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UP

 $\{x \mid \exists y R(x, y)\}$ 

Where R is polynomial time computable, polynomially balanced, and for each x, there is at most one y such that R(x, y).

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Complexity Theory

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**One-Way Functions Imply**  $P \neq UP$ 

Suppose f is a *one-way function*.

Define the language  $L_f$  by

 $L_f = \{(x, y) \mid \exists z (z \le x \text{ and } f(z) = y)\}.$ 

We can show that  $L_f$  is in UP but not in P.

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Complexity Theory
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                          UP One-way Functions
    We have
                                  \mathsf{P} \subset \mathsf{U}\mathsf{P} \subset \mathsf{N}\mathsf{P}
    It seems unlikely that there are any NP-complete problems in UP.
    One-way functions exist if, and only if, P \neq UP.
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Complexity Theory
             P \neq UP Implies One-Way Functions Exist
    Suppose that L is a language that is in UP but not in P. Let U be
     an unambiguous machine that accepts L.
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Define the function  $f_U$  by

if x is a string that encodes an accepting computation of U, then  $f_U(x) = 1y$  where y is the input string accepted by this computation.

 $f_U(x) = 0x$  otherwise.

We can prove that  $f_U$  is a one-way function.

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## **Space Complexity**

We've already seen the definition SPACE(f): the languages accepted by a machine which uses O(f(n)) tape cells on inputs of length *n*. Counting only work space.

NSPACE(f) is the class of languages accepted by a *nondeterministic* Turing machine using at most O(f(n)) work space.

As we are only counting work space, it makes sense to consider bounding functions f that are less than linear.

## **Classes**

$$\begin{split} \mathsf{L} &= \mathsf{SPACE}(\log n) \\ \mathsf{NL} &= \mathsf{NSPACE}(\log n) \\ \mathsf{PSPACE} &= \bigcup_{k=1}^{\infty} \mathsf{SPACE}(n^k) \\ & \text{The class of languages decidable in polynomial space.} \\ \mathsf{NPSPACE} &= \bigcup_{k=1}^{\infty} \mathsf{NSPACE}(n^k) \end{split}$$

Also, define

co-NL – the languages whose complements are in NL.

co-NPSPACE – the languages whose complements are in NPSPACE.

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Complexity Theory
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                                            Inclusions
                                                                                                                                                                   Establishing Inclusions
      We have the following inclusions:
                                                                                                                                        To establish the known inclusions between the main complexity
                                                                                                                                        classes, we prove the following.
                  \mathsf{L} \subset \mathsf{N}\mathsf{L} \subset \mathsf{P} \subset \mathsf{N}\mathsf{P} \subseteq \mathsf{PSPACE} \subseteq \mathsf{NPSPACE} \subseteq \mathsf{EXP}
                                                                                                                                          • SPACE(f(n)) \subset NSPACE(f(n));
                                                                                                                                          • TIME(f(n)) \subseteq \mathsf{NTIME}(f(n));
     where \mathsf{EXP} = \bigcup_{k=1}^{\infty} \mathsf{TIME}(2^{n^k})
                                                                                                                                          • NTIME(f(n)) \subseteq SPACE(f(n));
      Moreover,
                                                                                                                                          • NSPACE(f(n)) \subseteq \mathsf{TIME}(k^{\log n + f(n)});
                                         L \subseteq NL \cap co-NL
                                         P \subseteq NP \cap co-NP
                                                                                                                                        The first two are straightforward from definitions.
                           \mathsf{PSPACE} \subseteq \mathsf{NPSPACE} \cap \mathsf{co-NPSPACE}
                                                                                                                                        The third is an easy simulation.
                                                                                                                                        The last requires some more work.
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