Contextual equivalence

Two phrases of a programming language are contextually equivalent if any occurrences of the first phrase in a complete program can be replaced by the second phrase without affecting the <u>observable results</u> of executing the program.

Given PCF terms M_1, M_2 , PCF type τ , and a type environment Γ , the relation $|\Gamma \vdash M_1 \cong_{ctx} M_2 : \tau$ is defined to hold iff • Both the typings $\Gamma \vdash M_1 : \tau$ and $\Gamma \vdash M_2 : \tau$ hold. For all PCF contexts C for which $C[M_1]$ and $C[M_2]$ are closed terms of type γ , where $\gamma = nat$ or $\gamma = bool$, and for all values $V:\gamma$,

$$\mathcal{C}[M_1] \Downarrow_{\gamma} V \iff \mathcal{C}[M_2] \Downarrow_{\gamma} V.$$

- PCF types $\tau \mapsto$ domains $[\tau]$.
- Closed PCF terms $M : \tau \mapsto$ elements $\llbracket M \rrbracket \in \llbracket \tau \rrbracket$. Denotations of open terms will be continuous functions.
- Compositionality. In particular: $\llbracket M \rrbracket = \llbracket M' \rrbracket \Rightarrow \llbracket C[M] \rrbracket = \llbracket C[M'] \rrbracket$. $\int \llbracket n \rrbracket = \llbracket m' \rrbracket$

 $\llbracket G \llbracket M \rrbracket \rrbracket = \llbracket G \llbracket M \rrbracket \rrbracket \rrbracket$

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- Soundness.

For any type τ , $M \downarrow_{\tau} V \Rightarrow \llbracket M \rrbracket = \llbracket V \rrbracket . C [\![\mathcal{T}]\!]$

- PCF types $\tau \mapsto \text{domains } \llbracket \tau \rrbracket$.
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• Adequacy.

For $\tau = bool \text{ or } nat$, $\llbracket M \rrbracket = \llbracket V \rrbracket \in \llbracket \tau \rrbracket \implies M \Downarrow_{\tau} V$.

Theorem. For all types τ and closed terms $M_1, M_2 \in \mathrm{PCF}_{\tau}$, if $\llbracket M_1 \rrbracket$ and $\llbracket M_2 \rrbracket$ are equal elements of the domain $\llbracket \tau \rrbracket$, then $M_1 \cong_{\mathrm{ctx}} M_2 : \tau$.

 $\mathcal{C}[M_1] \downarrow V \implies \mathcal{I}[\mathcal{C}[M_1]] \downarrow = [V]$ [[M]]=[[M2]] $\Rightarrow \overline{RG[m_2]} = \overline{IV]} \overline{I[e[m_1]]} = \overline{IG[m_1]}$ S G[m2] WV $Sr that M_1 \cong che M_2$ $M_1 \bigoplus ct_x M_2$ $M_1 \bigoplus ct_x M_2$ $M_1 \bigoplus ct_x M_2$ $M_1 \bigoplus ct_x M_2$

Proof principle

To prove

$$M_1 \cong_{\mathrm{ctx}} M_2 : \tau$$

it suffices to establish

 $\llbracket M_1 \rrbracket = \llbracket M_2 \rrbracket \text{ in } \llbracket \tau \rrbracket$



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The proof principle is sound, but is it complete? That is, is equality in the denotational model also a necessary condition for contextual equivalence?

Topic 6

Denotational Semantics of PCF

$$\begin{aligned} \text{Japar Harlar, fr Clord M of type Z, [[M] \in [[Z]] \\ So fr P: G \rightarrow Z, [[P]] \in ([[G]] \rightarrow [[Z]]) \\ \text{Denotational semantics of PCF} \end{aligned}$$

$$\begin{aligned} \text{To every typing judgement} \\ \Gamma \vdash M : \tau \\ \text{we associate a continuous function} \\ [\Gamma \vdash M] : [\Gamma] \rightarrow [\tau] \\ \text{between domains.} \end{aligned}$$

$$\begin{aligned} \Pi \vdash M]: [\Gamma] \rightarrow [\tau] \\ \text{between domains.} \end{aligned}$$

$$\begin{bmatrix} nat \end{bmatrix} \stackrel{\text{def}}{=} \mathbb{N}_{\perp} \qquad (\text{flat domain})$$
$$\begin{bmatrix} bool \end{bmatrix} \stackrel{\text{def}}{=} \mathbb{B}_{\perp} \qquad (\text{flat domain})$$
$$\begin{bmatrix} \tau \to \tau' \end{bmatrix} \stackrel{\text{def}}{=} \begin{bmatrix} \tau \end{bmatrix} \to \begin{bmatrix} \tau' \end{bmatrix} \qquad (\text{function domain}).$$
where $\mathbb{N} = \{0, 1, 2, \dots\}$ and $\mathbb{B} = \{true, false\}.$



 $\llbracket \Gamma \rrbracket \stackrel{\text{def}}{=} \prod_{x \in dom(\Gamma)} \llbracket \Gamma(x) \rrbracket \quad (\Gamma \text{-environments})$

 $= \quad \text{the domain of partial functions } \rho \text{ from variables} \\ \text{to domains such that } \frac{dom(\rho) = dom(\Gamma)}{\rho(x) \in [\![\Gamma(x)]\!]} \text{ for all } x \in dom(\Gamma) \\ \end{cases}$

For
$$\Gamma = \{ 2i + 32i \}_{i=1, \dots, n}$$

 $f \in \Pi \mathcal{Y} \text{ s.t. } f(2i) \in \Pi \mathcal{Y}$
Equivalently viewly Γ as $(2_1: \mathcal{I}_1, \dots, \mathcal{M}: \mathcal{T}_n)$
 $\Pi \Pi = (\Pi \mathcal{Y} \times (\Pi \mathcal{Y} \times \dots \times \Pi \mathcal{T}_n))$

 $\llbracket \Gamma \rrbracket \stackrel{\text{def}}{=} \prod_{x \in dom(\Gamma)} \llbracket \Gamma(x) \rrbracket \quad (\Gamma \text{-environments})$

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Example:

1. For the empty type environment \emptyset ,

 $\llbracket \emptyset \rrbracket = \{ \bot \}$

where \perp denotes the unique partial function with $dom(\perp) = \emptyset$.

2. $[\![\langle x \mapsto \tau \rangle]\!] = (\{x\} \to [\![\tau]\!]) \cong [\![\tau]\!]$ 3.

$$\begin{bmatrix} \langle x_1 \mapsto \tau_1, \dots, x_n \mapsto \tau_n \rangle \end{bmatrix}$$

$$\cong (\{x_1\} \to \llbracket \tau_1 \rrbracket) \times \dots \times (\{x_n\} \to \llbracket \tau_n \rrbracket)$$

$$\cong \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_n \rrbracket$$

Denotational semantics of PCF terms, I Fn
$$\mathcal{P}\mathcal{P}\mathcal{M}$$
:

$$\begin{bmatrix} \Gamma \vdash \mathbf{0} \end{bmatrix}(\rho) \stackrel{\text{def}}{=} 0 \in \llbracket nat \rrbracket$$

$$\llbracket \Gamma \vdash \mathbf{true} \rrbracket(\rho) \stackrel{\text{def}}{=} true \in \llbracket bool \rrbracket$$

$$\llbracket \Gamma \vdash \mathbf{false} \rrbracket(\rho) \stackrel{\text{def}}{=} false \in \llbracket bool \rrbracket$$

$$\bigvee \mathcal{P} \in \llbracket \mathcal{P} \rrbracket$$

$$(\Gamma \vdash \mathcal{M}) (\mathcal{P}) \in \llbracket \mathcal{T} \varUpsilon \rrbracket$$

$$[\Gamma \vdash \mathbf{0}](\rho) \stackrel{\text{def}}{=} 0 \in [[nat]]$$
$$[\Gamma \vdash \mathbf{true}](\rho) \stackrel{\text{def}}{=} true \in [[bool]]$$
$$[\Gamma \vdash \mathbf{false}](\rho) \stackrel{\text{def}}{=} false \in [[bool]]$$
$$[\Gamma \vdash x](\rho) \stackrel{\text{def}}{=} \rho(x) \in [[\Gamma(x)]] \qquad (x \in dom(\Gamma))$$
$$\mathcal{N} = \langle \chi_{l} : \zeta_{l} : \cdots, \chi_{n} : \zeta_{n} \rangle$$
$$[\Gamma \vdash \chi_{l}] (\langle \zeta_{l} : \cdots, \nabla_{n} \rangle) = \mathcal{N}_{l}$$



 $\llbracket \Gamma \vdash \mathbf{succ}(M) \rrbracket(\rho)$ $\stackrel{\text{def}}{=} \begin{cases} \llbracket \Gamma \vdash M \rrbracket(\rho) + 1 & \text{if } \llbracket \Gamma \vdash M \rrbracket(\rho) \neq \bot \\ \bot & \text{if } \llbracket \Gamma \vdash M \rrbracket(\rho) = \bot \end{cases}$ $\llbracket \Gamma \vdash \mathbf{pred}(M) \rrbracket(\rho)$ $\stackrel{\text{def}}{=} \begin{cases} \llbracket \Gamma \vdash M \rrbracket(\rho) - 1 & \text{if } \llbracket \Gamma \vdash M \rrbracket(\rho) > 0 \\ \bot & \text{if } \llbracket \Gamma \vdash M \rrbracket(\rho) = 0, \bot \end{cases}$ $\llbracket \Gamma \vdash \mathbf{zero}(M) \rrbracket(\rho) \stackrel{\text{def}}{=} \begin{cases} true & \text{if } \llbracket \Gamma \vdash M \rrbracket(\rho) = 0\\ false & \text{if } \llbracket \Gamma \vdash M \rrbracket(\rho) > 0\\ \bot & \text{if } \llbracket \Gamma \vdash M \rrbracket(\rho) = \bot \end{cases}$

 $[[M_1]] : [[n]] \rightarrow (f_2] \rightarrow f_3])$ [m]:[r]-[~]

Denotational semantics of PCF terms, III

$$[M_{1}] f \in ([\alpha] \rightarrow [\beta]) \qquad [[M_{2}](f) \in [\alpha])$$

 $\llbracket \Gamma \vdash \mathbf{if} \ M_1 \ \mathbf{then} \ M_2 \ \mathbf{else} \ M_3 \rrbracket(\rho)$

$$\stackrel{\text{def}}{=} \begin{cases} \llbracket \Gamma \vdash M_2 \rrbracket(\rho) & \text{if } \llbracket \Gamma \vdash M_1 \rrbracket(\rho) = true \\ \llbracket \Gamma \vdash M_3 \rrbracket(\rho) & \text{if } \llbracket \Gamma \vdash M_1 \rrbracket(\rho) = false \\ \bot & \text{if } \llbracket \Gamma \vdash M_1 \rrbracket(\rho) = \bot \end{cases}$$

$$\begin{bmatrix} \Gamma \vdash M_1 M_2 \end{bmatrix} (\rho) \stackrel{\text{def}}{=} (\llbracket \Gamma \vdash M_1 \rrbracket (\rho)) (\llbracket \Gamma \vdash M_2 \rrbracket (\rho))$$

$$\begin{array}{cccc} \Gamma_{1} & Z:Z + M:G & \Gamma_{1} & \Gamma_{2} & \Gamma_{2} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & Z:Z & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{2} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{3} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{3} & \Gamma_{3} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} \\ \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} & \Gamma_{1} \\ \Gamma_{1} & \Gamma_{1} \\ \Gamma_{1} & \Gamma_$$

 $\begin{bmatrix} \Gamma \vdash \mathbf{fn} \, x : \tau \, . \, M \end{bmatrix} (\rho) \\ \stackrel{\text{def}}{=} \lambda d \in \llbracket \tau \rrbracket \, . \, \llbracket \Gamma[x \mapsto \tau] \vdash M \rrbracket (\rho[x \mapsto d]) \qquad (x \notin dom(\Gamma))$

NB: $\rho[x \mapsto d] \in \llbracket \Gamma[x \mapsto \tau] \rrbracket$ is the function mapping x to $d \in \llbracket \tau \rrbracket$ and otherwise acting like ρ .



$$\llbracket \Gamma \vdash \mathbf{fix}(M) \rrbracket(\rho) \stackrel{\text{def}}{=} fix(\llbracket \Gamma \vdash M \rrbracket(\rho))$$



Denotational semantics of PCF

Proposition. For all typing judgements $\Gamma \vdash M : \tau$, the denotation

$\llbracket \Gamma \vdash M \rrbracket : \llbracket \Gamma \rrbracket \to \llbracket \tau \rrbracket$

is a well-defined continous function.

Denotations of closed terms

For a closed term $M \in \mathrm{PCF}_{\tau}$, we get

 $\llbracket \emptyset \vdash M \rrbracket : \llbracket \emptyset \rrbracket \to \llbracket \tau \rrbracket$

and, since $\llbracket \emptyset \rrbracket = \{ \bot \}$, we have

$$\llbracket M \rrbracket \stackrel{\text{def}}{=} \llbracket \emptyset \vdash M \rrbracket (\bot) \in \llbracket \tau \rrbracket \qquad (M \in \mathrm{PCF}_{\tau})$$