

Proposal for a second Examples Class
(on 2nd $\frac{1}{2}$ of Example Sheet) :

THURSDAY 13 MARCH
16:00 - 17:00
SW01

Lecture 8: nominal unification

Sample α Prolog code

```
id : name_type. (* variables *)
tm : type.      (* lambda terms *)
var : id -> tm.
app : tm -> tm -> tm.
lam : id\tm -> tm.
pred subst (id\tm) tm tm.
(* "subst (a\X) Y Z" holds if Z is the result of capture-avoiding substitution
   of Y for all free occurrences of var a in X *)
subst (a\var a) Y Y.
subst (a\X) Y X :- a # X.
subst (a\app X X') Y (app Z Z') :- subst (a\X) Y Z, subst (a\X') Y Z'.
subst (a\lam(b\X)) Y (lam (b\Z)) :- subst (a\X) Y Z, b # Y.

?- subst (b\lam(a\var b)) (var a) X. (* search for X satisfying  $X = \lambda a.b[a/b]$  *)
Yes. X = lam(a'\var a) (* X is  $\lambda a'.a$ , not  $\lambda a.a$  *)
```

As for Prolog, search for solutions to queries involves resolution (try to unify query with head of each clause), but using **nominal unification**, which solves α -equivalence and freshness constraints.

Examples of unification 'mod α '

over the nominal algebraic signature Σ for λ -calculus:
name-sort **Var**, data-sort **Term**, operations

$V : \text{Var} \rightarrow \text{Term}$

$A : \text{Term}, \text{Term} \rightarrow \text{Term}$

$L : \text{Var} . \text{Term} \rightarrow \text{Term}$

Ex. 1: does there exist a $t \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(t, Vb))) =_{\alpha} L(b . L(a . A(Va, t)))$$

(where $a \neq b$)?

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(Vb, t_1))) =_{\alpha} L(a . L(a . A(Va, t_2)))$$

(where $a \neq b$)?

Alpha-equivalence

$$=_{\alpha} \subseteq \Sigma(S) \times \Sigma(S)$$

$$\frac{a \in A}{a =_{\alpha} a}$$

$$\frac{t =_{\alpha} t'}{\text{op } t =_{\alpha} \text{op } t'}$$

$$\overline{() =_{\alpha} ()}$$

$$\frac{t_1 =_{\alpha} t'_1 \quad t_2 =_{\alpha} t'_2}{t_1, t_2 =_{\alpha} t'_1, t'_2}$$

$$\frac{(a_1 \ a) \cdot t_1 =_{\alpha} (a_2 \ a) \cdot t_2 \quad a \# (a_1, t_1, a_2, t_2)}{a_1 \cdot t_1 =_{\alpha} a_2 \cdot t_2}$$

Ex. 1: does there exist $t \in \Sigma(\text{Term})$ with

$$L(a.L(b.A(t, V b))) =_{\alpha} L(b.L(a.A(V a, t)))$$

(where $a \neq b$)?

Ex. 1: does there exist $t \in \Sigma(\text{Term})$ with
$$L(a . L(b . A(t, V b))) =_{\alpha} L(b . L(a . A(V a, t)))$$

(where $a \neq b$)?

$$L(b . A((a \ c) \cdot t, V b)) =_{\alpha} L(a . A(V a, (b \ c) \cdot t))$$

where $c \# (a, b, t)$

Ex. 1: does there exist $t \in \Sigma(\text{Term})$ with
$$L(a.L(b.A(t, Vb))) =_{\alpha} L(b.L(a.A(Va, t)))$$

(where $a \neq b$)?

$$L(b.A((a\ c) \cdot t, Vb)) =_{\alpha} L(a.A(Va, (b\ c) \cdot t))$$

where $c \# (a, b, t)$

$$A((b\ d)(a\ c) \cdot t, Vd) =_{\alpha} A(Vd, (a\ d)(b\ c) \cdot t)$$

where $d \# c, d, c \# (a, b, t)$

Ex. 1: does there exist $t \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(t, \vee b))) =_{\alpha} L(b . L(a . A(\vee a, t)))$$
 (where $a \neq b$)?

$$L(b . A((a \ c) \cdot t, \vee b)) =_{\alpha} L(a . A(\vee a, (b \ c) \cdot t))$$

where $c \# (a, b, t)$

$$A((b \ d)(a \ c) \cdot t, \vee d) =_{\alpha} A(\vee d, (a \ d)(b \ c) \cdot t)$$

where $d \# c, d, c \# (a, b, t)$

$$(b \ d)(a \ c) \cdot t =_{\alpha} \vee d \text{ and } \vee d =_{\alpha} (a \ d)(b \ c) \cdot t$$

where $d \# c, d, c \# (a, b, t)$

Ex. 1: does there exist $t \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(t, \vee b))) =_{\alpha} L(b . L(a . A(\vee a, t)))$$
 (where $a \neq b$)?

$$L(b . A((a \ c) \cdot t, \vee b)) =_{\alpha} L(a . A(\vee a, (b \ c) \cdot t))$$

where $c \# (a, b, t)$

$$A((b \ d)(a \ c) \cdot t, \vee d) =_{\alpha} A(\vee d, (a \ d)(b \ c) \cdot t)$$

where $d \# c, d, c \# (a, b, t)$

$$(b \ d)(a \ c) \cdot t =_{\alpha} \vee d \text{ and } \vee d =_{\alpha} (a \ d)(b \ c) \cdot t$$

where $d \# c, d, c \# (a, b, t)$

$$t =_{\alpha} \vee b \text{ and } \vee a =_{\alpha} t$$

where $d \# c, d, c \# (a, b, t)$

Ex. 1: does there exist $t \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(t, \vee b))) =_{\alpha} L(b . L(a . A(\vee a, t)))$$
 (where $a \neq b$)?

$$L(b . A((a \ c) \cdot t, \vee b)) =_{\alpha} L(a . A(\vee a, (b \ c) \cdot t))$$

where $c \# (a, b, t)$

$$A((b \ d)(a \ c) \cdot t, \vee d) =_{\alpha} A(\vee d, (a \ d)(b \ c) \cdot t)$$

where $d \# c, d, c \# (a, b, t)$

$$(b \ d)(a \ c) \cdot t =_{\alpha} \vee d \text{ and } \vee d =_{\alpha} (a \ d)(b \ c) \cdot t$$

where $d \# c, d, c \# (a, b, t)$

$$t =_{\alpha} \vee b \text{ and } \vee a =_{\alpha} t$$

where $d \# c, d, c \# (a, b, t)$

$$\vee b =_{\alpha} \vee a$$

$$b = a$$

contradicting $a \neq b$ — so no such t can exist.

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a.L(b.A(V b, t_1))) =_\alpha L(a.L(a.A(V a, t_2)))$$

(where $a \neq b$)?

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(V b, t_1))) =_{\alpha} L(a . L(a . A(V a, t_2)))$$

(where $a \neq b$)?

$$L(b . A(V b, t_1)) =_{\alpha} L(a . A(V a, t_2))$$

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(V b, t_1))) =_{\alpha} L(a . L(a . A(V a, t_2)))$$

(where $a \neq b$)?

$$L(b . A(V b, t_1)) =_{\alpha} L(a . A(V a, t_2))$$

$$A(V c, (b c) \cdot t_1) =_{\alpha} A(V c, (a c) \cdot t_2)$$

where $c \# (a, b, t_1, t_2)$

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(V b, t_1))) =_{\alpha} L(a . L(a . A(V a, t_2)))$$

 (where $a \neq b$)?

$$L(b . A(V b, t_1)) =_{\alpha} L(a . A(V a, t_2))$$

$$A(V c, (b c) \cdot t_1) =_{\alpha} A(V c, (a c) \cdot t_2)$$

where $c \# (a, b, t_1, t_2)$

$$V c =_{\alpha} V c \text{ and } (b c) \cdot t_1 =_{\alpha} (a c) \cdot t_2$$

where $c \# (a, b, t_1, t_2)$

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(V b, t_1))) =_{\alpha} L(a . L(a . A(V a, t_2)))$$
 (where $a \neq b$)?

$$L(b . A(V b, t_1)) =_{\alpha} L(a . A(V a, t_2))$$

$$A(V c, (b c) \cdot t_1) =_{\alpha} A(V c, (a c) \cdot t_2)$$

where $c \# (a, b, t_1, t_2)$

$$V c =_{\alpha} V c \text{ and } (b c) \cdot t_1 =_{\alpha} (a c) \cdot t_2$$

where $c \# (a, b, t_1, t_2)$

$$t_1 = (b c)(a c) \cdot t_2 [= (a b)(b c) \cdot t_2]$$

where $c \# (a, b, (a b)(b c) \cdot t_2, t_2)$

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(V b, t_1))) =_{\alpha} L(a . L(a . A(V a, t_2)))$$
 (where $a \neq b$)?

$$L(b . A(V b, t_1)) =_{\alpha} L(a . A(V a, t_2))$$

$$A(V c, (b c) \cdot t_1) =_{\alpha} A(V c, (a c) \cdot t_2)$$

where $c \# (a, b, t_1, t_2)$

$$V c =_{\alpha} V c \text{ and } (b c) \cdot t_1 =_{\alpha} (a c) \cdot t_2$$

where $c \# (a, b, t_1, t_2)$

$$t_1 = (b c)(a c) \cdot t_2 [= (a b)(b c) \cdot t_2]$$

where $c \# (a, b, (a b)(b c) \cdot t_2, t_2)$

$$t_1 = (a b)(b c) \cdot t_2 [= (a b) \cdot t_2]$$

where $c \# (a, b, t_2)$ and $b \# t_2$

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with

$$L(a . L(b . A(V b, t_1))) =_{\alpha} L(a . L(a . A(V a, t_2)))$$
 (where $a \neq b$)?

$$L(b . A(V b, t_1)) =_{\alpha} L(a . A(V a, t_2))$$

$$A(V c, (b c) \cdot t_1) =_{\alpha} A(V c, (a c) \cdot t_2)$$

where $c \# (a, b, t_1, t_2)$

$$V c =_{\alpha} V c \text{ and } (b c) \cdot t_1 =_{\alpha} (a c) \cdot t_2$$

where $c \# (a, b, t_1, t_2)$

$$t_1 = (b c)(a c) \cdot t_2 [= (a b)(b c) \cdot t_2]$$

where $c \# (a, b, (a b)(b c) \cdot t_2, t_2)$

$$t_1 = (a b)(b c) \cdot t_2 [= (a b) \cdot t_2]$$

where $c \# (a, b, t_2)$ and $b \# t_2$

$$t_1 = (a b) \cdot t_2, \text{ for any } t_2 \text{ with } b \# t_2$$

Examples of unification 'mod α '

Ex. 1: does there exist a $t \in \Sigma(\text{Term})$ with
$$L(a.L(b.A(t, Vb))) =_{\alpha} L(b.L(a.A(Va, t)))$$

(where $a \neq b$)?

Ex. 2: do there exist $t_1, t_2 \in \Sigma(\text{Term})$ with
$$L(a.L(b.A(Vb, t_1))) =_{\alpha} L(a.L(a.A(Va, t_2)))$$

(where $a \neq b$)?

Can decide all such problems (over any nominal algebraic signature) using the **nominal unification algorithm**
[Urban+AMP+Gabbay, TCS 323(2004)473–497] \triangleq **NOMU**.

First, need to extend the syntax of terms over a nominal signature with **variables**...

$\Sigma(S)$ = raw terms over Σ of sort S

$$\begin{array}{c}
 \frac{a \in \mathbb{A}}{a \in \Sigma(N)} \qquad \frac{t \in \Sigma(S) \quad \text{op} : S \rightarrow D}{\text{op } t \in \Sigma(D)} \qquad \frac{}{() \in \Sigma(1)} \\
 \\
 \frac{t_1 \in \Sigma(S_1) \quad t_2 \in \Sigma(S_2)}{t_1, t_2 \in \Sigma(S_1, S_2)} \qquad \frac{a \in \mathbb{A} \quad t \in \Sigma(S)}{a . t \in \Sigma(N . S)}
 \end{array}$$

Each $\Sigma(S)$ is a nominal set once equipped with the obvious **Perm** \mathbb{A} -action—any finite set of atoms containing all those occurring in t supports $t \in \Sigma(S)$.

Open nominal terms

$()$	unit	a	atomic names
t, t'	pairs	$a . t$	abstractions
opt	constructed	$\pi * X$	suspensions

$\pi \in \mathbf{Perm} \mathbb{A}$

X ranges over variables, standing for unknown terms

E.g. $L(a . A(Vc, (a\ c) * X))$

Equality & freshness


Equality of open terms is not just

$$t =_{\alpha} t' \quad \alpha\text{-equivalence}$$

Equality & freshness

Equality is in general hypothetical

$\nabla \vdash t \approx t'$ hypothetical α -equivalence



finite set of **freshness assumptions**, $a \# X$, each with intended meaning: 'atomic name a will not occur freely in any term substituted for X '

Intended meaning:

'any closing **substitution** (= replacement of variables by terms) satisfying ∇ makes t and t' α -equivalent'

Equality & freshness

Equality is in general hypothetical

$$\nabla \vdash t \approx t' \quad \text{hypothetical } \alpha\text{-equivalence}$$

Examples of valid judgements:

$$\begin{aligned} & \{b \not\approx X\} \vdash a.X \approx b.((a\ b) * X) \\ & \{a \not\approx X, b \not\approx X\} \vdash a.X \approx b.X \end{aligned}$$

Equality & freshness

Also need freshness judgements

$$\nabla \vdash a \# t$$

Intended meaning:

‘any closing substitution satisfying ∇ makes t not contain the atom a freely’

Examples of valid judgements:

$$\begin{aligned} \{b \# X\} &\vdash b \# a.X \\ \{\} &\vdash a \# a.X \end{aligned}$$

Rules for $\nabla \vdash t \approx t'$

Excerpt

(see NOMU, or NSB chapter 12, for full details)

Rules for $\nabla \vdash t \approx t'$

$$\frac{\nabla \vdash t \approx t'}{\nabla \vdash a.t \approx a.t'}$$

$$\frac{a \neq a' \quad \nabla \vdash t \approx (a \ a') * t' \quad \nabla \vdash a \# t'}{\nabla \vdash a.t \approx a'.t'}$$

Rules for $\nabla \vdash t \approx t'$

$$\frac{\nabla \vdash t \approx t'}{\nabla \vdash a.t \approx a.t'}$$

$$\frac{a \neq a' \quad \nabla \vdash t \approx (a \ a') * t' \quad \nabla \vdash a \not\approx t'}{\nabla \vdash a.t \approx a'.t'}$$

$(a \ a') * t'$ is defined by recursion on the structure of t' , pushing the swap down through the structure, applying it to atoms and stopping with subterms like $((a \ a') \circ \pi) * X$

Rules for $\nabla \vdash t \approx t'$

$$\frac{(a \not\approx X) \in \nabla \text{ for all } a \text{ with } \pi(a) \neq \pi'(a)}{\nabla \vdash \pi * X \approx \pi' * X}$$

E.g.

$$\{a \not\approx X, c \not\approx X\} \vdash (a\ c)(a\ b) * X \approx (b\ c) * X$$

because

$$\begin{array}{ll} (a\ c)(a\ b) : & \begin{array}{l} a \mapsto b \\ b \mapsto c \\ c \mapsto a \end{array} & (b\ c) : & \begin{array}{l} a \mapsto a \\ b \mapsto c \\ c \mapsto b \end{array} \end{array}$$

disagree at a and c .

Rules for $\nabla \vdash a \not\approx t$

(Excerpt)

$$\frac{a \neq a'}{\nabla \vdash a \not\approx a'}$$

$$\frac{}{\nabla \vdash a \not\approx a.t}$$

$$\frac{a \neq a' \quad \nabla \vdash a \not\approx t}{\nabla \vdash a \not\approx a'.t}$$

$$\frac{(\pi^{-1} a \not\approx X) \in \nabla}{\nabla \vdash a \not\approx \pi * X}$$

Correctness

[NOMU, Proposition 2.16]

Theorem. \approx is an equivalence relation and agrees with $=_\alpha$ on ground terms: if t and t' contain no variables then

$\emptyset \vdash t \approx t'$ is valid iff $t =_\alpha t'$.

Furthermore

$\emptyset \vdash a \not\approx t$ is valid iff $a \notin \text{fn}(t)$.

Substitution

Substitutions σ are finite maps from variables to terms, $[X_1 := t_1, \dots, X_n := t_n]$.

Applying a substitution to a term: σt = result of replacing variables in t with terms according to σ , carrying out any permutations of atomic names that are generated.

E.g. if $\sigma = [X := A(V b, Y)]$, then

$$\begin{aligned}\sigma (L(a . (a b) * X)) &= L(a . (a b) * A(V b, Y)) \\ &= L(a . A(V a, (a b) * Y))\end{aligned}$$

Equational & freshness problems

An equational problem $t \approx? t'$ is **solved** by

- ▶ a substitution σ , plus
- ▶ a set of freshness assumptions ∇

so that $\nabla \vdash \sigma t \approx \sigma t'$.

Equational & freshness problems

An equational problem $t \approx? t'$ is **solved** by

- ▶ a substitution σ , plus
- ▶ a set of freshness assumptions ∇

so that $\nabla \vdash \sigma t \approx \sigma t'$.

Solving equations may entail solving **freshness problems**.

E.g. assuming that $a \neq a'$, then $L(a.t) \approx? L(a'.t')$ can only be solved if

$$t \approx? (a \ a') * t' \quad \text{and} \quad a \not\#? t'$$

can be solved.

Equational & freshness problems

An equational problem $t \approx? t'$ is **solved** by

- ▶ a substitution σ , plus
- ▶ a set of freshness assumptions ∇

so that $\nabla \vdash \sigma t \approx \sigma t'$.

A freshness problem $a \#? t$ is **solved** by

- ▶ a substitution σ , plus
- ▶ a set of freshness assumptions ∇

so that $\nabla \vdash a \# \sigma t$.

Existence of MGUs

Theorem. There is an algorithm which given any finite set P of equational and freshness problems (over any nominal algebraic signature), decides whether or not it has a solution (σ, ∇) , and returns a **most general** one if it does.

straightforward definition, omitted



Existence of MGUs

Theorem. There is an algorithm which given any finite set P of equational and freshness problems (over any nominal algebraic signature), decides whether or not it has a solution (σ, ∇) , and returns a most general one if it does.

Algorithm first reduces all the equations to 'solved form' (creating a substitution), possibly generating extra freshness problems, and then solves all the freshness problems (easy).

(See [NOMU, Sect. 3].)

$$\{L(a . L(b . A(V b, X))) \approx? L(a . L(a . A(V a, Y)))\}$$

$$(\xrightarrow{id})^3 \quad \{b . A(V b, X) \approx? a . A(V a, Y)\}$$

$$\xrightarrow{id} \quad \{A(V b, X) \approx? A(V b, (b a) * Y), b \not\approx? A(V a, Y)\}$$

$$(\xrightarrow{id})^3 \quad \{X \approx? (b a) * Y, b \not\approx? A(V a, Y)\}$$

$$[X := (b a) * Y] \xrightarrow{\quad} \{b \not\approx? A(V a, Y)\}$$

$$\xrightarrow{\emptyset} \quad \{b \not\approx? V a, b \not\approx? Y\}$$

$$(\xrightarrow{\emptyset})^2 \quad \{b \not\approx? Y\}$$

$$\{(b \not\approx Y)\} \xrightarrow{\quad} \emptyset$$

$$\{L(a.L(b.A(Vb,X))) \approx? L(a.L(a.A(Va,Y)))\}$$

$$(\xrightarrow{id})^3 \quad \{b.A(Vb,X) \approx? a.A(Va,Y)\}$$

$$\xrightarrow{id} \quad \{A(Vb,X) \approx? A(Vb,(ba)*Y), b \not\approx? A(Va,Y)\}$$

$$(\xrightarrow{id})^3 \quad \{X \approx? (ba)*Y, b \not\approx? A(Va,Y)\}$$

$$[X := (ba)*Y] \xrightarrow{\quad} \{b \not\approx? A(Va,Y)\}$$

$$\xrightarrow{\emptyset} \quad \{b \not\approx? Va, b \not\approx? Y\}$$

$$(\xrightarrow{\emptyset})^2 \quad \{b \not\approx? Y\}$$

$$\xrightarrow{\{(b \not\approx Y)\}} \quad \emptyset$$

most general solution = $[X := (ba)*Y], \{(b \not\approx Y)\}$

Existence of MGUs

Theorem. There is an algorithm which given any finite set P of equational and freshness problems (over any nominal algebraic signature), decides whether or not it has a solution (σ, ∇) , and returns a most general one if it does.

- ▶ Current best NOMU algorithm is quadratic [Levy & Villaret, Proc. RTA 2010].
- ▶ NOMU is (quadratically) inter-reducible with Dale Miller's **higher-order pattern unification**, which uses variables that depend on names $X(a_1, \dots, a_n)$ rather than NOMU's variables that are fresh for names $(\{a_1, \dots, a_n\} \# X)$. (Higher-order patterns form a subset of Church's simply typed λ -calculus.)

Other applications of nominal sets

► **Computational logic**

- Higher-order logic: Urban & Berghofer's Nominal package for the interactive theorem-prover Isabelle/HOL.
- Equational logic: rewriting for nominal terms [Fernandez+Gabbay+Calves+...]]

Other applications of nominal sets

► Computational logic

- Higher-order logic: Urban & Berghofer's Nominal package for the interactive theorem-prover Isabelle/HOL.
- Equational logic: rewriting for nominal terms [Fernandez+Gabbay+Calves+...]

► Automata theory & verification

- HD-automata [Montanari et al]
- fresh-register automata [Tzevelekos]
- **orbit-finite** computation theory [Bojańczyk et al]

Other applications of nominal sets

► Homotopy Type Theory (HoTT)

Cubical sets [Bezem-Coquand-Huber] model of Voevodsky's axiom of univalence makes use of nominal sets equipped with an operation of substitution $x \mapsto x(i/a)$ where $i \in \{0, 1\}$.

- names are **names of directions** (cartesian axes)
(so e.g., if an object has support $\{a, b, c\}$ it is 3-dimensional)
- freshness $(a \# x) = \text{degeneracy } (x(i/a) = x)$
- **identity types are modelled by name-abstraction**: $\langle a \rangle x$ is a proof that $x(0/a)$ is equal to $x(1/a)$.

HoTT and univalence is about (computable) *mathematical foundations* (a topic no longer very popular with mathematicians). That's where the mathematics of nominal sets came from. . .

Impact can take a long time

The mathematics behind nominal sets goes back a long way. . .



Abraham Fraenkel, *Der Begriff "definit" und die Unabhängigkeit des Auswahlaxioms*, Sitzungsberichte der Preussischen Akademie der Wissenschaften, Physikalisch-mathematische Klasse (1922), 253–257.



Andrzej Mostowski, *Über die Unabhängigkeit des Wohlordnungssatzes vom Ordnungsprinzip*, Fundamenta Mathematicae 32 (1939), 201–252.

Impact can take a long time

The mathematics behind nominal sets goes back a long way. . .

. . . and it's still too early to tell what will be the impact of the applications of it to CS developed over the last 15 years.