

Discovering information about how *data* (i.e. variables and their values) may move through a program.

Motivation

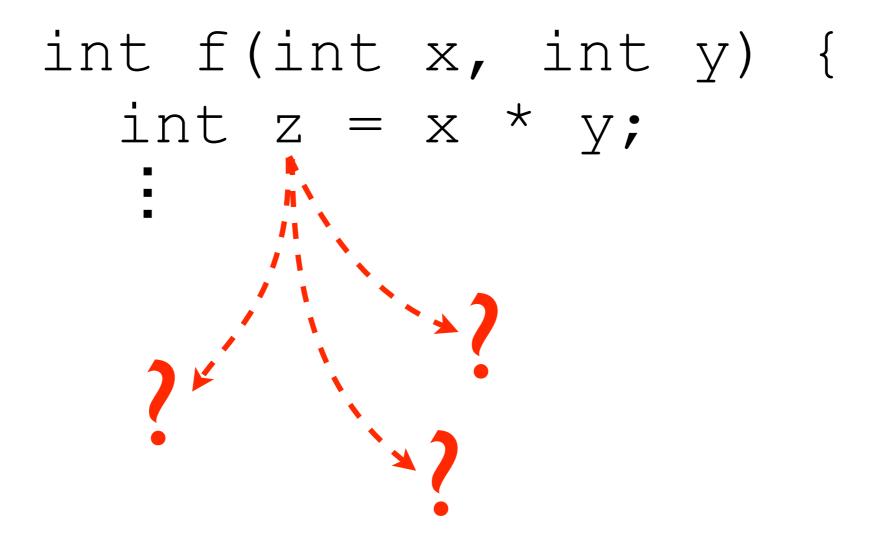
Programs may contain

- code which gets executed but which has no useful effect on the program's overall result;
- occurrences of variables being used before they are defined; and
- many variables which need to be allocated registers and/or memory locations for compilation.

The concept of *variable liveness* is useful in dealing with all three of these situations.

Liveness

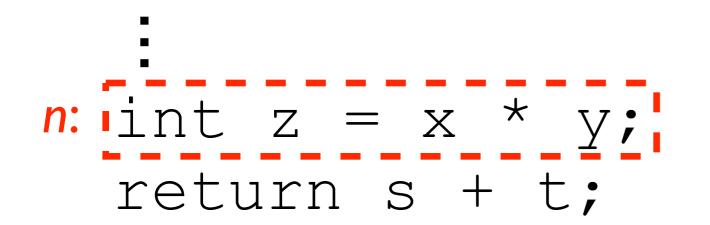
Liveness is a data-flow property of variables: "Is the value of this variable needed?" (cf. dead code)



Liveness

At each instruction, each variable in the program is either live or dead.

We therefore usually consider liveness from an instruction's perspective: each instruction (or node of the flowgraph) has an associated set of live variables.



live(n) = { s, t, x, y }

There are two kinds of variable liveness:

- Semantic liveness
- Syntactic liveness

A variable x is semantically live at a node n if there is some execution sequence starting at n whose (externally observable) behaviour can be affected by changing the value of x.

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Semantic liveness is concerned with the execution behaviour of the program.

This is undecidable in general. (e.g. Control flow may depend upon arithmetic.)

A variable is syntactically live at a node if there is a path to the exit of the flowgraph along which its value may be used before it is redefined.

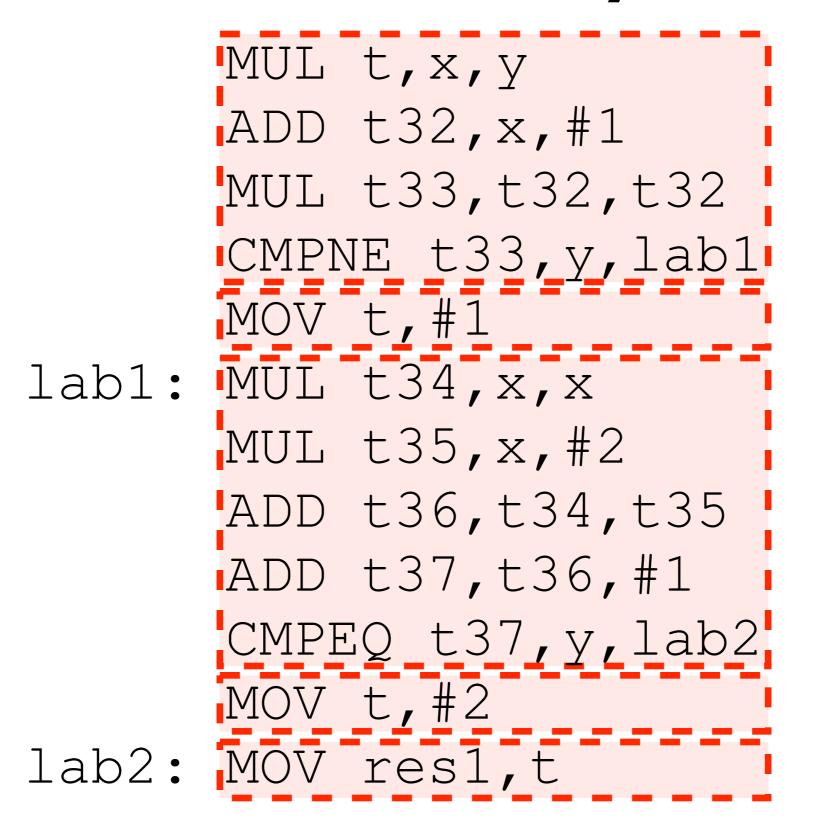
Syntactic liveness is concerned with properties of the syntactic structure of the program.

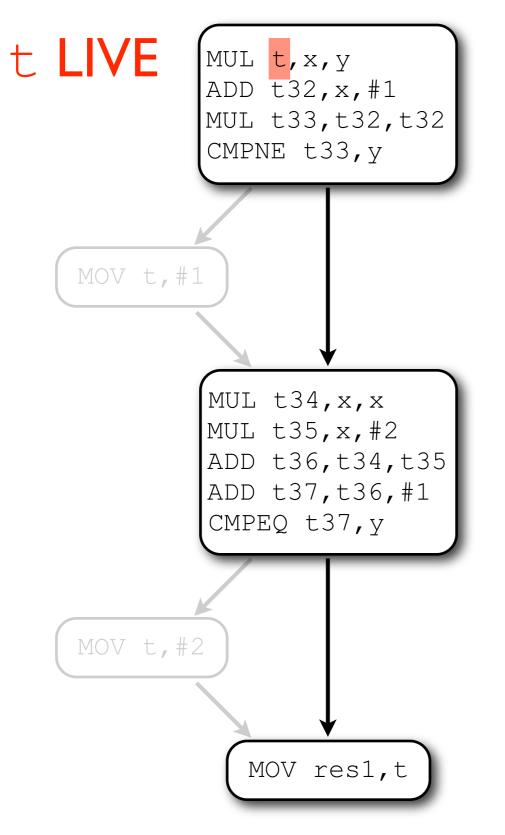
Of course, this is decidable.

So what's the difference?

Semantic vs. syntactic int t = x * y; t DEADif ((x+1)*(x+1) == v) { t = 1; if (x*x + 2*x + 1 != y) { t = 2;return t;

Semantically: one of the conditions will be true, so on every execution path t is redefined before it is returned. The value assigned by the first instruction is never used.

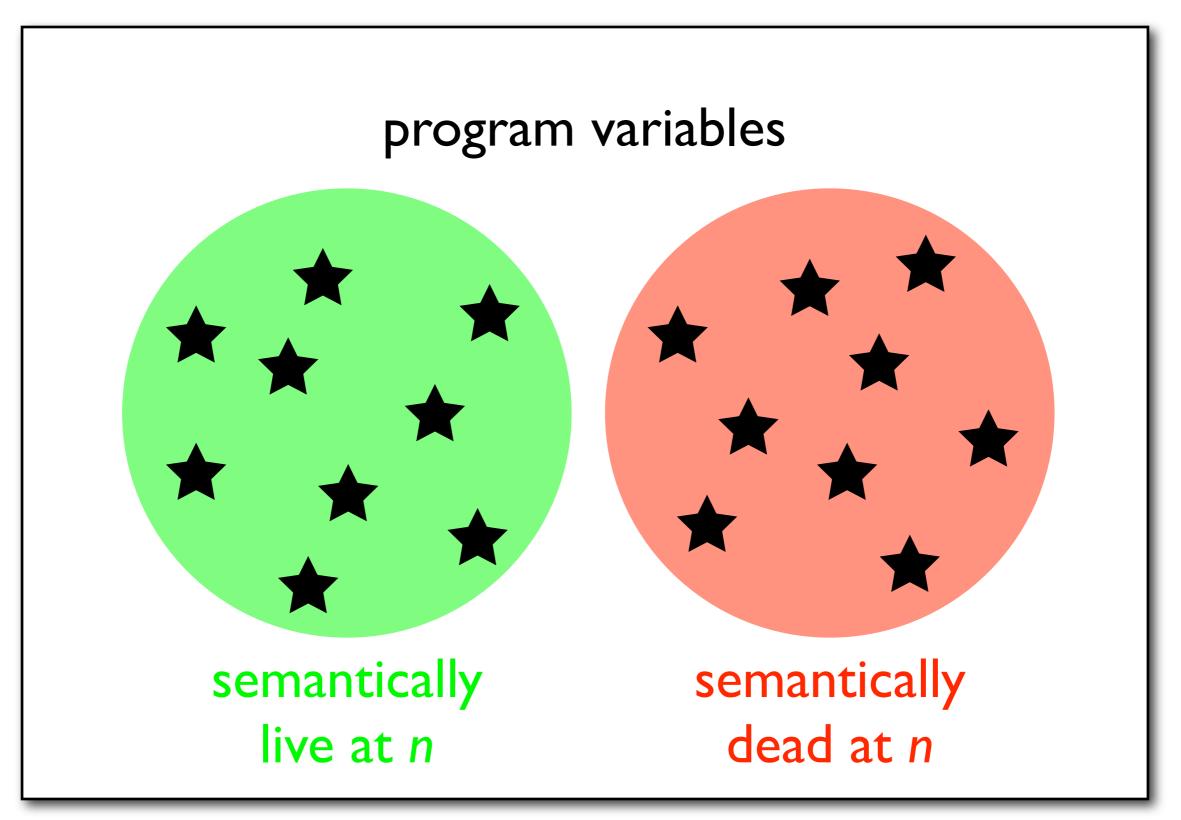


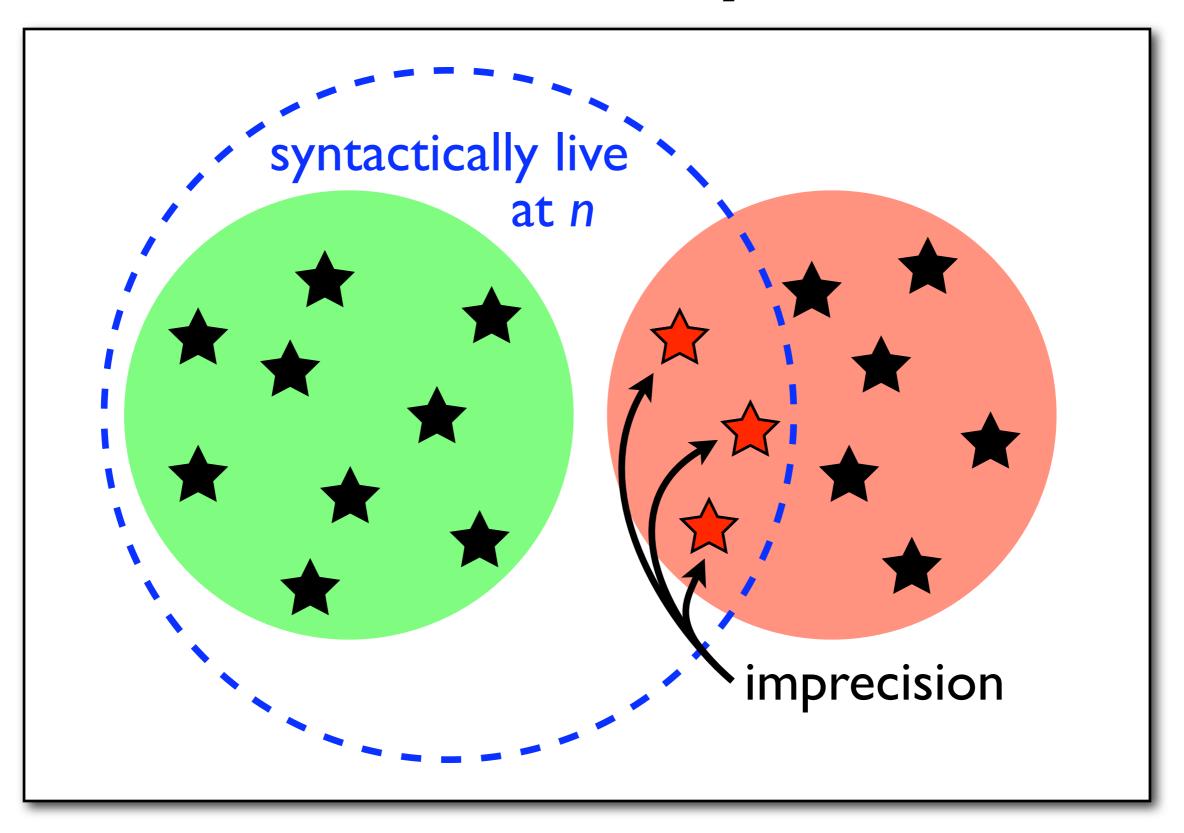


On this path through the flowgraph, t is not redefined before it's used, so t is syntactically live at the first instruction.

Note that this path never actually occurs during execution.

So, as we've seen before, syntactic liveness is a computable approximation of semantic liveness.

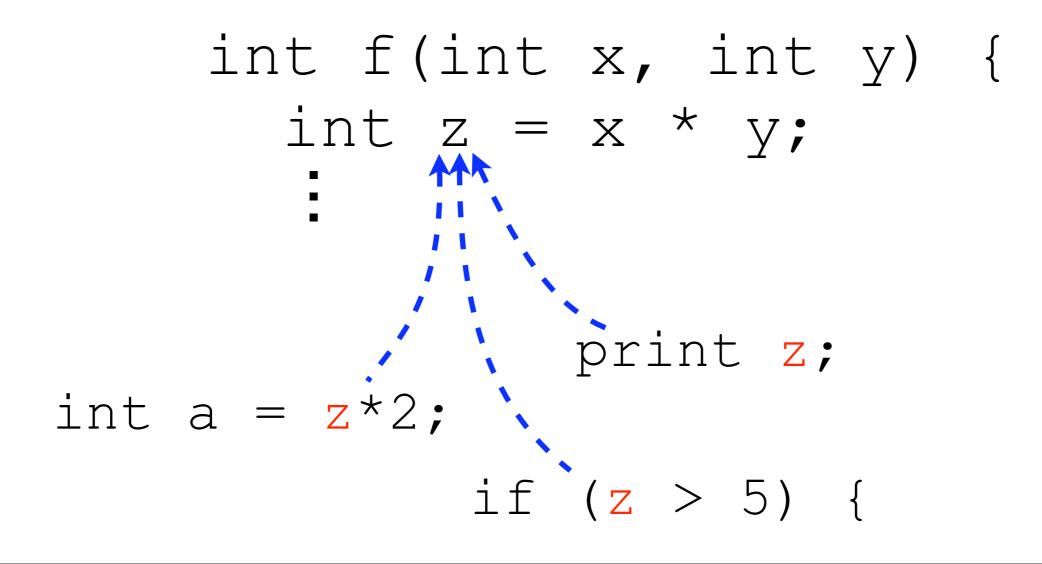




$sem-live(n) \subseteq syn-live(n)$

Using syntactic methods, we safely overestimate liveness.

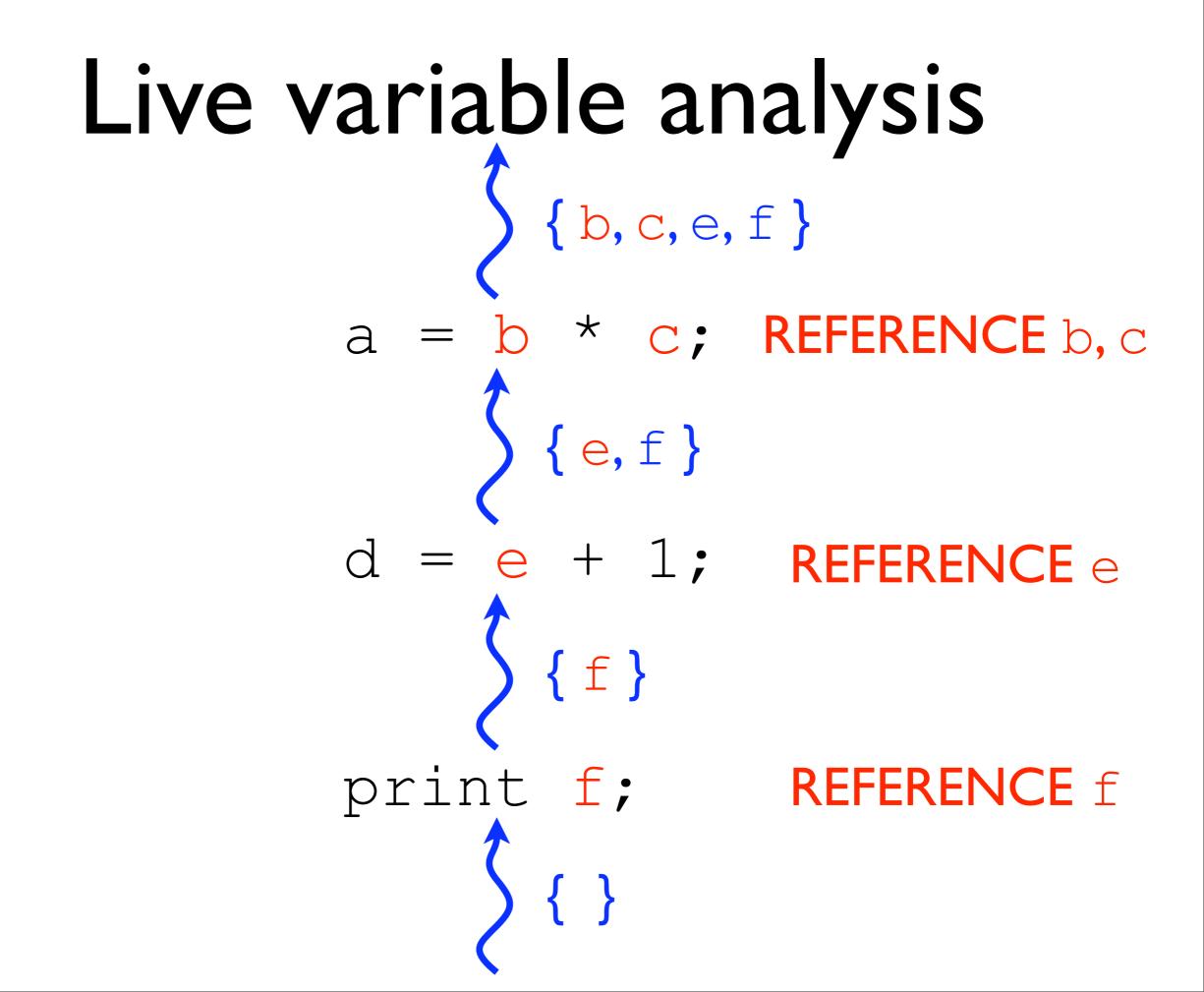
LVA is a *backwards* data-flow analysis: usage information from *future* instructions must be propagated backwards through the program to discover which variables are live.



Variable liveness flows (backwards) through the program in a continuous stream.

Each instruction has an effect on the liveness information as it flows past.

An instruction makes a variable live when it *references* (uses) it.



An instruction makes a variable dead when it *defines* (assigns to) it.

Live variable analysis = 7; **DEFINE** a a { a } b = 11; **DEFINE** b{a,b} c = 13; **DEFINE** c{a,b,c}

We can devise functions ref(n) and def(n) which give the sets of variables referenced and defined by the instruction at node n.

ref(
$$x = x + y$$
) = { x, y }
def($x = x + y$) = { x }

As liveness flows backwards past an instruction, we want to modify the liveness information by *adding* any variables which it references (they become live) and *removing* any which it defines (they become dead).

{ x, y }
ref(print x) = { x } **\$** { y }

If an instruction both references and defines variables, we must remove the defined variables before adding the referenced ones.

$${x, y, z}$$

x = x + y
 ${x, z}$

$$def(x = x + y) = \{x\}$$

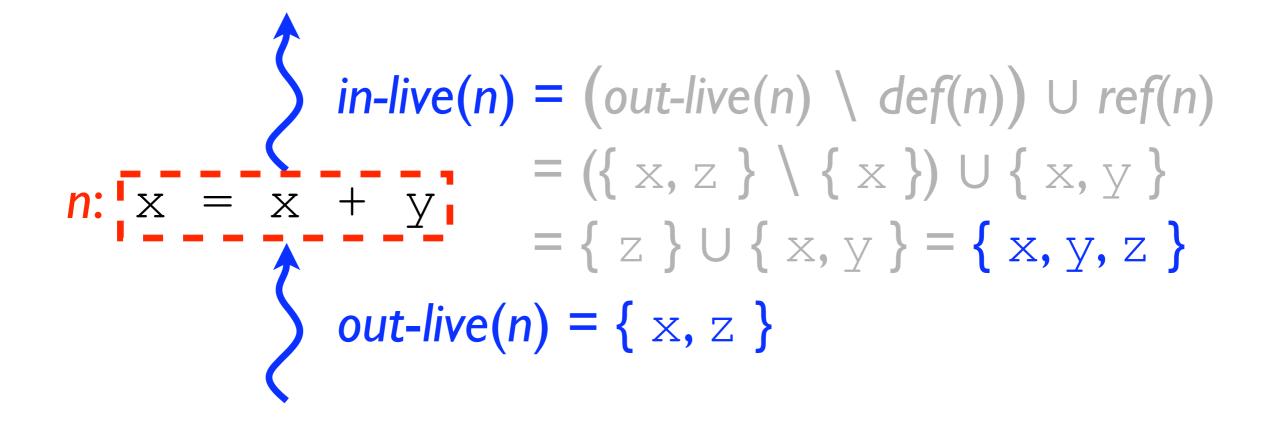
$$ref(x = x + y) = \{x, y\}$$

So, if we consider *in-live*(*n*) and *out-live*(*n*), the sets of variables which are live immediately *before* and immediately *after* a node, the following equation must hold:

$$in-live(n) = (out-live(n) \setminus def(n)) \cup ref(n)$$

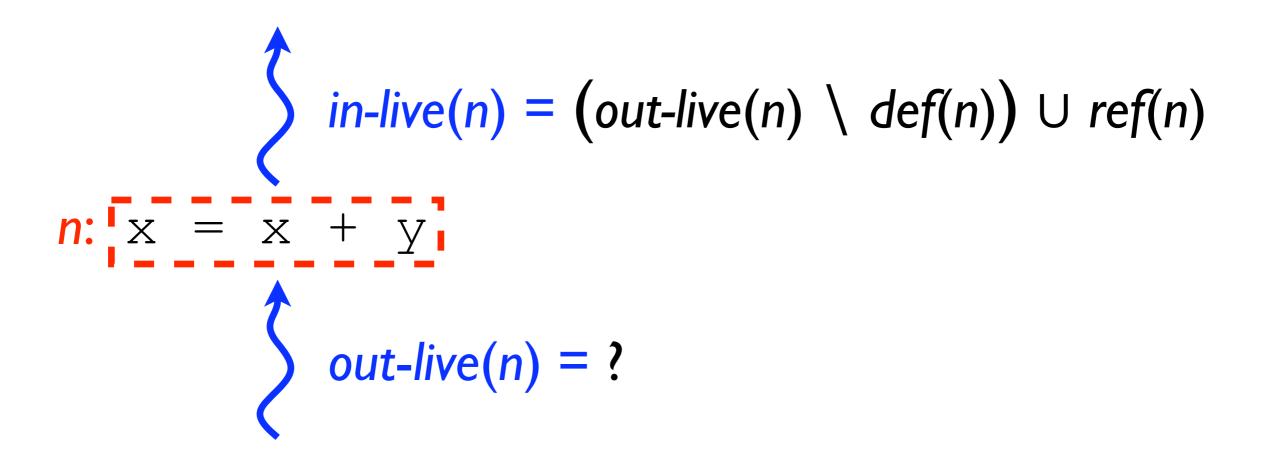
Live variable analysis

$$in-live(n) = (out-live(n) \setminus def(n)) \cup ref(n)$$



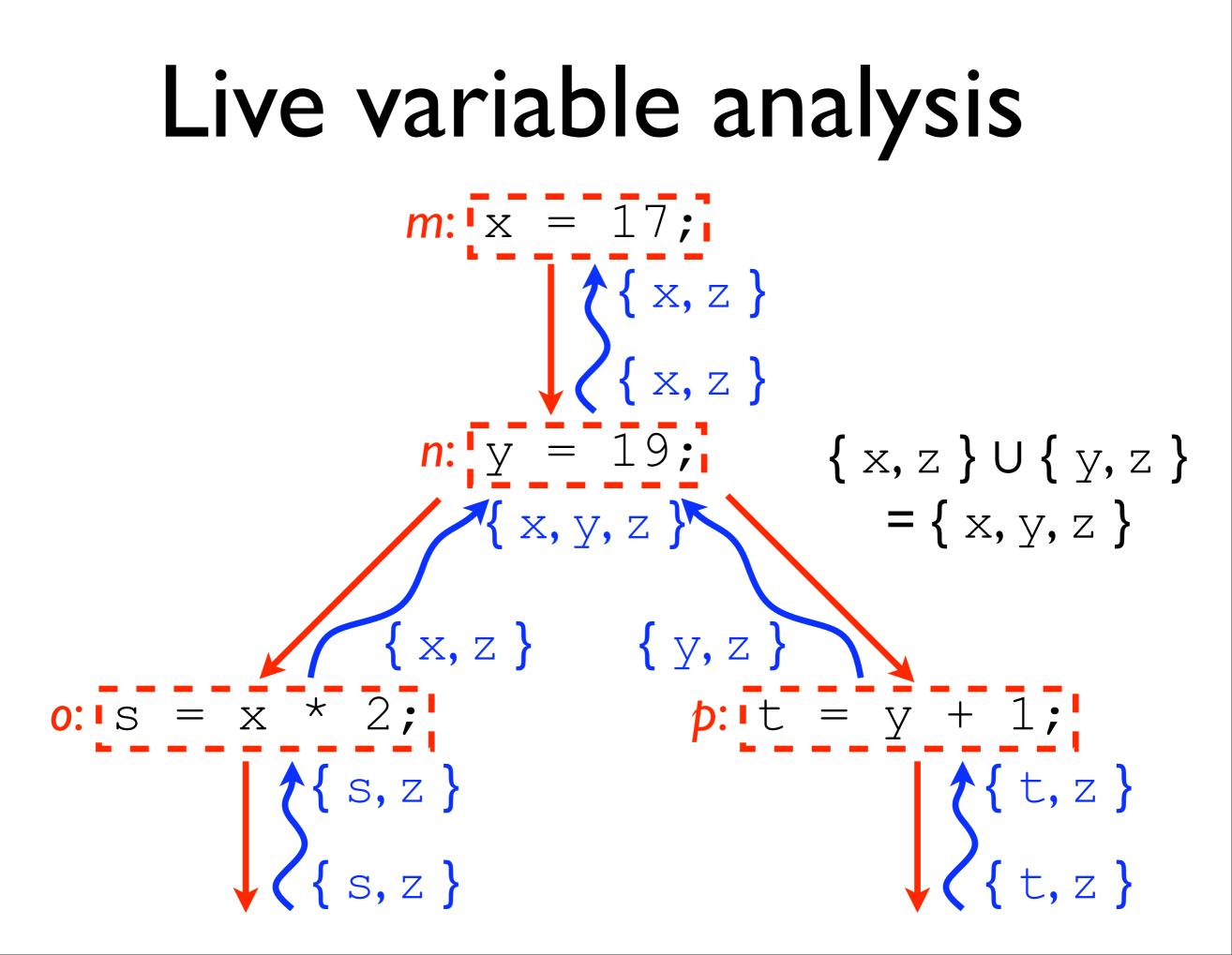
$$def(n) = \{ x \}$$
 $ref(n) = \{ x, y \}$

So we know how to calculate *in-live(n)* from the values of def(n), ref(n) and out-live(n). But how do we calculate out-live(n)?



In straight-line code each node has a unique successor, and the variables live at the exit of a node are exactly those variables live at the entry of its successor.

In general, however, each node has an arbitrary number of successors, and the variables live at the exit of a node are exactly those variables live at the entry of *any* of its successors.



So the following equation must also hold:

$$out-live(n) = \bigcup_{s \in succ(n)} in-live(s)$$

Data-flow equations

These are the *data-flow equations* for live variable analysis, and together they tell us everything we need to know about how to propagate liveness information through a program.

$$in-live(n) = \left(out-live(n) \setminus def(n)\right) \cup ref(n)$$
$$out-live(n) = \bigcup_{s \in succ(n)} in-live(s)$$

Data-flow equations

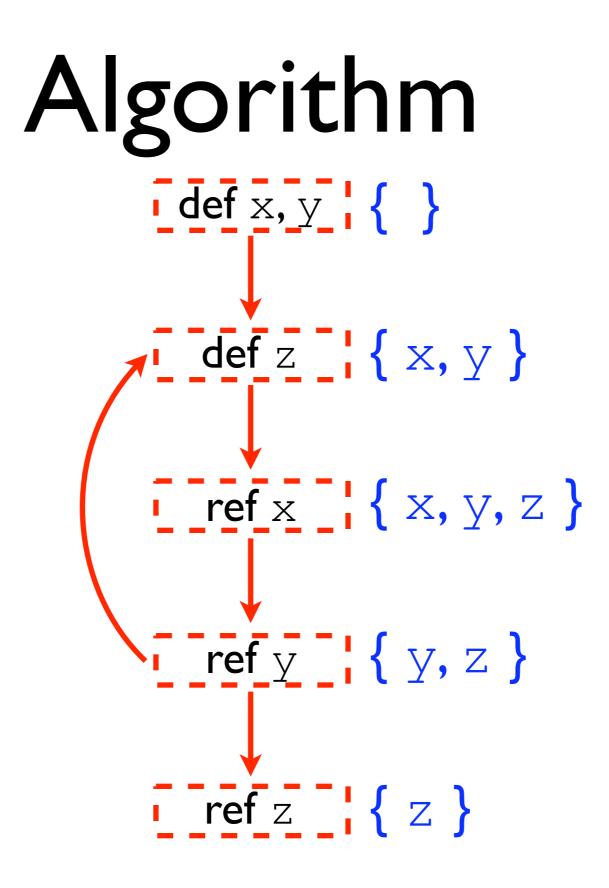
Each is expressed in terms of the other, so we can combine them to create one overall liveness equation.

$$live(n) = \left(\left(\bigcup_{s \in succ(n)} live(s) \right) \setminus def(n) \right) \cup ref(n)$$

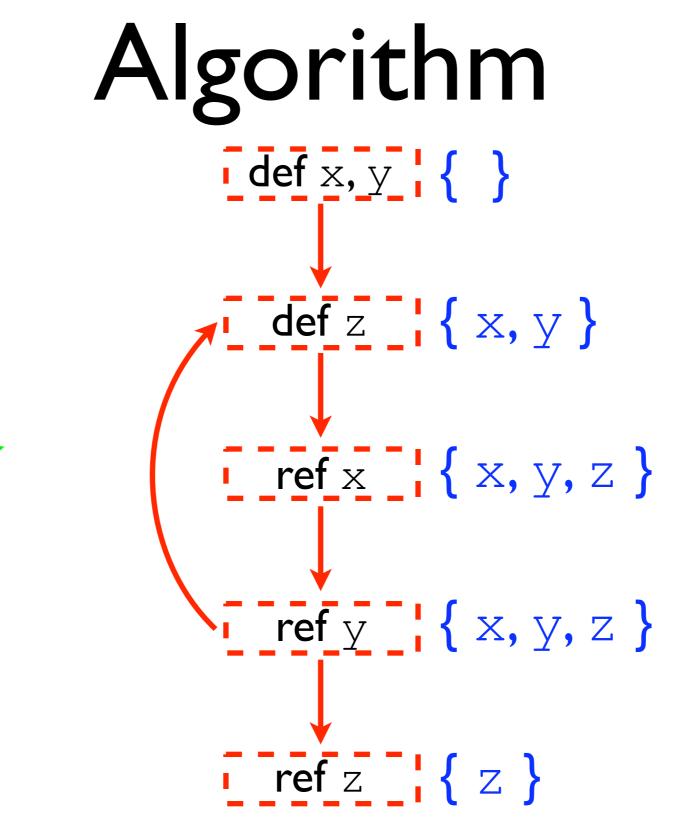
We now have a formal description of liveness, but we need an actual algorithm in order to do the analysis.

"Doing the analysis" consists of computing a value live(n) for each node n in a flowgraph such that the liveness data-flow equations are satisfied.

A simple way to solve the data-flow equations is to adopt an iterative strategy.









for i = 1 to n do live[i] := {} while (live[] changes) do for i = 1 to n do

live[i] :=
$$\left(\left(\bigcup_{s \in succ(i)} \text{live}[s] \right) \setminus def(i) \right) \cup ref(i)$$

This algorithm is guaranteed to terminate since there are a *finite* number of variables in each program and the effect of one iteration is *monotonic*.

Furthermore, although any solution to the data-flow equations is safe, this algorithm is guaranteed to give the *smallest* (and therefore most precise) solution.

(See the Knaster-Tarski theorem if you're interested.)

Implementation notes:

- If the program has n variables, we can implement each element of live[] as an n-bit value, with each bit representing the liveness of one variable.
- We can store liveness once per basic block and recompute inside a block when necessary. In this case, given a basic block *n* of instructions *i*₁, ..., *i*_k:

$$live(n) = \left(\bigcup_{s \in succ(n)} live(s)\right) \setminus def(i_k) \cup ref(i_k) \cdots \setminus def(i_1) \cup ref(i_1)$$

Safety of analysis

- Syntactic liveness safely overapproximates semantic liveness.
- The usual problem occurs in the presence of addresstaken variables (cf. labels, procedures): *ambiguous* definitions and references. For safety we must
 - overestimate ambiguous references (assume all address-taken variables are referenced) and
 - underestimate ambiguous definitions (assume no variables are defined); this increases the size of the smallest solution.

Safety of analysis

MOV x, #1 MOV y, #2 MOV z, #3MOV t32, #&x MOV t33, # & y MOV t34, # & z $def(m) = \{ \}$ *m*: STI t35, #7 ref(m) = { t 35 } n: LDI t36, t37 def(n) = { t36 } ref(n) = { t37, x, y, z }

Summary

- Data-flow analysis collects information about how data moves through a program
- Variable liveness is a data-flow property
- Live variable analysis (LVA) is a backwards data-flow analysis for determining variable liveness
- LVA may be expressed as a pair of complementary data-flow equations, which can be combined
- A simple iterative algorithm can be used to find the smallest solution to the LVA data-flow equations