

How do we represent a set of functions $F \subseteq S \rightarrow S$?

Assume we a set Λ and a function

$$\triangleright \in \Lambda \rightarrow (S \rightarrow S).$$

We normally write $\lambda \triangleright s$ rather than $\triangleright(\lambda)(s)$. We think of $\lambda \in \Lambda$ as the index for a function $f_\lambda(s) = \lambda \triangleright s$. In this way $(\Lambda, \triangleright)$ can be used to represent the set of functions

$$F = \{f_\lambda \mid \lambda \in \Lambda\}.$$

Indexed Algebra of Monoid Endomorphisms (IAME)

Let $(S, \oplus, \bar{0})$ be a commutative and idempotent monoid.

A (left) IAME $(S, \oplus, (\Lambda, \triangleright), \bar{0})$

- $\forall \lambda \in \Lambda, \lambda \triangleright \bar{0} = \bar{0}$
- $\exists \lambda \in \Lambda, \forall s \in S, \lambda \triangleright s = s$
- $\exists \lambda \in \Lambda, \forall s \in S, \lambda \triangleright s = \bar{0}$
- $\forall \lambda \in \Lambda, \forall n, m \in S, \lambda \triangleright (n \oplus m) = (\lambda \triangleright n) \oplus (\lambda \triangleright m)$

When we need closure? If needed, it would be

$$\forall \lambda_1, \lambda_2 \in \Lambda, \exists \lambda_3 \in \Lambda, \forall s \in S, \lambda_3 \triangleright s = \lambda_1 \triangleright (\lambda_2 \triangleright s)$$

But this does not appear to be very useful ...

IAME of Matrices

Given a left IAME $(S, \oplus, (L, \triangleright), \bar{0})$ define the left IAME of matrices

$$(\mathbb{M}_n(S), \oplus, (\mathbb{M}_n(L), \triangleright), \mathbf{J}).$$

For all i, j we have $\mathbf{J}(i, j) = \bar{0}$. For $\mathbf{A} \in \mathbb{M}_n(L)$ and $\mathbf{B}, \mathbf{C} \in \mathbb{M}_n(S)$ define

$$(\mathbf{B} \oplus \mathbf{C})(i, j) \equiv \mathbf{B}(i, j) \oplus \mathbf{C}(i, j)$$

$$(\mathbf{A} \triangleright \mathbf{B})(i, j) \equiv \bigoplus_{1 \leq q \leq n} \mathbf{A}(i, q) \triangleright \mathbf{B}(q, j)$$

Solving (some) equations. Left version here ...

We will be interested in solving for \mathbf{L} equations of the form

$$\mathbf{L} = (\mathbf{A} \triangleright \mathbf{L}) \oplus \mathbf{B}$$

Let

$$\begin{aligned} \mathbf{A} \triangleright^0 \mathbf{B} &= \mathbf{B} \\ \mathbf{A} \triangleright^{k+1} \mathbf{B} &= \mathbf{A} \triangleright (\mathbf{A} \triangleright^k \mathbf{B}) \end{aligned}$$

and

$$\mathbf{A} \triangleright^{(k)} \mathbf{B} = \mathbf{A} \triangleright^0 \mathbf{B} \oplus \mathbf{A} \triangleright^1 \mathbf{B} \oplus \mathbf{A} \triangleright^2 \mathbf{B} \oplus \dots \oplus \mathbf{A} \triangleright^k \mathbf{B}$$

$$\mathbf{A} \triangleright^* \mathbf{B} = \mathbf{A} \triangleright^0 \mathbf{B} \oplus \mathbf{A} \triangleright^1 \mathbf{B} \oplus \mathbf{A} \triangleright^2 \mathbf{B} \oplus \dots \oplus \mathbf{A} \triangleright^k \mathbf{B} \oplus \dots$$

Key result (again)

q stability

If there exists a q such that for all \mathbf{B} , $\mathbf{A} \triangleright^{(q)} \mathbf{B} = \mathbf{A} \triangleright^{(q+1)} \mathbf{B}$, then \mathbf{A} is q -stable. Therefore, $\mathbf{A} \triangleright^* \mathbf{B} = \mathbf{A} \triangleright^{(q)} \mathbf{B}$.

Theorem

If \mathbf{A} is q -stable, then $\mathbf{L} = \mathbf{A} \triangleright^* (\mathbf{B})$ solves the equation

$$\mathbf{L} = (\mathbf{A} \triangleright \mathbf{L}) \oplus \mathbf{B}.$$

Example

$$\begin{aligned} \text{TwoLevels}((\mathbf{S}, \oplus_{\mathbf{S}}, (\Lambda_{\mathbf{S}}, \triangleright_{\mathbf{S}})), (\mathbf{T}, \oplus_{\mathbf{T}}, (\Lambda_{\mathbf{S}}, \triangleright_{\mathbf{S}}))) \\ \equiv \\ (\mathbf{S} \uplus \mathbf{T}, \oplus, (\Lambda_{\mathbf{S}} \times \Lambda_{\mathbf{T}}, \triangleright)) \end{aligned}$$

where

$\oplus \equiv \oplus_{\mathbf{S}} + \oplus_{\mathbf{T}}$ over $\mathbf{S} \uplus \mathbf{T}$ is defined as

$$\begin{aligned} \text{inl}(\mathbf{s}) \oplus \text{inl}(\mathbf{s}') &\equiv \text{inl}(\mathbf{s} \oplus_{\mathbf{S}} \mathbf{s}') \\ \text{inr}(\mathbf{t}) \oplus \text{inr}(\mathbf{t}') &\equiv \text{inr}(\mathbf{t} \oplus_{\mathbf{T}} \mathbf{t}') \\ \text{inl}(\mathbf{s}) \oplus \text{inr}(\mathbf{t}) &\equiv \text{inl}(\mathbf{s}) \\ \text{inr}(\mathbf{t}) \oplus \text{inl}(\mathbf{s}) &\equiv \text{inl}(\mathbf{s}) \end{aligned}$$

$\triangleright \in (\Lambda_{\mathbf{S}} \times \Lambda_{\mathbf{T}}) \rightarrow ((\mathbf{S} \uplus \mathbf{T}) \rightarrow (\mathbf{S} \uplus \mathbf{T}))$ is defined as

$$\begin{aligned} (\lambda_{\mathbf{S}}, \lambda_{\mathbf{T}}) \triangleright \text{inl}(\mathbf{s}) &\equiv \text{inl}(\lambda_{\mathbf{S}} \triangleright_{\mathbf{S}} \mathbf{s}) \\ (\lambda_{\mathbf{S}}, \lambda_{\mathbf{T}}) \triangleright \text{inr}(\mathbf{t}) &\equiv \text{inr}(\lambda_{\mathbf{T}} \triangleright_{\mathbf{T}} \mathbf{t}) \end{aligned}$$

