

III. Linear Programming

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CAMBRIDGE

Outline

Introduction

Standard and Slack Forms

Formulating Problems as Linear Programs

Simplex Algorithm

Finding an Initial Solution



Linear Programming (informal definition)

- maximize or minimize an objective, given limited resources and competing constraint
- constraints are specified as (in)equalities



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- Imagine you are a politician trying to win an election
- Your district has three different types of areas: Urban, suburban and rural, each with, respectively, 100,000, 200,000 and 50,000 registered voters



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- Imagine you are a politician trying to win an election
- Your district has three different types of areas: Urban, suburban and rural, each with, respectively, 100,000, 200,000 and 50,000 registered voters
- **Aim:** at least half of the registered voters in each of the three regions should vote for you



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Example: Political Advertising

- Imagine you are a politician trying to win an election
- Your district has three different types of areas: Urban, suburban and rural, each with, respectively, 100,000, 200,000 and 50,000 registered voters
- **Aim:** at least half of the registered voters in each of the three regions should vote for you
- **Possible Actions:** Advertise on one of the primary issues which are (i) building more roads, (ii) gun control, (iii) farm subsidies and (iv) a gasoline tax dedicated to improve public transit.



Political Advertising Continued

policy	urban	suburban	rural
build roads	-2	5	3
gun control	8	2	-5
farm subsidies	0	0	10
gasoline tax	10	0	-2

The effects of policies on voters. Each entry describes the number of thousands of voters who could be **won** (**lost**) over by spending \$1,000 on advertising support of a policy on a particular issue.



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- Possible Solution:
 - \$20,000 on advertising to building roads
 - \$0 on advertising to gun control
 - \$4,000 on advertising to farm subsidies
 - \$9,000 on advertising to a gasoline tax



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What is the best possible strategy?



Towards a Linear Program

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Constraints:



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- $-2x_1 + 8x_2 + 0x_3 + 10x_4 \geq 50$



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- $-2x_1 + 8x_2 + 0x_3 + 10x_4 \geq 50$
- $5x_1 + 2x_2 + 0x_3 + 0x_4 \geq 100$
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Objective: Minimize $x_1 + x_2 + x_3 + x_4$



The Linear Program

Linear Program for the Advertising Problem

$$\begin{array}{llllllll} \text{minimize} & x_1 & + & x_2 & + & x_3 & + & x_4 \\ \text{subject to} & & & & & & & \\ & -2x_1 & + & 8x_2 & + & 0x_3 & + & 10x_4 & \geq & 50 \\ & 5x_1 & + & 2x_2 & + & 0x_3 & + & 0x_4 & \geq & 100 \\ & 3x_1 & - & 5x_2 & + & 10x_3 & - & 2x_4 & \geq & 25 \\ & & & x_1, x_2, x_3, x_4 & & & & & \geq & 0 \end{array}$$



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The solution of this linear program yields the optimal advertising strategy.



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Formal Definition of Linear Program

- Given a_1, a_2, \dots, a_n and a set of variables x_1, x_2, \dots, x_n , a **linear function** f is defined by

$$f(x_1, x_2, \dots, x_n) = a_1x_1 + a_2x_2 + \dots + a_nx_n.$$



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- Linear Equality:** $f(x_1, x_2, \dots, x_n) = b$



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- Linear Equality:** $f(x_1, x_2, \dots, x_n) = b$
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Linear Constraints



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- Linear Equality:** $f(x_1, x_2, \dots, x_n) = b$
- Linear Inequality:** $f(x_1, x_2, \dots, x_n) \geq b$ or $f(x_1, x_2, \dots, x_n) \leq b$
- Linear-Programming Problem:** either minimize or maximize a linear function subject to a set of linear constraints

Linear Constraints



A Small(er) Example

$$\begin{array}{llllll} \text{maximize} & x_1 & + & x_2 & & \\ \text{subject to} & & & & & \\ & 4x_1 & - & x_2 & \leq & 8 \\ & 2x_1 & + & x_2 & \leq & 10 \\ & 5x_1 & - & 2x_2 & \geq & -2 \\ & x_1, x_2 & & & \geq & 0 \end{array}$$



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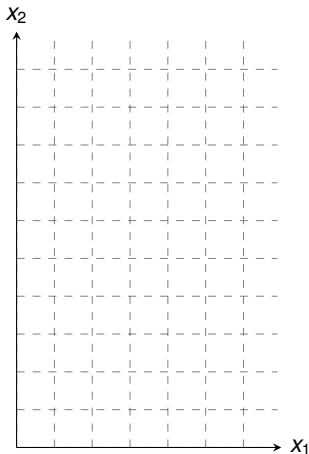
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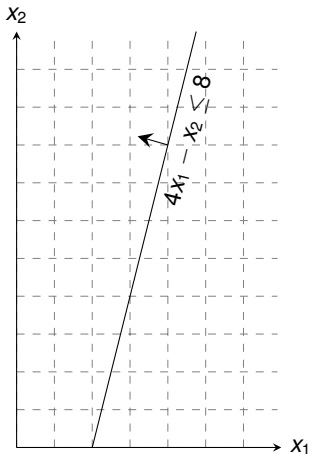
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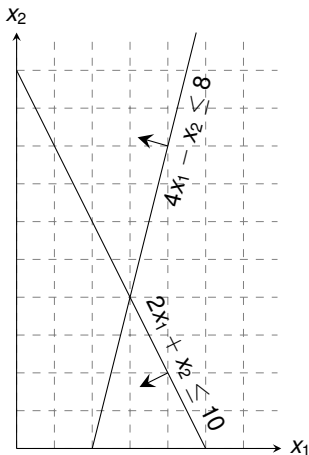
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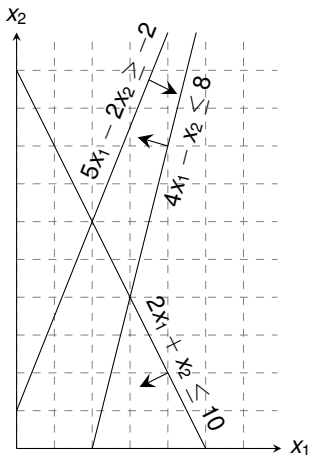
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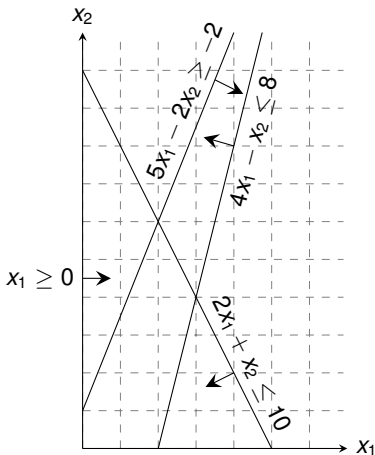
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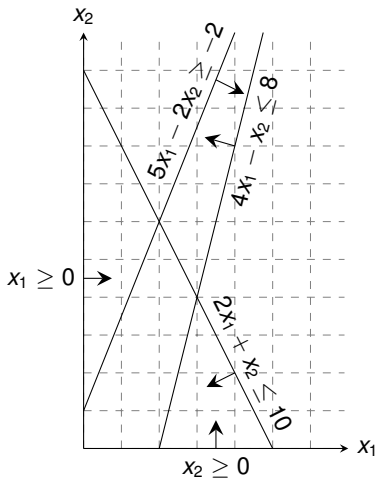
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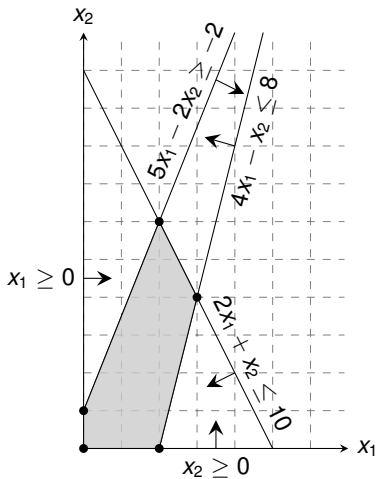
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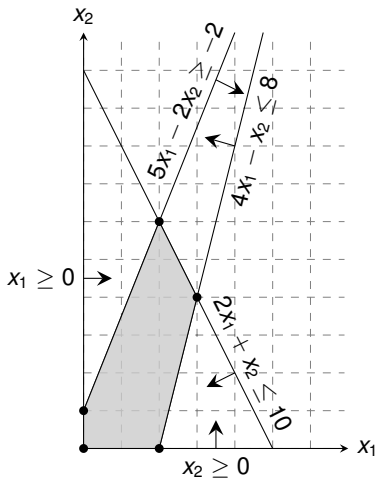
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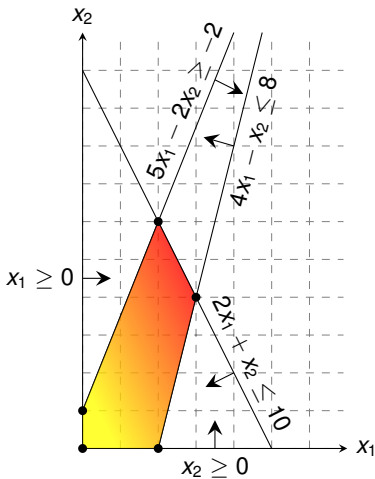
Graphical Procedure: Move the line $x_1 + x_2 = z$ as far up as possible.



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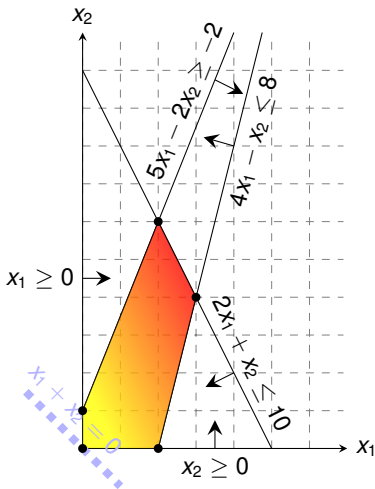
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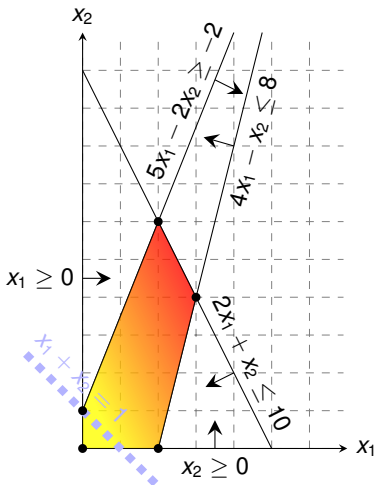
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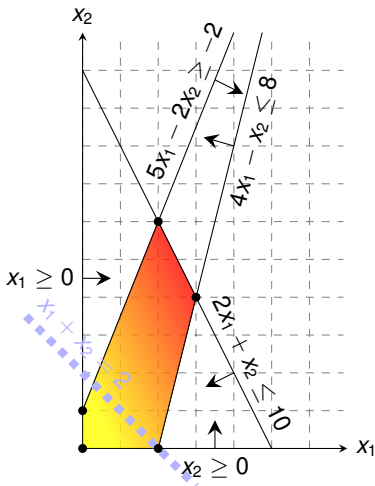
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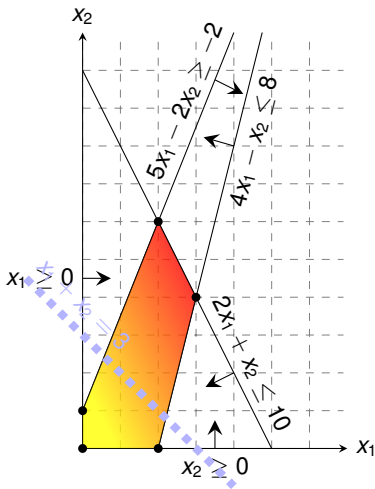
Graphical Procedure: Move the line $x_1 + x_2 = z$ as far up as possible.



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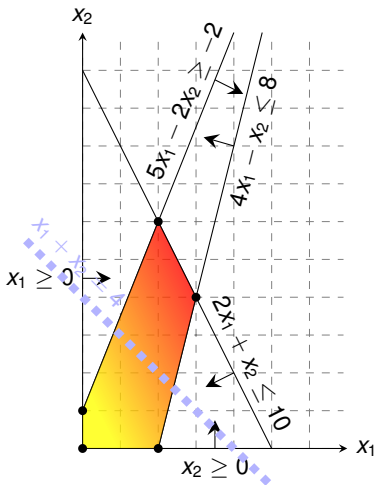
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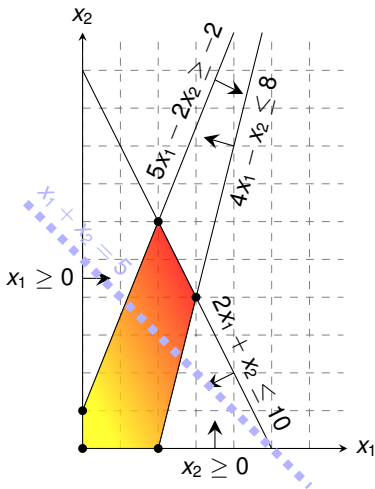
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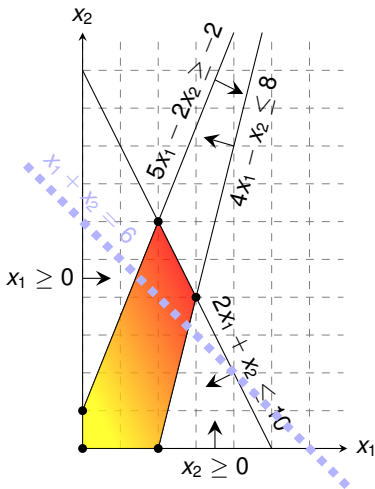
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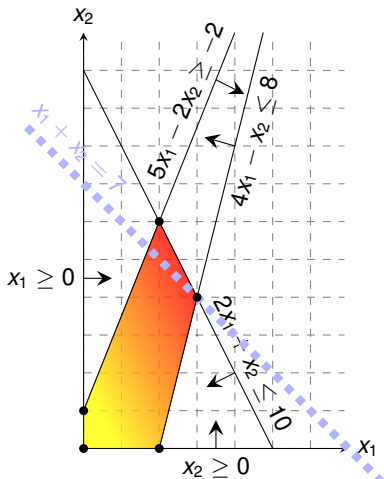
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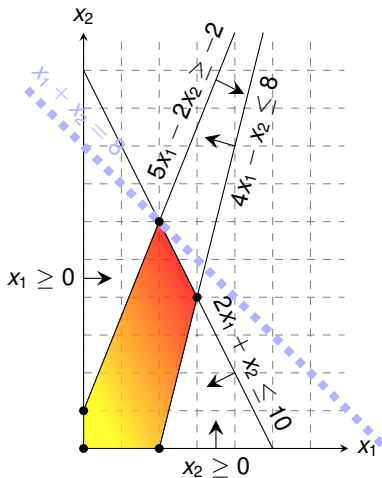
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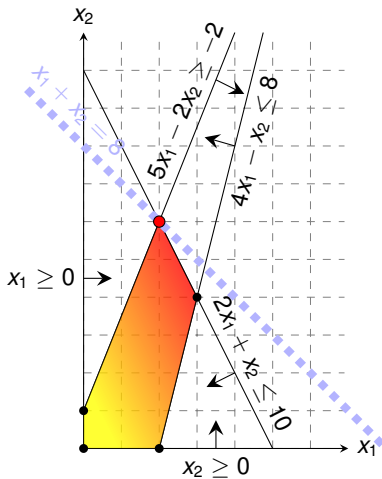
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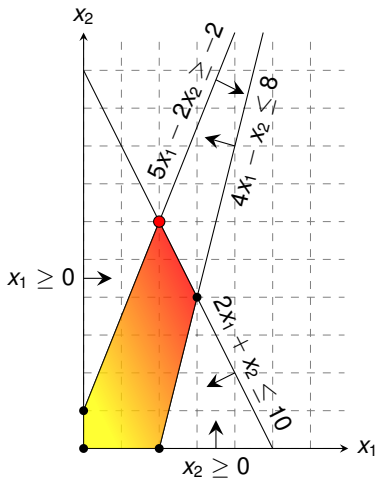
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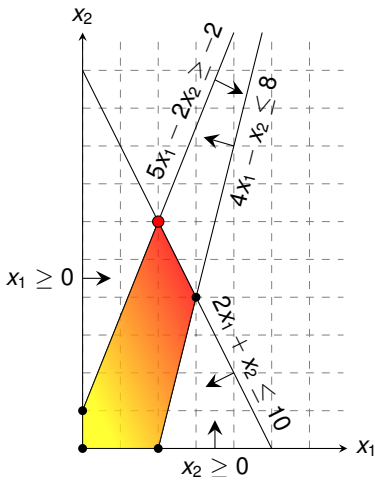
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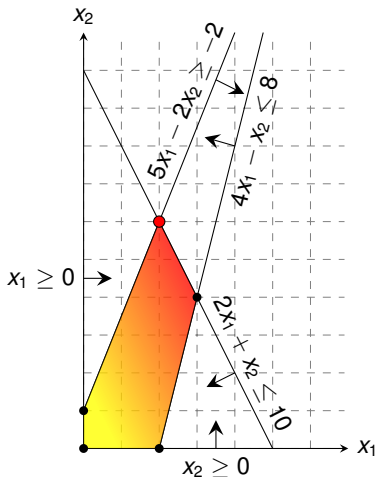
While the same approach also works for higher-dimensions, we need to take a more systematic and algebraic procedure.



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Outline

Introduction

Standard and Slack Forms

Formulating Problems as Linear Programs

Simplex Algorithm

Finding an Initial Solution



Standard and Slack Forms

Standard Form

$$\text{maximize} \quad \sum_{j=1}^n c_j x_j$$

subject to

$$\sum_{j=1}^n a_{ij} x_j \leq b_i \quad \text{for } i = 1, 2, \dots, m$$
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Non-Negativity Constraints

Standard Form (Matrix-Vector-Notation)

maximize $c^T x$ Inner product of two vectors

subject to

$Ax \leq b$ Matrix-vector product
 $x \geq 0$



Converting Linear Programs into Standard Form

Reasons for a LP not being in standard form:

1. The objective might be a **minimization** rather than **maximization**.
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When switching from maximization to minimization, sign of objective value changes.



Converting into Standard Form (1/5)

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It is always possible to convert a linear program into standard form.



Converting Standard Form into Slack Form (1/3)

Goal: Convert **standard form** into **slack form**, where all constraints except for the non-negativity constraints are equalities.



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- Denote slack variable of the i th inequality by x_{n+i}



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maximize
subject to

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Introduce slack variables

subject to

$$x_4 = 7 - x_1 - x_2 + x_3$$



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maximize
subject to

$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & x_1, x_2, x_3 & & & \geq & 0 \end{array}$$



Introduce slack variables

subject to

$$\begin{array}{rcccccc} x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \end{array}$$



Converting Standard Form into Slack Form (2/3)

maximize
subject to

$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & x_1, x_2, x_3 & & & \geq & 0 \end{array}$$



Introduce slack variables

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$$\begin{array}{rcccccc} x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \\ x_6 & = & 4 & - & x_1 & + & 2x_2 & - & 2x_3 \end{array}$$



Converting Standard Form into Slack Form (2/3)

maximize
subject to

$$\begin{array}{rcccccc} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & & & & \geq & 0 \end{array}$$

x_1, x_2, x_3



Introduce slack variables

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$$\begin{array}{rcccccc} x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \\ x_6 & = & 4 & - & x_1 & + & 2x_2 & - & 2x_3 \\ & & & & & & & & \geq & 0 \end{array}$$

$x_1, x_2, x_3, x_4, x_5, x_6$



Converting Standard Form into Slack Form (2/3)

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$$\begin{array}{rccccrcr} 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_1 & + & x_2 & - & x_3 & \leq & 7 \\ -x_1 & - & x_2 & + & x_3 & \leq & -7 \\ x_1 & - & 2x_2 & + & 2x_3 & \leq & 4 \\ & & & & & \geq & 0 \end{array}$$

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Converting Standard Form into Slack Form (3/3)

$$\begin{array}{rcl} \text{maximize} & & 2x_1 - 3x_2 + 3x_3 \\ \text{subject to} & & \\ x_4 = & 7 & -x_1 - x_2 + x_3 \\ x_5 = & -7 & +x_1 + x_2 - x_3 \\ x_6 = & 4 & -x_1 + 2x_2 - 2x_3 \\ x_1, x_2, x_3, x_4, x_5, x_6 & & \geq 0 \end{array}$$



Converting Standard Form into Slack Form (3/3)

maximize
subject to

$$\begin{array}{rccccr} & & & 2x_1 & - & 3x_2 & + & 3x_3 & & \\ x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 & \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 & \\ x_6 & = & 4 & - & x_1 & + & 2x_2 & - & 2x_3 & \\ & & & & x_1, x_2, x_3, x_4, x_5, x_6 & & \geq & 0 & & \end{array}$$

↓
Use variable z to denote objective function
and omit the nonnegativity constraints.



Converting Standard Form into Slack Form (3/3)

$$\begin{array}{l} \text{maximize} \\ \text{subject to} \end{array} \quad \begin{array}{r} 2x_1 - 3x_2 + 3x_3 \\ x_4 = 7 - x_1 - x_2 + x_3 \\ x_5 = -7 + x_1 + x_2 - x_3 \\ x_6 = 4 - x_1 + 2x_2 - 2x_3 \\ x_1, x_2, x_3, x_4, x_5, x_6 \geq 0 \end{array}$$

Use variable z to denote objective function and omit the nonnegativity constraints.

$$\begin{array}{l} z = 2x_1 - 3x_2 + 3x_3 \\ x_4 = 7 - x_1 - x_2 + x_3 \\ x_5 = -7 + x_1 + x_2 - x_3 \\ x_6 = 4 - x_1 + 2x_2 - 2x_3 \end{array}$$



Converting Standard Form into Slack Form (3/3)

$$\begin{array}{ll} \text{maximize} & 2x_1 - 3x_2 + 3x_3 \\ \text{subject to} & \\ x_4 = & 7 - x_1 - x_2 + x_3 \\ x_5 = & -7 + x_1 + x_2 - x_3 \\ x_6 = & 4 - x_1 + 2x_2 - 2x_3 \\ & x_1, x_2, x_3, x_4, x_5, x_6 \geq 0 \end{array}$$

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This is called **slack form**.



Basic and Non-Basic Variables

$$\begin{array}{rclclclcl} Z & = & & & 2x_1 & - & 3x_2 & + & 3x_3 \\ x_4 & = & 7 & - & x_1 & - & x_2 & + & x_3 \\ x_5 & = & -7 & + & x_1 & + & x_2 & - & x_3 \\ x_6 & = & 4 & - & x_1 & + & 2x_2 & - & 2x_3 \end{array}$$



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Basic Variables: $B = \{4, 5, 6\}$



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Slack Form (Formal Definition)

Slack form is given by a tuple (N, B, A, b, c, v) so that

$$z = v + \sum_{j \in N} c_j x_j$$

$$x_i = b_i - \sum_{j \in N} a_{ij} x_j \quad \text{for } i \in B,$$

and all variables are non-negative.



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and all variables are non-negative.

Variables/Coefficients on the right hand side are indexed by B and N .



Slack Form (Example)

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$



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Slack Form Notation



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$$A = \begin{pmatrix} a_{13} & a_{15} & a_{16} \\ a_{23} & a_{25} & a_{26} \\ a_{43} & a_{45} & a_{46} \end{pmatrix} = \begin{pmatrix} -1/6 & -1/6 & 1/3 \\ 8/3 & 2/3 & -1/3 \\ 1/2 & -1/2 & 0 \end{pmatrix}$$



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-

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- $v = 28$



The Structure of Optimal Solutions

Definition

A point x is a **vertex** if it cannot be represented as a strict convex combination of two other points in the feasible set.



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The set of feasible solutions is a convex set.



The Structure of Optimal Solutions

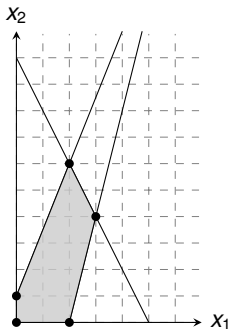
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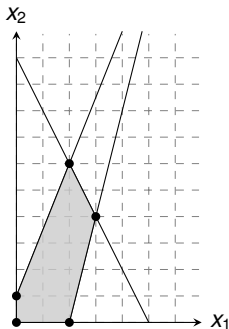
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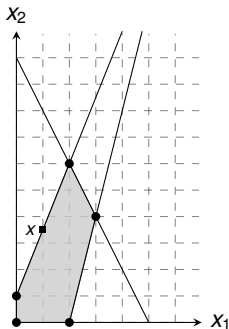
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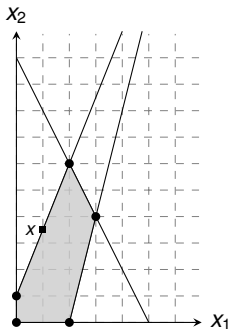
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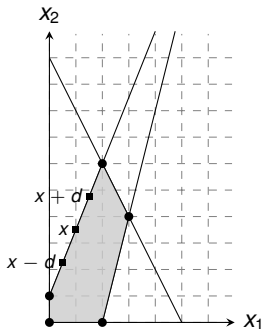
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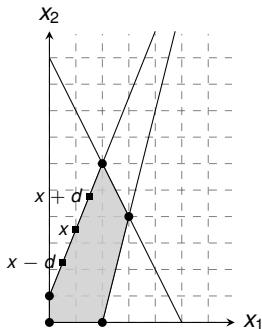
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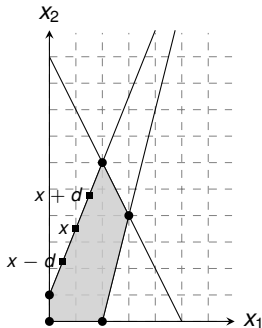
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- W.l.o.g. assume $c^T d \geq 0$ (otherwise replace d by $-d$)



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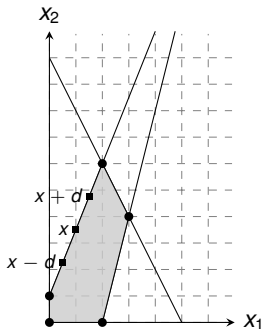
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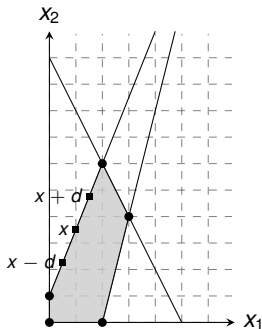
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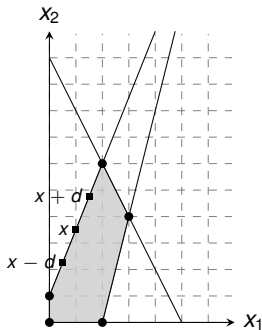
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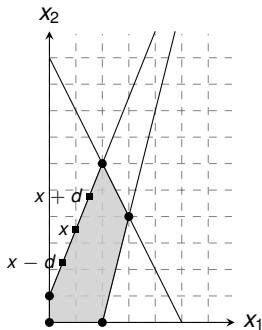
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 - $x + \lambda' d$ feasible, since $A(x + \lambda' d) = Ax = b$ and $x + \lambda' d \geq 0$



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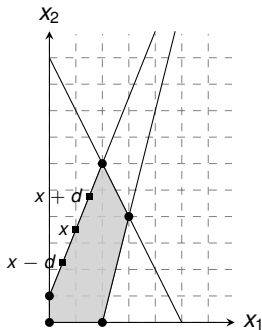
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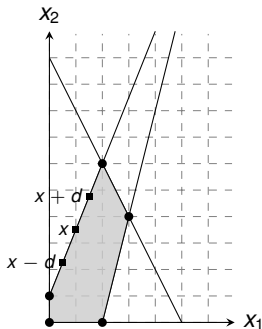
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The Structure of Optimal Solutions

Definition

A point x is a **vertex** if it cannot be represented as a strict convex combination of two other points in the feasible set.

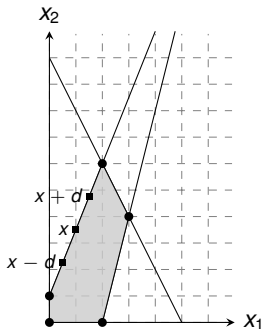
The set of feasible solutions is a convex set.

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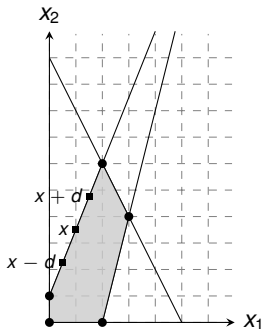
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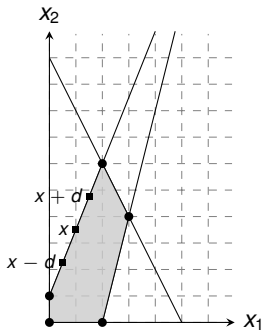
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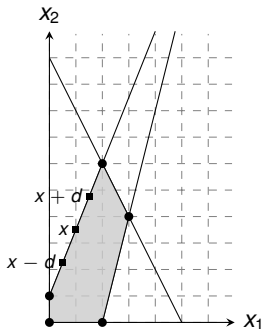
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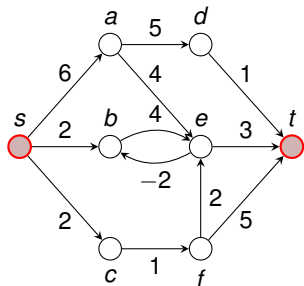
Finding an Initial Solution



Shortest Paths

Single-Pair Shortest Path Problem

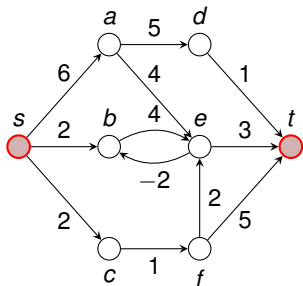
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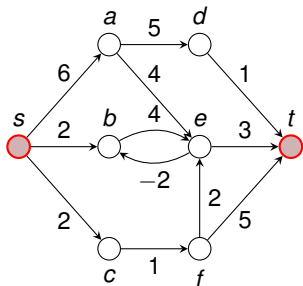


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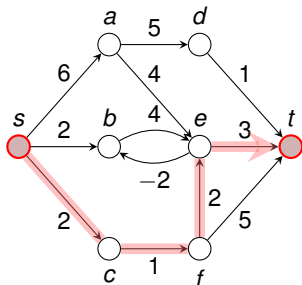


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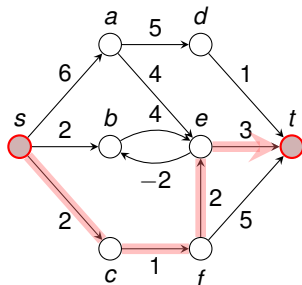


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Shortest Paths as LP

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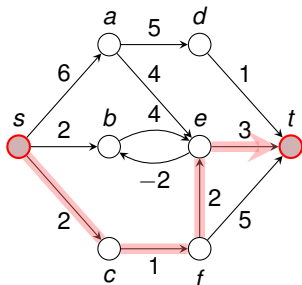


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$$\begin{aligned} d_v &\leq d_u + w(u, v) && \text{for each edge } (u, v) \in E, \\ d_s &= 0. \end{aligned}$$

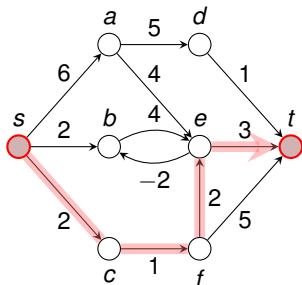


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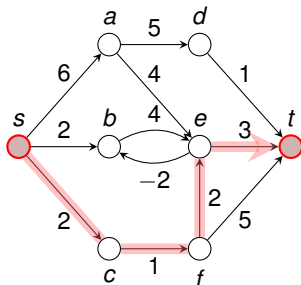


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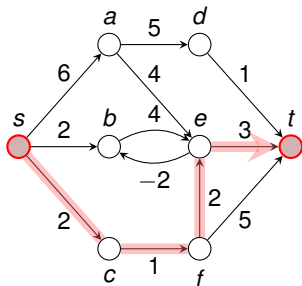


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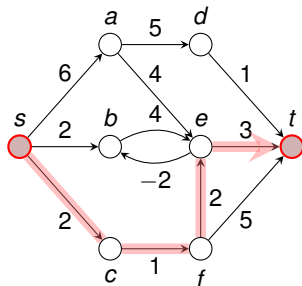


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Solution \bar{d} satisfies $\bar{d}_v = \min_{u: (u,v) \in E} \{ \bar{d}_u + w(u, v) \}$



Maximum Flow

Maximum Flow Problem

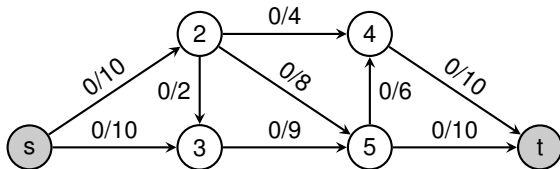
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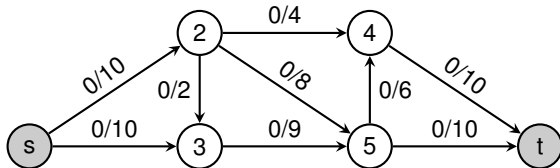
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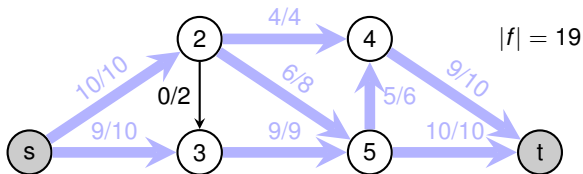
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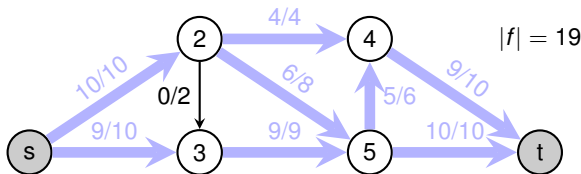
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Minimum-Cost Flow

Extension of the Maximum Flow Problem

Minimum-Cost-Flow Problem



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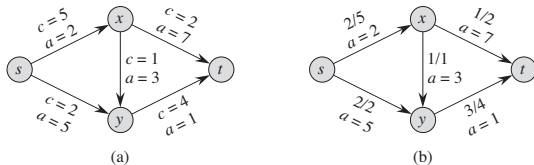


Figure 29.3 (a) An example of a minimum-cost-flow problem. We denote the capacities by c and the costs by a . Vertex s is the source and vertex t is the sink, and we wish to send 4 units of flow from s to t . (b) A solution to the minimum-cost flow problem in which 4 units of flow are sent from s to t . For each edge, the flow and capacity are written as flow/capacity.



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Optimal Solution with total cost:

$$\sum_{(u,v) \in E} a(u,v)f_{uv} = (2 \cdot 2) + (5 \cdot 2) + (3 \cdot 1) + (7 \cdot 1) + (1 \cdot 3) = 27$$

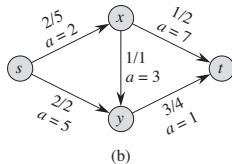
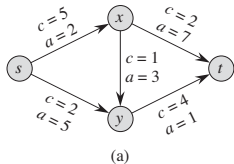


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Real power of Linear Programming comes from the ability to solve **new problems!**



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- Each iteration corresponds to a “basic solution” of the slack form
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In that sense, it is a **greedy algorithm**.



Extended Example: Conversion into Slack Form

$$\begin{array}{rcllcll} \text{maximize} & 3x_1 & + & x_2 & + & 2x_3 & & \\ \text{subject to} & & & & & & & \\ & x_1 & + & x_2 & + & 3x_3 & \leq & 30 \\ & 2x_1 & + & 2x_2 & + & 5x_3 & \leq & 24 \\ & 4x_1 & + & x_2 & + & 2x_3 & \leq & 36 \\ & & & x_1, x_2, x_3 & & & \geq & 0 \end{array}$$



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Conversion into slack form



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Conversion into slack form

$$\begin{array}{llllllll} z & = & & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$



Extended Example: Iteration 1

$$z = 3x_1 + x_2 + 2x_3$$

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Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (0, 0, 0, 30, 24, 36)$



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This basic solution is **feasible**

Objective value is 0.



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Increasing the value of x_1 would increase the objective value.

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$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (0, 0, 0, 30, 24, 36)$

This basic solution is **feasible**

Objective value is 0.



Extended Example: Iteration 1

Increasing the value of x_1 would increase the objective value.

$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

$$x_5 = 24 - 2x_1 - 2x_2 - 5x_3$$

$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

The third constraint is the tightest and limits how much we can increase x_1 .



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The third constraint is the tightest and limits how much we can increase x_1 .

Switch roles of x_1 and x_6 :

- Solving for x_1 yields:

$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}.$$



Extended Example: Iteration 1

Increasing the value of x_1 would increase the objective value.

$$z = 3x_1 + x_2 + 2x_3$$

$$x_4 = 30 - x_1 - x_2 - 3x_3$$

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$$x_6 = 36 - 4x_1 - x_2 - 2x_3$$

The third constraint is the tightest and limits how much we can increase x_1 .

Switch roles of x_1 and x_6 :

- Solving for x_1 yields:

$$x_1 = 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4}.$$

- Substitute this into x_1 in the other three equations



Extended Example: Iteration 2

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$



Extended Example: Iteration 2

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (9, 0, 0, 21, 6, 0)$ with objective value 27



Extended Example: Iteration 2

Increasing the value of x_3 would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (9, 0, 0, 21, 6, 0)$ with objective value 27



Extended Example: Iteration 2

Increasing the value of x_3 would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

The third constraint is the tightest and limits how much we can increase x_3 .



Extended Example: Iteration 2

Increasing the value of x_3 would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

The third constraint is the tightest and limits how much we can increase x_3 .

Switch roles of x_3 and x_5 :



Extended Example: Iteration 2

Increasing the value of x_3 would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

The third constraint is the tightest and limits how much we can increase x_3 .

Switch roles of x_3 and x_5 :

- Solving for x_3 yields:

$$x_3 = \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} - \frac{x_6}{8}.$$



Extended Example: Iteration 2

Increasing the value of x_3 would increase the objective value.

$$\begin{aligned}z &= 27 + \frac{x_2}{4} + \frac{x_3}{2} - \frac{3x_6}{4} \\x_1 &= 9 - \frac{x_2}{4} - \frac{x_3}{2} - \frac{x_6}{4} \\x_4 &= 21 - \frac{3x_2}{4} - \frac{5x_3}{2} + \frac{x_6}{4} \\x_5 &= 6 - \frac{3x_2}{2} - 4x_3 + \frac{x_6}{2}\end{aligned}$$

The third constraint is the tightest and limits how much we can increase x_3 .

Switch roles of x_3 and x_5 :

- Solving for x_3 yields:

$$x_3 = \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} - \frac{x_6}{8}.$$

- Substitute this into x_3 in the other three equations



Extended Example: Iteration 3

$$\begin{aligned} z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\ x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\ x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\ x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16} \end{aligned}$$



Extended Example: Iteration 3

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (\frac{33}{4}, 0, \frac{3}{2}, \frac{69}{4}, 0, 0)$ with objective value $\frac{111}{4} = 27.75$



Extended Example: Iteration 3

Increasing the value of x_2 would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (\frac{33}{4}, 0, \frac{3}{2}, \frac{69}{4}, 0, 0)$ with objective value $\frac{111}{4} = 27.75$



Extended Example: Iteration 3

Increasing the value of x_2 would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase x_2 .



Extended Example: Iteration 3

Increasing the value of x_2 would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase x_2 .

Switch roles of x_2 and x_3 :



Extended Example: Iteration 3

Increasing the value of x_2 would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase x_2 .

Switch roles of x_2 and x_3 :

- Solving for x_2 yields:

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3}.$$



Extended Example: Iteration 3

Increasing the value of x_2 would increase the objective value.

$$\begin{aligned}z &= \frac{111}{4} + \frac{x_2}{16} - \frac{x_5}{8} - \frac{11x_6}{16} \\x_1 &= \frac{33}{4} - \frac{x_2}{16} + \frac{x_5}{8} - \frac{5x_6}{16} \\x_3 &= \frac{3}{2} - \frac{3x_2}{8} - \frac{x_5}{4} + \frac{x_6}{8} \\x_4 &= \frac{69}{4} + \frac{3x_2}{16} + \frac{5x_5}{8} - \frac{x_6}{16}\end{aligned}$$

The second constraint is the tightest and limits how much we can increase x_2 .

Switch roles of x_2 and x_3 :

- Solving for x_2 yields:

$$x_2 = 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3}.$$

- Substitute this into x_2 in the other three equations



Extended Example: Iteration 4

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$



Extended Example: Iteration 4

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$

Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (8, 4, 0, 18, 0, 0)$ with objective value 28



Extended Example: Iteration 4

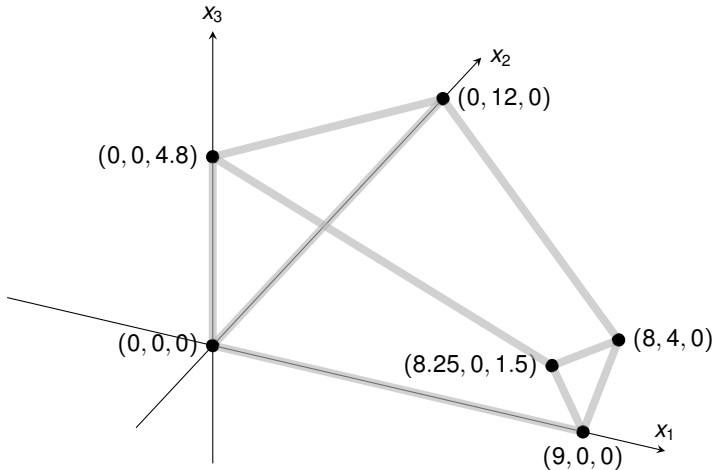
All coefficients are negative, and hence this basic solution is **optimal!**

$$\begin{aligned}z &= 28 - \frac{x_3}{6} - \frac{x_5}{6} - \frac{2x_6}{3} \\x_1 &= 8 + \frac{x_3}{6} + \frac{x_5}{6} - \frac{x_6}{3} \\x_2 &= 4 - \frac{8x_3}{3} - \frac{2x_5}{3} + \frac{x_6}{3} \\x_4 &= 18 - \frac{x_3}{2} + \frac{x_5}{2}\end{aligned}$$

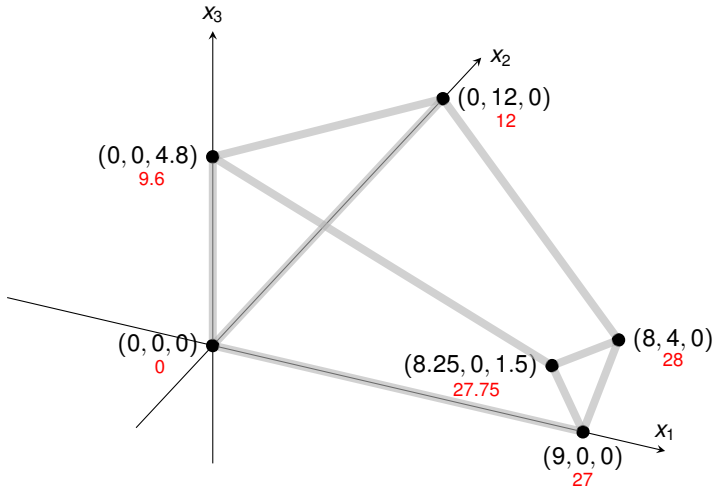
Basic solution: $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_6) = (8, 4, 0, 18, 0, 0)$ with objective value 28



Extended Example: Visualization of SIMPLEX



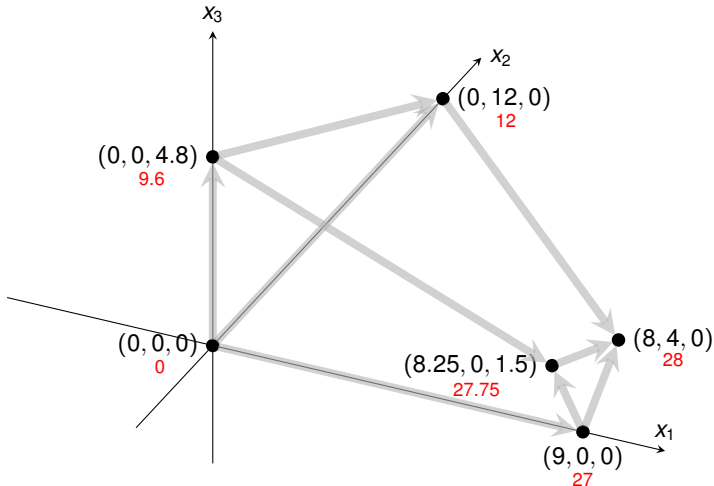
Extended Example: Visualization of SIMPLEX



Exercise: How many basic solutions (including non-feasible ones) are there?



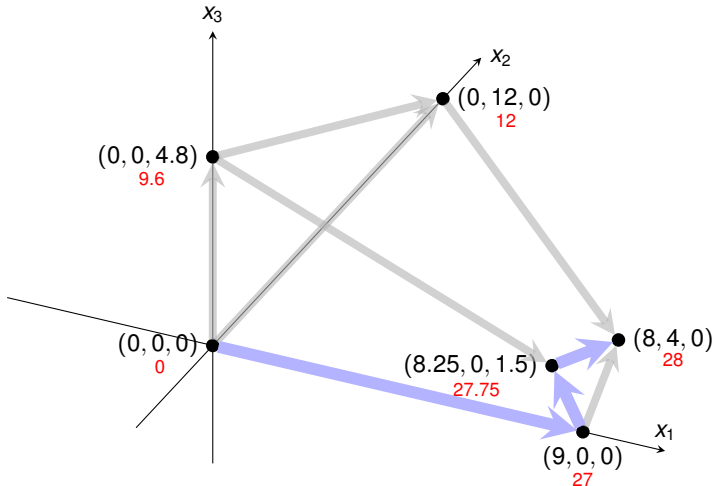
Extended Example: Visualization of SIMPLEX



Exercise: How many basic solutions (including non-feasible ones) are there?



Extended Example: Visualization of SIMPLEX



Exercise: How many basic solutions (including non-feasible ones) are there?



Extended Example: Alternative Runs (1/2)

$$\begin{aligned} z &= && 3x_1 &+& x_2 &+& 2x_3 \\ x_4 &= &30 &-& x_1 &-& x_2 &-& 3x_3 \\ x_5 &= &24 &-& 2x_1 &-& 2x_2 &-& 5x_3 \\ x_6 &= &36 &-& 4x_1 &-& x_2 &-& 2x_3 \end{aligned}$$



Extended Example: Alternative Runs (1/2)

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

↓ Switch roles of x_2 and x_5



Extended Example: Alternative Runs (1/2)

$$\begin{aligned}z &= && 3x_1 & + & x_2 & + & 2x_3 \\x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3\end{aligned}$$

Switch roles of x_2 and x_5

$$\begin{aligned}z &= & 12 & + & 2x_1 & - & \frac{x_3}{2} & - & \frac{x_5}{2} \\x_2 &= & 12 & - & x_1 & - & \frac{5x_3}{2} & - & \frac{x_5}{2} \\x_4 &= & 18 & - & x_2 & - & \frac{x_3}{2} & + & \frac{x_5}{2} \\x_6 &= & 24 & - & 3x_1 & + & \frac{x_3}{2} & + & \frac{x_5}{2}\end{aligned}$$



Extended Example: Alternative Runs (1/2)

$$\begin{aligned}z &= && 3x_1 & + & x_2 & + & 2x_3 \\x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3\end{aligned}$$

Switch roles of x_2 and x_5

$$\begin{aligned}z &= & 12 & + & 2x_1 & - & \frac{x_3}{2} & - & \frac{x_5}{2} \\x_2 &= & 12 & - & x_1 & - & \frac{5x_3}{2} & - & \frac{x_5}{2} \\x_4 &= & 18 & - & x_2 & - & \frac{x_3}{2} & + & \frac{x_5}{2} \\x_6 &= & 24 & - & 3x_1 & + & \frac{x_3}{2} & + & \frac{x_5}{2}\end{aligned}$$

Switch roles of x_1 and x_6



Extended Example: Alternative Runs (1/2)

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

Switch roles of x_2 and x_5

$$\begin{array}{rclclcl} z & = & 12 & + & 2x_1 & - & \frac{x_3}{2} & - & \frac{x_5}{2} \\ x_2 & = & 12 & - & x_1 & - & \frac{5x_3}{2} & - & \frac{x_5}{2} \\ x_4 & = & 18 & - & x_2 & - & \frac{x_3}{2} & + & \frac{x_5}{2} \\ x_6 & = & 24 & - & 3x_1 & + & \frac{x_3}{2} & + & \frac{x_5}{2} \end{array}$$

Switch roles of x_1 and x_6

$$\begin{array}{rclclcl} z & = & 28 & - & \frac{x_3}{6} & - & \frac{x_5}{6} & - & \frac{2x_6}{3} \\ x_1 & = & 8 & + & \frac{x_3}{6} & + & \frac{x_5}{6} & - & \frac{x_6}{3} \\ x_2 & = & 4 & - & \frac{8x_3}{3} & - & \frac{2x_5}{3} & + & \frac{x_6}{3} \\ x_4 & = & 18 & - & \frac{x_3}{2} & + & \frac{x_5}{2} & & \end{array}$$



Extended Example: Alternative Runs (2/2)

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$



Extended Example: Alternative Runs (2/2)

$$\begin{array}{rclclcl} z & = & & 3x_1 & + & x_2 & + & 2x_3 \\ x_4 & = & 30 & - & x_1 & - & x_2 & - & 3x_3 \\ x_5 & = & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\ x_6 & = & 36 & - & 4x_1 & - & x_2 & - & 2x_3 \end{array}$$

↓ Switch roles of x_3 and x_5



Extended Example: Alternative Runs (2/2)

$$\begin{aligned}z &= && 3x_1 & + & x_2 & + & 2x_3 \\x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3\end{aligned}$$

Switch roles of x_3 and x_5

$$\begin{aligned}z &= & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\x_4 &= & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\x_3 &= & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\x_6 &= & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}\end{aligned}$$



Extended Example: Alternative Runs (2/2)

$$\begin{aligned}z &= && 3x_1 & + & x_2 & + & 2x_3 \\x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3\end{aligned}$$

Switch roles of x_3 and x_5

$$\begin{aligned}z &= & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\x_4 &= & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\x_3 &= & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\x_6 &= & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}\end{aligned}$$

Switch roles of x_1 and x_6



Extended Example: Alternative Runs (2/2)

$$\begin{aligned}
 z &= && 3x_1 & + & x_2 & + & 2x_3 \\
 x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\
 x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\
 x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3
 \end{aligned}$$

Switch roles of x_3 and x_5

$$\begin{aligned}
 z &= & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\
 x_4 &= & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\
 x_3 &= & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\
 x_6 &= & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}
 \end{aligned}$$

Switch roles of x_1 and x_6

$$\begin{aligned}
 z &= & \frac{111}{4} & + & \frac{x_2}{16} & - & \frac{x_5}{8} & - & \frac{11x_6}{16} \\
 x_1 &= & \frac{33}{4} & - & \frac{x_2}{16} & + & \frac{x_5}{8} & - & \frac{5x_6}{16} \\
 x_3 &= & \frac{3}{2} & - & \frac{3x_2}{8} & - & \frac{x_5}{4} & + & \frac{x_6}{8} \\
 x_4 &= & \frac{69}{4} & + & \frac{3x_2}{16} & + & \frac{5x_5}{8} & - & \frac{x_6}{16}
 \end{aligned}$$



Extended Example: Alternative Runs (2/2)

$$\begin{aligned}
 z &= && 3x_1 & + & x_2 & + & 2x_3 \\
 x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\
 x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\
 x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3
 \end{aligned}$$

Switch roles of x_3 and x_5

$$\begin{aligned}
 z &= & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\
 x_4 &= & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\
 x_3 &= & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\
 x_6 &= & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}
 \end{aligned}$$

Switch roles of x_1 and x_6

Switch roles of x_2 and x_3

$$\begin{aligned}
 z &= & \frac{111}{4} & + & \frac{x_2}{16} & - & \frac{x_5}{8} & - & \frac{11x_6}{16} \\
 x_1 &= & \frac{33}{4} & - & \frac{x_2}{16} & + & \frac{x_5}{8} & - & \frac{5x_6}{16} \\
 x_3 &= & \frac{3}{2} & - & \frac{3x_2}{8} & - & \frac{x_5}{4} & + & \frac{x_6}{8} \\
 x_4 &= & \frac{69}{4} & + & \frac{3x_2}{16} & + & \frac{5x_5}{8} & - & \frac{x_6}{16}
 \end{aligned}$$



Extended Example: Alternative Runs (2/2)

$$\begin{aligned}
 z &= && 3x_1 & + & x_2 & + & 2x_3 \\
 x_4 &= & 30 & - & x_1 & - & x_2 & - & 3x_3 \\
 x_5 &= & 24 & - & 2x_1 & - & 2x_2 & - & 5x_3 \\
 x_6 &= & 36 & - & 4x_1 & - & x_2 & - & 2x_3
 \end{aligned}$$

Switch roles of x_3 and x_5

$$\begin{aligned}
 z &= & \frac{48}{5} & + & \frac{11x_1}{5} & + & \frac{x_2}{5} & - & \frac{2x_5}{5} \\
 x_4 &= & \frac{78}{5} & + & \frac{x_1}{5} & + & \frac{x_2}{5} & + & \frac{3x_5}{5} \\
 x_3 &= & \frac{24}{5} & - & \frac{2x_1}{5} & - & \frac{2x_2}{5} & - & \frac{x_5}{5} \\
 x_6 &= & \frac{132}{5} & - & \frac{16x_1}{5} & - & \frac{x_2}{5} & + & \frac{2x_3}{5}
 \end{aligned}$$

Switch roles of x_1 and x_6

Switch roles of x_2 and x_3

$$\begin{aligned}
 z &= & \frac{111}{4} & + & \frac{x_2}{16} & - & \frac{x_5}{8} & - & \frac{11x_6}{16} \\
 x_1 &= & \frac{33}{4} & - & \frac{x_2}{16} & + & \frac{x_5}{8} & - & \frac{5x_6}{16} \\
 x_3 &= & \frac{3}{2} & - & \frac{3x_2}{8} & - & \frac{x_5}{4} & + & \frac{x_6}{8} \\
 x_4 &= & \frac{69}{4} & + & \frac{3x_2}{16} & + & \frac{5x_5}{8} & - & \frac{x_6}{16}
 \end{aligned}$$

$$\begin{aligned}
 z &= & 28 & - & \frac{x_3}{6} & - & \frac{x_5}{6} & - & \frac{2x_6}{3} \\
 x_1 &= & 8 & + & \frac{x_3}{6} & + & \frac{x_5}{6} & - & \frac{x_6}{3} \\
 x_2 &= & 4 & - & \frac{8x_3}{3} & - & \frac{2x_5}{3} & + & \frac{x_6}{3} \\
 x_4 &= & 18 & - & \frac{x_3}{2} & + & \frac{x_5}{2}
 \end{aligned}$$



The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
4 for each  $j \in N - \{e\}$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
6  $\hat{a}_{el} = 1/a_{le}$ 
7 // Compute the coefficients of the remaining constraints.
8 for each  $i \in B - \{l\}$ 
9      $\hat{b}_i = b_i - a_{ie}\hat{b}_e$ 
10    for each  $j \in N - \{e\}$ 
11         $\hat{a}_{ij} = a_{ij} - a_{ie}\hat{a}_{ej}$ 
12     $\hat{a}_{il} = -a_{ie}\hat{a}_{el}$ 
13 // Compute the objective function.
14  $\hat{v} = v + c_e\hat{b}_e$ 
15 for each  $j \in N - \{e\}$ 
16      $\hat{c}_j = c_j - c_e\hat{a}_{ej}$ 
17  $\hat{c}_l = -c_e\hat{a}_{el}$ 
18 // Compute new sets of basic and nonbasic variables.
19  $\hat{N} = N - \{e\} \cup \{l\}$ 
20  $\hat{B} = B - \{l\} \cup \{e\}$ 
21 return ( $\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v}$ )
```



The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
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19  $\hat{N} = N - \{e\} \cup \{l\}$ 
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21 return  $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$ 
```

Rewrite “tight” equation
for entering variable x_e .



The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
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21 return  $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$ 
```

Rewrite "tight" equation
for entering variable x_e .

Substituting x_e into
other equations.



The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
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11         $\hat{a}_{ij} = a_{ij} - a_{ie}\hat{a}_{ej}$ 
12         $\hat{a}_{il} = -a_{ie}\hat{a}_{el}$ 
13 // Compute the objective function.
14  $\hat{v} = v + c_e\hat{b}_e$ 
15 for each  $j \in N - \{e\}$ 
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21 return ( $\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v}$ )
```

Rewrite "tight" equation for entering variable x_e .

Substituting x_e into other equations.

Substituting x_e into objective function.



The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
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```

Rewrite "tight" equation for entering variable x_e .

Substituting x_e into other equations.

Substituting x_e into objective function.

Update non-basic and basic variables



The Pivot Step Formally

PIVOT(N, B, A, b, c, v, l, e)

```
1 // Compute the coefficients of the equation for new basic variable  $x_e$ .
2 let  $\hat{A}$  be a new  $m \times n$  matrix
3  $\hat{b}_e = b_l/a_{le}$ 
4 for each  $j \in N - \{e\}$  Need that  $a_{le} \neq 0!$ 
5      $\hat{a}_{ej} = a_{lj}/a_{le}$ 
6  $\hat{a}_{el} = 1/a_{le}$ 
7 // Compute the coefficients of the remaining constraints.
8 for each  $i \in B - \{l\}$ 
9      $\hat{b}_i = b_i - a_{ie}\hat{b}_e$ 
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21 return  $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$ 
```

Rewrite "tight" equation for entering variable x_e .

Substituting x_e into other equations.

Substituting x_e into objective function.

Update non-basic and basic variables



Effect of the Pivot Step

— Lemma 29.1 —

Consider a call to $\text{PIVOT}(N, B, A, b, c, v, l, e)$ in which $a_{le} \neq 0$. Let the values returned from the call be $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$, and let \bar{x} denote the basic solution after the call. Then



Effect of the Pivot Step

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1. $\bar{x}_j = 0$ for each $j \in \hat{N}$.
2. $\bar{x}_e = b_l/a_{le}$.
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Proof:



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1. holds since the basic solution always sets all non-basic variables to zero.



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Proof:

1. holds since the basic solution always sets all non-basic variables to zero.
2. When we set each non-basic variable to 0 in a constraint

$$x_i = \hat{b}_i - \sum_{j \in \hat{N}} \hat{a}_{ij} x_j,$$



Effect of the Pivot Step

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we have $\bar{x}_i = \widehat{b}_i$ for each $i \in \widehat{B}$.



Effect of the Pivot Step

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Consider a call to $\text{PIVOT}(N, B, A, b, c, v, l, e)$ in which $a_{le} \neq 0$. Let the values returned from the call be $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$, and let \bar{x} denote the basic solution after the call. Then

1. $\bar{x}_j = 0$ for each $j \in \hat{N}$.
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3. $\bar{x}_i = b_i - a_{ie}\hat{b}_e$ for each $i \in \hat{B} \setminus \{e\}$.

Proof:

1. holds since the basic solution always sets all non-basic variables to zero.
2. When we set each non-basic variable to 0 in a constraint

$$x_i = \hat{b}_i - \sum_{j \in \hat{N}} \hat{a}_{ij} x_j,$$

we have $\bar{x}_i = \hat{b}_i$ for each $i \in \hat{B}$. Hence $\bar{x}_e = \hat{b}_e = b_l/a_{le}$.



Effect of the Pivot Step

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$$x_i = \hat{b}_i - \sum_{j \in \hat{N}} \hat{a}_{ij} x_j,$$

we have $\bar{x}_i = \hat{b}_i$ for each $i \in \hat{B}$. Hence $\bar{x}_e = \hat{b}_e = b_l/a_{le}$.

3. After the substituting in the other constraints, we have



Effect of the Pivot Step

Lemma 29.1

Consider a call to $\text{PIVOT}(N, B, A, b, c, v, l, e)$ in which $a_{le} \neq 0$. Let the values returned from the call be $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$, and let \bar{x} denote the basic solution after the call. Then

1. $\bar{x}_j = 0$ for each $j \in \hat{N}$.
2. $\bar{x}_e = b_l/a_{le}$.
3. $\bar{x}_i = b_i - a_{ie}\hat{b}_e$ for each $i \in \hat{B} \setminus \{e\}$.

Proof:

1. holds since the basic solution always sets all non-basic variables to zero.
2. When we set each non-basic variable to 0 in a constraint

$$x_i = \hat{b}_i - \sum_{j \in \hat{N}} \hat{a}_{ij} x_j,$$

we have $\bar{x}_i = \hat{b}_i$ for each $i \in \hat{B}$. Hence $\bar{x}_e = \hat{b}_e = b_l/a_{le}$.

3. After the substituting in the other constraints, we have

$$\bar{x}_i = \hat{b}_i = b_i - a_{ie}\hat{b}_e.$$



Effect of the Pivot Step

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Consider a call to $\text{PIVOT}(N, B, A, b, c, v, l, e)$ in which $a_{le} \neq 0$. Let the values returned from the call be $(\hat{N}, \hat{B}, \hat{A}, \hat{b}, \hat{c}, \hat{v})$, and let \bar{x} denote the basic solution after the call. Then

1. $\bar{x}_j = 0$ for each $j \in \hat{N}$.
2. $\bar{x}_e = b_l/a_{le}$.
3. $\bar{x}_i = b_i - a_{ie}\hat{b}_e$ for each $i \in \hat{B} \setminus \{e\}$.

Proof:

1. holds since the basic solution always sets all non-basic variables to zero.
2. When we set each non-basic variable to 0 in a constraint

$$x_i = \hat{b}_i - \sum_{j \in \hat{N}} \hat{a}_{ij} x_j,$$

we have $\bar{x}_i = \hat{b}_i$ for each $i \in \hat{B}$. Hence $\bar{x}_e = \hat{b}_e = b_l/a_{le}$.

3. After the substituting in the other constraints, we have

$$\bar{x}_i = \hat{b}_i = b_i - a_{ie}\hat{b}_e. \quad \square$$



Questions:

- How do we determine whether a linear program is feasible?
- What do we do if the linear program is feasible, but the initial basic solution is not feasible?
- How do we determine whether a linear program is unbounded?
- How do we choose the entering and leaving variables?



Questions:

- How do we determine whether a linear program is feasible?
- What do we do if the linear program is feasible, but the initial basic solution is not feasible?
- How do we determine whether a linear program is unbounded?
- How do we choose the entering and leaving variables?

Example before was a particularly nice one!



The formal procedure SIMPLEX

SIMPLEX(A, b, c)

```
1  ( $N, B, A, b, c, v$ ) = INITIALIZE-SIMPLEX( $A, b, c$ )
2  let  $\Delta$  be a new vector of length  $n$ 
3  while some index  $j \in N$  has  $c_j > 0$ 
4      choose an index  $e \in N$  for which  $c_e > 0$ 
5      for each index  $i \in B$ 
6          if  $a_{ie} > 0$ 
7               $\Delta_i = b_i/a_{ie}$ 
8          else  $\Delta_i = \infty$ 
9      choose an index  $l \in B$  that minimizes  $\Delta_i$ 
10     if  $\Delta_l == \infty$ 
11         return “unbounded”
12     else ( $N, B, A, b, c, v$ ) = PIVOT( $N, B, A, b, c, v, l, e$ )
13 for  $i = 1$  to  $n$ 
14     if  $i \in B$ 
15          $\bar{x}_i = b_i$ 
16     else  $\bar{x}_i = 0$ 
17 return ( $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n$ )
```



The formal procedure **SIMPLEX**

SIMPLEX(A, b, c)

```
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16     else  $\bar{x}_i = 0$ 
17 return ( $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n$ )
```

Returns a slack form with a feasible basic solution (if it exists)



The formal procedure SIMPLEX

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```
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13 for  $i = 1$  to  $n$ 
14     if  $i \in B$ 
15          $\bar{x}_i = b_i$ 
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17 return ( $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n$ )
```

Returns a slack form with a feasible basic solution (if it exists)



The formal procedure SIMPLEX

SIMPLEX(A, b, c)

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10     if  $\Delta_l == \infty$ 
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Main Loop:

- terminates if all coefficients in objective function are negative
- Line 4 picks entering variable x_e with negative coefficient
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Lemma 29.2

Suppose the call to INITIALIZE-SIMPLEX in line 1 returns a slack form for which the basic solution is feasible. Then if SIMPLEX returns a solution, it is a feasible solution. If SIMPLEX returns "unbounded", the linear program is unbounded.



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Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.



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$$\begin{aligned} Z &= && x_1 & + & x_2 & + & x_3 \\ x_4 &= & 8 & - & x_1 & - & x_2 & \\ x_5 &= &&&&& x_2 & - & x_3 \end{aligned}$$



Termination

Degeneracy: One iteration of SIMPLEX leaves the objective value unchanged.

$$Z = \quad \quad \quad x_1 + x_2 + x_3$$

$$x_4 = 8 - x_1 - x_2$$

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↓ Pivot with x_1 entering and x_4 leaving



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Cycling: If additionally slack at two iterations are identical, SIMPLEX fails to terminate!



Cycling: SIMPLEX may fail to terminate.



Termination and Running Time

It is theoretically possible, but very rare in practice.

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1. **Bland's rule:** Choose entering variable with smallest index
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Replace each b_i by $\hat{b}_i = b_i + \epsilon_i$, where $\epsilon_i \gg \epsilon_{i+1}$ are all small.



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Assuming INITIALIZE-SIMPLEX returns a slack form for which the basic solution is feasible, SIMPLEX either reports that the program is unbounded or returns a feasible solution in at most $\binom{n+m}{m}$ iterations.



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Every set B of basic variables uniquely determines a slack form, and there are at most $\binom{n+m}{m}$ unique slack forms.



Outline

Introduction

Standard and Slack Forms

Formulating Problems as Linear Programs

Simplex Algorithm

Finding an Initial Solution



Finding an Initial Solution

$$\begin{array}{llllll} \text{maximize} & 2x_1 & - & x_2 & & \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & \leq & 2 \\ & x_1 & - & 5x_2 & \leq & -4 \\ & x_1, x_2 & & & \geq & 0 \end{array}$$



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Conversion into slack form



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Conversion into slack form

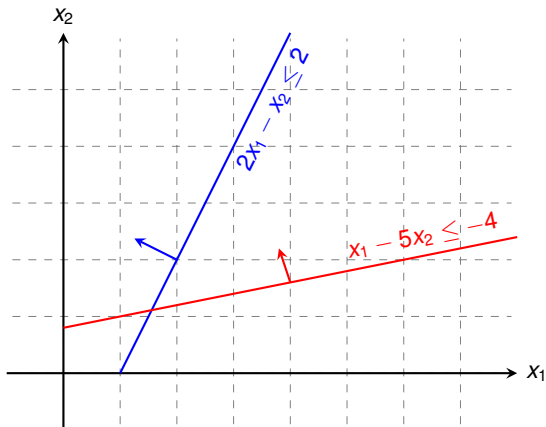
$$\begin{array}{rll} z & = & 2x_1 & - & x_2 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 \end{array}$$

Basic solution $(x_1, x_2, x_3, x_4) = (0, 0, 2, -4)$ is not feasible!



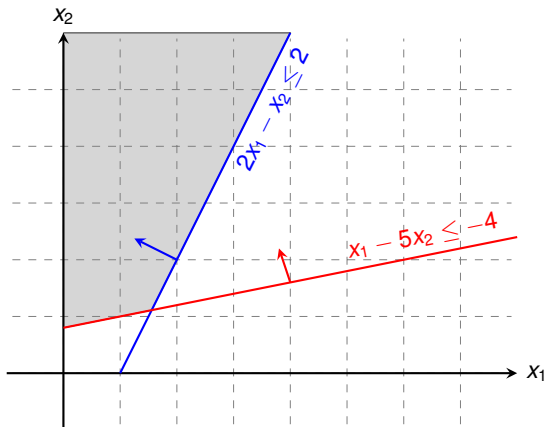
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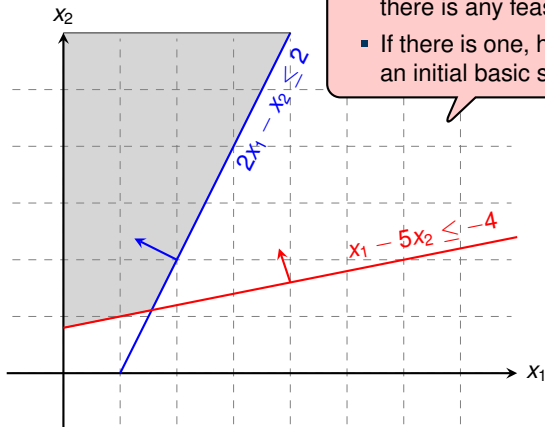
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Questions:

- How to determine whether there is any feasible solution?
- If there is one, how to determine an initial basic solution?



Formulating an Auxiliary Linear Program

maximize $\sum_{j=1}^n c_j x_j$
subject to

$$\begin{aligned} \sum_{j=1}^n a_{ij} x_j &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 1, 2, \dots, n \end{aligned}$$



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Let L_{aux} be the auxiliary LP of a linear program L in standard form. Then L is feasible if and only if the optimal objective value of L_{aux} is 0.



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Let L_{aux} be the auxiliary LP of a linear program L in standard form. Then L is feasible if and only if the optimal objective value of L_{aux} is 0.

Proof.

- “ \Rightarrow ”: Suppose L has a feasible solution $\bar{x} = (\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$
 - $\bar{x}_0 = 0$ combined with \bar{x} is a feasible solution to L_{aux} with objective value 0.
 - Since $\bar{x}_0 \geq 0$ and the objective is to maximize $-x_0$, this is optimal for L_{aux}



Formulating an Auxiliary Linear Program

maximize $\sum_{j=1}^n c_j x_j$
subject to

$$\begin{aligned} \sum_{j=1}^n a_{ij} x_j &\leq b_i && \text{for } i = 1, 2, \dots, m, \\ x_j &\geq 0 && \text{for } j = 1, 2, \dots, n \end{aligned}$$

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 - Then $\bar{x}_0 = 0$, and the remaining solution values $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$ satisfy L .



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INITIALIZE-SIMPLEX(A, b, c)

- 1 let k be the index of the minimum b_i
- 2 **if** $b_k \geq 0$ // is the initial basic solution feasible?
- 3 **return** $(\{1, 2, \dots, n\}, \{n+1, n+2, \dots, n+m\}, A, b, c, 0)$
- 4 form L_{aux} by adding $-x_0$ to the left-hand side of each constraint
and setting the objective function to $-x_0$
- 5 let (N, B, A, b, c, v) be the resulting slack form for L_{aux}
- 6 $l = n + k$
- 7 // L_{aux} has $n + 1$ nonbasic variables and m basic variables.
- 8 $(N, B, A, b, c, v) = \text{PIVOT}(N, B, A, b, c, v, l, 0)$
- 9 // The basic solution is now feasible for L_{aux} .
- 10 iterate the **while** loop of lines 3–12 of SIMPLEX until an optimal solution
to L_{aux} is found
- 11 **if** the optimal solution to L_{aux} sets \bar{x}_0 to 0
- 12 **if** \bar{x}_0 is basic
- 13 perform one (degenerate) pivot to make it nonbasic
- 14 from the final slack form of L_{aux} , remove x_0 from the constraints and
restore the original objective function of L , but replace each basic
variable in this objective function by the right-hand side of its
associated constraint
- 15 **return** the modified final slack form
- 16 **else return** “infeasible”



Test solution with $N = \{1, 2, \dots, n\}$, $B = \{n + 1, n + 2, \dots, n + m\}$, $\bar{x}_i = b_i$ for $i \in B$, $\bar{x}_i = 0$ otherwise.

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ℓ will be the leaving variable so that x_ℓ has the most negative value.



INITIALIZE-SIMPLEX

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ℓ will be the leaving variable so that x_ℓ has the most negative value.

Pivot step with x_ℓ leaving and x_0 entering.



INITIALIZE-SIMPLEX

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ℓ will be the leaving variable so that x_ℓ has the most negative value.

Pivot step with x_ℓ leaving and x_0 entering.

This pivot step does not change the value of any variable.



Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{llllll} \text{maximize} & 2x_1 & - & x_2 & & \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & \leq & 2 \\ & x_1 & - & 5x_2 & \leq & -4 \\ & & & x_1, x_2 & \geq & 0 \end{array}$$



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$$\begin{array}{llll} \text{maximize} & 2x_1 & - & x_2 \\ \text{subject to} & & & \\ & 2x_1 & - & x_2 \leq 2 \\ & x_1 & - & 5x_2 \leq -4 \\ & x_1, x_2 & & \geq 0 \end{array}$$

↓
Formulating the auxiliary linear program



Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{llll} \text{maximize} & 2x_1 & - & x_2 \\ \text{subject to} & & & \\ & 2x_1 & - & x_2 \leq 2 \\ & x_1 & - & 5x_2 \leq -4 \\ & & & x_1, x_2 \geq 0 \end{array}$$



Formulating the auxiliary linear program

$$\begin{array}{llllll} \text{maximize} & & & - & x_0 & \\ \text{subject to} & & & & & \\ & 2x_1 & - & x_2 & - & x_0 \leq 2 \\ & x_1 & - & 5x_2 & - & x_0 \leq -4 \\ & & & & & x_1, x_2, x_0 \geq 0 \end{array}$$



Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximize} & 2x_1 - x_2 \\ \text{subject to} & \\ & 2x_1 - x_2 \leq 2 \\ & x_1 - 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

$$\begin{array}{ll} \text{maximize} & -x_0 \\ \text{subject to} & \\ & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_1, x_2, x_0 \geq 0 \end{array}$$

Converting into slack form



Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximize} & 2x_1 - x_2 \\ \text{subject to} & \\ & 2x_1 - x_2 \leq 2 \\ & x_1 - 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

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Converting into slack form

$$\begin{array}{ll} Z = & -x_0 \\ x_3 = & 2 - 2x_1 + x_2 + x_0 \\ x_4 = & -4 - x_1 + 5x_2 + x_0 \end{array}$$



Example of INITIALIZE-SIMPLEX (1/3)

$$\begin{array}{ll} \text{maximize} & 2x_1 - x_2 \\ \text{subject to} & \\ & 2x_1 - x_2 \leq 2 \\ & x_1 - 5x_2 \leq -4 \\ & x_1, x_2 \geq 0 \end{array}$$

Formulating the auxiliary linear program

$$\begin{array}{ll} \text{maximize} & -x_0 \\ \text{subject to} & \\ & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_1, x_2, x_0 \geq 0 \end{array}$$

Basic solution
(0, 0, 0, 2, -4) not feasible!

Converting into slack form

$$\begin{array}{ll} z & = & & & -x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with x_0 entering and x_4 leaving



Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclclcl} Z & = & & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$



Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$



Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$

↓ Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!



Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$

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$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

Basic solution (4, 0, 0, 6, 0) is feasible!

↓ Pivot with x_2 entering and x_0 leaving

$$\begin{array}{rcllclcl} Z & = & & - & x_0 \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$



Example of INITIALIZE-SIMPLEX (2/3)

$$\begin{array}{rcllclcl} Z & = & & & & - & x_0 \\ x_3 & = & 2 & - & 2x_1 & + & x_2 & + & x_0 \\ x_4 & = & -4 & - & x_1 & + & 5x_2 & + & x_0 \end{array}$$

↓ Pivot with x_0 entering and x_4 leaving

$$\begin{array}{rcllclcl} Z & = & -4 & - & x_1 & + & 5x_2 & - & x_4 \\ x_0 & = & 4 & + & x_1 & - & 5x_2 & + & x_4 \\ x_3 & = & 6 & - & x_1 & - & 4x_2 & + & x_4 \end{array}$$

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$$\begin{array}{rcllclcl} Z & = & & - & x_0 \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$

Optimal solution has $x_0 = 0$, hence the initial problem was feasible!



Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{array}{rclclclcl} Z & = & & - & x_0 & & & & \\ x_2 & = & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 & = & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{array}$$



Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{aligned} Z &= && - && x_0 \\ x_2 &= & \frac{4}{5} & - & \frac{x_0}{5} & + & \frac{x_1}{5} & + & \frac{x_4}{5} \\ x_3 &= & \frac{14}{5} & + & \frac{4x_0}{5} & - & \frac{9x_1}{5} & + & \frac{x_4}{5} \end{aligned}$$

↓ Set $x_0 = 0$ and express objective function
by non-basic variables



Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{aligned} Z &= && - && x_0 \\ x_2 &= && \frac{4}{5} &- & \frac{x_0}{5} &+ & \frac{x_1}{5} &+ & \frac{x_4}{5} \\ x_3 &= && \frac{14}{5} &+ & \frac{4x_0}{5} &- & \frac{9x_1}{5} &+ & \frac{x_4}{5} \end{aligned}$$

Set $x_0 = 0$ and express objective function by non-basic variables

$$2x_1 - 2x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5} \right)$$

$$\begin{aligned} Z &= && -\frac{4}{5} &+ & \frac{9x_1}{5} &- & \frac{x_4}{5} \\ x_2 &= && \frac{4}{5} &+ & \frac{x_1}{5} &+ & \frac{x_4}{5} \\ x_3 &= && \frac{14}{5} &- & \frac{9x_1}{5} &+ & \frac{x_4}{5} \end{aligned}$$



Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{aligned} Z &= && - && x_0 \\ x_2 &= && \frac{4}{5} &- & \frac{x_0}{5} &+ & \frac{x_1}{5} &+ & \frac{x_4}{5} \\ x_3 &= && \frac{14}{5} &+ & \frac{4x_0}{5} &- & \frac{9x_1}{5} &+ & \frac{x_4}{5} \end{aligned}$$

Set $x_0 = 0$ and express objective function by non-basic variables

$$2x_1 - 2x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}\right)$$

$$\begin{aligned} Z &= && -\frac{4}{5} &+ & \frac{9x_1}{5} &- & \frac{x_4}{5} \\ x_2 &= && \frac{4}{5} &+ & \frac{x_1}{5} &+ & \frac{x_4}{5} \\ x_3 &= && \frac{14}{5} &- & \frac{9x_1}{5} &+ & \frac{x_4}{5} \end{aligned}$$

Basic solution $(0, \frac{4}{5}, \frac{14}{5}, 0)$, which is feasible!



Example of INITIALIZE-SIMPLEX (3/3)

$$\begin{aligned} Z &= & - & x_0 \\ x_2 &= & \frac{4}{5} & - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5} \\ x_3 &= & \frac{14}{5} & + \frac{4x_0}{5} - \frac{9x_1}{5} + \frac{x_4}{5} \end{aligned}$$

Set $x_0 = 0$ and express objective function by non-basic variables

$$2x_1 - 2x_2 = 2x_1 - \left(\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}\right)$$

$$\begin{aligned} Z &= & -\frac{4}{5} & + \frac{9x_1}{5} - \frac{x_4}{5} \\ x_2 &= & \frac{4}{5} & + \frac{x_1}{5} + \frac{x_4}{5} \\ x_3 &= & \frac{14}{5} & - \frac{9x_1}{5} + \frac{x_4}{5} \end{aligned}$$

Basic solution $(0, \frac{4}{5}, \frac{14}{5}, 0)$, which is feasible!

Lemma 29.12

If a linear program L has no feasible solution, then INITIALIZE-SIMPLEX returns “infeasible”. Otherwise, it returns a valid slack form for which the basic solution is feasible.



Fundamental Theorem of Linear Programming

Theorem 29.13 (Fundamental Theorem of Linear Programming)

Any linear program L , given in standard form, either

1. has an optimal solution with a finite objective value,
2. is infeasible, or
3. is unbounded.

If L is infeasible, SIMPLEX returns “infeasible”. If L is unbounded, SIMPLEX returns “unbounded”. Otherwise, SIMPLEX returns an optimal solution with a finite objective value.



Fundamental Theorem of Linear Programming

Theorem 29.13 (Fundamental Theorem of Linear Programming)

Any linear program L , given in standard form, either

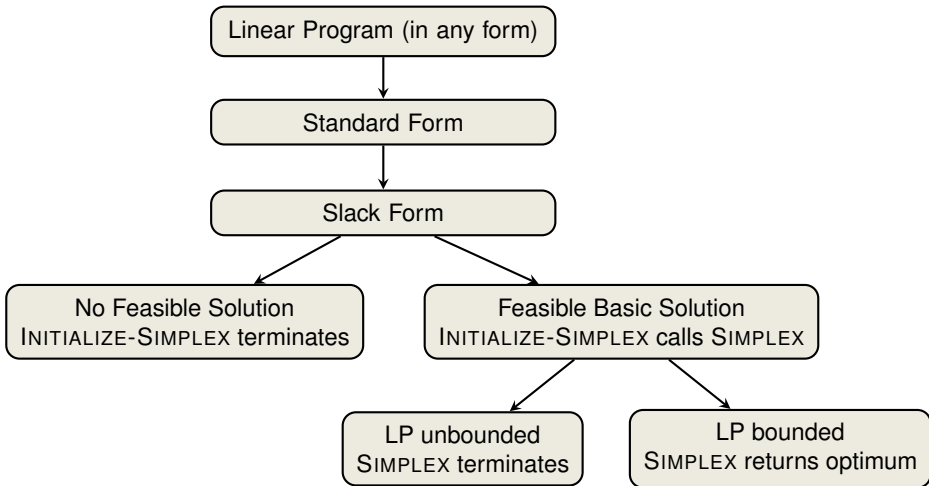
1. has an optimal solution with a finite objective value,
2. is infeasible, or
3. is unbounded.

If L is infeasible, SIMPLEX returns “infeasible”. If L is unbounded, SIMPLEX returns “unbounded”. Otherwise, SIMPLEX returns an optimal solution with a finite objective value.

Proof requires the concept of **duality**, which is not covered in this course (for details see CLRS3, Chapter 29.4)



Workflow for Solving Linear Programs



Linear Programming and Simplex: Summary and Outlook

Linear Programming



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Linear Programming

- extremely versatile tool for modelling problems of all kinds



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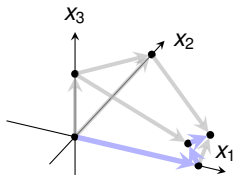
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Simplex Algorithm

- **In practice**: usually terminates in polynomial time, i.e., $O(m + n)$



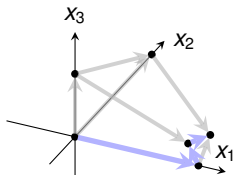
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Linear Programming and Simplex: Summary and Outlook

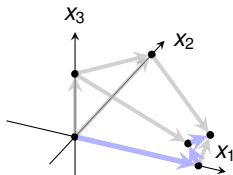
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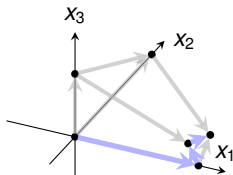
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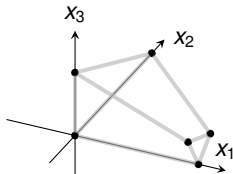
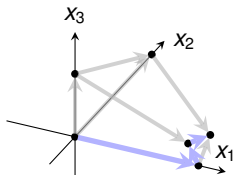
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