Topic 3: The Data Link Layer

Our goals:

- understand principles behind data link layer services:
  - error detection, correction
  - sharing a broadcast channel: multiple access
  - link layer addressing
  - reliable data transfer, flow control
- instantiation and implementation of various link layer technologies
  - Wired Ethernet (aka 802.3)
  - Wireless Ethernet (aka 802.11 WiFi)
- Algorithms
  - Binary Exponential Backoff
  - Spanning Tree
Link Layer: Introduction

Some terminology:

• hosts and routers are **nodes**
• communication channels that connect adjacent nodes along communication path are **links**
  – wired links
  – wireless links
  – LANs
• layer-2 packet is a **frame**, encapsulates datagram

**data-link layer** has responsibility of transferring datagram from one node to adjacent node over a link
Link Layer (Channel) Services

- **framing, physical addressing:**
  - encapsulate datagram into frame, adding header, trailer
  - channel access if shared medium
  - “MAC” addresses used in frame headers to identify source, dest
    - different from IP address!
- **reliable delivery between adjacent nodes**
  - we see some of this again in the Transport Topic
  - seldom used on low bit-error link (fiber, some twisted pair)
  - wireless links: high error rates
Link Layer (Channel) Services - 2

• *flow control:*
  – pacing between adjacent sending and receiving nodes

• *error control:*
  – *error detection:*
    – errors caused by signal attenuation, noise.
    – receiver detects presence of errors:
      • signals sender for retransmission or drops frame
  – *error correction:*
    – receiver identifies *and corrects* bit error(s) without resorting to retransmission

• *access control: half-duplex and full-duplex*
  – with half duplex, nodes at both ends of link can transmit, but not at same time
Where is the link layer implemented?

• in each and every host
• link layer implemented in “adaptor” (aka *network interface card* NIC)
  – Ethernet card, PCMCi card, 802.11 card
  – implements link, physical layer
• attaches into host’s system buses
• combination of hardware, software, firmware
Adaptors Communicating

- **sending side:**
  - encapsulates datagram in frame
  - encodes data for the physical layer
  - adds error checking bits, provide reliability, flow control, etc.

- **receiving side**
  - decodes data from the physical layer
  - looks for errors, provide reliability, flow control, etc
  - extracts datagram, passes to upper layer at receiving side
Coding – a channel function

Change the representation of data.

Given Data → Encoding → Changed Data ← Decoding
Coding
Change the representation of data.

1. Encryption: MyPasswd $\leftrightarrow$ AA$$ff
2. Error Detection: AA$$ff $\leftrightarrow$ AAffff
3. Compression: AAffff $\leftrightarrow$ A2$4f4$
4. Analog: A2$4f4$ $\leftrightarrow$ 

Given Data $\leftrightarrow$ Encoding $\leftrightarrow$ Decoding $\leftrightarrow$ Changed Data
Line Coding Examples
where Baud=bit-rate

Non-Return-to-Zero (NRZ)

```
0 1 0 1 1 0 0 1 0 1
```

Non-Return-to-Zero-Mark (NRZM) 1 = transition 0 = no transition

```
0 1 0 1 1 0 0 1 0 1
```

Non-Return-to-Zero Inverted (NRZI) (note transitions on the 1)

```
0 1 0 1 1 0 0 1 0 1
```
Line Coding Examples

Non-Return-to-Zero (NRZ) (Baud = bit-rate)

Manchester example (Baud = 2 x bit-rate)

Quad-level code (2 x Baud = bit-rate)
Line Coding – Block Code example

Data to send

<table>
<thead>
<tr>
<th>Name</th>
<th>4b</th>
<th>5b</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0000</td>
<td>1110</td>
<td>hex data 0</td>
</tr>
<tr>
<td>1</td>
<td>0001</td>
<td>0100</td>
<td>hex data 1</td>
</tr>
<tr>
<td>2</td>
<td>0010</td>
<td>1010</td>
<td>hex data 2</td>
</tr>
<tr>
<td>3</td>
<td>0011</td>
<td>1010</td>
<td>hex data 3</td>
</tr>
<tr>
<td>4</td>
<td>0100</td>
<td>0101</td>
<td>hex data 4</td>
</tr>
<tr>
<td>5</td>
<td>0101</td>
<td>0111</td>
<td>hex data 5</td>
</tr>
<tr>
<td>6</td>
<td>0110</td>
<td>0111</td>
<td>hex data 6</td>
</tr>
<tr>
<td>7</td>
<td>0111</td>
<td>0111</td>
<td>hex data 7</td>
</tr>
<tr>
<td>8</td>
<td>1000</td>
<td>1001</td>
<td>hex data 8</td>
</tr>
<tr>
<td>9</td>
<td>1001</td>
<td>1001</td>
<td>hex data 9</td>
</tr>
<tr>
<td>A</td>
<td>1010</td>
<td>1011</td>
<td>hex data A</td>
</tr>
<tr>
<td>B</td>
<td>1011</td>
<td>1011</td>
<td>hex data B</td>
</tr>
<tr>
<td>C</td>
<td>1100</td>
<td>1101</td>
<td>hex data C</td>
</tr>
<tr>
<td>D</td>
<td>1101</td>
<td>1101</td>
<td>hex data D</td>
</tr>
<tr>
<td>E</td>
<td>1110</td>
<td>1110</td>
<td>hex data E</td>
</tr>
<tr>
<td>F</td>
<td>1111</td>
<td>1110</td>
<td>hex data F</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Name</th>
<th>4b</th>
<th>5b</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q</td>
<td>-NONE-</td>
<td>00000</td>
<td>Quiet</td>
</tr>
<tr>
<td>I</td>
<td>-NONE-</td>
<td>11111</td>
<td>Idle</td>
</tr>
<tr>
<td>J</td>
<td>-NONE-</td>
<td>11000</td>
<td>SSD #1</td>
</tr>
<tr>
<td>K</td>
<td>-NONE-</td>
<td>10001</td>
<td>SSD #2</td>
</tr>
<tr>
<td>T</td>
<td>-NONE-</td>
<td>01101</td>
<td>ESD #1</td>
</tr>
<tr>
<td>R</td>
<td>-NONE-</td>
<td>00111</td>
<td>ESD #2</td>
</tr>
<tr>
<td>H</td>
<td>-NONE-</td>
<td>00100</td>
<td>Halt</td>
</tr>
</tbody>
</table>

Block coding transfers data with a fixed overhead: 20% less information per Baud in the case of 4B/5B

So to send data at 100Mbps; the line rate (the Baud rate) must be 125Mbps.

1Gbps uses an 8b/10b codec; encoding entire bytes at a time but with 25% overhead.
Line Coding Scrambling – with secrecy

Step 1

Step 2

Communications Channel

Scrambling Sequence

Message XOR Sequence

Message XOR Sequence

Scrambling Sequence

Scrambling Sequence

Step 3

Don’t ever reuse Scrambling sequence, ever. ***this is quite important***
Line Coding Scrambling—no secrecy

Message \rightarrow \text{Scrambling Sequence} \rightarrow \text{Communications Channel} \rightarrow \text{Scrambling Sequence} \rightarrow \text{Message}

\text{Message XOR Sequence}

\text{e.g. (Self-synchronizing) scrambler}
Line Coding Examples (Hybrid)

...100111101101010001000101100111010001010110101001001110101110100...
...1001111011010100010100101100111010001010110101001001110101110100...

Inserted bits marking “start of frame/block/sequence”

Scramble / Transmit / Unscramble

...010001011001110100010101101010010011101011101001001011101110111000...

Identify (and remove) “start of frame/block/sequence”
This gives you the Byte-delineations for free

64b/66b combines a scrambler and a framer. The start of frame is a pair of bits 01 or 10: 01 means “this frame is data” 10 means “this frame contains data and control” – control could be configuration information, length of encoded data or simply “this line is idle” (no data at all)
Multiple Access Mechanisms

Each dimension is orthogonal (so may be trivially combined)
There are other dimensions too; can you think of them?
Code Division Multiple Access (CDMA) 
(not to be confused with CSMA!)

- used in several wireless broadcast channels (cellular, satellite, etc) standards
- unique “code” assigned to each user; i.e., code set partitioning
- all users share same frequency, but each user has own “chipping” sequence (i.e., code) to encode data
- encoded signal = (original data) XOR (chipping sequence)
- decoding: inner-product of encoded signal and chipping sequence
- allows multiple users to “coexist” and transmit simultaneously with minimal interference (if codes are “orthogonal”)
**CDMA Encode/Decode**

<table>
<thead>
<tr>
<th>Sender adds code</th>
<th>Data bits</th>
<th>d₁ = -1</th>
<th>d₀ = 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Code</td>
<td>1 1 1 1 1 1</td>
<td>-1 -1 -1</td>
<td>-1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Slot 1</th>
<th>Slot 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>d₁ = -1</td>
<td>d₀ = 1</td>
</tr>
</tbody>
</table>

channel output $Z_{i,m} = d_i \cdot c_m$

<table>
<thead>
<tr>
<th>Slot 1 channel output</th>
<th>Slot 0 channel output</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 1 1 1 1 1 1 1</td>
<td>1 1 1 1 1 1</td>
</tr>
</tbody>
</table>

receiver removes code

<table>
<thead>
<tr>
<th>Received input</th>
<th>Code</th>
<th>d₁ = -1</th>
<th>d₀ = 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 1 1 1 1 1 1</td>
<td>-1</td>
<td>-1 -1</td>
<td>-1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Slot 1</th>
<th>Slot 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>d₁ = -1</td>
<td>d₀ = 1</td>
</tr>
</tbody>
</table>

received input $D_i = \sum_{m=1}^{M} Z_{i,m} \cdot c_m$

channel output $Z_{i,m}$

<table>
<thead>
<tr>
<th>M</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Slot 1</th>
<th>Slot 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>d₁ = -1</td>
<td>d₀ = 1</td>
</tr>
</tbody>
</table>

receiver removes code

<table>
<thead>
<tr>
<th>Receiver removes code</th>
<th>Code</th>
<th>d₁ = -1</th>
<th>d₀ = 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 1 1 1 1 1 1 1</td>
<td>-1</td>
<td>-1 -1</td>
<td>-1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Slot 1</th>
<th>Slot 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>d₁ = -1</td>
<td>d₀ = 1</td>
</tr>
</tbody>
</table>
CDMA: two-sender interference

Each sender adds a unique code.

sender removes its unique code.
Coding Examples summary

• Common Wired coding
  – Block codecs: table-lookups
    • fixed overhead, inline control signals
  – Scramblers: shift registers
    • overhead free

Like earlier coding schemes and error correction/detection; you can combine these
  – e.g, 10Gb/s Ethernet may use a hybrid

CDMA (Code Division Multiple Access)
  – coping intelligently with competing sources
  – Mobile phones
Error Detection and Correction

Transmission media are not perfect and cause signal impairments:

1. **Attenuation**
   - Loss of energy to overcome medium’s resistance

2. **Distortion**
   - The signal changes its form or shape, caused in composite signals

3. **Noise**
   - Thermal noise, induced noise, crosstalk, impulse noise

Interference can change the shape or timing of a signal:  
0 → 1 or 1 → 0
Error Detection and Correction

How to use coding to deal with errors in data communication?

Basic Idea:
1. Add additional information (redundancy) to a message.
2. Detect an error and re-send a message.
Or, fix an error in the received message.
Coding – a channel function

Change the representation of data.

Given Data \(\xrightarrow{\text{Encoding}}\) Changed Data \(\xleftarrow{\text{Decoding}}\)
Coding

Change the representation of data.

1. Encryption: MyPasswd <-> AA$$$$ff
2. Error Detection: AA$$$$ff <-> AA$$$$ffff
3. Compression: AA$$$$ffff <-> A2$4f4
4. Analog: A2$4f4 <-> 28
Error Detection Code: Parity

Add one bit, such that the number of all 1’s is even.

Problem: This simple parity cannot detect two-bit errors.
Error Detection Code

Sender:
Y = generateCheckBit(X);
send(XY);

Receiver:
receive(X1Y1);
Y2 = generateCheckBit(X1);
if (Y1 != Y2) ERROR;
else NOERROR

Noise
Error Detection Code: CRC

- CRC means “Cyclic Redundancy Check”.
- “A sequence of redundant bits, called CRC, is appended to the end of data so that the resulting data becomes exactly divisible by a second, predetermined binary number.”
- \(\text{CRC} := \text{remainder (data } \div \text{ predetermined divisor)}\)
- More powerful than parity.
  - It can detect various kinds of errors, including 2-bit errors.
- More complex: multiplication, binary division.
- Parameterized by n-bit divisor \(P\).
  - Example: 3-bit divisor 101.
  - Choosing good \(P\) is crucial.
CRC with 3-bit Divisor 101

- Multiplication by $2^3$
  \[ D_2 = D \times 2^3 \]

- Binary Division by 101
  \[ \text{CheckBit} = (D_2) \text{ rem } (101) \]

- Add three 0’s at the end

- Same check bits from Parity, but different ones from CRC

- Kurose p478 §5.2.3
- Peterson p97 §2.4.3

- 1111
  1001

- CRC

- 00
  11

- Parity
Sender:
Y = generateCRC(X div P);
send(X);
send(Y);

Receiver:
receive(X1);
receive(Y1);
Y2 = generateCRC(X1Y1 div P);
if (Y2 != 0s) ERROR;
else NOERROR
Error Detection Code becomes....

Sender:
Y = generateCheckBit(X);
send(XY);

Receiver:
receive(X1Y1);
Y2 = generateCheckBit(X1);
if (Y1 != Y2) ERROR;
else NOERROR

Noise
Forward Error Correction (FEC)

Sender:
Y = generateCheckBit(X);
send(XY);

Receiver:
receive(X1Y1);
Y2 = generateCheckBit(X1);
if (Y1 != Y2) FIXERROR(X1Y1);
else NOERROR
Forward Error Correction (FEC)

Sender:
Y = generateCheckBit(X);
send(XY);

Receiver:
receive(X1Y1);
Y2 = generateCheckBit(X1);
if (Y1 != Y2) FIXERROR(X1Y1);
else NOERROR
Basic Idea of Forward Error Correction

Replace erroneous data by its “closest” error-free data.
Error Detection vs Correction

Error Correction:
• Cons: More check bits. False recovery.
• Pros: No need to re-send.

Error Detection:
• Cons: Need to re-send.
• Pros: Less check bits.

Usage:
• Correction: A lot of noise. Expensive to re-send.
• Detection: Less noise. Easy to re-send.
• Can be used together.
Multiple Access Links and Protocols

Two types of “links”:

• point-to-point
  – point-to-point link between Ethernet switch and host

• broadcast (shared wire or medium)
  – old-fashioned wired Ethernet (*here be dinosaurs* – extinct)
  – upstream HFC (Hybrid Fiber-Coax – the Coax may be broadcast)
  – Home plug / Powerline networking
  – 802.11 wireless LAN

![Diagram of network types]

- shared wire (e.g., cabled Ethernet)
- shared RF (e.g., 802.11 WiFi)
- shared RF (satellite)
- humans at a cocktail party (shared air, acoustical)
Multiple Access protocols

• single shared broadcast channel
• two or more simultaneous transmissions by nodes: interference
  – collision if node receives two or more signals at the same time

*multiple access protocol*

• distributed algorithm that determines how nodes share channel, i.e., determine when node can transmit
• communication about channel sharing must use channel itself!
  – no out-of-band channel for coordination
Ideal Multiple Access Protocol

Broadcast channel of rate $R$ bps

1. when one node wants to transmit, it can send at rate $R$
2. when $M$ nodes want to transmit,
   each can send at average rate $R/M$
3. fully decentralized:
   - no special node to coordinate transmissions
   - no synchronization of clocks, slots
4. simple
MAC Protocols: a taxonomy

Three broad classes:

• **Channel Partitioning**
  – divide channel into smaller “pieces” (time slots, frequency, code)
  – allocate piece to node for exclusive use

• **Random Access**
  – channel not divided, allow collisions
  – “recover” from collisions

• **“Taking turns”**
  – nodes take turns, but nodes with more to send can take longer turns
Channel Partitioning MAC protocols: TDMA
(time travel warning – we mentioned this earlier)

TDMA: time division multiple access

- access to channel in "rounds"
- each station gets fixed length slot (length = pkt trans time) in each round
- unused slots go idle
- example: station LAN, 1,3,4 have pkt, slots 2,5,6 idle
Channel Partitioning MAC protocols: FDMA
(time travel warning – we mentioned this earlier)

FDMA: frequency division multiple access

- channel spectrum divided into frequency bands
- each station assigned fixed frequency band
- unused transmission time in frequency bands go idle
- example: station LAN, 1,3,4 have pkt, frequency bands 2,5,6 idle
“Taking Turns” MAC protocols

channel partitioning MAC protocols:

– share channel *efficiently* and *fairly* at high load
– inefficient at low load: delay in channel access, $1/N$
  bandwidth allocated even if only 1 active node!

random access MAC protocols:

– efficient at low load: single node can fully utilize channel
– high load: collision overhead

“taking turns” protocols:

look for best of both worlds!
“Taking Turns” MAC protocols

Polling:

- master node “invites” slave nodes to transmit in turn
- typically used with “dumb” slave devices
- concerns:
  - polling overhead
  - latency
  - single point of failure (master)
“Taking Turns” MAC protocols

Token passing:
- control token passed from one node to next sequentially.
- token message
- concerns:
  - token overhead
  - latency
  - single point of failure (token)
- concerns fixed in part by a slotted ring (many simultaneous tokens)

Cambridge students – this is YOUR heritage
Cambridge RING, Cambridge Fast RING, Cambridge Backbone RING, these things gave us ATDM (and ATM)
ATM

In TDM a sender may only use a pre-allocated slot

In ATM a sender transmits labeled cells whenever necessary

ATM = Asynchronous Transfer Mode – an ugly expression
think of it as ATDM – Asynchronous Time Division Multiplexing

That’s a variant of PACKET SWITCHING to the rest of us – just like Ethernet
but using fixed length slots/packets/cells

Use the media when you need it, but
ATM had virtual circuits and these needed setup....
Random Access MAC Protocols

• When node has packet to send
  – Transmit at full channel data rate
  – No *a priori* coordination among nodes

• Two or more transmitting nodes $\Rightarrow$ collision
  – Data lost

• Random access MAC protocol specifies:
  – How to detect collisions
  – How to recover from collisions

• Examples
  – ALOHA and Slotted ALOHA
  – CSMA, CSMA/CD, CSMA/CA (wireless)
Key Ideas of Random Access

- **Carrier sense**
  - *Listen before speaking, and don’t interrupt*
  - Checking if someone else is already sending data
  - ... and waiting till the other node is done

- **Collision detection**
  - *If someone else starts talking at the same time, stop*
  - Realizing when two nodes are transmitting at once
  - ... by detecting that the data on the wire is garbled

- **Randomness**
  - *Don’t start talking again right away*
  - Waiting for a random time before trying again
CSMA (Carrier Sense Multiple Access)

• CSMA: listen before transmit
  – If channel sensed idle: transmit entire frame
  – If channel sensed busy, defer transmission

• Human analogy: don’t interrupt others!

• Does this eliminate all collisions?
  – No, because of nonzero propagation delay
CSMA Collisions

Propagation delay: two nodes may not hear each other’s before sending.

Would slots hurt or help?

CSMA reduces but does not eliminate collisions

Biggest remaining problem?

Collisions still take full slot! How do you fix that?
CSMA/CD (Collision Detection)

• CSMA/CD: carrier sensing, deferral as in CSMA
  – *Collisions detected within short time*
  – Colliding transmissions aborted, reducing wastage

• Collision detection easy in wired LANs:
  – Compare transmitted, received signals

• Collision detection difficult in wireless LANs:
  – Reception shut off while transmitting (well, perhaps not)
  – Not perfect broadcast (limited range) so collisions local
  – Leads to use of *collision avoidance* instead (later)
CSMA/CD Collision Detection

B and D can tell that collision occurred.

Note: for this to work, need restrictions on minimum frame size and maximum distance. Why?
Limits on CSMA/CD Network Length

- Latency depends on physical length of link
  - Time to propagate a packet from one end to the other
- Suppose $A$ sends a packet at time $t$
  - And $B$ sees an idle line at a time just before $t+d$
  - ... so $B$ happily starts transmitting a packet
- $B$ detects a collision, and sends jamming signal
  - But $A$ can’t see collision until $t+2d$
Performance of CSMA/CD

• Time wasted in collisions
  – Proportional to distance $d$

• Time spend transmitting a packet
  – Packet length $p$ divided by bandwidth $b$

• Rough estimate for efficiency (K some constant)

\[ E \sim \frac{p}{b} + Kd \]

• Note:
  – For large packets, small distances, $E \sim 1$
  – As bandwidth increases, $E$ decreases
  – That is why high-speed LANs are all switched
Benefits of Ethernet

• Easy to administer and maintain
• Inexpensive
• Increasingly higher speed
• Evolvable!
Evolution of Ethernet

• Changed everything except the frame format
  – From single coaxial cable to hub-based star
  – From shared media to switches
  – From electrical signaling to optical

• Lesson #1
  – The right interface can accommodate many changes
  – Implementation is hidden behind interface

• Lesson #2
  – Really hard to displace the dominant technology
  – Slight performance improvements are not enough
Ethernet: CSMA/CD Protocol

• **Carrier sense**: wait for link to be idle
• **Collision detection**: listen while transmitting
  – No collision: transmission is complete
  – Collision: abort transmission & send jam signal
• **Random access**: binary exponential back-off
  – After collision, wait a random time before trying again
  – After $m^{th}$ collision, choose $K$ randomly from $\{0, ..., 2^m-1\}$
  – ... and wait for $K \times 512$ bit times before trying again
    • Using min packet size as “slot”
    • If transmission occurring when ready to send, wait until end of transmission (CSMA)
The Wireless Spectrum

- VLF: 100 km
- LF: 10 km
- MF: 1 km
- HF: 100 m
- VHF: 10 m
- UHF: 1 m
- SHF: 10 cm
- EHF: 1 cm

© 1999 Encyclopædia Britannica, Inc.
Metrics for evaluation / comparison of wireless technologies

- Bitrate or Bandwidth
- Range - PAN, LAN, MAN, WAN
- Two-way / One-way
- Multi-Access / Point-to-Point
- Digital / Analog
- Applications and industries
- Frequency – Affects most physical properties:
  - Distance (free-space loss)
  - Penetration, Reflection, Absorption
  - Energy proportionality
  - Policy: Licensed / Deregulated
  - Line of Sight (Fresnel zone)
  - Size of antenna
  - Determined by wavelength – $\lambda = \frac{v}{f}$
Wireless Communication Standards

• Cellular (800/900/1700/1800/1900Mhz):
  – 2G: GSM / CDMA / GPRS /EDGE
  – 3G: CDMA2000/UMTS/HSDPA/EVDO
  – 4G: LTE, WiMax
• IEEE 802.11 (aka WiFi): (some examples)
  – b: 2.4Ghz band, 11Mbps (~4.5 Mbps operating rate)
  – g: 2.4Ghz, 54-108Mbps (~19 Mbps operating rate)
  – a: 5.0Ghz band, 54-108Mbps (~25 Mbps operating rate)
  – n: 2.4/5Ghz, 150-600Mbps (4x4 mimo)
  – ac: 2.4/5Ghz, 433-1300Mbps (improved coding 256-QAM)
  – ad: 60Ghz, 7Gbps
  – af: 54/790Mhz, 26-35Mbps (TV whitespace)
• IEEE 802.15 – lower power wireless:
  – 802.15.1: 2.4Ghz, 2.1 Mbps (Bluetooth)
  – 802.15.4: 2.4Ghz, 250 Kbps (Sensor Networks)
What Makes Wireless Different?

• Broadcast and multi-access medium...
  – err, so....

• BUT, Signals sent by sender don’t always end up at receiver intact
  – Complicated physics involved, which we won’t discuss
  – But what can go wrong?
Lets focus on 802.11

aka - WiFi ...
What makes it special?

Deregulation > Innovation > Adoption > Lower cost = Ubiquitous technology

JUST LIKE ETHERNET – not lovely but sufficient
802.11 Architecture

- Designed for limited area
- AP’s (Access Points) set to specific channel
- Broadcast beacon messages with SSID (Service Set Identifier) and MAC Address periodically
- Hosts scan all the channels to discover the AP’s
  - Host associates with AP
Wireless Multiple Access Technique?

• Carrier Sense?
  – Sender can listen before sending
  – What does that tell the sender?

• Collision Detection?
  – Where do collisions occur?
  – How can you detect them?
A and C can both send to B but can’t hear each other
– A is a *hidden terminal* for C and vice versa
• Carrier Sense will be *ineffective*
Exposed Terminals

- **Exposed node**: B sends a packet to A; C hears this and decides not to send a packet to D (despite the fact that this will not cause interference)!
- **Carrier sense** would prevent a successful transmission.
Key Points

• No concept of a global collision
  – Different receivers hear different signals
  – Different senders reach different receivers

• Collisions are at receiver, not sender
  – Only care if receiver can hear the sender clearly
  – It does not matter if sender can hear someone else
  – As long as that signal does not interfere with receiver

• Goal of protocol:
  – Detect if receiver can hear sender
  – Tell senders who might interfere with receiver to shut up
Basic Collision Avoidance

• Since can’t detect collisions, we try to avoid them

• Carrier sense:
  – When medium busy, choose random interval
  – Wait that many idle timeslots to pass before sending

• When a collision is inferred, retransmit with binary exponential backoff (like Ethernet)
  – Use ACK from receiver to infer “no collision”
  – Use exponential backoff to adapt contention window
CSMA/CA -MA with Collision Avoidance

• Before every data transmission
  – Sender sends a Request to Send (RTS) frame containing the length of the transmission
  – Receiver respond with a Clear to Send (CTS) frame
  – Sender sends data
  – Receiver sends an ACK; now another sender can send data

• When sender doesn’t get a CTS back, it assumes collision
CSMA/CA, con’t

- If other nodes hear RTS, but not CTS: send
  - Presumably, destination for first sender is out of node’s range ...
• If other nodes hear RTS, but not CTS: send
  – Presumably, destination for first sender is out of node’s range ...
  – ... Can cause problems when a CTS is lost
• When you hear a CTS, you keep quiet until scheduled transmission is over (hear ACK)
Overcome hidden terminal problems with contention-free protocol

1. B sends to C Request To Send (RTS)
2. A hears RTS and defers (to allow C to answer)
3. C replies to B with Clear To Send (CTS)
4. D hears CTS and defers to allow the data
5. B sends to C
Preventing Collisions Altogether

• Frequency Spectrum partitioned into several channels
  – Nodes within interference range can use separate channels
  – Now A and C can send without any interference!

• Most cards have only 1 transceiver
  – Not Full Duplex: Cannot send and receive at the same time
  – Aggregate Network throughput doubles
CSMA/CA and RTS/CTS

- **RTS/CTS**
  - helps with hidden terminal
  - good for high-traffic Access Points
  - often turned on/off dynamically

- **Without RTS/CTS**
  - lower latency -> faster!
  - reduces wasted b/w
    - if the $Pr(\text{collision})$ is low
  - good for when net is small and not weird
    - eg no hidden/exposed terminals
CSMA/CD vs CSMA/CA (without RTS/CTS)

**CD** Collision Detect

wired – listen and talk

1. Listen for others
3. Send message (and listen)
4. Collision?
   a. JAM
   b. increase your BEB
   c. sleep
   d. goto 1.

**CA** Collision Avoidance

wireless – talk OR listen

1. Listen for others
2. Busy?
   a. increase your BEB
   b. sleep
   c. goto 1.
3. Send message
4. Wait for ACK (*MAC ACK*)
5. Got No ACK from MAC?
   a. increase your BEB
   b. sleep
   c. goto 1.
Summary of MAC protocols

• *channel partitioning*, by time, frequency or code
  – Time Division, Frequency Division

• *random access* (dynamic),
  – ALOHA, S-ALOHA, CSMA, CSMA/CD
  – carrier sensing: easy in some technologies (wire), hard in others (wireless)
  – CSMA/CD used in Ethernet
  – CSMA/CA used in 802.11

• *taking turns*
  – polling from central site, token passing
  – Bluetooth, FDDI, IBM Token Ring
MAC Addresses

• MAC (or LAN or physical or Ethernet) address:
  – function: *get frame from one interface to another physically-connected interface (same network)*
  – 48 bit MAC address (for most LANs)
    • *burned* in NIC ROM, nowadays usually software settable and set at boot time
LAN Address (more)

- MAC address allocation administered by IEEE
- manufacturer buys portion of MAC address space (to assure uniqueness)
- analogy:
  (a) MAC address: like Social Security Number
  (b) IP address: like postal address
- MAC flat address → portability
  - can move LAN card from one LAN to another
- IP hierarchical address NOT portable
  - address depends on IP subnet to which node is attached
Hubs

... physical-layer (“dumb”) repeaters:
– bits coming in one link go out all other links at same rate
– all nodes connected to hub can collide with one another
– no frame buffering
– no CSMA/CD at hub: host NICs detect collisions

Collision Domain in CSMA/CD speak
CSMA/CD Lives....

Home Plug and similar Powerline Networking....
Switch

*(like a Hub but smarter)*

- **link-layer device**: smarter than hubs, take *active* role
  - store, forward Ethernet frames
  - examine incoming frame’s MAC address, *selectively* forward frame to one-or-more outgoing links when frame is to be forwarded on segment, uses CSMA/CD to access segment

- **transparent**
  - hosts are unaware of presence of switches

- **plug-and-play, self-learning**
  - switches do not need to be configured
Switch: allows *multiple* simultaneous transmissions

- hosts have dedicated, direct connection to switch
- switches buffer packets
- Ethernet protocol used on *each* incoming link, but no collisions; full duplex
  - each link is its own collision domain
- **switching:** A-to-A’ and B-to-B’ simultaneously, without collisions
  - not possible with dumb hub

*switch with six interfaces (1,2,3,4,5,6)*
Switch Table

- **Q:** how does switch know that A' reachable via interface 4, B' reachable via interface 5?
- **A:** each switch has a switch table, each entry:
  - (MAC address of host, interface to reach host, time stamp)
- looks like a routing table!
- **Q:** how are entries created, maintained in switch table?
  - something like a routing protocol?
Switch: self-learning (recap)

- switch *learns* which hosts can be reached through which interfaces
  - when frame received, switch “learns” location of sender: incoming LAN segment
  - records sender/location pair in switch table

<table>
<thead>
<tr>
<th>MAC addr</th>
<th>interface</th>
<th>TTL</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>1</td>
<td>60</td>
</tr>
</tbody>
</table>

Switch table (initially empty)
Switch: frame filtering/forwarding

**When frame received:**

1. record link associated with sending host
2. index switch table using MAC dest address
3. if entry found for destination
   then {
     if dest on segment from which frame arrived
       then drop the frame
     else forward the frame on interface indicated
   }
else flood

*forward on all but the interface on which the frame arrived*
Self-learning, forwarding: example

- frame destination unknown: *flood*
- destination A location known: selective send

<table>
<thead>
<tr>
<th>MAC addr</th>
<th>interface</th>
<th>TTL</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>1</td>
<td>60</td>
</tr>
<tr>
<td>A'</td>
<td>4</td>
<td>60</td>
</tr>
</tbody>
</table>

Switch table *(initially empty)*
Interconnecting switches

- switches can be connected together

Q: sending from A to G - how does $S_1$ know to forward frame destined to F via $S_4$ and $S_3$?

A: self learning! (works exactly the same as in single-switch case – flood/forward/drop)
Flooding Can Lead to Loops

- Flooding can lead to forwarding loops
  - E.g., if the network contains a cycle of switches
  - “Broadcast storm”
Solution: Spanning Trees

• Ensure the forwarding topology has no loops
  – Avoid using some of the links when flooding
  – … to prevent loop from forming

• Spanning tree
  – Sub-graph that covers all vertices but contains no cycles
  – Links not in the spanning tree do not forward frames
What Do We Know?

• “Spanning tree algorithm is an algorithm to create a tree out of a graph that includes all nodes with a minimum number of edges connecting to vertices.”

• Shortest paths to (or from) a node form a tree

• So, algorithm has two aspects:
  – Pick a root
  – Compute shortest paths to it

• Only keep the links on shortest-path
Constructing a Spanning Tree

• Switches need to **elect a root**
  – The switch w/ smallest identifier (MAC addr)
• Each switch determines if each interface is on the **shortest path** from the root
  – Excludes it from the tree if not

• Messages (Y, d, X)
  – From node X
  – Proposing Y as the root
  – And the distance is d
Steps in Spanning Tree Algorithm

• Initially, each switch proposes itself as the root
  – Switch sends a message out every interface
  – … proposing itself as the root with distance 0
  – Example: switch X announces (X, 0, X)
• Switches update their view of the root
  – Upon receiving message (Y, d, Z) from Z, check Y’s id
  – If new id smaller, start viewing that switch as root
• Switches compute their distance from the root
  – Add 1 to the distance received from a neighbor
  – Identify interfaces not on shortest path to the root
  – … and exclude them from the spanning tree
• If root or shortest distance to it changed, “flood” updated message (Y, d+1, X)
Example From Switch #4’s Viewpoint

• Switch #4 thinks it is the root
  – Sends (4, 0, 4) message to 2 and 7

• Then, switch #4 hears from #2
  – Receives (2, 0, 2) message from 2
  – … and thinks that #2 is the root
  – And realizes it is just one hop away

• Then, switch #4 hears from #7
  – Receives (2, 1, 7) from 7
  – And realizes this is a longer path
  – So, prefers its own one-hop path
  – And removes 4-7 link from the tree
Example From Switch #4’s Viewpoint

- Switch #2 hears about switch #1
  - Switch 2 hears (1, 1, 3) from 3
  - Switch 2 starts treating 1 as root
  - And sends (1, 2, 2) to neighbors

- Switch #4 hears from switch #2
  - Switch 4 starts treating 1 as root
  - And sends (1, 3, 4) to neighbors

- Switch #4 hears from switch #7
  - Switch 4 receives (1, 3, 7) from 7
  - And realizes this is a longer path
  - So, prefers its own three-hop path
  - And removes 4-7 link from the tree
Robust Spanning Tree Algorithm

- Algorithm must react to failures
  - Failure of the root node
    - Need to elect a new root, with the next lowest identifier
  - Failure of other switches and links
    - Need to recompute the spanning tree
- Root switch continues sending messages
  - Periodically reannouncing itself as the root (1, 0, 1)
  - Other switches continue forwarding messages
- Detecting failures through timeout (soft state)
  - If no word from root, times out and claims to be the root
  - Delay in reestablishing spanning tree is major problem
  - Work on rapid spanning tree algorithms…
Summary

• principles behind data link layer services:
  – error detection, correction
  – sharing a broadcast channel: multiple access
  – link layer addressing

• instantiation and implementation of various link layer technologies
  – Ethernet
  – switched LANS
  – WiFi

• algorithms
  – Binary Exponential Backoff
  – Spanning Tree