

Unsupervised Clustering and Latent Dirichlet Allocation

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Machine Learning for Language Processing: Lecture 8

MPhil in Advanced Computer Science

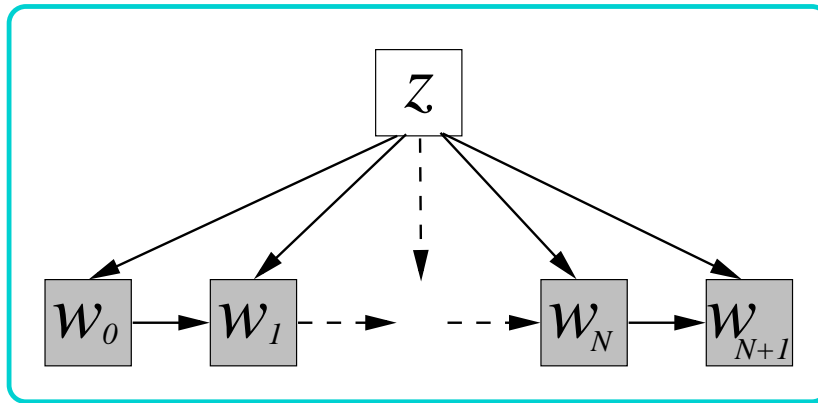
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Introduction

- So far described a number of models for word sequences
 - most common are based on N -grams and mixtures of N -grams
- In this lecture we will examine:
 - the application of N -grams (and extensions) to topic clustering;
 - an alternative generative model **latent Dirichlet allocation**
- The last slides will not be covered in the lectures - **briefly mention**
 - what happens as the number of clusters tends to infinity
 - infinite Gaussian mixture models
 - Dirichlet processes

Unsupervised Document Clustering

- Use a topic-dependent N -gram language model to perform clustering



- word sequence $\mathbf{w} = \{w_1, \dots, w_N\}$
- start, w_0 , and end w_{N+1} symbols added
- z indicator variable over topics $\mathbf{s}_1, \dots, \mathbf{s}_K$
- **plate** repeated for every document

- Training data fully observed (supervised training) standard N -gram training
 - **BUT** interested in **unsupervised clustering** - indicator variable z unobserved
- Likelihood of one document with word sequence \mathbf{w} can be written as

$$P(\mathbf{w}) = \sum_{k=1}^K P(\mathbf{s}_k) P(\mathbf{w} | \mathbf{s}_k) = \sum_{k=1}^K P(\mathbf{s}_k) \prod_{i=1}^{N+1} P(w_i | w_{i-1}, \mathbf{s}_k)$$

Unsupervised Clustering

- The likelihood has been written as **marginalising** over the latent variable
 - standard mixture model - use EM **BUT** interested in clustering documents
- Rather than using the “soft” assignment in EM, use a **hard assignment**

$$z_r^{[l]} = \operatorname{argmax}_{\mathbf{s}_k} \left\{ P(\mathbf{s}_k | \boldsymbol{\lambda}^{[l]}) P(\mathbf{w}^{(r)} | \mathbf{s}_k, \boldsymbol{\lambda}^{[l]}) \right\}$$

- compare to EM where at iteration l compute $P(\mathbf{s}_k | \mathbf{w}, \boldsymbol{\lambda}^{[l]})$
- allows documents to be clustered together (unique label for each document)

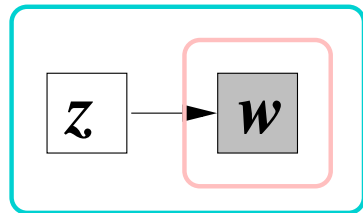
For parameters of component \mathbf{s}_k :

$$\boldsymbol{\lambda}_k^{[l+1]} = \operatorname{argmax}_{\boldsymbol{\lambda}} \left\{ \prod_{r: z_r^{[l]} = \mathbf{s}_k} P(\mathbf{w}^{(r)} | \boldsymbol{\lambda}) \right\}$$

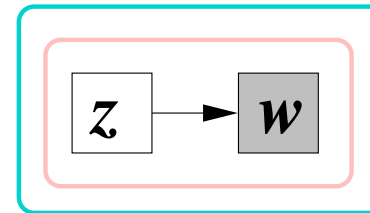
- Iterative procedure (similar to **Viterbi training**) - example of **K-means clustering**
 - can initialise model parameters by using K randomly selected examples

Language Model Components

- For simplicity only consider a unigram language model - for BNs below
 - **inner plate** repeated for each word (start/end symbols ignored as unigram)
 - **outer plate** for each document



$$\sum_{k=1}^K P(\mathbf{s}_k) \prod_{i=1}^N P(w_i | \mathbf{s}_k)$$



$$\prod_{i=1}^N \left(\sum_{k=1}^K P(\mathbf{s}_k) P(w_i | \mathbf{s}_k) \right)$$

- Interesting to contrast two forms of latent variable model
 - (left) indicator variable z over space of **language models**
 - (right) indicator variable z over space of **language model predictions**
- Possible to combine latent variable models (a hierarchical model)

Bayesian Approaches

- Consider a generative model for class ω_j (supervised training)
 - **training data**: $\mathcal{D} = \{\mathbf{x}_1 \dots, \mathbf{x}_n\}$
 - parametric form of distribution (the model), \mathcal{M} , is known (and fixed) with (unknown) parameters θ
- Rather than estimating the parameters of the model, $\hat{\theta}$, use a distribution
 - from training data obtain the **posterior distribution over model parameters**

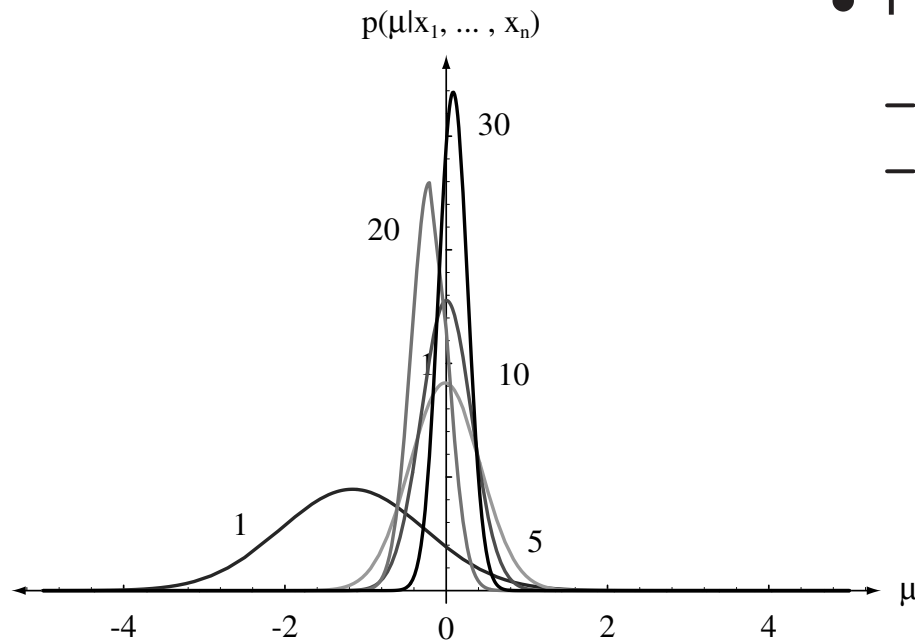
$$p(\theta|\mathcal{D}, \mathcal{M}) = \frac{p(\mathcal{D}|\theta, \mathcal{M})p(\theta|\mathcal{M})}{p(\mathcal{D}|\mathcal{M})} \quad \text{Note MAP } \hat{\theta} = \underset{\theta}{\operatorname{argmax}} \{p(\theta|\mathcal{D}, \mathcal{M})\}$$

- $p(\theta|\mathcal{M})$ is the **prior distribution** over the model parameters
- Likelihood of an observation \mathbf{x} then computed as

$$p(\mathbf{x}|\mathcal{D}, \mathcal{M}) = \int p(\mathbf{x}|\theta, \mathcal{M})p(\theta|\mathcal{D}, \mathcal{M})d\theta \quad \text{Note MAP } p(\mathbf{x}|\mathcal{D}, \mathcal{M}) \approx p(\mathbf{x}|\hat{\theta}, \mathcal{M})$$

Distribution of the Mean Estimate

- Consider Bayesian estimation of the mean μ of a Gaussian distribution



- Posterior $p(\mu | \mathcal{D}, \mathcal{M})$ variation (from DHS)
 - Gaussian distributed - $\mu \sim \mathcal{N}(\hat{\mu}, \hat{\Sigma})$
 - prior $\mathcal{N}(\mathbf{0}, \Sigma_p)$

$$\hat{\mu} = (n\Sigma^{-1} + \Sigma_p^{-1})^{-1} \left(\Sigma^{-1} \sum_{i=1}^n \mathbf{x}_i \right)$$

$$\hat{\Sigma} = (n\Sigma^{-1} + \Sigma_p^{-1})^{-1}$$

- Shape of posterior distribution changes as n increases
 - the posterior becomes more sharply peaked (reduced variance)
 - MAP estimate (the mode of the distribution) moves towards ML estimate

Latent Dirichlet Allocation

- Interested in applying Bayesian approaches to language processing
 - consider a mixture-of-unigrams language model

$$P(\mathbf{w}) = \prod_{i=1}^N \sum_{k=1}^K P(\mathbf{s}_k) P(w_i | \mathbf{s}_k)$$

where $P(\mathbf{s}_k)$ is estimated from training data

- **alternatively** consider a Bayesian version over the topic priors

$$P(\mathbf{w} | \boldsymbol{\alpha}) = \int p(\boldsymbol{\theta} | \boldsymbol{\alpha}) \left(\prod_{i=1}^N \sum_{k=1}^K P(\mathbf{s}_k | \boldsymbol{\theta}) P(w_i | \mathbf{s}_k) \right) d\boldsymbol{\theta}$$

where $p(\boldsymbol{\theta} | \boldsymbol{\alpha})$ obtained from the training data

What form of distribution/latent variable model to use?

(Reminder) Multinomial Distribution

- **Multinomial** distribution: $x_i \in \{0, \dots, n\}$

$$P(\mathbf{x}|\boldsymbol{\theta}) = \frac{n!}{\prod_{i=1}^d x_i!} \prod_{i=1}^d \theta_i^{x_i}, \quad n = \sum_{i=1}^d x_i, \quad \sum_{i=1}^d \theta_i = 1, \quad \theta_i \geq 0$$

- When $n = 1$ the multinomial distribution simplifies to

$$P(\mathbf{x}|\boldsymbol{\theta}) = \prod_{i=1}^d \theta_i^{x_i}, \quad \sum_{i=1}^d \theta_i = 1, \quad \theta_i \geq 0$$

- a unigram language model with **1-of-V coding** ($d = V$ the vocabulary size)
- x_i indicates word i of the vocabulary observed, $x_i = \begin{cases} 1, & \text{word } i \text{ observed} \\ 0, & \text{otherwise} \end{cases}$
- $\theta_i = P(w_i)$ the probability that word i is seen

(More) Probability Distributions

- **Dirichlet** (continuous) distribution with parameters α

$$p(\mathbf{x}|\boldsymbol{\alpha}) = \frac{\Gamma(\sum_{i=1}^d \alpha_i)}{\prod_{i=1}^d \Gamma(\alpha_i)} \prod_{i=1}^d x_i^{\alpha_i-1}; \quad \text{for "observations": } \sum_{i=1}^d x_i = 1, \quad x_i \geq 0$$

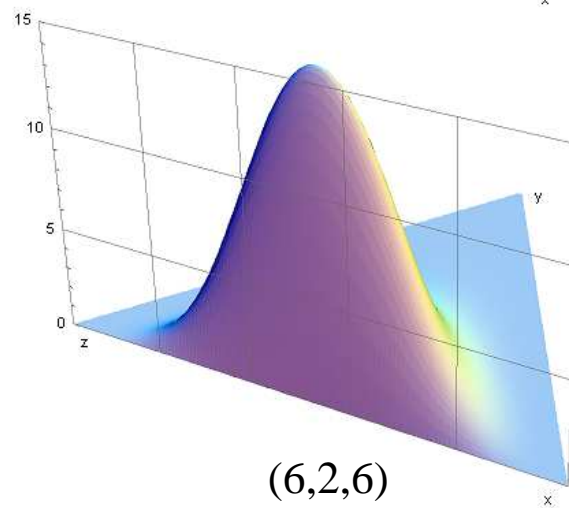
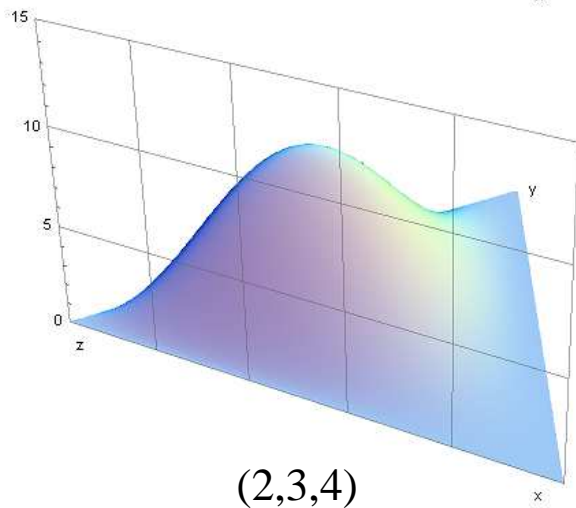
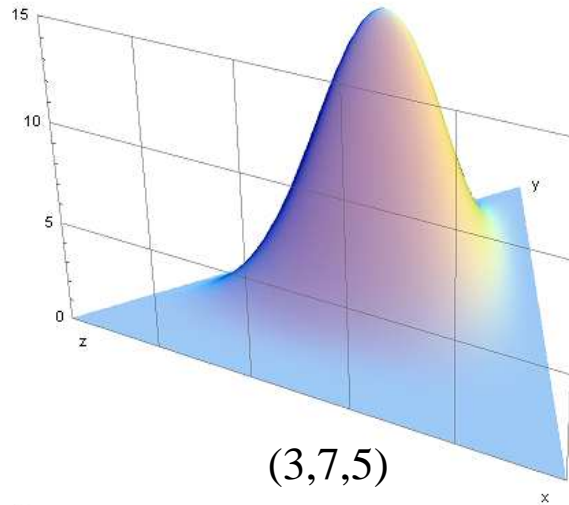
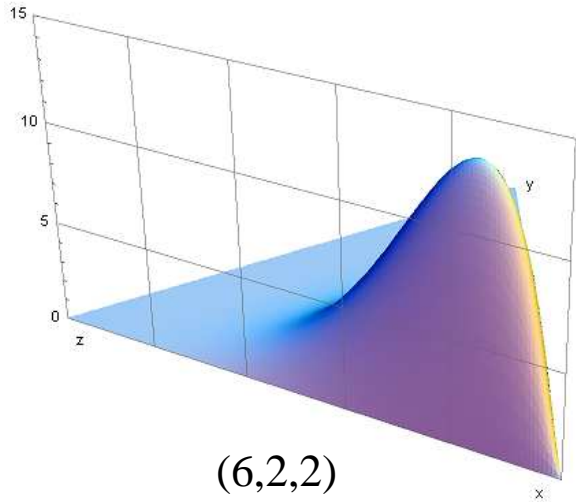
- $\Gamma()$ is the **Gamma distribution**
- **Conjugate prior** to the multinomial distribution
(form of posterior $p(\boldsymbol{\theta}|\mathcal{D}, \mathcal{M})$ is the same as the prior $p(\boldsymbol{\theta}|\mathcal{M})$)

- **Poisson** (discrete) distribution with parameter ξ

$$P(x|\xi) = \frac{\xi^x \exp(-\xi)}{x!}$$

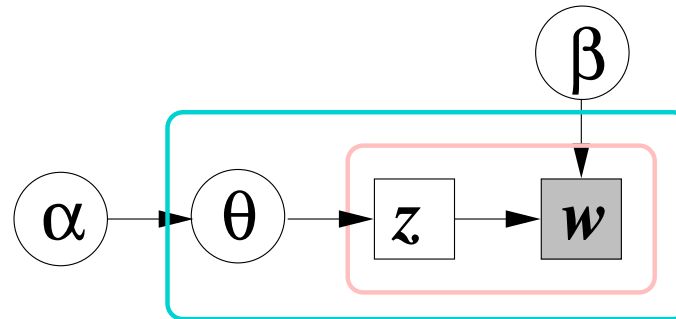
- probability of the number of events in a specific interval
- here used for number of words in a document

Dirichlet Distribution Example



- Note: $x + y + z = 1$
- Vector: $(\alpha_1, \alpha_2, \alpha_3)$

Latent Dirichlet Allocation Bayesian Network



- Bayesian Network for Latent Dirichlet Allocation (LDA) is shown above
 - **explicitly** includes dependence on model parameters $\lambda = \{\alpha, \beta\}$

$$P(\mathbf{w}|\alpha, \beta) = \int p(\boldsymbol{\theta}|\alpha) \left(\prod_{i=1}^N \sum_{k=1}^K P(\mathbf{s}_k|\boldsymbol{\theta}) P(w_i|\mathbf{s}_k, \beta) \right) d\boldsymbol{\theta}$$

- z is an indicator variable for one of the K **topics**: $\{\mathbf{s}_1, \dots, \mathbf{s}_K\}$
- **inner plate** is repeated for N words, **outer plate** is repeated for R documents
- **Bayesian approach** learn posterior distribution of the component priors, $\boldsymbol{\theta}$,
 - Dirichlet distribution $p(\boldsymbol{\theta}|\alpha) = p(\boldsymbol{\theta}|\mathcal{D}, \mathcal{M})$, and noting $P(\mathbf{s}_k|\boldsymbol{\theta}) = \theta_k$

LDA Generative Process

- LDA assumes the following generative process for the words w is a document
 1. Choose **length of document** - $N \sim \text{Poisson}(\xi)$
 2. Choose **parameters of multinomial** - $\theta \sim \text{Dir}(\alpha)$
 3. For each of the N words w_n :
 - (a) Choose **topic**: $z_n \sim \text{Multinomial}(\theta)$
 - (b) Choose **word**: w_n from multinomial probability conditioned on topic z_n with parameters β
- The parameters that need to be estimated for LDA
 - $\alpha = \{\alpha_1, \dots, \alpha_K\}$: K parameters
the prior distribution over the multinomial parameters
 - $\beta = \{\beta_{11}, \beta_{1V}, \dots, \beta_{K1}, \dots, \beta_{KV}\}$: KV parameters
Note $\beta_{ki} \geq 0, \sum_{i=1}^V \beta_{ki} = 1 \quad \forall k, i$ - this is the equivalent of **topic-unigrams**

LDA Parameter Estimation

- Given corpus of documents $\{\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(R)}\}$ need to estimate α, β

$$\mathcal{L}(\alpha, \beta) = \sum_{r=1}^R \log \left(P(\mathbf{w}^{(r)} | \alpha, \beta) \right)$$

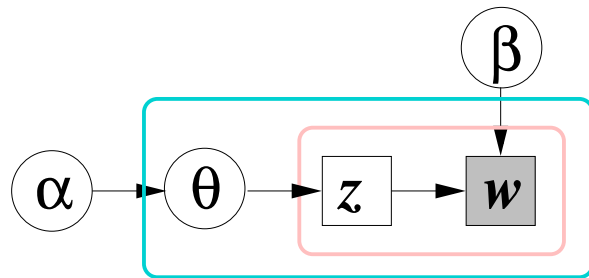
- Unfortunately likelihood calculation is **intractable** need to compute

$$P(\mathbf{w} | \alpha, \beta) = \frac{\Gamma(\sum_{k=1}^K \alpha_k)}{\prod_{k=1}^K \Gamma(\alpha_k)} \int \left(\prod_{k=1}^K \theta_k^{\alpha_k - 1} \right) \left(\prod_{i=1}^N \sum_{k=1}^K \theta_k \prod_{j=1}^V (\beta_{kj})^{I(w_i, j)} \right) d\theta$$

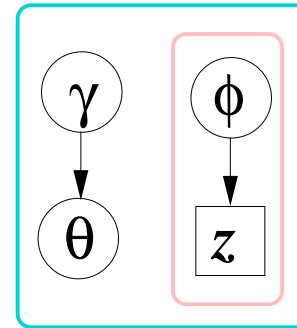
- **word indicator**: $I(w_i, j) = \begin{cases} 1, & w_i = \text{word } j \text{ in the vocabulary} \\ 0, & \text{otherwise} \end{cases}$
- $P(\mathbf{s}_k | \theta) = \theta_k$ and $P(w_i | \mathbf{s}_k, \beta) = \beta_{ki}$

- Not possible to use EM: require $p(\theta, \mathbf{z} | \mathbf{w}, \alpha, \beta) = \frac{p(\theta, \mathbf{z}, \mathbf{w} | \alpha, \beta)}{P(\mathbf{w} | \alpha, \beta)}$

Variational EM (Reference)



Latent Dirichlet Allocation



Variational Approximation

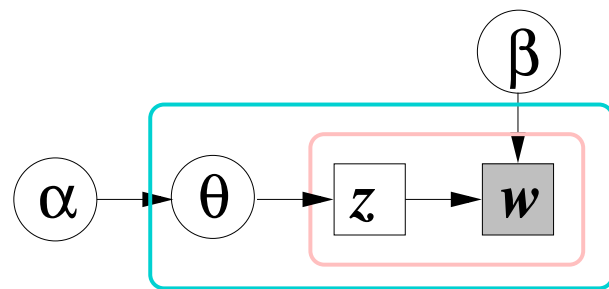
- LDA can be estimated using **variational EM** with the mean-field approximation
 - use a **variational approximation** $q(\theta, z|\gamma, \phi)$ - see diagram on right

$$q(\theta, z|\gamma, \phi) = q(\theta|\gamma) \prod_{i=1}^N q(z_i|\phi_i)$$

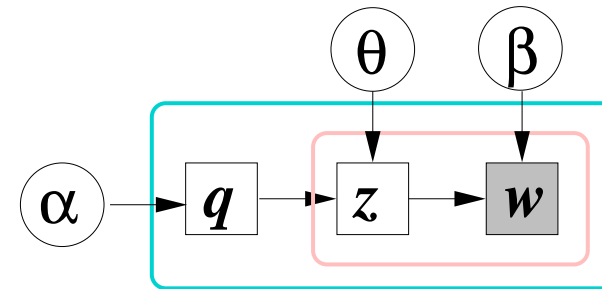
- parameters - minimise **KL-divergence**: $\text{KL}(q()||p()) = \int p(x) \log(q()/p()) dx$

$$\{\gamma^{[l]}, \phi^{[l]}\} = \underset{\gamma, \phi}{\text{argmin}} \left\{ \text{KL}(q(\theta, z|\gamma, \phi) || p(\theta, z|\mathbf{w}, \alpha^{[l]}, \beta^{[l]})) \right\}$$

LDA and Topic Mixture of Unigrams



Latent Dirichlet Allocation



Topic Mixture of Unigrams

- Latent Dirichlet allocation - parameters $K(1 + V)$ - continuous mixture

$$P(\mathbf{w}|\boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{\Gamma(\sum_{k=1}^K \alpha_k)}{\prod_{k=1}^K \Gamma(\alpha_k)} \int \left(\prod_{k=1}^K \theta_k^{\alpha_k - 1} \right) \left(\prod_{i=1}^N \sum_{k=1}^K \theta_k \prod_{j=1}^V (\beta_{kj})^{I(w_i, j)} \right) d\boldsymbol{\theta}$$

- Topic mixture of unigrams - parameters $M + K(M + V)$ - discrete mixture

$$P(\mathbf{w}|\boldsymbol{\alpha}, \boldsymbol{\beta}, \boldsymbol{\theta}) = \sum_{m=1}^M \alpha_m \left(\prod_{i=1}^N \sum_{k=1}^K \theta_{mk} \prod_{j=1}^V (\beta_{kj})^{I(w_i, j)} \right)$$

Properties of LDA

- LDA is a **generative model** of a document
 - **compact** model of the data
 - infinite component priors represented by K -parameter distribution $p(\boldsymbol{\theta}|\boldsymbol{\alpha})$
 - can be combined with standard language model smoothing for $\boldsymbol{\beta}$
- Consider using LDA as a generative model for classification for
 - for each class ω_j estimate $\{\boldsymbol{\alpha}^{(j)}, \boldsymbol{\beta}^{(j)}\}$ using all documents from class ω_j
 - estimate the prior for each class $P(\omega_j)$
 - perform classification for sequence \boldsymbol{w} based on

$$\hat{\omega} = \operatorname{argmax}_{\omega_j} \left\{ P(\omega_j) P(\boldsymbol{w} | \boldsymbol{\alpha}^{(j)}, \boldsymbol{\beta}^{(j)}) \right\}$$

- LDA has also been used for a range of language processing applications

How Many Topics?

- So far not consider the number of topics, K , for LDA
 - how about using a Bayesian approach

$$P(\mathbf{w}|\boldsymbol{\alpha}^{(1)}, \dots, \boldsymbol{\alpha}^{(\infty)}) = \sum_{K=1}^{\infty} P(K) \int p(\boldsymbol{\theta}^{(K)}|\boldsymbol{\alpha}^{(K)}) \left(\prod_{i=1}^N \sum_{k=1}^K P(\mathbf{s}_k|\boldsymbol{\theta}^{(K)}) P(w_i|\mathbf{s}_k, \boldsymbol{\beta}) \right) d\boldsymbol{\theta}^{(K)}$$

- each of the priors of **infinite mixture models** has a Dirichlet distribution
- There's a **infinite** number of components
 - unfortunately an infinite number of parameters $\boldsymbol{\alpha}^{(1)}, \dots, \boldsymbol{\alpha}^{(\infty)}, \boldsymbol{\beta}$ to train

Can we keep the infinite model, but make it tractable?

- **Non-parametric Bayesian** approaches: (hierarchical) Dirichlet Processes

Gaussian Mixture Models

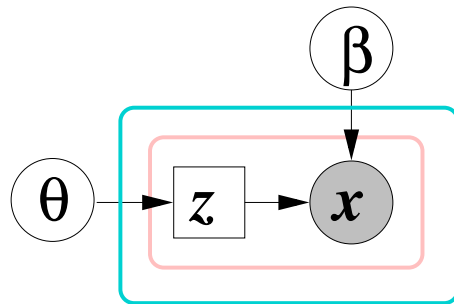
- Consider simpler (illustrative) example - the **Infinite Gaussian Mixture Model**
- Standard form of M -component Gaussian Mixture Model (GMM) is

$$p(\mathbf{x}|\boldsymbol{\theta}, \boldsymbol{\beta}) = \sum_{m=1}^M P(\mathbf{c}_m|\boldsymbol{\theta})p(\mathbf{x}|\mathbf{c}_m, \boldsymbol{\beta}) = \sum_{m=1}^M P(\mathbf{c}_m|\boldsymbol{\theta})\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_m, \boldsymbol{\Sigma}_m)$$

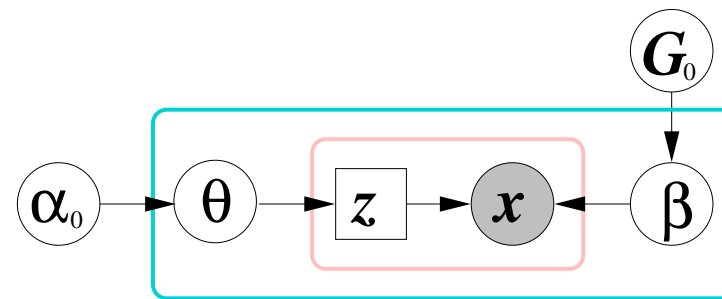
Interested in what happens as $M \rightarrow \infty$?

- Must use Bayesian approaches as the number of parameters infinite
 - what sort of prior distributions to use?
- Introduce **prior distributions** $\{\alpha_0, \boldsymbol{\beta}\}$
 - α_0 - prior parameter for the Dirichlet distribution
 - $\boldsymbol{\beta}$ - prior distribution for Gaussian components

Infinite Gaussian Mixture Models



Gaussian Mixture Model



Infinite Gaussian Mixture Model

- From the Bayesian network above

$$p(\mathbf{x}_1, \dots, \mathbf{x}_N | \alpha_0, G_0) = \int \int p(\boldsymbol{\theta} | \alpha_0) p(\boldsymbol{\beta} | G_0) \prod_{i=1}^N \sum_{m=1}^M P(\mathbf{c}_m | \boldsymbol{\theta}) p(\mathbf{x}_i | \mathbf{c}_m, \boldsymbol{\beta}) d\boldsymbol{\theta} d\boldsymbol{\beta}$$

where: $\boldsymbol{\theta} | \alpha_0 \sim \text{Dirichlet}(\frac{\alpha_0}{M}, \dots, \frac{\alpha_0}{M})$; $\boldsymbol{\beta}_m \sim G_0$; $\mathbf{c}_m | \boldsymbol{\theta} \sim \text{Multinomial}(\boldsymbol{\theta})$

- Estimate the hyper-parameters from training data, $\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ - maximise

$$\mathcal{L}(\alpha_0, G_0) = \log(p(\mathbf{x}_1, \dots, \mathbf{x}_N | \alpha_0, G_0))$$

THE END - SLIDES ARE FOR REFERENCE FROM HERE

Sample-Based Approximations

- Simple approach to approximate integrals is to use

$$\int f(\mathbf{x})p(\mathbf{x}|\boldsymbol{\theta})d\mathbf{x} \approx \frac{1}{N} \sum_{i=1}^N f(\mathbf{x}^{(i)}); \quad \mathbf{x}^{(i)} \sim p(\boldsymbol{\theta})$$

- as $N \rightarrow \infty$ the approximation will become an equality
- N needs to increase as dimension \mathbf{x} increases - need to sample the space

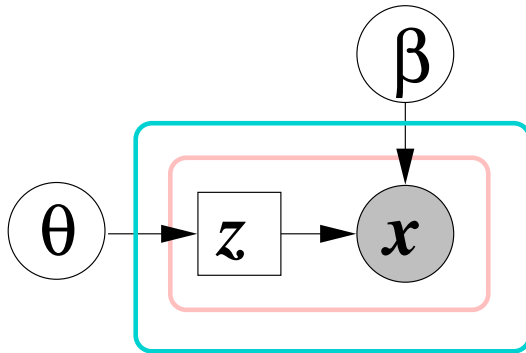
marginalising is simply sampling

- If a sample can't be directly generated from the multivariate distribution $p(\boldsymbol{\theta})$
 - Gibbs sampling from conditional distributions can be used
 - assume that we have samples $x_1^{(i)}, \dots, x_{k-1}^{(i)}, x_{k+1}^{(i)}, x_d^{(i)}$ generate $x_k^{(i)}$
 - sample from

$$p(x_k | x_1, \dots, x_{k-1}, x_{k+1}, x_d, \boldsymbol{\theta})$$

- assumes that possible to sample from the conditional

Gaussian Mixture Model Sampling



$$\begin{aligned} p(\mathbf{x}|\boldsymbol{\theta}, \boldsymbol{\beta}) &= \sum_{m=1}^M P(\mathbf{c}_m|\boldsymbol{\theta})p(\mathbf{x}|\mathbf{c}_m, \boldsymbol{\beta}) \\ &= \sum_{m=1}^M P(\mathbf{c}_m|\boldsymbol{\theta})p(\mathbf{x}|\boldsymbol{\beta}_m) \end{aligned}$$

- Sampling approach from distribution comprises
 1. Generate component indicator $z_n \sim \text{Multinomial}(\boldsymbol{\theta})$
 2. Generate observation: $\mathbf{x}_n \sim \mathcal{N}(\boldsymbol{\beta}_{z_n})$
- Simple to train using EM (see lecture 5)
 - non-Bayesian - point estimates of the model parameters $\{\boldsymbol{\theta}, \boldsymbol{\beta}\}$
 - number of components M fixed

IGMM Sampling Procedure

How to generate samples from infinite components?

- **Gibb's Sampling** process to generate $\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ for N samples

1. Generate component indicator $z_n | \mathbf{z}_{-n}$ ($\mathbf{z}_{-n} = \{z_1, \dots, z_{n-1}\}$)

$$P(z_n = c_j | \mathbf{z}_{-n}, \alpha_0) = \begin{cases} \frac{\sum_{i=1}^{n-1} \mathbf{1}(z_i, c_j)}{n-1+\alpha_0} & c_j \text{ represented} \\ \frac{\alpha_0}{n-1+\alpha_0} & c_j \text{ unrepresented} \end{cases}$$

2. If component indicted by z_n is unrepresented: $\beta_{z_n} \sim G_0$

3. Generate observation: $\mathbf{x}_n \sim \mathcal{N}(\beta_{z_n})$

- At most N of the infinite possible samples represented

IGMM Hyper-Parameter Training

- Using Gibb's sampling to training hyper-parameters of G_0
 - sampling process to generate $\{z^{(l)}, \beta^{(l)}\}$ for these N samples, $\{x_1, \dots, x_N\}$
1. Generate component indicators $z^{(l)} | z_{-n}^{(l)}, \beta^{(l-1)}, x_n$ (dropped dependence)

$$P(z_n^{(l)} = c_j | \alpha_0^{(l-1)}, G_0^{(l-1)}) \propto \begin{cases} \frac{\sum_{i=1}^{n-1} \mathbf{1}(z_i^{(l)}, c_j)}{n-1+\alpha_0^{(l-1)}} p(x_n | \beta_j^{(l-1)}) & c_j \text{ represented} \\ \frac{\alpha_0^{(l-1)}}{n-1+\alpha_0^{(l-1)}} \int p(x_n | \beta) p(\beta | G_0^{(l-1)}) d\beta & c_j \text{ unrepresented} \end{cases}$$

2. Foreach represented component $c_j, j \in \{1, \dots, k_{\text{rep}}\}$

sample component mean and variance: $\beta_j^{(l)} = \{\mu_j^{(l)}, \Sigma_j^{(l)}\} \sim G_0^{(l-1)}$

3. Update hyper-parameters $\{\alpha_0^{(l)}, G_0^{(l)}\}$ using component values $\beta_1^{(l)}, \dots, \beta_{k_{\text{rep}}}^{(l)}$
 - (a) increment the counter $l = l + 1$

IGMM Classification

- So how can we perform classification - need the class-likelihood (prior simple)
 - consider observation \mathbf{x} given training data for class ω_j : $\mathcal{D} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$

$$p(\mathbf{x}|\mathcal{D}, \alpha_0, G_0) = \frac{p(\mathbf{x}, \mathcal{D}|\alpha_0, G_0)}{p(\mathcal{D}|\alpha_0, G_0)} = \frac{p(\mathbf{x}, \mathbf{x}_1, \dots, \mathbf{x}_N|\alpha_0, G_0)}{p(\mathbf{x}_1, \dots, \mathbf{x}_N|\alpha_0, G_0)}$$

- clearly a **non-parametric model** - explicit dependence on training observations
- Use a sample-based approximations for numerator/denominator thus

$$p(\mathbf{x}_1, \dots, \mathbf{x}_N|\alpha_0, G_0) \approx \frac{1}{L} \sum_{l=1}^L \prod_{i=1}^N p(\mathbf{x}_i|\mathbf{z}^{(l)}, \boldsymbol{\beta}^{(l)})$$

- follow hyper-parameter training **without** update to hyper-parameters
 - similar for $p(\mathbf{x}, \mathbf{x}_1, \dots, \mathbf{x}_N|\alpha_0, G_0)$

Dirichlet Processes

- Dirichlet Processes are a generalisation of the Dirichlet distribution
 - both can be viewed as distributions over distributions
 - **BUT** Dirichlet processes act over infinite components

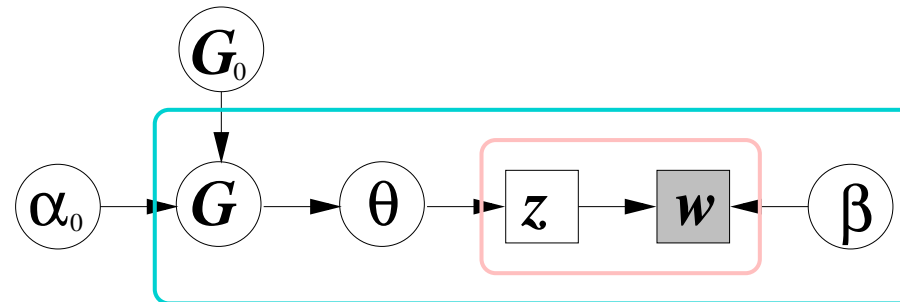
- Model has the form

$$G \sim \text{DP}(\alpha_0, G_0);$$

- G_0 is the **base measure** (distribution)
- α_0 is the **concentration parameter**
- If the measure is parametrised with θ
 - each **draw** of G from G_0 yields $\theta_k \sim G_0$
 - δ_{θ_k} indicates a δ function at the parameters for draw k , θ_k
 - **Reminder:**

$$\int f(\mathbf{x}|\theta)\delta_{\theta_k}d\theta = f(\mathbf{x}|\theta_k)$$

Example Dirichlet Process



- The likelihood of the word sequence $\mathbf{w} = \{w_1, \dots, w_N\}$ can be expressed as

$$P(\mathbf{w}|\alpha_0, G_0) = \int P(G|\alpha_0, G_0) \int P(\beta) \int p(\theta|G) P(\mathbf{w}|\theta, G, \beta) d\theta d\beta dG$$

- G is distributed according to the Dirichlet Process $DP(\alpha_0, G_0)$
- if K is the number of components associated with the G

$$P(\mathbf{w}|\theta, G, \beta) = \prod_{i=1}^N \sum_{k=1}^K P(\mathbf{s}_k|\theta) P(w_i|\mathbf{s}_k, \beta)$$

- **BUT** can't share cluster parameters (β) across different draws
 - no relationship between clusters ... **hierarchical Dirichlet priors**

Dirichlet Processes Generative Process

- Can't directly sample from Dirichlet process - use [Gibb's sampling](#)
 - behaviour of θ_n given previous $n - 1$ draw $\theta_1, \dots, \theta_{n-1}$

$$\theta_n | \theta_1, \dots, \theta_{n-1}, \alpha_0, G_0 \sim \frac{\alpha_0}{n-1+\alpha_0} G_0 + \sum_{i=1}^{n-1} \frac{1}{n-1+\alpha_0} \delta_{\theta_i}$$

- this is the equivalent of the generative process where

$$\theta_n = \begin{cases} \theta_i & \text{with probability } \frac{1}{n-1+\alpha_0} \text{ for } 1 \leq i \leq (n-1) \\ \theta \sim G_0() & \text{with probability } \frac{\alpha_0}{n-1+\alpha_0} \end{cases}$$

- A draw from a Dirichlet process ([stick-breaking representation](#))

$$G = \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}; \quad \theta_k \sim G_0; \quad \psi_k \sim \text{Beta}(1, \alpha_0); \quad \pi_k = \psi_k \prod_{i=1}^{k-1} (1 - \psi_i)$$

- Google [Chinese Restaurant Process](#) for a simple example