

# Concurrent systems

Lecture 1: Introduction to concurrency, threads,  
and mutual exclusion

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(With thanks to Dr Robert N.M. Watson  
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# Concurrent and distributed systems

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- One course, two parts
  - 8 lectures on concurrent systems
  - 8 further lectures of distributed systems
- Similar interests and concerns:
  - **Scalability** given parallelism and distributed systems
  - Mask local or distributed **communications latency**
  - Importance in observing (or enforcing) **execution orders**
  - **Correctness** in the presence of concurrency (+debugging)
- Important differences
  - Underlying primitives: **shared memory** vs. **message passing**
  - Distributed systems experience **communications failure**
  - Distributed systems (may) experience **unbounded latency**
  - (Further) difficulty of **distributed time**

# Concurrent systems outline

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1. Introduction to concurrency, threads, and mutual exclusion
2. More mutual exclusion, semaphores, producer-consumer, and MRSW
3. CCR, monitors, concurrency in practice
4. Safety and liveness
5. Concurrency without shared data; transactions
6. Further transactions
7. Crash recovery; lock free programming; TM
8. Concurrent systems case study: FreeBSD Kernel

# Recommended reading

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- “Operating Systems, Concurrent and Distributed Software Design“, Jean Bacon and Tim Harris, Addison-Wesley 2003
- “Modern Operating Systems“, (3<sup>rd</sup> Ed), Andrew Tanenbaum, Prentice-Hall 2007
- “Java Concurrency in Practice“, Brian Goetz and others, Addison-Wesley 2006

Throughout the term, I will suggest you look in Bacon and Harris for more detailed explanations of algorithms, as I can only present sketches in lecture.

# What is concurrency?

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- Computers appear to do many things at once
  - E.g. running multiple programs on your laptop
  - E.g. writing back data buffered in memory to the hard disk while the program(s) continue to execute
- In the first case, this may actually be an illusion
  - E.g. processes **time sharing** a single CPU
- In the second, there is **true parallelism**
  - E.g. Direct Memory Access (DMA) transfers data between memory and I/O devices (e.g., NIC, SATA) at the same time as the CPU executes code
  - E.g., two CPUs execute code at the same time
- In both cases, we have a **concurrency**
  - Many things are occurring “at the same time”

# In this course we will

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- Investigate concurrency in computer systems
  - Processes, threads, interrupts, hardware
- Consider how to control concurrency
  - Mutual exclusion (locks, semaphores), condition synchronization, lock-free programming
- Learn about deadlock, livelock, priority inversion
  - And prevention, avoidance, detection, recovery
- See how abstraction can provide support for correct & fault-tolerant concurrent execution
  - Transactions, serialisability, concurrency control
- Explore a detailed concurrent software case study
- Later, we will extend these ideas to distributed systems

# Recall: Processes and threads

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- **Processes** are instances of programs in execution
  - OS unit of protection & resource allocation
  - Has a virtual **address space**; and one or more threads
- **Threads** are entities managed by the **scheduler**
  - Represents an individual execution context
  - A thread control block (TCB) holds the saved context (registers, including stack pointer), scheduler info, etc
- Threads run in the **address spaces** of their process
  - (and also in the kernel address space on behalf of user code)
- **Context switches** occur when the OS saves the state of one thread and restores the state of another
  - If a switch is between threads in different processes, then process state is also switched – e.g., the address space

# Concurrency with a single CPU (1)

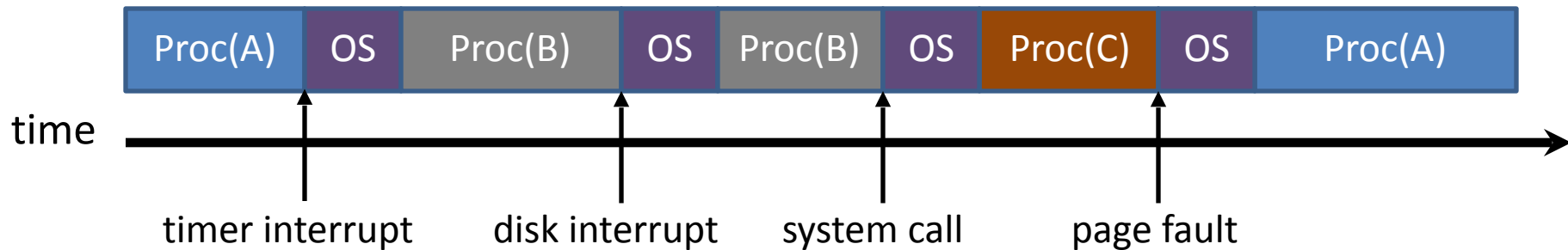
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- **Process / OS concurrency**
  - Process X runs for a while (until **blocks** or **interrupted**)
  - OS runs for a while (e.g. does some TCP processing)
  - Process X resumes where it left off...
- **Inter-process concurrency**
  - Process X runs for a while; then OS; then Process Y; then OS; then Process Z; etc
- **Intra-process concurrency**
  - Process X has multiple threads X1, X2, X3, ...
  - X1 runs for a while; then X3; then X1; then X2; then ...



# Concurrency with a single CPU (2)

- With just one CPU, can think of concurrency as **interleaving** of different executions, e.g.



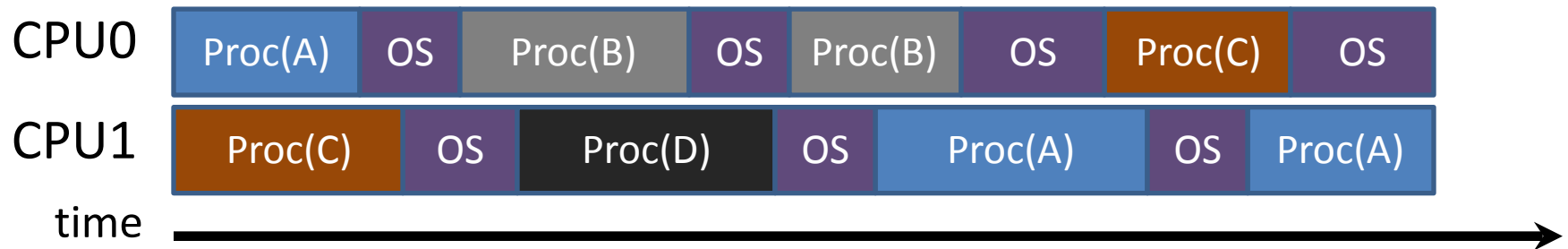
- Exactly where execution is interrupted and resumed is not usually known in advance...
  - this makes concurrency challenging!
- Generally should assume worst case behavior

Non-deterministic or so complex as to be unpredictable

# Concurrency with multiple processors

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- Many modern systems have multiple CPUs
  - And even if don't, have other processing elements
- Hence things can occur in parallel, e.g.



- Notice that the OS runs on both CPUs: tricky!
- More generally can have different threads of the same process executing on different CPUs too

# What might this code do?

```
#define NUMTHREADS 4
char *threadstr = "Thread";
```

```
void threadfn(int threadnum) {
    sleep(rand(2)); // Sleep 0 or 1 sec
    printf("%s %d\n", threadstr, threadnum);
}
```

```
void main(void) {
    threadid_t threads[NUMTHREADS];
    int i;

    for (i = 0; i < NUMTHREADS; i++)
        threads[i] = thread_create(thr

    for (i = 0; i < NUMTHREADS; i++)
        thread_join(threads[i]);
}
```

Global variables are shared by all threads

Each thread has its own local variables

main() is called once at startup

Additional threads are started explicitly

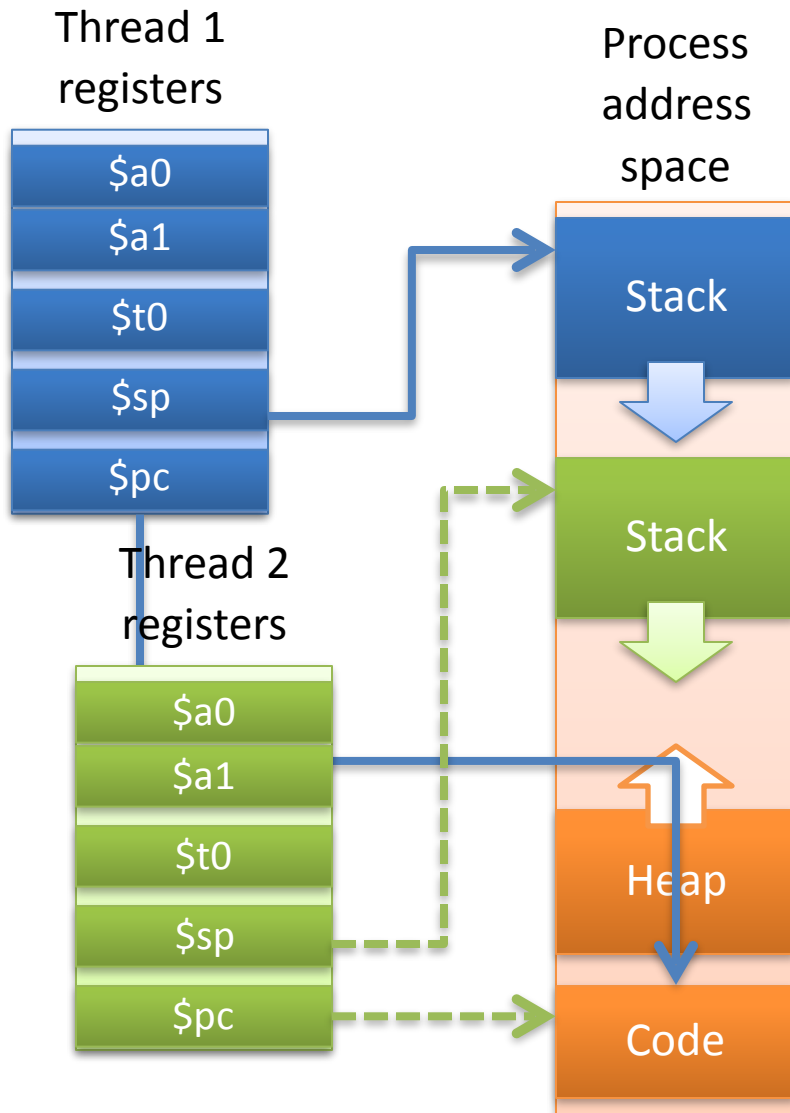
What orders could the `printf`s run in?

# Possible orderings of this program

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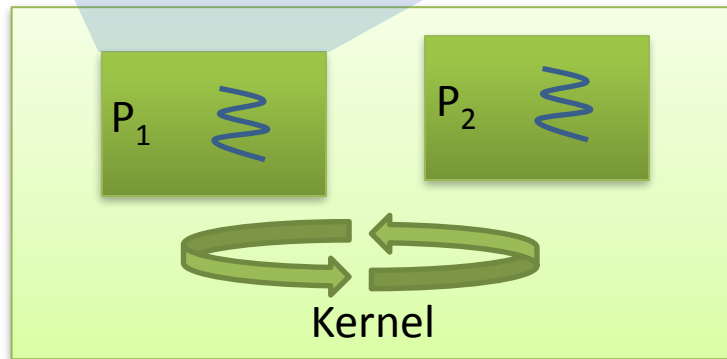
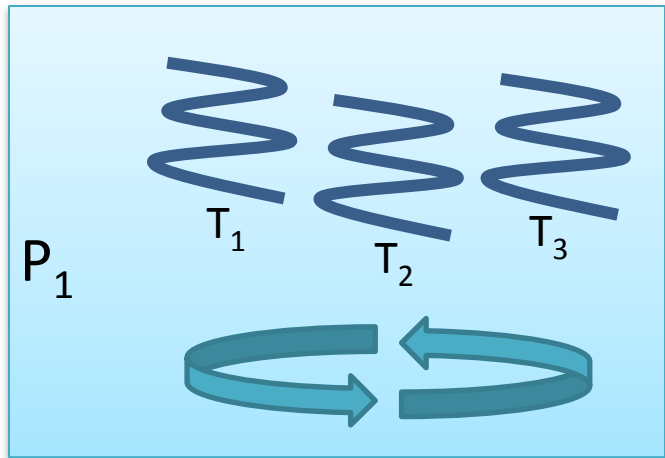
- What order could the **printf()**s occur in?
- Two sources of non-determinism in example:
  - **Program non-determinism**: Threads randomly sleep 0 or 1 seconds before printing
  - **Thread scheduling non-determinism**: Arbitrary order for unprioritised, concurrent wakeups, preemptions
- There are 4! (factorial) valid permutations
  - Assuming printf() is **indivisible**
  - Is printf() indivisible? Maybe.
- Even more potential **timings** of **printf()**s

# Multiple threads within a process



- A single-threaded process has **code**, a **heap**, a **stack**, **registers**
- Additional threads have their own registers and stacks
  - Per-thread **program counters** (\$pc) allow execution flows to differ
  - Per-thread **stack pointers** (\$sp) allow call stacks, local variables to differ
- Heap and code (+**global variables**) are shared between all threads
- Access to another thread's stack is possible in some languages – but deeply discouraged!

# 1:N - user-level threading

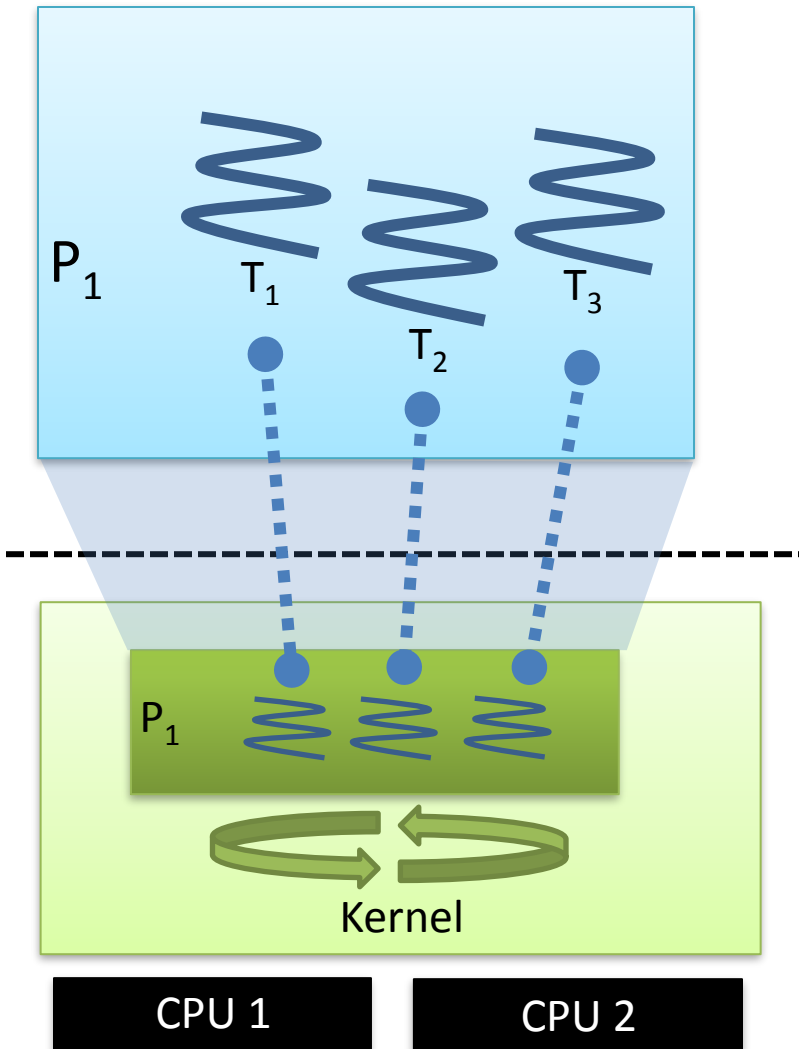


CPU 1

CPU 2

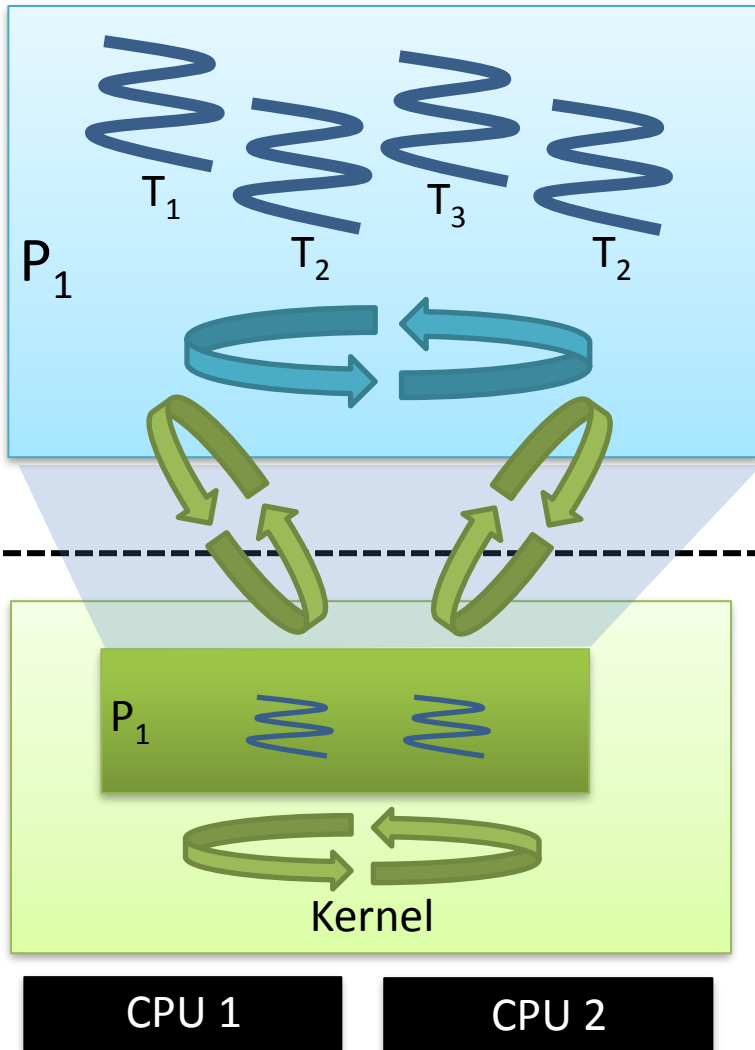
- Kernel only knows about (and schedules) processes
- A userspace library implements threads, context switching, scheduling, synchronisation, ...
  - E.g., the JVM or a threading library
- Advantages
  - Lightweight creation/termination + context switch; application-specific scheduling; OS independence
- Disadvantages
  - Awkward to handle blocking system calls or page faults, preemption; cannot use multiple CPUs
- Very early 1990s!

# 1:1 - kernel-level threading



- Kernel provides threads directly
  - By default, a process has one thread...
  - ... but can create more via system calls
- Kernel implements threads, thread context switching, scheduling, etc.
- Userspace thread library **1:1** maps **user threads** into **kernel threads**
- Advantages:
  - Handles preemption, blocking syscalls
  - Straightforward to use multiple CPUs
- Disadvantages:
  - Higher overhead (trap to kernel); less flexible; less portable
- Model of choice across major OSes
  - Windows, Linux, MacOS, FreeBSD, Solaris, ...

# M:N - hybrid threading



- Best of both worlds?
  - M:N threads, scheduler activations, ...
- Kernel exposes a smaller number (M) of activations – typically 1:1 with CPUs
- Userspace schedules a larger number (N) of threads onto available activations
  - Kernel **upcalls** when a thread blocks, returning the activation to userspace
  - Kernel **upcalls** when a thread wakes up, userspace schedules it on an activation
  - Kernel controls maximum parallelism by limiting number of activations
- Removed from most OSes – why?
- Now: **Virtual Machine Monitors (VMMs)**
  - Each **Virtual CPU (VCPU)** is an activation
- Reappears in concurrency frameworks
  - E.g., Apple's Grand Central Dispatch (GCD)



# Advantages of concurrency

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- Allows us to overlap computation and I/O on a single machine
- Can simplify code structuring and/or improve responsiveness
  - E.g. one thread redraws the GUI, another handles user input, and another computes game logic
  - E.g. one thread per HTTP request
  - E.g. background GC thread in JVM/CLR
- Enables the seamless (?!) use of multiple CPUs – greater performance through parallel processing

# Concurrent systems

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- In general, have some number of processes...
  - ... each with some number of threads ...
  - ... running on some number of computers...
  - ... each with some number of CPUs.
- For this half of the course we'll focus on a single computer running a multi-threaded process
  - most problems & solutions generalize to multiple processes, CPUs, and machines, but more complex
  - (we'll look at distributed systems later in the term)
- Challenge: threads will access shared resources concurrently via their common address space

# Example: Housemates Buying Beer

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- Thread 1 (person 1)
  1. Look in fridge
  2. If no beer, go buy beer
  3. Put beer in fridge
- Thread 2 (person 2)
  1. Look in fridge
  2. If no beer, go buy beer
  3. Put beer in fridge
- In most cases, this works just fine...
  - But if both people look (step 1) before either refills the fridge (step 3)... we'll end up with too much beer!
  - Obviously more worrying if “look in fridge” is “check reactor”, and “buy beer” is “toggle safety system” ;-)

# Solution #1: Leave a Note

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- Thread 1 (person 1)
  1. Look in fridge
  2. If no beer & no note
    1. Leave note on fridge
    2. Go buy beer
    3. Put beer in fridge
    4. Remove note
- Thread 2 (person 2)
  1. Look in fridge
  2. If no beer & no note
    1. Leave note on fridge
    2. Go buy beer
    3. Put beer in fridge
    4. Remove note
- Probably works for human beings...
  - But computers are stooopid!
- Can you see the problem?

# Non-Solution #1: Leave a Note

---

```
// thread 1
beer = checkFridge();
if(!beer) {
    if(!note) {
        note = 1;
        buyBeer();
        note = 0;
    }
}
```

```
// thread 2
beer = checkFridge();
if(!beer) {
    if(!note) {
        note = 1;
        buyBeer();
        note = 0;
    }
}
```

- Easier to see with pseudo-code...

# Non-Solution #1: Leave a Note

---

```
// thread 1
beer = checkFridge();
if(!beer) {
  if(!note) {

    note = 1;
    buyBeer();
    note = 0;

  }
}
```

context switch

context switch

```
// thread 2
beer = checkFridge();
if(!beer) {
  if(!note) {
    note = 1;
    buyBeer();
    note = 0;
  }
}
```

- Easier to see with pseudo-code...

# Non-Solution #1: Leave a Note

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- Of course this won't happen all the time
  - Need threads to interleave in the just the right way (or just the wrong way ;-)
- Unfortunately code that is 'mostly correct' is much worse than code that is 'mostly wrong'!
  - Difficult to catch in testing, as occurs rarely
  - May even go away when running under debugger
    - e.g. only context switches threads when they block
    - (such bugs are sometimes called [Heisenbugs](#))

# Critical Sections & Mutual Exclusion

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- The high-level problem here is that we have two threads trying to solve the same problem
  - Both execute buyBeer() concurrently
  - Ideally want only one thread doing that at a time
- We call this code a **critical section**
  - A piece of code which should never be concurrently executed by more than one thread
- Ensuring this involves **mutual exclusion**
  - If one thread is executing within a critical section, all other threads are prohibited from entering it



# Achieving Mutual Exclusion

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- One way is to let only one thread ever execute a particular critical section – e.g. a nominated beer buyer – but this restricts concurrency
- Alternatively our (broken) solution #1 was trying to provide mutual exclusion via the note
  - Leaving a note means “I’m in the critical section”;
  - Removing the note means “I’m done”
  - But, as we saw, it didn’t work ;-)
- This was because we could experience a context switch between reading ‘note’, and setting it

# Non-Solution #1: Leave a Note

```
// thread 1
beer = checkFridge();
if(!beer) {
  if(!note) {
```

We decide to enter the critical section here...

```
    note = 1;
    buyBeer();
    note = 0;
```

context switch

But only mark the fact here ...

context switch

```
// thread 2
beer = checkFridge();
if(!beer) {
  if(!note) {
    note = 1;
    buyBeer();
    note = 0;
```

These problems are referred to as race conditions in which multiple threads “race” with one another during conflicting access to shared resources

# Atomicity

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- What we want is for the checking of note and the (conditional) setting of note to happen without any other thread being involved
  - We don't care if another thread reads it after we're done; or sets it before we start our check
  - But once we start our check, we want to continue without any interruption
- If a sequence of operations (e.g. read-and-set) occur as if one operation, we call them **atomic**
  - Since **indivisible** from the point of view of the program
- An atomic **read-and-set** operation is sufficient for us to implement a correct beer program

# Solution #2: Atomic Note

---

```
// thread 1
beer = checkFridge();
if(!beer) {
    if(read-and-set(note)) {
        buyBeer();
        note = 0;
    }
}
```

```
// thread 2
beer = checkFridge();
if(!beer) {
    if(read-and-set(note)) {
        buyBeer();
        note = 0;
    }
}
```

- `read-and-set(&address)` **atomically** checks the value in memory and iff it is zero, sets it to one
  - returns 1 iff the value was changed from 0 -> 1
- This prevents the behavior we saw before, and is sufficient to implement a correct program...
  - although this is not that program :-)

# Non-Solution #2: Atomic Note

---

```
// thread 1
beer = checkFridge();
if(!beer) {
```

```
    if(read-and-set(note)) {
        buyBeer();
        note = 0;
    }
}
```

context switch

```
// thread 2
```

```
beer = checkFridge();
if(!beer) {
    if(read-and-set(note)) {
        buyBeer();
        note = 0;
    }
}
```

context switch

- Our critical section doesn't cover enough!

# General mutual exclusion

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- We would like the ability to define a region of code as a critical section e.g.

```
// thread 1
ENTER_CS();
beer = checkFridge();
if(!beer)
    buyBeer();
LEAVE_CS();
```

```
// thread 2
ENTER_CS();
beer = checkFridge();
if(!beer)
    buyBeer();
LEAVE_CS();
```

- This should work ...
  - ... providing that our implementation of ENTER\_CS() / LEAVE\_CS() is correct

# Implementing mutual exclusion

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- One option is to prevent context switches
  - e.g. disable interrupts (for kernel threads), or set an in-memory flag (for user threads)
- ENTER\_CS() = “disable context switches”;  
LEAVE\_CS() = “re-enable context switches”
- Can work but:
  - Rather brute force (stops all other threads, not just those who want to enter the critical section)
  - Potentially unsafe (if disable interrupts and then sleep waiting for a timer interrupt ;-)
  - And doesn't work across multiple CPUs

# Implementing mutual exclusion

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- Associate a **mutual exclusion lock** with each critical section, e.g. a variable L
  - (must ensure use correct lock variable!)
- ENTER\_CS() = “LOCK(L)”
- LEAVE\_CS() = “UNLOCK(L)”
- Can implement LOCK() using read-and-set():

```
LOCK(L) {  
    while(!read-and-set(L))  
        ; // do nothing  
}
```

```
UNLOCK(L) {  
    L = 0;  
}
```



# Solution #3: mutual exclusion locks

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```
// thread 1
LOCK(fridgeLock);
beer = checkFridge();
if(!beer)
    buyBeer();
UNLOCK(fridgeLock);
```

```
// thread 2
LOCK(fridgeLock);
beer = checkFridge();
if(!beer)
    buyBeer();
UNLOCK(fridgeLock);
```

- This is – finally! – a correct program
- Still not perfect
  - Lock might be held for quite a long time (e.g. imagine another person wanting to get the milk!)
  - Waiting threads waste CPU time (or worse)
  - **Contention** occurs when consumers have to wait for locks
- Mutual exclusion locks often known as **mutexes**
  - But we will prefer this term for **sleepable locks** – see Lecture 2
  - So think of the above as a **spin lock**

# Summary + next time

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- Definition of a concurrent system
- Origins of concurrency within a computer
- Processes and threads
- Challenge: concurrent access to shared resources
- Critical sections, mutual exclusion, race conditions, atomicity
- Mutual exclusion locks (mutexes)
  
- Next time:
  - More on mutual exclusion
  - Hardware support for mutual exclusion
  - Semaphores for mutual exclusion, process synchronisation, and resource allocation
  - Producer-consumer relationships.