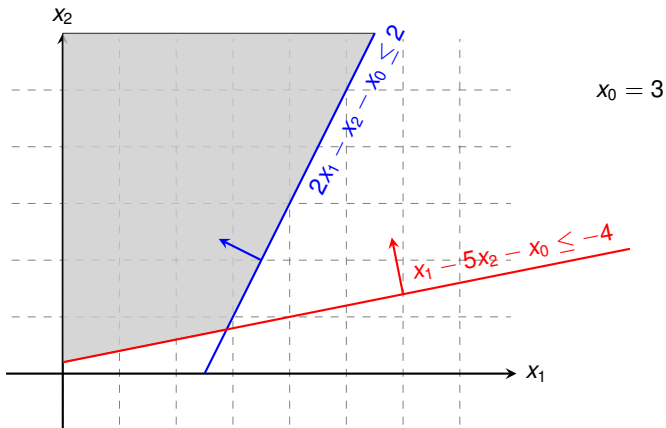
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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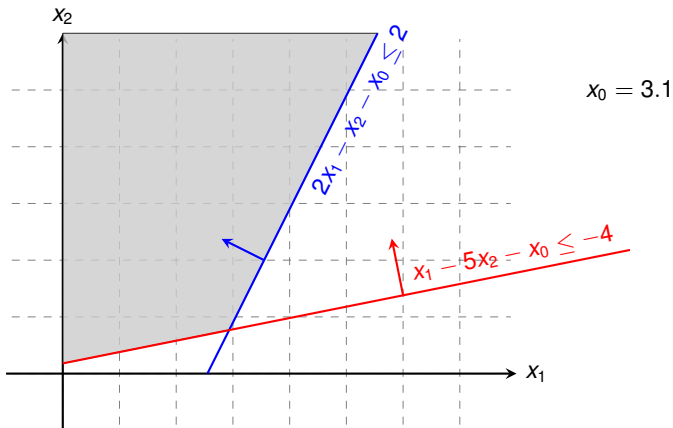
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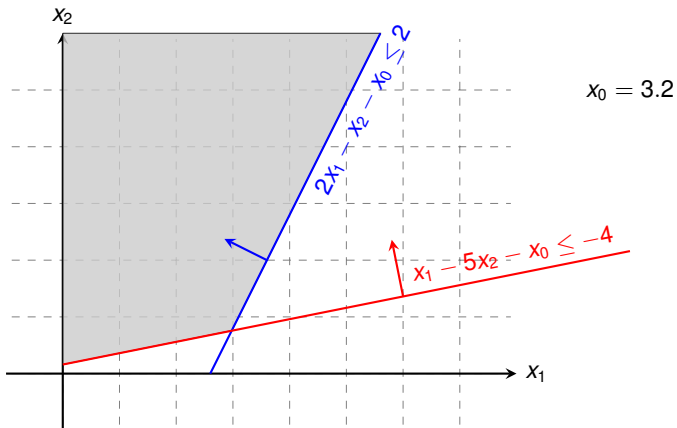
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Geometric Illustration

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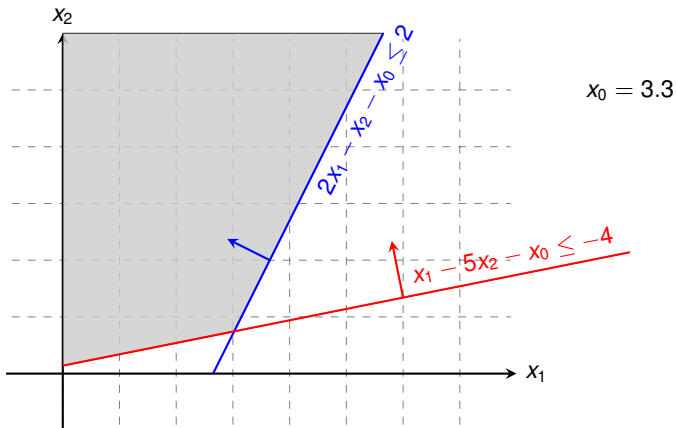
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Geometric Illustration

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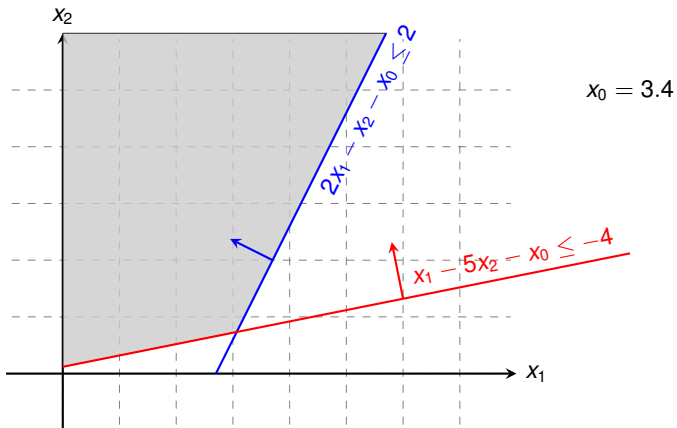
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Geometric Illustration

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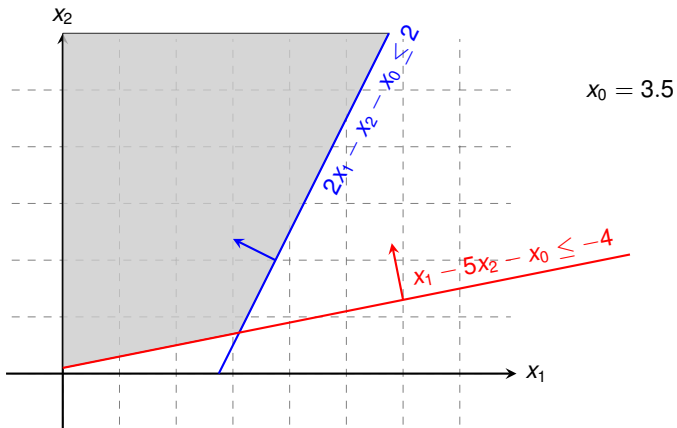
$$\begin{array}{rcllcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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subject to

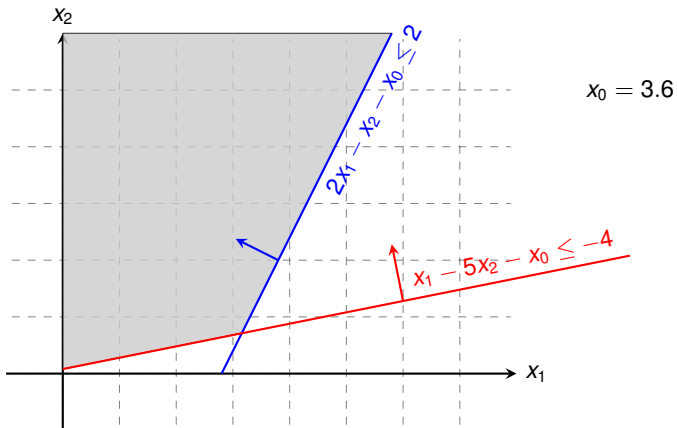
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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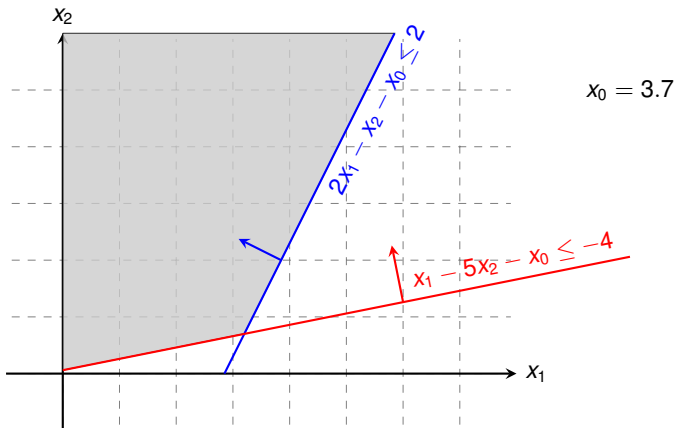
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Geometric Illustration

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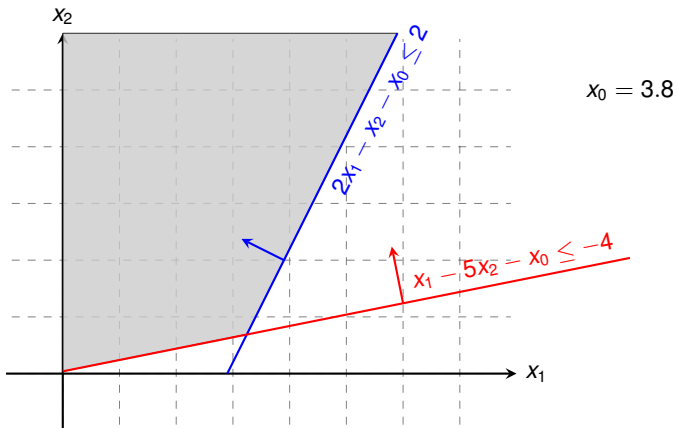
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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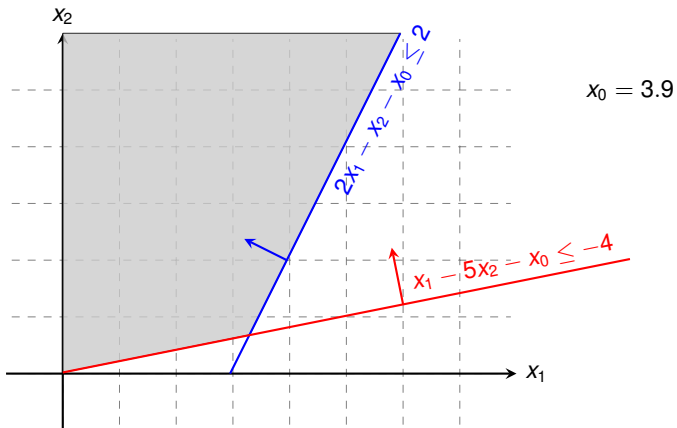
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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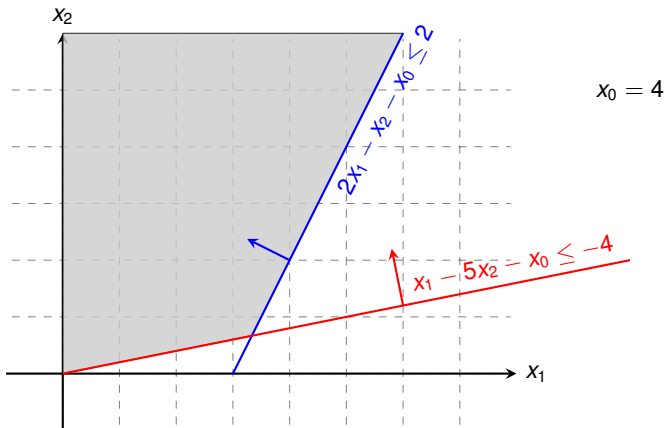
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

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$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



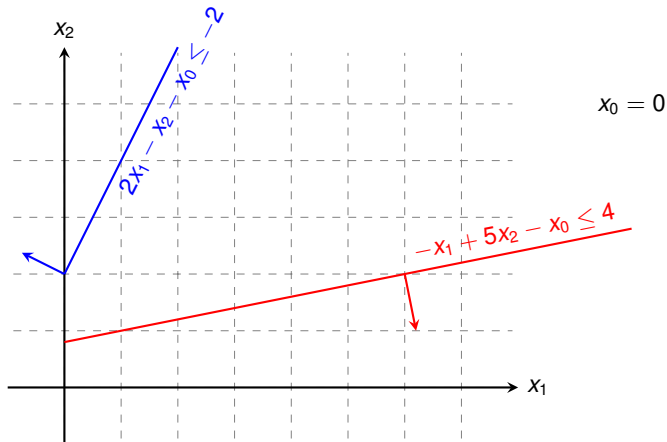
- Let us now modify the original linear program so that it is not feasible

- Let us now modify the original linear program so that it is **not feasible**
- ⇒ Hence the auxiliary linear program has only a solution for a sufficiently large $x_0 > 0$!

Geometric Illustration

maximise
subject to

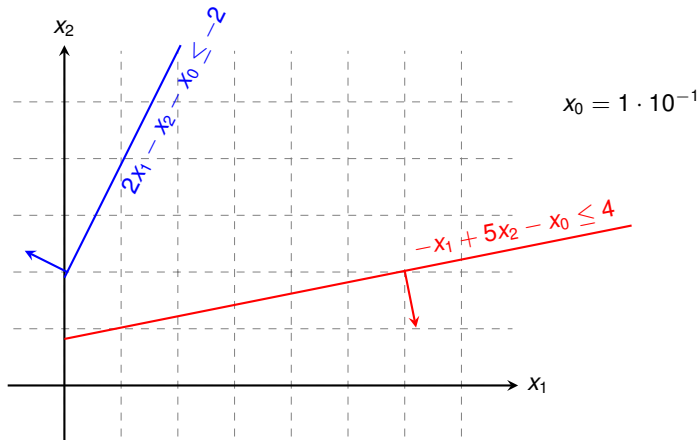
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

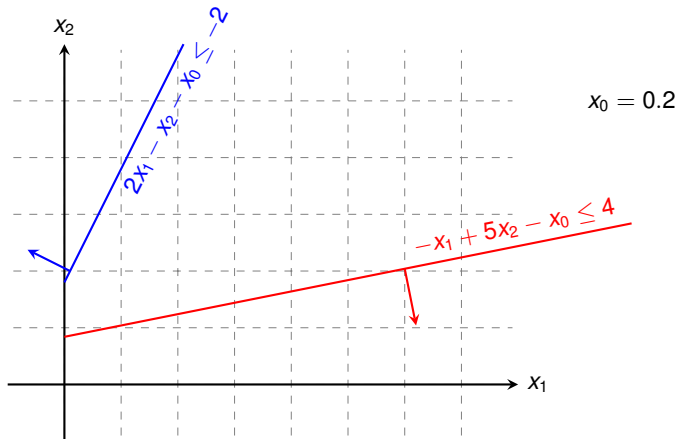
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Geometric Illustration

maximise
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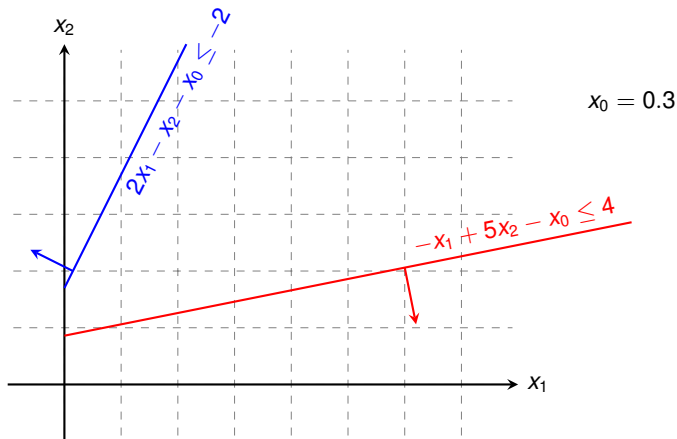
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Geometric Illustration

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subject to

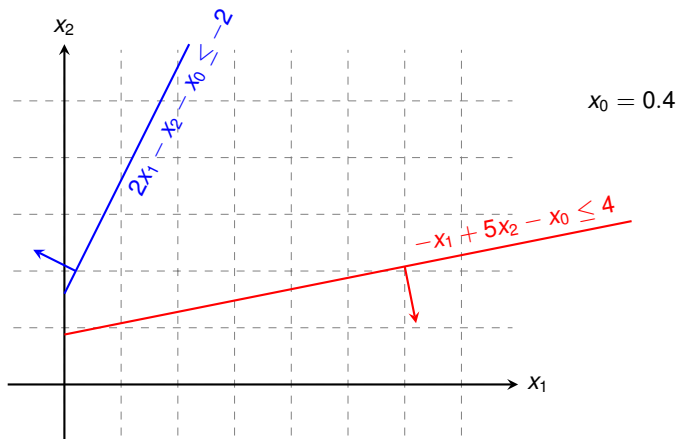
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Geometric Illustration

maximise
subject to

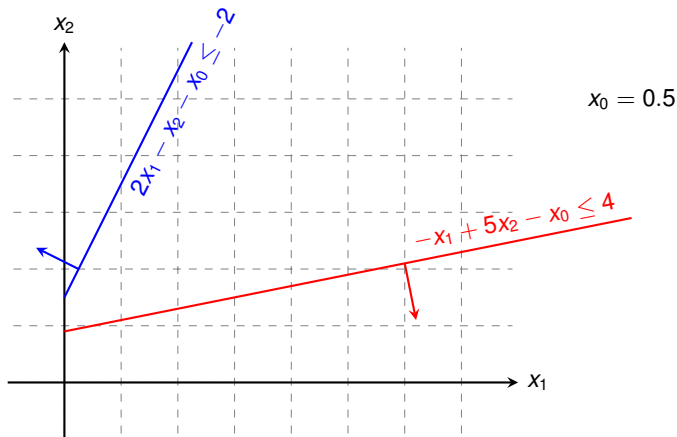
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Geometric Illustration

maximise
subject to

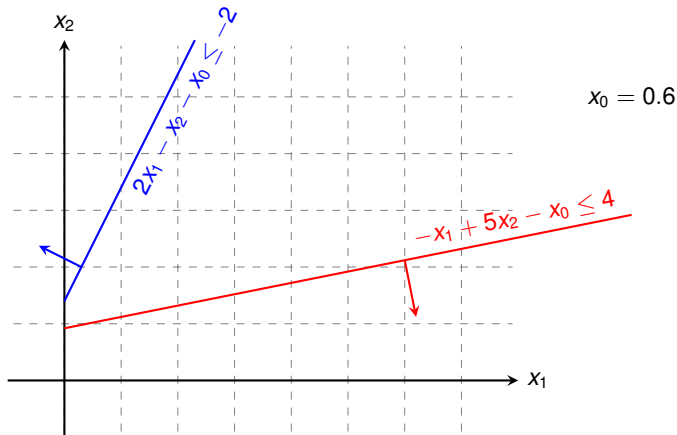
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

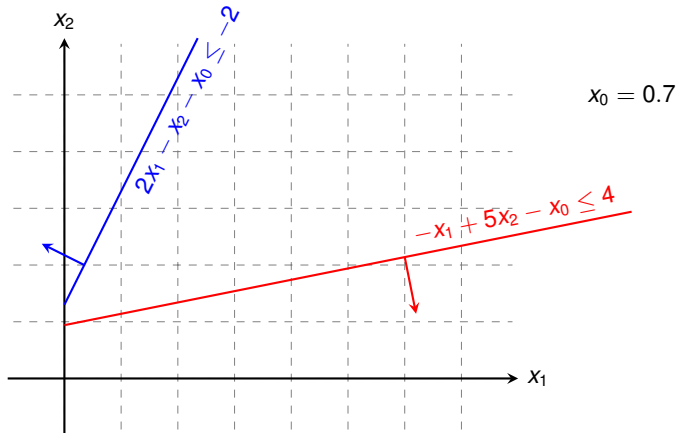
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Geometric Illustration

maximise
subject to

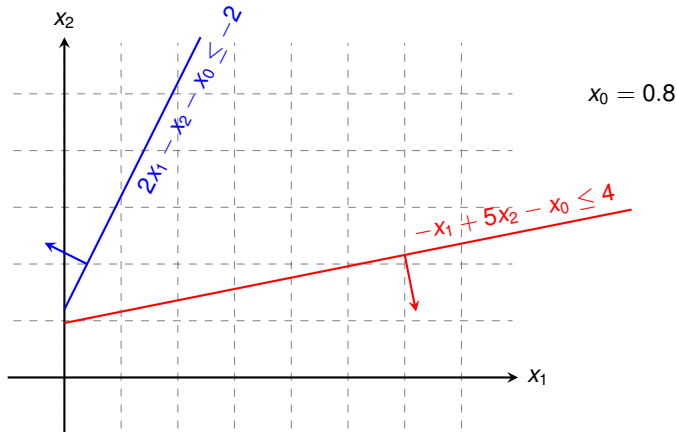
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Geometric Illustration

maximise
subject to

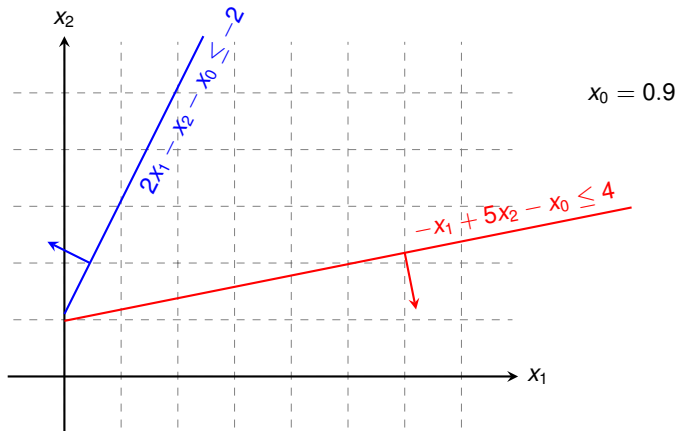
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Geometric Illustration

maximise
subject to

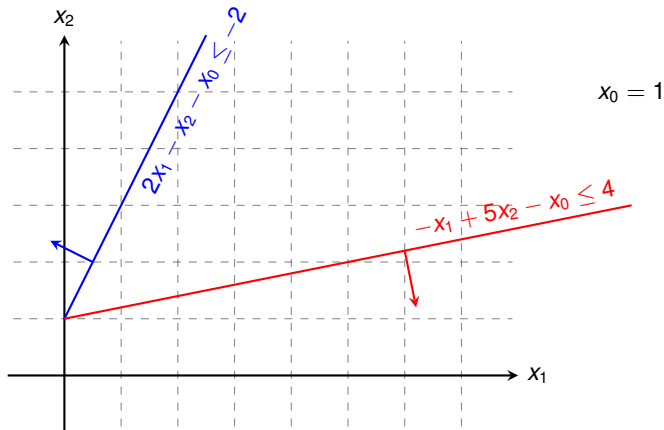
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Geometric Illustration

maximise
subject to

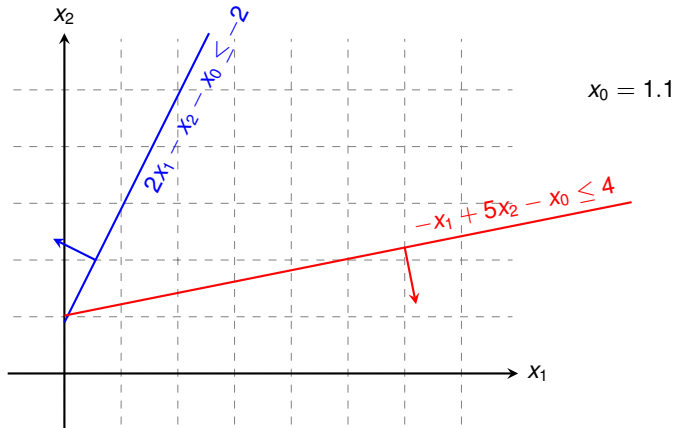
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Geometric Illustration

maximise
subject to

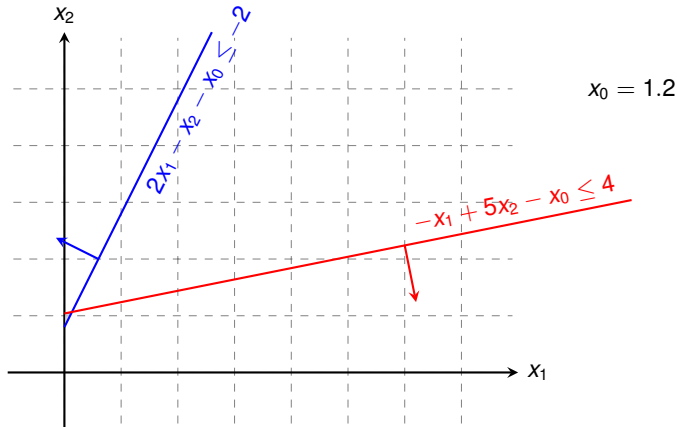
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Geometric Illustration

maximise
subject to

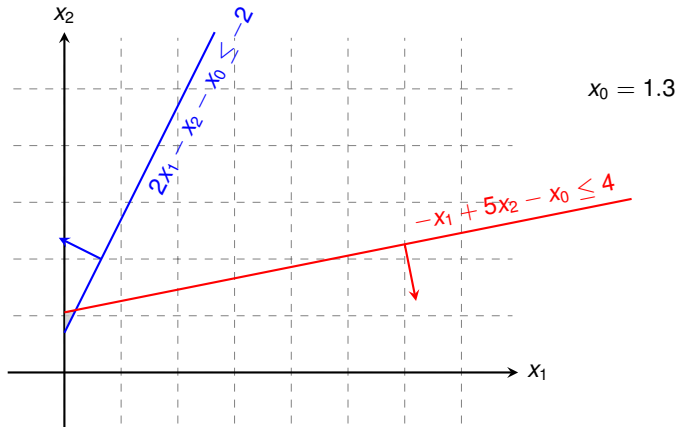
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Geometric Illustration

maximise
subject to

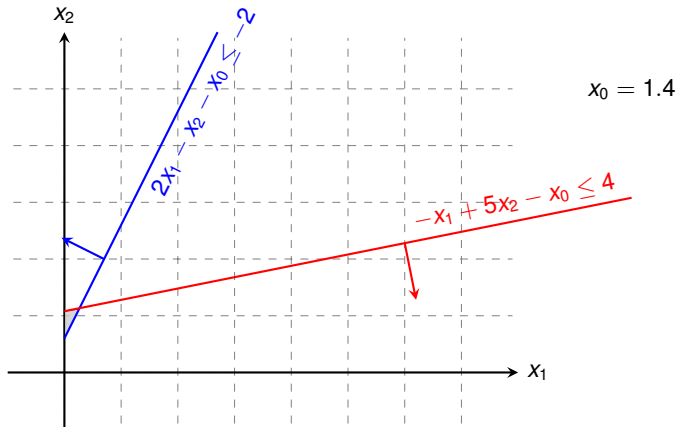
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

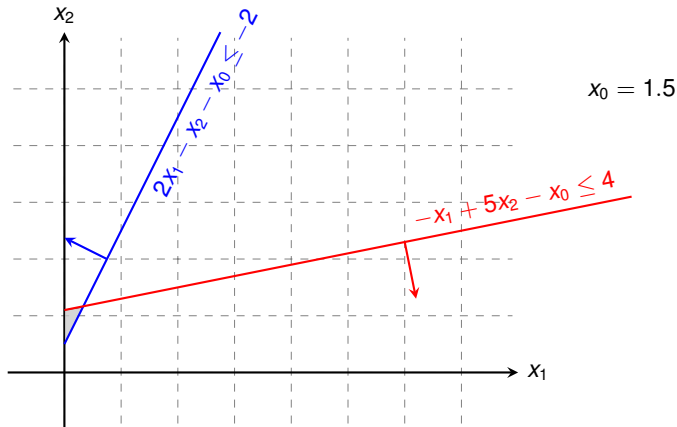
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Geometric Illustration

maximise
subject to

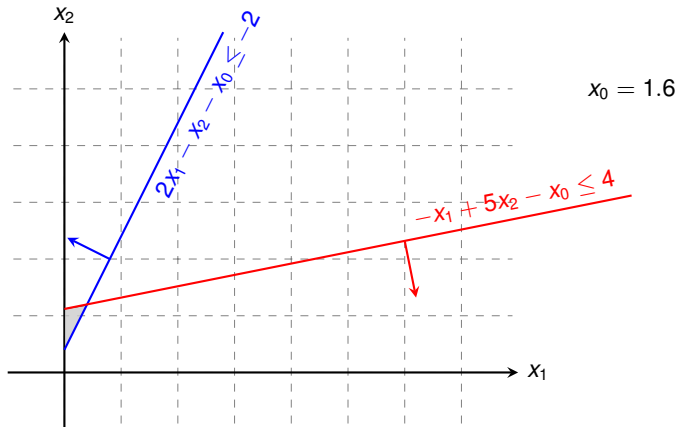
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ & & & & x_0, x_1, x_2 & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

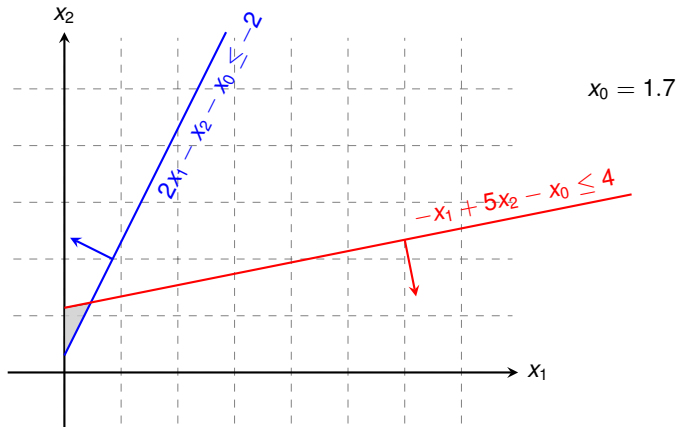
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Geometric Illustration

maximise
subject to

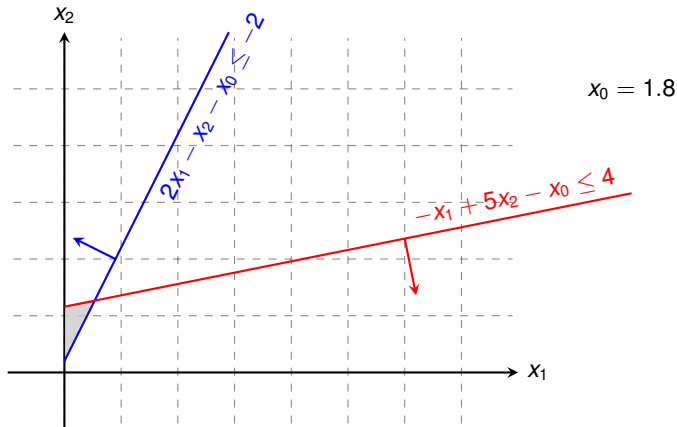
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Geometric Illustration

maximise
subject to

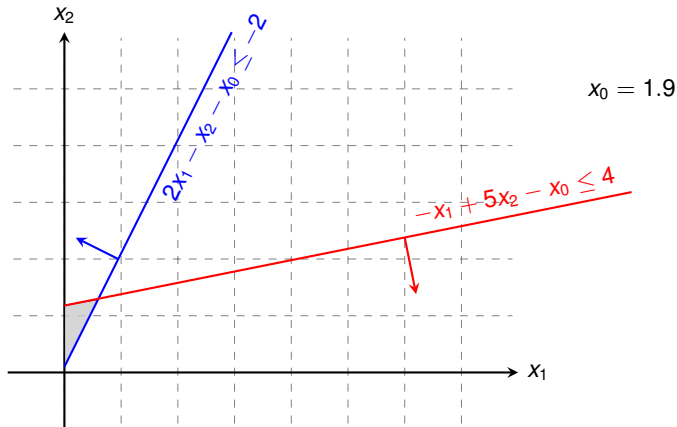
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Geometric Illustration

maximise
subject to

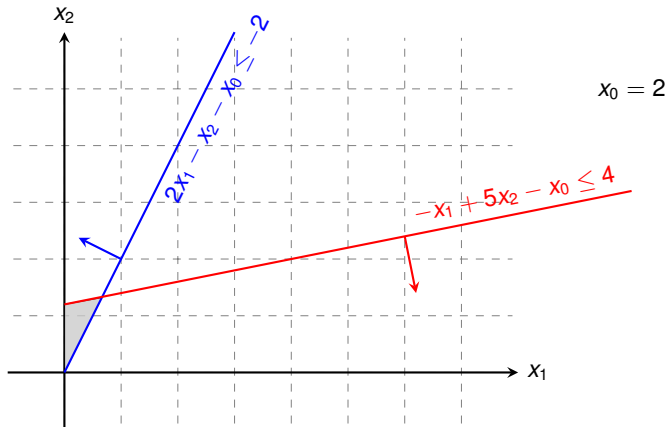
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Geometric Illustration

maximise
subject to

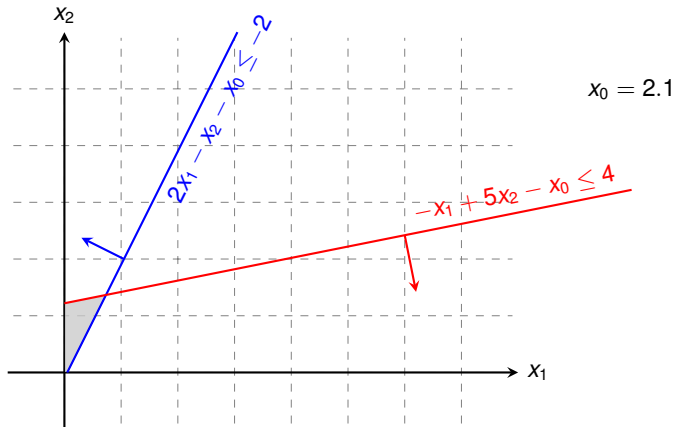
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Geometric Illustration

maximise
subject to

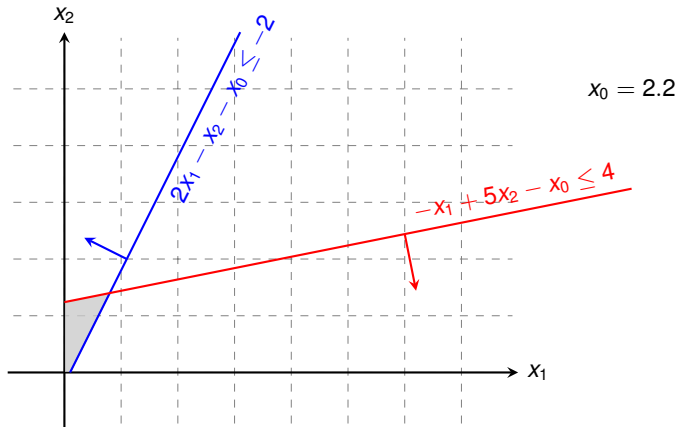
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Geometric Illustration

maximise
subject to

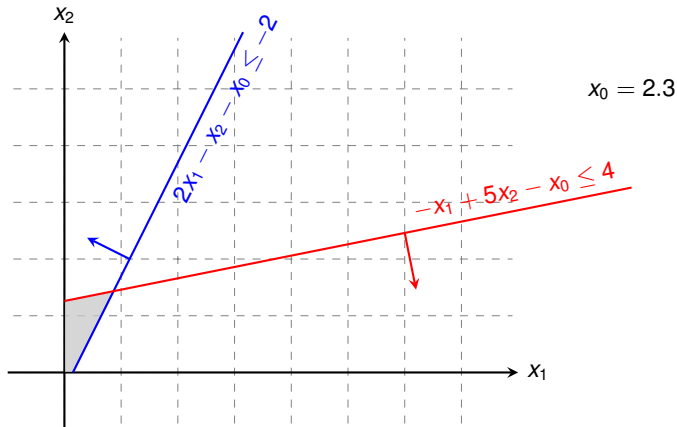
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ & & & & x_0, x_1, x_2 & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

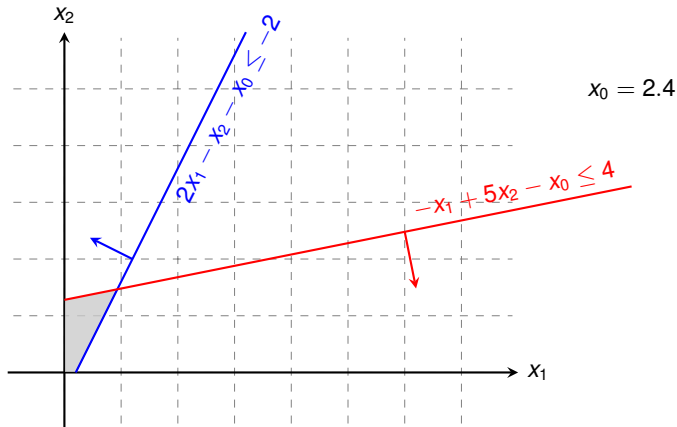
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ & & x_0, x_1, x_2 & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

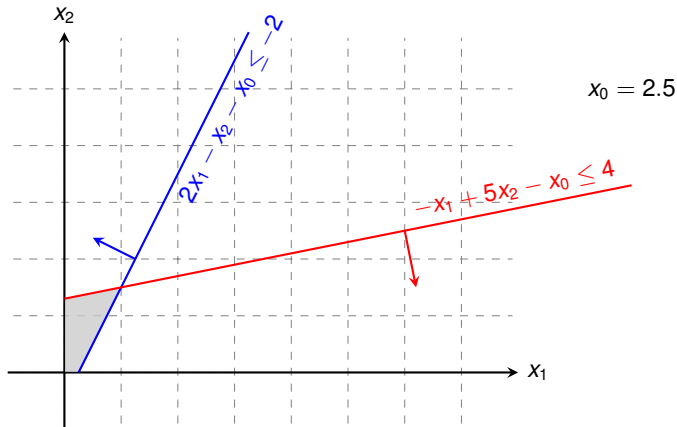
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ & & & & x_0, x_1, x_2 & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

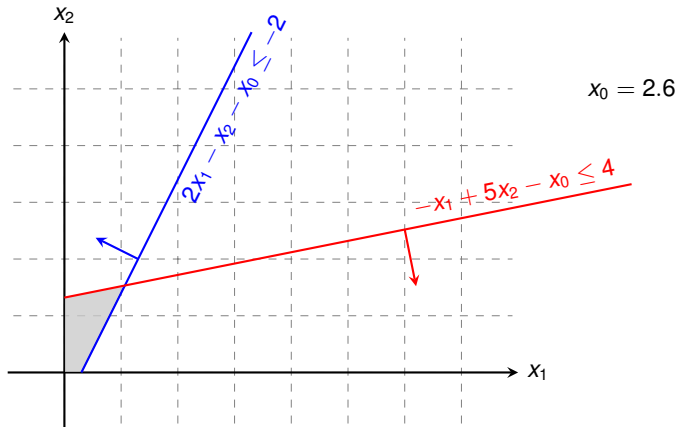
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Geometric Illustration

maximise
subject to

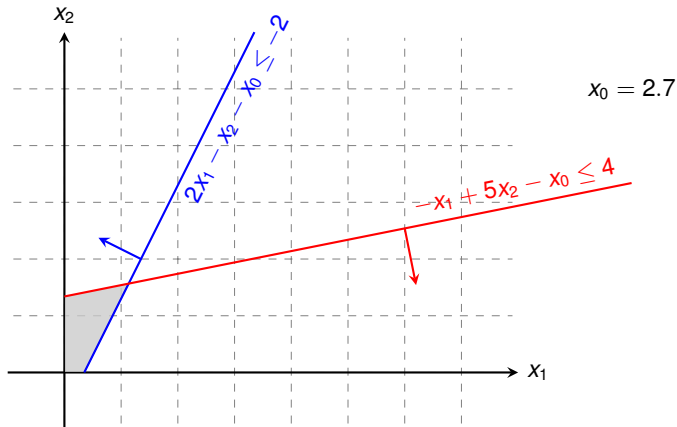
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Geometric Illustration

maximise
subject to

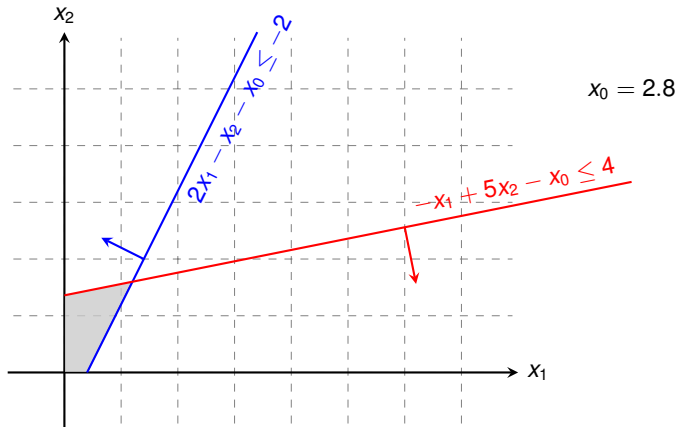
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

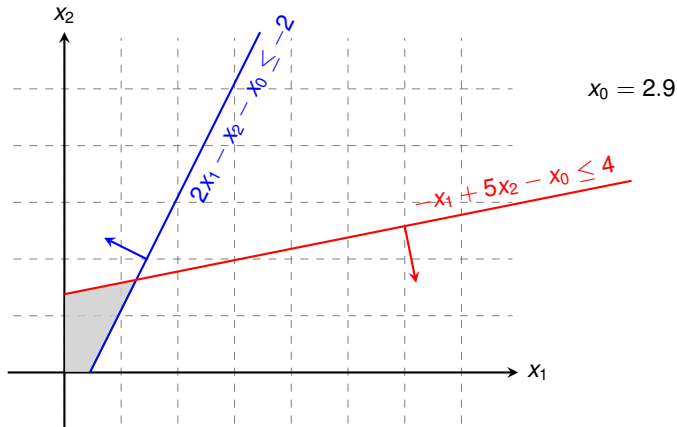
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ & & & & x_0, x_1, x_2 & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

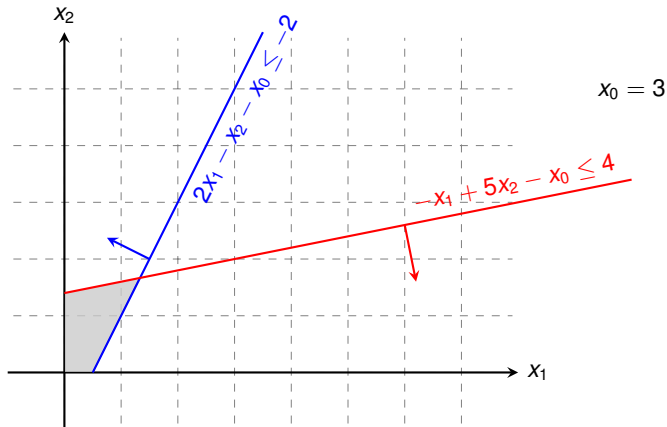
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Geometric Illustration

maximise
subject to

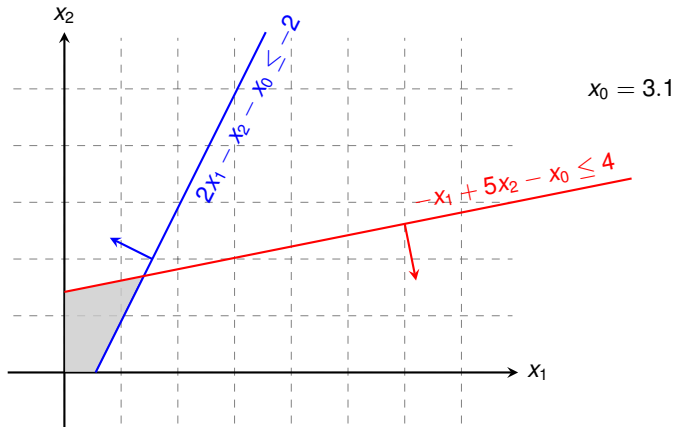
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Geometric Illustration

maximise
subject to

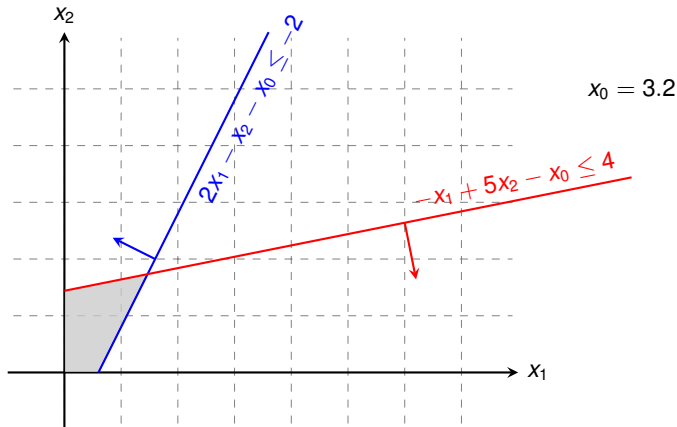
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ & & & & x_0, x_1, x_2 & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

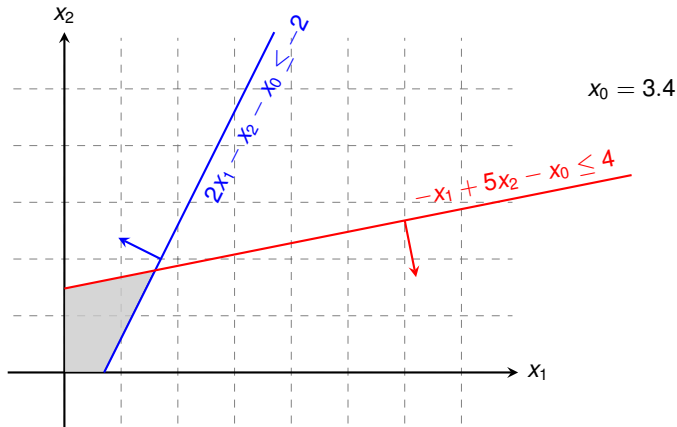
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

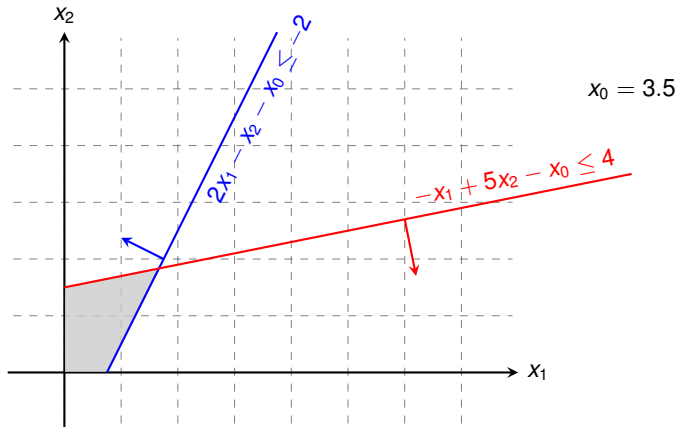
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Geometric Illustration

maximise
subject to

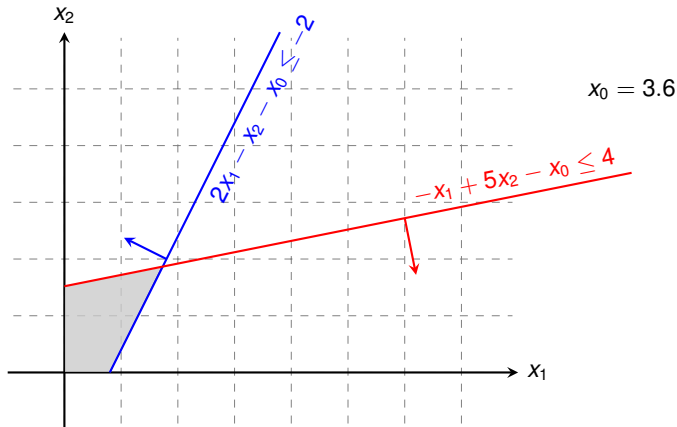
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Geometric Illustration

maximise
subject to

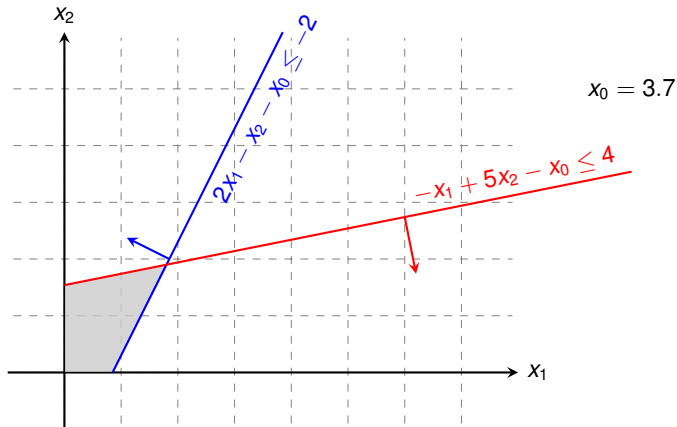
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

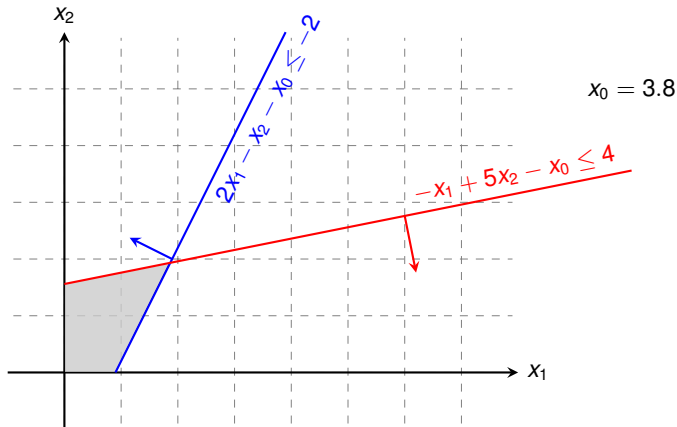
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Geometric Illustration

maximise
subject to

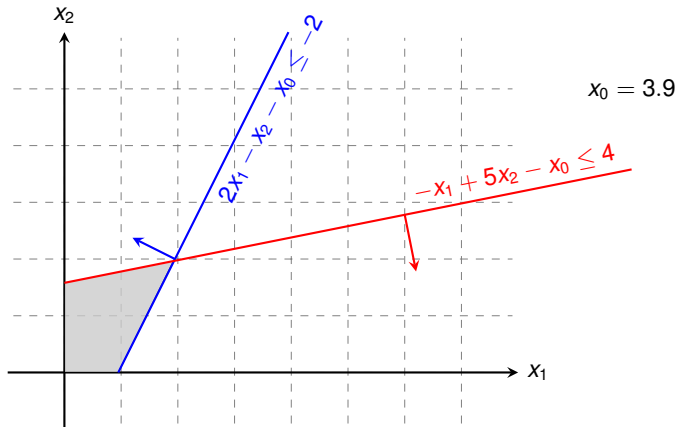
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

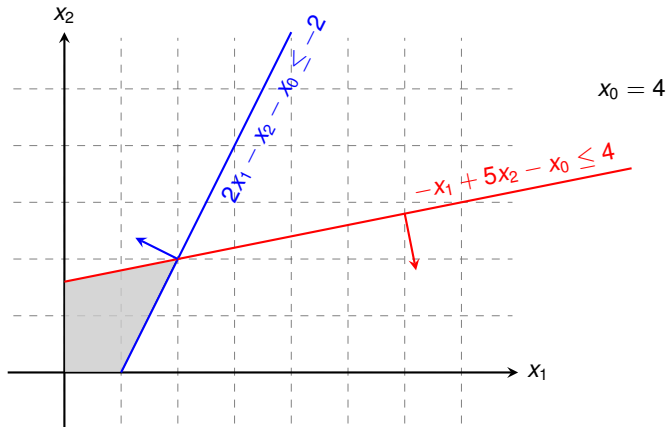
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Geometric Illustration

maximise
subject to

$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



INITIALIZE-SIMPLEX

```
INITIALIZE-SIMPLEX( $A, b, c$ )
1  let  $k$  be the index of the minimum  $b_i$ 
2  if  $b_k \geq 0$  // is the initial basic solution feasible?
3      return ( $\{1, 2, \dots, n\}, \{n + 1, n + 2, \dots, n + m\}, A, b, c, 0$ )
4  form  $L_{\text{aux}}$  by adding  $-x_0$  to the left-hand side of each constraint
   and setting the objective function to  $-x_0$ 
5  let  $(N, B, A, b, c, v)$  be the resulting slack form for  $L_{\text{aux}}$ 
6   $l = n + k$ 
7  //  $L_{\text{aux}}$  has  $n + 1$  nonbasic variables and  $m$  basic variables.
8   $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$ 
9  // The basic solution is now feasible for  $L_{\text{aux}}$ .
10 iterate the while loop of lines 3–12 of SIMPLEX until an optimal solution
   to  $L_{\text{aux}}$  is found
11 if the optimal solution to  $L_{\text{aux}}$  sets  $\bar{x}_0$  to 0
12     if  $\bar{x}_0$  is basic
13         perform one (degenerate) pivot to make it nonbasic
14         from the final slack form of  $L_{\text{aux}}$ , remove  $x_0$  from the constraints and
           restore the original objective function of  $L$ , but replace each basic
           variable in this objective function by the right-hand side of its
           associated constraint
15     return the modified final slack form
16 else return “infeasible”
```

Test solution with $N = \{1, 2, \dots, n\}$, $B = \{n + 1, n + 2, \dots, n + m\}$, $\bar{x}_i = b_i$ for $i \in B$, $\bar{x}_i = 0$ otherwise.

INITIALIZE-SIMPLEX(A, b, c)

- 1 let k be the index of the minimum b_i
- 2 **if** $b_k \geq 0$ // is the initial basic solution feasible?
- 3 **return** ($\{1, 2, \dots, n\}, \{n + 1, n + 2, \dots, n + m\}, A, b, c, 0$)
- 4 form L_{aux} by adding $-x_0$ to the left-hand side of each constraint and setting the objective function to $-x_0$
- 5 let (N, B, A, b, c, v) be the resulting slack form for L_{aux}
- 6 $l = n + k$
- 7 // L_{aux} has $n + 1$ nonbasic variables and m basic variables.
- 8 $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$
- 9 // The basic solution is now feasible for L_{aux} .
- 10 iterate the **while** loop of lines 3–12 of SIMPLEX until an optimal solution to L_{aux} is found
- 11 **if** the optimal solution to L_{aux} sets \bar{x}_0 to 0
- 12 **if** \bar{x}_0 is basic
- 13 perform one (degenerate) pivot to make it nonbasic
- 14 from the final slack form of L_{aux} , remove x_0 from the constraints and restore the original objective function of L , but replace each basic variable in this objective function by the right-hand side of its associated constraint
- 15 **return** the modified final slack form
- 16 **else return** “infeasible”

INITIALIZE-SIMPLEX(A, b, c)

- 1 let k be the index of the minimum b_i
- 2 **if** $b_k \geq 0$ // is the initial basic solution feasible?
- 3 **return** ($\{1, 2, \dots, n\}, \{n+1, n+2, \dots, n+m\}, A, b, c, 0$)
- 4 form L_{aux} by adding $-x_0$ to the left-hand side of each constraint
and setting the objective function to $-x_0$
- 5 let (N, B, A, b, c, v) be the resulting slack form for L_{aux}
- 6 $l = n + k$
- 7 // L_{aux} has $n + 1$ nonbasic variables and m basic variables.
- 8 $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$
- 9 // The basic solution is now feasible for L_{aux} .
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- 15 **return** the modified final slack form
- 16 **else return** “infeasible”

Test solution with $N = \{1, 2, \dots, n\}$, $B = \{n+1, n+2, \dots, n+m\}$, $\bar{x}_i = b_i$ for $i \in B$, $\bar{x}_i = 0$ otherwise.

ℓ will be the leaving variable so
that x_ℓ has the most negative value.

INITIALIZE-SIMPLEX(A, b, c)

- 1 let k be the index of the minimum b_i
- 2 **if** $b_k \geq 0$ // is the initial basic solution feasible?
- 3 **return** ($\{1, 2, \dots, n\}, \{n+1, n+2, \dots, n+m\}, A, b, c, 0$)
- 4 form L_{aux} by adding $-x_0$ to the left-hand side of each constraint
and setting the objective function to $-x_0$
- 5 let (N, B, A, b, c, v) be the resulting slack form for L_{aux}
- 6 $l = n + k$
- 7 // L_{aux} has $n + 1$ nonbasic variables and m basic variables.
- 8 $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$
- 9 // The basic solution is now feasible for L_{aux} .
- 10 iterate the **while** loop of lines 3–12 of SIMPLEX until an optimal solution
to L_{aux} is found
- 11 **if** the optimal solution to L_{aux} sets \bar{x}_0 to 0
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- 13 perform one (degenerate) pivot to make it nonbasic
- 14 from the final slack form of L_{aux} , remove x_0 from the constraints and
restore the original objective function of L , but replace each basic
variable in this objective function by the right-hand side of its
associated constraint
- 15 **return** the modified final slack form
- 16 **else return** “infeasible”

Test solution with $N = \{1, 2, \dots, n\}$, $B = \{n+1, n+2, \dots, n+m\}$, $\bar{x}_i = b_i$ for $i \in B$, $\bar{x}_i = 0$ otherwise.

ℓ will be the leaving variable so that x_ℓ has the most negative value.

Pivot step with x_ℓ leaving and x_0 entering.

INITIALIZE-SIMPLEX

INITIALIZE-SIMPLEX(A, b, c)

- 1 let k be the index of the minimum b_i
- 2 **if** $b_k \geq 0$ // is the initial basic solution feasible?
- 3 **return** ($\{1, 2, \dots, n\}, \{n+1, n+2, \dots, n+m\}, A, b, c, 0$)
- 4 form L_{aux} by adding $-x_0$ to the left-hand side of each constraint
and setting the objective function to $-x_0$
- 5 let (N, B, A, b, c, v) be the resulting slack form for L_{aux}
- 6 $l = n + k$
- 7 // L_{aux} has $n + 1$ nonbasic variables and m basic variables.
- 8 $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$
- 9 // The basic solution is now feasible for L_{aux} .
- 10 iterate the **while** loop of lines 3–12 of SIMPLEX until an optimal solution
to L_{aux} is found
- 11 **if** the optimal solution to L_{aux} sets \bar{x}_0 to 0
- 12 **if** \bar{x}_0 is basic
- 13 perform one (degenerate) pivot to make it nonbasic
- 14 from the final slack form of L_{aux} , remove x_0 from the constraints and
restore the original objective function of L , but replace each basic
variable in this objective function by the right-hand side of its
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ℓ will be the leaving variable so that x_ℓ has the most negative value.

Pivot step with x_ℓ leaving and x_0 entering.

This pivot step does not change the value of any variable.

Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{llllll} \text{maximise} & 2x_1 & - & x_2 & & \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & \leq & 2 \\ & x_1 & - & 5x_2 & \leq & -4 \\ & & & x_1, x_2 & \geq & 0 \end{array}$$

Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximise} & 2x_1 - x_2 \\ \text{subject to} & \\ & 2x_1 - x_2 \leq 2 \\ & x_1 - 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

↓
Formulating the auxiliary linear program

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Formulating the auxiliary linear program

$$\begin{array}{llllll} \text{maximise} & & & - & x_0 \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & - & x_0 \leq 2 \\ & x_1 & - & 5x_2 & - & x_0 \leq -4 \\ & & & & & x_1, x_2, x_0 \geq 0 \end{array}$$

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Converting into slack form

Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximise} & 2x_1 - x_2 \\ \text{subject to} & \\ & 2x_1 - x_2 \leq 2 \\ & x_1 - 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

$$\begin{array}{ll} \text{maximise} & -x_0 \\ \text{subject to} & \\ & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_1, x_2, x_0 \geq 0 \end{array}$$

Converting into slack form

$$\begin{array}{ll} Z = & -x_0 \\ x_3 = & 2 - 2x_1 + x_2 + x_0 \\ x_4 = & -4 - x_1 + 5x_2 + x_0 \end{array}$$

Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximise} & 2x_1 - x_2 \\ \text{subject to} & \\ & 2x_1 - x_2 \leq 2 \\ & x_1 - 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

$$\begin{array}{ll} \text{maximise} & -x_0 \\ \text{subject to} & \\ & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_1, x_2, x_0 \geq 0 \end{array}$$

Basic solution
(0, 0, 0, 2, -4) not feasible!

Converting into slack form

$$\begin{array}{ll} Z = & -x_0 \\ x_3 = & 2 - 2x_1 + x_2 + x_0 \\ x_4 = & -4 - x_1 + 5x_2 + x_0 \end{array}$$

Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$

Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with x_0 entering and x_4 leaving

Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!

Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!



Pivot with x_2 entering and x_0 leaving

Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!



Pivot with x_2 entering and x_0 leaving

$$\begin{array}{rcllclcl} Z & = & & - & x_0 \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$

Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!

Pivot with x_2 entering and x_0 leaving

$$\begin{array}{rcllclcl} Z & = & & - & x_0 \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Optimal solution has $x_0 = 0$, hence the initial problem was feasible!

Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{array}{rclclclcl} Z & = & & - & x_0 & & & & \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{array}{rclclclcl} Z & = & & - & x_0 & & & \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

↓ Set $x_0 = 0$ and express objective function
by non-basic variables

Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{aligned}z &= && - && x_0 \\x_2 &= & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\x_3 &= & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5}\end{aligned}$$

$$2x_1 - x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}\right)$$

Set $x_0 = 0$ and express objective function by non-basic variables

$$\begin{aligned}z &= & -\frac{4}{5} & + & \frac{9x_1}{5} & - & \frac{x_4}{5} \\x_2 &= & \frac{4}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\x_3 &= & \frac{14}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5}\end{aligned}$$

Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{aligned} Z &= && - && x_0 \\ x_2 &= && \frac{4}{5} &- & \frac{x_0}{5} &+ & \frac{x_1}{5} &+ & \frac{x_4}{5} \\ x_3 &= && \frac{14}{5} &+ & \frac{4x_0}{5} &- & \frac{9x_1}{5} &+ & \frac{x_4}{5} \end{aligned}$$

$$2x_1 - x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}\right)$$

Set $x_0 = 0$ and express objective function by non-basic variables

$$\begin{aligned} Z &= && -\frac{4}{5} &+ & \frac{9x_1}{5} &- & \frac{x_4}{5} \\ x_2 &= && \frac{4}{5} &+ & \frac{x_1}{5} &+ & \frac{x_4}{5} \\ x_3 &= && \frac{14}{5} &- & \frac{9x_1}{5} &+ & \frac{x_4}{5} \end{aligned}$$

Basic solution $(0, \frac{4}{5}, \frac{14}{5}, 0)$, which is feasible!

Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{array}{rclclcl} z & = & & - & x_0 & & & & \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

$$2x_1 - x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}\right)$$

Set $x_0 = 0$ and express objective function by non-basic variables

$$\begin{array}{rclclcl} z & = & -\frac{4}{5} & + & \frac{9x_1}{5} & - & \frac{x_4}{5} \\ x_2 & = & \frac{4}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Basic solution $(0, \frac{4}{5}, \frac{14}{5}, 0)$, which is feasible!

Lemma 29.12

If a linear program L has no feasible solution, then INITIALIZE-SIMPLEX returns “infeasible”. Otherwise, it returns a valid slack form for which the basic solution is feasible.

Fundamental Theorem of Linear Programming

Theorem 29.13 (Fundamental Theorem of Linear Programming)

Any linear program L , given in standard form, either

1. has an optimal solution with a finite objective value,
2. is infeasible, or
3. is unbounded.

If L is infeasible, SIMPLEX returns “infeasible”. If L is unbounded, SIMPLEX returns “unbounded”. Otherwise, SIMPLEX returns an optimal solution with a finite objective value.

Fundamental Theorem of Linear Programming

Theorem 29.13 (Fundamental Theorem of Linear Programming)

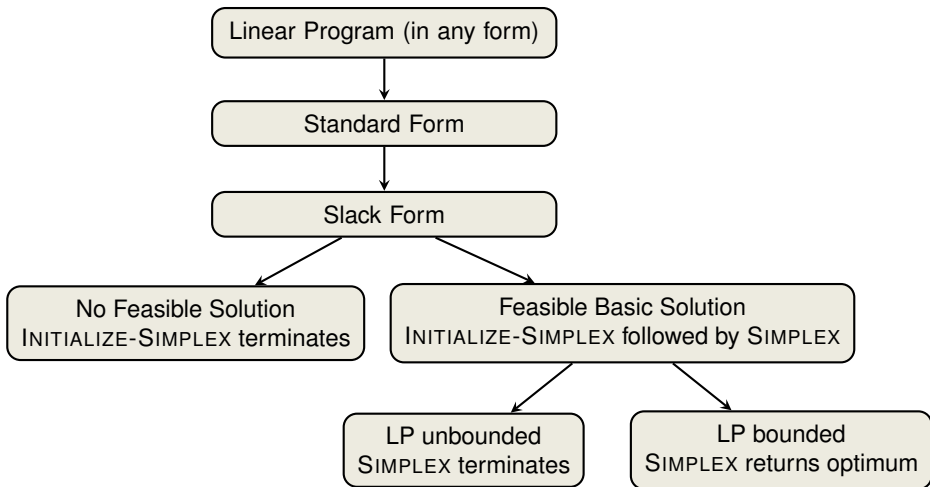
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Proof requires the concept of **duality**, which is not covered in this course (for details see CLRS3, Chapter 29.4)

Workflow for Solving Linear Programs



Linear Programming and Simplex: Summary and Outlook

Linear Programming



Linear Programming and Simplex: Summary and Outlook

Linear Programming

- extremely versatile tool for modelling problems of all kinds

Linear Programming and Simplex: Summary and Outlook

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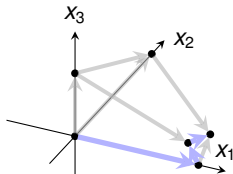
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Simplex Algorithm

- **In practice**: usually terminates in polynomial time, i.e., $O(m + n)$



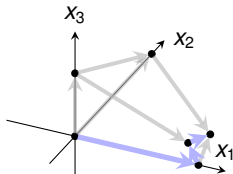
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Linear Programming and Simplex: Summary and Outlook

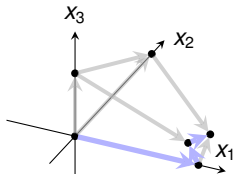
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Research Problem: Is there a pivoting rule which makes SIMPLEX a polynomial-time algorithm?



Linear Programming and Simplex: Summary and Outlook

Linear Programming

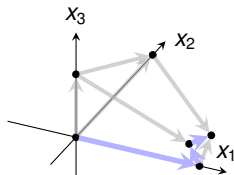
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Polynomial-Time Algorithms



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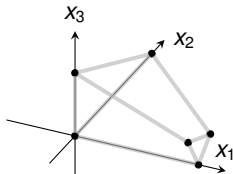
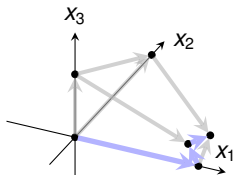
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Polynomial-Time Algorithms

- **Interior-Point Methods**: traverses the interior of the feasible set of solutions (not just vertices!)



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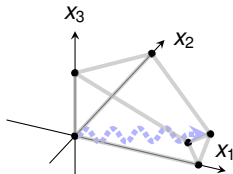
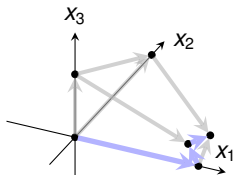
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Polynomial-Time Algorithms

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Outline

Simplex Algorithm by Example

Details of the Simplex Algorithm

Finding an Initial Solution

Appendix: Cycling and Termination (non-examinable)

Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.

Termination

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$$Z = \quad \quad \quad x_1 + x_2 + x_3$$

$$x_4 = 8 - x_1 - x_2$$

$$x_5 = \quad \quad \quad x_2 - x_3$$

Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.

$$Z = \quad \quad \quad x_1 + x_2 + x_3$$

$$x_4 = 8 - x_1 - x_2$$

$$x_5 = \quad \quad \quad x_2 - x_3$$

↓ Pivot with x_1 entering and x_4 leaving

Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.

$$Z = \quad \quad \quad x_1 + x_2 + x_3$$

$$x_4 = 8 - x_1 - x_2$$

$$x_5 = \quad \quad \quad x_2 - x_3$$

↓ Pivot with x_1 entering and x_4 leaving

$$Z = 8 \quad \quad \quad + x_3 - x_4$$

$$x_1 = 8 - x_2 \quad \quad \quad - x_4$$

$$x_5 = \quad \quad \quad x_2 - x_3$$

Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.

$$Z = \quad \quad \quad x_1 + x_2 + x_3$$

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↓ Pivot with x_1 entering and x_4 leaving

$$Z = 8 \quad \quad \quad + x_3 - x_4$$

$$x_1 = 8 - x_2 \quad \quad \quad - x_4$$

$$x_5 = \quad \quad \quad x_2 - x_3$$

↓ Pivot with x_3 entering and x_5 leaving

Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.

$$\begin{array}{rcll} Z & = & & x_1 + x_2 + x_3 \\ x_4 & = & 8 & - x_1 - x_2 \\ x_5 & = & & x_2 - x_3 \end{array}$$

↓ Pivot with x_1 entering and x_4 leaving

$$\begin{array}{rcll} Z & = & 8 & + x_3 - x_4 \\ x_1 & = & 8 & - x_2 - x_4 \\ x_5 & = & & x_2 - x_3 \end{array}$$

↓ Pivot with x_3 entering and x_5 leaving

$$\begin{array}{rcll} Z & = & 8 & + x_2 - x_4 - x_5 \\ x_1 & = & 8 & - x_2 - x_4 \\ x_3 & = & & x_2 - x_5 \end{array}$$

Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.

$$\begin{array}{rcll} Z & = & & x_1 + x_2 + x_3 \\ x_4 & = & 8 & - x_1 - x_2 \\ x_5 & = & & x_2 - x_3 \end{array}$$

↓ Pivot with x_1 entering and x_4 leaving

$$\begin{array}{rcll} Z & = & 8 & + x_3 - x_4 \\ x_1 & = & 8 & - x_2 - x_4 \\ x_5 & = & & x_2 - x_3 \end{array}$$

↓ Pivot with x_3 entering and x_5 leaving

$$\begin{array}{rcll} Z & = & 8 & + x_2 - x_4 - x_5 \\ x_1 & = & 8 & - x_2 - x_4 \\ x_3 & = & & x_2 - x_5 \end{array}$$

Cycling: If additionally slack form at two iterations are identical, SIMPLEX fails to terminate!



Exercise: Execute one more step of the Simplex Algorithm on the tableau from the previous slide.

Cycling: SIMPLEX may fail to terminate.

Termination and Running Time

It is theoretically possible, but very rare in practice.

Cycling: SIMPLEX may fail to terminate.

Termination and Running Time

It is theoretically possible, but very rare in practice.

Cycling: SIMPLEX may fail to terminate.

Anti-Cycling Strategies



Termination and Running Time

It is theoretically possible, but very rare in practice.

Cycling: SIMPLEX may fail to terminate.

Anti-Cycling Strategies

1. **Bland's rule:** Choose entering variable with smallest index

Termination and Running Time

It is theoretically possible, but very rare in practice.

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Every set B of basic variables uniquely determines a slack form, and there are at most $\binom{n+m}{m}$ unique slack forms.