

Lecture 6: Concentration Inequalities - Introduction to Martingales

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More Chernoff Bounds

Conditional Expectation



Chernoff Bounds

Remember the Chernoff Bounds from the previous lecture..

Chernoff Bounds: upper tails

Suppose X_1, \dots, X_n are independent Bernoulli random variables with parameter p_i . Let $X = X_1 + \dots + X_n$ and $\mu = \mathbf{E}[X] = \sum p_i$. Then, for any $\delta > 0$ it holds that

$$\mathbf{P}[X \geq (1 + \delta)\mu] \leq \left[\frac{e^\delta}{(1 + \delta)^{(1 + \delta)}} \right]^\mu.$$

and for $t > \mu$ it holds that

$$\mathbf{P}[X \geq t] \leq e^{-\mu} \left(\frac{e\mu}{t} \right)^t,$$



.. and the lower tails..

Chernoff Bounds: Lower Tails

Suppose X_1, \dots, X_n are independent Bernoulli random variables with parameter p_i . Let $X = X_1 + \dots + X_n$ and $\mu = \mathbf{E}[X] = \sum p_i$. Then, for any $\delta > 0$ it holds that

$$\mathbf{P}[X \leq (1 - \delta)\mu] \leq \left[\frac{e^{-\delta}}{(1 - \delta)^{1-\delta}} \right]^\mu.$$

and for any $t < \mu$

$$\mathbf{P}[X \leq t] \leq e^{-\mu} \left(\frac{e\mu}{t} \right)^t.$$



..and the nicer version!

Nicer Chernoff Bounds

Suppose X_1, \dots, X_n are independent Bernoulli random variables with parameter p_i . Let $X = X_1 + \dots + X_n$ and $\mu = \mathbf{E}[X] = \sum p_i$. Then,

- For all $t > 0$,

$$\mathbf{P}[X \geq \mathbf{E}[X] + t] \leq e^{-2t^2/n}$$

$$\mathbf{P}[X \leq \mathbf{E}[X] - t] \leq e^{-2t^2/n}$$

- For $0 < \delta < 1$,

$$\mathbf{P}[X \geq (1 + \delta)\mathbf{E}[X]] \leq \exp\left(-\frac{\delta^2\mathbf{E}[X]}{3}\right)$$

$$\mathbf{P}[X \leq (1 - \delta)\mathbf{E}[X]] \leq \exp\left(-\frac{\delta^2\mathbf{E}[X]}{2}\right)$$



Chernoff Bound: Extension to other Random Variables

- Most of the time we will use Chernoff Bounds for **sum of independent Bernoulli** random variables
- but not always
- it does not hurt to know how to derive similar bounds for other random variables

Remember the key steps:

Chernoff Bound recipe

1. Let $\lambda > 0$, then

$$\mathbf{P}[X \geq (1 + \delta)\mu] \leq e^{-\lambda(1+\delta)\mu} \mathbf{E}[e^{\lambda X}]$$

2. Compute an upper bound for $\mathbf{E}[e^{\lambda X}]$
3. Optimise the value of $\lambda > 0$.



Exercise:

- Let X be a Poisson random variable of mean μ . Prove that

$$\mathbf{E}\left[e^{\lambda X}\right] = e^{\mu(e^{\lambda}-1)}$$

and deduce that for $t \geq \mu$

$$\mathbf{P}[X \geq t] \leq e^{-\mu} \left(\frac{e\lambda}{t}\right)^t \quad \text{and} \quad \mathbf{P}[X \geq (1 + \delta)\mu] \leq e^{-\delta^2\mu},$$

and the corresponding lower tails.

- Let X be a Normal random variable of mean μ and variance σ^2 . Prove that

$$\mathbf{E}\left[e^{\lambda X}\right] = e^{\mu\lambda + \sigma^2\lambda^2/2},$$

and deduce that for $t > \mu$

$$\mathbf{P}[X \geq t] \leq e^{-(t-\mu)^2/2}.$$



Hoeffding's Extension

- Beside **sums of independent Bernoulli** Random variables, **sums of independent and bounded** random variables is very important in applications.
- Unfortunately the distribution of the X_i will be unknown or very hard to compute, thus it will be very hard to compute the moment-generating function of X_i .
- Hoeffding's Lemma helps us here

You can always consider $X' = X - \mathbf{E}[X]$

Hoeffding's Extension Lemma

Let X be a random variable with mean 0 such that $a \leq X \leq b$, then for all $\lambda \in \mathbb{R}$.

$$\mathbf{E} \left[e^{\lambda X} \right] \leq \exp \left(\frac{(b-a)^2 \lambda^2}{8} \right)$$



Chernoff-Hoeffding Bounds

Chernoff-Hoeffding's Bounds

Let X_1, \dots, X_n be independent random variable with mean μ_i such that $a_i \leq X_i \leq b_i$. Let $X = X_1 + \dots + X_n$, and let $\mu = \mathbf{E}[X] = \sum_{i=1}^n \mu_i$. Then for any $t > 0$

$$\mathbf{P}[X \geq \mu + t] \leq \exp \left[\frac{-2t^2}{\sum_{i=1}^n (b_i - a_i)^2} \right]$$

and

$$\mathbf{P}[X \leq \mu - t] \leq \exp \left[\frac{-2t^2}{\sum_{i=1}^n (b_i - a_i)^2} \right]$$

Proof:

- Let $X'_i = X_i - \mu_i$ and $X' = X'_1 + \dots, X'_n$, then $\mathbf{P}[X \geq \mu + t] = \mathbf{P}[X' \geq t]$
- $\mathbf{P}[X' \geq t] \leq e^{-\lambda t} \prod_{i=1}^n \mathbf{E} \left[e^{\lambda X'_i} \right] \leq \exp \left[-\lambda t + \frac{\lambda^2}{8} \sum_{i=1}^n (b_i - a_i)^2 \right]$
- Choose $\lambda = \frac{4t}{\sum_{i=1}^n (b_i - a_i)^2}$ to get the result.

This is not magic! you just need to optimise on λ

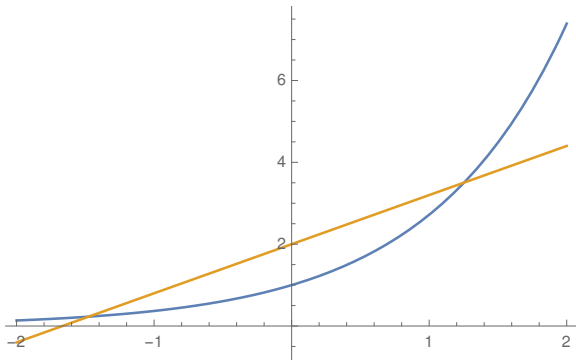


Let X be a random variable with mean 0 such that $a \leq X \leq b$, then for all $\lambda \in \mathbb{R}$.

$$\mathbf{E} \left[e^{\lambda X} \right] \leq \exp \left(\frac{(b-a)^2 \lambda^2}{8} \right)$$

Proof (for $\lambda \geq 0$):

- $f(x) = e^{\lambda x}$ is a convex function.



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$$\mathbf{E} \left[e^{\lambda X} \right] \leq \exp \left(\frac{(b-a)^2 \lambda^2}{8} \right)$$

Proof (for $\lambda \geq 0$):

1. $f(x) = e^{\lambda x}$ is a convex function.
2. As $a \leq X \leq b$, we consider the points $(a, e^{\lambda a})$ and $(b, e^{\lambda b})$
3. The straight line between those points is always above the graph of $e^{\lambda x}$
4. i.e.

$$e^{\lambda X} \leq \frac{b-X}{b-a} e^{\lambda a} + \frac{X-a}{b-a} e^{\lambda b}$$

5. Then

$$\mathbf{E} \left[e^{\lambda X} \right] \leq \frac{b e^{\lambda a}}{b-a} - \frac{a e^{\lambda b}}{b-a}$$



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6. Consider

$$\phi(\lambda) = \log \left(\frac{b e^{\lambda a}}{b-a} - \frac{a e^{\lambda b}}{b-a} \right)$$

and check that (**Exercise**)

- $\phi(0) = 0$
 - $\phi'(0) = 0$
 - $\phi''(t) \leq (b-a)^2/4$ for all $t \in \mathbb{R}$
7. For $t \geq 0$, use that $\phi'(t) = \int_0^t \phi''(x) dx \leq t(b-a)^2/4$
 8. For $t \geq 0$, use that

$$\phi(t) = \int_0^t \phi'(x) dx \leq \int_0^t x(b-a)^2/4 dx \leq t^2(b-a)^2/8$$

9. replace $t = \lambda$ for non-negative λ .



- There are several version of Chernoff-style Bounds that work for sum of independent random variables.
- The proof of all of them usually follows the same **recipe**
- Some bounds include more information about the random variables, e.g. the variance
- the limit is the amount of information we have about the random variables and our ability to manipulate/bound quantities.



Can we prove concentration of other type of random variables? Yes.. but

- There is no general tool to prove concentration beyond the basic **recipe**
- but in general it is very hard to compute moment generating functions
- It is worth trying to transform the problem into the setting of sum of independent random variable
- If everything fails.. There are a few other families of random variables for which proving concentration is doable One of them are the so-called **Martingales**



Outline

More Chernoff Bounds

Conditional Expectation



Conditional Expectation

Before talking about martingales, we need to review **conditional expectation**.

- Given two events A and B with $\mathbf{P}[A] > 0$ we define $\mathbf{P}[B|A] = \mathbf{P}[B \cap A] / \mathbf{P}[A]$.
- if $\mathbf{P}[A] = 0$, the usual convention is that $\mathbf{P}[B|A] = 0$.
- Given a discrete random variable Y , we define its conditional expectation with respect to the event A by

$$\mathbf{E}[Y|A] = \sum_b b\mathbf{P}[Y = b|A]$$

- a particular case is when the event $A = \{X = a\}$ where X is another discrete random variable. In such a case we define the function $f(a)$ by

$$f(a) = \mathbf{E}[Y|X = a],$$

- We define the conditional expectation $\mathbf{E}[Y|X]$, as the **random variable** that takes the value $\mathbf{E}[Y|X = a]$ then $X = a$, i.e. $f(X)$.



Important Remarks

- The conditional expectation of Y w.r.t a event A , $\mathbf{E}[Y|A]$ is a **deterministic number** .
- The conditional expectation of Y w.r.t a random variable X , $\mathbf{E}[Y|X]$ is a **random variable** .
- X can be a random vector (X_1, \dots, X_N) in the definition of $\mathbf{E}[Y|X]$.
- There is a definition of conditional expectation with respect to general random variables¹, but most of the results in the discrete setting extend to the continuous setting.
- The conditional expectation $\mathbf{E}[Y|X]$ is always a function of X .
- Behind conditional expectation there is the notion of **information**². The standard notion of expectation is like 'the best estimate of a random variable given no information of it', while the conditional expectation given X is like 'the best estimate of a random variable given the information of X '

¹such a definition require the understanding of Measure theory

²Measure theory, again



Conditional Expectation: two dices

Suppose we independently roll two standard 6-sided dice. Let X_1 and X_2 the observed number in the first and second dice respectively. We compute a few conditional expectations.

1. $\mathbf{E}[X_1 + X_2|X_1] = 3.5 + X_1$. Why? Because if $X_1 = a$ then

$$\begin{aligned}\mathbf{E}[X_1 + X_2|X_1 = a] &= \sum_{b=1}^{12} b\mathbf{P}[X_1 + X_2 = b|X_1 = a] \\ &= \sum_{b=1}^{12} b\mathbf{P}[X_1 + X_2 = b, X_1 = a] / \mathbf{P}[X_1 = a] \\ &= \sum_{b=1}^{12} b\mathbf{P}[X_2 = b - a, X_1 = a] / \mathbf{P}[X_1 = a] \\ X_1 \text{ indep } X_2 &= \sum_{b=1}^{12} b\mathbf{P}[X_2 = b - a] \\ &= \sum_{c=1}^6 (c + a)\mathbf{P}[X_2 = c] \\ &= 3.5 + a\end{aligned}$$



Conditional Expectation: Properties

1. $\mathbf{E}[\mathbf{E}[Y|X]] = \mathbf{E}[Y]$.
2. $\mathbf{E}[1|X] = 1$
3. **Linearity** :
 - For any constant $c \in \mathbb{R}$, $\mathbf{E}[cY|X] = c\mathbf{E}[Y|X]$
 - $\mathbf{E}[Y + Z|X] = \mathbf{E}[Y|X] + \mathbf{E}[Z|X]$
4. If X is independent of Y , then $\mathbf{E}[Y|X] = \mathbf{E}[Y]$.
5. if Y is a function of X^3 , i.e. $Y = f(X)$, then $\mathbf{E}[YZ|X] = Y\mathbf{E}[Z|X]$.
Particularly, $\mathbf{E}[X|X] = X$
6. **Tower Property**:
 - $\mathbf{E}[\mathbf{E}[X|(Z, Y)]|Y] = \mathbf{E}[X|Y]$.
7. **Jensen Inequality**:
 - if f is a convex real function, then $f(\mathbf{E}[X|Y]) \leq \mathbf{E}[f(X)|Y]$.

By using these properties, everything becomes a bit easier, e.g., our two dices example

$$\mathbf{E}[X_1 + X_2|X_1] \stackrel{p3}{=} \mathbf{E}[X_1|X_1] + \mathbf{E}[X_2|X_1] \stackrel{p5, p4}{=} X_1 + \mathbf{E}[X_2] = X_1 + 3.5$$

³measurable function



Exercise: Prove the properties

1. $\mathbf{E}[\mathbf{E}[Y|X]] = \mathbf{E}[Y]$.

Proof: e.g.

$$\begin{aligned}\sum_x \mathbf{E}[Y|X = x] \mathbf{P}[X = x] &= \sum_x \sum_y y \mathbf{P}[Y = y|X = x] \mathbf{P}[X = x] \\ &= \sum_x \sum_y y \mathbf{P}[Y = y, X = x] \\ &= \sum_y y \mathbf{P}[Y = y]\end{aligned}$$



Example: Expectation of a Geometric Random Variable

Suppose X_1, X_2, \dots , are an infinite sequence of independent Bernoulli (coins) random variables of parameter p , i.e. $\mathbf{P}[X_i = 1] = p$. Define

$G = \min\{k \geq 1 : X_k = 1\}$, which is the number of coins we have to observe until we get a head.

G has geometric distribution of parameter p . Indeed $\mathbf{P}[G = k] = p(1 - p)^{k-1}$.

The expectation of G is given by the formula

$$\mathbf{E}[G] = \sum_{k=1}^{\infty} kp(1 - p)^{k-1}$$

Let say that we forgot how to compute that type of sums...



We can compute $\mathbf{E}[G]$ by other means.

- $\mathbf{E}[G] \stackrel{p1}{=} \mathbf{E}[\mathbf{E}[G|X_1]]$
- $G = X_1 + (1 - X_1)(1 + G')$ where G' is the number of coins we need to wait to see a head after the first coin.
- $\mathbf{E}[X_1 + (1 - X_1)(1 + G')|X_1] \stackrel{p3,p5}{=} X_1 + (1 - X_1)\mathbf{E}[1 + G'|X_1]$
- G' has geometric distribution of parameter p and it is independent of X_1 . Hence

$$\mathbf{E}[1 + G'|X_1] \stackrel{p4}{=} \mathbf{E}[1 + G'] = 1 + \mathbf{E}[G]$$

- Solve

$$\mathbf{E}[G] = p + (1 - p)(1 + \mathbf{E}[G])$$



Example: Balls into Bins

Suppose we have n bins but a random number of balls, say M . Suppose M has finite expectation. **What is the expected number of balls in the first bin?**

1. Recall balls are assigned to bins uniformly at random and independent of everything
2. Let $X_i = 1$ if the ball i falls in bin 1
3. The total number of balls in bin 1 is $\sum_{i=1}^M X_i$ (recall M is a random variable, and M is independent of X_i)



$$4. \mathbf{E} \left[\sum_{i=1}^M X_i \right] \stackrel{p1}{=} \mathbf{E} \left[\mathbf{E} \left[\sum_{i=1}^M X_i \mid M \right] \right]$$

$$5. \mathbf{E} \left[\sum_{i=1}^M X_i \mid M \right] = \mathbf{E} \left[\sum_{i=1}^{\infty} X_i \mathbf{1}_{\{i \leq M\}} \mid M \right] \stackrel{p3}{=} \sum_{i=1}^{\infty} \mathbf{E} \left[X_i \mathbf{1}_{\{i \leq M\}} \mid M \right]$$

$$6. \mathbf{E} \left[X_i \mathbf{1}_{\{i \leq M\}} \mid M \right] \stackrel{p5}{=} \mathbf{1}_{\{i \leq M\}} \mathbf{E} \left[X_i \mid M \right] \stackrel{p4}{=} \mathbf{1}_{\{i \leq M\}} \mathbf{E} [X_i] = \mathbf{1}_{\{i \leq M\}} \cdot (1/n)$$

$$7. \text{Replacing 6 in 5: } \mathbf{E} \left[\sum_{i=1}^M X_i \mid M \right] = \sum_{i=1}^{\infty} (1/n) \cdot \mathbf{1}_{\{i \leq M\}}$$

$$8. \text{replacing 7 into 4: } \mathbf{E} \left[\sum_{i=1}^M X_i \right] = \sum_{i=1}^{\infty} (1/n) \cdot \mathbf{P}[i \leq M] \stackrel{5}{=} (1/n) \cdot \mathbf{E}[M]$$

⁴Technically linearity works for a finite sum, but in most cases it can be done for infinite case. We need measure theory to justify that

⁵See Q2 of the Homework Assessment

