

Last time: abstraction and parametricity

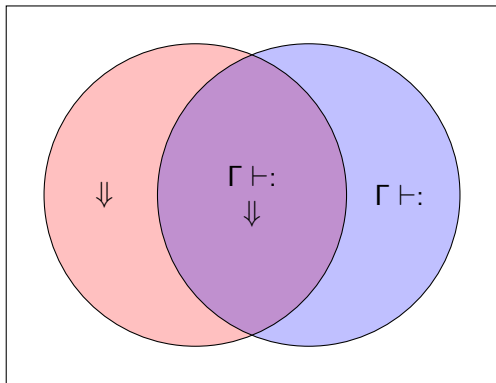
\exists

\forall

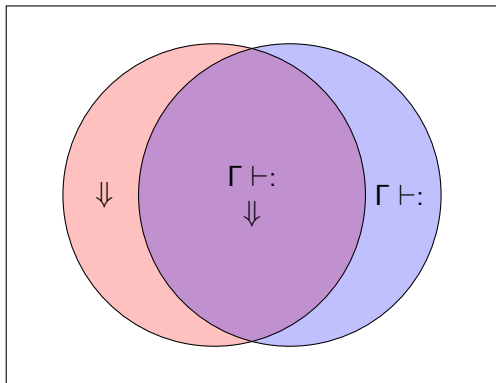
This time: GADTs

$a \equiv b$

What we gain



What we gain



(Additionally, some programs become faster!)

What it costs

We'll need to:

describe our data more precisely

strengthen the **relationship between data and types**

look at programs through a **propositions-as-types lens**

What we'll write

Non-regularity in constructor return types

```
type _ t = T : t1 → t2 t
```

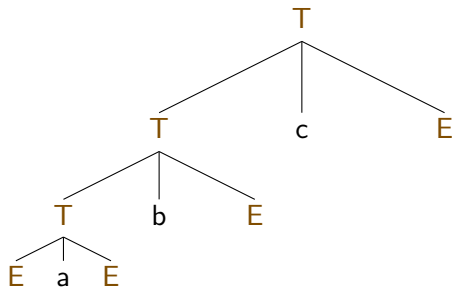
Locally abstract types:

```
let f : type a b. a t → b t = function ...
```

```
let g (type a) (type b) (x : a t) : b t = ...
```

Nested types

Unconstrained trees



```
type 'a tree =  
  Empty : 'a tree  
| Tree : 'a tree * 'a * 'a tree → 'a tree
```

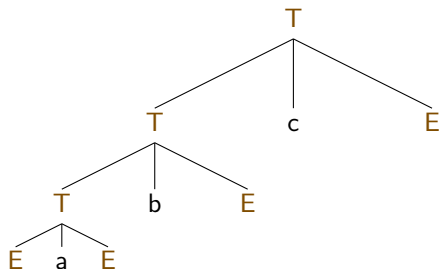

Functions on unconstrained trees

```
val ? : 'a tree → int
```

```
val ? : 'a tree → 'a option
```

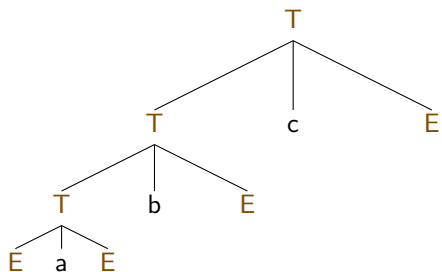
```
val ? : 'a tree → 'a tree
```

Unconstrained trees: depth


$$1 + \max$$
$$(1 + \max$$
$$(1 + \max$$
$$0$$
$$0)$$
$$0)$$
$$0)$$

```
let rec depth : 'a.'a tree → int =  
  function  
    Empty → 0  
  | Tree (l,_,r) → 1 + max (depth l) (depth r)
```

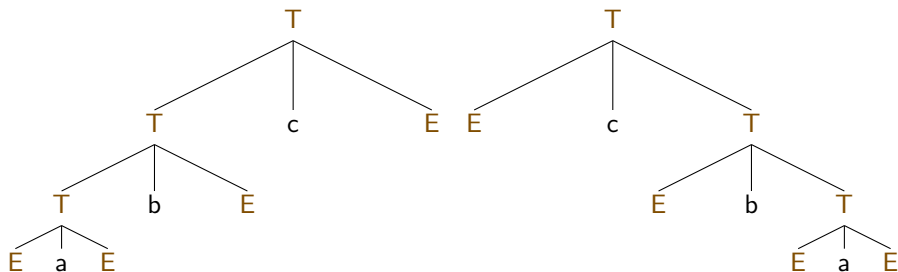
Unconstrained trees: top



Some c

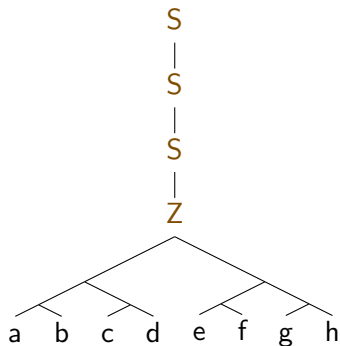
```
let top : 'a.'a tree → 'a option =  
  function  
    Empty → None  
  | Tree (_,v,_) → Some v
```

Unconstrained trees: swivel



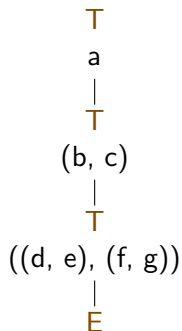
```
let rec swivel : 'a.'a tree → 'a tree =  
function  
  Empty → Empty  
| Tree (l,v,r) → Tree (swivel r, v, swivel l)
```

Perfect leaf trees via nesting



```
type 'a perfect =  
  ZeroP : 'a → 'a perfect  
  | SuccP : ('a * 'a)perfect → 'a perfect
```

Perfect (branch) trees via nesting



```
type _ ntree =  
  EmptyN : 'a ntree  
| TreeN : 'a * ('a * 'a) ntree → 'a ntree
```

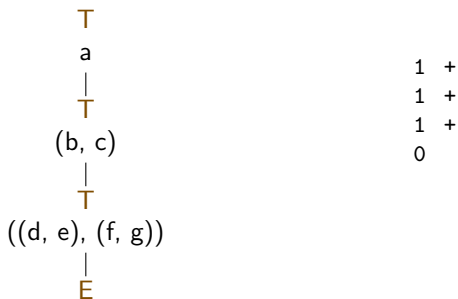
Functions on perfect nested trees

```
val ? : 'a ntree → int
```

```
val ? : 'a ntree → 'a option
```

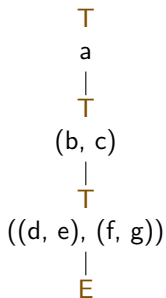
```
val ? : 'a ntree → 'a ntree
```

Perfect trees: depth



```
let rec depthN : 'a.'a ntree → int =  
  function  
    EmptyN → 0  
  | TreeN (_,t) → 1 + depthN t
```

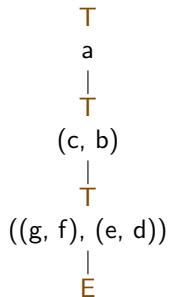
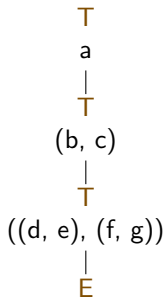

Perfect trees: top



Some a

```
let rec topN : 'a.'a ntree → 'a option =  
function  
  EmptyN → None  
| TreeN (v, _) → Some v
```

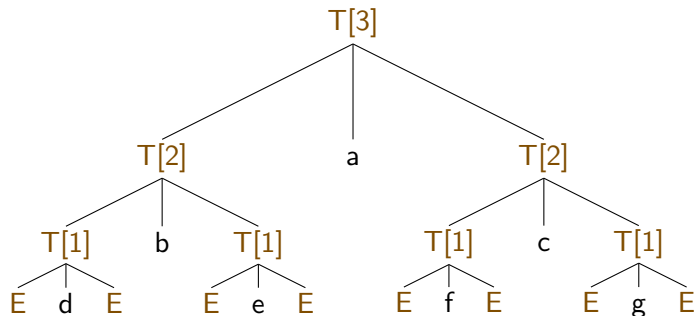
Perfect trees: swivel



```
let rec swiv : 'a.('a→'a) → 'a ntree → 'a ntree =  
  fun f t → match t with  
    EmptyN → EmptyN  
  | TreeN (v,t) →  
    TreeN (f v,swiv (fun (x,y) → (f y, f x)) t)  
  
let swivelN p = swiv id p
```

GADTs

Perfect trees, take two



```
type ('a, _) gtree =  
  EmptyG : ('a, z) gtree  
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree -> ('a, 'n s)  
  gtree
```

Natural numbers

```
type z = Z
type _ s = S : 'n → 'n s

# let zero = Z;;
val zero : z = Z
# let three = S (S (S Z));;
val three : z s s s = S (S (S Z))
```

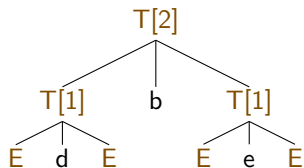
Functions on perfect trees (GADTs)

```
val ? : ('a, 'n) gtree → 'n
```

```
val ? : ('a, 'n s) gtree → 'a
```

```
val ? : ('a, 'n) gtree → ('a, 'n) gtree
```

Perfect trees (GADTs): depth



S (depth
S (depth
Z))

```
let rec depthG : type a n.(a, n) gtree → n =  
function  
  EmptyG → Z  
  | TreeG (l, _, _) → S (depthG l)
```

Perfect trees (GADTs): depth

```
type ('a, _) gtree =  
  EmptyG : ('a, z) gtree  
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)  
  gtree
```

```
let rec depthG : type a n.(a, n) gtree → n =  
  function  
    EmptyG → Z  
  | TreeG (l, _, _) → S (depthG l)
```

Type refinement

In the `EmptyG` branch: $n \equiv z$

In the `TreeG` branch: $n \equiv m\ s$ (for some m)

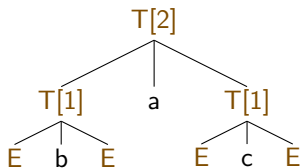
$l : (a, m)\text{gtree}$

$\text{depthG } l : m$

Polymorphic recursion

The argument to the recursive call has size m (s.t. $s\ m \equiv n$)

Perfect trees (GADTs): top



a

```
let topG : type a n.(a,n s) gtree → a =  
  function TreeG (_,v,_) → v
```

Perfect trees (GADTs): depth

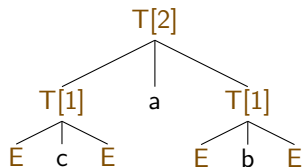
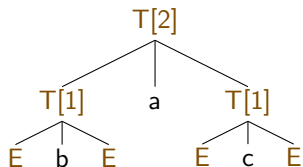
```
type ('a, _) gtree =  
  EmptyG : ('a, z) gtree  
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)  
  gtree
```

```
let topG : type a n.(a, n s) gtree → a =  
  function TreeG (_, v, _) → v
```

Type refinement

In an `EmptyG` branch we would have: $n \text{ s} \equiv z$
— impossible!

Perfect trees (GADTs): swivel



```
let rec swivelG : type a n. (a,n) gtree → (a,n) gtree =  
function  
  EmptyG → EmptyG  
  | TreeG (l,v,r) → TreeG (swivelG r, v, swivelG l)
```

Perfect trees (GADTs): swivel

```
type ('a, _) gtree =  
  EmptyG : ('a, z) gtree  
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)  
  gtree
```

```
let rec swivelG : type a n. (a, n) gtree → (a, n) gtree =  
  function  
    EmptyG → EmptyG  
  | TreeG (l, v, r) → TreeG (swivelG r, v, swivelG l)
```

Type refinement

In the `EmptyG` branch:

$$n \equiv z$$

In the `TreeG` branch:

$$n \equiv m \ s \quad (\text{for some } m)$$

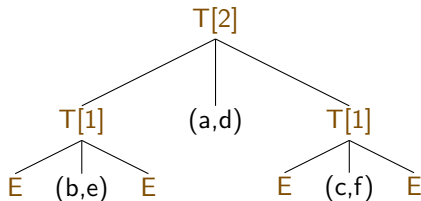
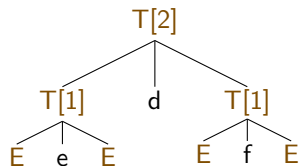
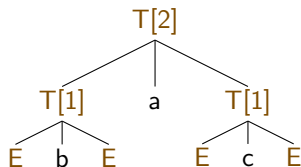
$$l, r : (a, m)\text{gtree}$$

$$\text{swivelG } l : (a, m)\text{gtree}$$

Polymorphic recursion

The argument to the recursive call has size m (s.t. $s \ m \equiv n$)

Zipping perfect trees



```
let rec zipTree :
  type a b n.(a,n) gtree → (b,n) gtree →
    (a * b,n) gtree =
  fun x y → match x, y with
    EmptyG, EmptyG → EmptyG
  | TreeG (l,v,r), TreeG (m,w,s) →
    TreeG (zipTree l m, (v,w), zipTree r s)
```

Zippering perfect trees

```
type ('a, _) gtree =
  EmptyG : ('a,z) gtree
| TreeG : ('a,'n) gtree * 'a * ('a,'n) gtree → ('a,'n s)
  gtree

let rec zipTree :
  type a b n.(a,n) gtree → (b,n) gtree → (a * b,n)
    gtree =
  fun x y → match x, y with
    EmptyG, EmptyG → EmptyG
  | TreeG (l,v,r), TreeG (m,w,s) →
    TreeG (zipTree l m, (v,w), zipTree r s)
```

Type refinement

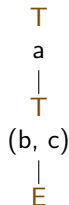
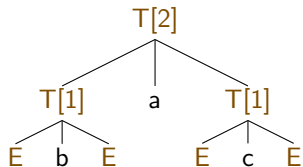
In the EmptyG branch: $n \equiv z$

In the TreeG branch: $n \equiv m \ s$ (for some m)

EmptyG, TreeG _ produces $n \equiv z$ **and** $n \equiv m \ s$

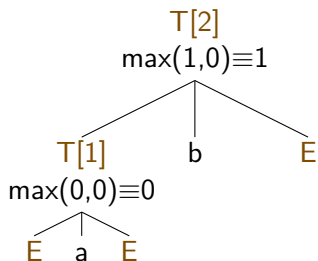
— impossible!

Conversions between perfect tree representations



```
let rec nestify : type a n.(a,n) gtree → a ntree =  
function  
  EmptyG → EmptyN  
| TreeG (l, v, r) →  
  TreeN (v, nestify (zipTree l r))
```

Depth-annotated trees



```
type ('a,_) dtree =  
  EmptyD : ('a,z) dtree  
| TreeD : ('a,'m) dtree * 'a * ('a,'n) dtree * ('m,'n,'o) max  
  → ('a,'o s) dtree
```


The untyped maximum function

```
val max : 'a → 'a → 'a
```

Parametricity: `max` is one of

```
fun x _ → x
```

```
fun _ y → y
```

A typed maximum function

```
val max : ('a,'b,'c) max → 'a → 'b → 'c
```

```
(max (a,b) ≡ c) → a → b → c
```

A typed maximum function: a max predicate

```
type (_,_,_) max =  
  MaxEq : ('a,'a,'a) max  
| MaxFlip : ('a,'b,'c) max → ('b,'a,'c) max  
| MaxSuc : ('a,'b,'a) max → ('a s,'b,'a s) max
```

$$\begin{aligned} a \equiv b &\rightarrow \max(a,b) \equiv a \\ \max(a,b) \equiv c &\rightarrow \max(b,a) \equiv c \\ \max(a,b) \equiv a &\rightarrow \max(a+1,b) \equiv a+1 \end{aligned}$$

A typed maximum function

```
type (_,_) eq1 = Refl : ('a,'a) eq1
```

```
type (_,_,_) max =  
  MaxEq : ('a,'a,'a) max  
  | MaxFlip : ('a,'b,'c) max → ('b,'a,'c) max  
  | MaxSuc : ('a,'b,'a) max → ('a s,'b,'a s) max
```

```
let rec max  
  : type a b c.(a,b,c) max → a → b → c  
= fun mx m n → match mx,m with  
  MaxEq , _           → m  
  | MaxFlip mx' , _   → max mx' n m  
  | MaxSuc mx' , S m' → S (max mx' m' n)
```

A typed maximum function

```
type (_,_,_) max =
  MaxEq  : ('a,'a,'a) max
  | MaxFlip : ('a,'b,'c) max → ('b,'a,'c) max
  | MaxSuc  : ('a,'b,'a) max → ('a s,'b,'a s) max

let rec max : type a b c.(a,b,c) max → a → b → c
= fun mx m n → match mx,m with
  MaxEq , _      → m
  | MaxFlip mx' , _      → max mx' n m
  | MaxSuc mx' , S m' → S (max mx' m' n)
```

Type refinement

In the `MaxEq` branch: $a \equiv b, a \equiv c$
 $m : c$

In the `MaxFlip` branch: *no refinement*

In the `MaxSuc` branch: $a \equiv d\ s, c \equiv d\ s$ (for some d)
 $mx' : (d, b, d)\max$
 $m' : d$
 $\max\ mx'\ m'\ n : d$

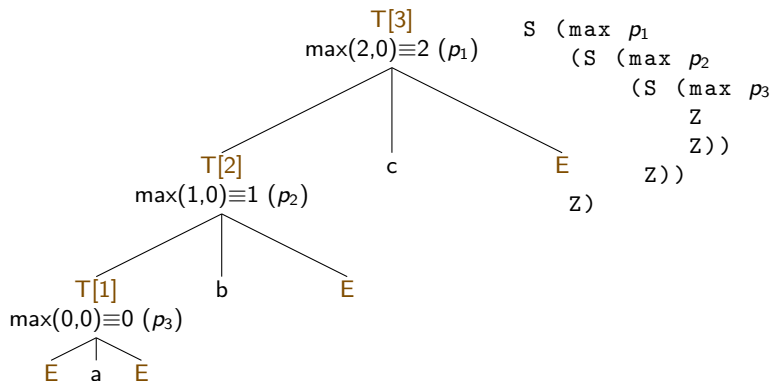
Functions on depth-annotated trees

```
val ? : ('a,'n) dtree → 'n
```

```
val ? : ('a,'n s) dtree → 'a
```

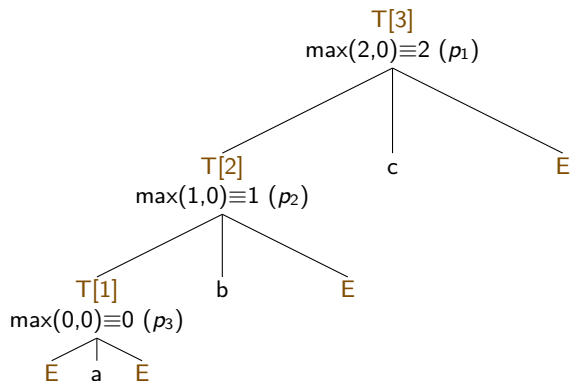
```
val ? : ('a,'n) dtree → ('a,'n) dtree
```

Depth-annotated trees: depth



```
let rec depthD : type a n.(a,n) dtree → n =  
  function  
    EmptyD → Z  
  | TreeD (l,_,r,mx) → S (max mx (depthD l) (depthD r))
```

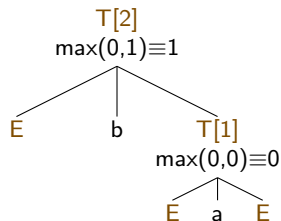
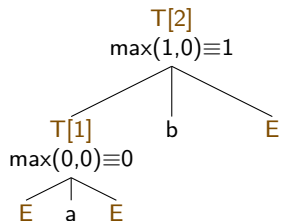
Depth-annotated trees: top



c

```
let topD : type a n.(a,n s) dtree → a =  
  function TreeD (_,v,_,_) → v
```


Depth-annotated trees: swivel



```
let rec swivelD :
  type a n.(a,n) dtree → (a,n) dtree =
  function
    EmptyD → EmptyD
  | TreeD (l,v,r,m) →
    TreeD (swivelD r, v, swivelD l, MaxFlip m)
```

Next time

GADTs in practice