7: Catchup Session & very short intro to other classifiers

Machine Learning and Real-world Data (MLRD)

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What happens in a catchup session?

- Lecture and practical session as normal.
- New material is non-examinable.
- Time for you to catch-up or attempt some starred ticks.

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Demonstrators help as per usual.

Naive Bayes is a probabilistic classifier

- Given a set of input features a probabilistic classifier provide a distribution over classess.
- That is, for a set of observed features *O* and classes $c_1...c_n \in C$ gives $P(c_i|O)$ for all $c_i \in C$
- For us O was the set all the words in a review $\{w_1, w_2, ..., w_n\}$ where w_i is the *i*th word in a review, $C = \{\text{POS}, \text{NEG}\}$
- We decided on a single class by choosing the one with the highest probability given the features:

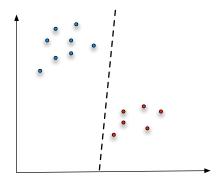
$$\hat{c} = \operatorname*{argmax}_{c \in C} P(c|O)$$

An SVM is a popular non-probabilistic classifier

- A Support Vector Machine (SVM) is a non-probabilistic binary linear classifier
- SVMs assign new examples to one category or the other
- SVMs can reduce the amount of labeled data required to gain good accuracy
- SVMs can be efficiently adapted to perform a non-linear classification

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SVMs find hyper-planes that separate classes

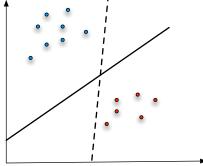


Our classes exist in a multidimensional feature space

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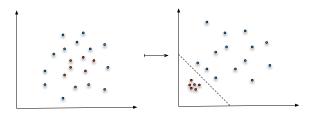
 A linear classifier will separate the points with a hyper-plane SVMs find a maximum-margin hyperplane in noisy data



- There are many possible hyperplanes
- SVMs find the best hyperplane such that the distance from it to the nearest data point from each class is maximised
- i.e. the hyperplane that passes through the widest possible gap (hopefully helps to avoid over-fitting)

SVMs can be very efficient and effective

- Efficient when learning from a large number of features (good for text)
- Effective even with relatively small amounts of labelled data (we only need points close to the plane to calculate it)
- We can choose how many points to involve (size of margin) when calculating the plane (tuning vs. over-fitting)
- Can separate non-linear boundaries by changing the feature space (using a kernal function)



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Choice of classifier will depend on the task

Comparison of a SVM and Naive Bayes on the same task:

- 2000 imdb movie reviews, 400 kept for testing
- preprocess with improved tokeniser (lowercased, removed uninformative words, dealt with punctuation, lemmatised words)

	SVM	Naive Bayes
Accuracy on train		0.96
Accuracy on test	0.84	0.80

- But from Naive Bayes I know that *character*, *good*, *story*, *great*, ... are informative features
- SVMs are more difficult to interpret

Decision tree can be used to visually represent classifications



- Simple to interpret
- Can mix numerical and categorical data
- You specify the parameters of the tree (maximum depth, number of items at leaf nodes—both change accuracy)
- But finding the optimal decision tree can be NP-complete

Information gain can be used to decide how to split

Information gain is defined in terms of entropy H Entropy of tree node:

$$H(n) = -\sum_{p} p_i \log_2 p_i$$

where p_i are the probabilities of each class at node n

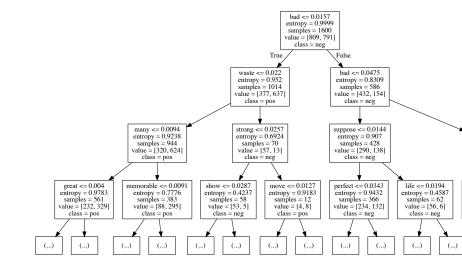
Information gain I is the reduction in entropy of n achieved by learning the state of the random variable D.

Information gain:

$$I(n,D) = H(n) - H(n|D)$$

where H(n|D) is the weighted entropy of the daughter nodes if we split on D.

Information gain can be used to decide how to split



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Results on the 2000 movie reviews:

	SVM	Naive Bayes	DTree (max depth 7)
Accuracy on train		0.96	0.80
Accuracy on test	0.84	0.80	0.69

Today

- Pretester for Tick 1 cuts out Midnight on Friday
- Friday session last chance to get help
- Get in touch with me if you are behind
- New topic starts on Monday—try to have ticks 1–6 by end of today

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