From last lecture

C and C++ 6. Operators — Inheritance — Virtual	<pre>1 class Complex { 2 double re,im; 3 public: 4 Complex(double r=0.0L, double i=0.0L); 5 };</pre>
Stephen Clark	<pre>6 7 Complex::Complex(double r,double i) {</pre>
University of Cambridge on last year's notes (Andrew Moore) with thanks to Alastair R. Beresford and Bjarne Stroustrup)	<pre>8 re=r,im=i; 9 } 10 11 int main() {</pre>
Michaelmas Term 2011	<pre>12 Complex c(2.0), d(), e(1,5.0L); 13 return 0; 14 }</pre>

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Operators

(heavily based

- ► C++ allows the programmer to overload the built-in operators
- ► For example, a new test for equality:

```
1 bool operator==(Complex a, Complex b) {
2 return a.real()==b.real()
          && a.imag()==b.imag();
3
4 }
```

An operator can be defined or declared within the body of a class, and in this case one fewer argument is required; for example:

```
1 bool Complex::operator==(Complex b) {
2 return re==b.real() && im==b.imag();
3 }
```

Almost all operators can be overloaded

Streams

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- Overloaded operators also work with built-in types
- ▶ Overloading is used to define a C++ "printf"; for example:

```
1 #include <iostream>
2
3 int main() {
    const char* s = "char array";
4
5
     std::cout << s << std::endl;</pre>
    //Unexpected output; prints &s[0]
8
    std::cout.operator<<(s).operator<<(std::endl);</pre>
9
10
    //Expected output; prints s
11
    std::operator<<(std::cout,s);</pre>
12
    std::cout.operator<<(std::endl);</pre>
13
    return 0;
14
15 }
```

The 'this' pointer

- If an operator is defined in the body of a class, it may need to return a reference to the current object
 - ► The keyword this can be used

► For example:

```
1 Complex& Complex::operator+=(Complex b) {
2 re += b.real();
```

```
3 this->im += b.imag();
```

```
4 return *this;
```

```
5 }
```

Class instances as member variables

- A class can have an instance of another class as a member variable
- ▶ How can we pass arguments to the class constructor?
- New notation for a constructor:

```
1 class X {
2   Complex c;
3   Complex d;
4   X(double a, double b): c(a,b), d(b) {
5    ...
6   }
7 };
```

- ► This notation must be used to initialise const and reference members
- It can also be more efficient

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Temporary objects

- Temporary objects are often created during execution
- A temporary which is not bound to a reference or named object exists only during evaluation of a full expression
- Example: the string class has a function c_str() which returns a pointer to a C representation of a string:

```
1 string a("A "), b("string");
2 const char *s1 = a.c_str(); //Okay
3 const char *s2 = (a+b).c_str(); //Wrong
4 ...
5 //s still in scope here, but the temporary holding
6 //"a+b" has been deallocated
7 ...
8 string tmp = a+b;
9 const char *s3 = tmp.c_str(); //Okay
```

Friends

- A (non-member) friend function can access the private members of a class instance it befriends
- This can be done by placing the function declaration inside the class definition and prefixing it with the keyword friend; for example:

```
1 class Matrix {
2 ...
3 friend Vector operator*(const Matrix&, \
4 const Vector&);
5 ...
6 };
7 }
```

Inheritance

► C++ allows a class to inherit features of another:

```
1 class vehicle {
2 int wheels:
3 public:
4 vehicle(int w=4):wheels(w) {}
5 }:
6
7 class bicycle : public vehicle {
8 bool panniers;
9 public:
   bicycle(bool p):vehicle(2),panniers(p) {}
10
11 };
12
13 int main() {
   bicycle(false);
14
15 }
```

Example

```
1 #include <iostream>
2 #include "example13.hh"
3
4 void print_speed(vehicle &v, bicycle &b) {
    std::cout << v.maxSpeed() << " ";</pre>
5
    std::cout << b.maxSpeed() << std::endl;</pre>
6
7 }
8
9 int main() {
    bicycle b = bicycle(true);
10
    print_speed(b,b); //prints "60 12"
11
12 }
```

Derived member function call

Default derived member function call semantics differ from Java:

```
1 class vehicle {
2 int wheels;
3 public:
    vehicle(int w=4):wheels(w) {}
4
   int maxSpeed() {return 60;}
5
6 };
7
% class bicycle : public vehicle {
    int panniers;
9
10 public:
   bicycle(bool p=true):vehicle(2),panniers(p) {}
11
   int maxSpeed() {return panniers ? 12 : 15;}
12
13 };
```

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Virtual functions

- Non-virtual member functions are called depending on the static type of the variable, pointer or reference
- Since a derived class can be cast to a base class, this prevents a derived class from overloading a function
- To get polymorphic behaviour, declare the function virtual in the superclass:

```
1 class vehicle {
2    int wheels;
3    public:
4    vehicle(int w=4):wheels(w) {}
5    virtual int maxSpeed() {return 60;}
6 };
```

Virtual functions

Enabling virtual functions

In general, for a virtual function, selecting the right function has to be run-time decision; for example:

```
1 bicycle b(true);
2 vehicle v;
3 vehicle* pv;
4
5 user_input() ? pv = &b : pv = &v;
6
7 std::cout << pv->maxSpeed() << std::endl;
8 }
```

- To enable virtual functions, the compiler generates a virtual function table or vtable
- A vtable contains a pointer to the correct function for each object instance
- The vtable is an example of indirection
- The vtable introduces run-time overhead

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Abstract classes

- Sometimes a base class is an un-implementable concept
- In this case we can create an abstract class:

```
1 class shape {
2 public:
3 virtual void draw() = 0;
4 }
```

- It is not possible to instantiate an abstract class: shape s; //Wrong
- A derived class can provide an implementation for some (or all) the abstract functions
- ▶ A derived class with no abstract functions can be instantiated

Example

```
1 class shape {
2 public:
3 virtual void draw() = 0;
4 };
5
6 class circle : public shape {
7 public:
8 //...
9 void draw() { /* impl */ }
10 };
```

Multiple inheritance

It is possible to inherit from multiple base classes; for example:

1 class ShapelyVehicle: public vehicle, public shape {
2 ...
3 }

- Members from both base classes exist in the derived class
- ► If there is a name clash, explicit naming is required
- This is done by specifying the class name; for example: ShapelyVehicle sv; sv.vehicle::maxSpeed();

Multiple instances of a base class

▶ With multiple inheritance, we can build:

1 class A {}; 2 class B : public A {}; 3 class C : public A {}; 4 class D : public B, public C {};

- This means we have two instances of A even though we only have a single instance of D
- This is legal C++, but means all references to A must be stated explicitly:
 - 1 D d; 2 d.B::var=3; 3 d.C::var=4;

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Virtual base classes

- > Alternatively, we can have a single instance of the base class
- Such a "virtual" base class is shared amongst all those deriving from it
 - 1 class Vehicle {int VIN;};
 - 2 class Boat : public virtual Vehicle { ... };
 - 3 class Car : public virtual Vehicle { ... };
 - 4 class JamesBondCar : public Boat, public Car { ... };

Exercises

- 1. If a function f has a static instance of a class as a local variable, when might the class constructor be called?
- Write a class Matrix which allows a programmer to define two dimensional matrices. Overload the common operators (e.g. +, -, *, and /)
- 3. Write a class Vector which allows a programmer to define a vector of length two. Modify your Matrix and Vector classes so that they interoperate correctly (e.g. v2 = m*v1 should work as expected)
- 4. Why should destructors in an abstract class almost always be declared virtual?