



Interpretability in Machine Learning

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ML algorithms optimized:

- Not only for task performance, e.g. accuracy.
- But also other criteria, e.g. safety, fairness, providing the right to explanation.
- There are often trade-offs among these goals.

However,

- Accuracy can be quantified.
- Not precisely the case for the other criteria.

- Interpret means to explain or to present in understandable terms.
- In the ML context: The ability to explain or to present in understandable terms to humans.
- What constitutes an explanation? What makes some explanations better than others? How are explanations generated? When are explanations sought?
- Automatic ways to generate and, to some extent, evaluate interpretability.

Task-related:

- Global interpretability: A general understanding of how the system is working as a whole, and of the patterns present in the data.
- Local interpretability: Providing an explanation of a particular prediction or decision.

Method-related (what are the basic units of the explanation?):

- Raw features.
- Derived features that have some semantic meaning to the expert.
- Prototypes.

The nature of the data/tasks should match the type of the explanation.



Visualizing Deep Neural Network Decisions: Prediction Difference Analysis

Zintgraf, Cohen, Adel, Welling, ICLR 2017

- Visualize the response of a deep neural network to a specific input.
- For an individual classifier prediction, assign each feature a *relevance value* reflecting its contribution towards or against the predicted class.

- Looking under the hood: explaining why a decision was made.
- Can help to understand strengths and limitations of a model, help to improve it [wolves/huskies based on presence/absence of snow].



- Important for liability: why does the algorithm decide this patient has Alzheimer?
- Can lead to new insights and theories in poorly understood domains.

- Relevance of a feature x_i can be estimated by measuring how the prediction changes if the feature is *unknown*.
- The difference between $p(c|\mathbf{x})$ and $p(c|\mathbf{x}_{\setminus i})$, where $\mathbf{x}_{\setminus i}$ denotes the set of all input features except x_i .
- But how would a classifier recognize a feature as *unknown*?
 - Label the feature as unknown.
 - Retrain the classifier with the feature left out.
 - Marginalize the feature.

$$p(c|\mathbf{x}_{\setminus i}) = \sum_{x_i} p(x_i|\mathbf{x}_{\setminus i})p(c|\mathbf{x}_{\setminus i}, x_i) \quad (1)$$

Assume x_i is independent of $\mathbf{x}_{\setminus i}$

$$p(c|\mathbf{x}_{\setminus i}) \approx \sum_{x_i} p(x_i)p(c|\mathbf{x}_{\setminus i}, x_i) \quad (2)$$

Compare $p(c|\mathbf{x}_{\setminus i})$ to $p(c|\mathbf{x})$:

$$\text{odds}(c|\mathbf{x}) = \frac{p(c|\mathbf{x})}{(1-p(c|\mathbf{x}))}$$

$$\text{WE}_i(c|\mathbf{x}) = \log_2(\text{odds}(c|\mathbf{x})) - \log_2(\text{odds}(c|\mathbf{x}_{\setminus i})), \quad (3)$$

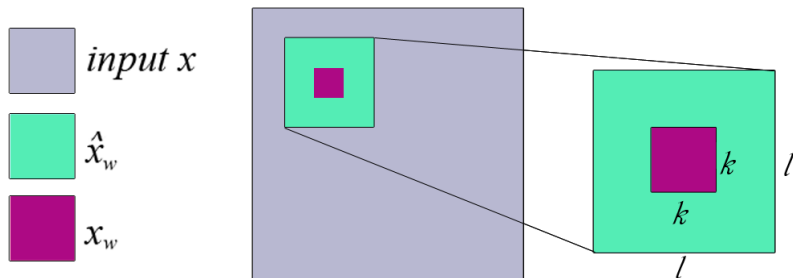
- A large prediction difference \rightarrow the feature contributed substantially to the classification.
- A small prediction difference \rightarrow the feature was not important for the decision.
- A positive value $\text{WE}_i \rightarrow$ the feature has contributed evidence *for* the class of interest.
- A negative value $\text{WE}_i \rightarrow$ the feature displays evidence *against* the class.

- A pixel depends most strongly on a small neighbourhood around it.
- The conditional of a pixel given its neighbourhood does not depend on the position of the pixel in the image.

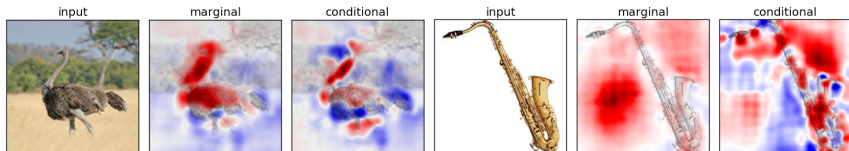
$$p(x_i | \mathbf{x}_{\setminus i}) \approx p(x_i | \hat{\mathbf{x}}_{\setminus i}) \quad (4)$$

A neural network is relatively robust to the marginalization of just one feature.

- Remove several features at once
- Connected pixels.
- patches of size $k \times k$.

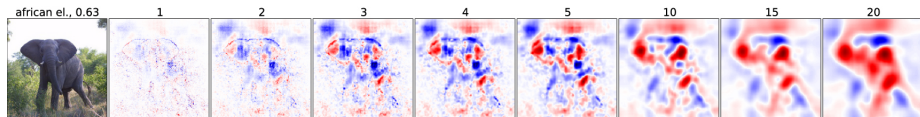


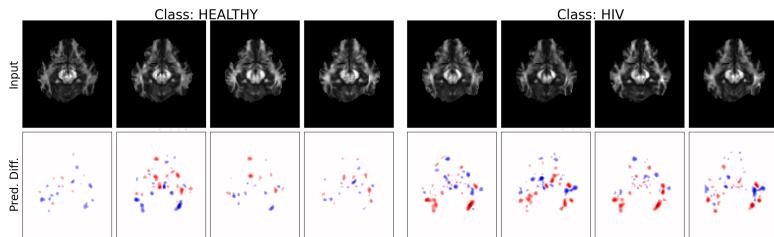
Conditional sampling

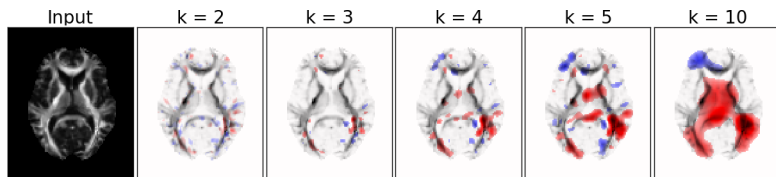


- Red: For.
- Blue: Against.

Multivariate analysis







- A method for visualizing deep neural networks by using a more powerful conditional, multivariate model.

- The visualization method shows which pixels of a specific input image are evidence for or against a node in the network.



Discovering Interpretable Representations for Both Deep Generative and Discriminative Models

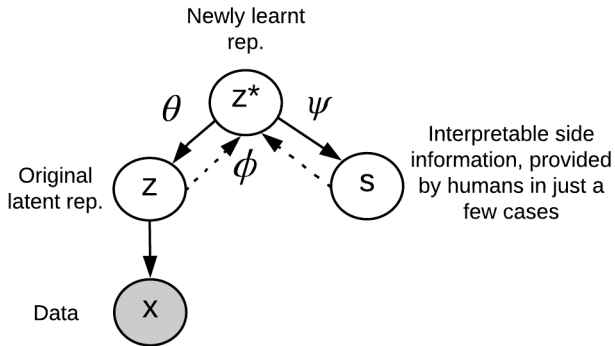
Adel, Ghahramani, Weller, ICML 2018

- Generative models seek to infer the data-generating latent space.
- This implies capturing to some extent the salient characteristics of the data.
- Generative models can potentially provide disentangled (and perhaps interpretable?) data representations (Kingma et al., 2014; Chen et al., 2016; Desjardins et al., 2012; Higgins et al., 2017; Kulkarni et al., 2015) .

“What I cannot create, I do not understand.”, Richard Feynman

We propose:

- An interpretability framework as a lens on an existing model using fully invertible transformations.
- An active learning methodology basing the acquisition function on mutual information with interpretable data attributes.
- A quantitative metric. We define interpretability as a *simple relationship to something we can understand*.
- A second interpretability framework jointly optimized for reconstruction and interpretability. This provides a novel analogy between data compression and regularization.
- Qualitative and quantitative state-of-the-art results on three datasets.



- Interactive 'human-in-the-loop' interpretability
- Choose the point with index \mathbf{j} that maximizes :

$$\begin{aligned}\hat{\mathbf{j}} &= \operatorname{argmax}_{\mathbf{j}} \mathbf{l}(\mathbf{s}_{\mathbf{j}}, \psi) = \mathbf{H}(\mathbf{s}_{\mathbf{j}}) - \mathbb{E}_{\mathbf{q}_{\phi}(\mathbf{z}^*|\mathbf{s})}[\mathbf{H}(\mathbf{s}_{\mathbf{j}}|\mathbf{z}_{\mathbf{j}}^*)] \\ &= - \int \mathbf{p}(\mathbf{s}_{\mathbf{j}}) \log \mathbf{p}(\mathbf{s}_{\mathbf{j}}) d\mathbf{s} \\ &\quad + \mathbb{E}_{\mathbf{q}_{\phi}(\mathbf{z}^*|\mathbf{s})} \left[\int \mathbf{p}_{\psi}(\mathbf{s}_{\mathbf{j}}|\mathbf{z}^*) \log \mathbf{p}_{\psi}(\mathbf{s}_{\mathbf{j}}|\mathbf{z}^*) d\mathbf{s} \right].\end{aligned}\quad (5)$$

- Choose the point possessing side information about which:
 - the model is most uncertain -maximized $\mathbf{H}(\mathbf{s}_{\mathbf{j}})$ -, but
 - in which the individual settings of the founding latent space \mathbf{z}^* are confident -minimized $\mathbb{E}_{\mathbf{q}_{\phi}(\mathbf{z}^*|\mathbf{s})}[\mathbf{H}(\mathbf{s}_{\mathbf{j}}|\mathbf{z}_{\mathbf{j}}^*)]$ -

- Interpretability refers to a *simple relationship to something we can understand*.
- A latent space is (more) interpretable if it manages to explain the relationship to salient attributes (more) simply.

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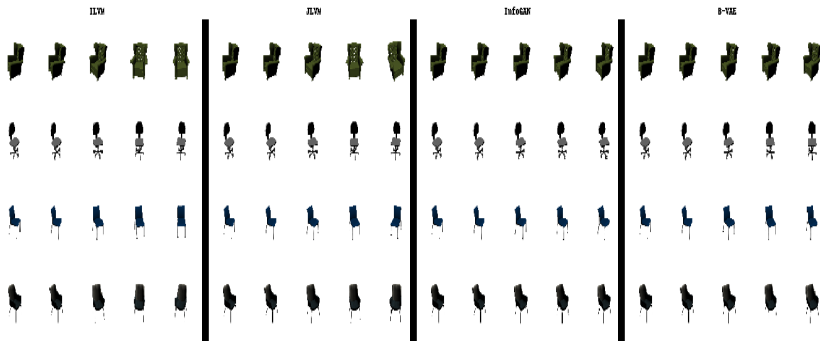
- JLVM jointly optimizes for interpretability and reconstruction fidelity.
- It is based on the information bottleneck concept:
- Make \mathbf{z}^* maximally expressive about the side information \mathbf{s} while being maximally compressive about the data \mathbf{x} . :

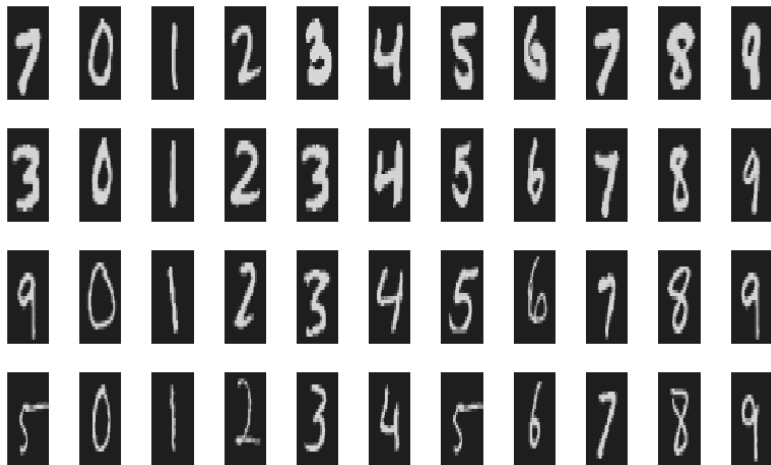
$$\mathbf{IB}(\mathbf{z}^*, \mathbf{x}, \mathbf{s}) = \mathbf{I}(\mathbf{z}^*, \mathbf{s}) - \beta \mathbf{I}(\mathbf{z}^*, \mathbf{x}).$$

- We prove that being maximally compressive about the input for the sake of interpretability is analogous to further regularization.

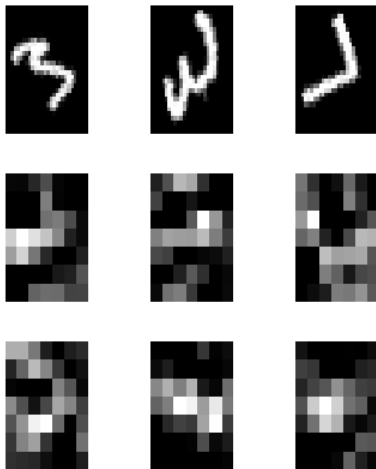
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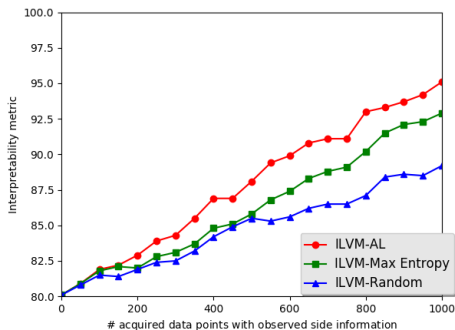




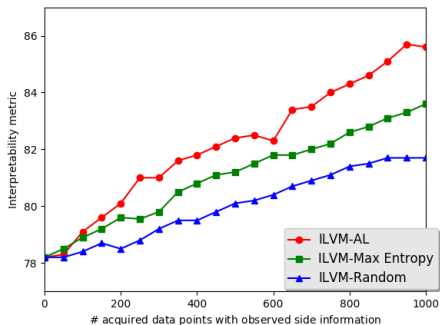
Interpretable Lens on a Hidden Layer of a Neural Network



	MNIST	SVHN	Chairs
ILVM	95.2 ± 1.3 %	85.7 ± 0.9 %	87.4 ± 1.0 %
JLVM	89.8 ± 0.9 %	90.1 ± 1.1 %	89.8 ± 1.5 %
InfoGAN	83.3 ± 1.8 %	83.9 ± 1.3 %	85.2 ± 1.4 %



(a) MNIST



(b) SVHN

- In ILVM, interpretability does not conflict with the original objective, be it reconstruction fidelity or classification accuracy.
- A strategy to bring human subjectivity into interpretability to yield interactive 'human-in-the-loop' interpretability.
- JLVM sheds light on a newly derived relationship between compression and regularization.
- The introduced frameworks achieve state-of-the-art results on three datasets.



The End