FoCS Lecture 5: SriogntSorting

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Applications of sorting

- fast **search**
- fast merging
- finding duplicates
- inverting tables
- graphics algorithms

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- fast **search**
- fast merging
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- graphics algorithms

Once a set of items is sorted, it simplifies many other problems in computer science.

Complexity of Comparison Sort?

- typically count the number of comparisons C(n)
- there are *n*! permutations of *n* elements
- each comparison eliminates *half* of the permutations $2^{C(n)} \ge n!$
- therefore $C(n) \ge \log(n!) \approx n \log n 1.44n$
- The lower bound of comparison is $O(n \log n)$

Common sorting algorithms

We begin by examining three in detail:

- Insertion sort
- Quicksort
- Mergesort

```
# let rec ins = function
    | x, [] -> [x]
    | x, y::ys ->
        if x <= y then
            x :: y :: ys
        else
            y :: ins (x, ys)
# let rec insort = function
    | [] -> []
    | x::xs -> ins (x, insort xs)
```

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$x::xs \rightarrow ins (x, insort x)$	(S)
Input is inserted in the output in	Then continue to process the
the right place to be sorted	remainder of the input

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    if x <= y then
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- Items from input are copied to the output
- Inserted in order, so the output is always sorted



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Complexity is $O(n^2)$ comparisons vs the theoretical best case of $O(n \log n)$

- Choose a pivot element a
- **Divide:** partition the input into two sublists
 - those at most *a* in value
 - those exceeding a
- Conquer: using recursive calls to sort sublists
- Combine: sorted lists by appending them

"Divide"





Complexity is $O(n \log n)$ in the average case

Complexity is $O(n \log n)$ in the average case but $O(n^2)$ in the worst case!

Append-free Quicksort

Comparing both quicksorts

```
let rec quik = function
    [], sorted -> sorted
    [x], sorted -> x::sorted
    a::bs, sorted ->
    let rec part = function
        | 1, r, [] ->
            quik (1, a :: quik (r, sorted))
        | 1, r, x::xs ->
            if x <= a then
               part (x::1, r, xs)
            else
               part (1, x::r, xs)
            in
            part ([], [], bs)
</pre>
```

Comparing both quicksorts

let rec quik = function [], sorted -> sorted [x], sorted -> x::sorted a::bs, sorted -> let rec part = function | l, r, [] -> quik (1, a :: quik (r, sorted)) | l, r, x::xs -> if x <= a then part (x::1, r, xs) else part (1, x::r, xs) in part ([], [], bs)

Call "quick" twice and then append results

Call "quik" once, cons "a" to it, then call "quik" again

Mergesort

Merge Two Lists

#	let	rec	me	erge	e = fur	nctio	n	
		[],	ys	>	> ys			
		xs,	[]	_>	> xs			
		x:::	ks,	У	::ys ->	>		
if x <= y then								
			Х	::	merge	(xs,	у:	ys)
		e	lse					
			У	•••	merge	(x:::	xs,	ys)

Merge Two Lists



- Does at most (m + n 1)
 comparisons where m and n
 are length of input lists
- Fast if lists are roughly equal and >1 length

Useful as the basis for several other divide-and-conquer algorithms.

```
# let rec tmergesort = function
    [] -> []
    [x] -> [x]
    [xs ->
    let k = List.length xs / 2 in
    let l = tmergesort (take (xs, k)) in
    let r = tmergesort (drop (xs, k)) in
    merge (l, r)
```



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- Count half the list and divide using take and drop



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```

- Complexity of mergesort is $O(n \log n)$
- But unlike quicksort, is *always* that even in the worst case.
- So why not always use mergesort?

Sorting through sorting algorithms

Optimal is $O(n \log n)$ **comparisons**

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Insertion sort: simple to code, quadratic complexity Quicksort: fast on average, quadratic complexity in worst case Mergesort: optimal in theory, often slower than quicksort in practise

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Match the algorithm to the application

Exercises

Optimal is $O(n \log n)$ **comparisons**

Insertion sort: simple to code, quadratic complexity Quicksort: fast on average, quadratic complexity in worst case Mergesort: optimal in theory, often slower than quicksort in practise

> Work through selection sort and bubblesort, and examine the complexity and runtime tradeoffs of their approaches