# Mobile Health: Practical 2

# Machine Learning and Features of Health Data

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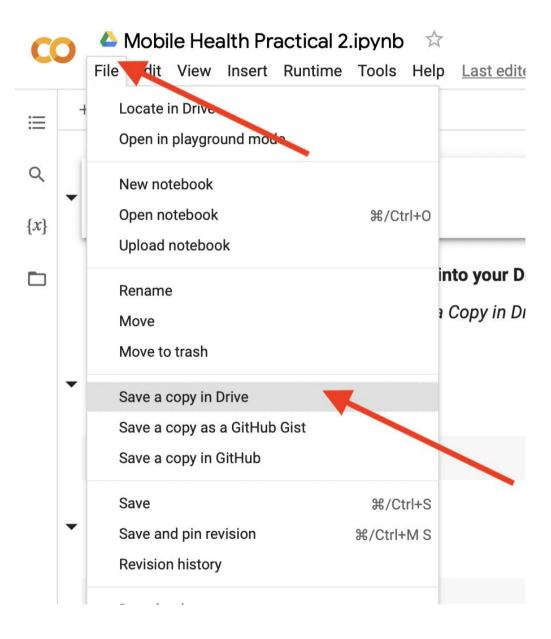


## Colab Notebook

Please open the Colab notebook for today's session by visiting the relevant link on Moodle

Then, please save a copy of this notebook into your Drive:

• File > Save a Copy in Drive





### Recap: IMU data

Inertial Measurement Unit (IMU) data is collected via:

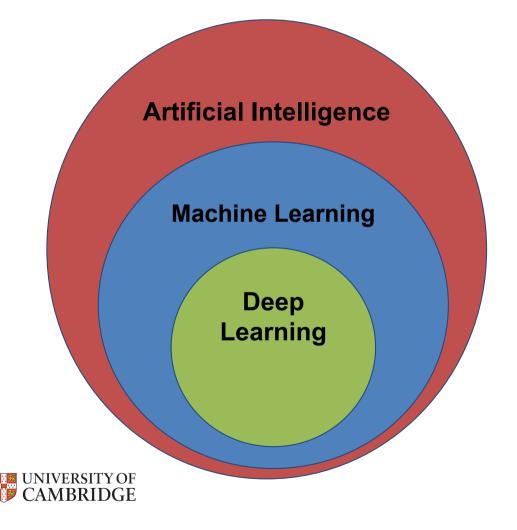
- Accelerometers
- Gyroscopes
- Magnetometers

Its preprocessing may involve:

- Signal filtering (removing certain frequencies)
- Magnitude normalisation
- Localising temporal patterns of interest
- Mapping classes with windows



### We will be focusing on Deep Learning



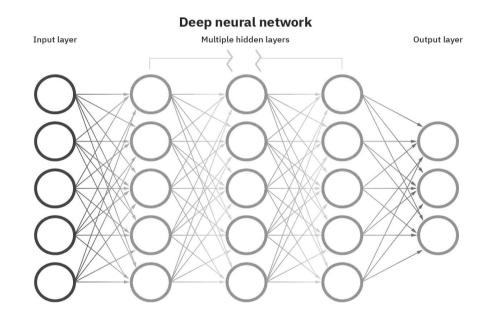
### **Traditional ML**

Enables machines to "learn" how to undertake certain tasks with no human supervision

**Deep Learning** Subset of ML targeted on building artificial neural networks

### More on Deep Learning

- DL is implemented using Neural Networks
- Layers are the highest-level building blocks in DL:
  - They receive weighted inputs and transform them using mathematical functions
  - Each layer passes the transformed values as output to the next layer
  - Consequently, higher-level features are identified from lower-level features obtained at previous layers





### MotionSense: IMU dataset we will be using

- Time-series data generated by accelerometer and gyroscope sensors
  - Altitude, gravity, user acceleration, rotation rate
- Collected with an iPhone 6s kept in the participant's front pocket
- All data collected in 50Hz sample rate
- 24 participants
- 6 activities in 15 trials in the same environment and conditions
  - Going downstairs, upstairs, walking, jogging, sitting, and standing



Malekzadeh, Mohammad & Clegg, Richard & Cavallaro, Andrea & Haddadi, Hamed. (2019). Mobile sensor data anonymization. Proceedings of the International Conference on Internet of Things Design and Implementation, 49-58.

### Libraries to import to our Colab notebook

- <u>import tensorflow as tf</u>
- import pandas as pd
- import **numpy** as np
- import **sklearn**.model selection
- import **sklearn**.metrics
- import scipy
- import requests
- import zipfile
- import os
- import re
- import glob





### 1.1 Downloading the Dataset

```
file_url = "..."
dataset_file_name = "B_Accelerometer_data.zip"
data_directory = "data"
accelerometer_data_folder_path = "data/B_Accelerometer_data/B_Accelerometer_data"
```

```
r = requests.get(file url)
```

```
with open(dataset_file_name, 'wb') as f:
```

```
f.write(r.content)
```

```
with zipfile.ZipFile(dataset_file_name, 'r') as zip_ref:
    zip_ref.extractall(os.path.join(data_directory, dataset_file_name.split(".")[0]))
```



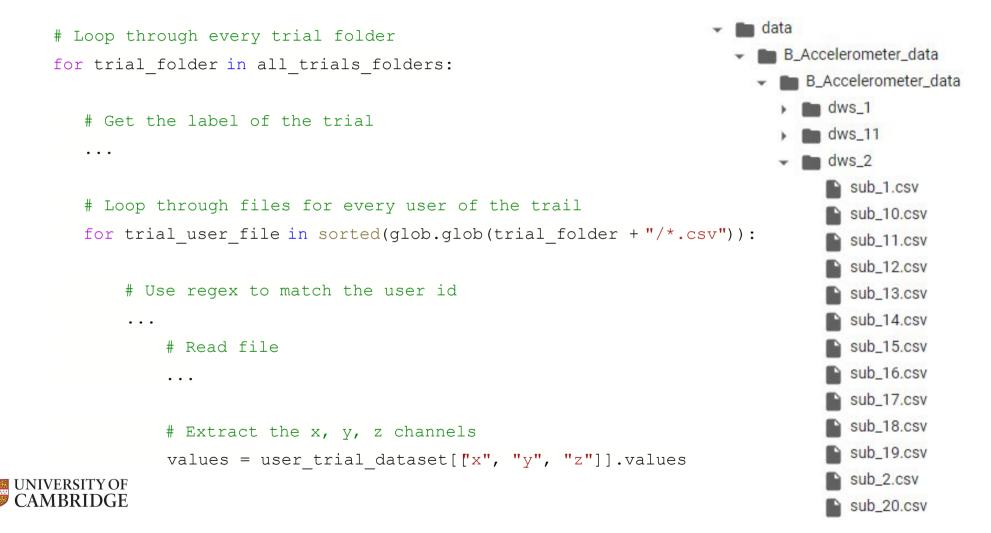
### Labels in this Dataset

There are 6 different labels:

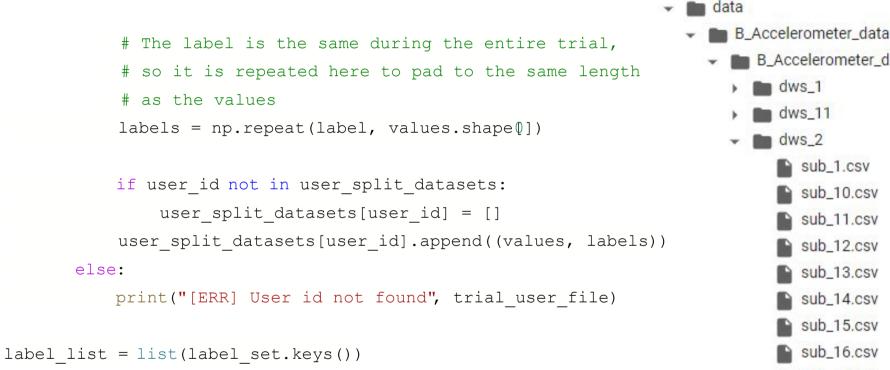
- dws: downstairs
- **ups:** upstairs
- **sit:** sitting
- **std:** standing
- wlk: walking
- **jog:** jogging



### 1.2 Loading the Dataset to Memory



### 1.2 Loading the Dataset to Memory

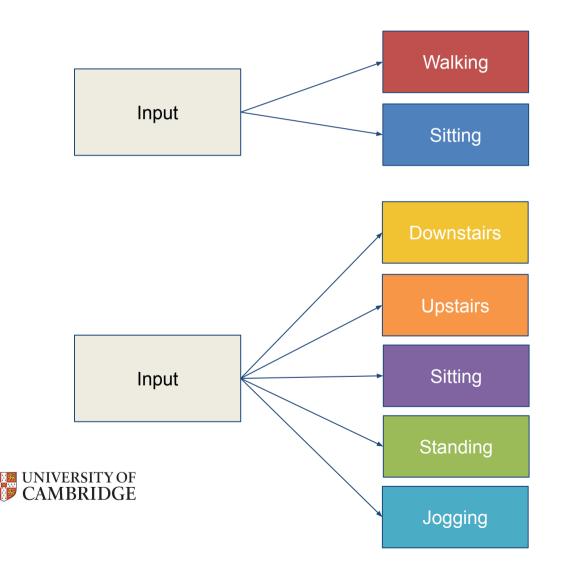


user split datasets.keys()





### Potential tasks that can be performed



**Binary Classification** 

Data is classified into two mutually exclusive groups

Multi-Class Classification Data is classified into three or more groups

# Splitting the dataset: train/validation/test

### • Training set:

• Data used to fit the model

### • Validation set:

- Data used to evaluate the model while tuning model's hyperparameters
- Can lead to biases as the "knowledge" of the validation set can indirectly affect the training
- Test set:
  - Data used to evaluate success of the final model
  - Fully unbiased

### How to partition our dataset into the subsets for optimal evaluation?



### Pre-processing the dataset

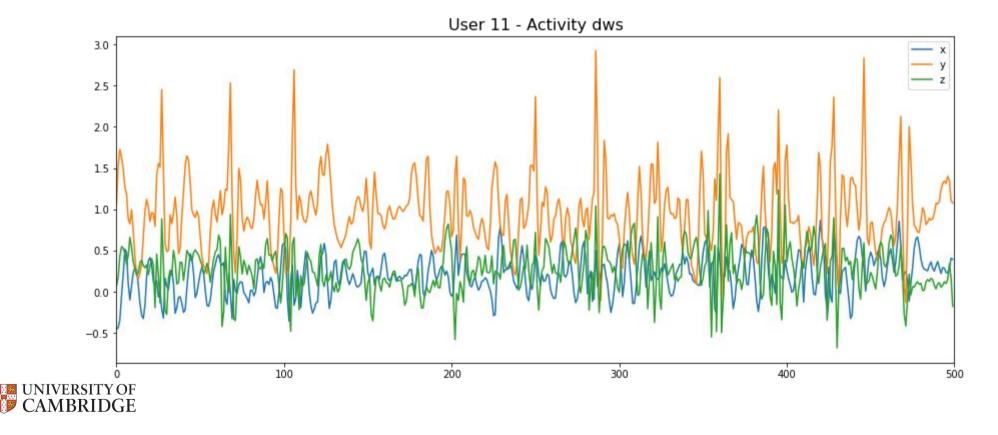
We need to:

- 1. Use a sliding window to make a windowed dataset
- 2. Split the dataset into a training and a test set
- 3. Normalise the datasets
- 4. Apply label encoding
- 5. Subdivide the training set into training and validation sets



### 1.3 Visualising the Data

timeseries, labels = user\_split\_datasets[user\_id][session]
plot\_accelerometer\_timeseries(timeseries[500])



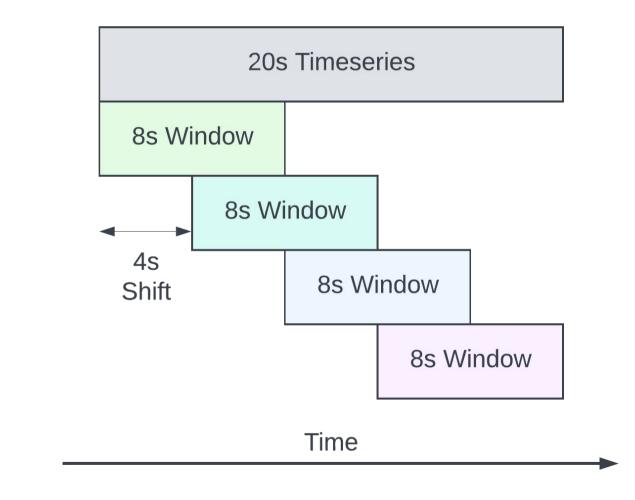
### Pre-processing the dataset

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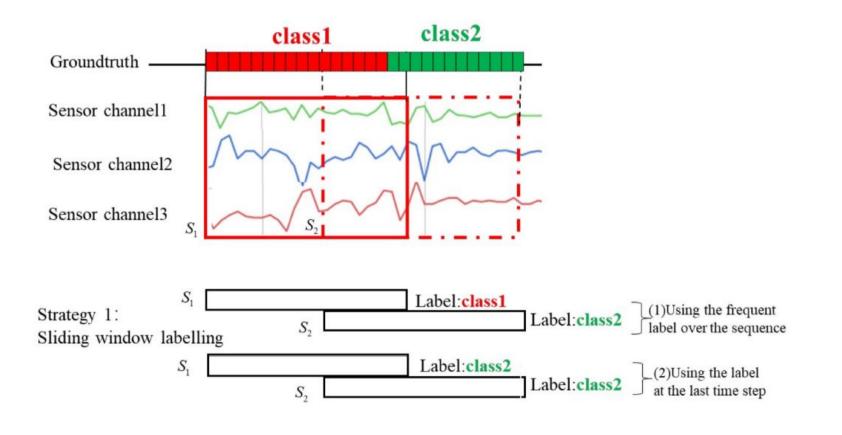


### 2.1 Sliding Window











Zhang, Yong & Zhang, Yu & Zhang, Zhao & Bao, Jie & Song, Yunpeng. (2018). Human activity recognition based on time series analysis using U-Net.

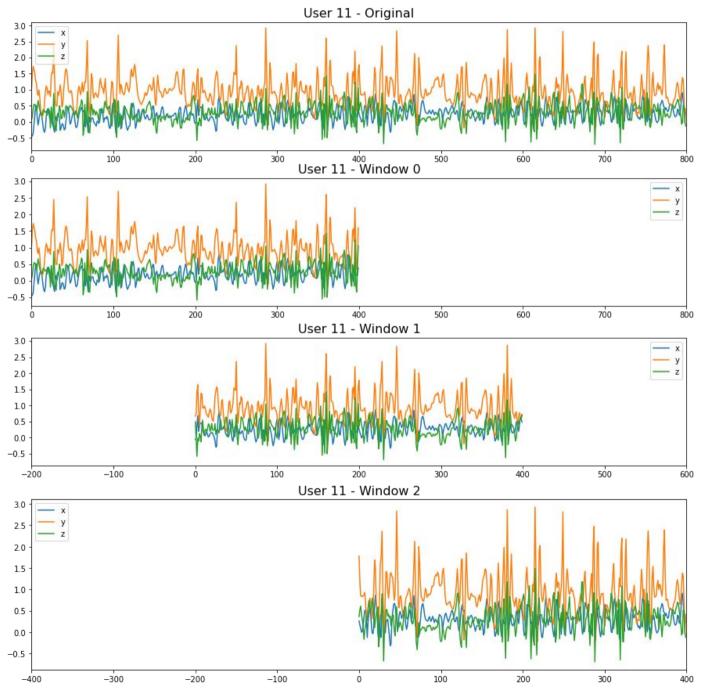
### 2.1 Making a Windowed Dataset

```
def get_windows_dataset_from_user_list_format(user_datasets, window_size=400,
shift=200, stride=1, verbose=0)
```

```
window_size = 400
user_datasets_windowed =
    get_windows_dataset_from_user_list_format(
        user_split_datasets,
        window_size=window_size,
        shift=window_size//2
    )
```



### 2.1.1 Windowed Dataset



### Pre-processing the dataset

We need to:

- 1. Use a sliding window to make a windowed dataset
- 2. Split the dataset into a training and a test set
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## 2.2 Training & Testing Split

def combine\_windowed\_dataset(user\_datasets\_windowed, train\_users, test\_users = None, verbose = 0)

Tr	aining	set			
+	(280,	400,	3)	Samples from User 10	9
+	(279,	400,	3)	Samples from User 1	1
+	(248,	400,	3)	Samples from User 1	2
+	(238,	400,	3)	Samples from User 1	3
+	(281,	400,	3)	Samples from User 1	5
+	(311,	400,	3)	Samples from User 10	5
+	(258,	400,	3)	Samples from User 1	7
+	(297,	400,	3)	Samples from User 18	8
+	(292,	400,	3)	Samples from User 2	
+	(259,	400,	3)	Samples from User 20	Э
+	(327,	400,	3)	Samples from User 2	1
+	(263,	400,	3)	Samples from User 2	2
+	(238,	400,	3)	Samples from User 24	4
+	(295,	400,	3)	Samples from User 3	
+	(262,	400,	3)	Samples from User 4	
+	(244,	400,	3)	Samples from User 5	
+	(287,	400,	3)	Samples from User 7	
+	(285,	400,	3)	Samples from User 8	
+	(267,	400,	3)	Samples from User 9	
					-
=	(5211	, 400	, 3)	Samples	

+	(293,	400,	3)	Samples	from User	1
+	(263,	400,	3)	Samples	from User	14
+	(343,	400,	3)	Samples	from User	19
+	(252,	400,	3)	Samples	from User	23
+	(268,	400,	3)	Samples	from User	6

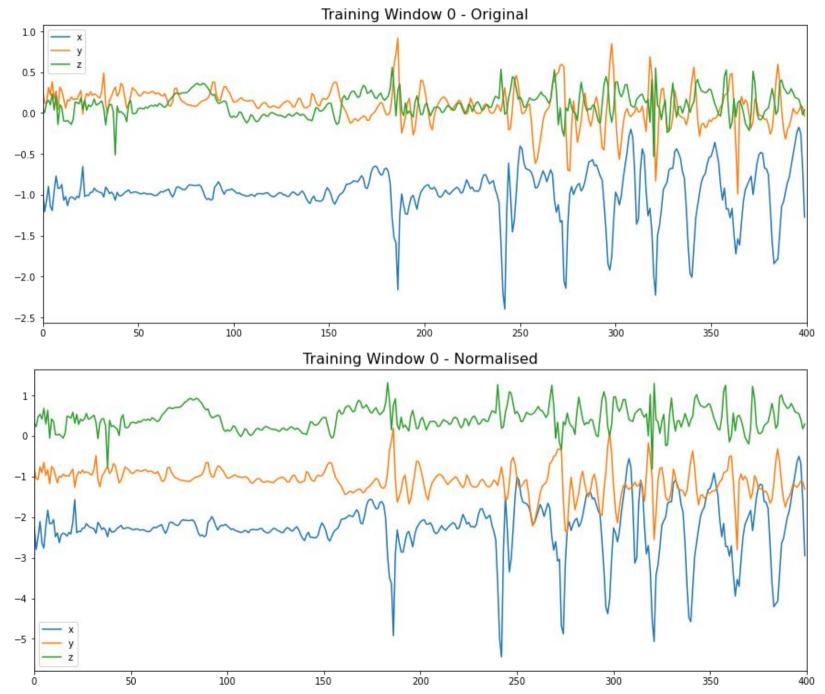
### Pre-processing the dataset

We need to:

- 1. Use a sliding window to make a windowed dataset
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### 2.3 Normalisation



### Pre-processing the dataset

We need to:

- 1. Use a sliding window to make a windowed dataset
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- 4. Apply label encoding
- 5. Subdivide the training set into training and validation sets



### 2.4 Label Encoding

def apply\_label\_map(y, label\_map)

Mapping						
dws> 0						
jog> 1	Original:	['dws'	'wlk' 'sit'	'wlk'	'std'	'sit']
sit> 2	Mapped:	-				-
std> 3		L	-			
ups> 4						
wlk> 5						



### Pre-processing the dataset

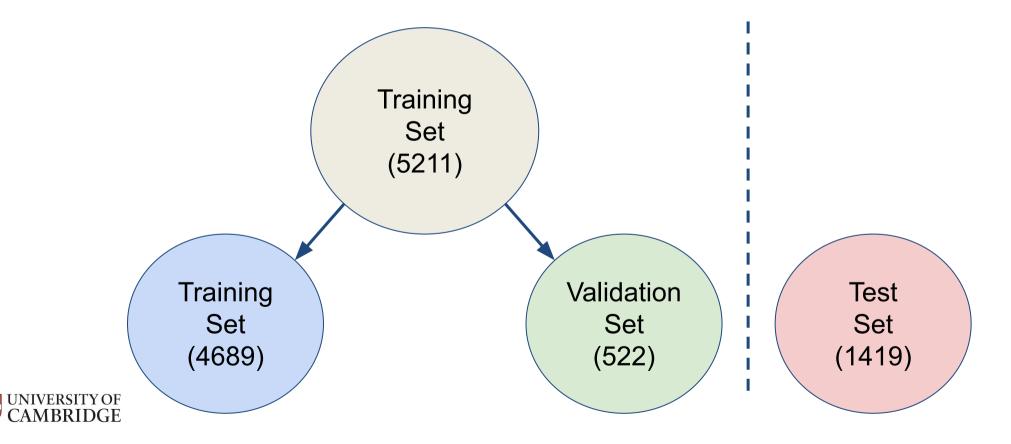
We need to:

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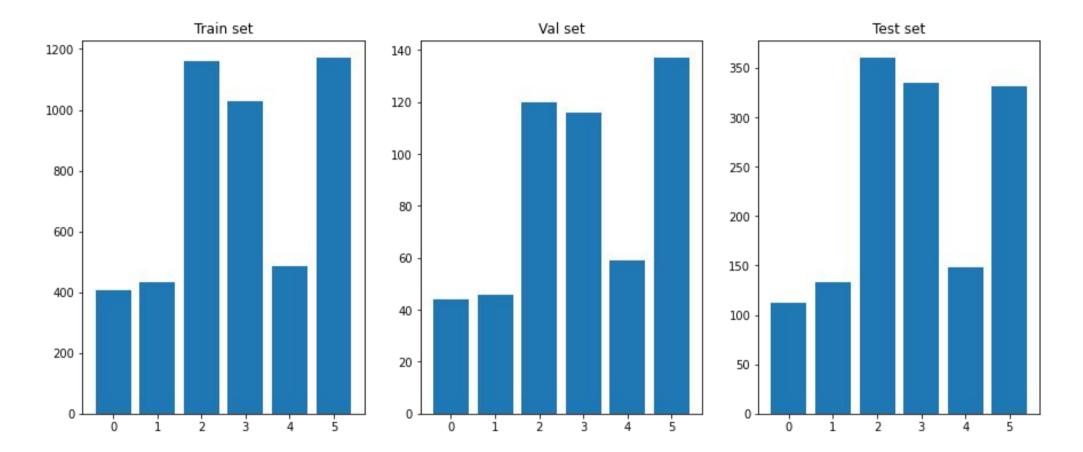


### 2.5 Training & Validation Split

sklearn.model\_selection.train\_test\_split



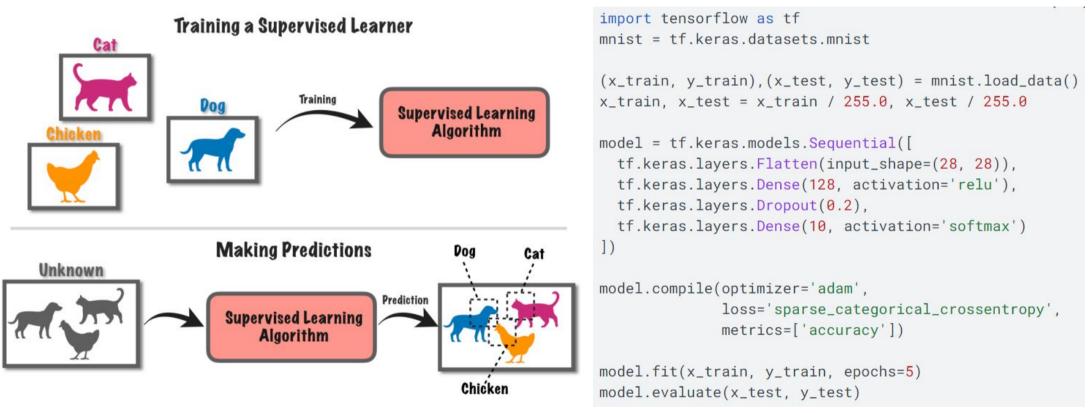
### 2.6 Label Distribution





# 3 Deep Learning

• Supervised Learning

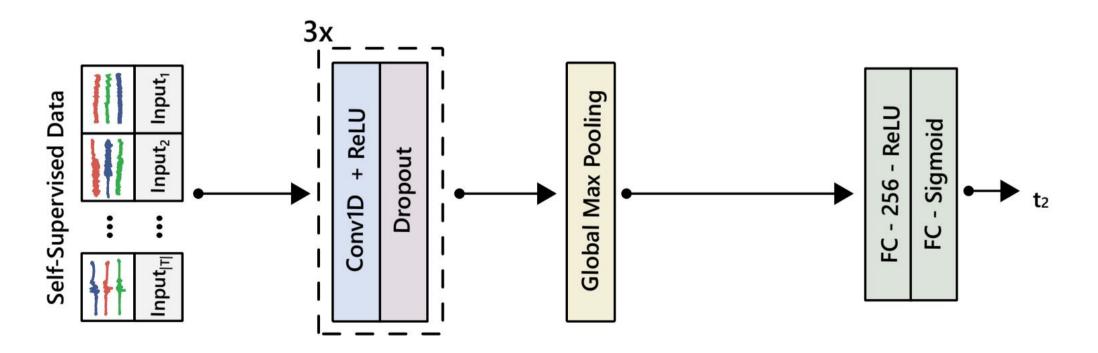




Jeffares, A. (2018). Supervised vs Unsupervised Learning in 3 Minutes [infographic]. https://towardsdatascience.com/supervised-vs-unsupervised-learning-in-2-minutes-72dad148f242

## 3.1 Building a CNN

• Transformation Prediction Network (TPN)



UNIVERSITY OF CAMBRIDGE

Saeed, A., Ozcelebi, T., & Lukkien, J. (2019). Multi-task self-supervised learning for human activity detection. Proceedings of the ACM on Interactive, Mobile, Wearable and Ubiquitous Technologies, 3(2), 1-30.

# 3.1 Building a CNN

• Transformation Prediction Network (TPN)

```
model = tf.keras.Sequential([
    tf.keras.Input(shape=train_x.shape[1:], name='input'),
    tf.keras.layers.Conv1D(32, 24, activation='relu', kernel_regularizer=tf.keras.regularizers.l2(l=1e-4)),
    tf.keras.layers.Dropout(0.1),
    tf.keras.layers.Conv1D(64, 16, activation='relu', kernel_regularizer=tf.keras.regularizers.l2(l=1e-4)),
    tf.keras.layers.Dropout(0.1),
    tf.keras.layers.Conv1D(96, 8, activation='relu', kernel_regularizer=tf.keras.regularizers.l2(l=1e-4)),
    tf.keras.layers.Conv1D(96, 8, activation='relu', kernel_regularizer=tf.keras.regularizers.l2(l=1e-4)),
    tf.keras.layers.Dropout(0.1),
    tf.keras.layers.GlobalMaxPool1D(data_format='channels_last', name='global_max_pooling1d'),
    tf.keras.layers.Dense(output_shape),
    tf.keras.layers.Softmax()
])
```



Saeed, A., Ozcelebi, T., & Lukkien, J. (2019). Multi-task self-supervised learning for human activity detection. Proceedings of the ACM on Interactive, Mobile, Wearable and Ubiquitous Technologies, 3(2), 1-30.

### 3.2 Training a Neural Network

```
optimizer = tf.keras.optimizers.Adam(learning_rate=0.003)
model.compile(
    optimizer=optimizer,
    loss=tf.keras.losses.SparseCategoricalCrossentropy(),
    metrics=['accuracy']
)
```

```
history = model.fit(
    x=train_set[0],
    y=train_set[1],
    validation_data=val_set,
    batch_size=256,
    shuffle=True,
    epochs=30
)
```

## **3.2 Training History**

Slide redacted due to this being a live coding exercise to be completed during the practical



## **3.2 Training History**

Slide redacted due to this being a live coding exercise to be completed during the practical



### 3.3 Evaluation

Slide redacted due to this being a live coding exercise to be completed during the practical

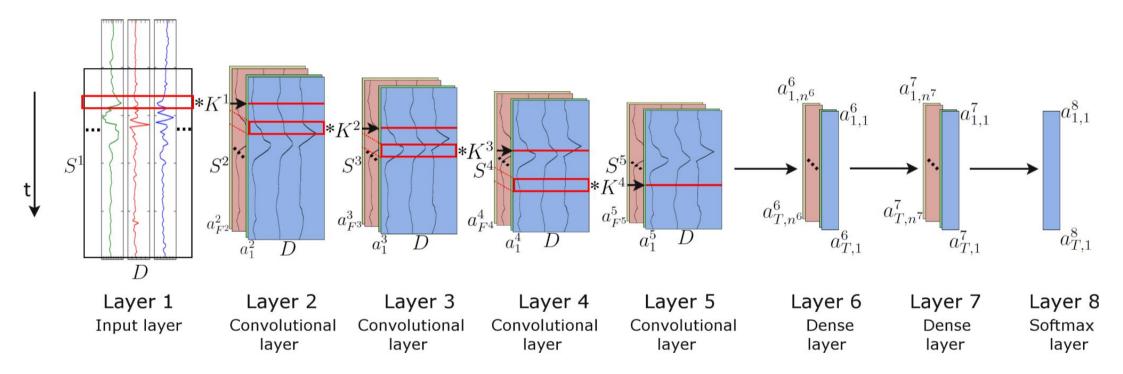


### 3.3 Evaluation

Slide redacted due to this being a live coding exercise to be completed during the practical



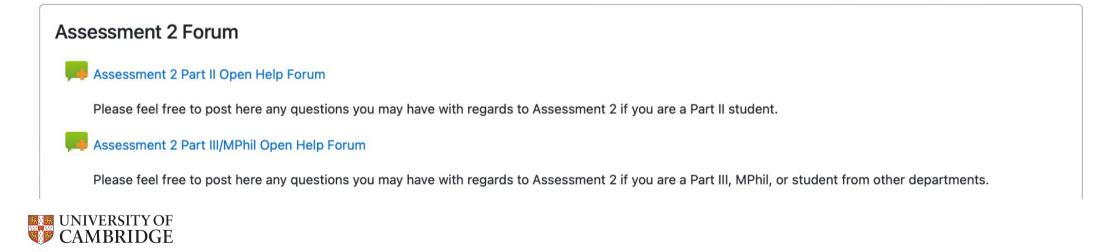
### 4 Exploration: DeepConvLSTM



UNIVERSITY OF Ordóñez, F. J., & Roggen, D. (2016). Deep convolutional and lstm recurrent neural networks for multimodal wearable activity recognition. Sensors, 16(1), 115.

## Assignment 2

- Released today, due on the **17th of March**
- Weighting: **70%** of the course grade
- **Part II:** Colab notebook and reflection report of 1,000 words
- **Part III/MPhil:** Colab notebook and a reflection report of 1,500 words
- Please use the help forum on Moodle for any questions



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### Mobile Health 2022-23

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### Questions

