

# Randomised Algorithms

## Lecture 6-7: Linear Programming

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Lent 2022



UNIVERSITY OF  
CAMBRIDGE

# Outline

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## Introduction

A Simple Example of a Linear Program

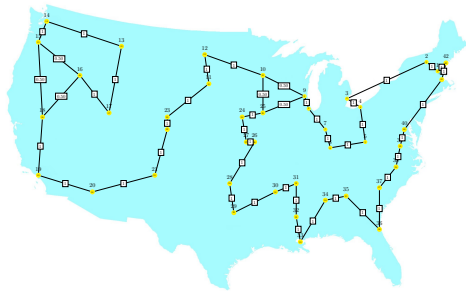
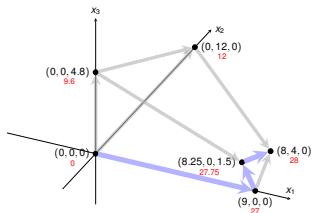
Formulating Problems as Linear Programs

Standard and Slack Forms

Simplex Algorithm

Finding an Initial Solution

# Introduction



- linear programming is a powerful tool in optimisation
- inspired more sophisticated techniques such as quadratic optimisation, convex optimisation, integer programming and semi-definite programming
- we will later use the connection between linear and integer programming to tackle several problems (Vertex-Cover, Set-Cover, TSP, satisfiability)

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Introduction

**A Simple Example of a Linear Program**

Formulating Problems as Linear Programs

Standard and Slack Forms

Simplex Algorithm

Finding an Initial Solution

# What are Linear Programs?

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Linear Programming (informal definition)

- maximise or minimise an objective, given limited resources (competing constraint)
- constraints are specified as (in)equalities
- objective function and constraints are **linear**

## A Simple Example of a Linear Optimisation Problem

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- Laptop

## A Simple Example of a Linear Optimisation Problem

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- Laptop
  - selling price to retailer: 1,000 GBP

## A Simple Example of a Linear Optimisation Problem

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- Laptop
  - selling price to retailer: 1,000 GBP
  - glass: 4 units



# A Simple Example of a Linear Optimisation Problem

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- Laptop

- selling price to retailer: 1,000 GBP
- glass: 4 units
- copper: 2 units

# A Simple Example of a Linear Optimisation Problem

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## ▪ Laptop

- selling price to retailer: 1,000 GBP
- glass: 4 units
- copper: 2 units
- rare-earth elements: 1 unit

# A Simple Example of a Linear Optimisation Problem

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- Laptop

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- selling price to retailer: 1,000 GBP
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- You have a **daily supply** of:



# A Simple Example of a Linear Optimisation Problem

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- copper: 2 units
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## ▪ Smartphone

- selling price to retailer: 1,000 GBP
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## ▪ You have a daily supply of:

- glass: 20 units

# A Simple Example of a Linear Optimisation Problem

## ▪ Laptop

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- copper: 2 units
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## ▪ Smartphone

- selling price to retailer: 1,000 GBP
- glass: 1 unit
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- rare-earth elements: 2 units



## ▪ You have a daily supply of:

- glass: 20 units
- copper: 10 units



# A Simple Example of a Linear Optimisation Problem

## ▪ Laptop

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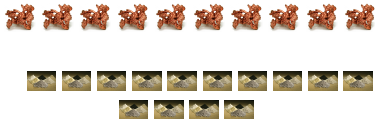
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## ▪ You have a daily supply of:

- glass: 20 units
- copper: 10 units
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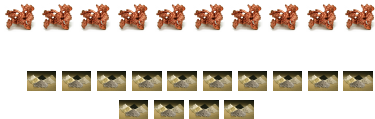
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## ▪ You have a daily supply of:

- glass: 20 units
- copper: 10 units
- rare-earth elements: 14 units
- (and enough of everything else...)

How to maximise your daily earnings?

## The Linear Program

Linear Program for the Production Problem

$$\begin{array}{llllll} \text{maximise} & x_1 & + & x_2 & & \\ \text{subject to} & & & & & \\ & 4x_1 & + & x_2 & \leq & 20 \\ & 2x_1 & + & x_2 & \leq & 10 \\ & x_1 & + & 2x_2 & \leq & 14 \\ & x_1, x_2 & & & \geq & 0 \end{array}$$

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The solution of this linear program yields the optimal production schedule.

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Formal Definition of Linear Program



## The Linear Program

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### Formal Definition of Linear Program

- Given  $a_1, a_2, \dots, a_n$  and a set of variables  $x_1, x_2, \dots, x_n$ , a **linear function**  $f$  is defined by

$$f(x_1, x_2, \dots, x_n) = a_1x_1 + a_2x_2 + \dots + a_nx_n.$$

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- Linear Equality:**  $f(x_1, x_2, \dots, x_n) = b$
- Linear Inequality:**  $f(x_1, x_2, \dots, x_n) \begin{matrix} \geq \\ \leq \end{matrix} b$

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Linear Constraints

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- Linear Inequality:**  $f(x_1, x_2, \dots, x_n) \begin{matrix} \geq \\ \leq \end{matrix} b$
- Linear-Programming Problem:** either minimise or maximise a linear function subject to a set of linear constraints

Linear Constraints

## Finding the Optimal Production Schedule

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## Finding the Optimal Production Schedule

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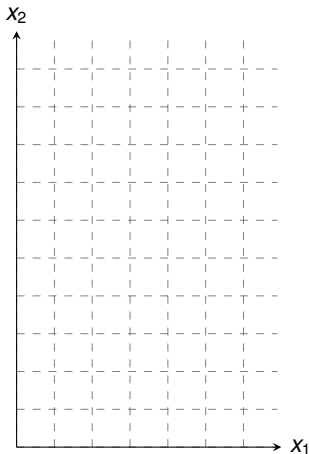
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Any setting of  $x_1$  and  $x_2$  satisfying all constraints is a feasible solution

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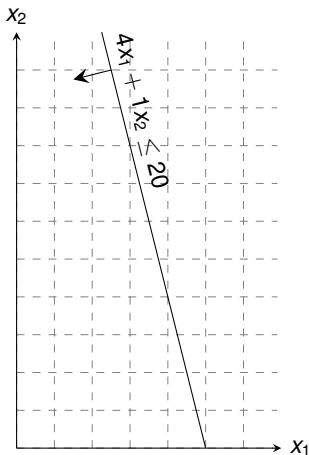
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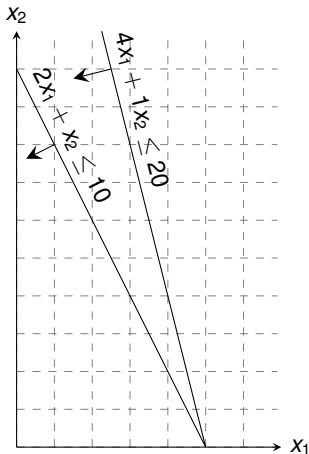




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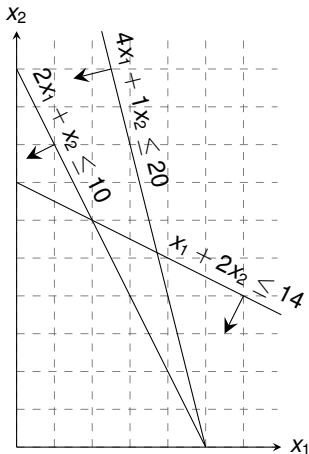
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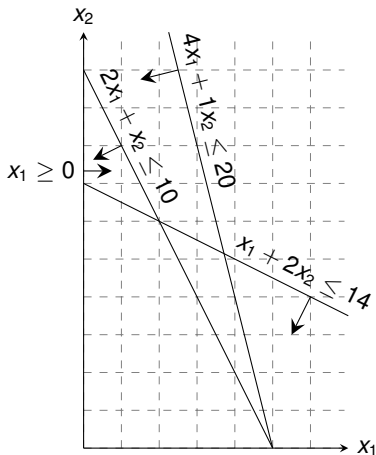
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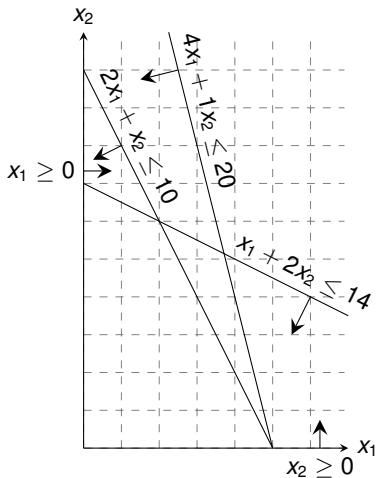
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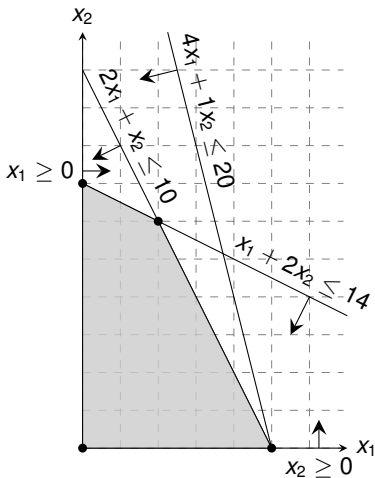




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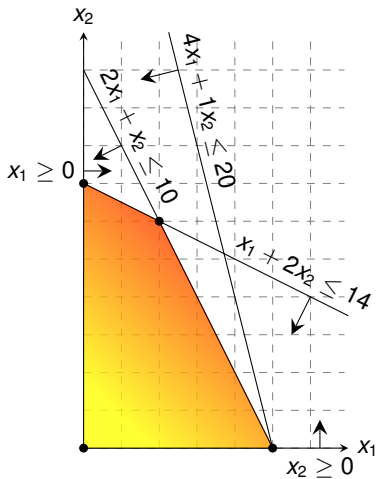
**Graphical Procedure:** Move the line  $x_1 + x_2 = z$  as far up as possible.



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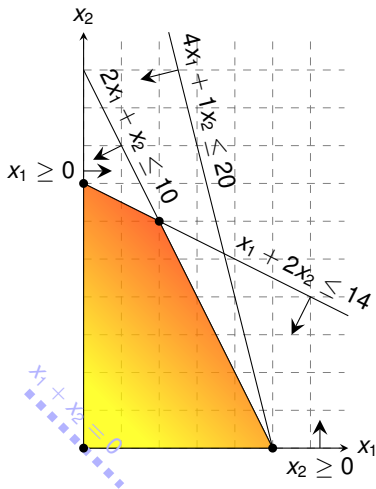
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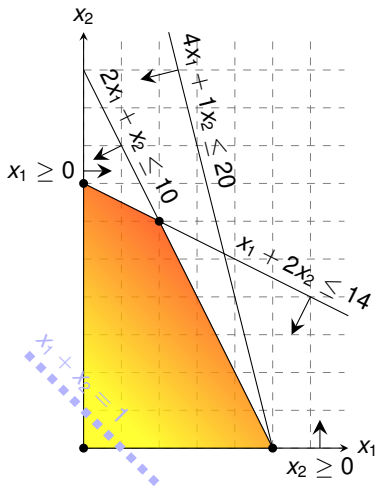




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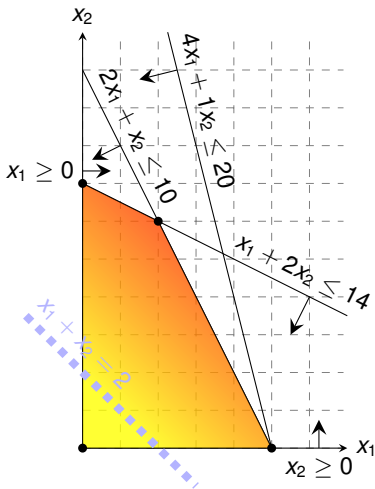
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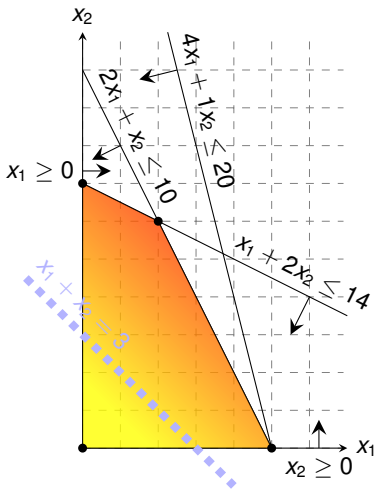
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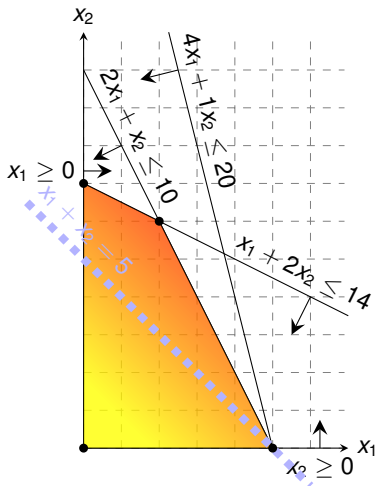




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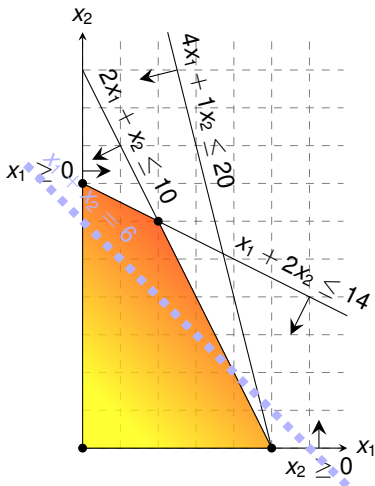
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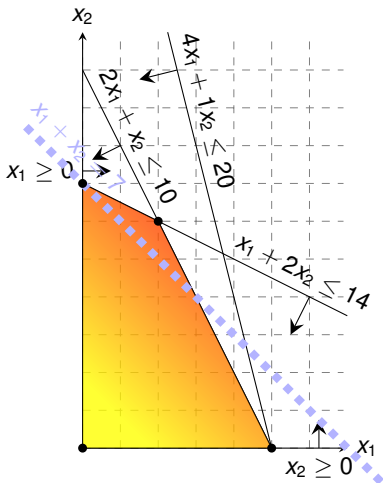


## Finding the Optimal Production Schedule

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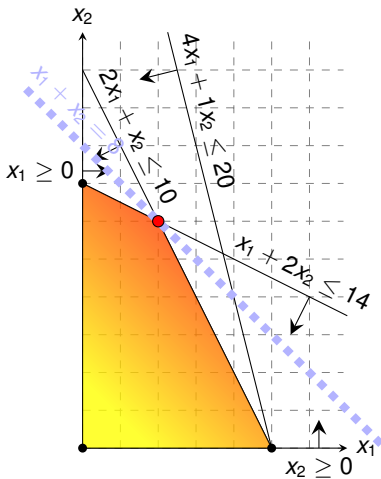




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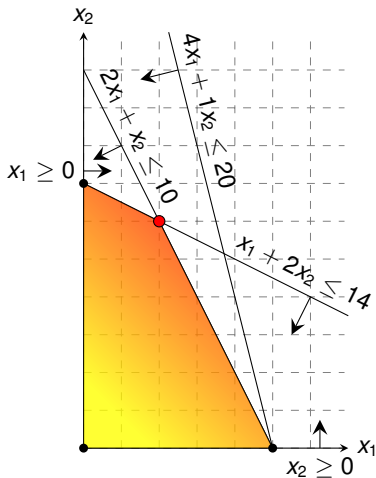
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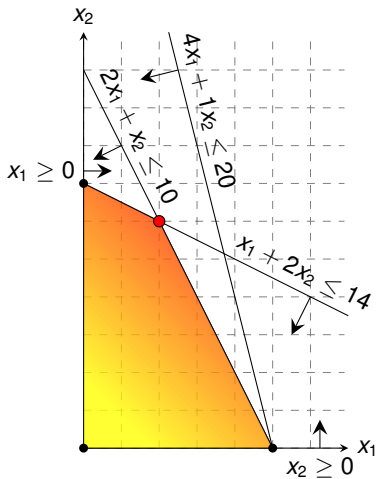


**Exercise:** Which aspect did we ignore in the formulation of the linear program?

## Finding the Optimal Production Schedule

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While the same approach also works for higher-dimensions, we need to take a more systematic and algebraic procedure.

# Outline

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Introduction

A Simple Example of a Linear Program

**Formulating Problems as Linear Programs**

Standard and Slack Forms

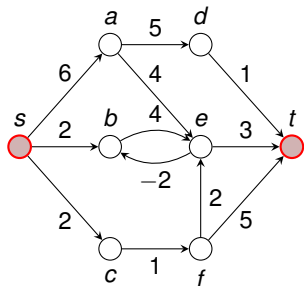
Simplex Algorithm

Finding an Initial Solution

## Shortest Paths

### Single-Pair Shortest Path Problem

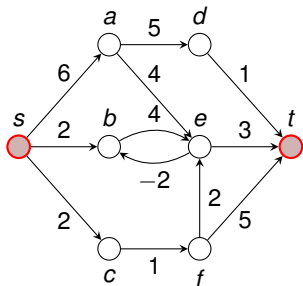
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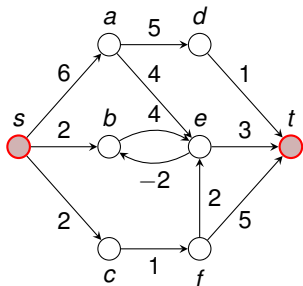


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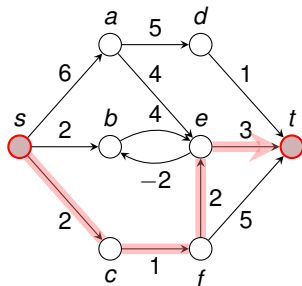


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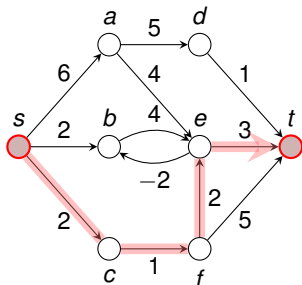


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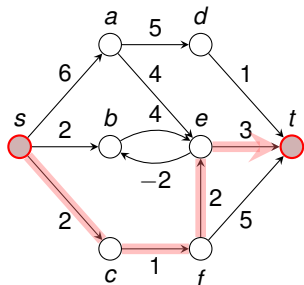
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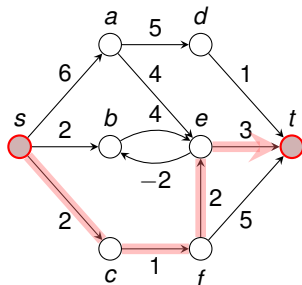
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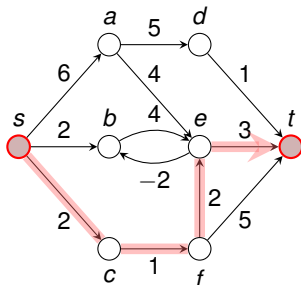
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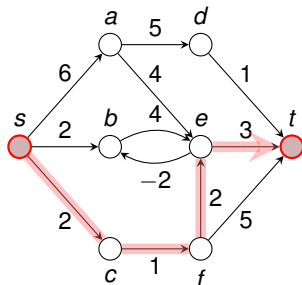
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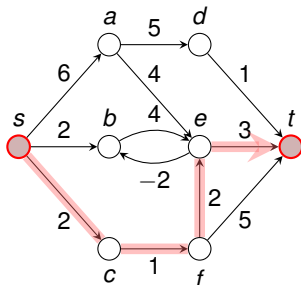
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Recall: When BELLMAN-FORD terminates, all these inequalities are satisfied.

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Solution  $\bar{d}$  satisfies  $\bar{d}_v = \min_{u: (u,v) \in E} \{\bar{d}_u + w(u, v)\}$

## Maximum Flow

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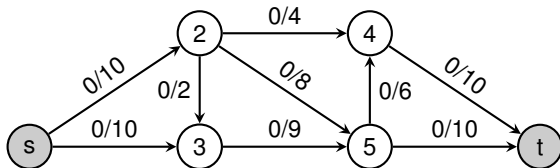
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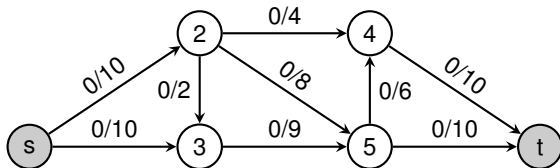




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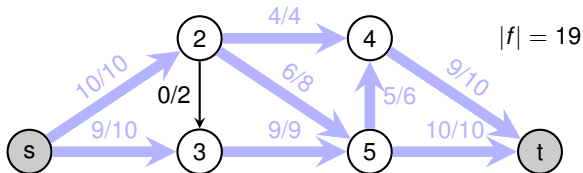
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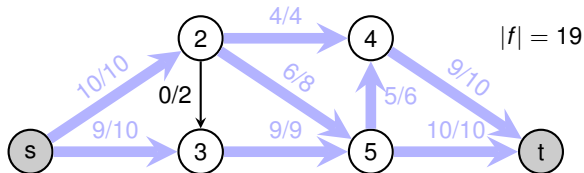
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### Maximum Flow as LP

maximise  
subject to

$$\sum_{v \in V} f_{sv} - \sum_{v \in V} f_{vs}$$

$$\begin{aligned} f_{uv} &\leq c(u, v) && \text{for each } u, v \in V, \\ \sum_{v \in V} f_{vu} &= \sum_{v \in V} f_{uv} && \text{for each } u \in V \setminus \{s, t\}, \\ f_{uv} &\geq 0 && \text{for each } u, v \in V. \end{aligned}$$

## Minimum-Cost Flow

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Extension of the Maximum Flow Problem

Minimum-Cost-Flow Problem



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- **Given:** directed graph  $G = (V, E)$  with capacities  $c : E \rightarrow \mathbb{R}^+$ , pair of vertices  $s, t \in V$ , **cost function**  $a : E \rightarrow \mathbb{R}^+$ , **flow demand of  $d$  units**

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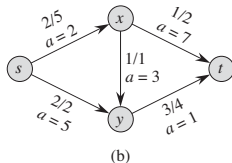
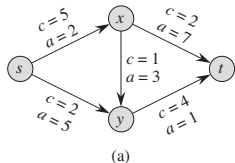
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**Figure 29.3** (a) An example of a minimum-cost-flow problem. We denote the capacities by  $c$  and the costs by  $a$ . Vertex  $s$  is the source and vertex  $t$  is the sink, and we wish to send 4 units of flow from  $s$  to  $t$ . (b) A solution to the minimum-cost flow problem in which 4 units of flow are sent from  $s$  to  $t$ . For each edge, the flow and capacity are written as flow/capacity.

## Minimum-Cost Flow

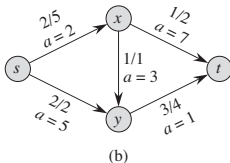
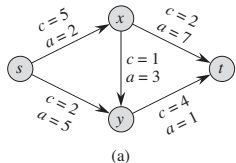
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**Optimal Solution** with total cost:

$$\sum_{(u,v) \in E} a(u,v)f_{uv} = (2 \cdot 2) + (5 \cdot 2) + (3 \cdot 1) + (7 \cdot 1) + (1 \cdot 3) = 27$$



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Real power of Linear Programming comes from the ability to solve **new problems!**

# Outline

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Non-Negativity Constraints

Standard Form (Matrix-Vector-Notation)

maximise  $c^T x$  Inner product of two vectors

subject to

$Ax \leq b$  Matrix-vector product  
 $x \geq 0$



## Converting Linear Programs into Standard Form

---

Reasons for a LP not being in standard form:

1. The objective might be a **minimisation** rather than **maximisation**.
2. There might be variables without **nonnegativity constraints**.
3. There might be **equality constraints**.
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**Equivalence:** a correspondence (not necessarily a bijection) between solutions.

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maximise  
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↓  
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maximise  
subject to

$$2x_1 - 3x_2' + 3x_2''$$

$$\begin{array}{rcll} x_1 + x_2' - x_2'' & \leq & 7 \\ x_1 + x_2' - x_2'' & \geq & 7 \\ x_1 - 2x_2' + 2x_2'' & \leq & 4 \\ x_1, x_2', x_2'' & \geq & 0 \end{array}$$

## Converting into Standard Form (4/5)

---

Reasons for a LP not being in standard form:

4. There might be inequality constraints (with  $\geq$  instead of  $\leq$ ).



## Converting into Standard Form (4/5)

Reasons for a LP not being in standard form:

4. There might be *inequality constraints* (with  $\geq$  instead of  $\leq$ ).

maximise  
subject to

$$2x_1 - 3x_2' + 3x_2''$$

$$x_1 + x_2' - x_2'' \leq 7$$

$$x_1 + x_2' - x_2'' \geq 7$$

$$x_1 - 2x_2' + 2x_2'' \leq 4$$

$$x_1, x_2', x_2'' \geq 0$$

## Converting into Standard Form (4/5)

Reasons for a LP not being in standard form:

4. There might be inequality constraints (with  $\geq$  instead of  $\leq$ ).

maximise  
subject to

$$2x_1 - 3x_2' + 3x_2''$$

$$x_1 + x_2' - x_2'' \leq 7$$

$$x_1 + x_2' - x_2'' \geq 7$$

$$x_1 - 2x_2' + 2x_2'' \leq 4$$

$$x_1, x_2', x_2'' \geq 0$$

Negate respective inequalities.



## Converting into Standard Form (4/5)

Reasons for a LP not being in standard form:

4. There might be **inequality constraints** (with  $\geq$  instead of  $\leq$ ).

maximise  
subject to

$$2x_1 - 3x_2' + 3x_2''$$

$$x_1 + x_2' - x_2'' \leq 7$$

$$x_1 + x_2' - x_2'' \geq 7$$

$$x_1 - 2x_2' + 2x_2'' \leq 4$$

$$x_1, x_2', x_2'' \geq 0$$

Negate respective inequalities.

maximise  
subject to

$$2x_1 - 3x_2' + 3x_2''$$

$$x_1 + x_2' - x_2'' \leq 7$$

$$-x_1 - x_2' + x_2'' \leq -7$$

$$x_1 - 2x_2' + 2x_2'' \leq 4$$

$$x_1, x_2', x_2'' \geq 0$$

## Converting into Standard Form (5/5)

---

maximise  
subject to

$$2x_1 - 3x_2 + 3x_3$$

$$x_1 + x_2 - x_3 \leq 7$$

$$-x_1 - x_2 + x_3 \leq -7$$

$$x_1 - 2x_2 + 2x_3 \leq 4$$

$$x_1, x_2, x_3 \geq 0$$

## Converting into Standard Form (5/5)

---

Rename variable names (for consistency).

$$\begin{array}{ll} \text{maximise} & 2x_1 - 3x_2 + 3x_3 \\ \text{subject to} & \\ & x_1 + x_2 - x_3 \leq 7 \\ & -x_1 - x_2 + x_3 \leq -7 \\ & x_1 - 2x_2 + 2x_3 \leq 4 \\ & x_1, x_2, x_3 \geq 0 \end{array}$$

## Converting into Standard Form (5/5)

Rename variable names (for consistency).

$$\begin{array}{rllllll} \text{maximise} & 2x_1 & - & 3x_2 & + & 3x_3 & \\ \text{subject to} & & & & & & \\ & x_1 & + & x_2 & - & x_3 & \leq & 7 \\ & -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ & x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & x_1, x_2, x_3 & & & & & \geq & 0 \end{array}$$

It is always possible to convert a linear program into standard form.

## Converting Standard Form into Slack Form (1/3)

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**Goal:** Convert **standard form** into **slack form**, where all constraints except for the non-negativity constraints are equalities.

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For the **simplex algorithm**, it is more convenient to work with equality constraints.



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For the **simplex algorithm**, it is more convenient to work with equality constraints.

Introducing Slack Variables



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### Introducing Slack Variables

- Let  $\sum_{j=1}^n a_{ij}x_j \leq b_i$  be an inequality constraint

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- Let  $\sum_{j=1}^n a_{ij}x_j \leq b_i$  be an inequality constraint
- Introduce a **slack variable**  $s$  by

$$s = b_i - \sum_{j=1}^n a_{ij}x_j$$

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$$s = b_i - \sum_{j=1}^n a_{ij}x_j$$

$$s \geq 0.$$

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**Goal:** Convert **standard form** into **slack form**, where all constraints except for the non-negativity constraints are equalities.

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### Introducing Slack Variables

- Let  $\sum_{j=1}^n a_{ij}x_j \leq b_i$  be an inequality constraint
- Introduce a **slack variable**  $s$  by

$s$  measures the slack between the two sides of the inequality.

$$s = b_i - \sum_{j=1}^n a_{ij}x_j$$

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For the **simplex algorithm**, it is more convenient to work with equality constraints.

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$s$  measures the slack between the two sides of the inequality.

$$s = b_i - \sum_{j=1}^n a_{ij}x_j$$

$$s \geq 0.$$

- Denote slack variable of the  $i$ -th inequality by  $x_{n+i}$

## Converting Standard Form into Slack Form (2/3)

---

maximise  
subject to

$$2x_1 - 3x_2 + 3x_3$$

$$x_1 + x_2 - x_3 \leq 7$$

$$-x_1 - x_2 + x_3 \leq -7$$

$$x_1 - 2x_2 + 2x_3 \leq 4$$

$$x_1, x_2, x_3 \geq 0$$



## Converting Standard Form into Slack Form (2/3)

---

maximise  
subject to

$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & & & & \geq & 0 \end{array}$$

$x_1, x_2, x_3$



Introduce slack variables

## Converting Standard Form into Slack Form (2/3)

maximise  
subject to

$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & & & & \geq & 0 \end{array}$$

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Introduce slack variables

subject to

$$x_4 = 7 - x_1 - x_2 + x_3$$

## Converting Standard Form into Slack Form (2/3)

maximise  
subject to

$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & & & & \geq & 0 \end{array}$$

$x_1, x_2, x_3$

Introduce slack variables

subject to

$$\begin{array}{rccccccccc} x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \end{array}$$

## Converting Standard Form into Slack Form (2/3)

maximise  
subject to

$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & & & & \geq & 0 \end{array}$$

$x_1, x_2, x_3$

Introduce slack variables

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$$\begin{array}{rcccccc} x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \\ x_6 & = & 4 & - & x_1 & + & 2x_2 & - & 2x_3 \end{array}$$

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maximise  
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$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ x_1, x_2, x_3 & & & & & \geq & 0 \end{array}$$

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## Converting Standard Form into Slack Form (3/3)

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$$\begin{array}{rcllclclcl} \text{maximise} & 2x_1 & - & 3x_2 & + & 3x_3 & & & \\ \text{subject to} & & & & & & & & \\ & x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ & x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \\ & x_6 & = & 4 & - & x_1 & + & 2x_2 & - & 2x_3 \\ & & & x_1, x_2, x_3, x_4, x_5, x_6 & & & \geq & 0 & & \end{array}$$

## Converting Standard Form into Slack Form (3/3)

maximise  
subject to

$$2x_1 - 3x_2 + 3x_3$$

$$x_4 = 7 - x_1 - x_2 + x_3$$

$$x_5 = -7 + x_1 + x_2 - x_3$$

$$x_6 = 4 - x_1 + 2x_2 - 2x_3$$

$$x_1, x_2, x_3, x_4, x_5, x_6 \geq 0$$

Use variable  $z$  to denote objective function and omit the nonnegativity constraints.



## Converting Standard Form into Slack Form (3/3)

maximise  
subject to

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$$x_6 = 4 - x_1 + 2x_2 - 2x_3$$

$$x_1, x_2, x_3, x_4, x_5, x_6 \geq 0$$

Use variable  $z$  to denote objective function  
and omit the nonnegativity constraints.

$$z = 2x_1 - 3x_2 + 3x_3$$

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$$\begin{array}{l} \text{maximise} \\ \text{subject to} \end{array} \quad \begin{array}{r} 2x_1 - 3x_2 + 3x_3 \\ x_4 = 7 - x_1 - x_2 + x_3 \\ x_5 = -7 + x_1 + x_2 - x_3 \\ x_6 = 4 - x_1 + 2x_2 - 2x_3 \\ x_1, x_2, x_3, x_4, x_5, x_6 \geq 0 \end{array}$$

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This is called **slack form**.

## Basic and Non-Basic Variables

---

$$\begin{array}{rclclclcl} Z & = & & & 2x_1 & - & 3x_2 & + & 3x_3 \\ x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \\ x_6 & = & 4 & - & x_1 & + & 2x_2 & - & 2x_3 \end{array}$$

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**Basic Variables:**  $B = \{4, 5, 6\}$

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**Basic Variables:**  $B = \{4, 5, 6\}$

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## Basic and Non-Basic Variables

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**Basic Variables:**  $B = \{4, 5, 6\}$

**Non-Basic Variables:**  $N = \{1, 2, 3\}$

Slack Form (Formal Definition)

Slack form is given by a tuple  $(N, B, A, b, c, v)$  so that

$$z = v + \sum_{j \in N} c_j x_j$$

$$x_i = b_i - \sum_{j \in N} a_{ij} x_j \quad \text{for } i \in B,$$

and all variables are non-negative.

## Basic and Non-Basic Variables

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and all variables are non-negative.

Variables/Coefficients on the right hand side are indexed by  $B$  and  $N$ .

## Slack Form (Example)

---

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$



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Slack Form Notation



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Slack Form Notation

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- 

$$A = \begin{pmatrix} a_{13} & a_{15} & a_{16} \\ a_{23} & a_{25} & a_{26} \\ a_{43} & a_{45} & a_{46} \end{pmatrix} = \begin{pmatrix} -1/6 & -1/6 & 1/3 \\ 8/3 & 2/3 & -1/3 \\ 1/2 & -1/2 & 0 \end{pmatrix}$$

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- 

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Slack Form Notation

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- $$b = \begin{pmatrix} b_1 \\ b_2 \\ b_4 \end{pmatrix} = \begin{pmatrix} 8 \\ 4 \\ 18 \end{pmatrix}, c = \begin{pmatrix} c_3 \\ c_5 \\ c_6 \end{pmatrix} = \begin{pmatrix} -1/6 \\ -1/6 \\ -2/3 \end{pmatrix}$$

- $v = 28$

# Outline

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Introduction

A Simple Example of a Linear Program

Formulating Problems as Linear Programs

Standard and Slack Forms

**Simplex Algorithm**

Finding an Initial Solution

## Simplex Algorithm: Introduction

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### Simplex Algorithm

- classical method for solving linear programs (Dantzig, 1947)
- usually fast in practice although worst-case runtime not polynomial
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### Basic Idea:

- Each iteration corresponds to a “basic solution” of the slack form
- All non-basic variables are 0, and the basic variables are determined from the equality constraints
- Each iteration converts one slack form into an equivalent one while the objective value will not decrease
- Conversion (“pivoting”) is achieved by switching the roles of one basic and one non-basic variable

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In that sense, it is a **greedy algorithm**.

## Extended Example: Conversion into Slack Form

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$$\begin{array}{l} \text{maximise} \\ \text{subject to} \end{array} \quad \begin{array}{r} 3x_1 + x_2 + 2x_3 \\ x_1 + x_2 + 3x_3 \leq 30 \\ 2x_1 + 2x_2 + 5x_3 \leq 24 \\ 4x_1 + x_2 + 2x_3 \leq 36 \\ x_1, x_2, x_3 \geq 0 \end{array}$$

## Extended Example: Conversion into Slack Form

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$$\begin{array}{lll} \text{maximise} & 3x_1 & + & x_2 & + & 2x_3 \\ \text{subject to} & & & & & \\ & x_1 & + & x_2 & + & 3x_3 & \leq & 30 \\ & 2x_1 & + & 2x_2 & + & 5x_3 & \leq & 24 \\ & 4x_1 & + & x_2 & + & 2x_3 & \leq & 36 \\ & & & x_1, x_2, x_3 & & & \geq & 0 \end{array}$$



Conversion into slack form

## Extended Example: Conversion into Slack Form

$$\begin{array}{ll} \text{maximise} & 3x_1 + x_2 + 2x_3 \\ \text{subject to} & \\ & x_1 + x_2 + 3x_3 \leq 30 \\ & 2x_1 + 2x_2 + 5x_3 \leq 24 \\ & 4x_1 + x_2 + 2x_3 \leq 36 \\ & x_1, x_2, x_3 \geq 0 \end{array}$$

Conversion into slack form

$$\begin{array}{rcl} z & = & 3x_1 + x_2 + 2x_3 \\ x_4 & = & 30 - x_1 - x_2 - 3x_3 \\ x_5 & = & 24 - 2x_1 - 2x_2 - 5x_3 \\ x_6 & = & 36 - 4x_1 - x_2 - 2x_3 \end{array}$$

## Extended Example: Iteration 1

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$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

$$x_5 = 24 - 2x_1 - 2x_2 - 5x_3$$

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$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (0, 0, 0, 30, 24, 36)$

## Extended Example: Iteration 1

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$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

$$x_5 = 24 - 2x_1 - 2x_2 - 5x_3$$

$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (0, 0, 0, 30, 24, 36)$

This basic solution is **feasible**



## Extended Example: Iteration 1

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$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

$$x_5 = 24 - 2x_1 - 2x_2 - 5x_3$$

$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (0, 0, 0, 30, 24, 36)$

This basic solution is **feasible**

Objective value is 0.

## Extended Example: Iteration 1

Increasing the value of  $x_1$  would increase the objective value.

$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

$$x_5 = 24 - 2x_1 - 2x_2 - 5x_3$$

$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (0, 0, 0, 30, 24, 36)$

This basic solution is **feasible**

Objective value is 0.

## Extended Example: Iteration 1

Increasing the value of  $x_1$  would increase the objective value.

$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

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$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

The third constraint is the tightest and limits how much we can increase  $x_1$ .

## Extended Example: Iteration 1

Increasing the value of  $x_1$  would increase the objective value.

$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

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The third constraint is the tightest and limits how much we can increase  $x_1$ .

**Switch roles of  $x_1$  and  $x_6$ :**

## Extended Example: Iteration 1

Increasing the value of  $x_1$  would increase the objective value.

$$z = 3x_1 + x_2 + 2x_3$$

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The third constraint is the tightest and limits how much we can increase  $x_1$ .

**Switch roles of  $x_1$  and  $x_6$ :**

- Solving for  $x_1$  yields:

$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}.$$

## Extended Example: Iteration 1

Increasing the value of  $x_1$  would increase the objective value.

$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

$$x_5 = 24 - 2x_1 - 2x_2 - 5x_3$$

$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

The third constraint is the tightest and limits how much we can increase  $x_1$ .

**Switch roles of  $x_1$  and  $x_6$ :**

- Solving for  $x_1$  yields:

$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}.$$

- Substitute this into  $x_1$  in the other three equations

## Extended Example: Iteration 2

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$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

## Extended Example: Iteration 2

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (9, 0, 0, 21, 6, 0)$  with objective value 27



## Extended Example: Iteration 2

Increasing the value of  $x_3$  would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (9, 0, 0, 21, 6, 0)$  with objective value 27

## Extended Example: Iteration 2

Increasing the value of  $x_3$  would increase the objective value.

$$\begin{array}{rclclcl} z & = & 27 & + & \frac{x_2}{4} & + & \frac{x_3}{2} & - & \frac{3x_6}{4} \\ x_1 & = & 9 & - & \frac{x_2}{4} & - & \frac{x_3}{2} & - & \frac{x_6}{4} \\ x_4 & = & 21 & - & \frac{3x_2}{4} & - & \frac{5x_3}{2} & + & \frac{x_6}{4} \\ x_5 & = & 6 & - & \frac{3x_2}{2} & - & 4x_3 & + & \frac{x_6}{2} \end{array}$$

The third constraint is the tightest and limits how much we can increase  $x_3$ .

## Extended Example: Iteration 2

Increasing the value of  $x_3$  would increase the objective value.

$$\begin{array}{rclclcl} z & = & 27 & + & \frac{x_2}{4} & + & \frac{x_3}{2} & - & \frac{3x_6}{4} \\ x_1 & = & 9 & - & \frac{x_2}{4} & - & \frac{x_3}{2} & - & \frac{x_6}{4} \\ x_4 & = & 21 & - & \frac{3x_2}{4} & - & \frac{5x_3}{2} & + & \frac{x_6}{4} \\ x_5 & = & 6 & - & \frac{3x_2}{2} & - & 4x_3 & + & \frac{x_6}{2} \end{array}$$

The third constraint is the tightest and limits how much we can increase  $x_3$ .

**Switch roles of  $x_3$  and  $x_5$ :**

## Extended Example: Iteration 2

Increasing the value of  $x_3$  would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

The third constraint is the tightest and limits how much we can increase  $x_3$ .

**Switch roles of  $x_3$  and  $x_5$ :**

- Solving for  $x_3$  yields:

$$x_3 = \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} - \frac{x_6}{8}.$$

## Extended Example: Iteration 2

Increasing the value of  $x_3$  would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

The third constraint is the tightest and limits how much we can increase  $x_3$ .

**Switch roles of  $x_3$  and  $x_5$ :**

- Solving for  $x_3$  yields:

$$x_3 = \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} - \frac{x_6}{8}.$$

- Substitute this into  $x_3$  in the other three equations

## Extended Example: Iteration 3

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$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

## Extended Example: Iteration 3

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (\frac{33}{4}, 0, \frac{3}{2}, \frac{69}{4}, 0, 0)$  with objective value  $\frac{111}{4} = 27.75$

## Extended Example: Iteration 3

Increasing the value of  $x_2$  would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (\frac{33}{4}, 0, \frac{3}{2}, \frac{69}{4}, 0, 0)$  with objective value  $\frac{111}{4} = 27.75$



## Extended Example: Iteration 3

Increasing the value of  $x_2$  would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase  $x_2$ .

## Extended Example: Iteration 3

Increasing the value of  $x_2$  would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase  $x_2$ .

**Switch roles of  $x_2$  and  $x_3$ :**

## Extended Example: Iteration 3

Increasing the value of  $x_2$  would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase  $x_2$ .

**Switch roles of  $x_2$  and  $x_3$ :**

- Solving for  $x_2$  yields:

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3}.$$

## Extended Example: Iteration 3

Increasing the value of  $x_2$  would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase  $x_2$ .

**Switch roles of  $x_2$  and  $x_3$ :**

- Solving for  $x_2$  yields:

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3}.$$

- Substitute this into  $x_2$  in the other three equations

## Extended Example: Iteration 4

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$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$

## Extended Example: Iteration 4

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$

Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (8, 4, 0, 18, 0, 0)$  with objective value 28

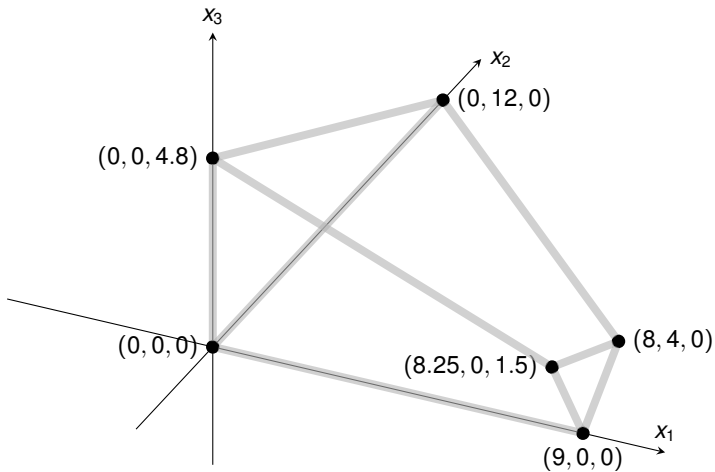
## Extended Example: Iteration 4

All coefficients are negative, and hence this basic solution is **optimal!**

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$

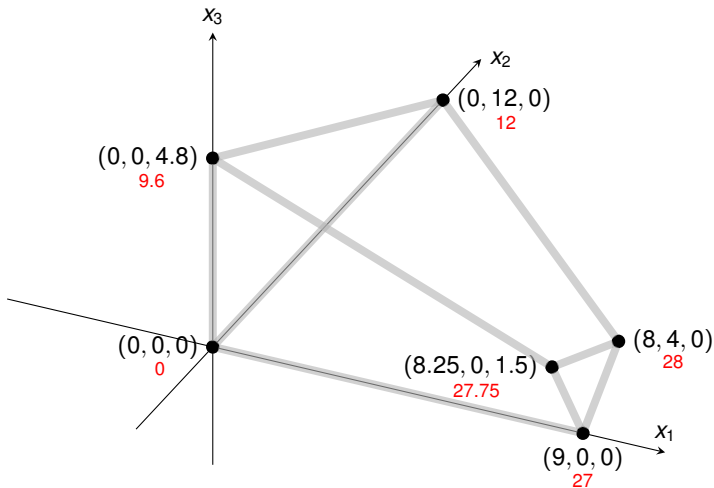
Basic solution:  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (8, 4, 0, 18, 0, 0)$  with objective value 28

## Extended Example: Visualization of SIMPLEX

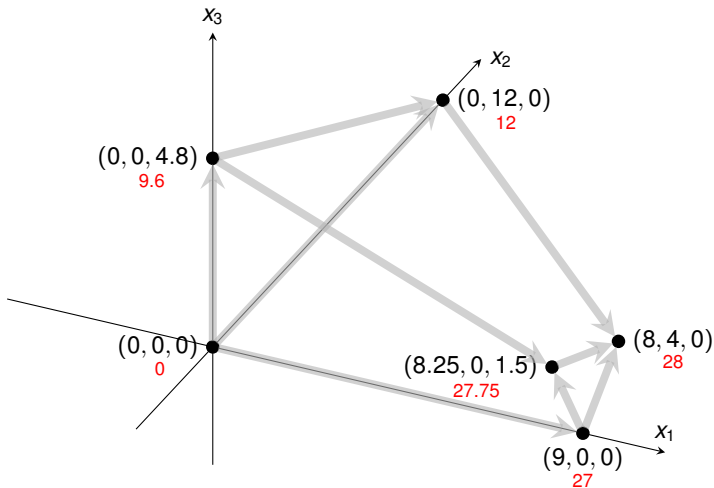




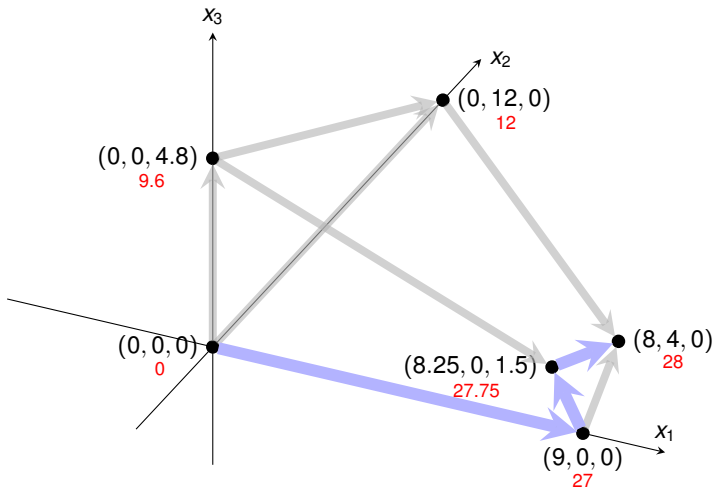
## Extended Example: Visualization of SIMPLEX



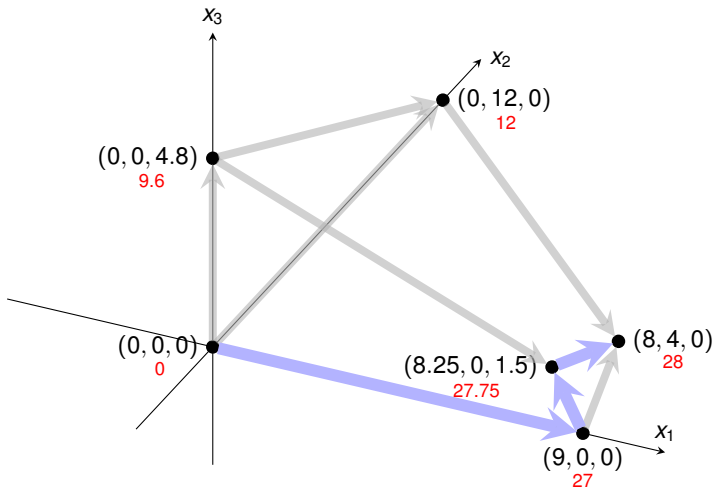
## Extended Example: Visualization of SIMPLEX



## Extended Example: Visualization of SIMPLEX



## Extended Example: Visualization of SIMPLEX



**Exercise:** How many basic solutions (including non-feasible ones) are there?

## Extended Example: Alternative Runs (1/2)

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$$\begin{array}{rcccccc} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

## Extended Example: Alternative Runs (1/2)

---

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

↓ Switch roles of  $x_2$  and  $x_5$

▼

## Extended Example: Alternative Runs (1/2)

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

↓ Switch roles of  $x_2$  and  $x_5$

$$\begin{array}{rclclcl} z & = & 12 & + & 2x_1 & - & \frac{x_3}{2} & - & \frac{x_5}{2} \\ x_2 & = & 12 & - & x_1 & - & \frac{5x_3}{2} & - & \frac{x_5}{2} \\ x_4 & = & 18 & - & x_2 & - & \frac{x_3}{2} & + & \frac{x_5}{2} \\ x_6 & = & 24 & - & 3x_1 & + & \frac{x_3}{2} & + & \frac{x_5}{2} \end{array}$$

## Extended Example: Alternative Runs (1/2)

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

Switch roles of  $x_2$  and  $x_5$   
↓

$$\begin{array}{rclclcl} z & = & 12 & + & 2x_1 & - & \frac{x_3}{2} & - & \frac{x_5}{2} \\ x_2 & = & 12 & - & x_1 & - & \frac{5x_3}{2} & - & \frac{x_5}{2} \\ x_4 & = & 18 & - & x_2 & - & \frac{x_3}{2} & + & \frac{x_5}{2} \\ x_6 & = & 24 & - & 3x_1 & + & \frac{x_3}{2} & + & \frac{x_5}{2} \end{array}$$

Switch roles of  $x_1$  and  $x_6$   
↓



## Extended Example: Alternative Runs (1/2)

$$\begin{array}{rcllclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

Switch roles of  $x_2$  and  $x_5$   
↓

$$\begin{array}{rcllclcl} z & = & 12 & + & 2x_1 & - & \frac{x_3}{2} & - & \frac{x_5}{2} \\ x_2 & = & 12 & - & x_1 & - & \frac{5x_3}{2} & - & \frac{x_5}{2} \\ x_4 & = & 18 & - & x_2 & - & \frac{x_3}{2} & + & \frac{x_5}{2} \\ x_6 & = & 24 & - & 3x_1 & + & \frac{x_3}{2} & + & \frac{x_5}{2} \end{array}$$

Switch roles of  $x_1$  and  $x_6$   
↓

$$\begin{array}{rcllclcl} z & = & 28 & - & \frac{x_3}{6} & - & \frac{x_5}{6} & - & \frac{2x_6}{3} \\ x_1 & = & 8 & + & \frac{x_3}{6} & + & \frac{x_5}{6} & - & \frac{x_6}{3} \\ x_2 & = & 4 & - & \frac{8x_3}{3} & - & \frac{2x_5}{3} & + & \frac{x_6}{3} \\ x_4 & = & 18 & - & \frac{x_3}{2} & + & \frac{x_5}{2} & & \end{array}$$

## Extended Example: Alternative Runs (2/2)

---

$$\begin{array}{rclclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

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↓ Switch roles of  $x_3$  and  $x_5$

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$$\begin{aligned}z &= & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\x_4 &= & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\x_3 &= & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\x_6 &= & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}\end{aligned}$$

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 \end{aligned}$$

Switch roles of  $x_1$  and  $x_6$

$$\begin{aligned}
 z &= &\frac{111}{4} &+& \frac{x_2}{16} &-& \frac{x_5}{8} &-& \frac{11x_6}{16} \\
 x_1 &= &\frac{33}{4} &-& \frac{x_2}{16} &+& \frac{x_5}{8} &-& \frac{5x_6}{16} \\
 x_3 &= &\frac{3}{2} &-& \frac{3x_2}{8} &-& \frac{x_5}{4} &+& \frac{x_6}{8} \\
 x_4 &= &\frac{69}{4} &+& \frac{3x_2}{16} &+& \frac{5x_5}{8} &-& \frac{x_6}{16}
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 x_4 &= &18 &-& \frac{x_3}{2} &+& \frac{x_5}{2}
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## The Pivot Step Formally

---

PIVOT( $N, B, A, b, c, v, l, e$ )

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
4 for each  $j \in N - \{e\}$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
6  $\hat{a}_{el} = 1/a_{le}$ 
7 // Compute the coefficients of the remaining constraints.
8 for each  $i \in B - \{l\}$ 
9      $\hat{b}_i = b_i - a_{ie}\hat{b}_e$ 
10    for each  $j \in N - \{e\}$ 
11         $\hat{a}_{ij} = a_{ij} - a_{ie}\hat{a}_{ej}$ 
12     $\hat{a}_{il} = -a_{ie}\hat{a}_{el}$ 
13 // Compute the objective function.
14  $\hat{v} = v + c_e\hat{b}_e$ 
15 for each  $j \in N - \{e\}$ 
16      $\hat{c}_j = c_j - c_e\hat{a}_{ej}$ 
17  $\hat{c}_l = -c_e\hat{a}_{el}$ 
18 // Compute new sets of basic and nonbasic variables.
19  $\hat{N} = N - \{e\} \cup \{l\}$ 
20  $\hat{B} = B - \{l\} \cup \{e\}$ 
21 return ( $\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v}$ )
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## The Pivot Step Formally

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Rewrite “tight” equation  
for entering variable  $x_e$ .

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Rewrite “tight” equation for entering variable  $x_e$ .

Substituting  $x_e$  into other equations.

Substituting  $x_e$  into objective function.

Update non-basic and basic variables

## The Pivot Step Formally

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2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
4 for each  $j \in N - \{e\}$  Need that  $a_{le} \neq 0!$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
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Update non-basic and basic variables

## Effect of the Pivot Step (extra material, non-examinable)

---

— Lemma 29.1 —

Consider a call to  $\text{PIVOT}(N, B, A, b, c, v, l, e)$  in which  $a_{le} \neq 0$ . Let the values returned from the call be  $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$ , and let  $\bar{x}$  denote the basic solution after the call. Then

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1.  $\bar{x}_j = 0$  for each  $j \in \hat{N}$ .
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Proof:

1. holds since the basic solution always sets all non-basic variables to zero.
2. When we set each non-basic variable to 0 in a constraint

$$x_i = \hat{b}_i - \sum_{j \in \hat{N}} \hat{a}_{ij} x_j,$$

we have  $\bar{x}_i = \hat{b}_i$  for each  $i \in \hat{B}$ . Hence  $\bar{x}_e = \hat{b}_e = b_l/a_{le}$ .

3. After substituting into the other constraints, we have

$$\bar{x}_i = \hat{b}_i = b_i - a_{ie}\hat{b}_e.$$

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3. After substituting into the other constraints, we have

$$\bar{x}_i = \widehat{b}_i = b_i - a_{ie}\widehat{b}_e. \quad \square$$

### Questions:

- How do we determine whether a linear program is feasible?
- What do we do if the linear program is feasible, but the initial basic solution is not feasible?
- How do we determine whether a linear program is unbounded?
- How do we choose the entering and leaving variables?

### Questions:

- How do we determine whether a linear program is feasible?
- What do we do if the linear program is feasible, but the initial basic solution is not feasible?
- How do we determine whether a linear program is unbounded?
- How do we choose the entering and leaving variables?

Example before was a particularly nice one!

## The formal procedure SIMPLEX

---

SIMPLEX( $A, b, c$ )

```
1  ( $N, B, A, b, c, v$ ) = INITIALIZE-SIMPLEX( $A, b, c$ )
2  let  $\Delta$  be a new vector of length  $m$ 
3  while some index  $j \in N$  has  $c_j > 0$ 
4      choose an index  $e \in N$  for which  $c_e > 0$ 
5      for each index  $i \in B$ 
6          if  $a_{ie} > 0$ 
7               $\Delta_i = b_i/a_{ie}$ 
8          else  $\Delta_i = \infty$ 
9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
10     if  $\Delta_l == \infty$ 
11         return “unbounded”
12     else ( $N, B, A, b, c, v$ ) = PIVOT( $N, B, A, b, c, v, l, e$ )
13 for  $i = 1$  to  $n$ 
14     if  $i \in B$ 
15          $\bar{x}_i = b_i$ 
16     else  $\bar{x}_i = 0$ 
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Returns a slack form with a feasible basic solution (if it exists)

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Main Loop:

# The formal procedure SIMPLEX

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## Main Loop:

- terminates if all coefficients in objective function are negative
- Line 4 picks entering variable  $x_e$  with negative coefficient
- Lines 6 – 9 pick the tightest constraint, associated with  $x_l$
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- Line 12 calls PIVOT, switching roles of  $x_l$  and  $x_e$

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Returns a slack form with a feasible basic solution (if it exists)

### Lemma 29.2

Suppose the call to INITIALIZE-SIMPLEX in line 1 returns a slack form for which the basic solution is feasible. Then if SIMPLEX returns a solution, it is a feasible solution. If SIMPLEX returns "unbounded", the linear program is unbounded.

## The formal procedure **SIMPLEX**

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**Proof** is based on the following three-part loop invariant:

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Returns a slack form with a feasible basic solution (if it exists)

**Proof** is based on the following three-part loop invariant:

1. the slack form is always equivalent to the one returned by INITIALIZE-SIMPLEX,
2. for each  $i \in B$ , we have  $b_i \geq 0$ ,
3. the basic solution associated with the (current) slack form is feasible.

Lemma 29.2

Suppose the call to INITIALIZE-SIMPLEX in line 1 returns a slack form for which the basic solution is feasible. Then if SIMPLEX returns a solution, it is a feasible solution. If SIMPLEX returns “unbounded”, the linear program is unbounded.

## Termination

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**Degeneracy:** One iteration of SIMPLEX leaves the objective value unchanged.

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$$x_5 = \quad \quad \quad x_2 - x_3$$



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**Cycling:** If additionally slack form at two iterations are identical, SIMPLEX fails to terminate!



**Exercise:** Execute one more step of the Simplex Algorithm on the tableau from the previous slide.

**Cycling:** SIMPLEX may fail to terminate.

## Termination and Running Time

---

It is theoretically possible, but very rare in practice.

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Anti-Cycling Strategies



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Replace each  $b_i$  by  $\hat{b}_i = b_i + \epsilon_i$ , where  $\epsilon_i \gg \epsilon_{i+1}$  are all small.

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### Lemma 29.7

Assuming INITIALIZE-SIMPLEX returns a slack form for which the basic solution is feasible, SIMPLEX either reports that the program is unbounded or returns a feasible solution in at most  $\binom{n+m}{m}$  iterations.

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Every set  $B$  of basic variables uniquely determines a slack form, and there are at most  $\binom{n+m}{m}$  unique slack forms.

# Outline

---

Introduction

A Simple Example of a Linear Program

Formulating Problems as Linear Programs

Standard and Slack Forms

Simplex Algorithm

**Finding an Initial Solution**



## Finding an Initial Solution

---

$$\begin{array}{llll} \text{maximise} & 2x_1 & - & x_2 \\ \text{subject to} & & & \\ & 2x_1 & - & x_2 \leq 2 \\ & x_1 & - & 5x_2 \leq -4 \\ & x_1, x_2 & & \geq 0 \end{array}$$

## Finding an Initial Solution

---

maximise  
subject to

$$2x_1 - x_2$$

$$2x_1 - x_2 \leq 2$$

$$x_1 - 5x_2 \leq -4$$

$$x_1, x_2 \geq 0$$



Conversion into slack form

## Finding an Initial Solution

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Conversion into slack form

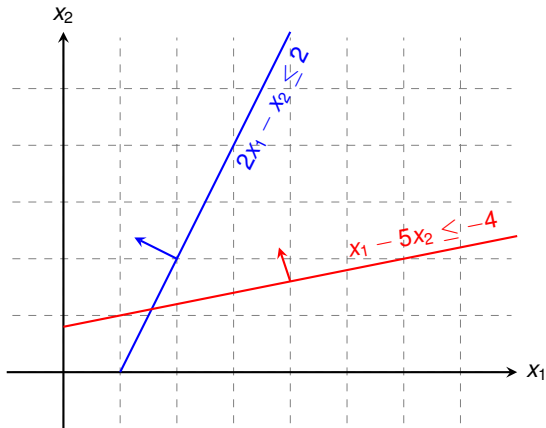
$$\begin{array}{rcl} z & = & 2x_1 - x_2 \\ x_3 & = & 2 - 2x_1 + x_2 \\ x_4 & = & -4 - x_1 + 5x_2 \end{array}$$

Basic solution  $(x_1, x_2, x_3, x_4) = (0, 0, 2, -4)$  is not feasible!

## Geometric Illustration

maximise  
subject to

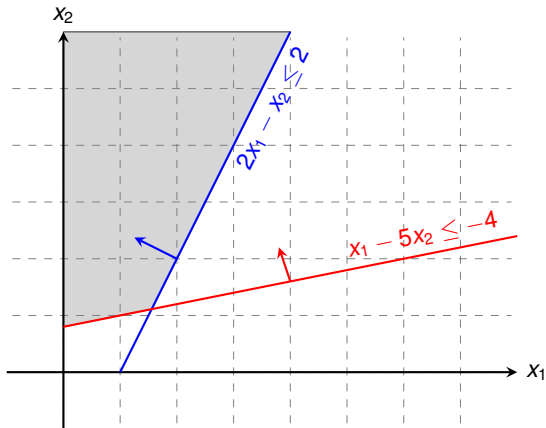
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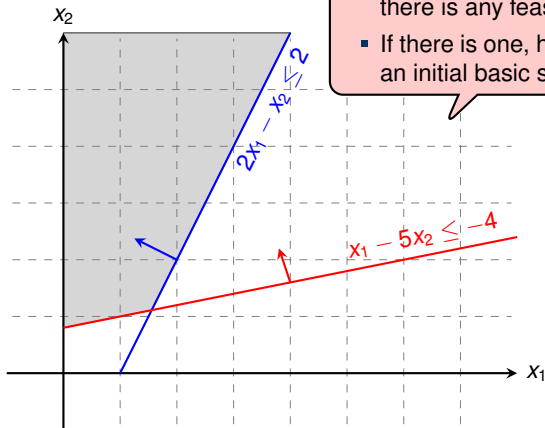
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Questions:

- How to determine whether there is any feasible solution?
- If there is one, how to determine an initial basic solution?

## Formulating an Auxiliary Linear Program

---

maximise  
subject to

$$\sum_{j=1}^n c_j x_j$$

$$\begin{aligned} \sum_{j=1}^n a_{ij} x_j &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 1, 2, \dots, n \end{aligned}$$

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Let  $L_{aux}$  be the auxiliary LP of a linear program  $L$  in standard form. Then  $L$  is feasible if and only if the optimal objective value of  $L_{aux}$  is 0.

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Proof.

- “ $\Rightarrow$ ”: Suppose  $L$  has a feasible solution  $\bar{x} = (\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$

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- “ $\Rightarrow$ ”: Suppose  $L$  has a feasible solution  $\bar{x} = (\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$ 
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## Formulating an Auxiliary Linear Program

maximise  $\sum_{j=1}^n c_j x_j$   
subject to

$$\begin{aligned} \sum_{j=1}^n a_{ij} x_j &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 1, 2, \dots, n \end{aligned}$$

↓ Formulating an Auxiliary Linear Program

maximise  $-x_0$   
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$$\begin{aligned} \sum_{j=1}^n a_{ij} x_j - x_0 &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 0, 1, \dots, n \end{aligned}$$

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  - Then  $\bar{x}_0 = 0$ , and the remaining solution values  $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$  satisfy  $L$ .



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- Let us illustrate the role of  $x_0$  as “distance from feasibility”

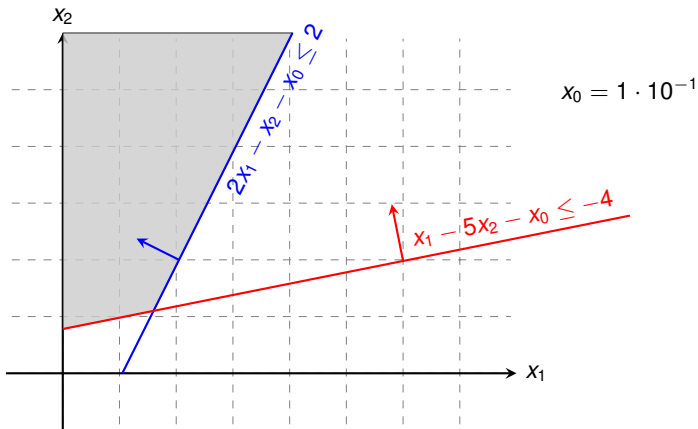
- Let us illustrate the role of  $x_0$  as “distance from feasibility”
- We will also see that increasing  $x_0$  enlarges the feasible region.



## Geometric Illustration

maximise  
subject to

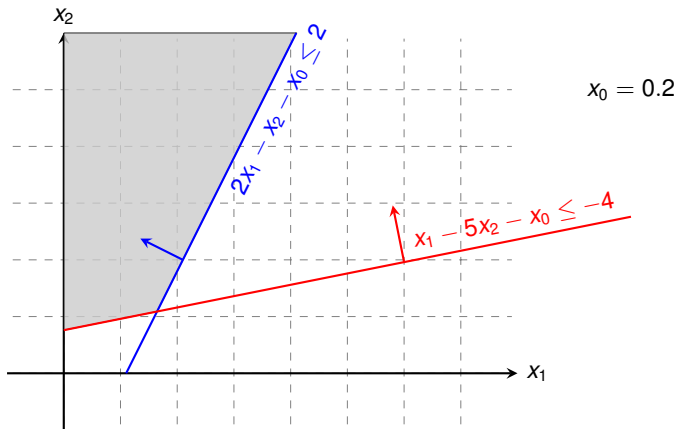
$$\begin{array}{rcllcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
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## Geometric Illustration

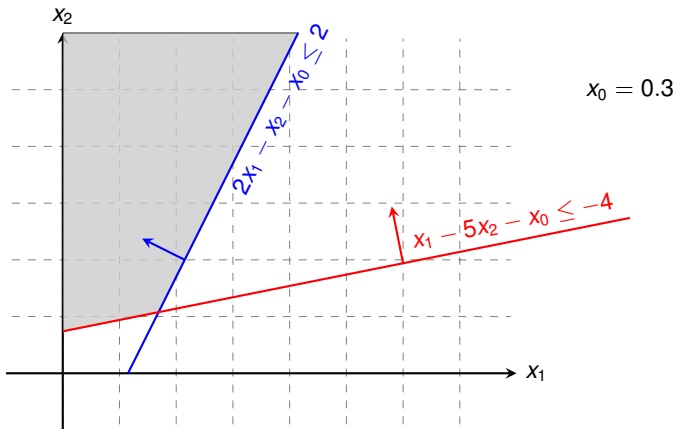
maximise  
subject to

$$-x_0$$

$$2x_1 - x_2 - x_0 \leq 2$$

$$x_1 - 5x_2 - x_0 \leq -4$$

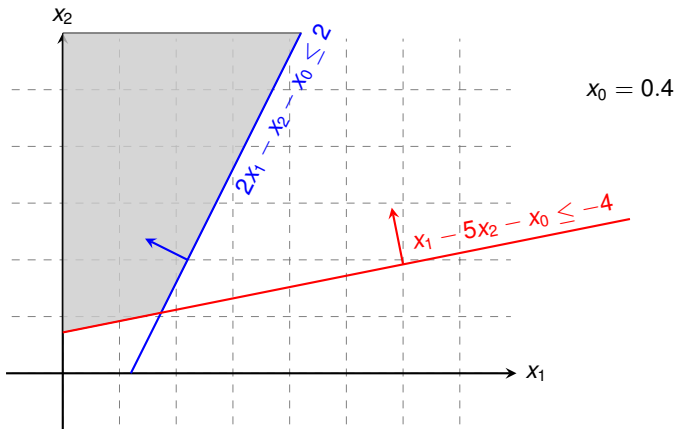
$$x_0, x_1, x_2 \geq 0$$



## Geometric Illustration

maximise  
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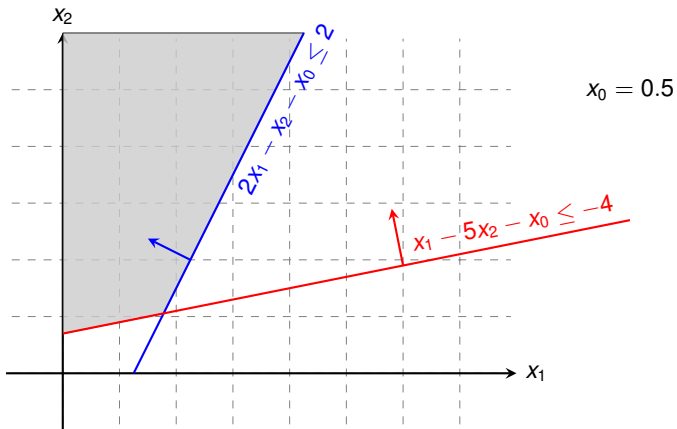




## Geometric Illustration

maximise  
subject to

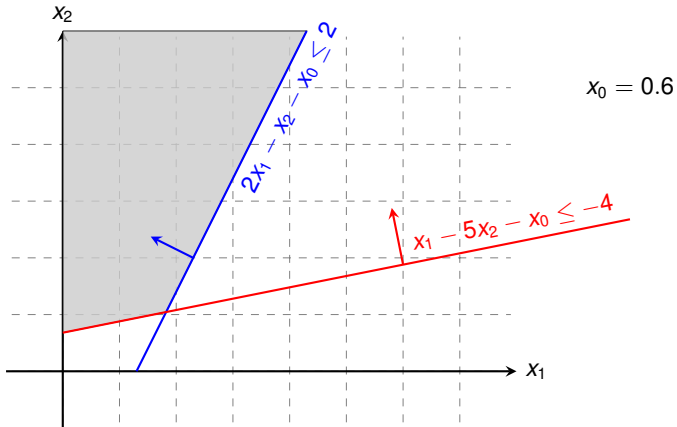
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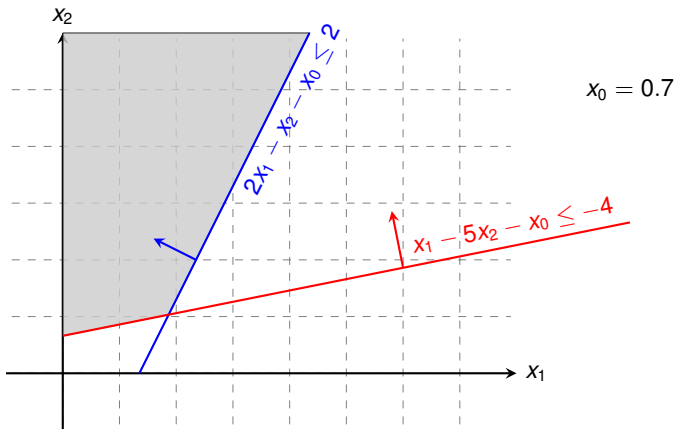
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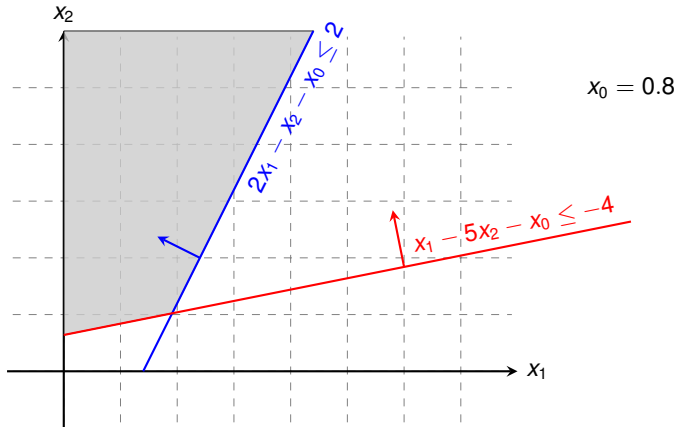
maximise  
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## Geometric Illustration

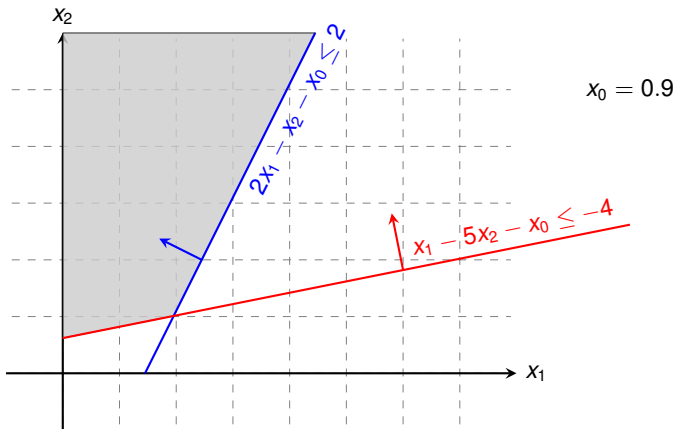
maximise  
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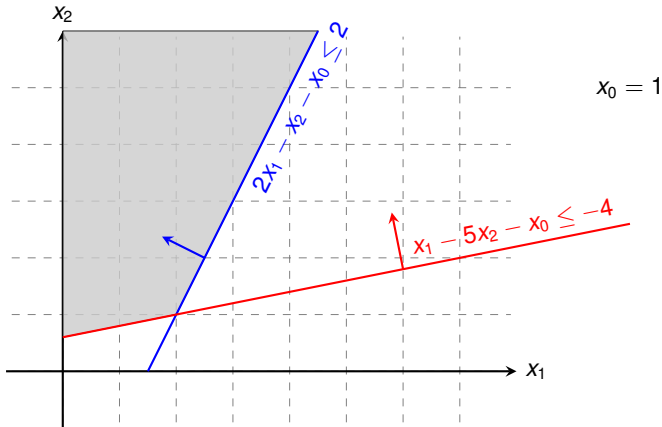
## Geometric Illustration

maximise  
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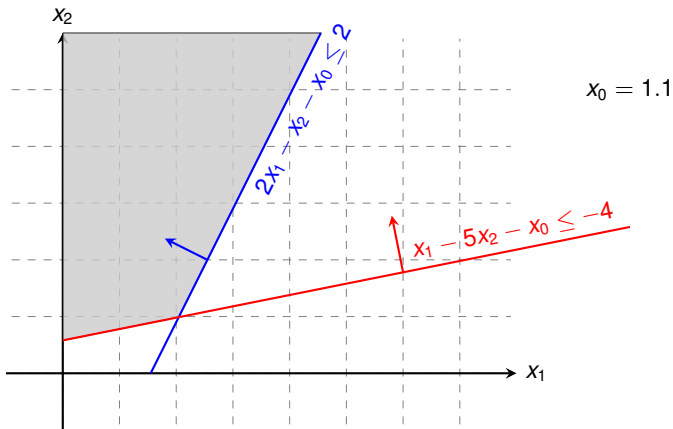
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maximise  
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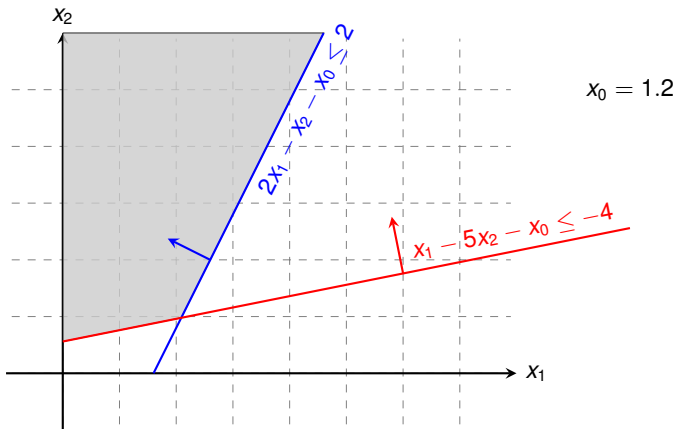
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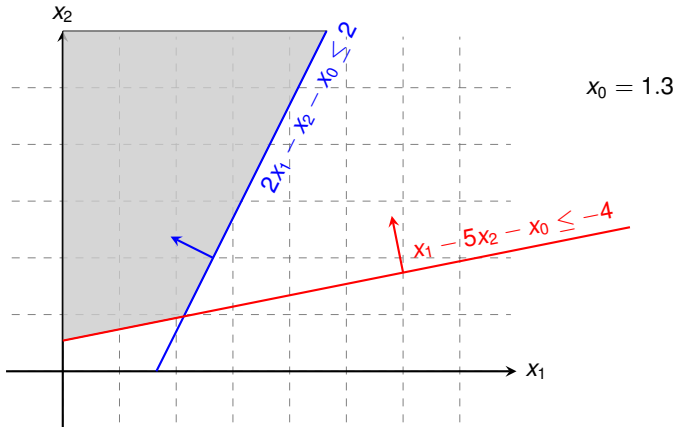




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maximise  
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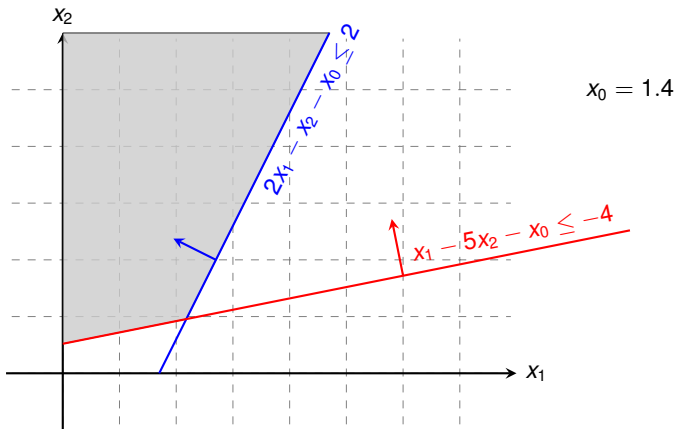
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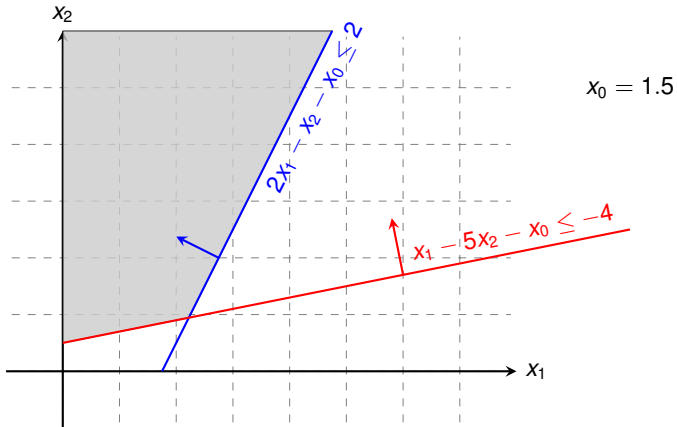
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maximise  
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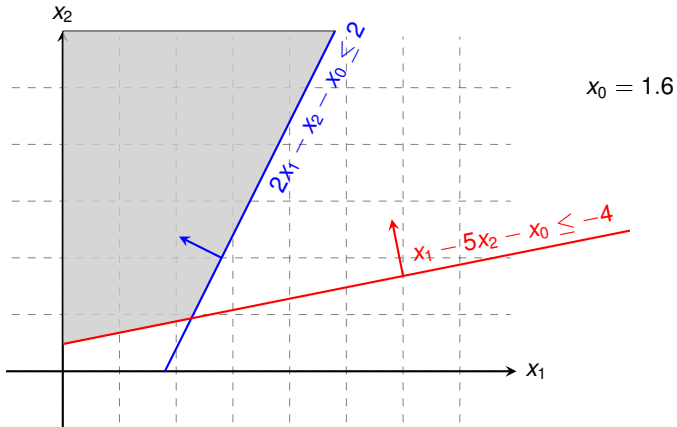
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maximise  
subject to

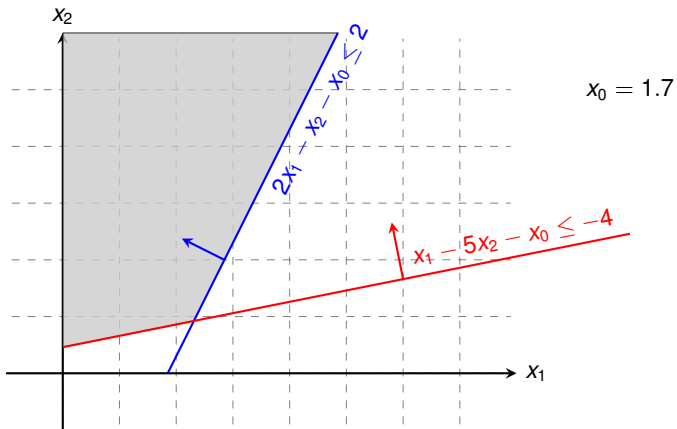
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maximise  
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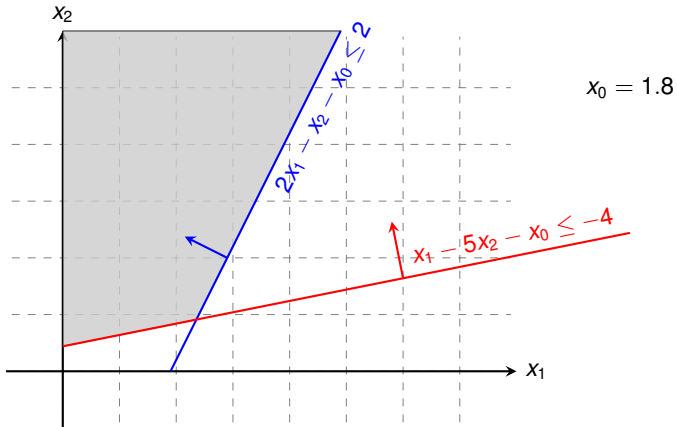
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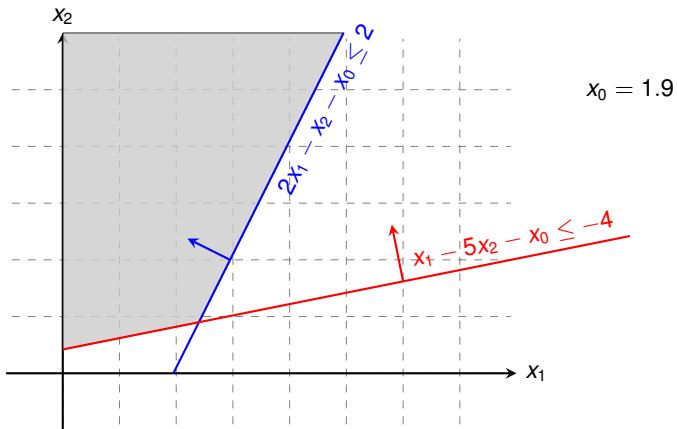
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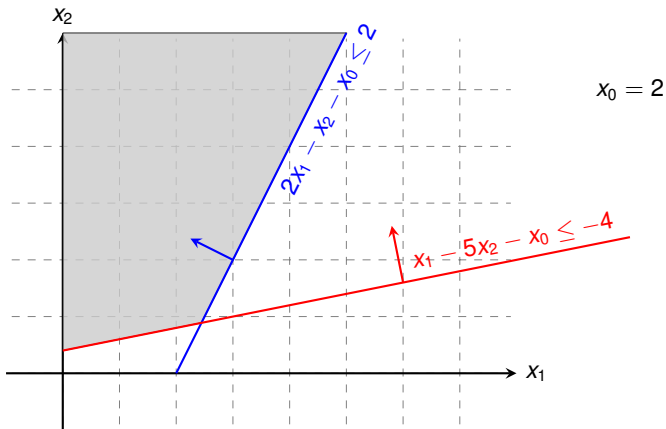
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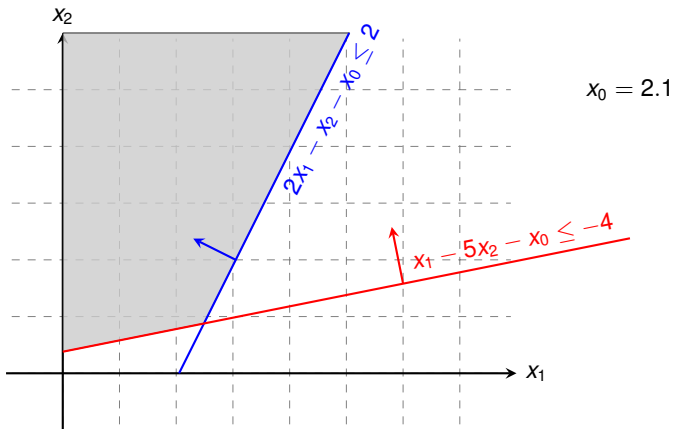
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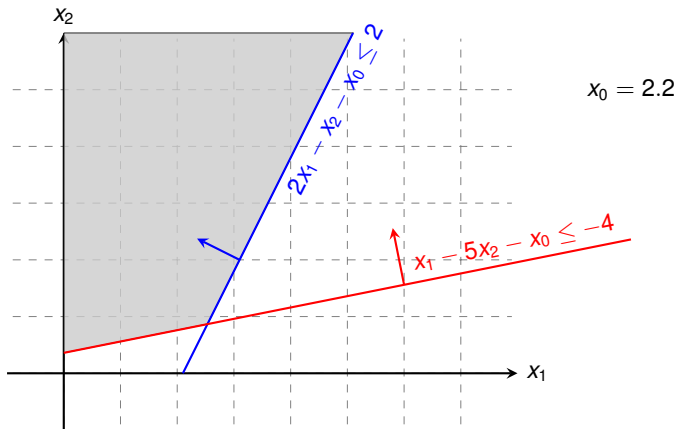
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maximise  
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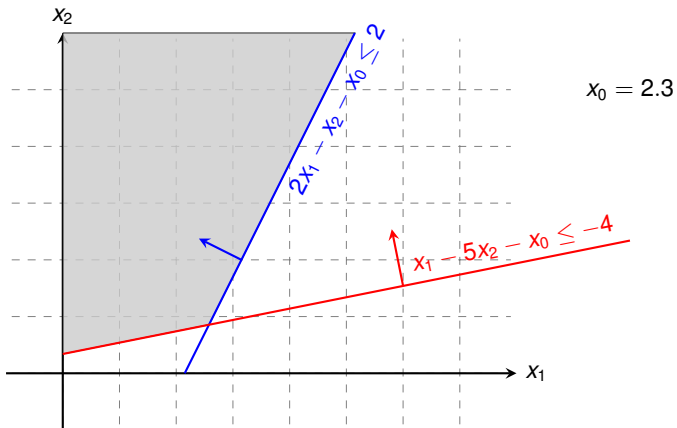
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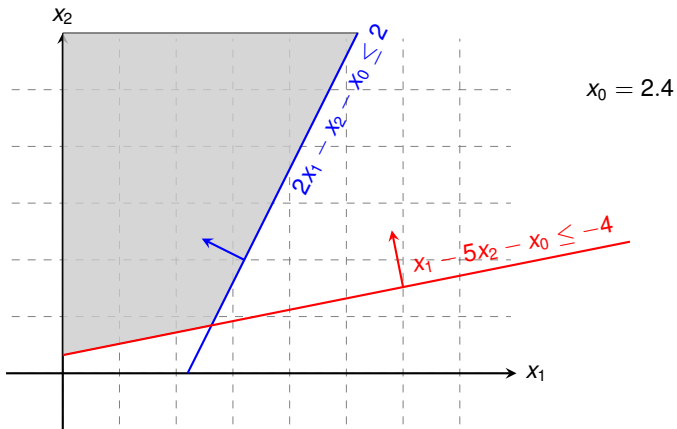
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maximise  
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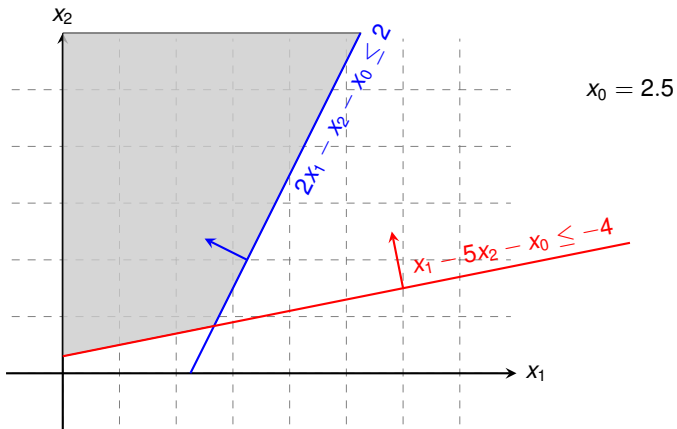
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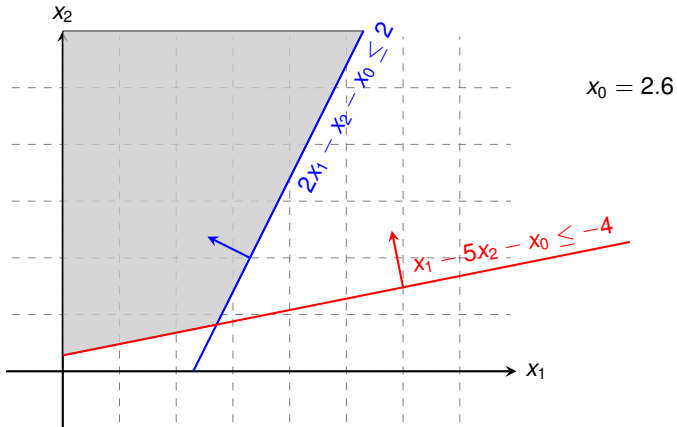
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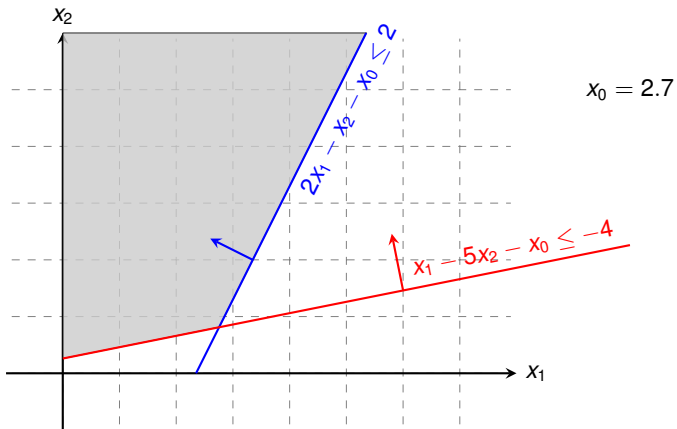
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maximise  
subject to

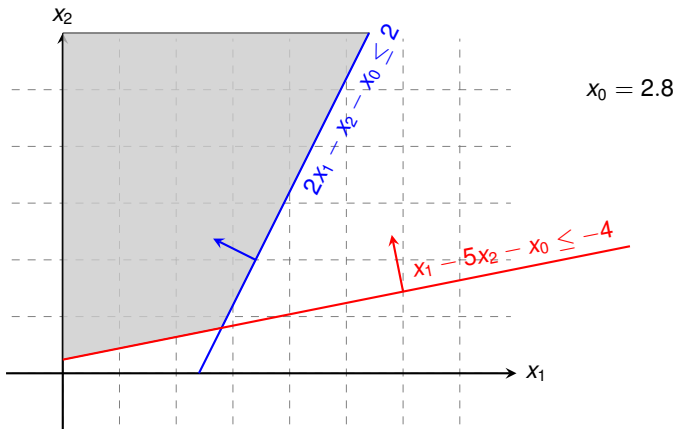
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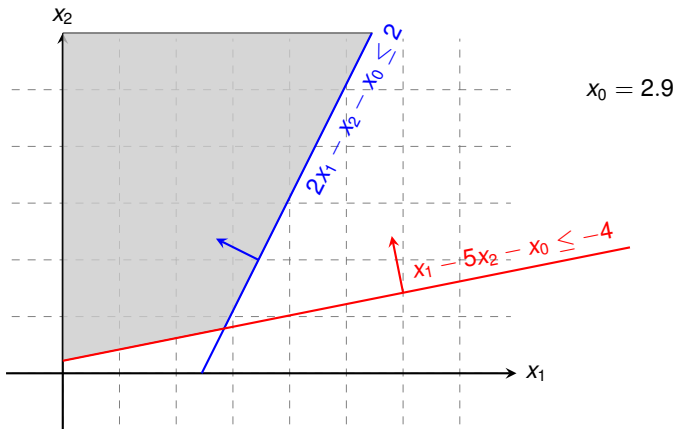




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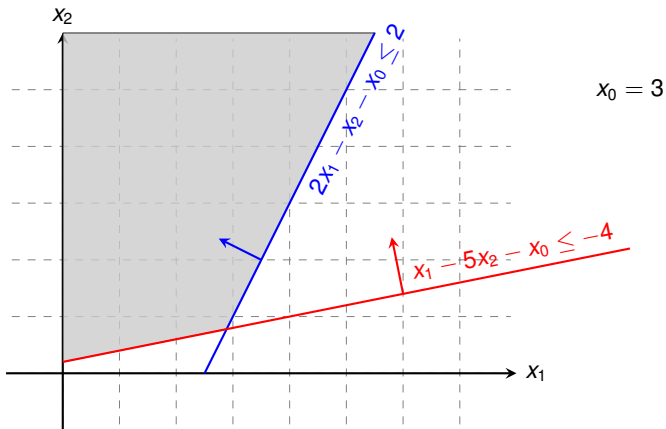
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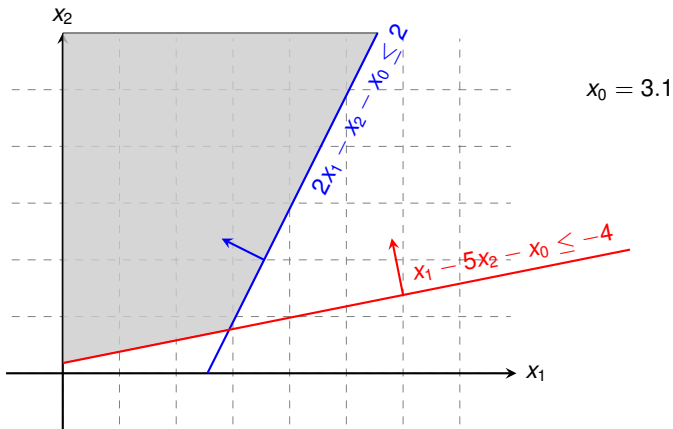
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maximise  
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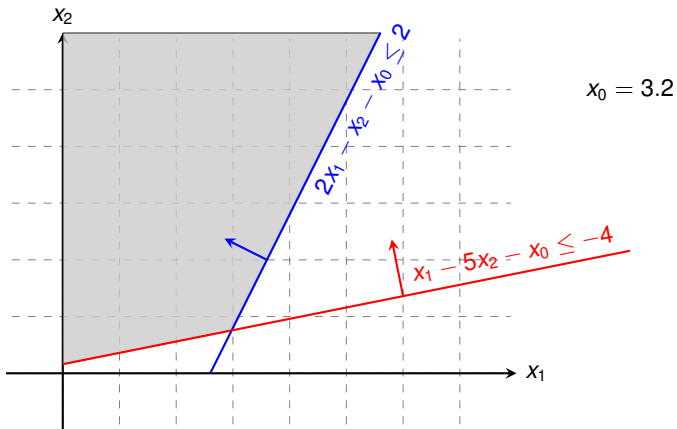
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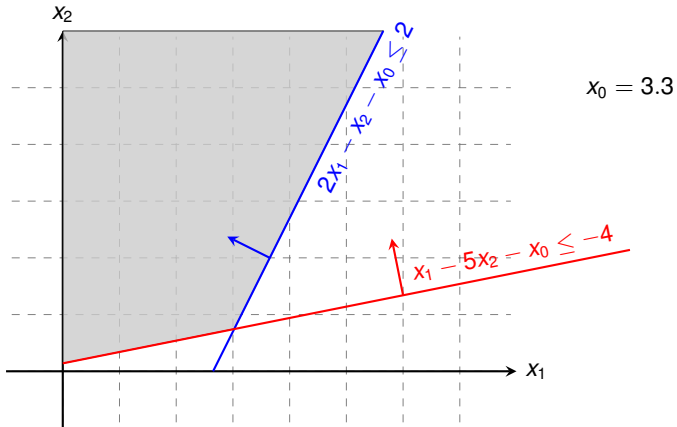
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subject to

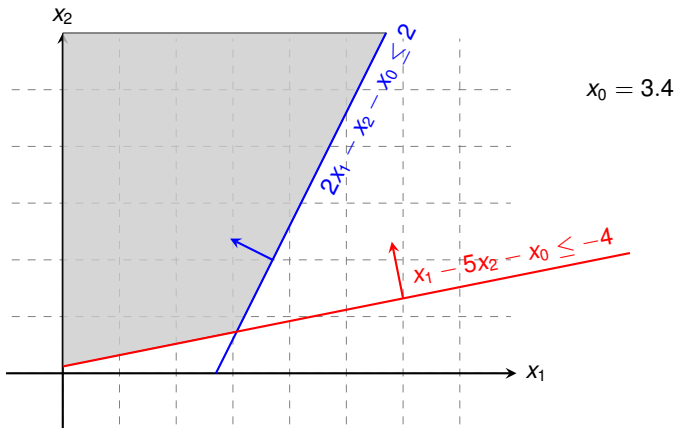
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  $-x_0$   
subject to

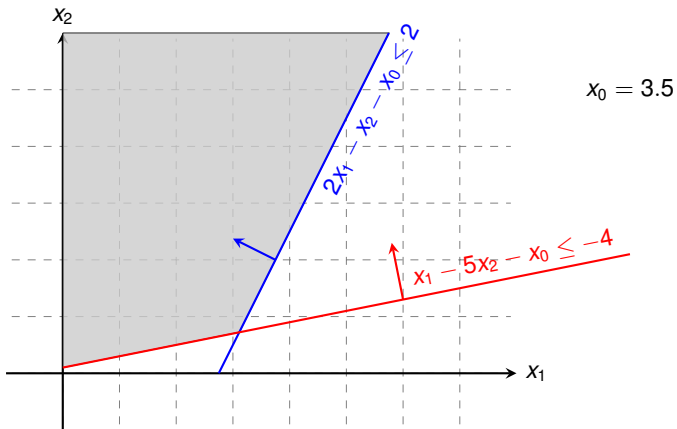
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

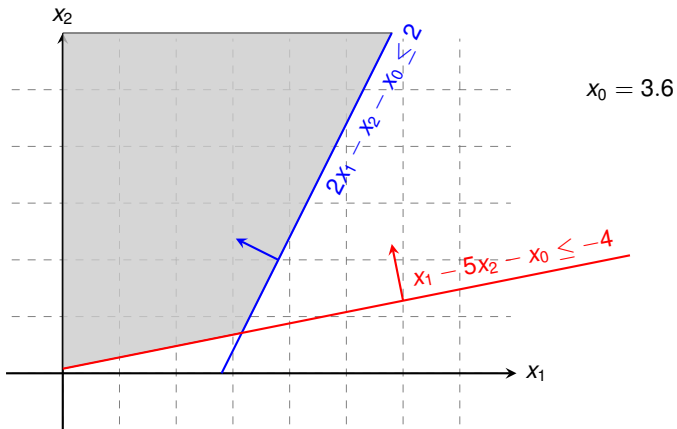
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

$$\begin{array}{rcllcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$

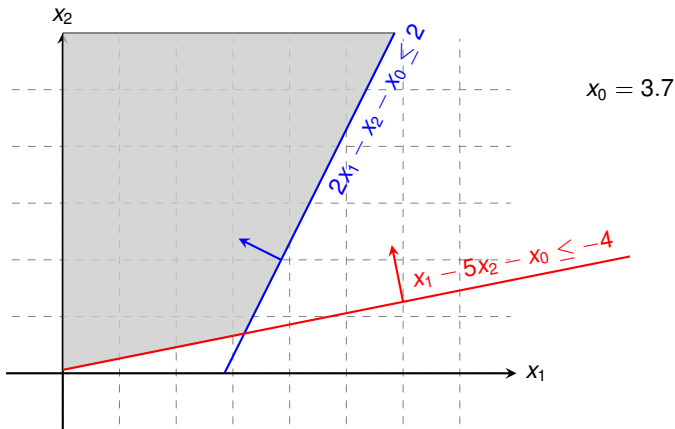




## Geometric Illustration

maximise  
subject to

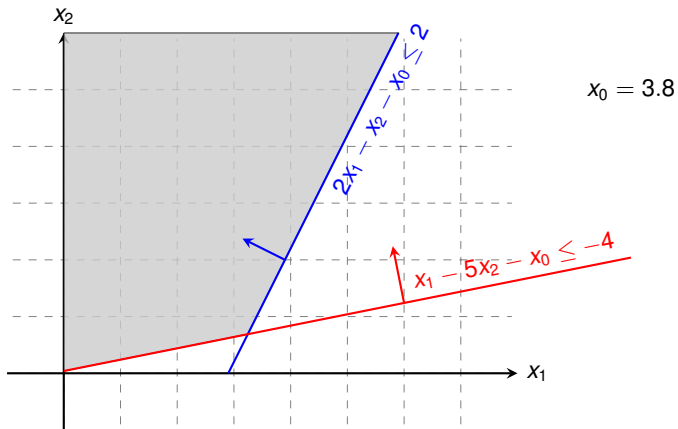
$$\begin{array}{rclclcl} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

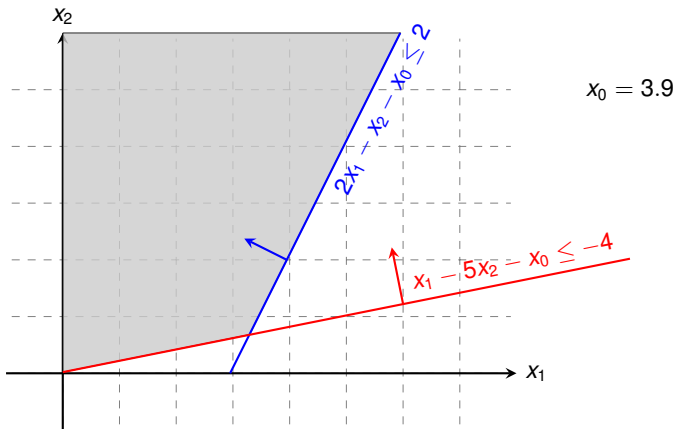
$$\begin{array}{rclclcl} -x_0 & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



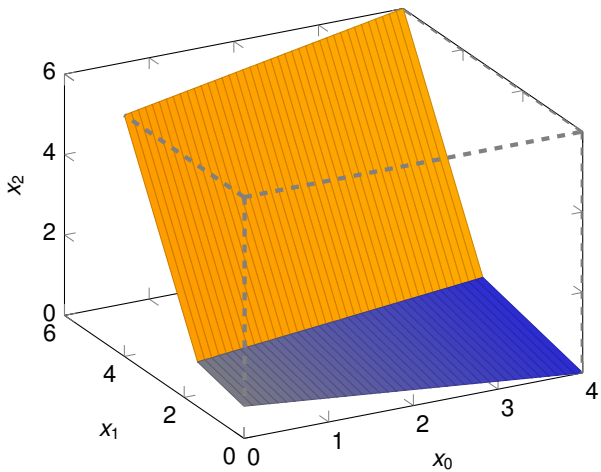
## Geometric Illustration

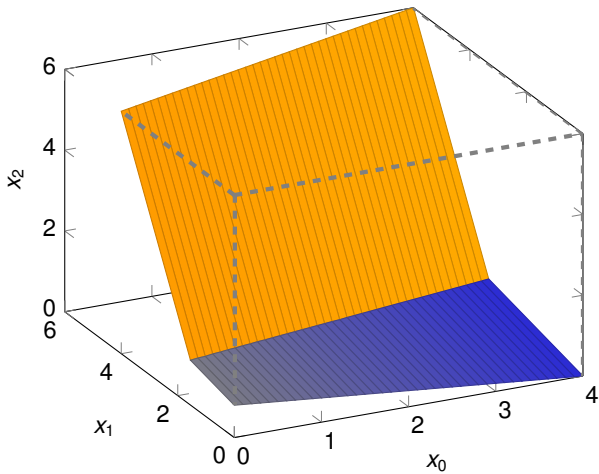
maximise  
subject to

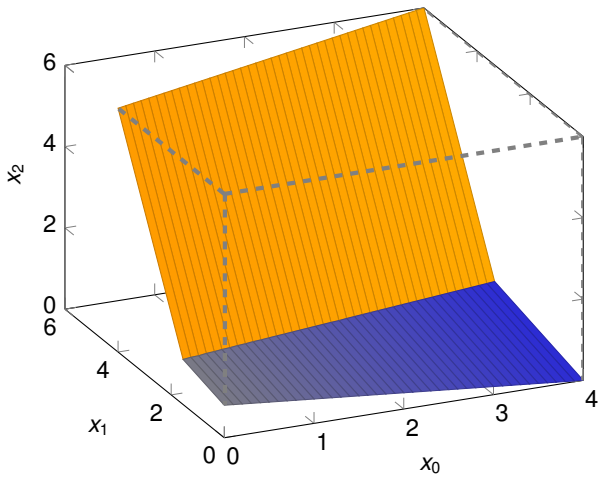
$$\begin{array}{rclclcl} 2x_1 & - & x_2 & - & x_0 & \leq & 2 \\ x_1 & - & 5x_2 & - & x_0 & \leq & -4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$

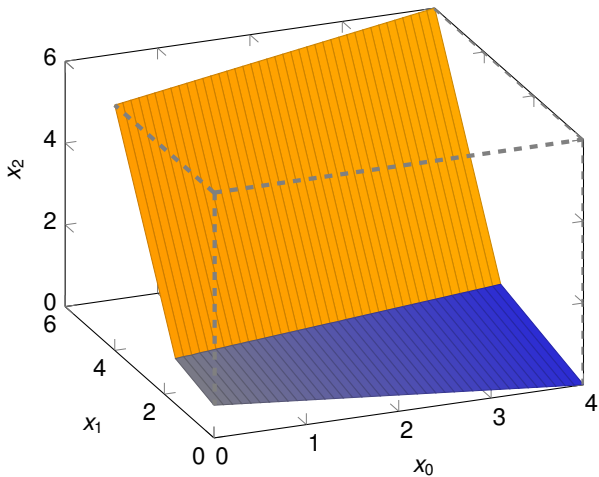


Now the Feasible Region of the Auxiliary LP in 3D

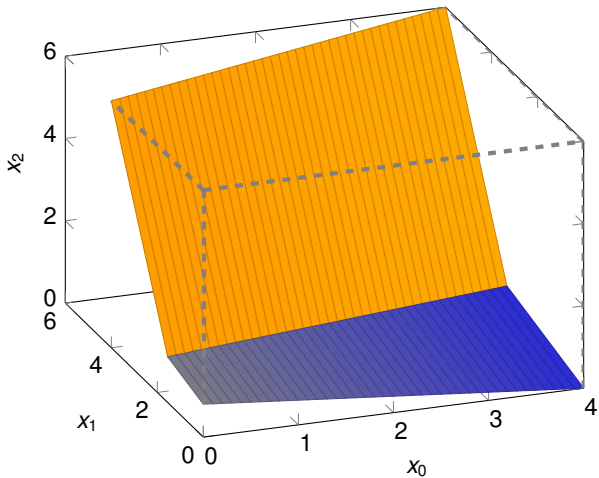


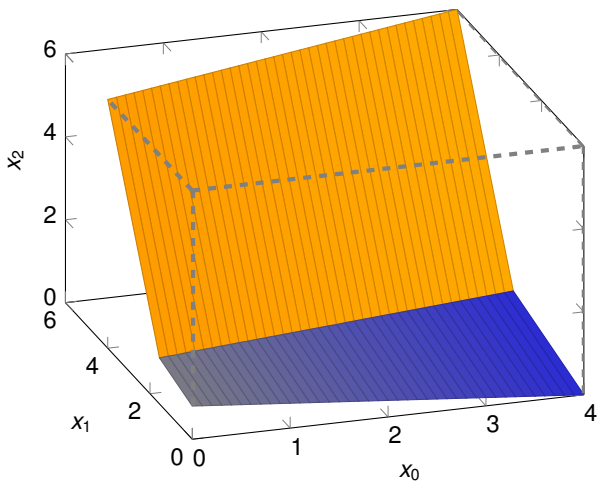


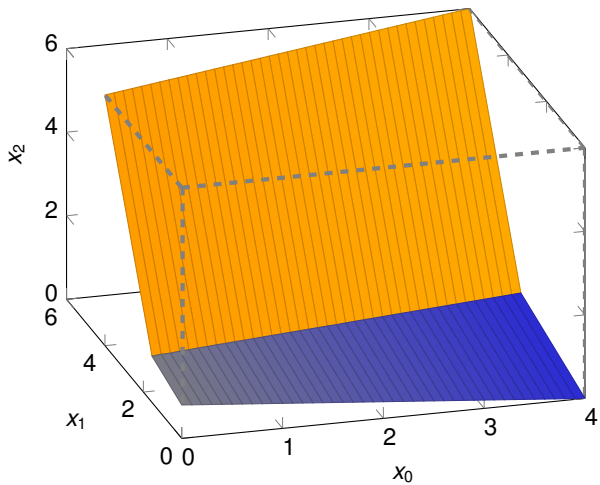


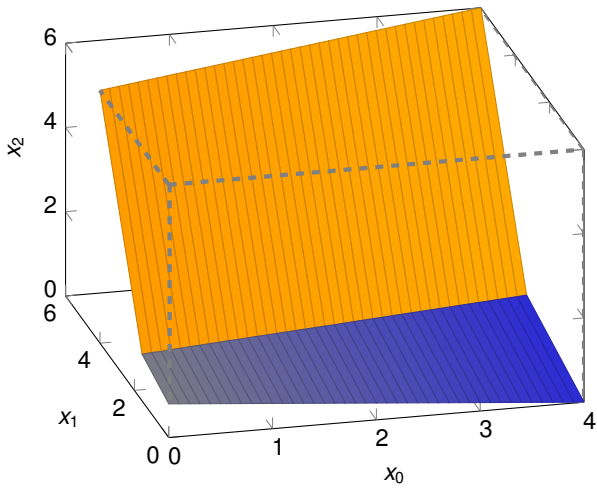


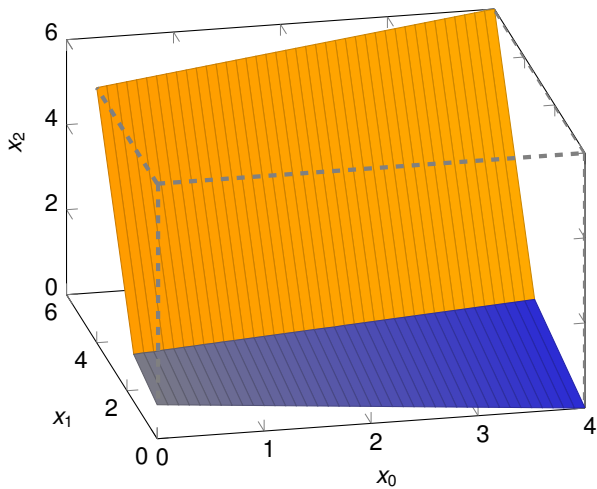


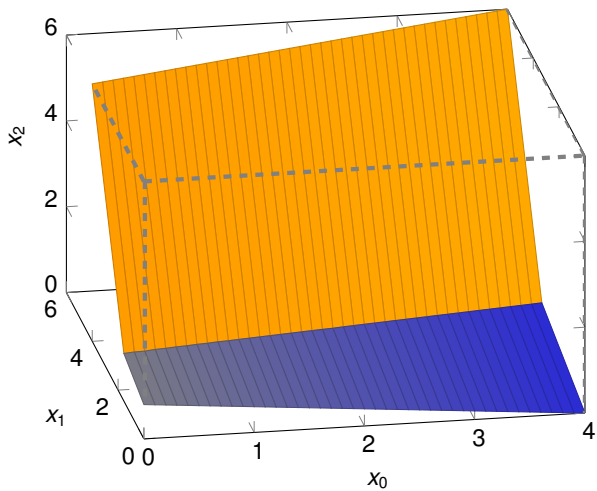


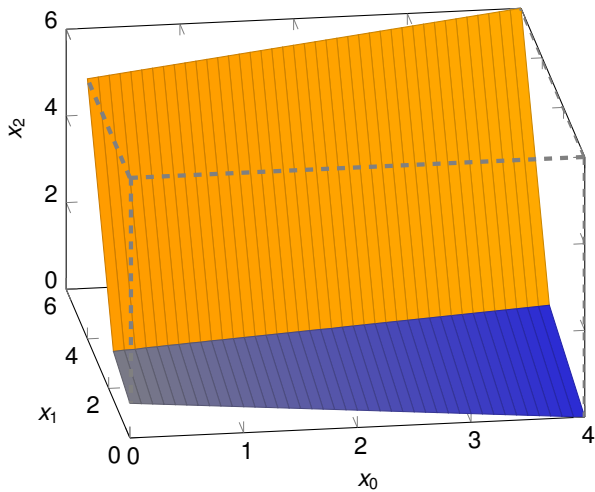


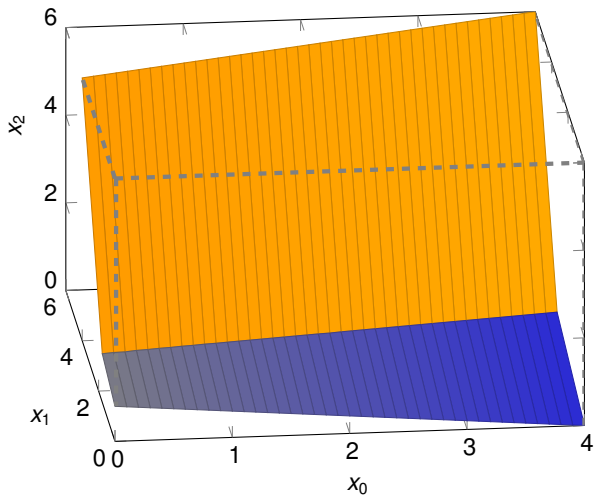




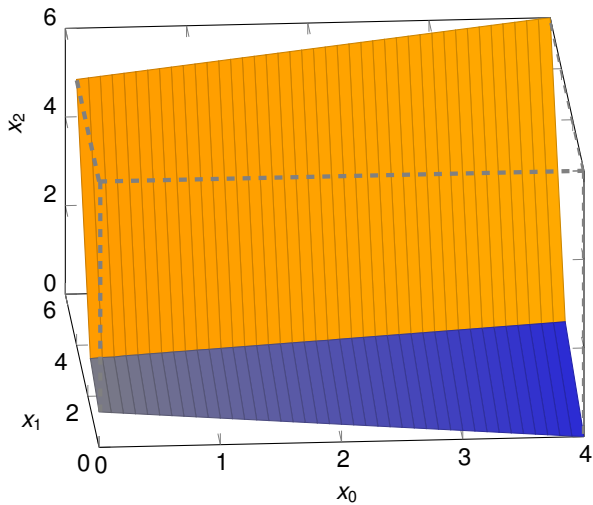


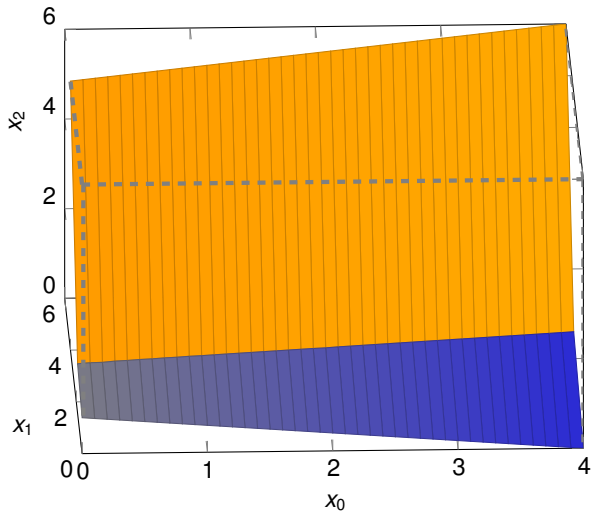


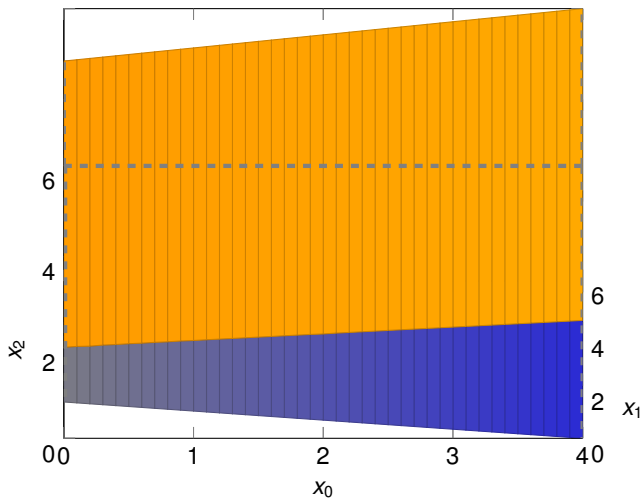


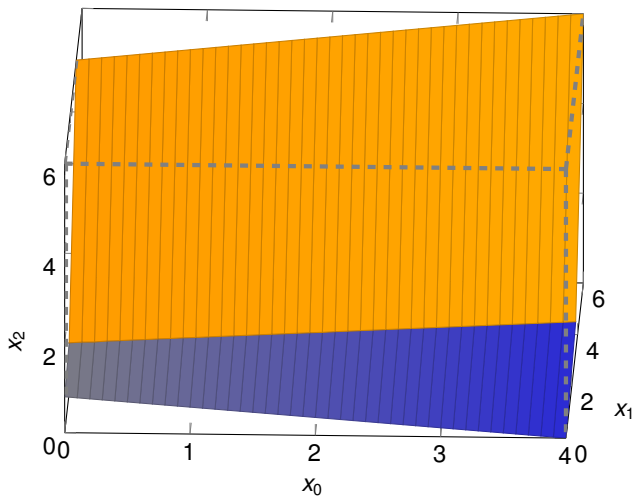


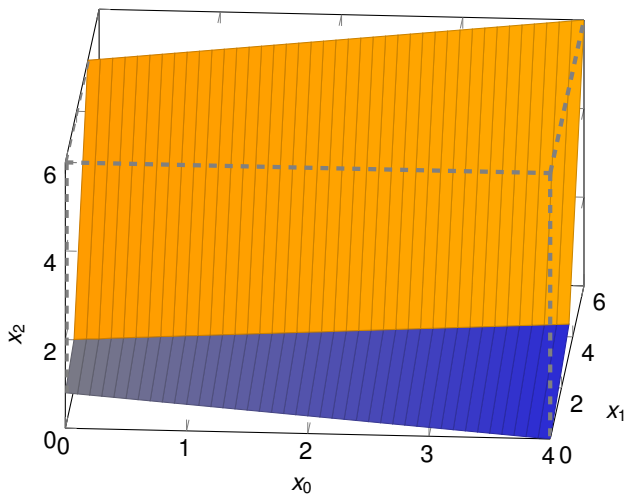


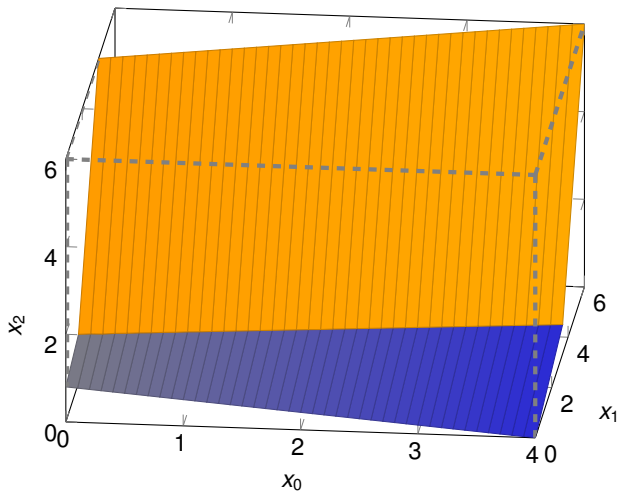


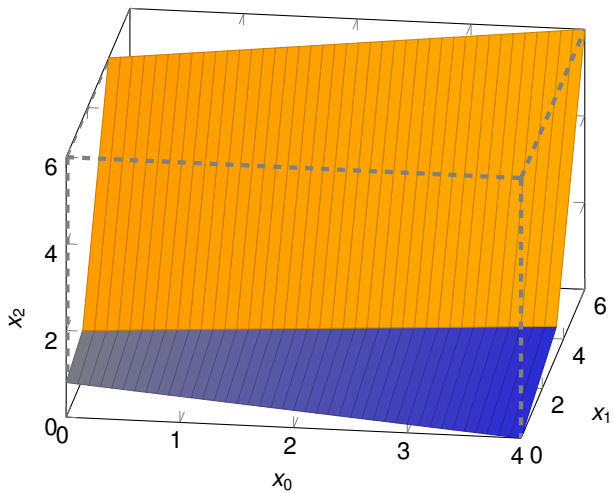


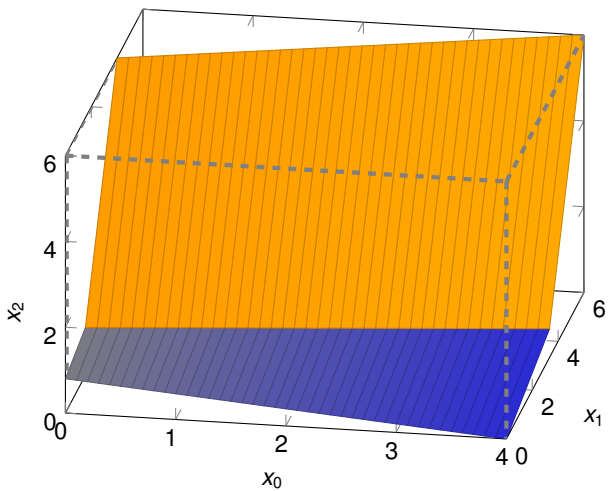




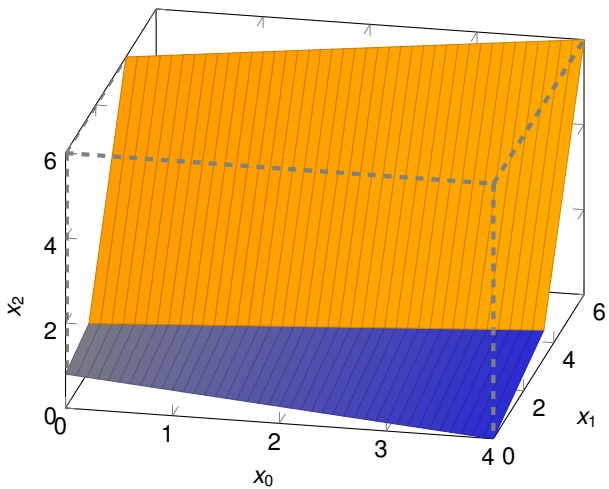


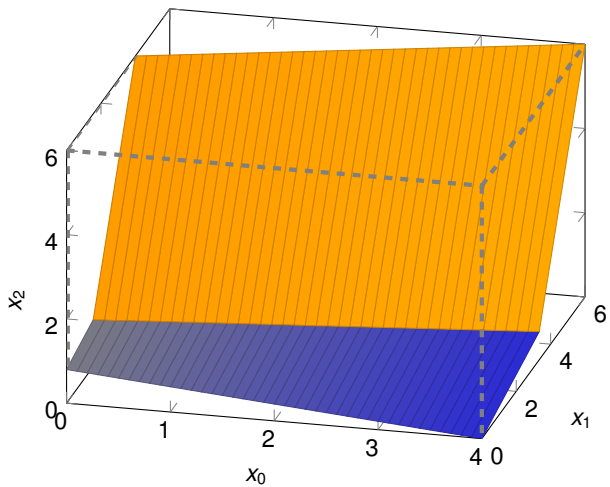


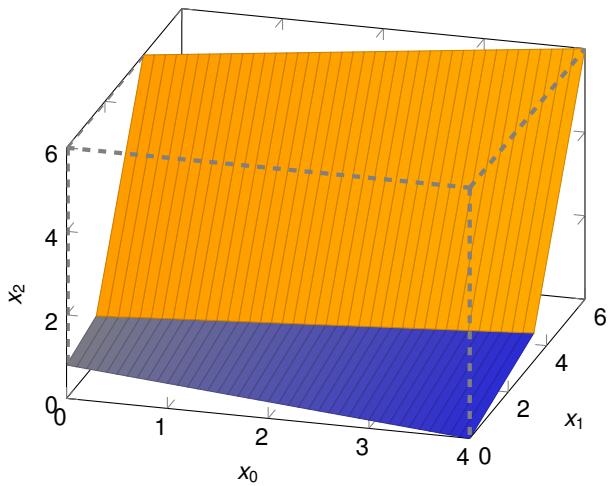


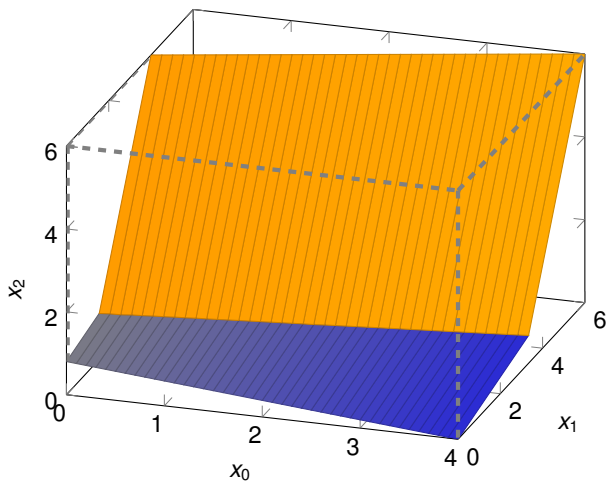


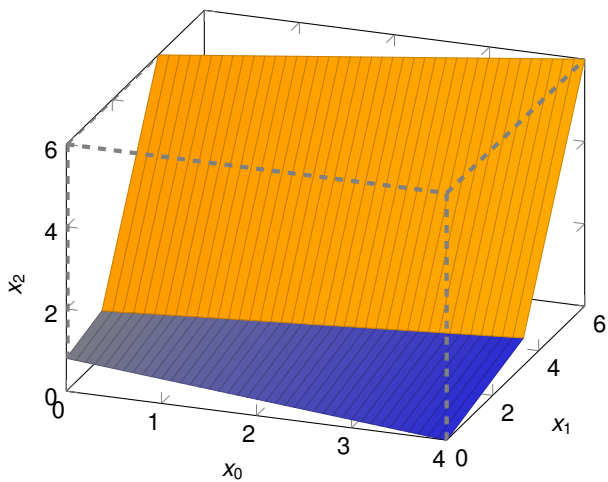


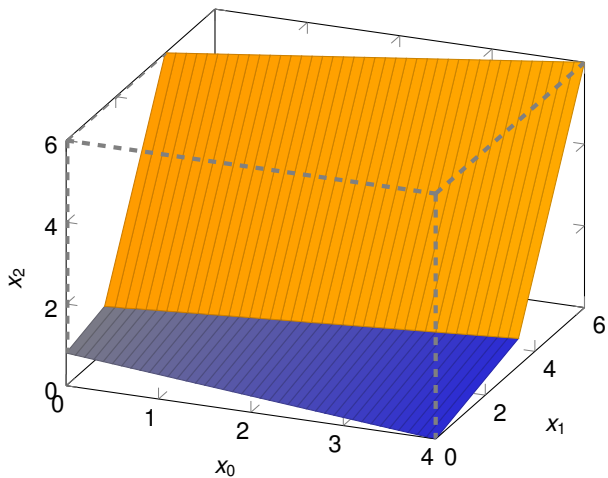


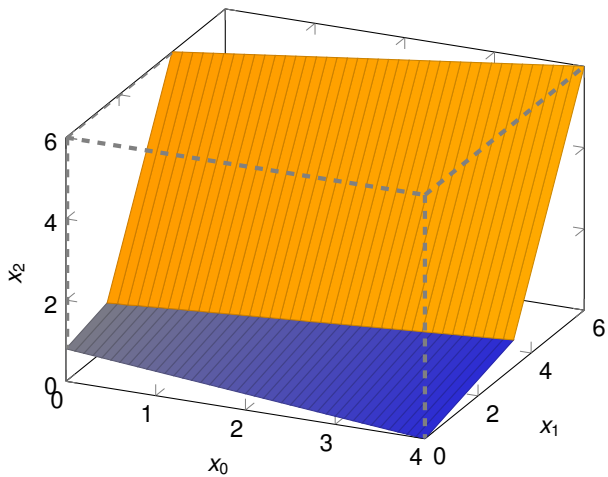


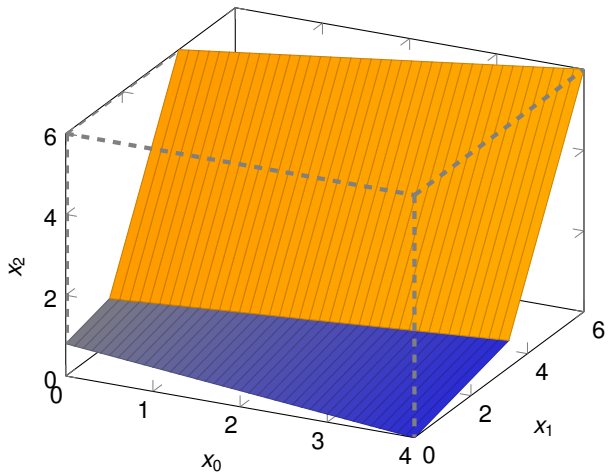




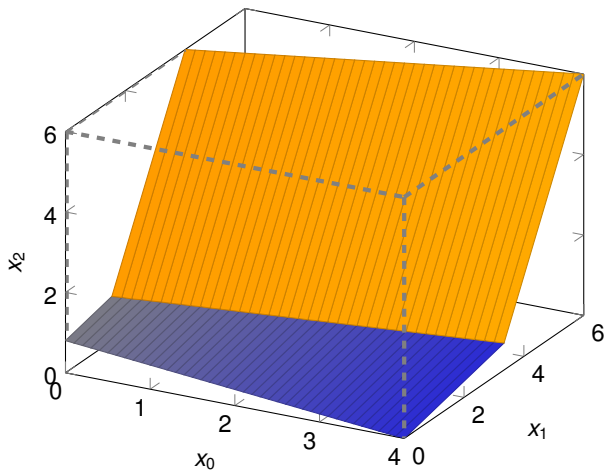


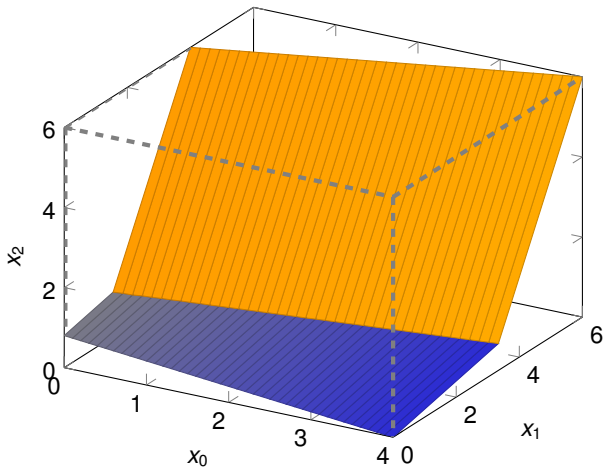


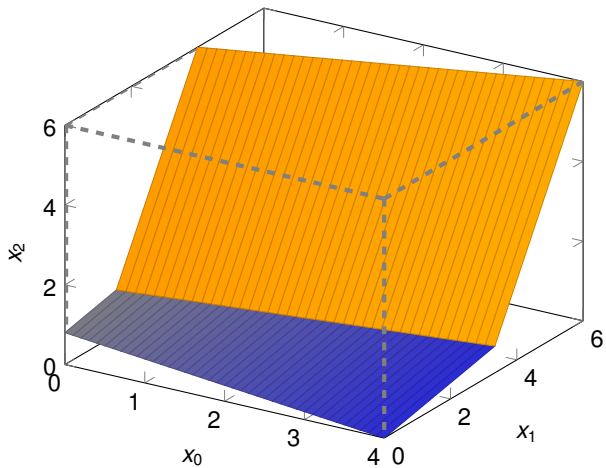


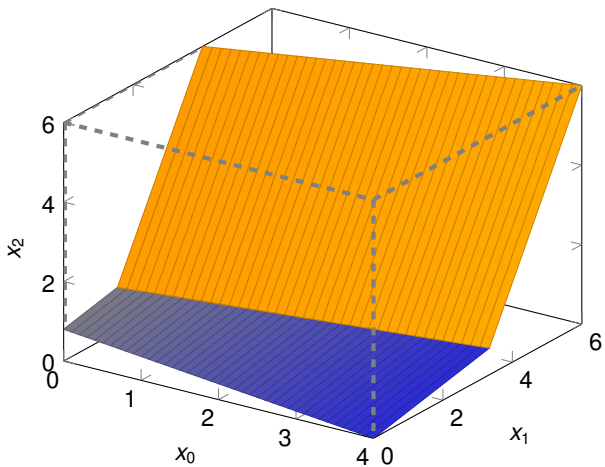


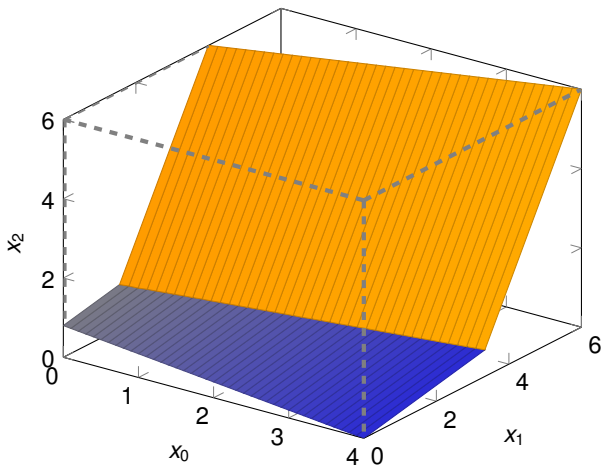


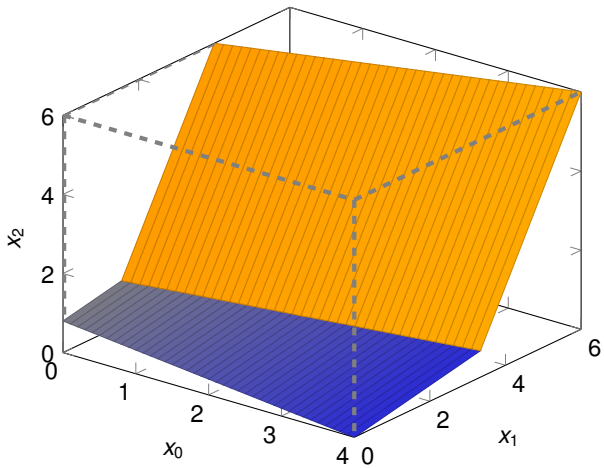


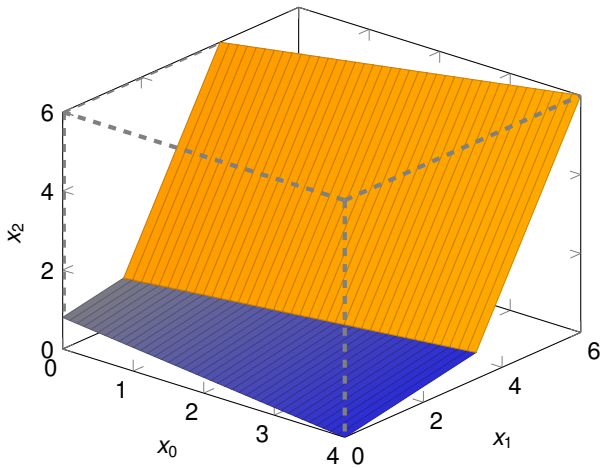


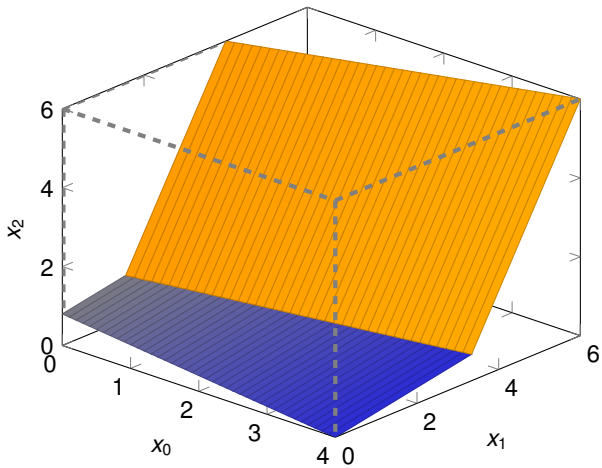




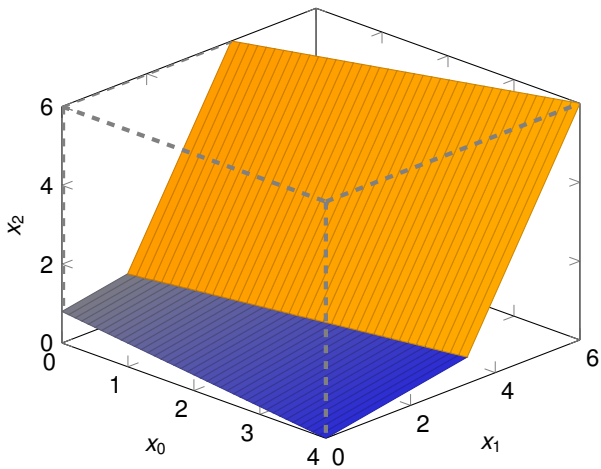


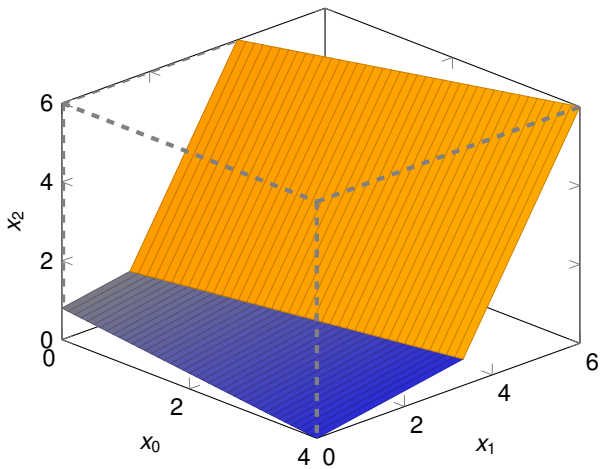


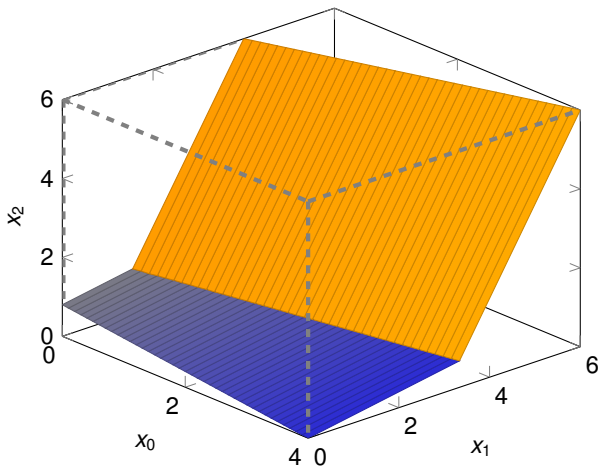


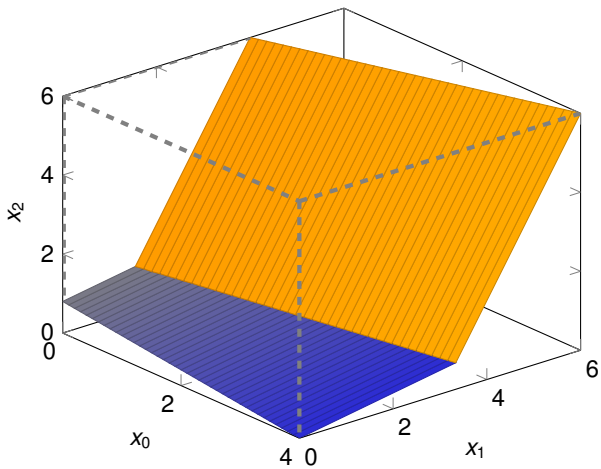


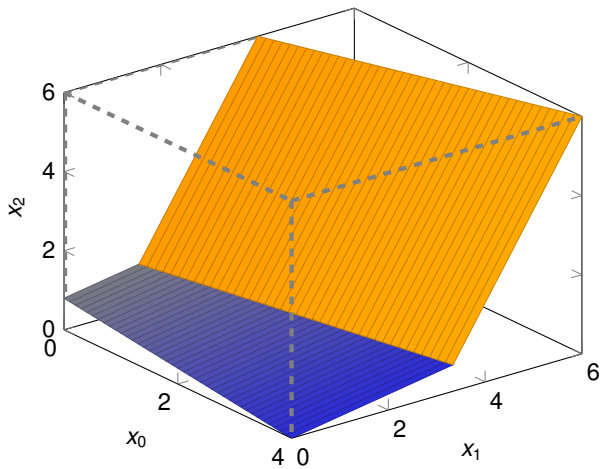


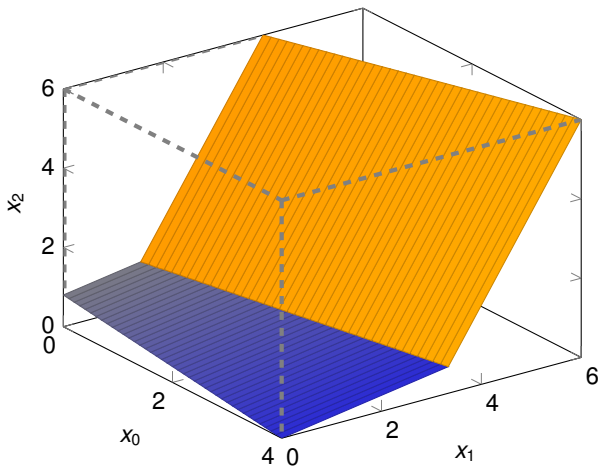


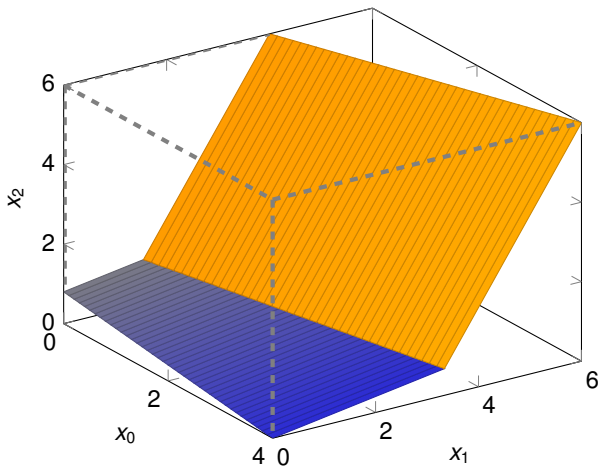


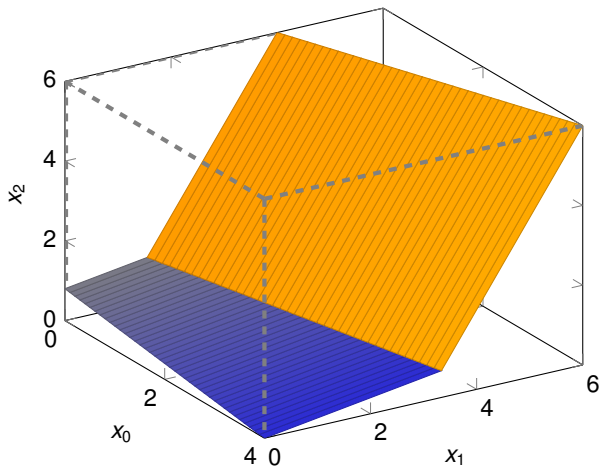




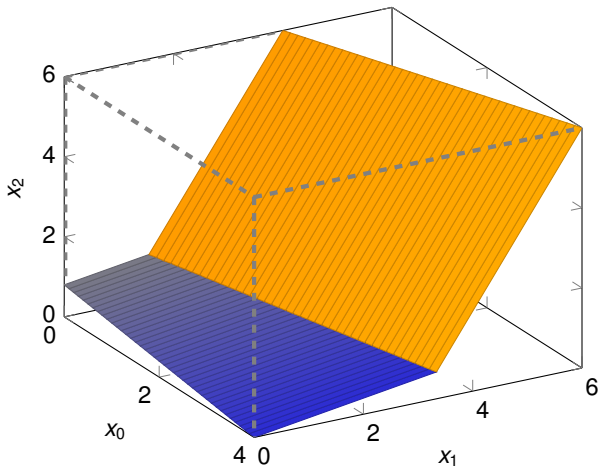


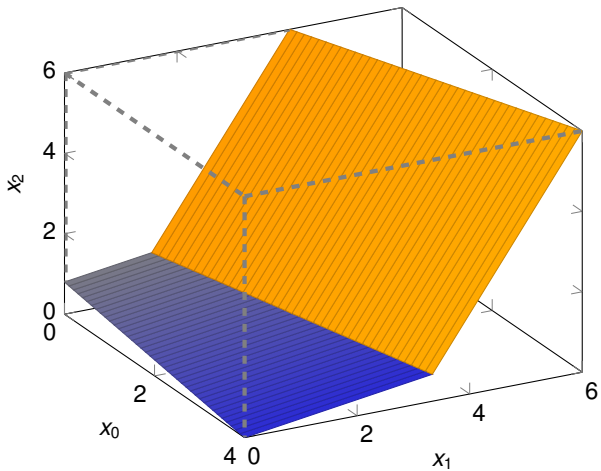


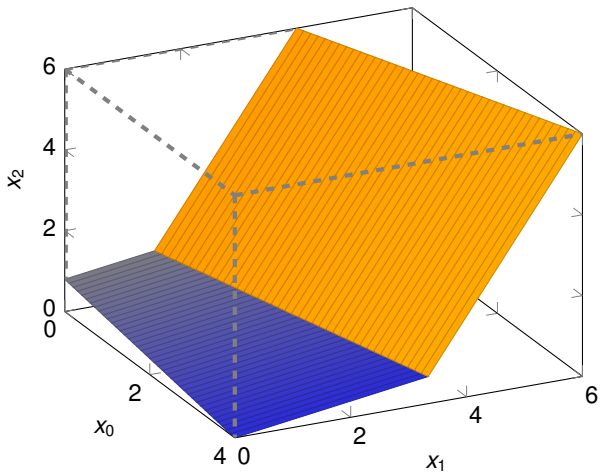


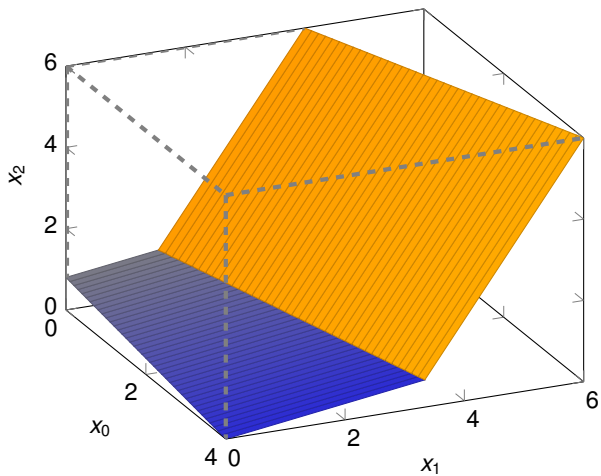


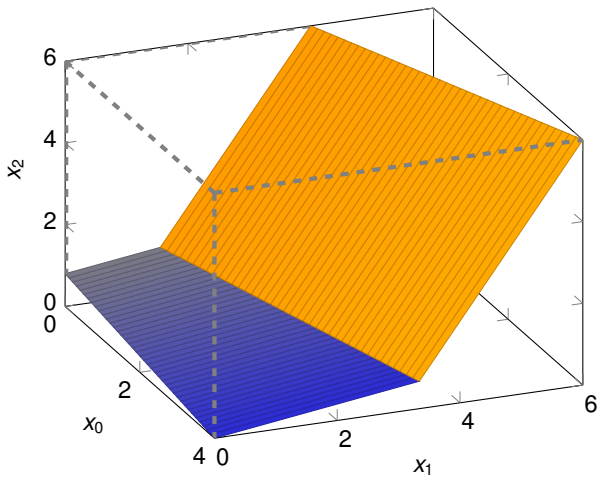


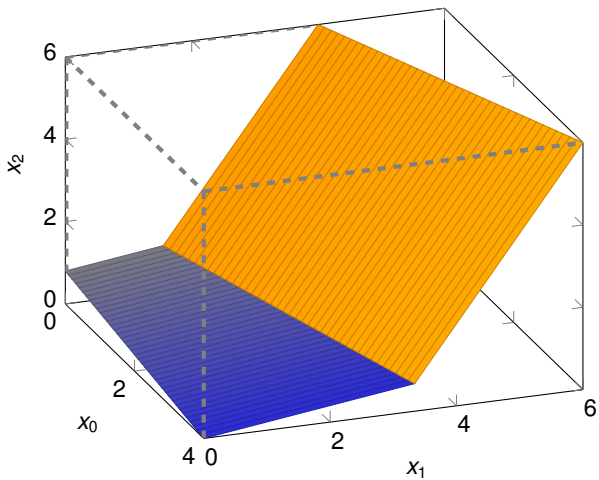


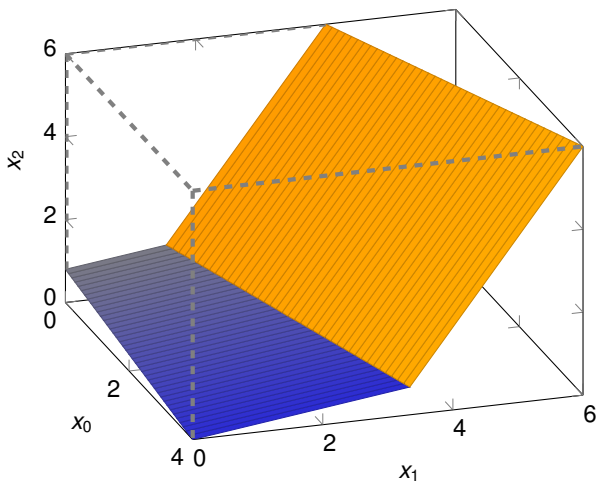


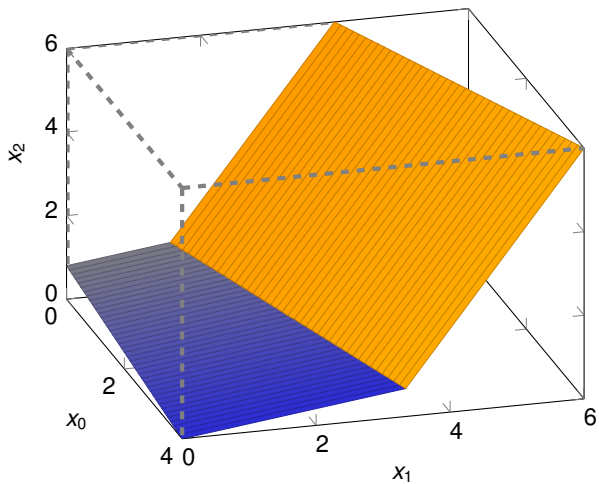




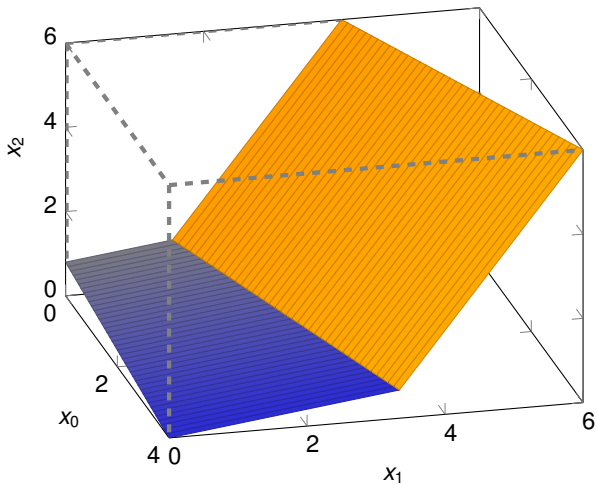


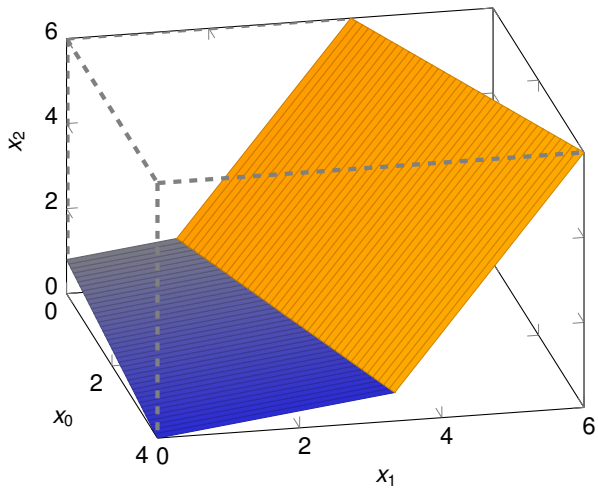


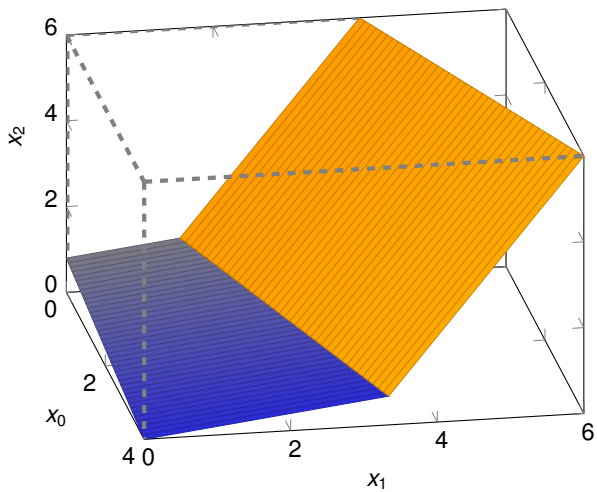


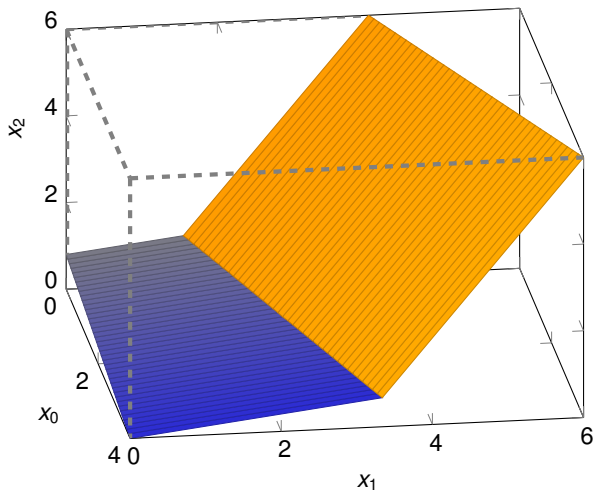


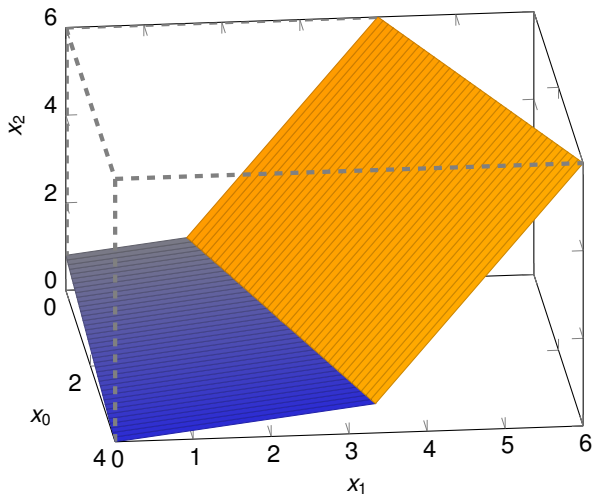


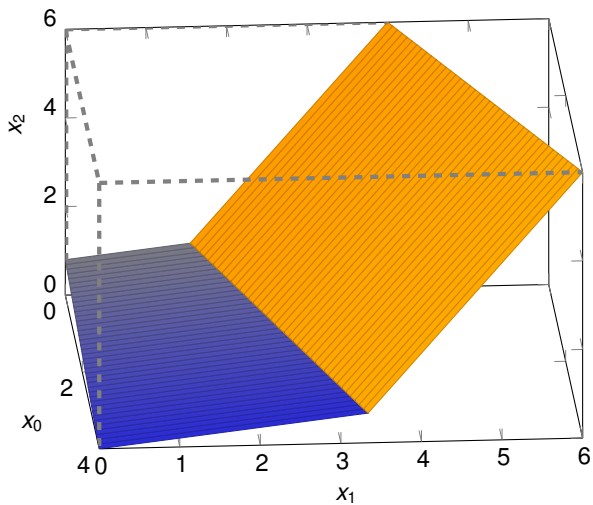


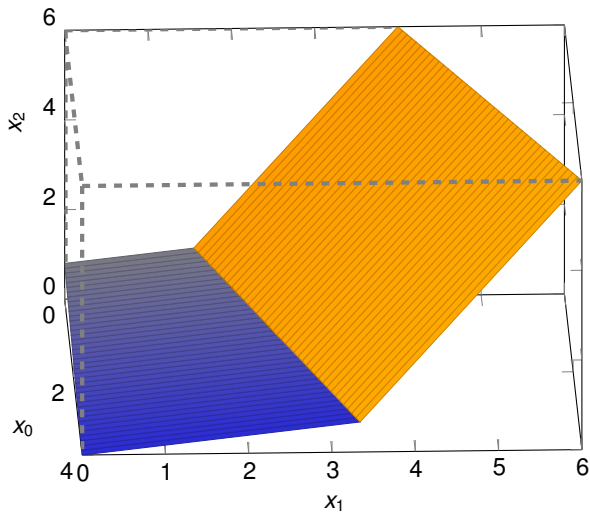


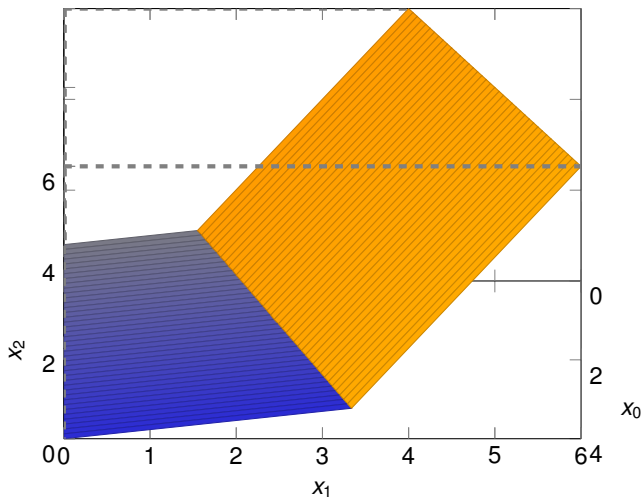




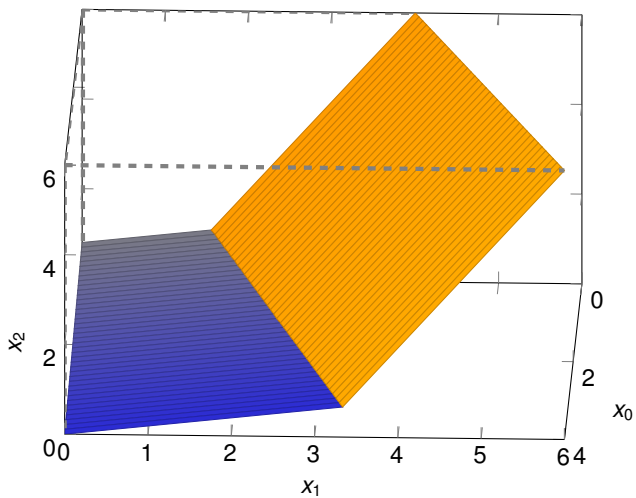


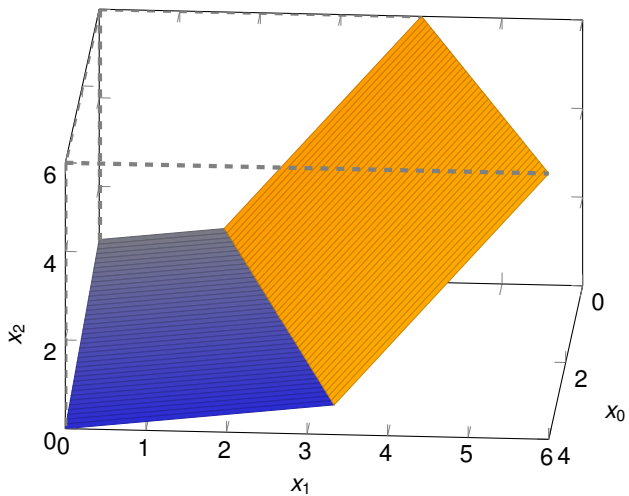


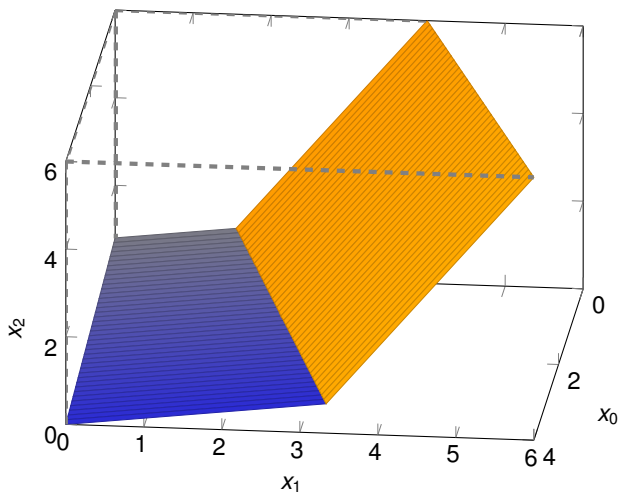


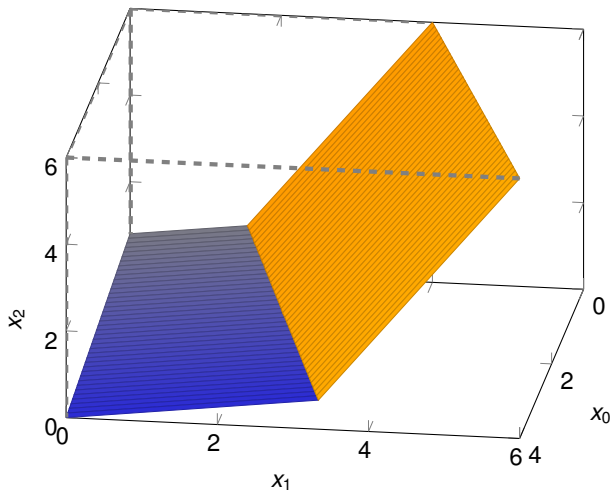


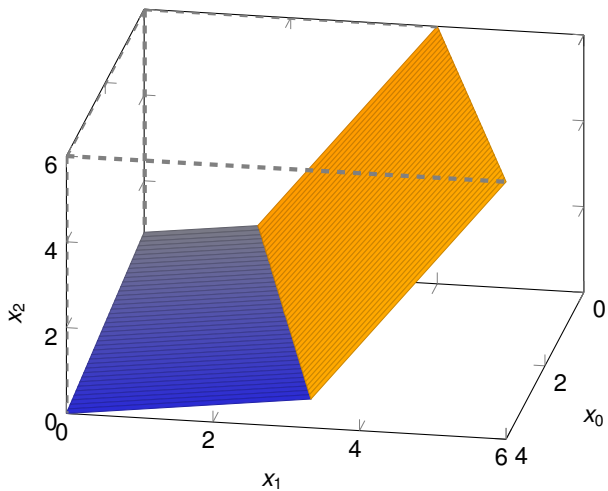


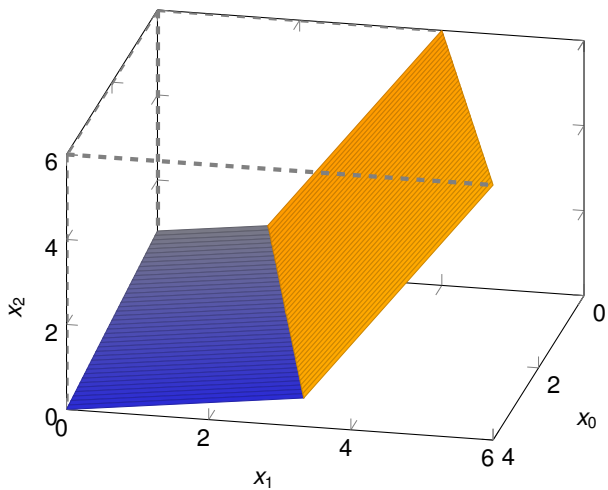


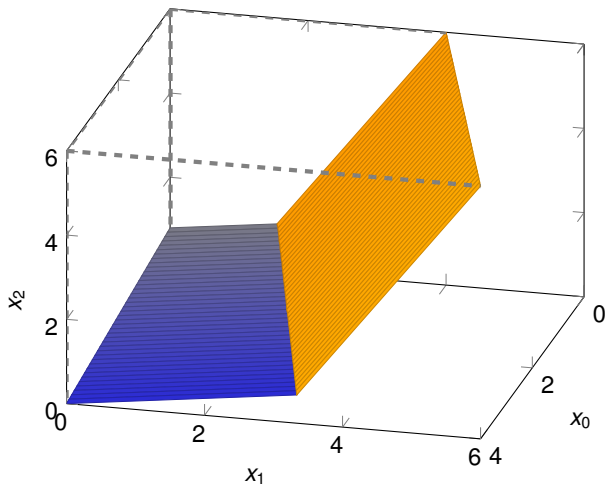


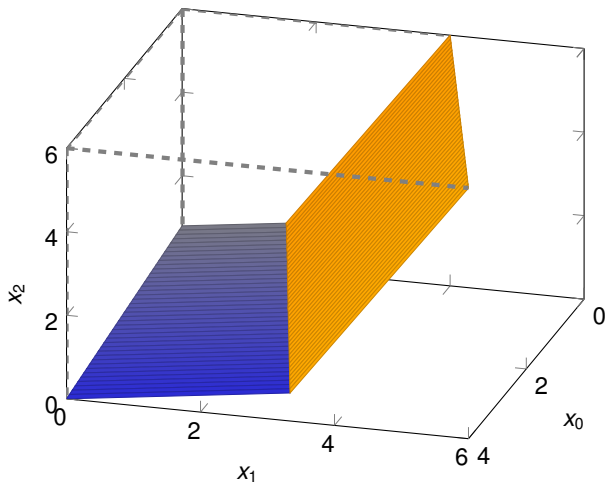




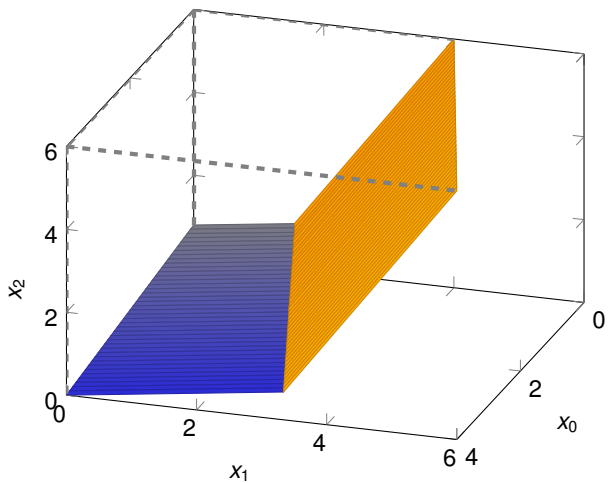


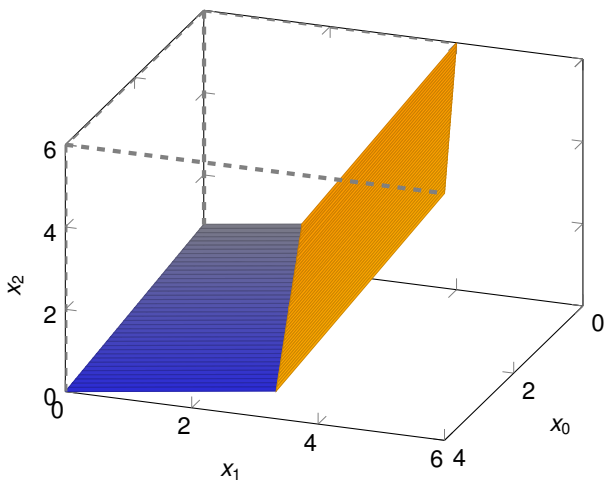


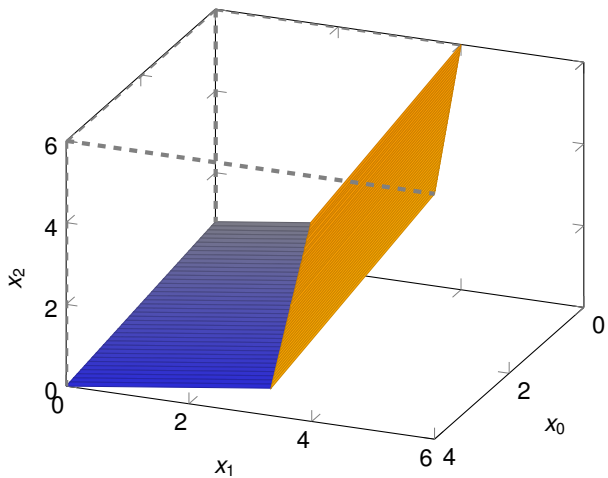


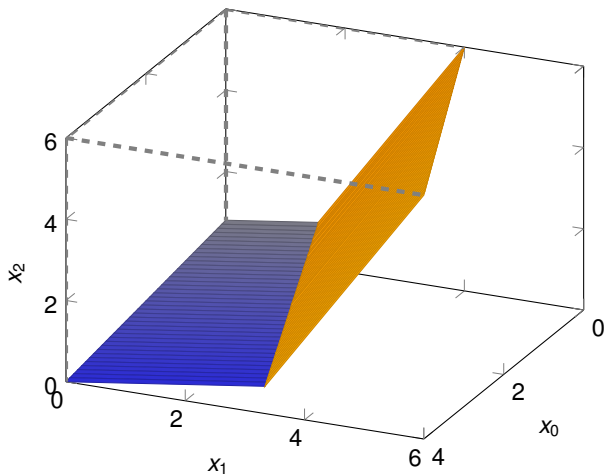


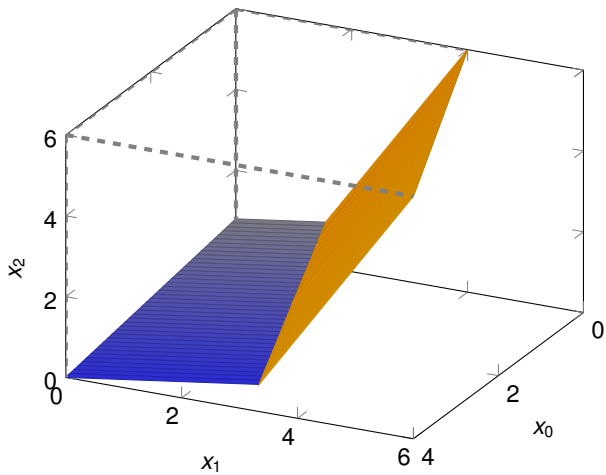


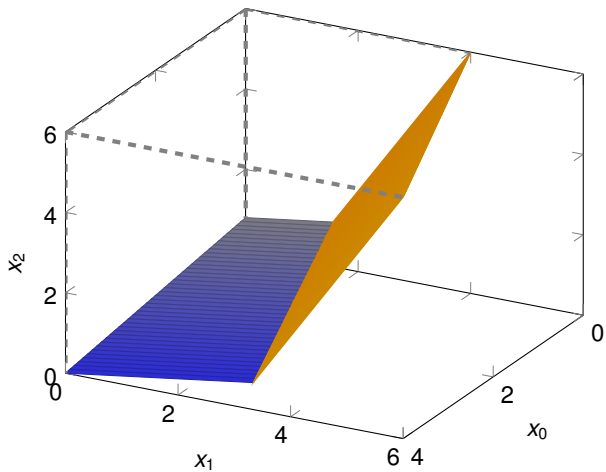


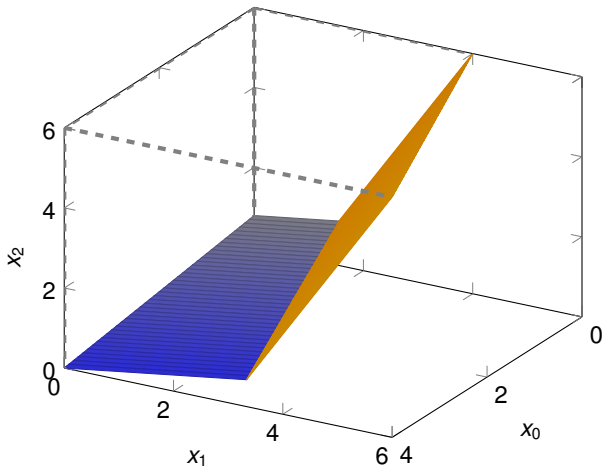


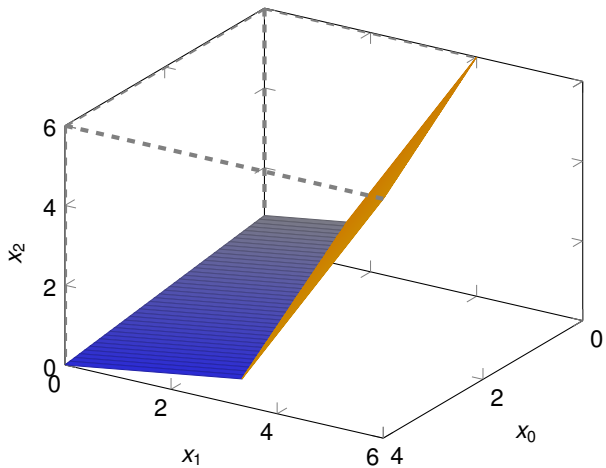




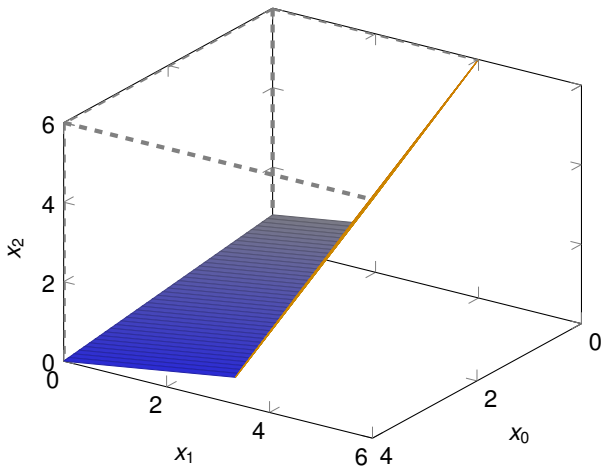


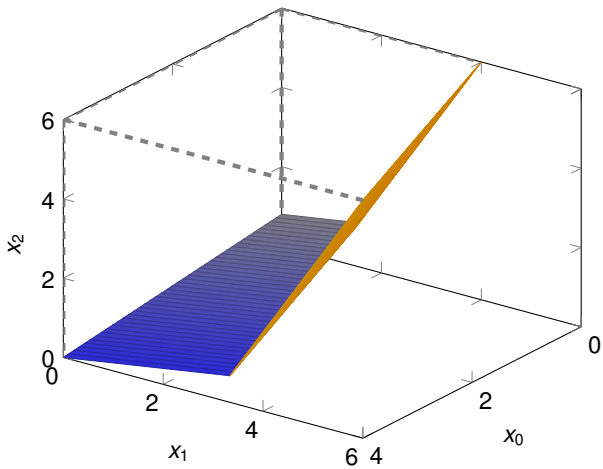


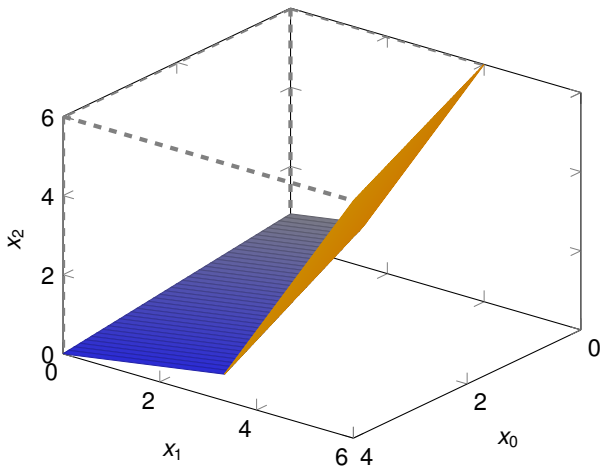


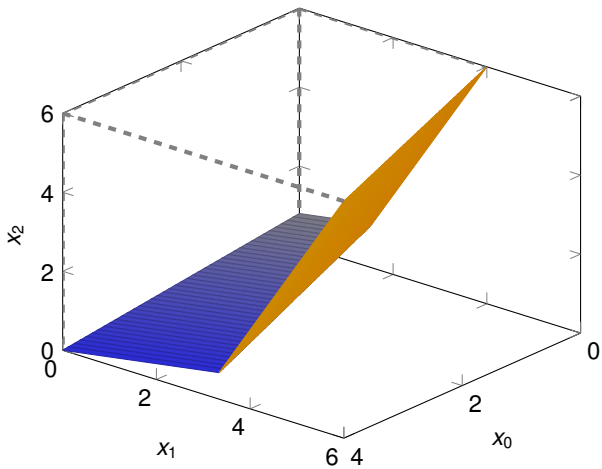


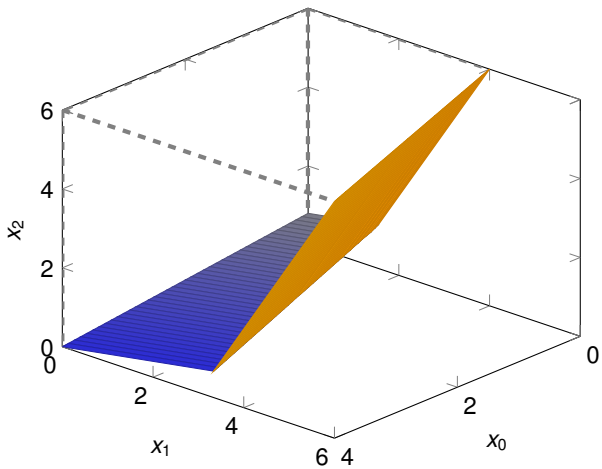


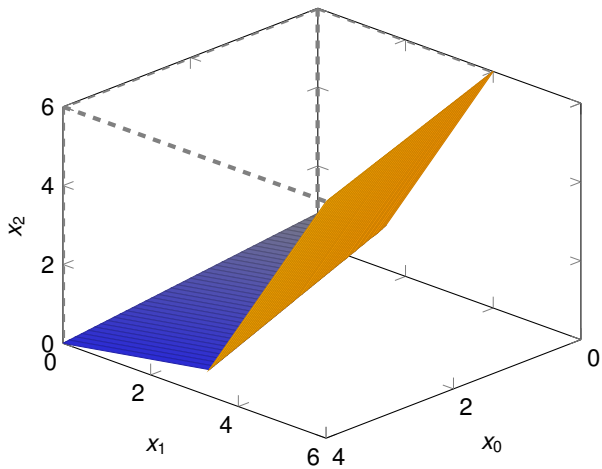


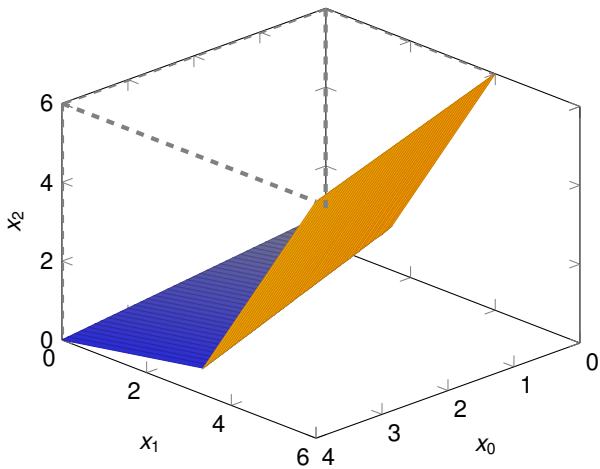


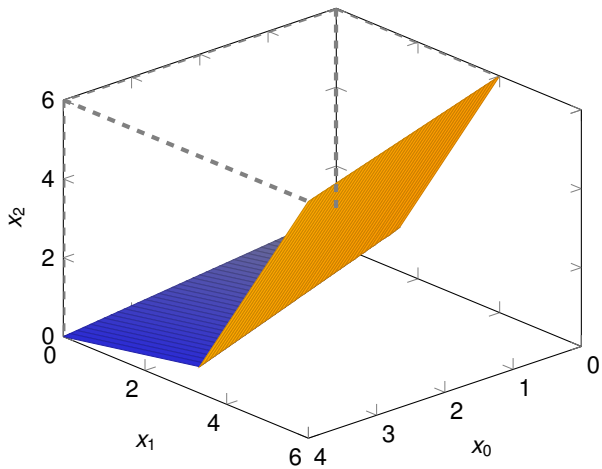




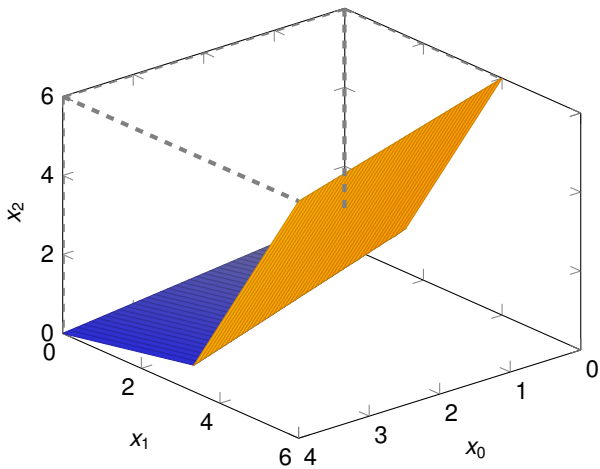


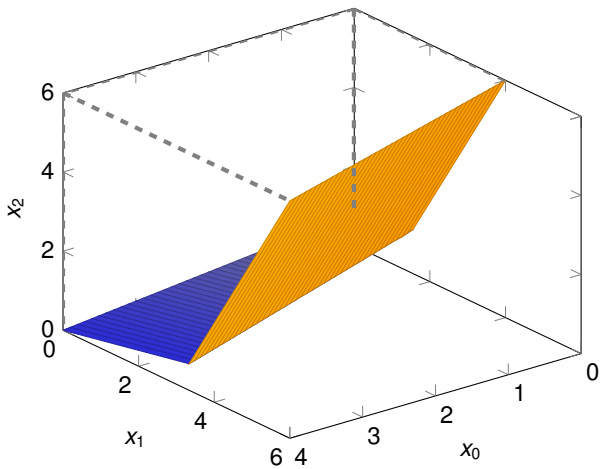


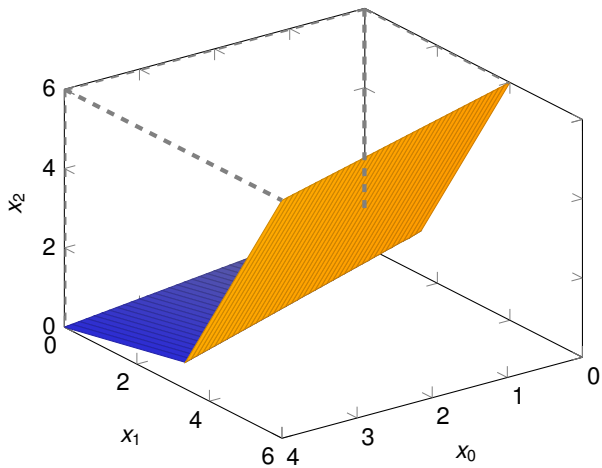


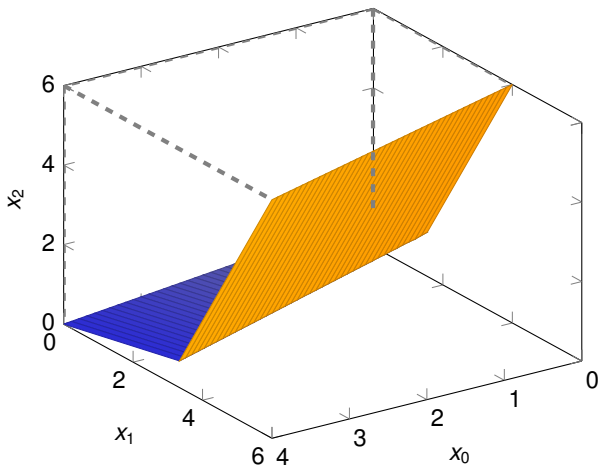


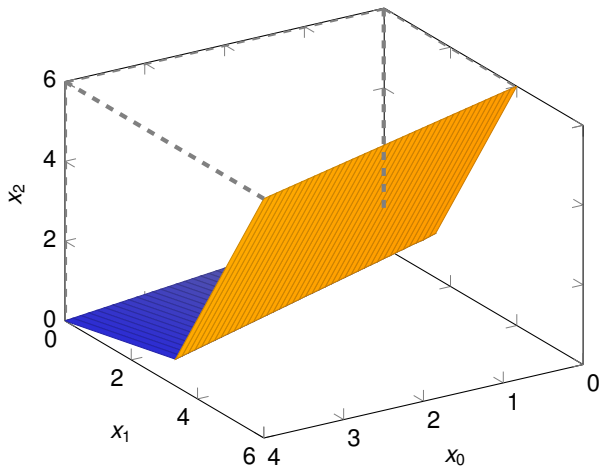


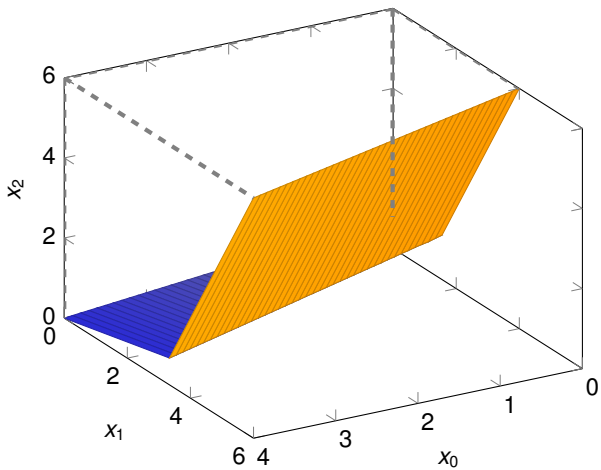


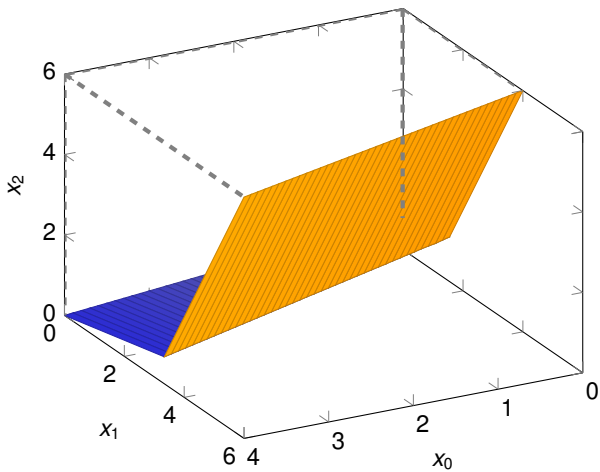


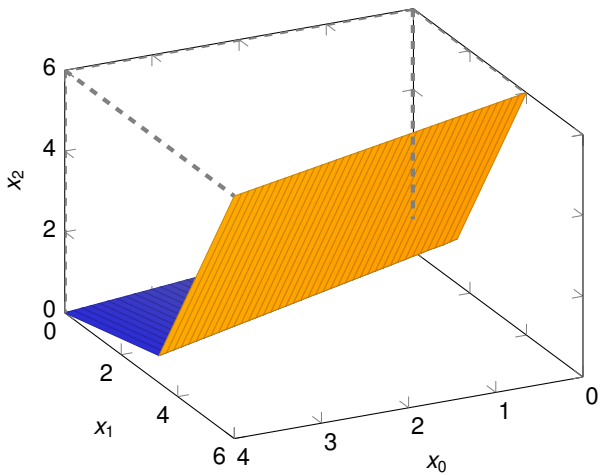




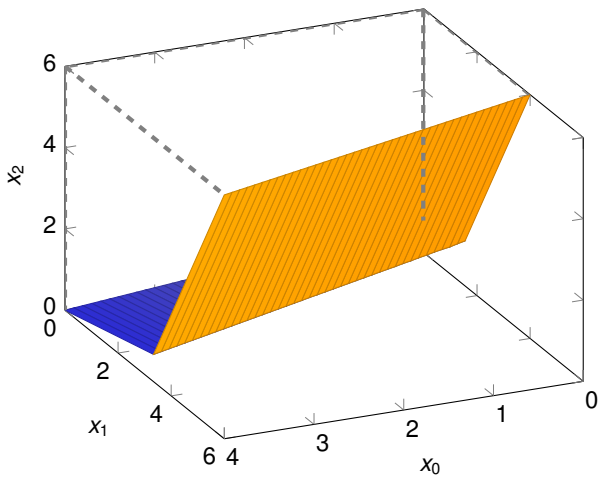


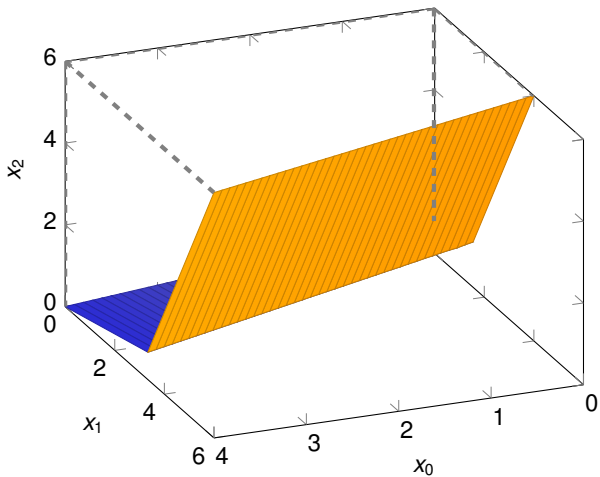


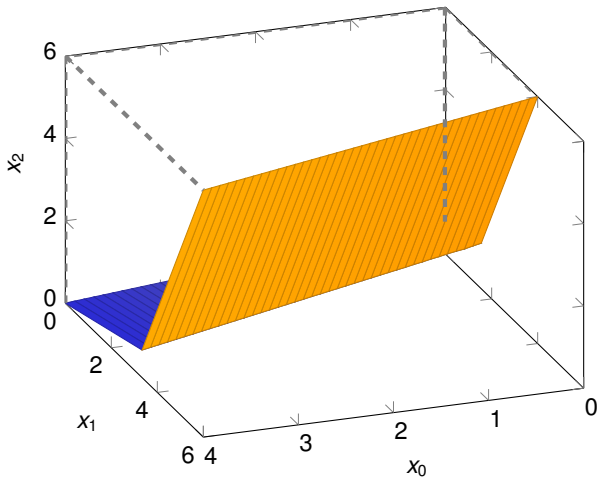


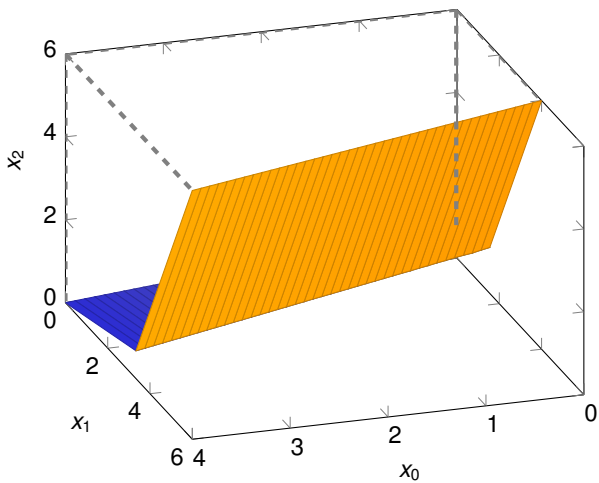


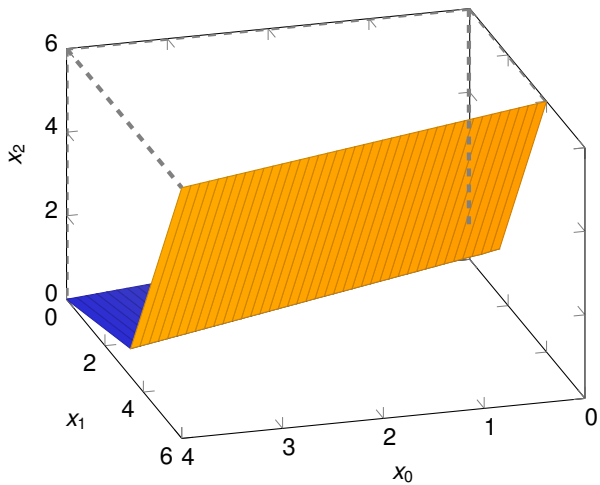


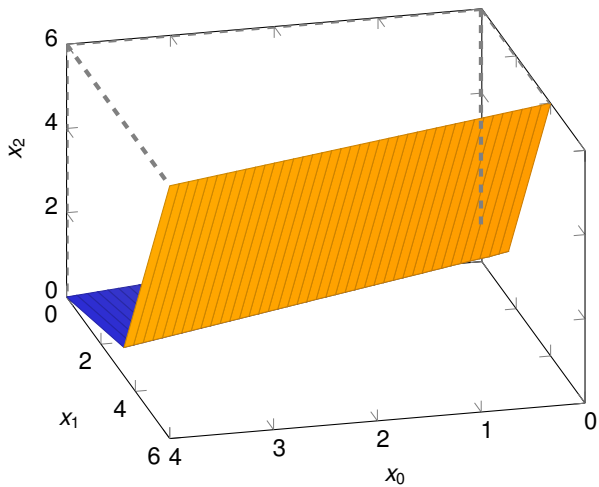


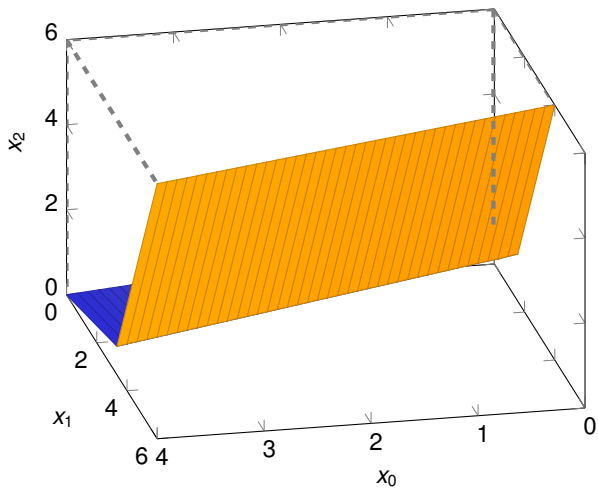


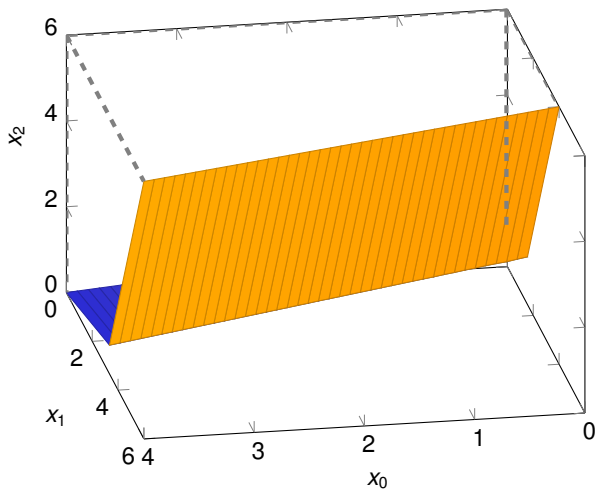














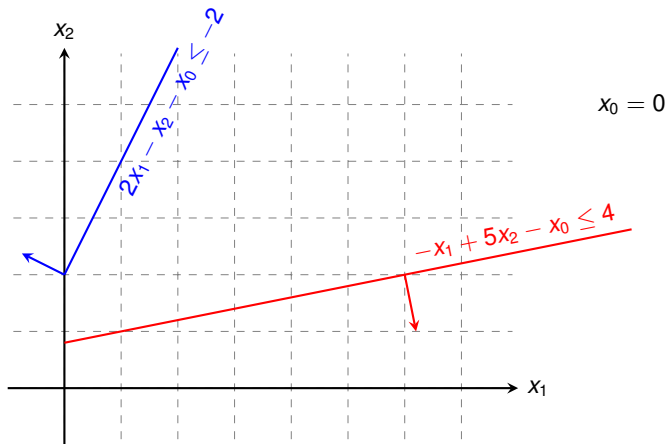
- Let us now modify the original linear program so that it is not feasible

- Let us now modify the original linear program so that it is **not feasible**
- ⇒ Hence the auxiliary linear program has only a solution for a sufficiently large  $x_0 > 0$ !

## Geometric Illustration

maximise  
subject to

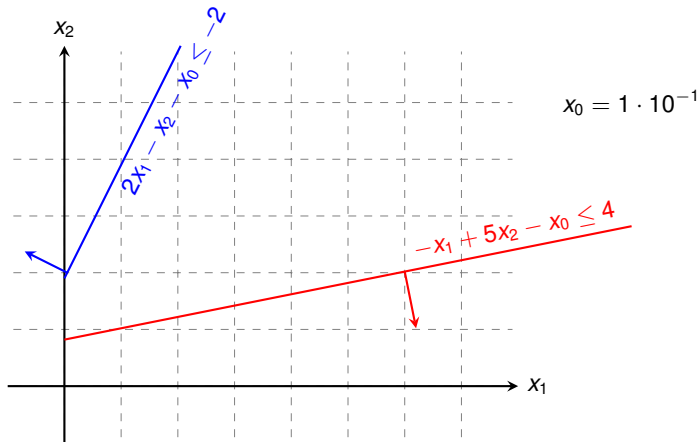
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

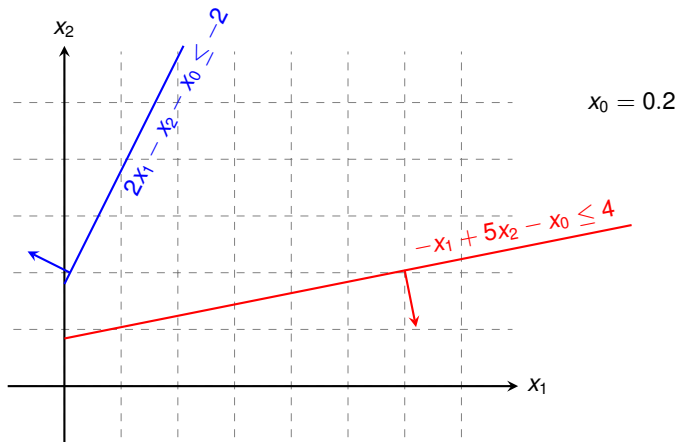
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
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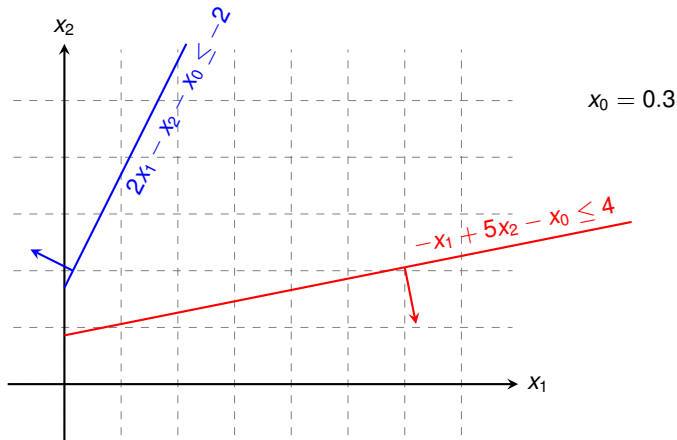
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
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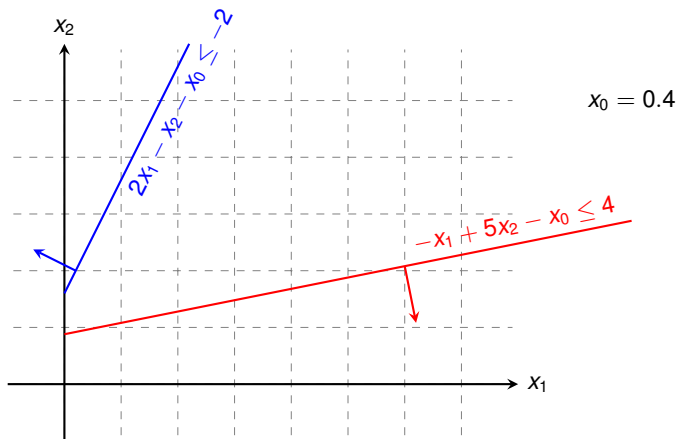
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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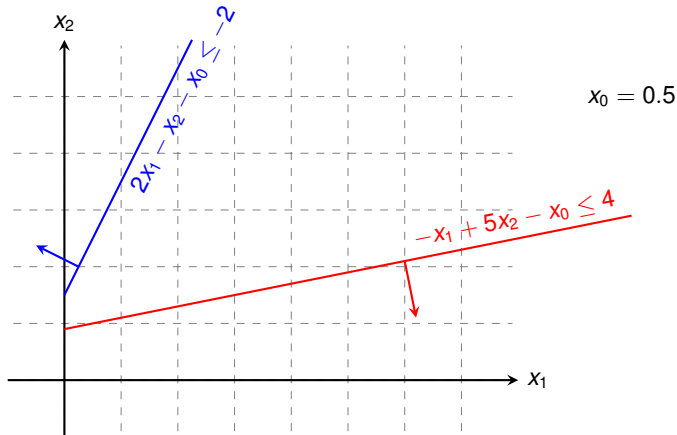
$$\begin{array}{rccccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$

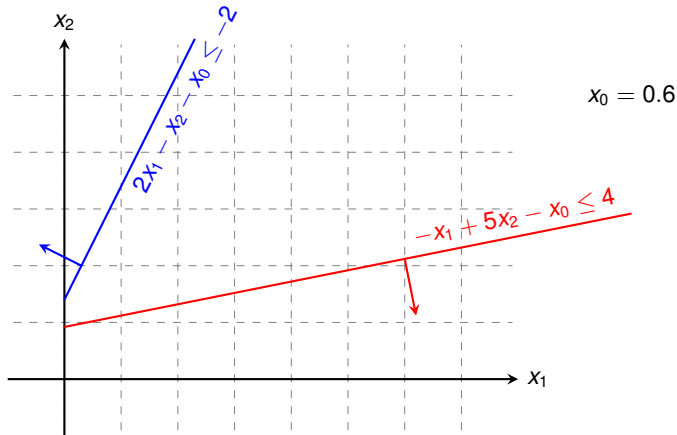




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maximise  
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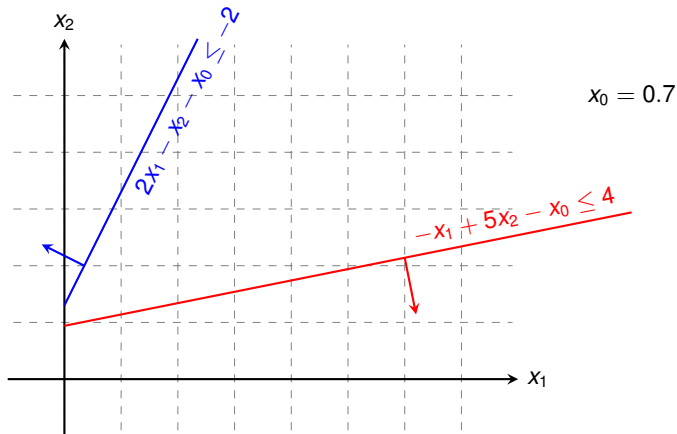
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
subject to

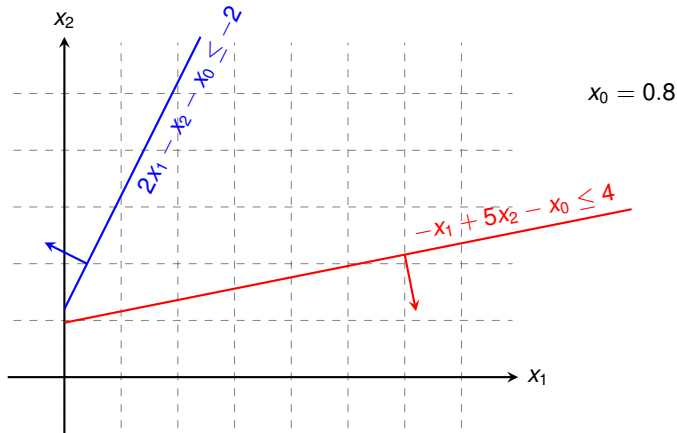
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
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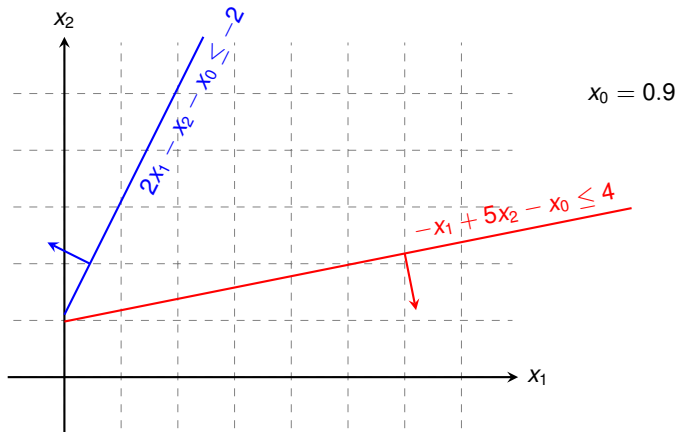
$$\begin{array}{rccccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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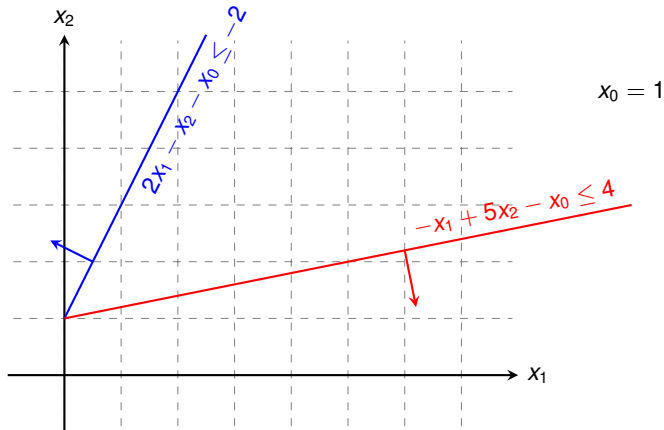
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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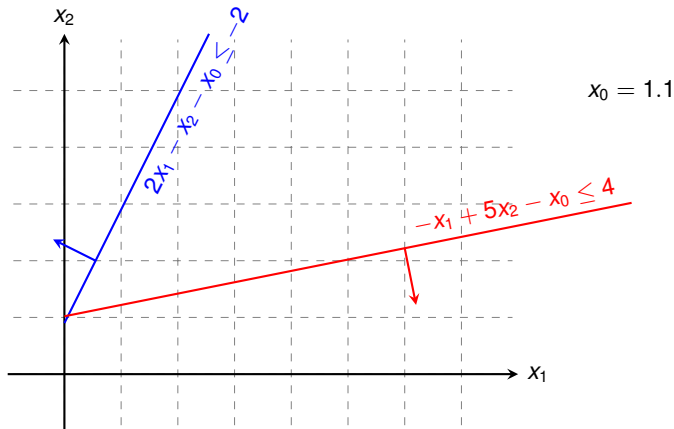
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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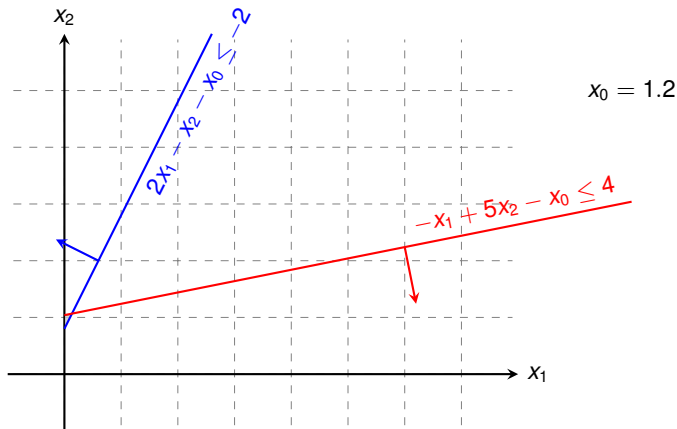
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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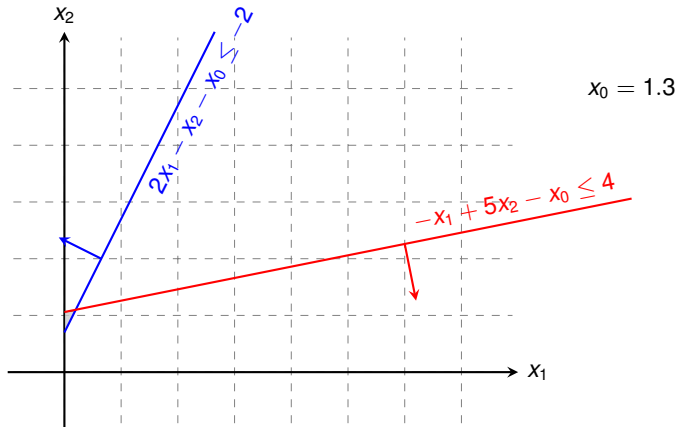
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
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$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$

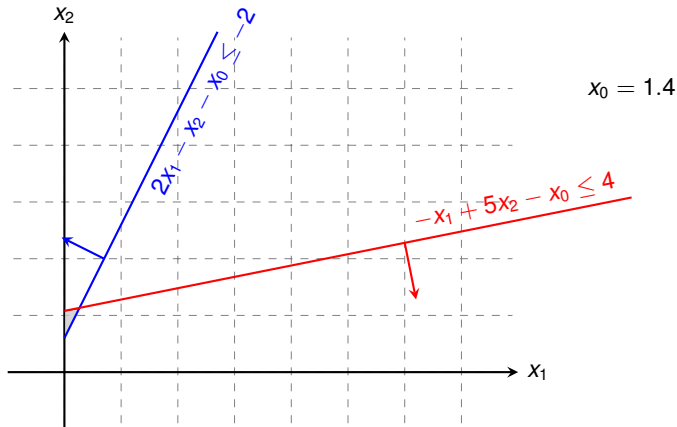




## Geometric Illustration

maximise  
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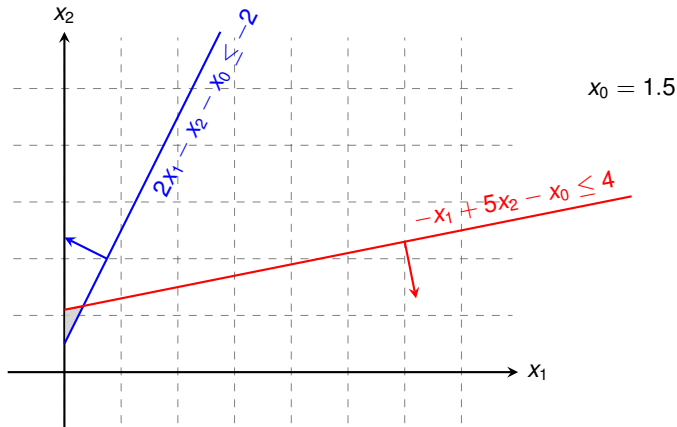
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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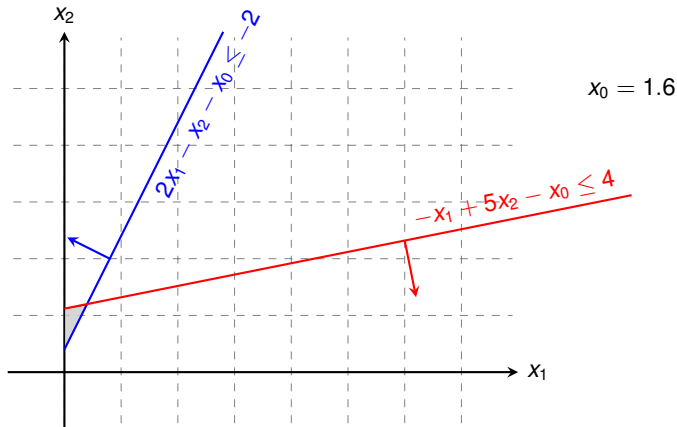
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maximise  
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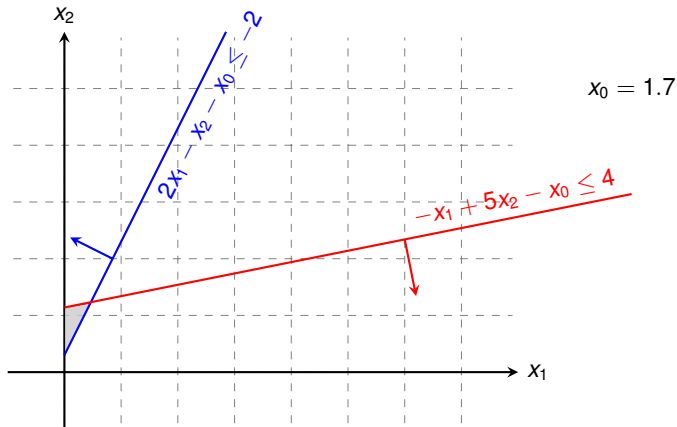
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
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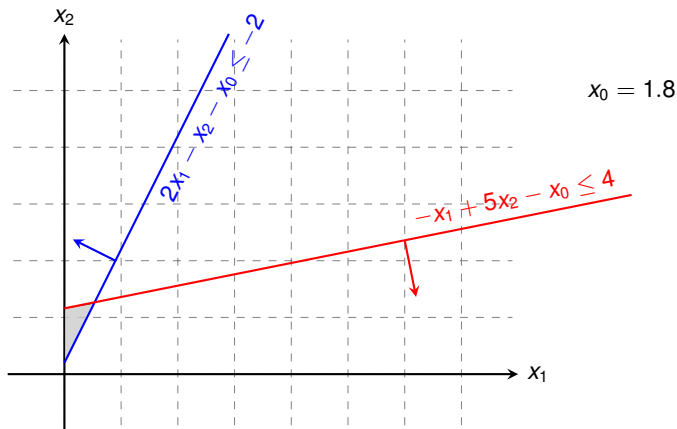
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
subject to

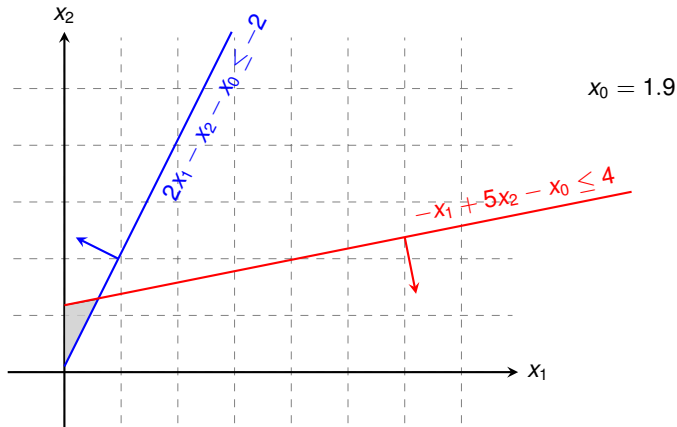
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
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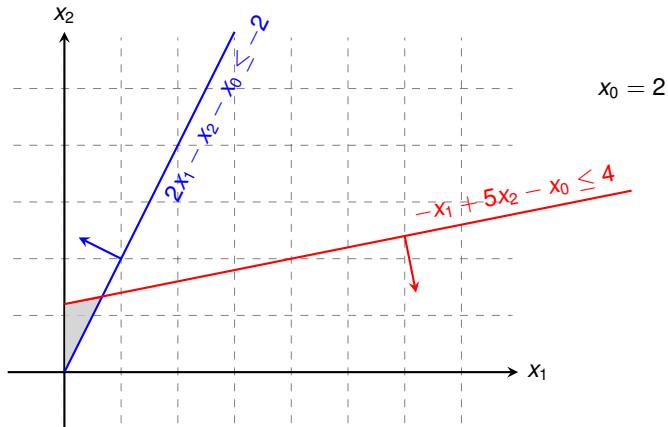
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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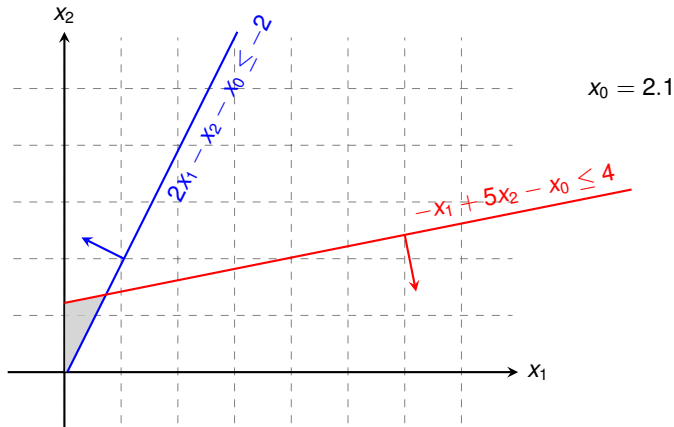
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$

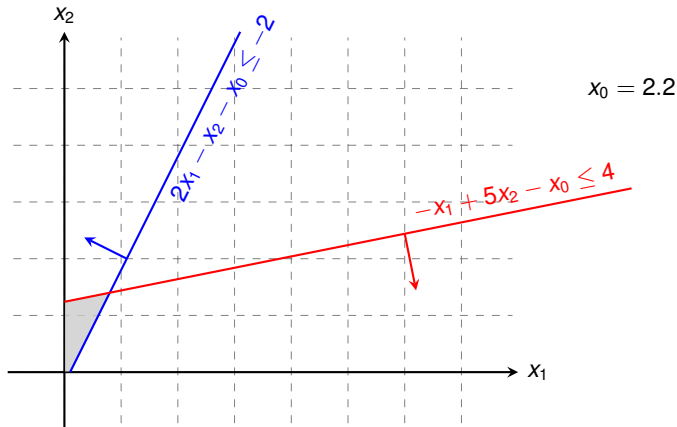




## Geometric Illustration

maximise  
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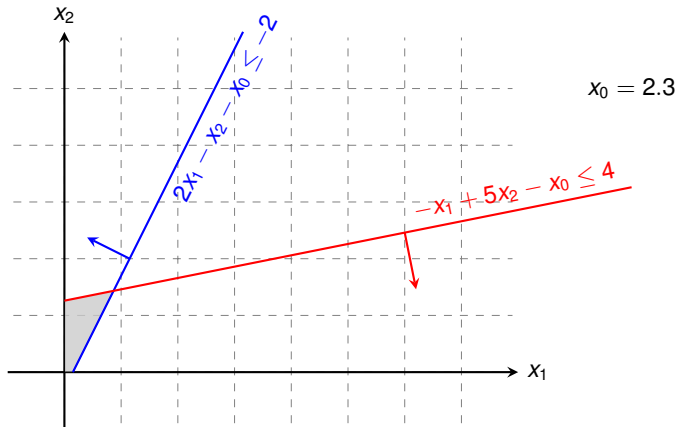
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
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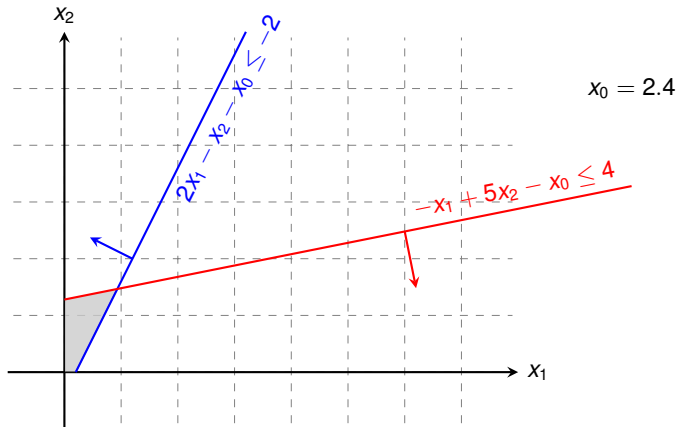
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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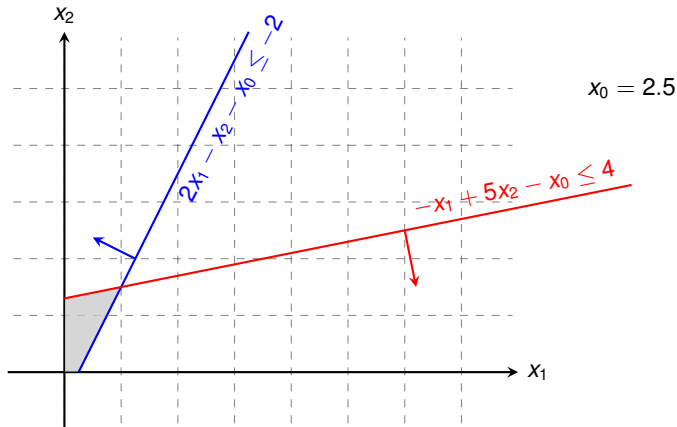
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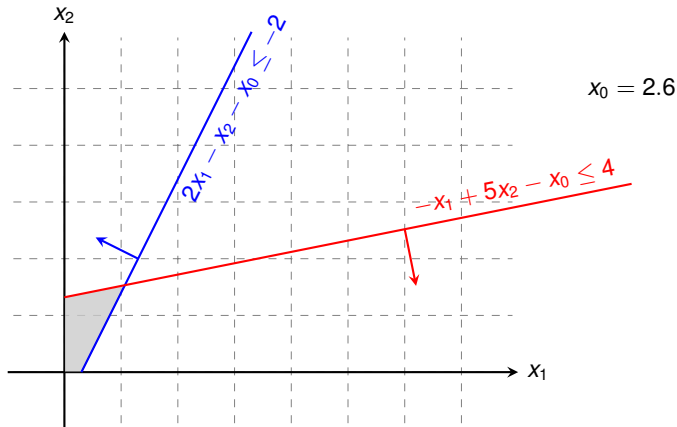
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
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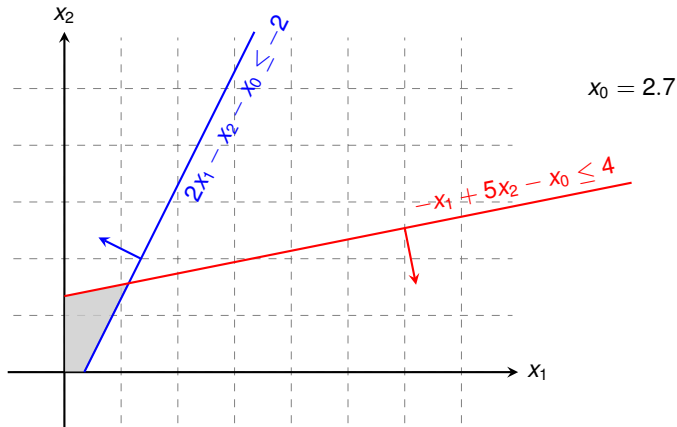
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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maximise  
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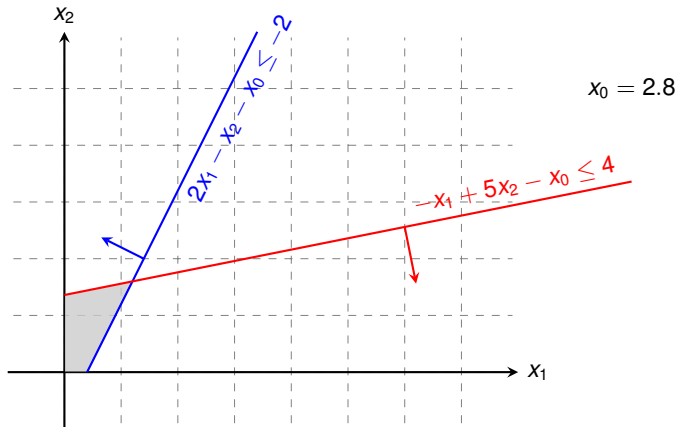
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maximise  
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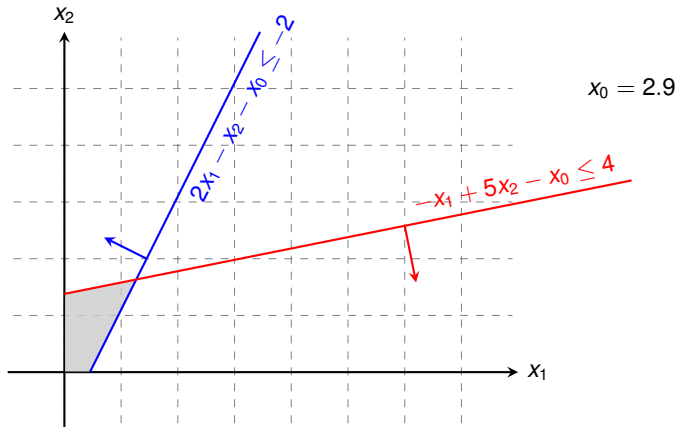
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$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$

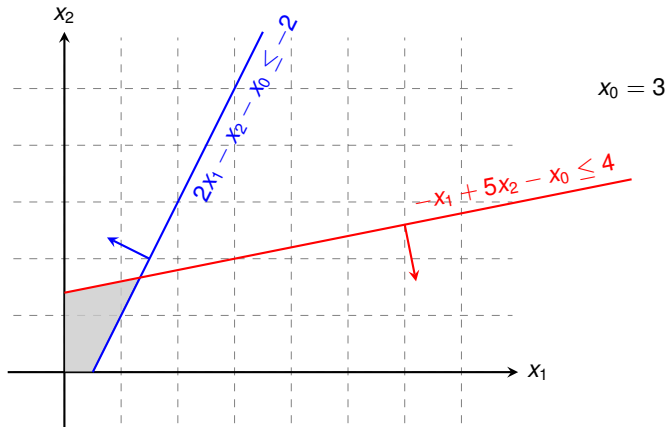




## Geometric Illustration

maximise  
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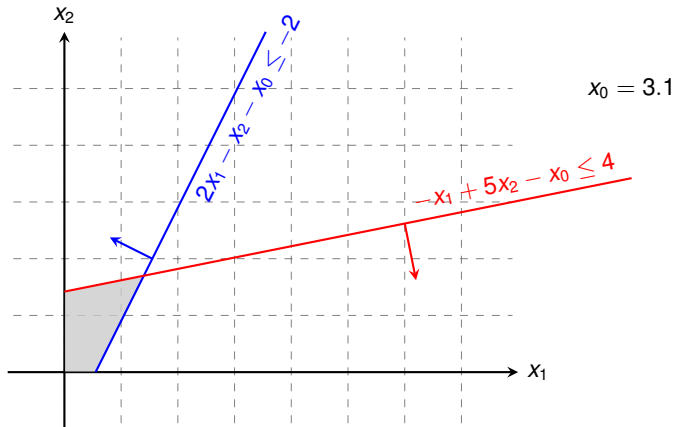
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



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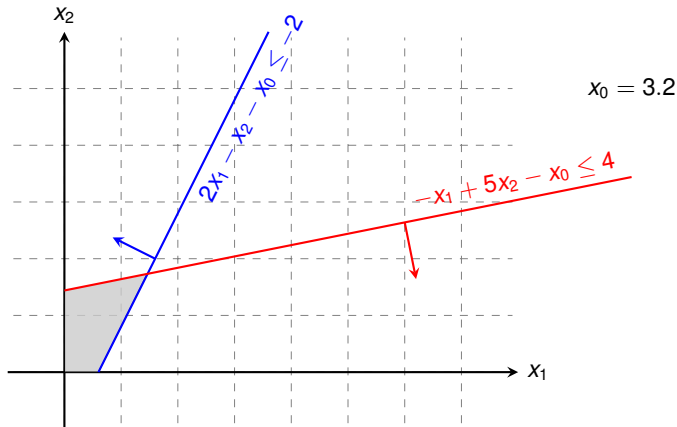
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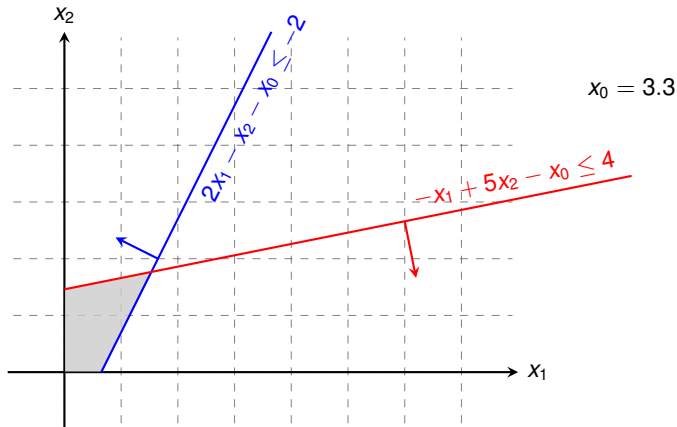
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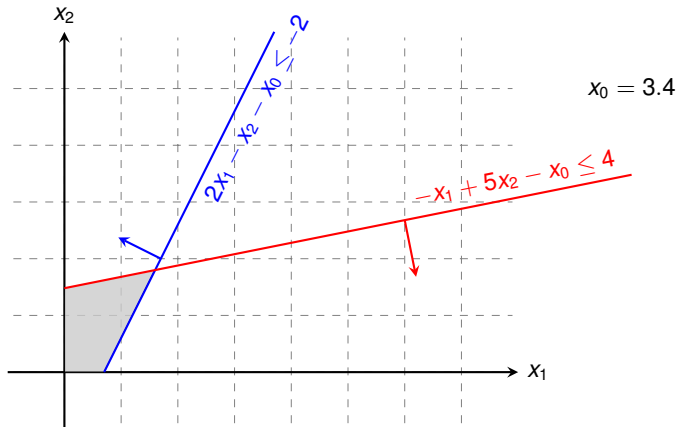
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## Geometric Illustration

maximise  
subject to

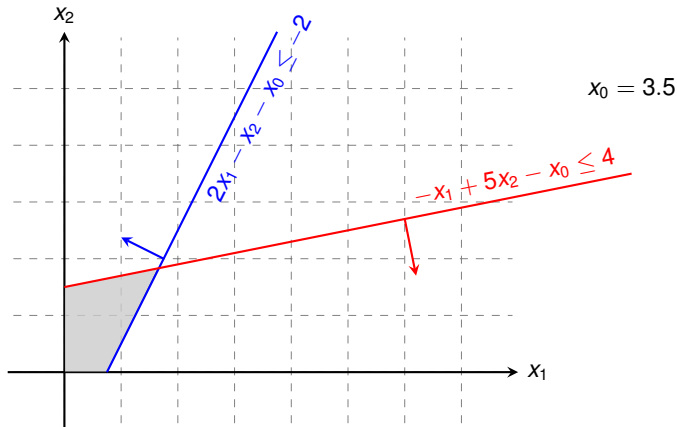
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ & & x_0, x_1, x_2 & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

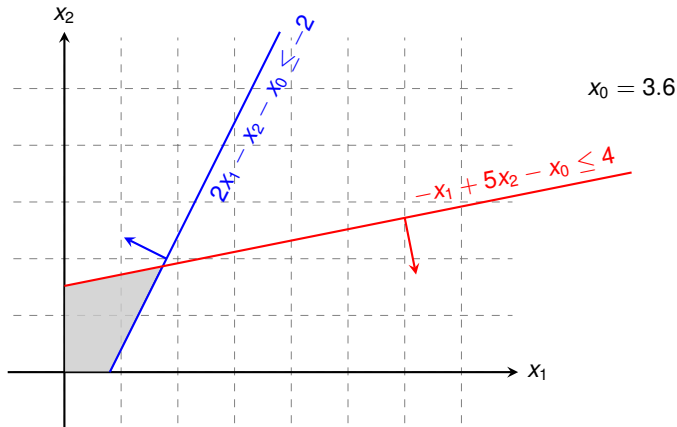
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

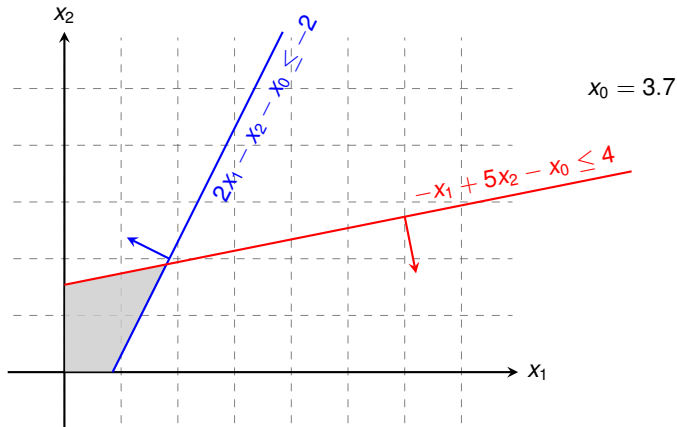
$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

$$\begin{array}{rcccccc} 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$

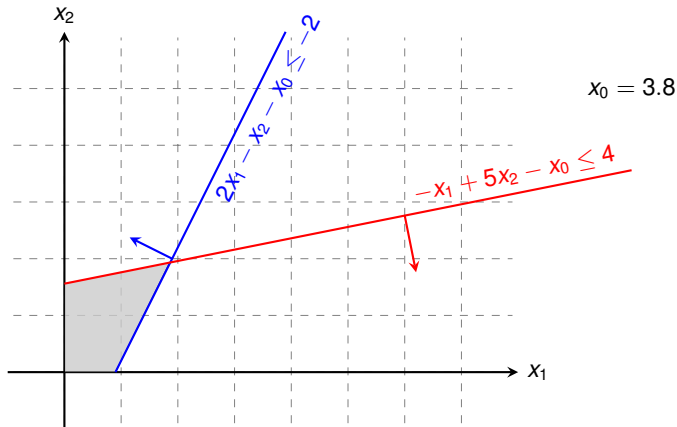




## Geometric Illustration

maximise  
subject to

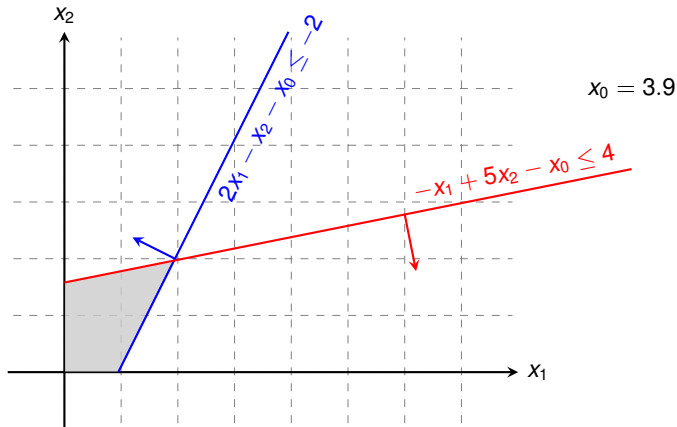
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



## Geometric Illustration

maximise  
subject to

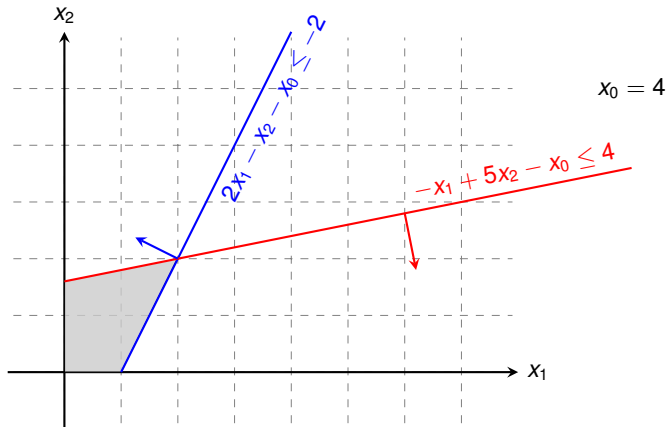
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



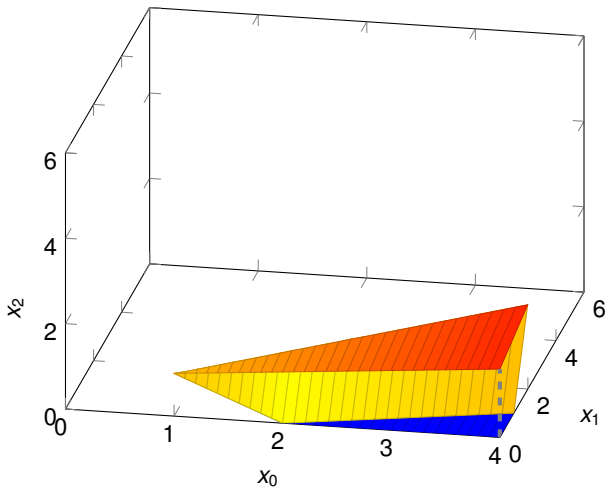
## Geometric Illustration

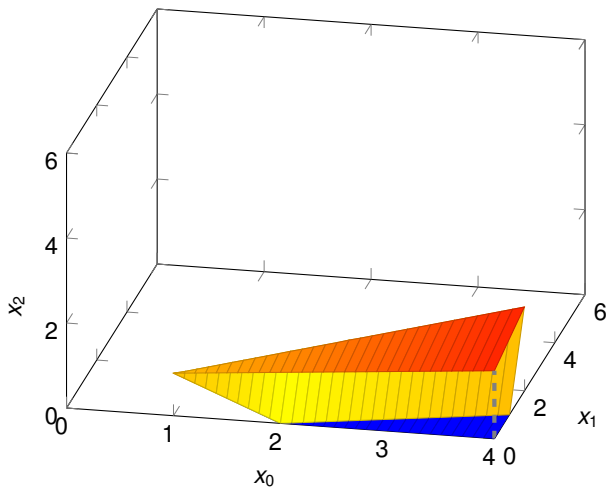
maximise  
subject to

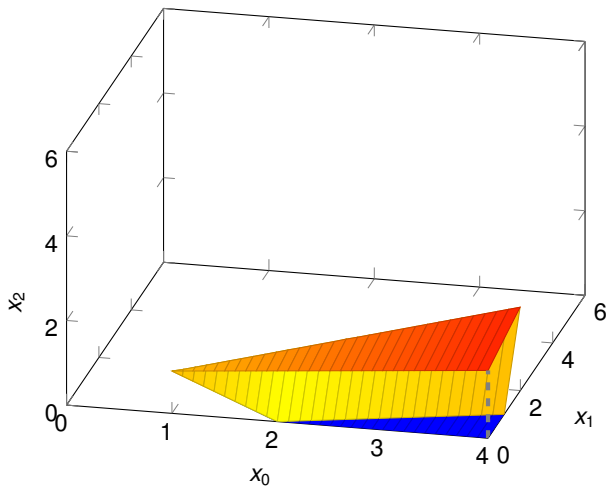
$$\begin{array}{rcccccc} -x_0 & & & & & & \\ 2x_1 & - & x_2 & - & x_0 & \leq & -2 \\ -x_1 & + & 5x_2 & - & x_0 & \leq & 4 \\ x_0, x_1, x_2 & & & & & \geq & 0 \end{array}$$



Now the Feasible Region of the Auxiliary LP in 3D

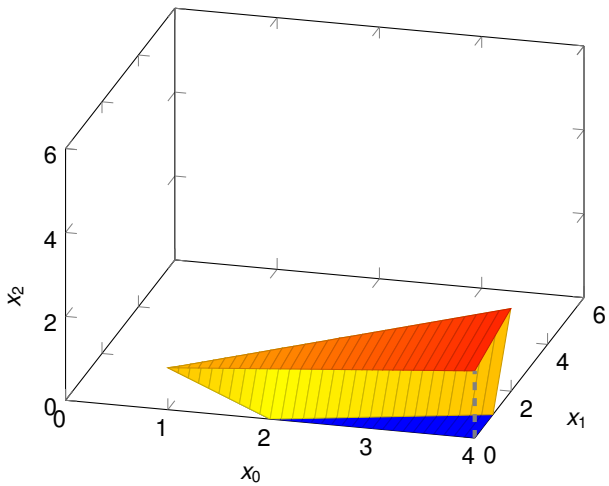


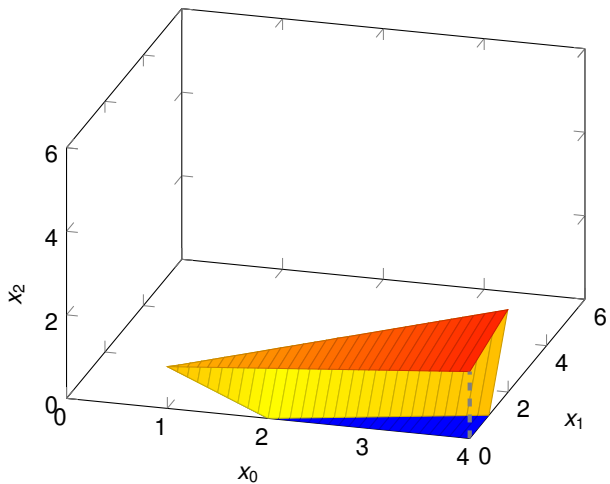


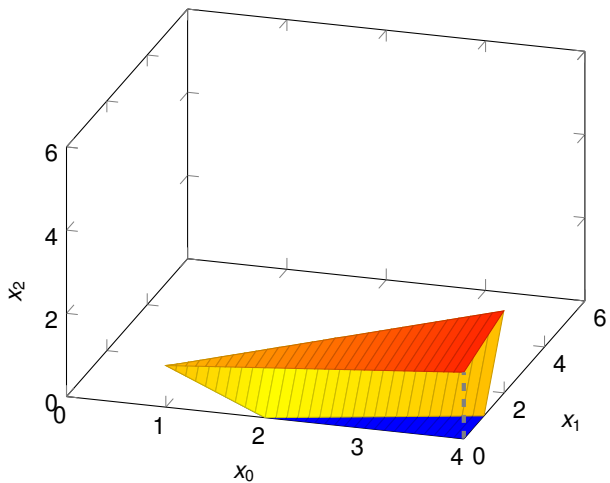


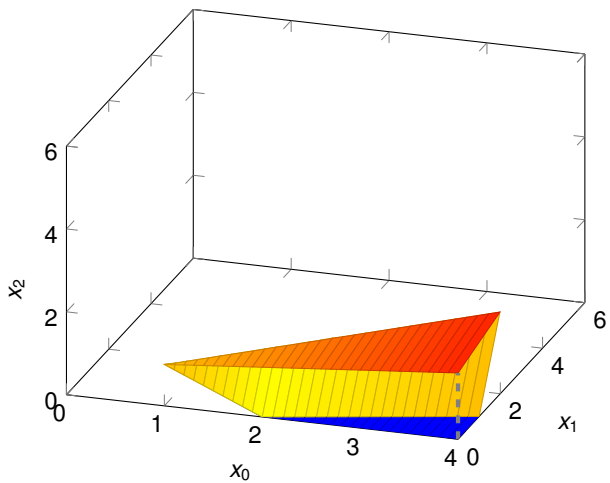


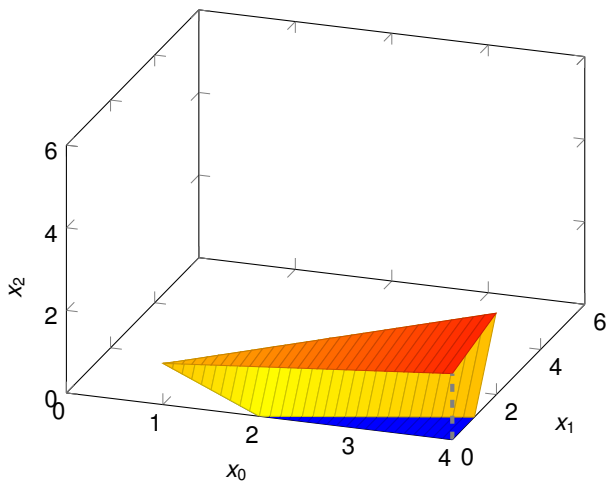


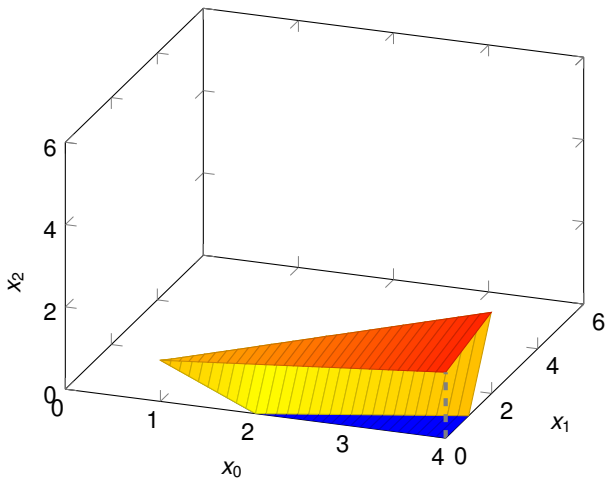


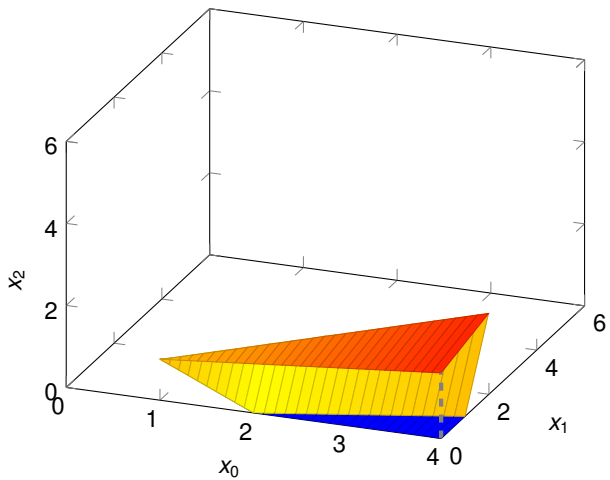


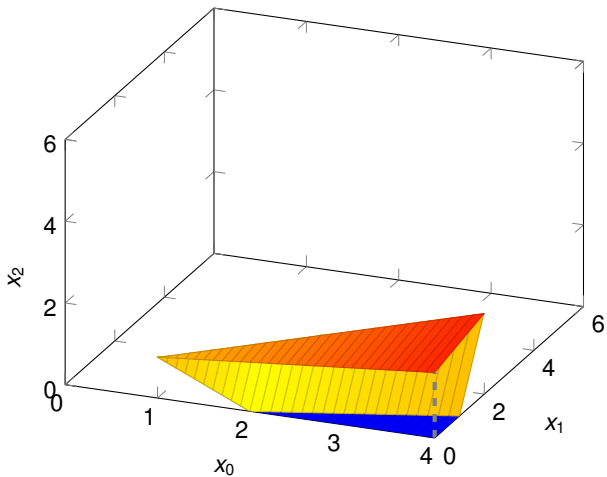




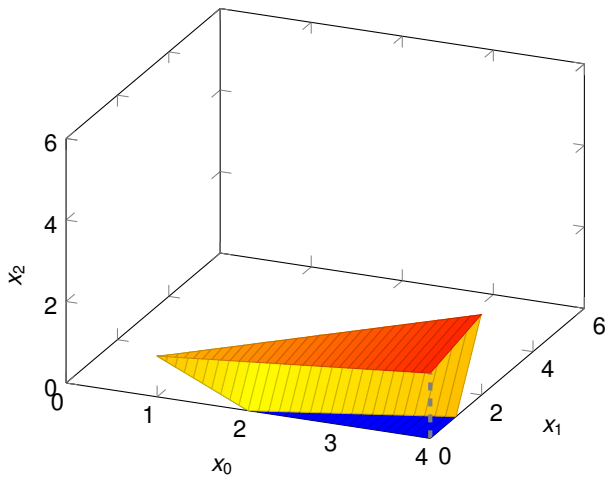


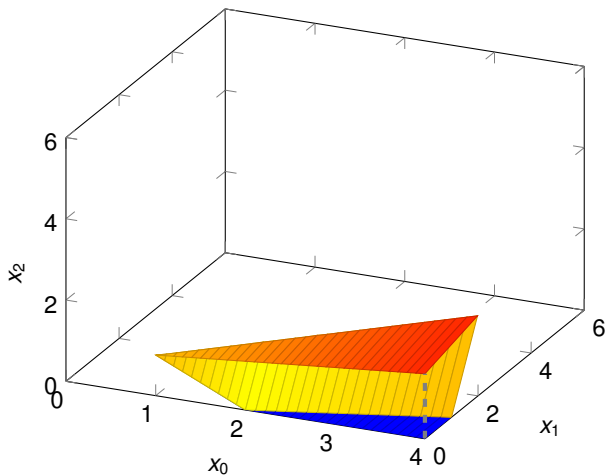


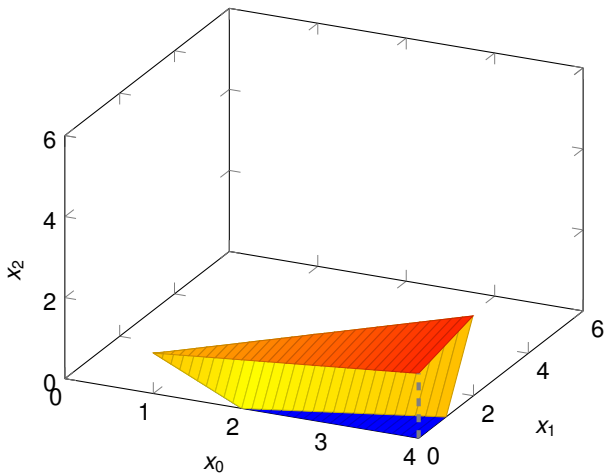


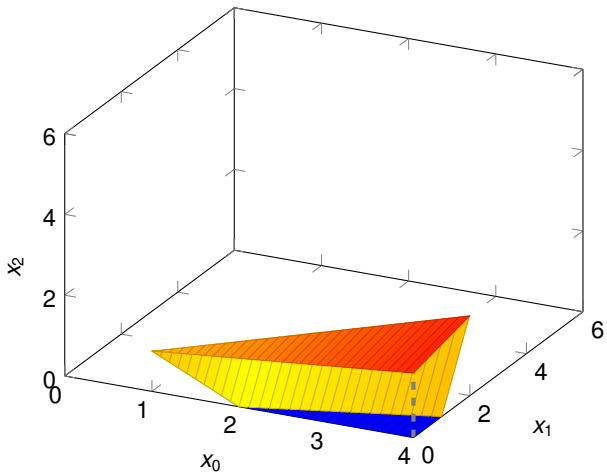


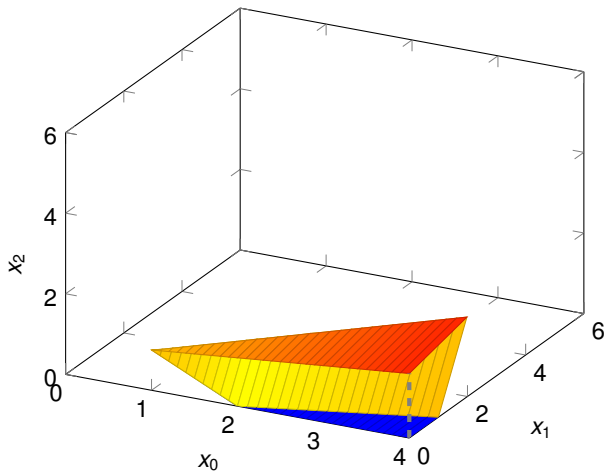


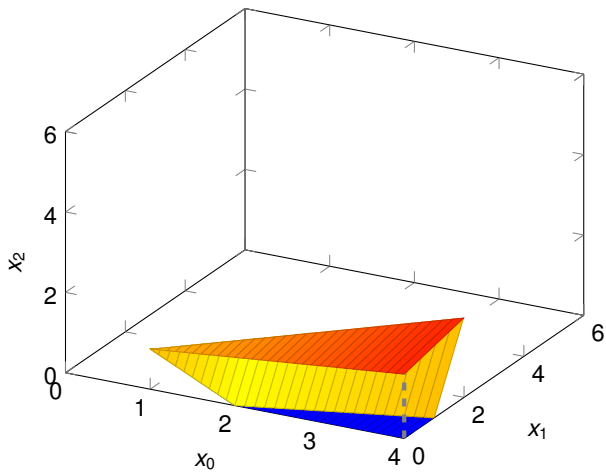


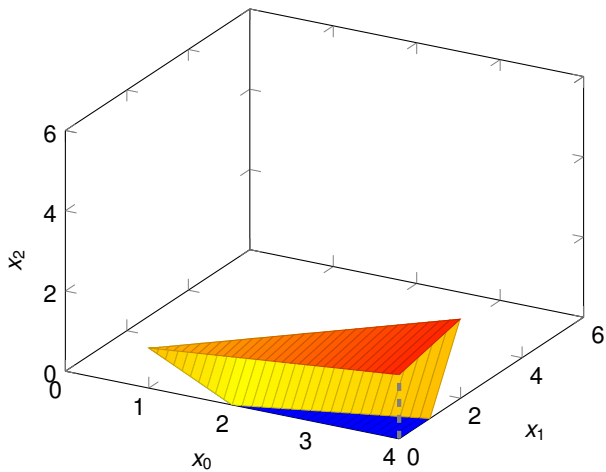


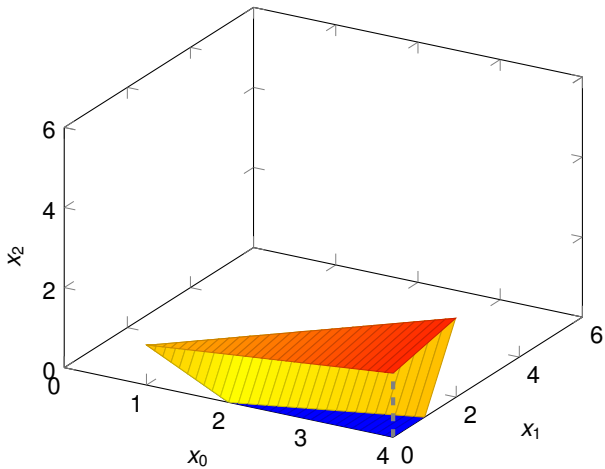




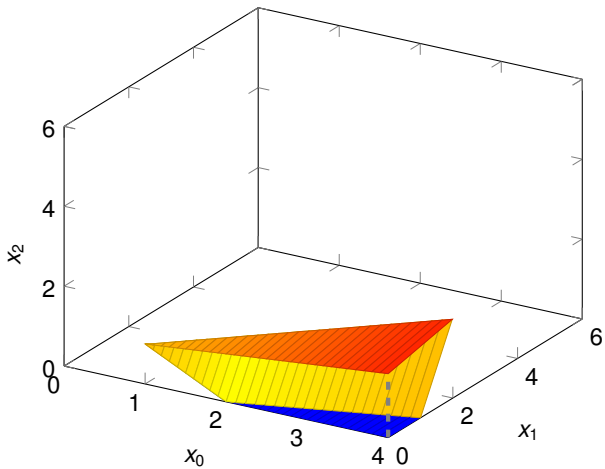


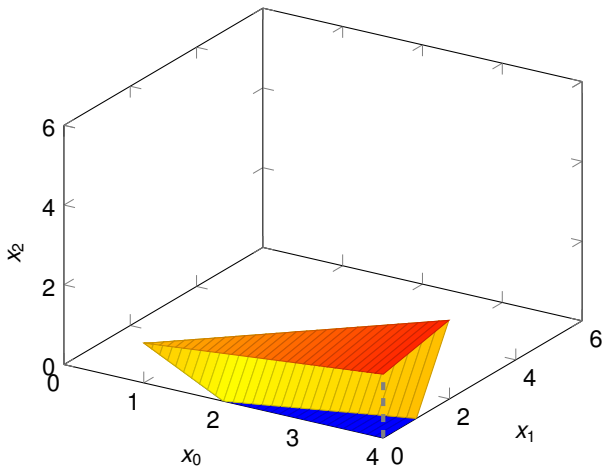


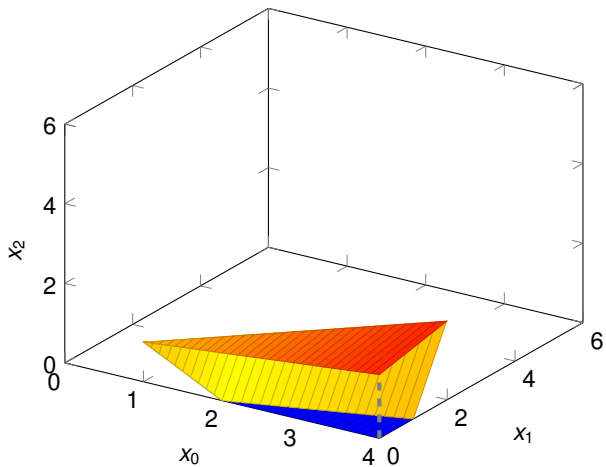


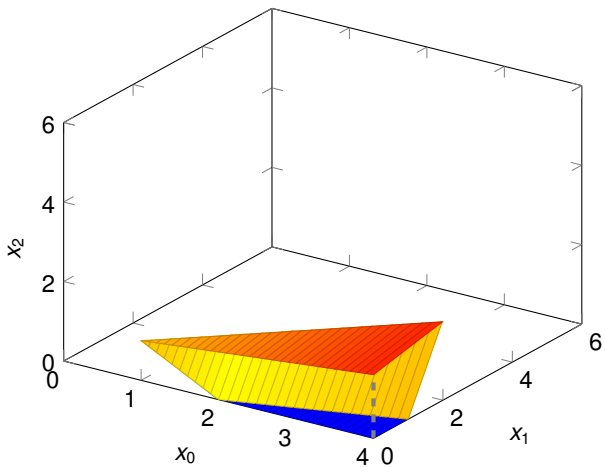


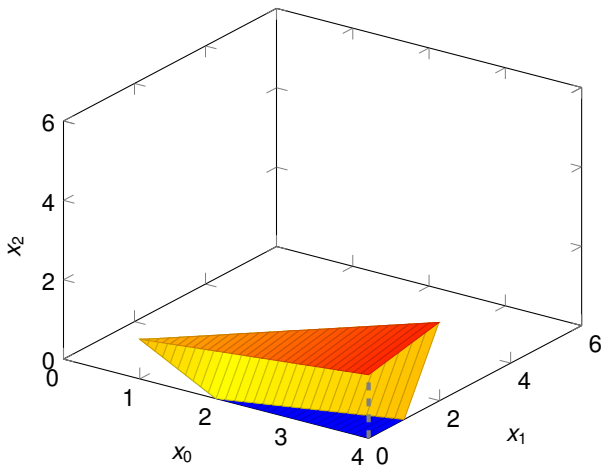


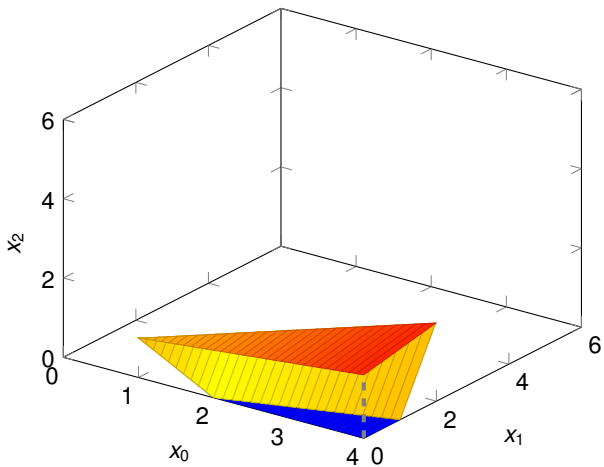


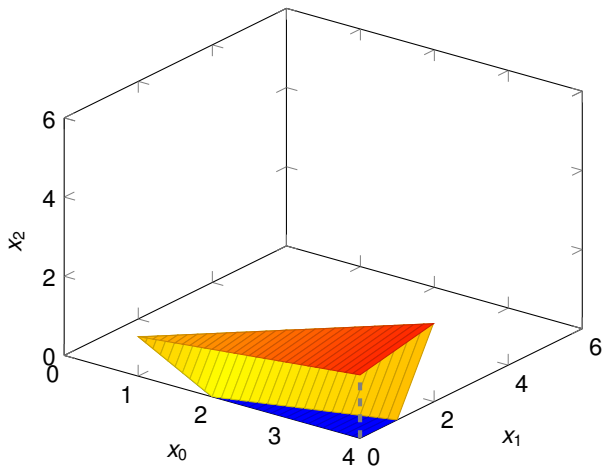


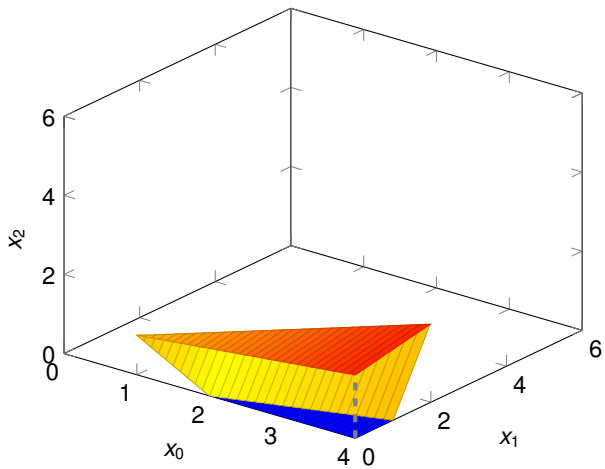




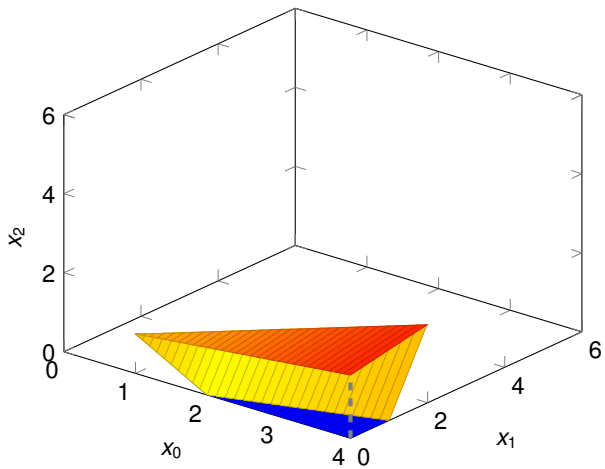


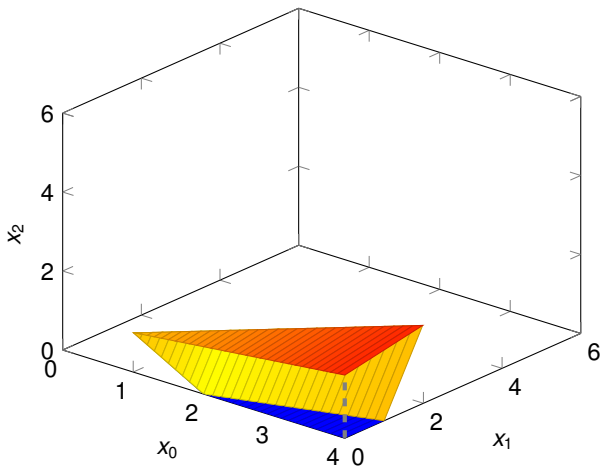


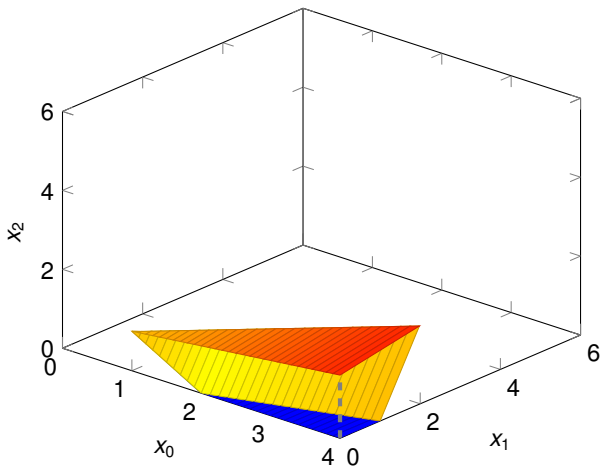


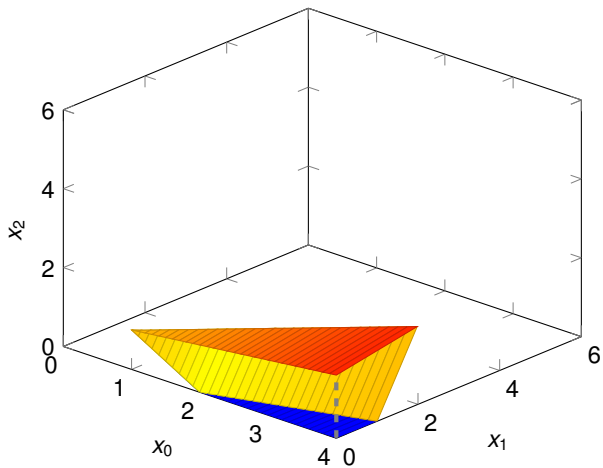


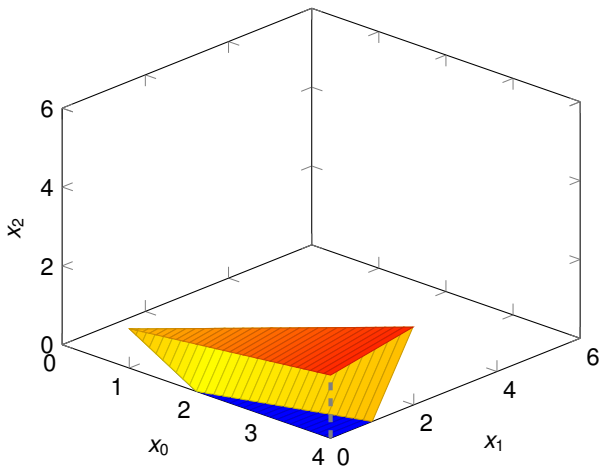


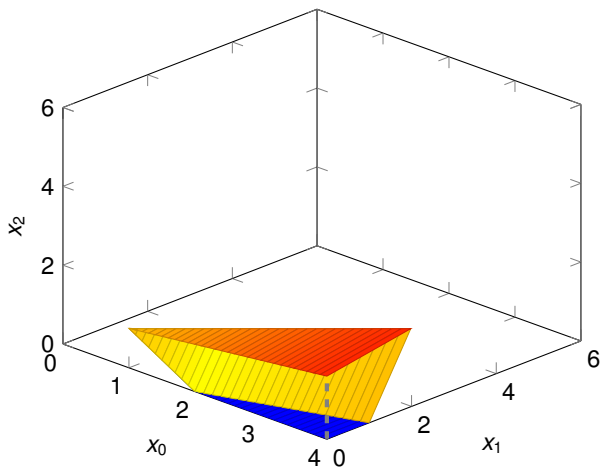


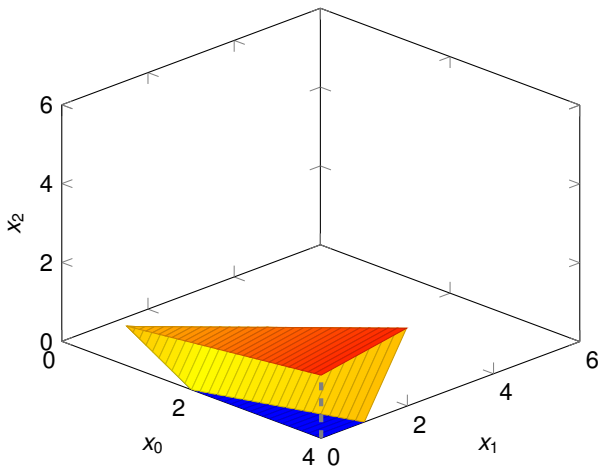


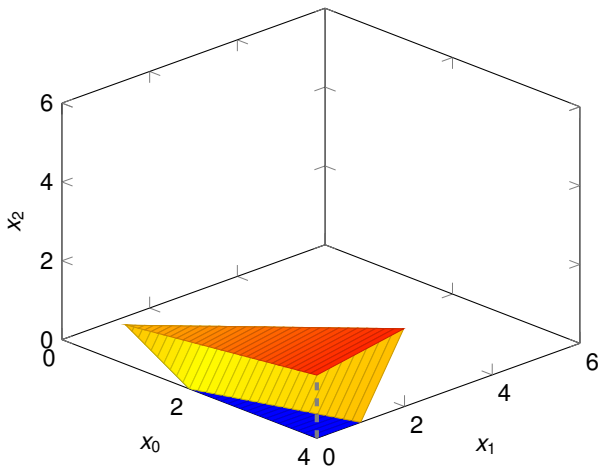




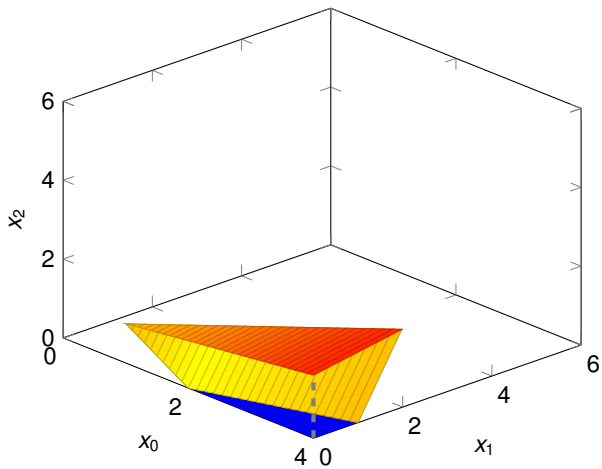


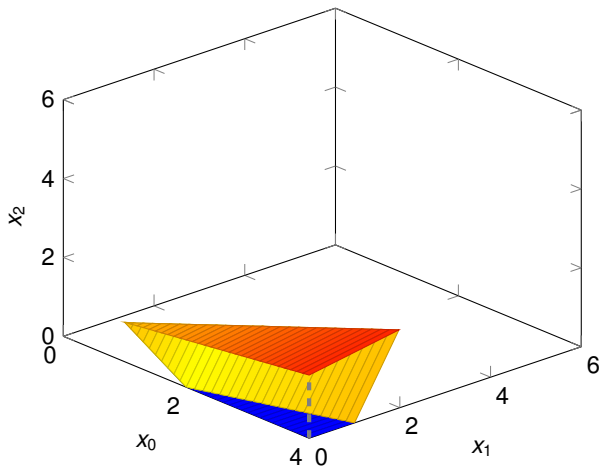


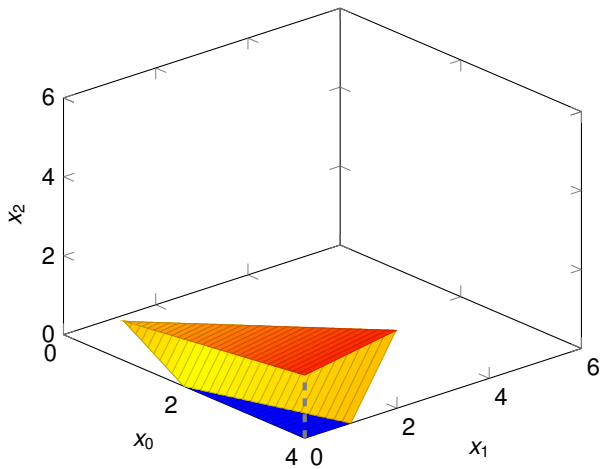


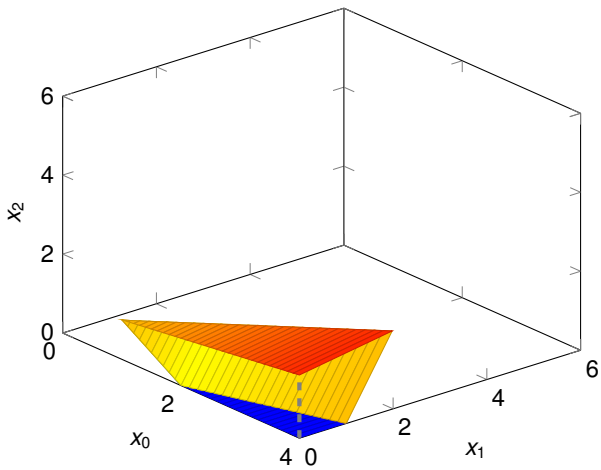


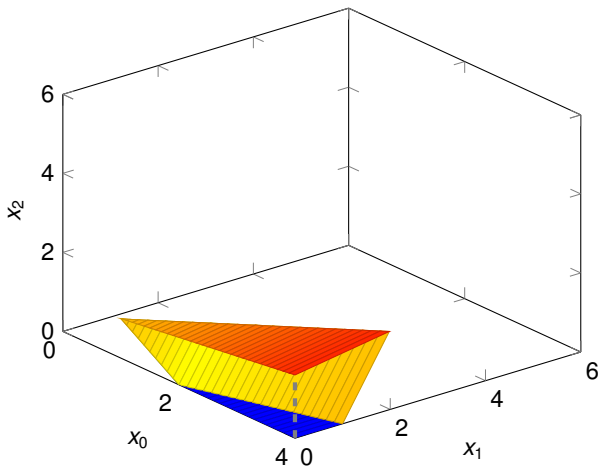


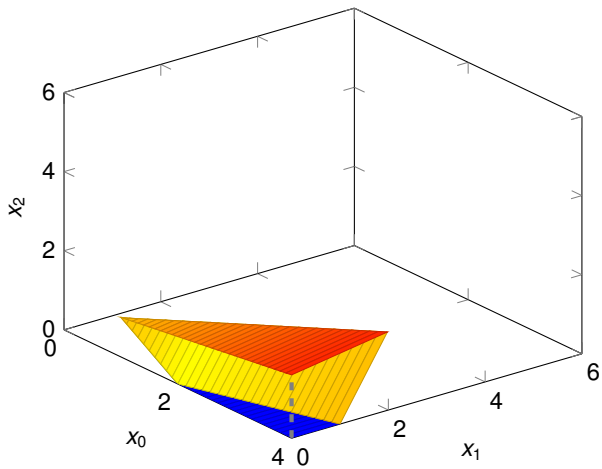


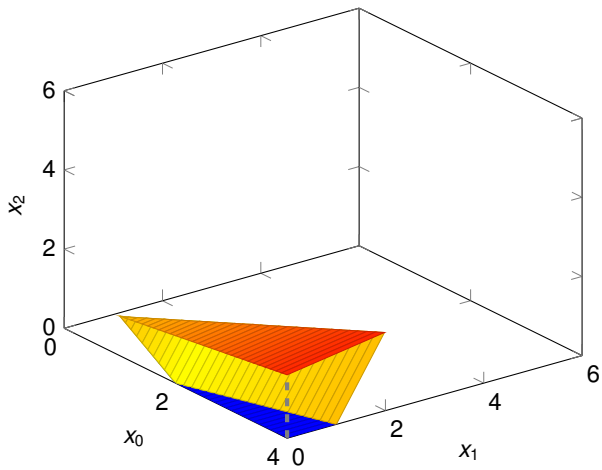


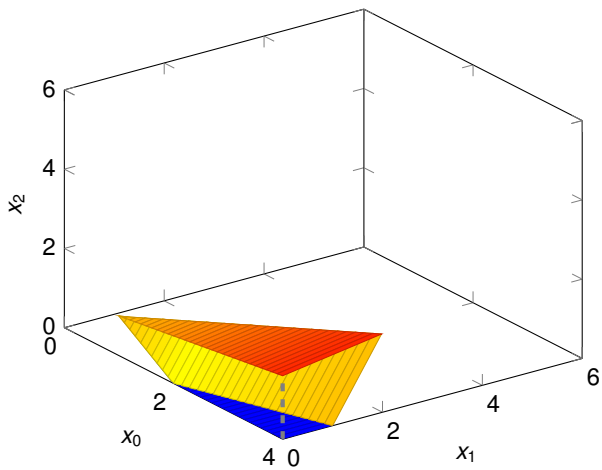




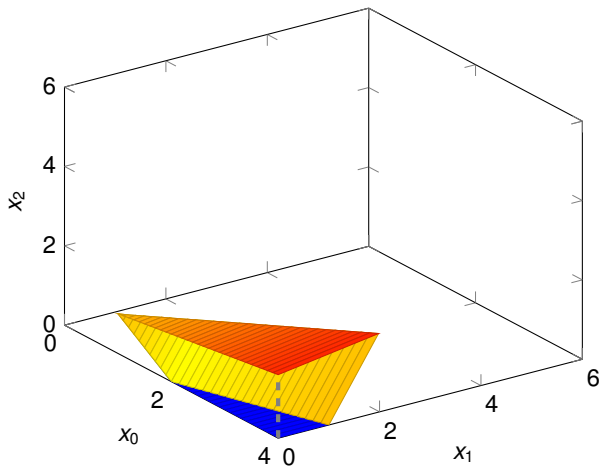


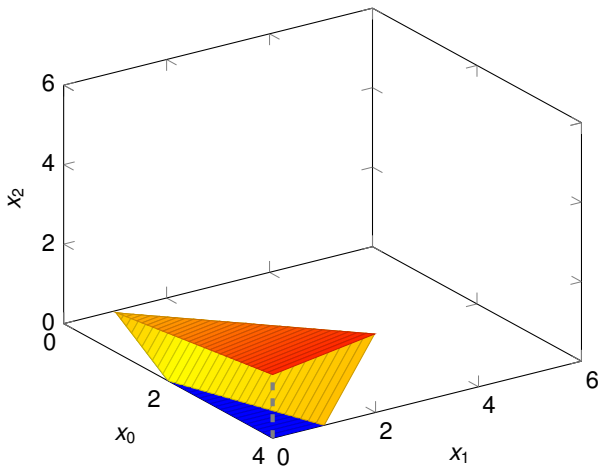


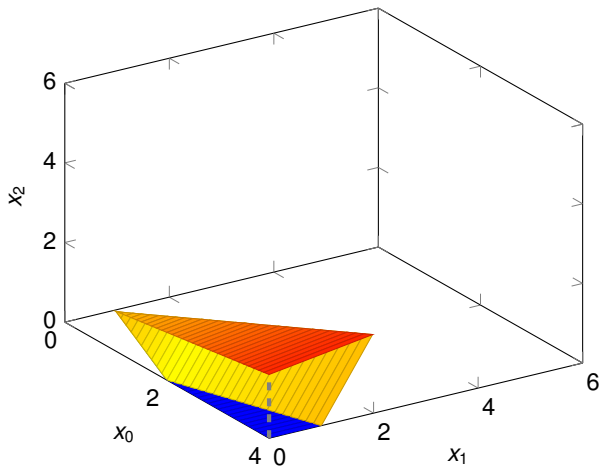


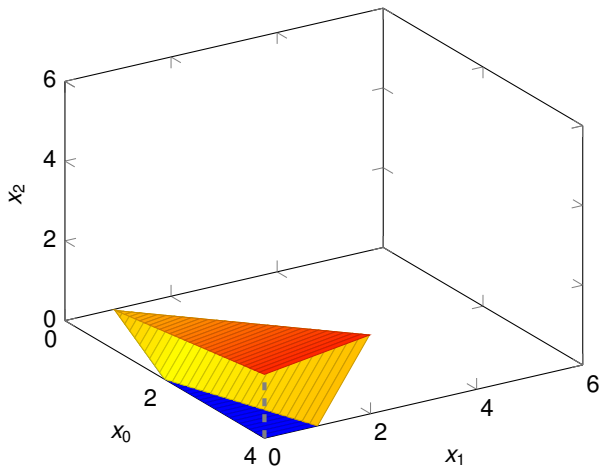


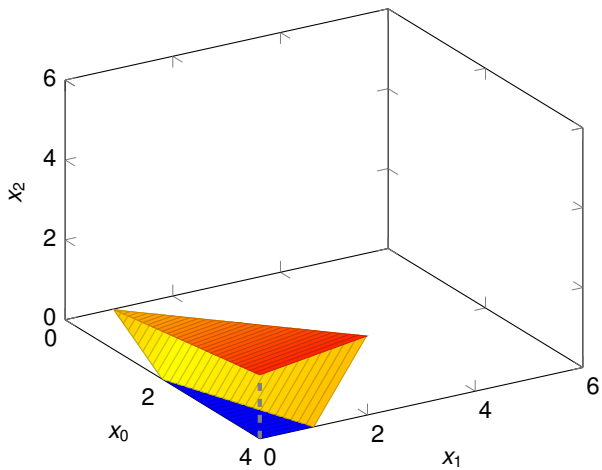


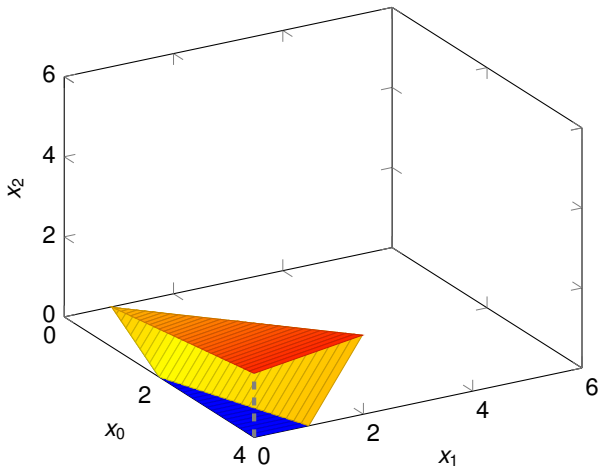


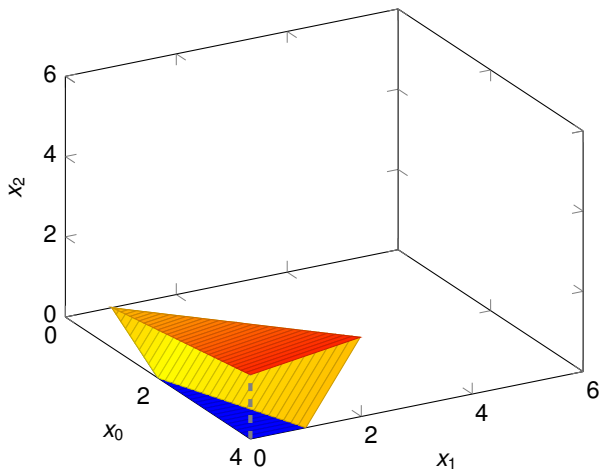


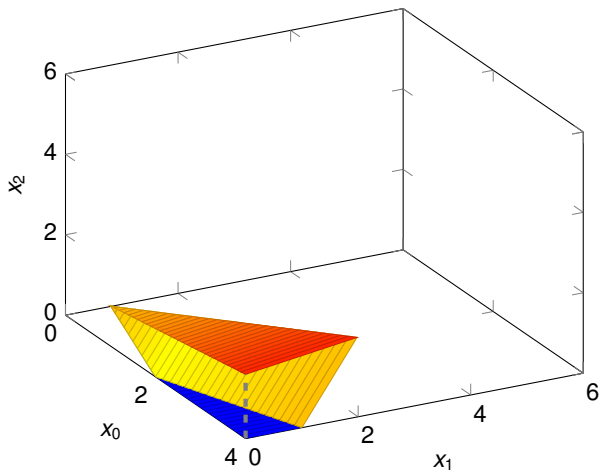




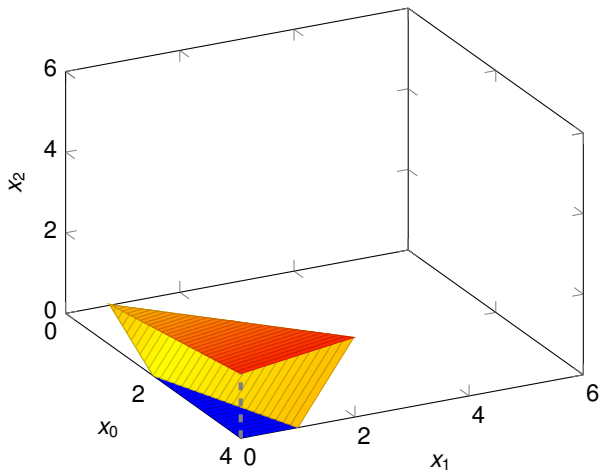


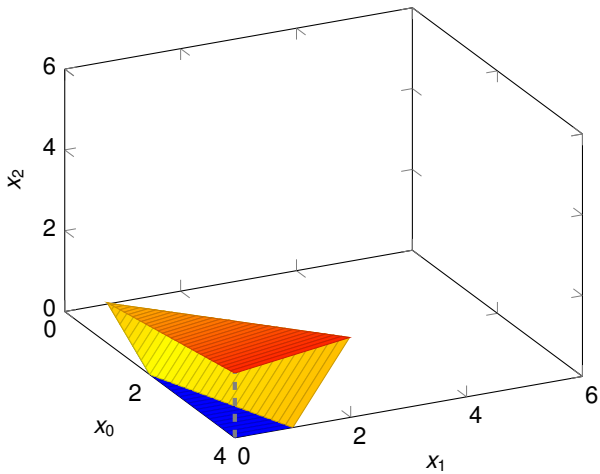


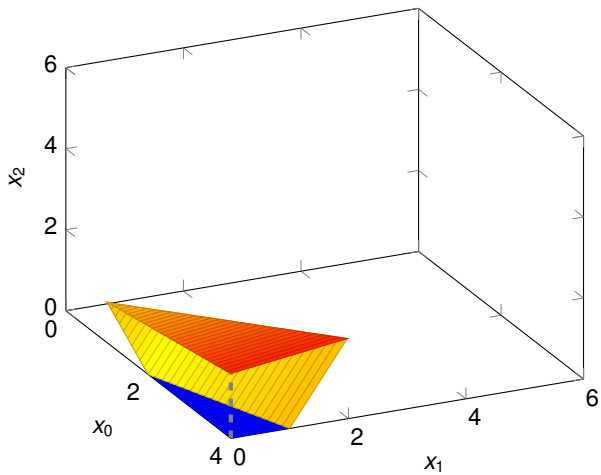


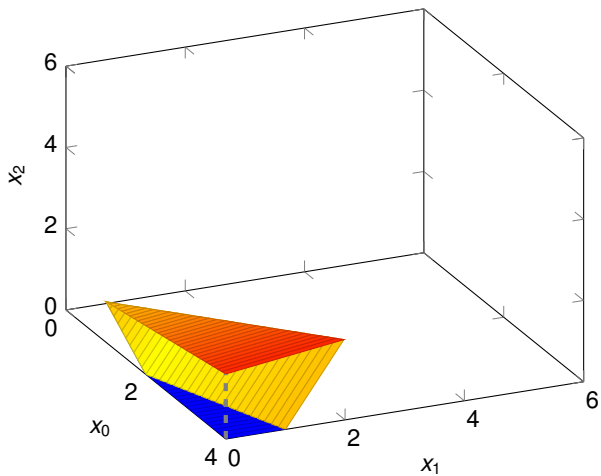


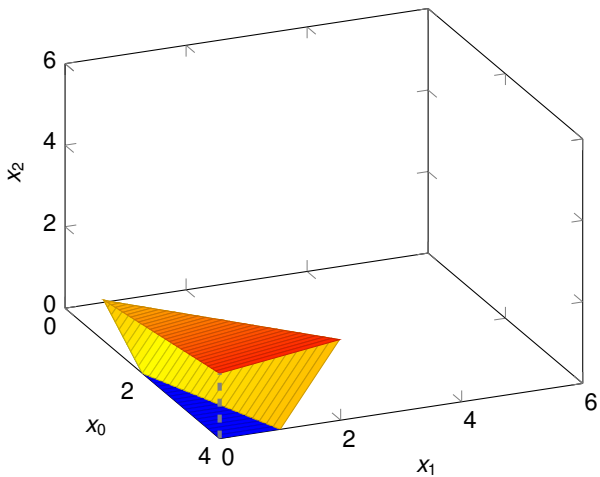


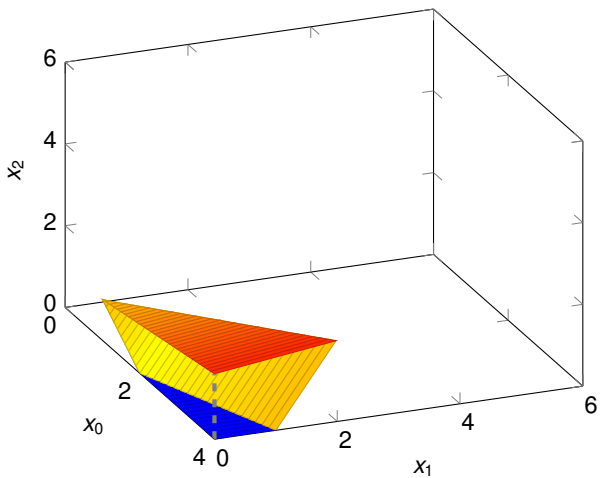


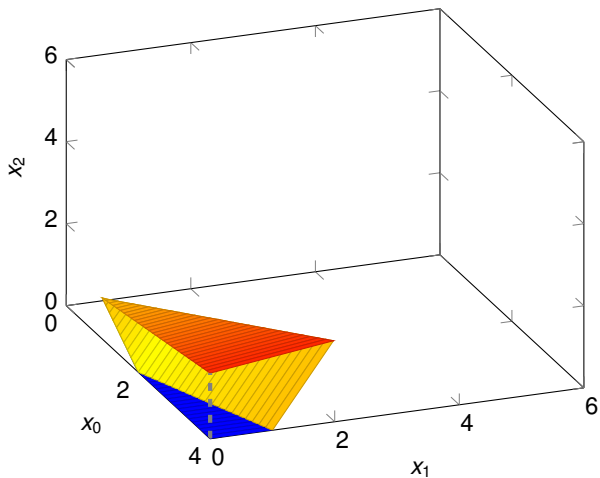


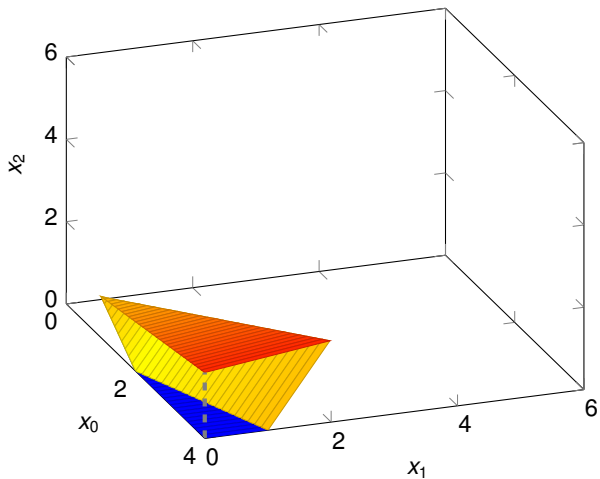




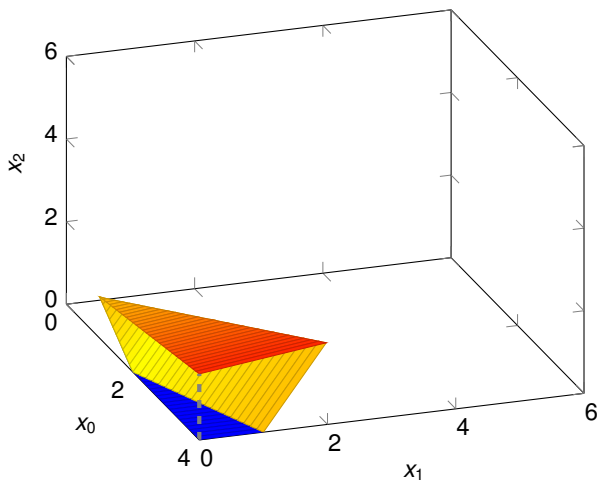


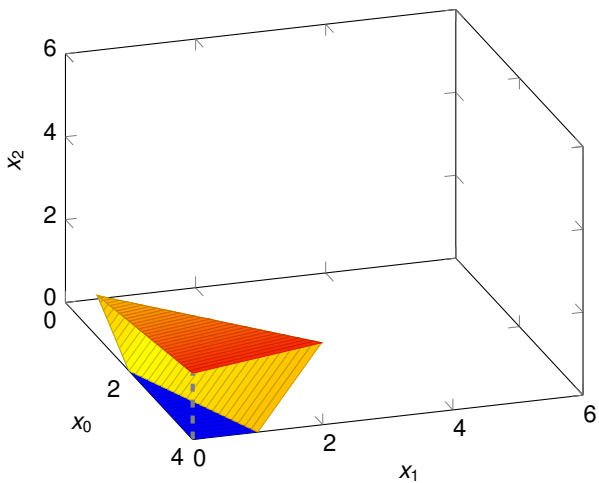


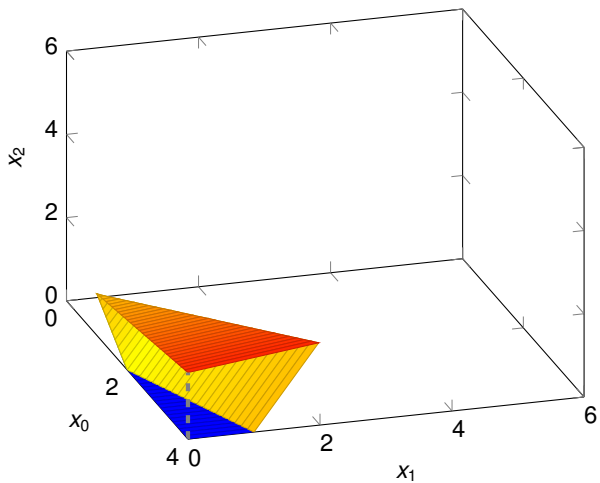


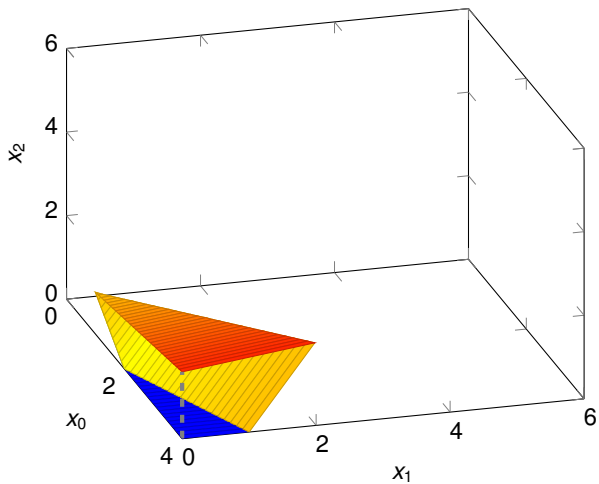


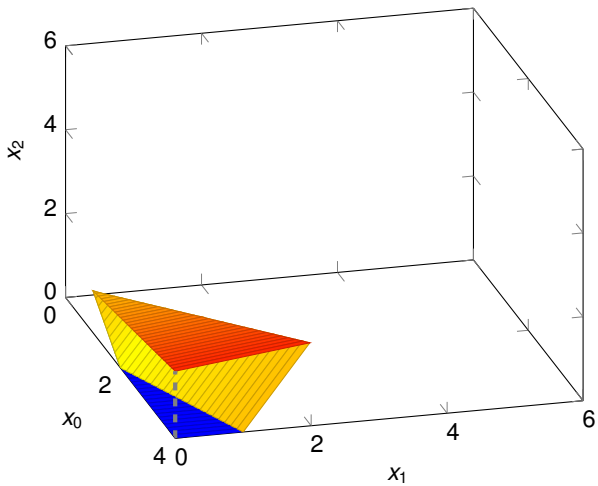


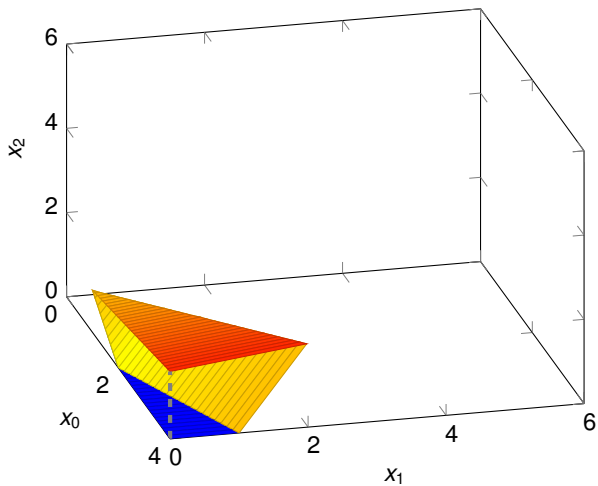


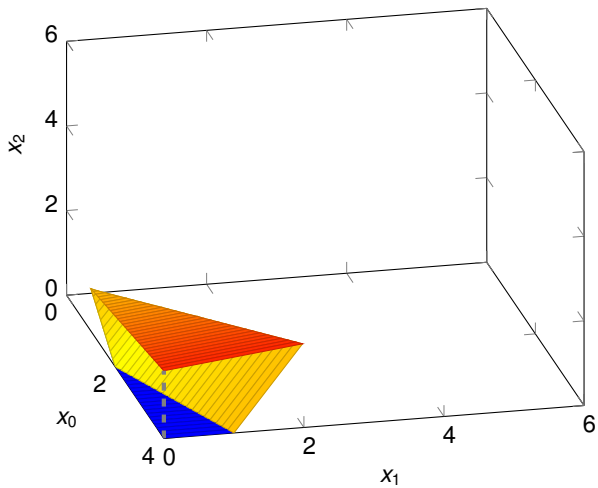


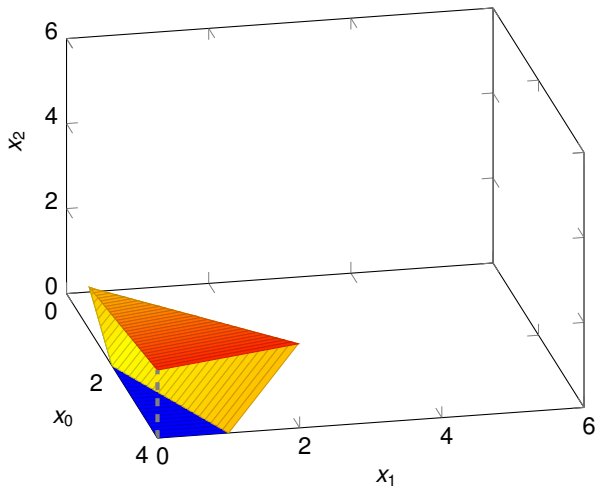




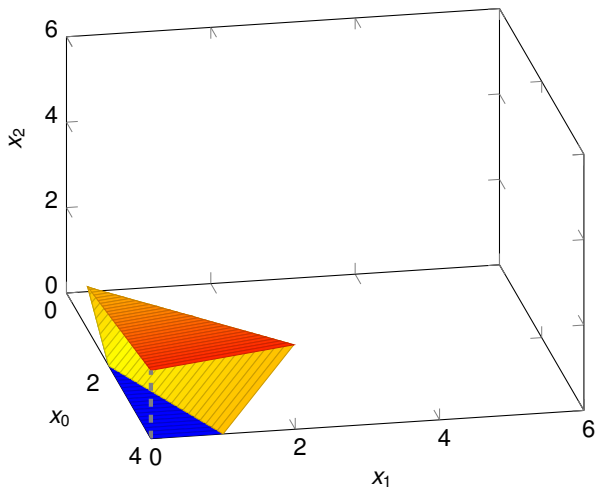


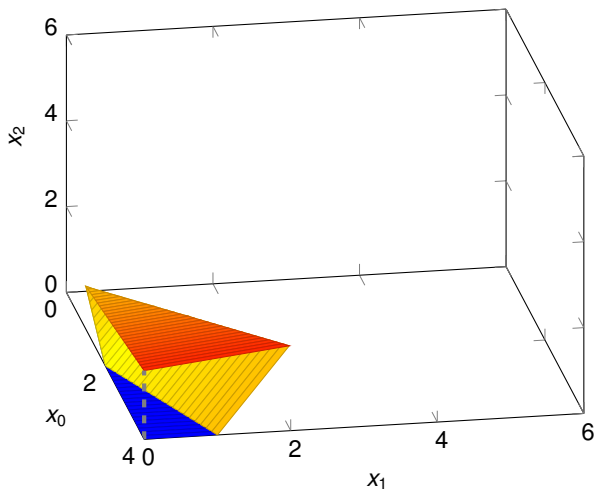


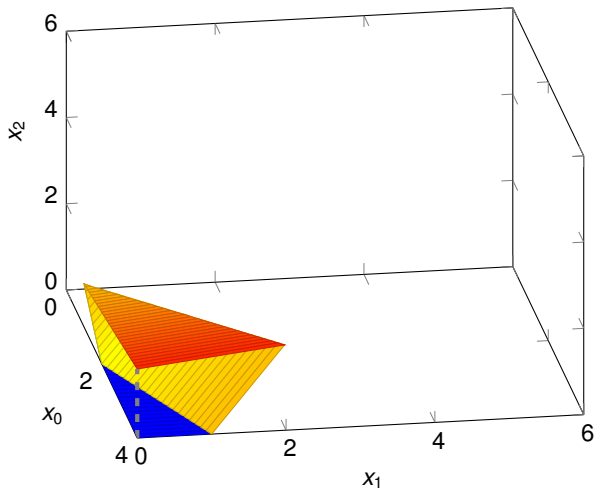


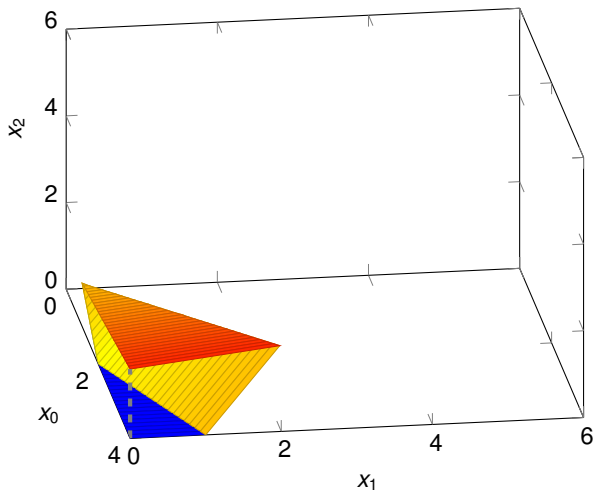


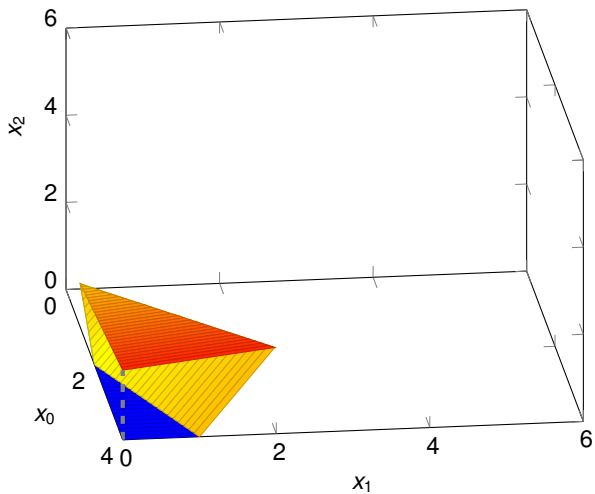


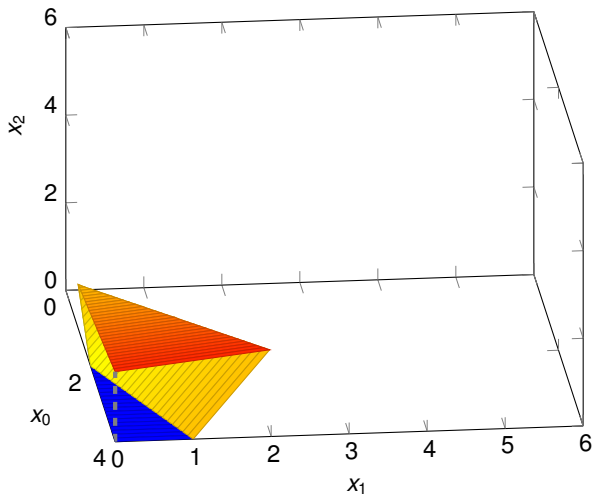


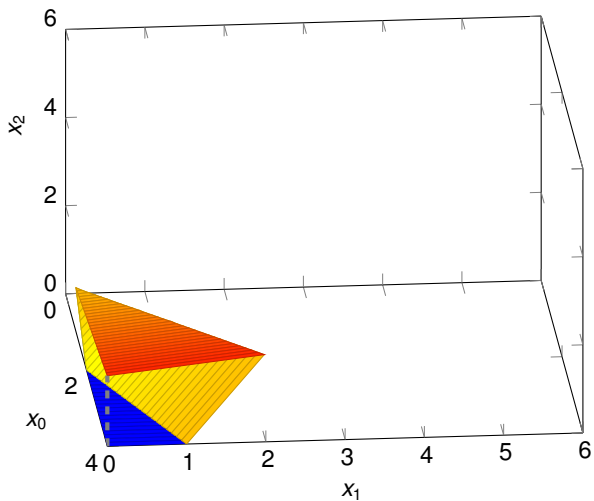


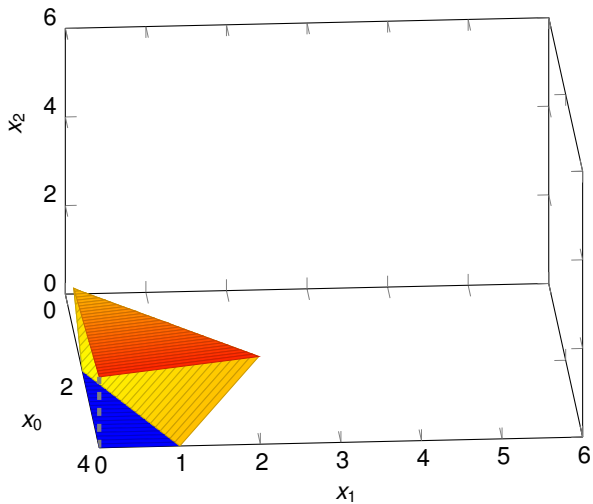




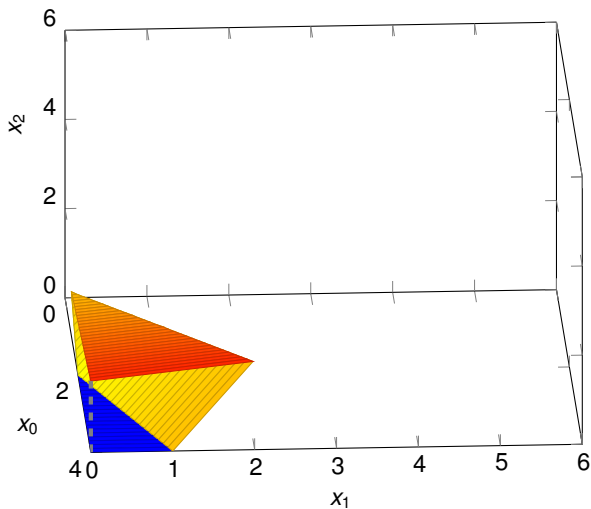


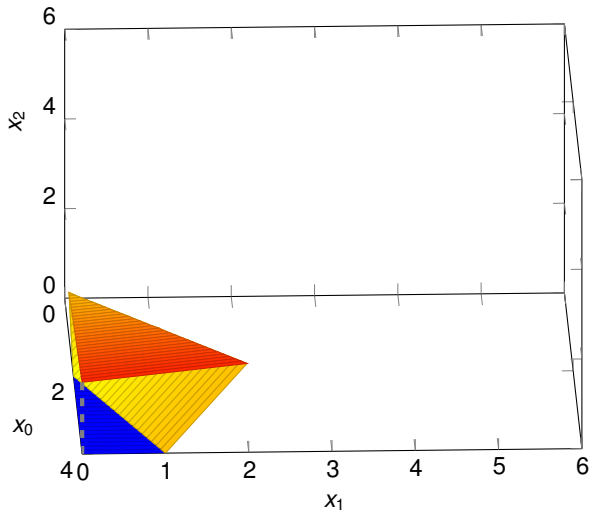


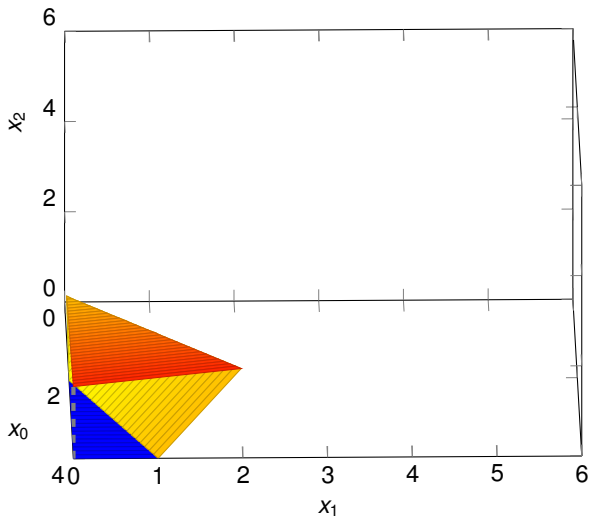












## INITIALIZE-SIMPLEX

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INITIALIZE-SIMPLEX( $A, b, c$ )

- 1 let  $k$  be the index of the minimum  $b_i$
- 2 **if**  $b_k \geq 0$  // is the initial basic solution feasible?
- 3 **return**  $(\{1, 2, \dots, n\}, \{n+1, n+2, \dots, n+m\}, A, b, c, 0)$
- 4 form  $L_{\text{aux}}$  by adding  $-x_0$  to the left-hand side of each constraint  
and setting the objective function to  $-x_0$
- 5 let  $(N, B, A, b, c, v)$  be the resulting slack form for  $L_{\text{aux}}$
- 6  $l = n + k$
- 7 //  $L_{\text{aux}}$  has  $n + 1$  nonbasic variables and  $m$  basic variables.
- 8  $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$
- 9 // The basic solution is now feasible for  $L_{\text{aux}}$ .
- 10 iterate the **while** loop of lines 3–12 of SIMPLEX until an optimal solution  
to  $L_{\text{aux}}$  is found
- 11 **if** the optimal solution to  $L_{\text{aux}}$  sets  $\bar{x}_0$  to 0
- 12 **if**  $\bar{x}_0$  is basic
- 13 perform one (degenerate) pivot to make it nonbasic
- 14 from the final slack form of  $L_{\text{aux}}$ , remove  $x_0$  from the constraints and  
restore the original objective function of  $L$ , but replace each basic  
variable in this objective function by the right-hand side of its  
associated constraint
- 15 **return** the modified final slack form
- 16 **else return** “infeasible”

Test solution with  $N = \{1, 2, \dots, n\}$ ,  $B = \{n + 1, n + 2, \dots, n + m\}$ ,  $\bar{x}_i = b_i$  for  $i \in B$ ,  $\bar{x}_i = 0$  otherwise.

INITIALIZE-SIMPLEX( $A, b, c$ )

- 1 let  $k$  be the index of the minimum  $b_i$
- 2 **if**  $b_k \geq 0$  // is the initial basic solution feasible?
- 3 **return** ( $\{1, 2, \dots, n\}, \{n + 1, n + 2, \dots, n + m\}, A, b, c, 0$ )
- 4 form  $L_{\text{aux}}$  by adding  $-x_0$  to the left-hand side of each constraint  
and setting the objective function to  $-x_0$
- 5 let  $(N, B, A, b, c, v)$  be the resulting slack form for  $L_{\text{aux}}$
- 6  $l = n + k$
- 7 //  $L_{\text{aux}}$  has  $n + 1$  nonbasic variables and  $m$  basic variables.
- 8  $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$
- 9 // The basic solution is now feasible for  $L_{\text{aux}}$ .
- 10 iterate the **while** loop of lines 3–12 of SIMPLEX until an optimal solution  
to  $L_{\text{aux}}$  is found
- 11 **if** the optimal solution to  $L_{\text{aux}}$  sets  $\bar{x}_0$  to 0
- 12 **if**  $\bar{x}_0$  is basic
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## INITIALIZE-SIMPLEX

INITIALIZE-SIMPLEX( $A, b, c$ )

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- 2 **if**  $b_k \geq 0$  // is the initial basic solution feasible?
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and setting the objective function to  $-x_0$
- 5 let  $(N, B, A, b, c, v)$  be the resulting slack form for  $L_{\text{aux}}$
- 6  $l = n + k$
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variable in this objective function by the right-hand side of its  
associated constraint
- 15 **return** the modified final slack form
- 16 **else return** “infeasible”

Test solution with  $N = \{1, 2, \dots, n\}$ ,  $B = \{n+1, n+2, \dots, n+m\}$ ,  $\bar{x}_i = b_i$  for  $i \in B$ ,  $\bar{x}_i = 0$  otherwise.

$\ell$  will be the leaving variable so  
that  $x_\ell$  has the most negative value.

## INITIALIZE-SIMPLEX

INITIALIZE-SIMPLEX( $A, b, c$ )

- 1 let  $k$  be the index of the minimum  $b_i$
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$l$  will be the leaving variable so that  $x_l$  has the most negative value.

Pivot step with  $x_l$  leaving and  $x_0$  entering.

## INITIALIZE-SIMPLEX

INITIALIZE-SIMPLEX( $A, b, c$ )

- 1 let  $k$  be the index of the minimum  $b_i$
- 2 **if**  $b_k \geq 0$  // is the initial basic solution feasible?
- 3 **return**  $(\{1, 2, \dots, n\}, \{n+1, n+2, \dots, n+m\}, A, b, c, 0)$
- 4 form  $L_{\text{aux}}$  by adding  $-x_0$  to the left-hand side of each constraint  
and setting the objective function to  $-x_0$
- 5 let  $(N, B, A, b, c, v)$  be the resulting slack form for  $L_{\text{aux}}$
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$l$  will be the leaving variable so that  $x_l$  has the most negative value.

Pivot step with  $x_l$  leaving and  $x_0$  entering.

This pivot step does not change the value of any variable.



## Example of INITIALIZE-SIMPLEX (1/3)

---

$$\begin{array}{llllll} \text{maximise} & 2x_1 & - & x_2 & & \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & \leq & 2 \\ & x_1 & - & 5x_2 & \leq & -4 \\ & & & x_1, x_2 & \geq & 0 \end{array}$$

## Example of INITIALIZE-SIMPLEX (1/3)

---

$$\begin{array}{llll} \text{maximise} & 2x_1 & - & x_2 \\ \text{subject to} & & & \\ & 2x_1 & - & x_2 \leq 2 \\ & x_1 & - & 5x_2 \leq -4 \\ & & & x_1, x_2 \geq 0 \end{array}$$

↓  
Formulating the auxiliary linear program

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Formulating the auxiliary linear program

$$\begin{array}{llllll} \text{maximise} & & & & - & x_0 \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & - & x_0 \leq 2 \\ & x_1 & - & 5x_2 & - & x_0 \leq -4 \\ & & & & & x_1, x_2, x_0 \geq 0 \end{array}$$

## Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{llll} \text{maximise} & 2x_1 & - & x_2 \\ \text{subject to} & & & \\ & 2x_1 & - & x_2 \leq 2 \\ & x_1 & - & 5x_2 \leq -4 \\ & & & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

$$\begin{array}{llllll} \text{maximise} & & & & - & x_0 \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & - & x_0 \leq 2 \\ & x_1 & - & 5x_2 & - & x_0 \leq -4 \\ & & & & & x_1, x_2, x_0 \geq 0 \end{array}$$

Converting into slack form

## Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximise} & 2x_1 \quad - \quad x_2 \\ \text{subject to} & \\ & 2x_1 \quad - \quad x_2 \leq 2 \\ & x_1 \quad - \quad 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

$$\begin{array}{ll} \text{maximise} & \quad \quad \quad - \quad x_0 \\ \text{subject to} & \\ & 2x_1 \quad - \quad x_2 \quad - \quad x_0 \leq 2 \\ & x_1 \quad - \quad 5x_2 \quad - \quad x_0 \leq -4 \\ & x_1, x_2, x_0 \geq 0 \end{array}$$

Converting into slack form

$$\begin{array}{ll} Z & = \quad \quad \quad - \quad x_0 \\ x_3 & = \quad 2 \quad - \quad 2x_1 \quad + \quad x_2 \quad + \quad x_0 \\ x_4 & = \quad -4 \quad - \quad x_1 \quad + \quad 5x_2 \quad + \quad x_0 \end{array}$$

## Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximise} & 2x_1 - x_2 \\ \text{subject to} & \\ & 2x_1 - x_2 \leq 2 \\ & x_1 - 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

$$\begin{array}{ll} \text{maximise} & -x_0 \\ \text{subject to} & \\ & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_1, x_2, x_0 \geq 0 \end{array}$$

Basic solution  
(0, 0, 0, 2, -4) not feasible!

Converting into slack form

$$\begin{array}{ll} z & = & & -x_0 \\ x_3 & = & 2 & - 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - x_1 & + & 5x_2 & + & x_0 \end{array}$$

## Example of INITIALIZE-SIMPLEX (2/3)

---

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$

## Example of INITIALIZE-SIMPLEX (2/3)

---

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with  $x_0$  entering and  $x_4$  leaving



## Example of INITIALIZE-SIMPLEX (2/3)

---

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with  $x_0$  entering and  $x_4$  leaving

$$\begin{array}{rcllclclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

## Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with  $x_0$  entering and  $x_4$  leaving

$$\begin{array}{rcllclclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!

## Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with  $x_0$  entering and  $x_4$  leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!



Pivot with  $x_2$  entering and  $x_0$  leaving

## Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with  $x_0$  entering and  $x_4$  leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!



Pivot with  $x_2$  entering and  $x_0$  leaving

$$\begin{array}{rcllclcl} Z & = & & - & x_0 \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

## Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with  $x_0$  entering and  $x_4$  leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!



Pivot with  $x_2$  entering and  $x_0$  leaving

$$\begin{array}{rcllclcl} Z & = & & - & x_0 \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Optimal solution has  $x_0 = 0$ , hence the initial problem was feasible!

## Example of INITIALIZE-SIMPLEX (3/3)

---

$$\begin{array}{rclclclcl} Z & = & & - & x_0 & & & & \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

## Example of INITIALIZE-SIMPLEX (3/3)

---

$$\begin{aligned} Z &= && - && x_0 \\ x_2 &= & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 &= & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{aligned}$$

↓ Set  $x_0 = 0$  and express objective function  
by non-basic variables

## Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{aligned} Z &= && - && x_0 \\ x_2 &= & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 &= & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{aligned}$$

$$2x_1 - x_2 = 2x_1 - \left( \frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5} \right)$$

Set  $x_0 = 0$  and express objective function by non-basic variables

$$\begin{aligned} Z &= & -\frac{4}{5} & + & \frac{9x_1}{5} & - & \frac{x_4}{5} \\ x_2 &= & \frac{4}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 &= & \frac{14}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{aligned}$$



## Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{array}{rcllclcl} Z & = & & - & x_0 & & \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

$$2x_1 - x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}\right)$$

Set  $x_0 = 0$  and express objective function by non-basic variables

$$\begin{array}{rcllclcl} Z & = & -\frac{4}{5} & + & \frac{9x_1}{5} & - & \frac{x_4}{5} \\ x_2 & = & \frac{4}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Basic solution  $(0, \frac{4}{5}, \frac{14}{5}, 0)$ , which is feasible!

## Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{array}{rcllclcl} Z & = & & - & x_0 & & \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

$$2x_1 - x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}\right)$$

Set  $x_0 = 0$  and express objective function by non-basic variables

$$\begin{array}{rcllclcl} Z & = & -\frac{4}{5} & + & \frac{9x_1}{5} & - & \frac{x_4}{5} \\ x_2 & = & \frac{4}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Basic solution  $(0, \frac{4}{5}, \frac{14}{5}, 0)$ , which is feasible!

### Lemma 29.12

If a linear program  $L$  has no feasible solution, then INITIALIZE-SIMPLEX returns “infeasible”. Otherwise, it returns a valid slack form for which the basic solution is feasible.

## Fundamental Theorem of Linear Programming

---

### Theorem 29.13 (Fundamental Theorem of Linear Programming)

Any linear program  $L$ , given in standard form, either

1. has an optimal solution with a finite objective value,
2. is infeasible, or
3. is unbounded.

If  $L$  is infeasible, SIMPLEX returns “infeasible”. If  $L$  is unbounded, SIMPLEX returns “unbounded”. Otherwise, SIMPLEX returns an optimal solution with a finite objective value.

## Fundamental Theorem of Linear Programming

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### Theorem 29.13 (Fundamental Theorem of Linear Programming)

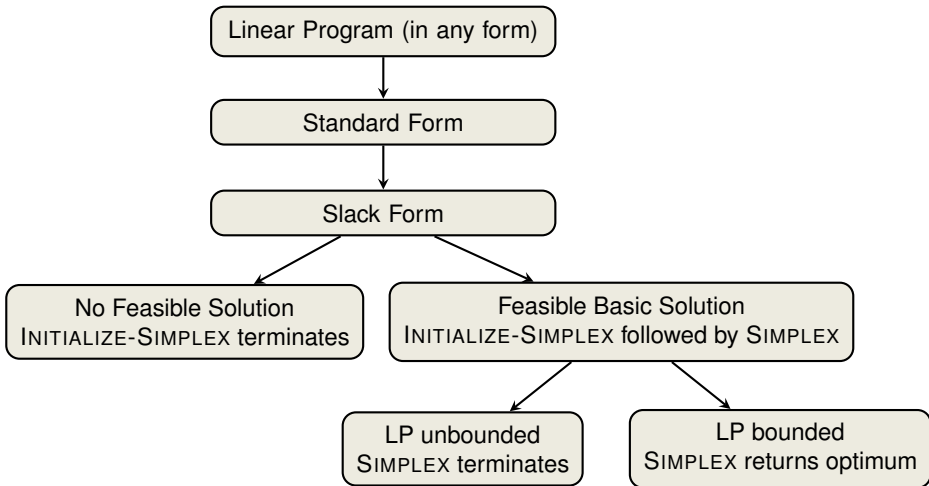
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If  $L$  is infeasible, SIMPLEX returns “infeasible”. If  $L$  is unbounded, SIMPLEX returns “unbounded”. Otherwise, SIMPLEX returns an optimal solution with a finite objective value.

Proof requires the concept of **duality**, which is not covered in this course (for details see CLRS3, Chapter 29.4)

## Workflow for Solving Linear Programs



# Linear Programming and Simplex: Summary and Outlook

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Linear Programming



## Linear Programming and Simplex: Summary and Outlook

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### Linear Programming

- extremely versatile tool for modelling problems of all kinds

## Linear Programming and Simplex: Summary and Outlook

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### Linear Programming

- extremely versatile tool for modelling problems of all kinds
- basis of [Integer Programming](#), to be discussed in later lectures



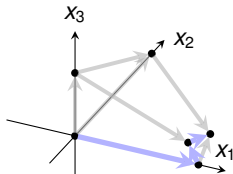
# Linear Programming and Simplex: Summary and Outlook

## Linear Programming

- extremely versatile tool for modelling problems of all kinds
- basis of **Integer Programming**, to be discussed in later lectures

## Simplex Algorithm

- **In practice**: usually terminates in polynomial time, i.e.,  $O(m + n)$



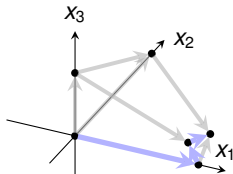
# Linear Programming and Simplex: Summary and Outlook

## Linear Programming

- extremely versatile tool for modelling problems of all kinds
- basis of **Integer Programming**, to be discussed in later lectures

## Simplex Algorithm

- **In practice**: usually terminates in polynomial time, i.e.,  $O(m + n)$
- **In theory**: even with anti-cycling may need exponential time



# Linear Programming and Simplex: Summary and Outlook

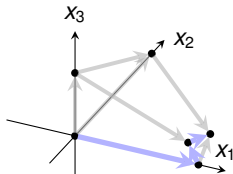
## Linear Programming

- extremely versatile tool for modelling problems of all kinds
- basis of **Integer Programming**, to be discussed in later lectures

## Simplex Algorithm

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# Linear Programming and Simplex: Summary and Outlook

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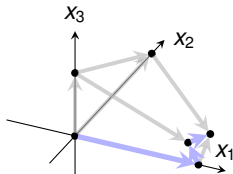
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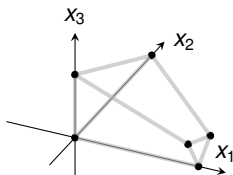
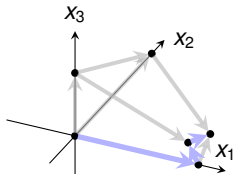
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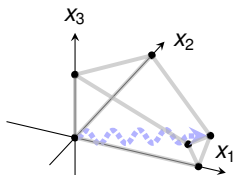
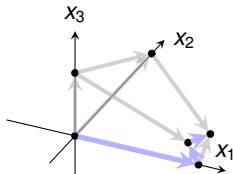
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Which of the following statements are true?

1. In each iteration of the Simplex algorithm, the objective function increases.
2. There exist linear programs that have exactly two optimal solutions.
3. There exist linear programs that have infinitely many optimal solutions.
4. The Simplex algorithm always runs in worst-case polynomial time.