

## Topics in Logic and Complexity

### Part 9

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### Syntax of LFP

- Any relation symbol of arity  $k$  is a predicate expression of arity  $k$ ;
- If  $R$  is a relation symbol of arity  $k$ ,  $\mathbf{x}$  is a tuple of variables of length  $k$  and  $\phi$  is a formula of LFP in which the symbol  $R$  only occurs positively, then

$$\mathbf{lfp}_{R,\mathbf{x}}\phi$$

is a predicate expression of LFP of arity  $k$ .

All occurrences of  $R$  and variables in  $\mathbf{x}$  in  $\mathbf{lfp}_{R,\mathbf{x}}\phi$  are *bound*

### Syntax of LFP

- If  $t_1$  and  $t_2$  are terms, then  $t_1 = t_2$  is a formula of LFP.
- If  $P$  is a predicate expression of LFP of arity  $k$  and  $\mathbf{t}$  is a tuple of terms of length  $k$ , then  $P(\mathbf{t})$  is a formula of LFP.
- If  $\phi$  and  $\psi$  are formulas of LFP, then so are  $\phi \wedge \psi$ , and  $\neg\phi$ .
- If  $\phi$  is a formula of LFP and  $x$  is a variable then,  $\exists x\phi$  is a formula of LFP.

### Semantics of LFP

Let  $\mathbb{A} = (A, \mathcal{I})$  be a structure with universe  $A$ , and an interpretation  $\mathcal{I}$  of a fixed vocabulary  $\sigma$ .

Let  $\phi$  be a formula of LFP, and  $\nu$  an interpretation in  $A$  of all the free variables (*first or second order*) of  $\phi$ .

To each individual variable  $x$ ,  $\nu$  associates an element of  $A$ , and to each  $k$ -ary relation symbol  $R$  in  $\phi$  that is not in  $\sigma$ ,  $\nu$  associates a relation  $\nu(R) \subseteq A^k$ .

$\nu$  is extended to terms  $t$  in the usual way.

For constants  $c$ ,  $\nu(c) = \mathcal{I}(c)$ .

$$\nu(f(t_1, \dots, t_n)) = \mathcal{I}(f)(\nu(t_1), \dots, \nu(t_n))$$

## Semantics of LFP

- If  $R$  is a relation symbol in  $\sigma$ , then  $\iota(R) = \mathcal{I}(R)$ .
- If  $P$  is a predicate expression of the form  $\mathbf{lfp}_{R,\mathbf{x}}\phi$ , then  $\iota(P)$  is the relation that is the least fixed point of the monotone operator  $F$  on  $A^k$  defined by:

$$F(X) = \{\mathbf{a} \in A^k \mid \mathbb{A} \models \phi[\iota\langle X/R, \mathbf{x}/\mathbf{a} \rangle],$$

where  $\iota\langle X/R, \mathbf{x}/\mathbf{a} \rangle$  denotes the interpretation  $\iota'$  which is just like  $\iota$  *except* that  $\iota'(R) = X$ , and  $\iota'(\mathbf{x}) = \mathbf{a}$ .

## Semantics of LFP

- If  $\phi$  is of the form  $t_1 = t_2$ , then  $\mathbb{A} \models \phi[\iota]$  if,  $\iota(t_1) = \iota(t_2)$ .
- If  $\phi$  is of the form  $R(t_1, \dots, t_k)$ , then  $\mathbb{A} \models \phi[\iota]$  if,

$$(\iota(t_1), \dots, \iota(t_k)) \in \iota(R).$$

- If  $\phi$  is of the form  $\psi_1 \wedge \psi_2$ , then  $\mathbb{A} \models \phi[\iota]$  if,  $\mathbb{A} \models \psi_1[\iota]$  *and*  $\mathbb{A} \models \psi_2[\iota]$ .
- If  $\phi$  is of the form  $\neg\psi$  then,  $\mathbb{A} \models \phi[\iota]$  if,  $\mathbb{A} \not\models \psi[\iota]$ .
- If  $\phi$  is of the form  $\exists x\psi$ , then  $\mathbb{A} \models \phi[\iota]$  if there is an  $a \in A$  such that  $\mathbb{A} \models \psi[\iota\langle x/a \rangle]$ .

## Transitive Closure

The formula (with free variables  $u$  and  $v$ )

$$\theta \equiv \mathbf{lfp}_{T,xy}[(x = y \vee \exists z(E(x,z) \wedge T(z,y)))](u, v)$$

defines the *reflexive and transitive closure* of the relation  $E$ .

Thus  $\forall u \forall v \theta$  defines *connectedness*.

The expressive power of LFP properly extends that of first-order logic.

## Greatest Fixed Points

If  $\phi$  is a formula in which the relation symbol  $R$  occurs *positively*, then the *greatest fixed point* of the monotone operator  $F_\phi$  defined by  $\phi$  can be defined by the formula:

$$\neg[\mathbf{lfp}_{R,\mathbf{x}} \neg\phi(R/\neg R)](\mathbf{x})$$

where  $\phi(R/\neg R)$  denotes the result of replacing all occurrences of  $R$  in  $\phi$  by  $\neg R$ .

*Exercise:* Verify!.

## Simultaneous Inductions

We are given two formulas  $\phi_1(S, T, \mathbf{x})$  and  $\phi_2(S, T, \mathbf{y})$ ,  
 $S$  is  $k$ -ary,  $T$  is  $l$ -ary.

The pair  $(\phi_1, \phi_2)$  can be seen as defining a map:

$$F : \text{Pow}(A^k) \times \text{Pow}(A^l) \rightarrow \text{Pow}(A^k) \times \text{Pow}(A^l)$$

If both formulas are positive in both  $S$  and  $T$ , then there is a least fixed point.

$$(P_1, P_2)$$

defined by *simultaneous induction* on  $\mathbb{A}$ .

## Simultaneous Inductions

### Theorem

For any pair of formulas  $\phi_1(S, T)$  and  $\phi_2(S, T)$  of LFP, in which the symbols  $S$  and  $T$  appear only positively, there are formulas  $\phi_S$  and  $\phi_T$  of LFP which, on any structure  $\mathbb{A}$  containing at least two elements, define the two relations that are defined on  $\mathbb{A}$  by  $\phi_1$  and  $\phi_2$  by simultaneous induction.

## Proof

Assume  $k \leq l$ .

We define  $P$ , of arity  $l + 2$  such that:

$$(c, d, a_1, \dots, a_l) \in P \text{ if, and only if, either } c = d \text{ and } (a_1, \dots, a_k) \in P_1 \text{ or } c \neq d \text{ and } (a_1, \dots, a_l) \in P_2$$

For new variables  $x_1$  and  $x_2$  and a new  $l + 2$ -ary symbol  $R$ , define  $\phi'_1$  and  $\phi'_2$  by replacing all occurrences of  $S(t_1, \dots, t_k)$  by:

$$x_1 = x_2 \wedge \exists y_{k+1}, \dots, \exists y_l R(x_1, x_2, t_1, \dots, t_k, y_{k+1}, \dots, y_l),$$

and replacing all occurrences of  $T(t_1, \dots, t_l)$  by:

$$x_1 \neq x_2 \wedge R(x_1, x_2, t_1, \dots, t_l).$$

## Proof

Define  $\phi$  as

$$(x_1 = x_2 \wedge \phi'_1) \vee (x_1 \neq x_2 \wedge \phi'_2).$$

Then,

$$(\text{lfp}_{R, x_1 x_2 \mathbf{y}} \phi)(x, x, \mathbf{y})$$

defines  $P$ , so

$$\phi_S \equiv \exists x \exists y_{k+1}, \dots, \exists y_l (\text{lfp}_{R, x_1 x_2 \mathbf{y}} \phi)(x, x, \mathbf{y});$$

and

$$\phi_T \equiv \exists x_1 \exists x_2 (x_1 \neq x_2 \wedge \text{lfp}_{R, x_1 x_2 \mathbf{y}} \phi)(x_1, x_2, \mathbf{y}).$$

## Inflationary Fixed Points

We can associate with any formula  $\phi(R, \mathbf{x})$  (even one that is not *monotone* in  $R$  an *inflationary operator*

$$IF_\phi(P) = P \cup F_\phi(P),$$

On any *finite* structure  $\mathbb{A}$  the sequence

$$\begin{aligned} IF^0 &= \emptyset \\ IF^{n+1} &= IF_\phi(IF^n) \end{aligned}$$

converges to a limit  $IF^\infty$ .

If  $F_\phi$  is monotone, then this fixed point is, in fact, the least fixed point of  $F_\phi$ .

## IFP

We define the logic **IFP** with a syntax similar to **LFP** except, instead of the **lfp** rule, we have

If  $R$  is a relation symbol of arity  $k$ ,  $\mathbf{x}$  is a tuple of variables of length  $k$  and  $\phi$  is any formula of **IFP**, then

$$\mathbf{ifp}_{R, \mathbf{x}} \phi$$

is a predicate expression of **IFP** of arity  $k$ .

*Semantics:* we say that the predicate expression  $\mathbf{ifp}_{R, \mathbf{x}} \phi$  denotes the relation that is the limit reached by the iteration of the inflationary operator  $IF_\phi$ .

## IFP

If  $\phi$  defines a monotone operator, the relation defined by

$$\mathbf{ifp}_{R, \mathbf{x}} \phi$$

is the least fixed point of  $\phi$ .

Thus, the *expressive power* of **IFP** is at least as great as that of **LFP**.

In fact, it is no greater:

### Theorem (Gurevich-Shelah)

For every formula  $\phi$  of **LFP**, there is a predicate expression  $\psi$  of **LFP** such that, on any finite structure  $\mathbb{A}$ ,  $\psi$  defines the same relation as  $\mathbf{ifp}_{R, \mathbf{x}} \phi$ .

## Ranks

Let  $\phi(R, \mathbf{x})$  be a formula defining an operator  $F_\phi$  and  $IF_\phi$  be the associated *inflationary* operator given by

$$IF_\phi(S) = S \cup F_\phi(S)$$

In a structure  $\mathbb{A}$ , we define for each  $\mathbf{a} \in A^k$  a *rank*  $|\mathbf{a}|_\phi$ .

The least  $n$  such that  $\mathbf{a} \in IF^n$ , if there is such an  $n$  and  $\infty$  otherwise.

## Stage Comparison

We define the two *stage comparison* relations  $\preceq$  and  $\prec$  by:

$$\mathbf{a} \preceq \mathbf{b} \Leftrightarrow \mathbf{a} \in IF_\phi^\infty \wedge |\mathbf{a}|_\phi \leq |\mathbf{b}|_\phi;$$

$$\mathbf{a} \prec \mathbf{b} \Leftrightarrow |\mathbf{a}|_\phi < |\mathbf{b}|_\phi.$$

These two relations can themselves be defined in IFP.

## Stage Comparison

$$\mathbf{a} \preceq \mathbf{b} \Leftrightarrow \mathbf{a} \in IF_\phi(\{\mathbf{b}' \mid \mathbf{b}' \prec \mathbf{b}\}).$$

$$\mathbf{a} \prec \mathbf{b} \Leftrightarrow \mathbf{b} \notin \{\mathbf{a}' \mid \neg(\mathbf{a} \preceq \mathbf{a}')\}.$$

Together, these give:

$$\mathbf{a} \preceq \mathbf{b} \Leftrightarrow \mathbf{a} \in IF_\phi(\{\mathbf{b}' \mid \mathbf{b} \notin \{\mathbf{a}' \mid \neg(\mathbf{a} \preceq \mathbf{b}')\}\}).$$

This is an inductive definition of  $\preceq$ .

A similar inductive definition is obtained from  $\prec$ .

## Stage Comparison in LFP

In the inductive definition of  $\preceq$ :

$$\mathbf{a} \preceq \mathbf{b} \Leftrightarrow \mathbf{a} \in IF_\phi(\{\mathbf{b}' \mid \mathbf{b} \notin \{\mathbf{a}' \mid \neg(\mathbf{a} \preceq \mathbf{b}')\}\}).$$

we can replace the *negative* occurrences of  $\mathbf{a} \preceq \mathbf{b}$  with  $\neg(\mathbf{b} \prec \mathbf{a})$ ,  
and similarly, in the definition of  $\prec$  replace negative occurrences of  
 $\prec$  with positive occurrences of  $\preceq$

*as long as we can define the maximal rank*

## Maximal Rank

There is a formula  $\mu(\mathbf{y})$ , which defines the set of tuples of maximal rank.

$$IF_\phi(\{\mathbf{b} \mid \mathbf{b} \preceq \mathbf{a}\}) \subseteq IF_\phi(\{\mathbf{b} \mid \mathbf{b} \prec \mathbf{a}\}).$$

Replace the negative occurrence of  $\mathbf{b} \preceq \mathbf{a}$  by  $\neg(\mathbf{a} \prec \mathbf{b})$ .

## Reading List for this Part

1. Immerman. Chapter 4.
2. Libkin. Sections 10.2 and 10.3
3. Grädel et al. Section 2.6.
4. Ebbinghaus and Flum Sections 8.1 and 8.2.

## Topics in Logic and Complexity

### Part 10

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## Complexity of LFP

Any *query* definable in LFP is decidable by a *deterministic* machine in *polynomial time*.

To be precise, we can show, by induction on the structure of the formula  $\phi(\mathbf{x})$  that for each formula  $\phi$  there is a  $k$  such that

$$\mathbb{A} \models \phi[\mathbf{a}]$$

is decidable in time  $O(n^t)$  where  $n$  is the number of elements of  $\mathbb{A}$ .

We prove this by induction on the structure of the formula.

## Complexity of LFP

- Atomic formulas by direct lookup ( $O(n^a)$  time, where  $a$  is the maximum arity of any predicate symbol in  $\sigma$ ).
- Boolean connectives are easy.
  - If  $\mathbb{A} \models \phi_1$  can be decided in time  $O(n^{t_1})$  and  $\mathbb{A} \models \phi_2$  in time  $O(n^{t_2})$ , then  $\mathbb{A} \models \phi_1 \wedge \phi_2$  can be decided in time  $O(n^{\max(t_1, t_2)})$
- If  $\phi \equiv \exists x \psi$  then for each  $a \in \mathbb{A}$  check whether

$$(\mathbb{A}, c \mapsto a) \models \psi[c/x],$$

where  $c$  is a new constant symbol. If  $\mathbb{A} \models \psi$  can be decided in time  $O(n^t)$ , then  $\mathbb{A} \models \phi$  can be decided in time  $O(n^{t+1})$ .

## Complexity of LFP

Suppose  $\phi \equiv \text{lfp}_{R,x}\psi(t)$  ( $R$  is  $l$ -ary)

To decide  $\mathbb{A} \models \phi[\mathbf{a}]$ :

```

R := ∅
for i := 1 to nl do
  R := Fψ(R)
end
if a ∈ R then accept else reject
  
```

## Complexity of LFP

To compute  $F_\psi(R)$

For every tuple  $\mathbf{a} \in A^l$ , determine whether  $(\mathbb{A}, R) \models \psi[\mathbf{a}]$ .

If deciding  $(\mathbb{A}, R) \models \psi$  takes time  $O(n^t)$ , then each assignment to  $R$  inside the loop requires time  $O(n^{l+t})$ . The total time taken to execute the loop is then  $O(n^{2l+t})$ . Finally, the last line can be done by a search through  $R$  in time  $O(n^l)$ . The total running time is, therefore,  $O(n^{2l+t})$ .

The *space* required is  $O(n^l)$ .

## Capturing P

For any  $\phi$  of LFP, the language  $\{[\mathbb{A}]_{<} \mid \mathbb{A} \models \phi\}$  is in P.

Suppose  $\rho$  is a signature that contains a *binary relation symbol*  $<$ , possibly along with other symbols.

Let  $\mathcal{O}_\rho$  denote those structures  $\mathbb{A}$  in which  $<$  is a *linear order* of the universe.

For any language  $L \in \text{P}$ , there is a sentence  $\phi$  of LFP that defines the class of structures

$$\{\mathbb{A} \in \mathcal{O}_\rho \mid [\mathbb{A}]_{<} \in L\}$$

(Immerman; Vardi 1982)

## Capturing P

Recall the proof of *Fagin's Theorem*, that ESO captures NP.

Given a machine  $M$  and an integer  $k$ , there is a *first-order* formula  $\phi_{M,k}$  such that

$$\mathbb{A} \models \exists < \exists T_{\sigma_1} \cdots T_{\sigma_s} \exists S_{q_1} \cdots S_{q_m} \exists H \phi_{M,k}$$

if, and only if,  $M$  accepts  $[\mathbb{A}]_{<}$  in time  $n^k$ , for some order  $<$ .

If we *fix* the order  $<$  as part of the structure  $\mathbb{A}$ , we do not need the outermost quantifier.

Moreover, for a *deterministic* machine  $M$ , the relations  $T_{\sigma_1} \cdots T_{\sigma_s}, S_{q_1} \cdots S_{q_m}, H$  can be defined *inductively*.

## Capturing P

For any  $\phi$  of LFP, the language  $\{[\mathbb{A}]_< \mid \mathbb{A} \models \phi\}$  is in P.

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For any language  $L \in \text{P}$ , there is a sentence  $\phi$  of LFP that defines the class of structures

$$\{\mathbb{A} \in \mathcal{O}_\rho \mid [\mathbb{A}]_{<} \in L\}$$

(Immerman; Vardi 1982)

## Capturing P

Recall the proof of *Fagin's Theorem*, that ESO captures NP.

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if, and only if,  $M$  accepts  $[\mathbb{A}]_<$  in time  $n^k$ , for some order  $<$ .

If we *fix* the order  $<$  as part of the structure  $\mathbb{A}$ , we do not need the outermost quantifier.

Moreover, for a *deterministic* machine  $M$ , the relations  $T_{\sigma_1} \cdots T_{\sigma_s}, S_{q_1} \cdots S_{q_m}, H$  can be defined *inductively*.

## Capturing P

$$\text{Tape}_a(\mathbf{x}, \mathbf{y}) \Leftrightarrow$$

$$(\mathbf{x} = \mathbf{1} \wedge \text{Init}_a(\mathbf{y})) \vee$$

$$\exists t \exists \mathbf{h} \bigvee_q (\mathbf{x} = \mathbf{t} + 1 \wedge \text{State}_q(\mathbf{t}, \mathbf{h}) \wedge$$

$$[(\mathbf{h} = \mathbf{y} \wedge \bigvee_{\{b,d,q' \mid \Delta(q,b,q',a,d)\}} \text{Tape}_b(\mathbf{t}, \mathbf{y}) \vee$$

$$\mathbf{h} \neq \mathbf{y} \wedge \text{Tape}_a(\mathbf{t}, \mathbf{y})]);$$

where  $\text{Init}_a(\mathbf{y})$  is the formula that defines the positions in which the symbol  $a$  appears in the input.

## Capturing P

$$\text{State}_q(\mathbf{x}, \mathbf{y}) \Leftrightarrow$$

$$(\mathbf{x} = \mathbf{1} \wedge \mathbf{y} = \mathbf{1} \wedge q = q_0) \vee$$

$$\exists t \exists \mathbf{h} \bigvee_{\{a,b,q' \mid \Delta(q',a,q,b,R)\}} (\mathbf{x} = \mathbf{t} + 1 \wedge \text{State}_{q'}(\mathbf{t}, \mathbf{h}) \wedge$$

$$\text{Tape}_a(\mathbf{t}, \mathbf{h}) \wedge \mathbf{y} = \mathbf{h} + 1))$$

$$\bigvee_{\{a,b,q' \mid \Delta(q',a,q,b,L)\}} (\mathbf{x} = \mathbf{t} + 1 \wedge \text{State}'_{q'}(\mathbf{t}, \mathbf{h}) \wedge$$

$$\text{Tape}_a(\mathbf{t}, \mathbf{h}) \wedge \mathbf{h} = \mathbf{y} + 1)).$$



## Unordered Structures

In the absence of an *order relation*, there are properties in  $\mathbf{P}$  that are not definable in LFP.

There is no sentence of LFP which defines the structures with an *even* number of elements.

## Evenness

Let  $\mathcal{E}$  be the collection of all structures in the empty signature.

In order to prove that *evenness* is not defined by any LFP sentence, we show the following.

### Lemma

For every LFP formula  $\phi$  there is a first order formula  $\psi$ , such that for all structures  $\mathbb{A}$  in  $\mathcal{E}$ ,  $\mathbb{A} \models (\phi \leftrightarrow \psi)$ .

## Unordered Structures

Let  $\psi(\mathbf{x}, \mathbf{y})$  be a first order formula.

$\text{lfp}_{R, \mathbf{x}} \psi$  defines the relation

$$F_{\psi, \mathbf{b}}^{\infty} = \bigcup_{i \in \mathbb{N}} F_{\psi, \mathbf{b}}^i$$

for a fixed interpretation of the variables  $\mathbf{y}$  by the tuple of parameters  $\mathbf{b}$ .

For each  $i$ , there is a first order formula  $\psi^i$  such that on any structure  $\mathbb{A}$ ,

$$F_{\psi, \mathbf{b}}^i = \{\mathbf{a} \mid \mathbb{A} \models \psi^i[\mathbf{a}, \mathbf{b}]\}.$$

## Defining the Stages

These formulas are obtained by *induction*.

$\psi^1$  is obtained from  $\psi$  by replacing all occurrences of subformulas of the form  $R(\mathbf{t})$  by  $t \neq t$ .

$\psi^{i+1}$  is obtained by replacing in  $\psi$ , all subformulas of the form  $R(\mathbf{t})$  by  $\psi^i(\mathbf{t}, \mathbf{y})$

Let  $\mathbf{b}$  be an  $l$ -tuple, and  $\mathbf{a}$  and  $\mathbf{c}$  two  $k$ -tuples in a structure  $\mathbb{A}$  such that

there is an automorphism  $\iota$  of  $\mathbb{A}$  (i.e. an *isomorphism* from  $\mathbb{A}$  to itself) such that

- $\iota(\mathbf{b}) = \mathbf{b}$
- $\iota(\mathbf{a}) = \mathbf{c}$

Then,

$$\mathbf{a} \in F_{\psi, \mathbf{b}}^i \quad \text{if, and only if,} \quad \mathbf{c} \in F_{\psi, \mathbf{b}}^i.$$

## Bounding the Induction

This defines an *equivalence relation*  $\mathbf{a} \sim_{\mathbf{b}} \mathbf{c}$ .

If there are  $p$  distinct equivalence classes, then

$$F_{\psi, \mathbf{b}}^{\infty} = F_{\psi, \mathbf{b}}^p$$

In  $\mathcal{E}$  there is a uniform bound  $p$ , that does not depend on the size of the structure.

## Reading List for this Part

1. Libkin. Chapter 10.
2. Grädel et al. Section 3.3.

## Topics in Logic and Complexity Part 11

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## Complexity of First-Order Logic

The problem of deciding whether  $\mathbb{A} \models \phi$  for first-order  $\phi$  is in time  $O(ln^m)$  and  $O(m \log n)$  space.

where  $n$  is the size of  $\mathbb{A}$ ,  $l$  is the length of  $\phi$  and  $m$  is the quantifier rank of  $\phi$ .

We have seen that the problem is PSPACE-complete, even for fixed  $\mathbb{A}$ .

For each fixed  $\phi$ , the problem is in L.

## Is FO contained in an initial segment of P?

Is there a fixed  $c$  such that for every first-order  $\phi$ ,  $\text{Mod}(\phi)$  is decidable in time  $O(n^c)$ ?

If  $P = PSPACE$ , then the answer is yes, as the satisfaction relation is then itself decidable in time  $O(n^c)$ .

Thus, though we expect the answer is no, this would be difficult to prove.

A more uniform version of the question is:

Is there a constant  $c$  and a computable function  $f$  so that the satisfaction relation for first-order logic is decidable in time  $O(f(l)n^c)$ ?

In this case we say that the satisfaction problem is *fixed-parameter tractable* (FPT) with the formula length as parameter.

## Parameterized Problems

Some problems are given a graph  $G$  and a positive integer  $k$

**Independent Set:** does  $G$  contain  $k$  vertices that are pairwise distinct and non-adjacent?

**Dominating Set:** does  $G$  contain  $k$  vertices such that every vertex is among them or adjacent to one of them?

**Vertex Cover:** does  $G$  contain  $k$  vertices such that every edge is incident on one of them?

For each fixed value of  $k$ , there is a first-order sentence  $\phi_k$  such that  $G \models \phi_k$  if, and only if,  $G$  contains an independent set of  $k$  vertices.

Similarly for dominating set and vertex cover.

## Parameterized Complexity

FPT—the class of problems of input size  $n$  and *parameter*  $l$  which can be solved in time  $O(f(l)n^c)$  for some computable function  $f$  and constant  $c$ .

There is a hierarchy of *intractable* classes.

$$\text{FPT} \subseteq W[1] \subseteq W[2] \subseteq \dots \subseteq \text{AW}[*]$$

Vertex Cover is FPT.

Independent Set is  $W[1]$ -complete.

Dominating Set is  $W[2]$ -complete.

## Parameterized Complexity of First-Order Satisfaction

Writing  $\Pi_t$  for those formulas which, in prenex normal form have  $t$  alternating blocks of quantifiers starting with a universal block:

The satisfaction problem restricted to  $\Pi_t$  formulas (parameterized by the length of the formula) is hard for the class  $W[t]$ .

The satisfaction relation for first-order logic ( $\mathbb{A} \models \phi$ ), parameterized by the length of  $\phi$  is  $AW[\star]$ -complete.

Thus, if the satisfaction problem for first-order logic were  $FPT$ , this would collapse the edifice of parameterized complexity theory.

## Restricted Classes

One way to get a handle on the complexity of first-order satisfaction is to consider restricted classes of structures.

Given: a first-order formula  $\phi$  and a structure  $\mathbb{A} \in \mathcal{C}$   
Decide: if  $\mathbb{A} \models \phi$

For many interesting classes  $\mathcal{C}$ , this problem has been shown to be  $FPT$ , even for formulas of  $MSO$ .

We say that satisfaction of  $FO$  (or  $MSO$ ) is *fixed-parameter tractable on  $\mathcal{C}$* .

## Words as Relational Structures

For an alphabet  $\Sigma = \{a_1, \dots, a_s\}$  let

$$\sigma_\Sigma = (\langle, P_{a_1}, \dots, P_{a_s})$$

where

$\langle$  is binary; and  $P_{a_1}, \dots, P_{a_s}$  are unary.

With each  $w \in \Sigma^*$  we associate the canonical structure

$$S_w = (\{1, \dots, n\}, \langle, P_{a_1}, \dots, P_{a_s})$$

where

- $n$  is the length of  $w$
- $\langle$  is the natural linear order on  $\{1, \dots, n\}$ .
- $i \in P_a$  if, and only if, the  $i$ th symbol in  $w$  is  $a$ .

## Languages Defined by Formulas

The formula  $\phi$  in the signature  $\sigma_\Sigma$  defines:

$$\{w \mid S_w \models \phi\}.$$

The class of structures isomorphic to word models is given by:

$$lo(\langle) \wedge \forall x \bigvee_{a \in A} P_a(x) \wedge \forall x \bigwedge_{a, b \in A, a \neq b} (P_a(x) \rightarrow \neg P_b(x)),$$

where

$lo(\langle)$  is the formula that states that  $\langle$  is a linear order

## Examples

The set of strings of length 3 or more:

$$\exists x \exists y \exists z (x \neq y \wedge y \neq z \wedge z \neq x).$$

The set of strings which begin with an  $a$ :

$$\exists x (P_a(x) \wedge \forall y y \geq x)$$

The set of strings of even length:

$$\begin{aligned} \exists X \forall x (\forall y \quad y \leq x \rightarrow X(x) \wedge \\ \forall x \forall y \quad (x < y \wedge \forall z (z \leq x \vee y \leq z)) \\ \rightarrow (X(x) \leftrightarrow \neg X(y)) \wedge \\ \forall x (\forall y \quad x \leq y) \rightarrow \neg X(x). \end{aligned}$$

## Examples

$(ab)^*$ :

$$\begin{aligned} \forall x (\forall y \quad y \leq x \rightarrow P_a(x) \wedge \\ \forall x \forall y \quad (x < y \wedge \forall z (z \leq x \vee y \leq z)) \\ \rightarrow (P_a(x) \leftrightarrow P_b(y)) \wedge \\ \forall x (\forall y \quad x \leq y) \rightarrow P_b(x). \end{aligned}$$

## MSO on Words

### Theorem (Büchi-Elgot-Trakhtenbrot)

A language  $L$  is defined by a sentence of MSO if, and only if,  $L$  is regular.

Recall that a language  $L$  is *regular* if:

- it is the set of words matching a *regular expression*; or equivalently
- it is the set of words accepted by some *nondeterministic finite automaton*; or equivalently
- it is the set of words accepted by some *deterministic finite automaton*.

## Myhill-Nerode Theorem

Let  $\sim$  be an equivalence relation on  $\Sigma^*$ .

We say  $\sim$  is *right invariant* if, for all  $u, v \in \Sigma^*$ ,

if  $u \sim v$ , then for all  $w \in \Sigma^*$ ,  $uw \sim vw$ .

### Theorem (Myhill-Nerode)

The following are equivalent for any language  $L \subseteq \Sigma^*$ :

- $L$  is regular;
- $L$  is the union of equivalence classes of a right invariant equivalence relation of finite index on  $\Sigma^*$ .

## MSO Equivalence

We write  $\mathbb{A} \equiv_m^{\text{MSO}} \mathbb{B}$  to denote that, for all MSO sentences  $\phi$  with  $\text{qr}(\phi) \leq m$ ,

$$\mathbb{A} \models \phi \text{ if, and only if, } \mathbb{B} \models \phi.$$

We count both first and second order quantifiers towards the rank.

The relation  $\equiv_m^{\text{MSO}}$  has finite index for every  $m$ .

For any  $m$ , there are up to logical equivalence, only finitely many formulas with quantifier rank at most  $m$ , with at most  $k$  free variables.

## Invariance

Suppose  $u_1, u_2, v_1, v_2$  are words over an alphabet  $\Sigma$  such that

$$u_1 \equiv_m^{\text{MSO}} u_2 \quad \text{and} \quad v_1 \equiv_m^{\text{MSO}} v_2$$

then  $u_1 \cdot v_1 \equiv_m^{\text{MSO}} u_2 \cdot v_2$ .

*Duplicator* has a winning strategy on the game played on the pair of words  $u_1 \cdot v_1, u_2 \cdot v_2$  that is obtained as a composition of its strategies in the games on  $u_1, u_2$  and  $v_1, v_2$ .

It follows that  $\equiv_m^{\text{MSO}}$  is *right invariant*.

For any MSO sentence  $\phi$ , the language defined by  $\phi$  is the union of equivalence classes of  $\equiv_m^{\text{MSO}}$  where  $m$  is the quantifier rank of  $\phi$ .

## Regular Expressions to MSO

For the converse, we translate a regular expression  $r$  to an MSO sentence  $\phi_r$ .

$$r = \emptyset: \phi_r = \exists x(x \neq x).$$

$$r = \varepsilon: \phi_r = \neg \exists x(x = x).$$

$$r = a: \phi_r = \exists x \forall y(y = x \wedge P_a(x)).$$

$$r = s + t: \phi_r = \phi_s \vee \phi_t.$$

$$r = st: \phi_r = \exists x(\phi_s^{<x} \wedge \phi_t^{\geq x}),$$

where  $\phi_s^{<x}$  and  $\phi_t^{\geq x}$  are obtained from  $\phi_s$  and  $\phi_t$  by relativising the first order quantifiers.

That is, every subformula of  $\phi_s$  of the form  $\exists y \psi$  is replaced by  $\exists y(y < x \wedge \psi^{<x})$ ,

and similarly every subformula  $\exists y \psi$  of  $\phi_t$  by  $\exists y(y \geq x \wedge \psi^{\geq x})$

## Kleene Star

$r = s^*$ :

$$\begin{aligned} \phi_r = & \phi_\varepsilon \vee \\ & \exists X \forall x(X(x) \wedge \forall y(y < x \rightarrow \neg X(y)) \rightarrow \phi_s^{<x}) \wedge \\ & \forall x(X(x) \wedge \forall y(y \geq x \rightarrow \neg X(y)) \rightarrow \phi_s^{\geq x}) \wedge \\ & \forall x \forall y (X < y \wedge X(x) \wedge X(y) \wedge \\ & \quad \forall z(x < z \wedge z < y \rightarrow \neg X(z)) \\ & \rightarrow \phi_s^{\geq x, <y}), \end{aligned}$$

where  $\phi_s^{\geq x, <y}$  is obtained from  $\phi_s$  by relativising all first order quantifiers simultaneously with  $< y$  and  $\geq x$ .

## First-Order Languages

The class of *star-free* regular expressions is defined by:

- the strings  $\emptyset$  and  $\varepsilon$  are star-free regular expressions;
- for any element  $a \in A$ , the string  $a$  is a star-free regular expression;
- if  $r$  and  $s$  are star-free regular expressions, then so are  $(rs)$ ,  $(r + s)$  and  $(\bar{r})$ .

A language is defined by a first order sentence *if, and only if*, it is denoted by a star-free regular expression.

## Applications

A class of linear orders is definable by a sentence of **MSO** if, and only if, its set of cardinalities is *eventually periodic*.

*Some results on graphs:*

The class of balanced bipartite graphs is not definable in **MSO**.

The class of Hamiltonian graphs is not definable by a sentence of **MSO**.

## Reading List for this Handout

1. Libkin. Sections 7.4 and 7.5
2. Ebbinghaus, Flum Chapter 6

## Topics in Logic and Complexity Part 12

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MPhil Advanced Computer Science, Lent 2013

## MSO is FPT on Words

There is a computable function  $f$  such that the problem of deciding, given a word  $w$  and an MSO sentence  $\phi$  whether,

$$S_w \models \phi$$

can be decided in time  $O(f(l)n)$  where  $l$  is the length of  $\phi$  and  $n$  is the length of  $w$ .

The algorithm proceeds by constructing, from  $\phi$  an *automaton*  $\mathcal{A}_\phi$  such that the language recognized by  $\mathcal{A}_\phi$  is

$$\{w \mid S_w \models \phi\}$$

then running  $\mathcal{A}_\phi$  on  $w$ .

## The automaton $\mathcal{A}_\phi$

The states of  $\mathcal{A}_\phi$  are the equivalence classes of  $\equiv_m^{\text{MSO}}$  where  $m$  is the quantifier rank of  $\phi$ .

We write  $\text{Type}_m^{\text{MSO}}(\mathbb{A})$  for the set of all formulas  $\phi$  with  $\text{qr}(\phi) \leq m$  such that  $\mathbb{A} \models \phi$ .

$\mathbb{A} \equiv_m^{\text{MSO}} \mathbb{B}$  is equivalent to

$$\text{Type}_m^{\text{MSO}}(\mathbb{A}) = \text{Type}_m^{\text{MSO}}(\mathbb{B})$$

There is a single formula  $\theta_{\mathbb{A}}$  that characterizes  $\text{Type}_m^{\text{MSO}}(\mathbb{A})$ .

It turns out that we can compute  $\theta_{S_{w \cdot a}}$  from  $\theta_{S_w}$ .

## Trees

An (undirected) *forest* is an *acyclic* graph and a *tree* is a connected forest.

We next aim to show that there is an algorithm that decides, given a tree  $T$  and an MSO sentence  $\phi$  whether

$$T \models \phi$$

and runs in time  $O(f(l)n)$  where  $l$  is the length of  $\phi$  and  $n$  is the size of  $T$ .

## Rooted Directed Trees

A *rooted, directed tree*  $(T, a)$  is a directed graph with a distinguished vertex  $a$  such that for every vertex  $v$  there is a *unique* directed path from  $a$  to  $v$ .

We will actually see that MSO satisfaction is FPT for rooted, directed trees.

The result for undirected trees follows, as any undirected tree can be turned into a rooted directed one by choosing any vertex as a root and directing edges away from it.



## Sums of Rooted Trees

Given rooted, directed trees  $(T, a)$  and  $(S, b)$  we define the sum

$$(T, a) \oplus (S, b)$$

to be the rooted directed tree which is obtained by taking the *disjoint union* of the two trees while *identifying* the roots.

That is,

- the set of vertices of  $(T, a) \oplus (S, b)$  is  $V(T) \uplus V(S) \setminus \{b\}$ .
- the set of edges is  $E(T) \cup E(S) \cup \{(a, v) \mid (b, v) \in E(S)\}$ .

## Congruence

If  $(T_1, a_1) \equiv_m^{\text{MSO}} (T_2, a_2)$  and  $(S_1, b_1) \equiv_m^{\text{MSO}} (S_2, b_2)$ , then

$$(T_1, a_1) \oplus (S_1, b_1) \equiv_m^{\text{MSO}} (T_2, a_2) \oplus (S_2, b_2).$$

This can be proved by an application of Ehrenfeucht games.

Moreover (though we skip the proof),  $\text{Type}_m^{\text{MSO}}((T, a) \oplus (S, b))$  can be computed from  $\text{Type}_m^{\text{MSO}}((T, a))$  and  $\text{Type}_m^{\text{MSO}}((S, b))$ .

## Add Root

For any rooted, directed tree  $(T, a)$  define  $r(T, a)$  to be rooted directed tree obtained by adding to  $(T, a)$  a new vertex, which is the root and whose only child is  $a$ .

That is,

- the vertices of  $r(T, a)$  are  $V(T) \cup \{a'\}$  where  $a'$  is not in  $V(T)$ ;
- the root of  $r(T, a)$  is  $a'$ ; and
- the edges of  $r(T, a)$  are  $E(T) \cup \{(a', a)\}$ .

Again,  $\text{Type}_m^{\text{MSO}}(r(T, a))$  can be computed from  $\text{Type}_m^{\text{MSO}}(T, a)$ .

## MSO satisfaction is FPT on Trees

Any *rooted, directed tree*  $(T, a)$  can be obtained from *singleton trees* by a sequence of applications of  $\oplus$  and  $r$ .

The length of the sequence is linear in the size of  $T$ .

We can compute  $\text{Type}_m^{\text{MSO}}(T, a)$  in linear time.

## The Method of Decompositions

Suppose  $\mathcal{C}$  is a class of graphs such that there is a finite class  $\mathcal{B}$  and a finite collection  $\text{Op}$  of operations such that:

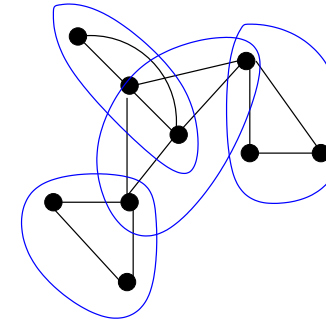
- $\mathcal{C}$  is contained in the closure of  $\mathcal{B}$  under the operations in  $\text{Op}$ ;
- there is a polynomial-time algorithm which computes, for any  $G \in \mathcal{C}$ , an  $\text{Op}$ -decomposition of  $G$  over  $\mathcal{B}$ ; and
- for each  $m$ , the equivalence class  $\equiv_m^{\text{MSO}}$  is an *effective* congruence with respect to to all operations  $o \in \text{Op}$  (i.e., the  $\equiv_m^{\text{MSO}}$ -type of  $o(G_1, \dots, G_s)$  can be computed from the  $\equiv_m^{\text{MSO}}$ -types of  $G_1, \dots, G_s$ ).

Then, **MSO** satisfaction is fixed-parameter tractable on  $\mathcal{C}$ .

## Treewidth

The *treewidth* of an undirected graph is a measure of how tree-like the graph is.

A graph has treewidth  $k$  if it can be covered by subgraphs of at most  $k + 1$  nodes in a tree-like fashion.



This gives a *tree decomposition* of the graph.

## Treewidth

Treewidth is a measure of how *tree-like* a graph is.

For a graph  $G = (V, E)$ , a *tree decomposition* of  $G$  is a relation  $D \subset V \times T$  with a tree  $T$  such that:

- for each  $v \in V$ , the set  $\{t \mid (v, t) \in D\}$  forms a connected subtree of  $T$ ; and
- for each edge  $(u, v) \in E$ , there is a  $t \in T$  such that  $(u, t), (v, t) \in D$ .

The *treewidth* of  $G$  is the least  $k$  such that there is a tree  $T$  and a tree decomposition  $D \subset V \times T$  such that for each  $t \in T$ ,

$$|\{v \in V \mid (v, t) \in D\}| \leq k + 1.$$

## Dynamic Programming

It has long been known that graphs of small treewidth admit efficient *dynamic programming* algorithms for intractable problems.

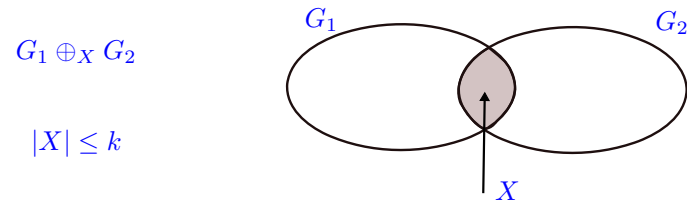
In general, these algorithms proceed bottom-up along a tree decomposition of  $G$ .

At any stage, a small set of vertices form the “*interface*” to the rest of the graph.

This allows a recursive decomposition of the problem.

## Treewidth

Looking at the decomposition *bottom-up*, a graph of treewidth  $k$  is obtained from graphs with at most  $k + 1$  nodes through a finite sequence of applications of the operation of taking *sums over sets* of at most  $k$  elements.



We let  $\mathcal{T}_k$  denote the class of graphs  $G$  such that  $\text{tw}(G) \leq k$ .

## Treewidth

More formally,

Consider graphs with up to  $k + 1$  distinguished vertices  $C = \{c_0, \dots, c_k\}$ .

Define a *merge* operation  $(G \oplus_C H)$  that forms the union of  $G$  and  $H$  *disjointly apart from*  $C$ .

Also define  $\text{erase}_i(G)$  that erases the name  $c_i$ .

Then a graph  $G$  is in  $\mathcal{T}_k$  if it can be formed from graphs with at most  $k + 1$  vertices through a sequence of such operations.

## Congruence

- Any  $G \in \mathcal{T}_k$  is obtained from  $\mathcal{B}_k$  by finitely many applications of the operations  $\text{erase}_i$  and  $\oplus_C$ .

- If  $G_1, \rho_1 \equiv_m^{\text{MSO}} G_2, \rho_2$ , then

$$\text{erase}_i(G_1, \rho_1) \equiv_m^{\text{MSO}} \text{erase}_i(G_2, \rho_2)$$

- If  $G_1, \rho_1 \equiv_m^{\text{MSO}} G_2, \rho_2$ , and  $H_1, \sigma_1 \equiv_m^{\text{MSO}} H_2, \sigma_2$  then

$$(G_1, \rho_1) \oplus_C (H_1, \sigma_1) \equiv_m^{\text{MSO}} (G_2, \rho_2) \oplus_C (H_2, \sigma_2)$$

*Note:* a special case of this is that  $\equiv_m^{\text{MSO}}$  is a congruence for *disjoint union* of graphs.

## Courcelle's Theorem

### Theorem (Courcelle)

For any MSO sentence  $\phi$  and any  $k$  there is a linear time algorithm that decides, given  $G \in \mathcal{T}_k$  whether  $G \models \phi$ .

Given  $G \in \mathcal{T}_k$  and  $\phi$ , compute:

- from  $G$  a labelled tree  $T$ ; and
- from  $\phi$  a bottom-up tree automaton  $\mathcal{A}$

such that  $\mathcal{A}$  accepts  $T$  if, and only if,  $G \models \phi$ .

## Bounded Degree Graphs

In a graph  $G = (V, E)$  the *degree* of a vertex  $v \in V$  is the number of neighbours of  $v$ , i.e.

$$|\{u \in V \mid (u, v) \in E\}|.$$

We write  $\delta(G)$  for the *smallest* degree of any vertex in  $G$ .

We write  $\Delta(G)$  for the *largest* degree of any vertex in  $G$ .

$\mathcal{D}_k$ —the class of graphs  $G$  with  $\Delta(G) \leq k$ .

## Bounded Degree Graphs

### Theorem (Seese)

For every sentence  $\phi$  of FO and every  $k$  there is a linear time algorithm which, given a graph  $G \in \mathcal{D}_k$  determines whether  $G \models \phi$ .

A proof is based on *locality* of first-order logic.

To be precise a strengthening of *Hanf's theorem*.

**Note:** this is not true for MSO unless  $P = NP$ .

Construct, for any graph  $G$ , a graph  $G'$  such that  $\Delta(G') \leq 5$  and  $G'$  is 3-colourable iff  $G$  is, and the map  $G \mapsto G'$  is polynomial-time computable.

## Hanf Types

For an element  $a$  in a structure  $\mathbb{A}$ , define

$N_r^{\mathbb{A}}(a)$ —the substructure of  $\mathbb{A}$  generated by the elements whose distance from  $a$  (in  $G\mathbb{A}$ ) is at most  $r$ .

We say  $\mathbb{A}$  and  $\mathbb{B}$  are *Hanf equivalent* with radius  $r$  and threshold  $q$  ( $\mathbb{A} \simeq_{r,q} \mathbb{B}$ ) if, for every  $a \in A$  the two sets

$$\{a' \in a \mid N_r^{\mathbb{A}}(a) \cong N_r^{\mathbb{A}}(a')\} \quad \text{and} \quad \{b \in B \mid N_r^{\mathbb{A}}(a) \cong N_r^{\mathbb{B}}(b)\}$$

either have the same size or both have size greater than  $q$ ;

and, similarly for every  $b \in B$ .

## Hanf Locality Theorem

### Theorem (Hanf)

For every vocabulary  $\sigma$  and every  $m$  there are  $r \leq 3^m$  and  $q \leq m$  such that for any  $\sigma$ -structures  $\mathbb{A}$  and  $\mathbb{B}$ : if  $\mathbb{A} \simeq_{r,q} \mathbb{B}$  then  $\mathbb{A} \equiv_m \mathbb{B}$ .

In other words, if  $r \geq 3^m$ , the equivalence relation  $\simeq_{r,m}$  is a refinement of  $\equiv_m$ .

For  $\mathbb{A} \in \mathcal{D}_k$ :

$N_r^{\mathbb{A}}(a)$  has at most  $k^r + 1$  elements

each  $\simeq_{r,m}$  has finite index.

Each  $\simeq_{r,m}$ -class  $t$  can be characterised by a finite table,  $I_t$ , giving isomorphism types of neighbourhoods and numbers of their occurrences up to threshold  $m$ .

## Satisfaction on $\mathcal{D}_k$

For a sentence  $\phi$  of FO, we can compute a set of tables  $\{I_1, \dots, I_s\}$  describing  $\simeq_{r,m}$ -classes consistent with it.

This computation is independent of any structure  $\mathbb{A}$ .

Given a structure  $\mathbb{A} \in \mathcal{D}_k$ ,

for each  $a$ , determine the isomorphism type of  $N_r^{\mathbb{A}}(a)$

construct the table describing the  $\simeq_{r,m}$ -class of  $\mathbb{A}$ .

compare against  $\{I_1, \dots, I_s\}$  to determine whether  $\mathbb{A} \models \phi$ .

For fixed  $k, r, m$ , this requires time *linear* in the size of  $\mathbb{A}$ .

**Note:** satisfaction for FO is in  $O(f(l, k)n)$ .

## Reading List for this Handout

1. Libkin. Sections 7.6 and 7.7