Complexity Theory

Complexity Theory
Lecture 11

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http://www.cl.cam.ac.uk/teaching/1112/Complexity/

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Establishing Inclusions

To establish the known inclusions between the main complexity classes, we prove the following.

- SPACE $(f(n)) \subseteq NSPACE(f(n));$
- TIME $(f(n)) \subseteq NTIME(f(n))$;
- $\mathsf{NTIME}(f(n)) \subseteq \mathsf{SPACE}(f(n));$
- $\mathsf{NSPACE}(f(n)) \subseteq \mathsf{TIME}(k^{\log n + f(n)});$

The first two are straightforward from definitions.

The third is an easy simulation.

The last requires some more work.

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Inclusions

We have the following inclusions:

 $\mathsf{L} \subset \mathsf{NL} \subset \mathsf{P} \subset \mathsf{NP} \subset \mathsf{PSPACE} \subset \mathsf{NPSPACE} \subset \mathsf{EXP}$

where $\mathsf{EXP} = \bigcup_{k=1}^{\infty} \mathsf{TIME}(2^{n^k})$

Moreover,

 $L \subseteq NL \cap co-NL$

 $P \subseteq NP \cap co-NP$

 $\mathsf{PSPACE} \subset \mathsf{NPSPACE} \cap \mathsf{co-NPSPACE}$

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Reachability

Recall the Reachability problem: given a *directed* graph G = (V, E) and two nodes $a, b \in V$, determine whether there is a path from a to b in G.

A simple search algorithm solves it:

- 1. mark node a, leaving other nodes unmarked, and initialise set S to $\{a\}$;
- 2. while S is not empty, choose node i in S: remove i from S and for all j such that there is an edge (i, j) and j is unmarked, mark j and add j to S;
- 3. if b is marked, accept else reject.

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NL Reachability

We can construct an algorithm to show that the Reachability problem is in NL:

- 1. write the index of node a in the work space;
- 2. if i is the index currently written on the work space:
 - (a) if i = b then accept, else guess an index i (log n bits) and write it on the work space.
 - (b) if (i, j) is not an edge, reject, else replace i by j and return to (2).

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Configuration Graph

Define the *configuration graph* of M, x to be the graph whose nodes are the possible configurations, and there is an edge from i to j if, and only if, $i \to_M j$.

Then, M accepts x if, and only if, some accepting configuration is reachable from the starting configuration $(s, \triangleright, x, \triangleright, \varepsilon)$ in the configuration graph of M, x.

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We can use the $O(n^2)$ algorithm for Reachability to show that: $\mathsf{NSPACE}(f(n)) \subset \mathsf{TIME}(k^{\log n + f(n)})$

for some constant k.

Let M be a nondeterministic machine working in space bounds f(n).

For any input x of length n, there is a constant c (depending on the number of states and alphabet of M) such that the total number of possible configurations of M within space bounds f(n) is bounded by $n \cdot c^{f(n)}$.

Here, $c^{f(n)}$ represents the number of different possible contents of the work space, and n different head positions on the input.

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Using the $O(n^2)$ algorithm for Reachability, we get that M can be simulated by a deterministic machine operating in time

$$c'(nc^{f(n)})^2 \sim c'c^{2(\log n + f(n))} \sim k^{(\log n + f(n))}$$

In particular, this establishes that $NL \subseteq P$ and $NPSPACE \subseteq EXP$.

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Savitch's Theorem

Further simulation results for nondeterministic space are obtained by other algorithms for Reachability.

We can show that Reachability can be solved by a *deterministic* algorithm in $O((\log n)^2)$ space.

Consider the following recursive algorithm for determining whether there is a path from a to b of length at most n (for n a power of 2):

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Savitch's Theorem - 2

The space efficient algorithm for reachability used on the configuration graph of a nondeterministic machine shows:

$$\mathsf{NSPACE}(f(n)) \subseteq \mathsf{SPACE}(f(n)^2)$$

for $f(n) \ge \log n$.

This yields

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PSPACE = NPSPACE = co-NPSPACE.

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 $O((\log n)^2)$ space Reachability algorithm:

Path(a, b, i)

if i = 1 and $a \neq b$ and (a, b) is not an edge reject else if (a, b) is an edge or a = b accept else, for each node x, check:

- 1. is there a path a x of length i/2; and
- 2. is there a path x b of length i/2?

if such an x is found, then accept, else reject.

The maximum depth of recursion is $\log n$, and the number of bits of information kept at each stage is $3 \log n$.

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Complementation

A still more clever algorithm for Reachability has been used to show that nondeterministic space classes are closed under complementation:

If $f(n) \ge \log n$, then

NSPACE(f(n)) = co-NSPACE(f(n))

In particular

NL = co-NL

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