

Topic 1

Introduction

What is this course about?

- General area.

Formal methods: Mathematical techniques for the specification, development, and verification of software and hardware systems.

- Specific area.

Formal semantics: Mathematical theories for ascribing meanings to computer languages.

Why do we care?

- Rigour.
 - ... specification of programming languages
 - ... justification of program transformations
- Insight.
 - ... generalisations of notions computability
 - ... higher-order functions
 - ... data structures

- Feedback into language design.
 - ... continuations
 - ... monads
- Reasoning principles.
 - ... Scott induction
 - ... Logical relations
 - ... Co-induction

Styles of formal semantics

Operational.

Meanings for program phrases defined in terms of the *steps of computation* they can take during program execution.

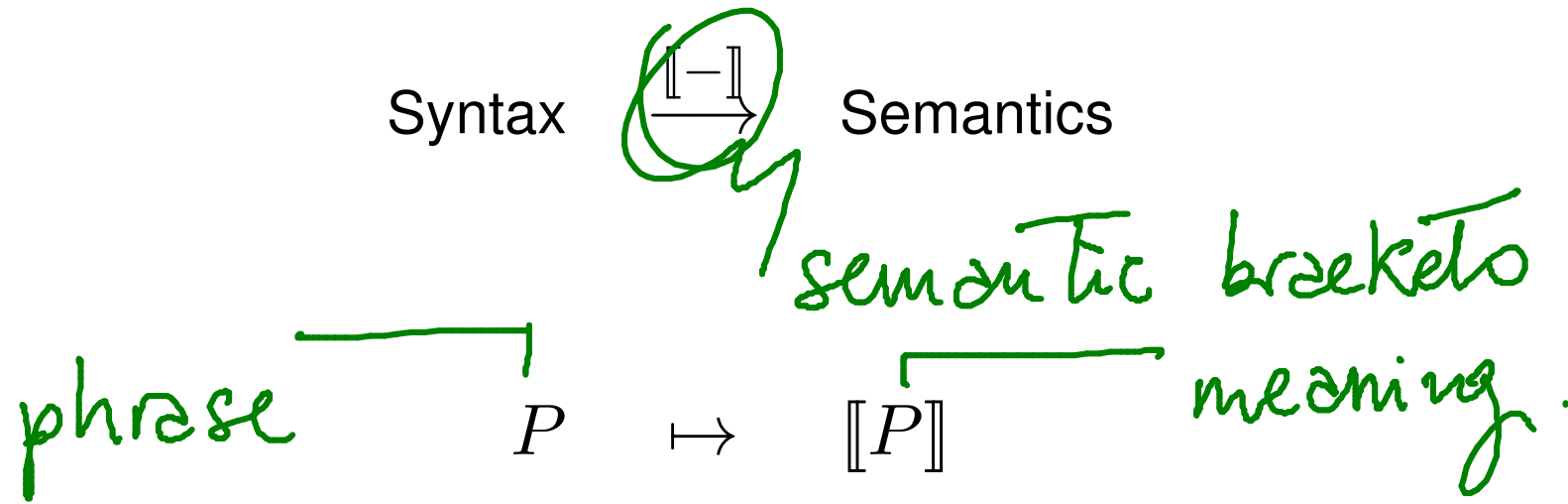
Axiomatic.

Meanings for program phrases defined indirectly via the *axioms and rules* of some logic of program properties.

Denotational.

Concerned with giving *mathematical models* of programming languages. Meanings for program phrases defined abstractly as elements of some suitable mathematical structure.

Basic idea of denotational semantics



Basic idea of denotational semantics

Syntax $\xrightarrow{\llbracket - \rrbracket}$ Semantics

Recursive program \mapsto Partial recursive function

$P \mapsto \llbracket P \rrbracket$

Basic idea of denotational semantics

Syntax $\xrightarrow{\llbracket - \rrbracket}$ Semantics

Recursive program \mapsto Partial recursive function

Boolean circuit \mapsto Boolean function

$P \mapsto \llbracket P \rrbracket$

Concerns

- Abstract models.
- Compositionality.
- Relationship to computation.

Characteristic features of a denotational semantics

- Each phrase (= part of a program), P , is given a **denotation**, $\llbracket P \rrbracket$ — a mathematical object representing the contribution of P to the meaning of *any* complete program in which it occurs.
- The denotation of a phrase is determined just by the denotations of its subphrases (one says that the semantics is **compositional**).

Basic example of denotational semantics (I)

IMP⁻ syntax

Arithmetic expressions

$A \in \mathbf{Aexp} ::= \underline{n} \mid L \mid A + A \mid \dots$

where n ranges over *integers* and

L over a specified set of *locations* \mathbb{L}

Boolean expressions

$B \in \mathbf{Bexp} ::= \mathbf{true} \mid \mathbf{false} \mid A = A \mid \dots$
 $\mid \neg B \mid \dots$

Commands

$C \in \mathbf{Comm} ::= \mathbf{skip} \mid L := A \mid C; C$
 $\mid \mathbf{if } B \mathbf{ then } C \mathbf{ else } C$

Basic example of denotational semantics (II)

Semantic functions

$$A: \text{Aexp} \rightarrow (\text{State} \rightarrow \mathbb{Z})$$

$$A[E]: \text{State} \rightarrow \mathbb{Z} \quad s \in \text{State}$$

where $E \in \underline{\text{Aexp}}$

$$A[E](s) \in \mathbb{Z}$$

$$\mathbb{Z} = \{\dots, -1, 0, 1, \dots\}$$

$$\text{State} = (\mathbb{L} \rightarrow \mathbb{Z})$$

Basic example of denotational semantics (II)

Semantic functions

$$A : \mathbf{Aexp} \rightarrow (\text{State} \rightarrow \mathbb{Z})$$

$$B : \mathbf{Bexp} \rightarrow (\text{State} \rightarrow \mathbb{B})$$

where $E \in \underline{\mathbf{BExp}}$, $s \in \underline{\text{State}}$, $B \llbracket E \rrbracket (s) \in \mathbb{B}$

$$\mathbb{Z} = \{ \dots, -1, 0, 1, \dots \}$$

$$\mathbb{B} = \{ \text{true}, \text{false} \}$$

$$\text{State} = (\mathbb{L} \rightarrow \mathbb{Z})$$

\mathcal{C} : commands \mapsto state transformers

Basic example of denotational semantics (II)

Semantic functions

$$A: \mathbf{Aexp} \rightarrow (\text{State} \rightarrow \mathbb{Z})$$

$$B: \mathbf{Bexp} \rightarrow (\text{State} \rightarrow \mathbb{B})$$

$$C: \mathbf{Comm} \rightarrow (\text{State} \rightarrow \text{State})$$

formally, a partial function from State to State.

where

$$P \in \mathbf{Comm}, s \in \text{State} : \mathcal{C}[[P]](s) \in \text{State}.$$

$$\mathbb{Z} = \{\dots, -1, 0, 1, \dots\}$$

$$\mathbb{B} = \{\text{true}, \text{false}\}$$

$$\text{State} = (\mathbb{L} \rightarrow \mathbb{Z})$$

The state resulting from the computation of P on states.

Basic example of denotational semantics (II)

Semantic functions

$$A : \mathbf{Aexp} \rightarrow (State \rightarrow \mathbb{Z})$$

$$B : \mathbf{Bexp} \rightarrow (State \rightarrow \mathbb{B})$$

$$C : \mathbf{Comm} \rightarrow (State \rightarrow State)$$

where

$$\mathbb{Z} = \{ \dots, -1, 0, 1, \dots \}$$

$$\mathbb{B} = \{ true, false \}$$

$$State = (\mathbb{L} \rightarrow \mathbb{Z})$$

$$L \in \mathbb{L}$$

$$s \in State$$

$$s(L) \in \mathbb{Z}$$

or
memory
or
store

= functions from locations to integers

Recall

$\lambda x. e[x]$ denotes the function that on input, say a , results in output $e[a]$.

Basic example of denotational semantics (III)

Semantic function A

$$A[\underline{n}] = \lambda s \in \text{State}. n$$

$$A[L] = \lambda s \in \text{State}. s(L)$$

$$A[A_1 + A_2] = \lambda s \in \text{State}. A[A_1](s) + A[A_2](s)$$

$$A[A_1 + A_2](s) = A[A_1](s) + A[A_2](s)$$

↑
plus symbol

Abuse of notation ↑

↑
integer addition

$$A[\underline{n}](s) = n$$

$$A[L](s) = s(L)$$

compositionality

Basic example of denotational semantics (IV)

Semantic function \mathcal{B}

$$\mathcal{B}[\underline{\text{true}}](s) = \underline{\text{true}}$$

$$\mathcal{B}[\text{true}] = \lambda s \in \text{State}. \text{true}$$

$$\mathcal{B}[\text{false}] = \lambda s \in \text{State}. \text{false}$$

$$\mathcal{B}[A_1 = A_2] = \lambda s \in \text{State}. \text{eq}(\mathcal{A}[A_1](s), \mathcal{A}[A_2](s))$$

$$\text{where } \text{eq}(a, a') = \begin{cases} \text{true} & \text{if } a = a' \\ \text{false} & \text{if } a \neq a' \end{cases}$$

$$\mathcal{B}[[A_1 = A_2]](s) = \begin{cases} \text{true} & \text{if } \mathcal{A}[A_1](s) = \mathcal{A}[A_2](s) \\ \text{false} & \text{otherwise.} \end{cases}$$

state transformer
 $\llbracket P \rrbracket : \underline{\text{State}} \rightarrow \underline{\text{State}}$

PEComm

Basic example of denotational semantics (V)

Semantic function \mathcal{C}

$$\llbracket \text{skip} \rrbracket = \lambda s \in \text{State}. s$$

identity function

$$\llbracket \text{skip} \rrbracket (s) = s$$

NB: From now on the names of semantic functions are omitted!

$$\llbracket \text{if } B \text{ then } C \text{ else } C' \rrbracket (s) = \begin{cases} \llbracket C \rrbracket (s) \\ \llbracket C' \rrbracket (s) \end{cases}$$

$$\llbracket B \rrbracket (s) = \text{true} \\ \text{otherwise}$$

A simple example of compositionality

Given partial functions $\llbracket C \rrbracket, \llbracket C' \rrbracket : \text{State} \rightarrow \text{State}$ and a function $\llbracket B \rrbracket : \text{State} \rightarrow \{\text{true}, \text{false}\}$, we can define

$$\llbracket \text{if } B \text{ then } C \text{ else } C' \rrbracket =$$

$$\lambda s \in \text{State}. \text{if} (\llbracket B \rrbracket (s), \llbracket C \rrbracket (s), \llbracket C' \rrbracket (s))$$

where

$$\text{if}(b, x, x') = \begin{cases} x & \text{if } b = \text{true} \\ x' & \text{if } b = \text{false} \end{cases}$$

Basic example of denotational semantics (VI)

Semantic function \mathcal{C}

$$\llbracket L := A \rrbracket = \lambda s \in \text{State}. \lambda \ell \in \mathbb{L}. \text{if } (\ell = L, \llbracket A \rrbracket(s), s(\ell))$$

$$\llbracket L := A \rrbracket(s) = \lambda \ell \in \mathbb{L}. \begin{cases} \llbracket A \rrbracket(s) & \ell = L \\ s(\ell) & \text{otherwise} \end{cases}$$

Denotational semantics of sequential composition

Denotation of sequential composition $C; C'$ of two commands

$$\llbracket C; C' \rrbracket = \llbracket C' \rrbracket \circ \llbracket C \rrbracket = \lambda s \in \text{State}. \llbracket C' \rrbracket (\llbracket C \rrbracket (s))$$

given by composition of the partial functions from states to states $\llbracket C \rrbracket, \llbracket C' \rrbracket : \text{State} \rightarrow \text{State}$ which are the denotations of the commands.

$$\llbracket C; C' \rrbracket (s) = \llbracket C' \rrbracket (\llbracket C \rrbracket (s))$$

Denotational semantics of sequential composition

Denotation of sequential composition $C; C'$ of two commands

$$\llbracket C; C' \rrbracket = \llbracket C' \rrbracket \circ \llbracket C \rrbracket = \lambda s \in \text{State}. \llbracket C' \rrbracket (\llbracket C \rrbracket (s))$$

given by composition of the partial functions from states to states $\llbracket C \rrbracket, \llbracket C' \rrbracket : \text{State} \rightarrow \text{State}$ which are the denotations of the commands.

Cf. operational semantics of sequential composition:

$$\frac{C, s \Downarrow s' \quad C', s' \Downarrow s''}{C; C', s \Downarrow s''} .$$

One can show
 $\forall C, s, s'. \llbracket C \rrbracket (s) = s' \text{ iff } C, s \Downarrow s'.$

$\llbracket \text{while } B \text{ do } C \rrbracket : \text{State} \rightarrow \text{State}$

$C \in \text{Comm} ::= \dots | \underline{\text{while } B \text{ do } C} | \dots$

$\llbracket \underline{\text{while } B \text{ do } C} \rrbracket (s)$

$= \dots \llbracket B \rrbracket (s) \dots \llbracket C \rrbracket (s) \dots$

$\llbracket \text{while } B \text{ do } C \rrbracket : \text{State} \rightarrow \text{State}$

Program equivalence

$\text{while } B \text{ do } C$

$\equiv \text{if } B \text{ Then } (C; \text{while } B \text{ do } C) \text{ else skip.}$

Expect

$\llbracket \text{while } B \text{ do } C \rrbracket$

$= \llbracket \text{if } B \text{ Then } (C; \text{while } B \text{ do } C) \text{ else skip} \rrbracket$

That is,

for all states s

$$\llbracket \text{while } B \text{ do } C \rrbracket (s)$$

$$= \llbracket \text{if } B \text{ then } (C; \text{while } B \text{ do } C) \text{ else skip} \rrbracket (s)$$

$$= \text{if} (\llbracket B \rrbracket (s), \llbracket \text{while } B \text{ do } C \rrbracket (\llbracket C \rrbracket s), s)$$

tempting to define

$$\llbracket \text{while } B \text{ do } C \rrbracket (s)$$

$$= \text{def of} (\llbracket B \rrbracket (s), \llbracket \text{while } B \text{ do } C \rrbracket (\llbracket C \rrbracket s), s)$$

but this is non-sense!

$\llbracket \text{while } B \text{ do } C \rrbracket$ is a fixed point

recall that a fixed of a function f is an element x such that $x = f(x)$.

$\llbracket \text{while } B \text{ do } C \rrbracket$

$= \lambda s \in \text{State}. \text{if } (\llbracket B \rrbracket(s), \llbracket \text{while } B \text{ do } C \rrbracket(\llbracket C \rrbracket s), s)$

$f_{\llbracket B \rrbracket, \llbracket C \rrbracket} : (\text{State} \rightarrow \text{State}) \rightarrow (\text{State} \rightarrow \text{State})$

s.t. $f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(\llbracket \text{while } B \text{ do } C \rrbracket) = \llbracket \text{while } B \text{ do } C \rrbracket$

Fixed point property of [[while B do C]]

$$\llbracket \text{while } B \text{ do } C \rrbracket = f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(\llbracket \text{while } B \text{ do } C \rrbracket)$$

where, for each $b : \text{State} \rightarrow \{\text{true}, \text{false}\}$ and
 $c : \text{State} \rightarrow \text{State}$, we define

as $f_{b,c} : (\text{State} \rightarrow \text{State}) \rightarrow (\text{State} \rightarrow \text{State})$

$$f_{b,c} = \lambda w \in (\text{State} \rightarrow \text{State}). \lambda s \in \text{State}. \text{if}(b(s), w(c(s)), s).$$

$$\llbracket \text{while } B \text{ do } C \rrbracket = \text{fix} (f_{\llbracket B \rrbracket, \llbracket C \rrbracket})$$

}

[?]

Fixed point property of [[while B do C]]

$$\llbracket \text{while } B \text{ do } C \rrbracket = f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(\llbracket \text{while } B \text{ do } C \rrbracket)$$

where, for each $b : \text{State} \rightarrow \{\text{true}, \text{false}\}$ and $c : \text{State} \rightarrow \text{State}$, we define

as $f_{b,c} : (\text{State} \rightarrow \text{State}) \rightarrow (\text{State} \rightarrow \text{State})$

$$f_{b,c} = \lambda w \in (\text{State} \rightarrow \text{State}). \lambda s \in \text{State}. \text{if } (b(s), w(c(s))), s).$$

-
- Why does $w = f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(w)$ have a solution?
 - What if it has several solutions—which one do we take to be $\llbracket \text{while } B \text{ do } C \rrbracket$?

$\text{fix}_{\perp}(f[\llbracket B \rrbracket], \llbracket C \rrbracket)$ by approximation

Approximating $\llbracket \text{while } B \text{ do } C \rrbracket$

• $w_0: \text{State} \rightarrow \text{State}$

"

\emptyset empty partial function

$w_0(s) = \uparrow$ ("undefined")

• $w_1 = f[\llbracket B \rrbracket, \llbracket C \rrbracket](w_0)$

$w_1(s) = \text{if}(\llbracket B \rrbracket(s), w_0(\llbracket C \rrbracket s), s)$

$= \text{if}(\llbracket B \rrbracket(s), \uparrow, s)$

- $\omega_2 = f_{\pi_B \gamma, \pi_C \gamma}(\omega_1)$

$$\omega_2(s) = f(\bar{\pi}_B \gamma(s), \omega_1(\pi_C \gamma(s)), s)$$

$$= f(\bar{\pi}_B \gamma(s),$$

$$f(\pi_B \gamma(\pi_C \gamma(s)), \uparrow, \pi_C \gamma(s),$$

$$s)$$

⋮

- $\omega_n = f_{\pi_B \gamma, \bar{\pi}_C \gamma}(\omega_{n-1})$

approximates π while B do $C \gamma$
up to n iterations.

union
join

$$\bigcup_{n \in \omega} \omega_n = \bigcup_{n \in \omega} f_{[[B], [C]]^n}(\perp)$$

Approximating $[[\text{while } B \text{ do } C]]$

empty partial function

$$\omega_n \stackrel{\text{def}}{=} f_{[[B], [C]]^n}(\perp)$$

$$= \lambda s \in \text{State}.$$

$$\left\{ \begin{array}{l} [C]^k(s) \quad \text{if } \exists 0 \leq k < n. [B]([C]^k(s)) = \text{false} \\ \quad \text{and } \forall 0 \leq i < k. [B]([C]^i(s)) = \text{true} \\ \uparrow \quad \quad \quad \text{if } \forall 0 \leq i < n. [B]([C]^i(s)) = \text{true} \end{array} \right.$$

● while true do C

$$\omega_0 = \perp$$

$$\omega_1 = \lambda s. \text{if } (\llbracket \text{true} \rrbracket (s), \uparrow, s)$$

$$= \lambda s. \uparrow = \omega_0$$

$$\llbracket \text{while } \text{true } \text{do } C \rrbracket = \bigcup_n \omega_n = \bigcup_n \perp$$
$$= \perp$$

• while false do c

$$\omega_0 = \perp$$

$$\omega_1 = \lambda s. \text{if } (\llbracket \text{false} \rrbracket (s), \uparrow, s) = \lambda s. s$$

for all $n \geq 1$ $\omega_n = \lambda s. s.$

$$\llbracket \text{while false do c} \rrbracket = \bigcup_n (\perp, \lambda s. s, \dots)$$

$$= \lambda s. s$$

$$= \llbracket \text{skip} \rrbracket$$

The domain of state transformers.

$$D \stackrel{\text{def}}{=} (\text{State} \rightarrow \text{State})$$

- **Partial order \sqsubseteq on D :**

$w \sqsubseteq w'$ iff for all $s \in \text{State}$, if w is defined at s then so is w' and moreover $w(s) = w'(s)$.

iff the graph of w is included in the graph of w' .

- **Least element $\perp \in D$ w.r.t. \sqsubseteq :**

\perp = totally undefined partial function

= partial function with empty graph

(satisfies $\perp \sqsubseteq w$, for all $w \in D$).

For a chain of approximations of
state transformers

$$\omega_0 \subseteq \omega_1 \subseteq \dots \subseteq \omega_n \subseteq \dots \quad (n \in \mathbb{N})$$

We let

$$\bigcup (\omega_0 \subseteq \omega_1 \subseteq \dots \subseteq \omega_n \subseteq \dots) = \bigcup_{n \in \mathbb{N}} \omega_n$$

be the state transformer whose graph is

$$\bigcup_{n \in \mathbb{N}} \text{graph}(\omega_n).$$