

Further Generalizations

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Part 1

About These Slides

Copyright

These slides constitute the lecture notes for

- MACS L111 Advanced Data Flow Analysis course at Cambridge University, and
- CS 618 Program Analysis course at IIT Bombay.

They have been made available under GNU FDL v1.2 or later (purely for academic or research use) as teaching material accompanying the book:

- Uday Khedker, Amitabha Sanyal, and Bageshri Karkare. *Data Flow Analysis: Theory and Practice*. CRC Press (Taylor and Francis Group). 2009.

Apart from the above book, some slides are based on the material from the following books

- M. S. Hecht. *Flow Analysis of Computer Programs*. Elsevier North-Holland Inc. 1977.
- F. Nielson, H. R. Nielson, and C. Hankin. *Principles of Program Analysis*. Springer-Verlag. 1998.



Outline

- Partial Redundancy Elimination (previous lecture)
- Introduction to Constant Propagation (previous lecture)
- Theoretical Abstractions in Data Flow Analysis
 - ▶ The world of data flow values (previous lecture)
 - ▶ The world of functions and operations that compute data values (today)
 - ▶ Results of data flow analysis (today)
 - ▶ Algorithms for performing data flow analysis (today)
- Precise Modelling of General flows (today)
Example: Constant Propagation



Part 2

Flow Functions

Flow Functions: An Outline of Our Discussion

- Defining flow functions
- Properties of flow functions
(Some properties discussed in the context of solutions of data flow analysis)



The Set of Flow Functions

- F is the set of functions $f : L \mapsto L$ such that
 - ▶ F contains an identity function
To model “empty” statements, i.e. statements which do not influence the data flow information
 - ▶ F is closed under composition
Cumulative effect of statements should generate data flow information from the same set.
 - ▶ For every $x \in L$, there must be a finite set of flow functions $\{f_1, f_2, \dots, f_m\} \subseteq F$ such that

$$x = \prod_{1 \leq i \leq m} f_i(BI)$$

- Properties of f
 - ▶ Monotonicity and Distributivity
 - ▶ Separability



Flow Functions in Bit Vector Data Flow Frameworks

- Bit Vector Frameworks: Available Expressions Analysis, Reaching Definitions Analysis Live variable Analysis, Anticipable Expressions Analysis, Partial Redundancy Elimination etc.
 - ▶ All functions can be defined in terms of constant *Gen* and *Kill*

$$f(x) = Gen \cup (x - Kill)$$

- ▶ Lattices are powersets with partial orders as \subseteq or \supseteq relations
- ▶ Information is merged using \cap or \cup



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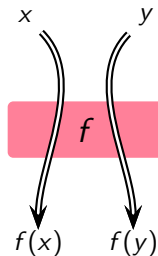
- ▶ Lattices are powersets with partial orders as \subseteq or \supseteq relations
- ▶ Information is merged using \cap or \cup
- Flow functions in Faint Variables Analysis, Pointer Analyses, Constant Propagation, Possibly Uninitialized Variables cannot be expressed using constant *Gen* and *Kill*.

Local context alone is not sufficient to describe the effect of statements fully.



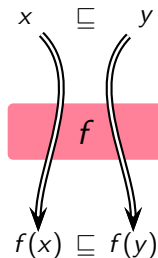
Monotonicity of Flow Functions

- Partial order is preserved: If x can be safely used in place of y then $f(x)$ can be safely used in place of $f(y)$



Monotonicity of Flow Functions

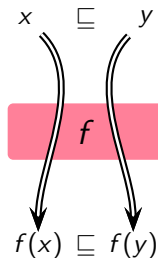
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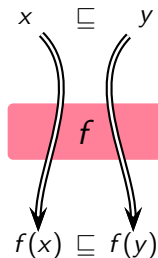
$$\forall x, y \in L, x \sqsubseteq y \Rightarrow f(x) \sqsubseteq f(y)$$



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- Alternative definition

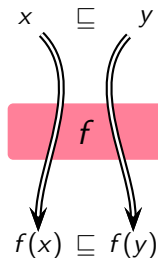
$$\forall x, y \in L, f(x \sqcap y) \sqsubseteq f(x) \sqcap f(y)$$



Monotonicity of Flow Functions

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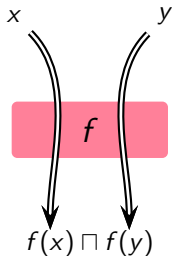
$$\forall x, y \in L, f(x \sqcap y) \sqsubseteq f(x) \sqcap f(y)$$

- Merging at intermediate points in shared segments of paths is safe (However, it may lead to imprecision).



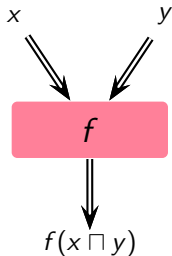
Distributivity of Flow Functions

- Merging distributes over function application



Distributivity of Flow Functions

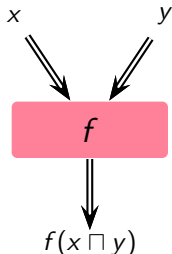
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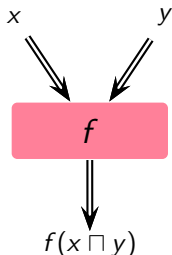
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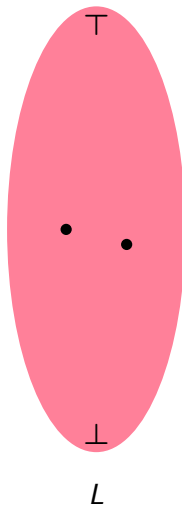
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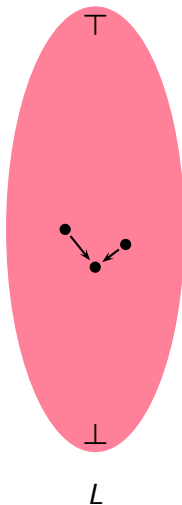
- Merging at intermediate points in shared segments of paths does not lead to imprecision.



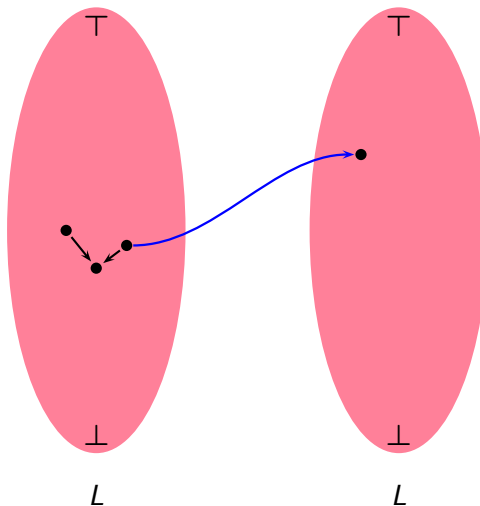
Monotonicity and Distributivity



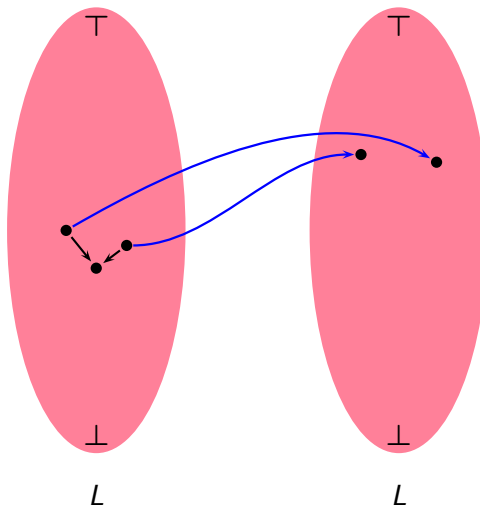
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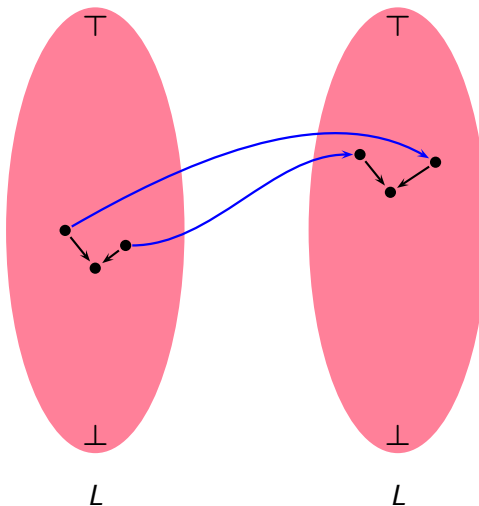
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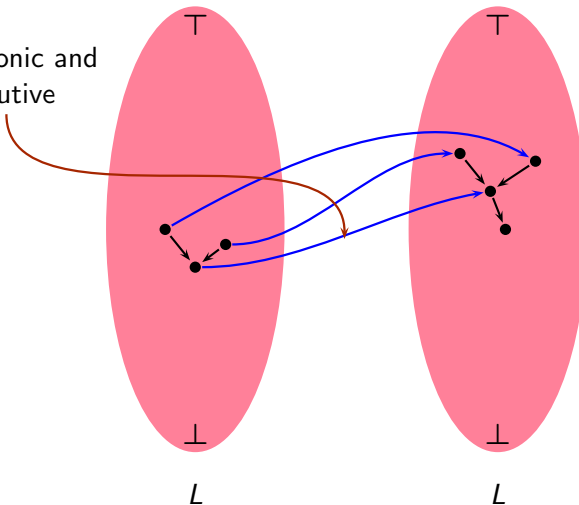


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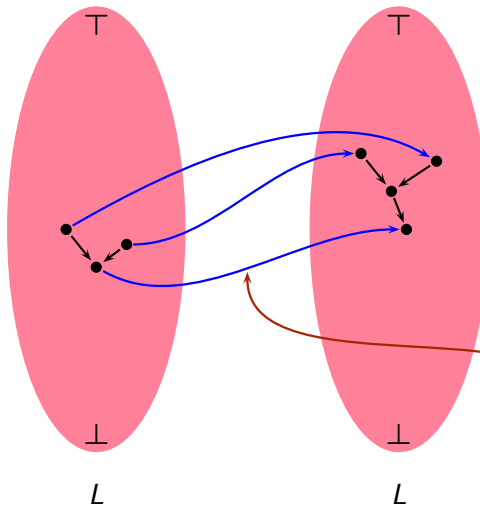


Monotonicity and Distributivity

Monotonic and
Distributive



Monotonicity and Distributivity



Monotonic but
not Distributive



Distributivity of Bit Vector Frameworks

$$f(x) = Gen \cup (x - Kill)$$

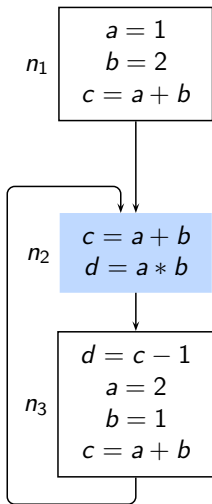
$$f(y) = Gen \cup (y - Kill)$$

$$\begin{aligned} f(x \cup y) &= Gen \cup ((x \cup y) - Kill) \\ &= Gen \cup ((x - Kill) \cup (y - Kill)) \\ &= (Gen \cup (x - Kill) \cup Gen \cup (y - Kill)) \\ &= f(x) \cup f(y) \end{aligned}$$

$$\begin{aligned} f(x \cap y) &= Gen \cup ((x \cap y) - Kill) \\ &= Gen \cup ((x - Kill) \cap (y - Kill)) \\ &= (Gen \cup (x - Kill) \cap Gen \cup (y - Kill)) \\ &= f(x) \cap f(y) \end{aligned}$$

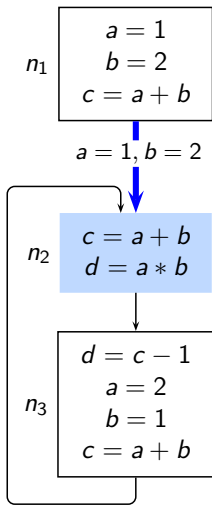


Non-Distributivity of Constant Propagation

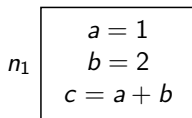


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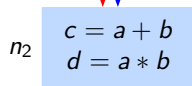
- $x = \langle 1, 2, 3, ? \rangle$ (Along $Out_{n_1} \rightarrow In_{n_2}$)



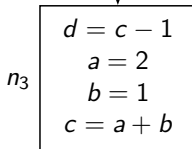
Non-Distributivity of Constant Propagation



$a = 1, b = 2$



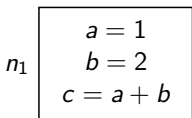
$a = 2, b = 1$



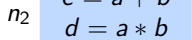
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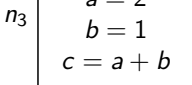
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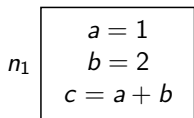


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- $y = \langle 2, 1, 3, 2 \rangle$ (Along $Out_{n_3} \rightarrow In_{n_2}$)
- Function application for block n_2 before merging

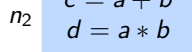
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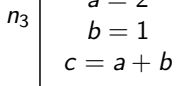
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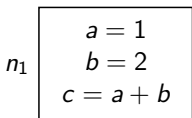
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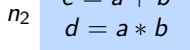
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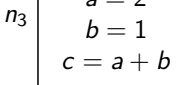
Non-Distributivity of Constant Propagation



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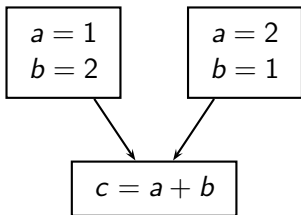
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- $f(x \sqcap y) \sqsubset f(x) \sqcap f(y)$

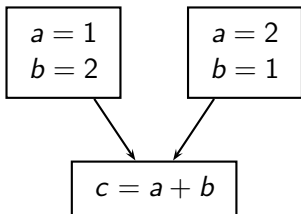


Why is Constant Propagation Non-Distributive?

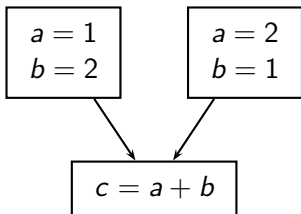


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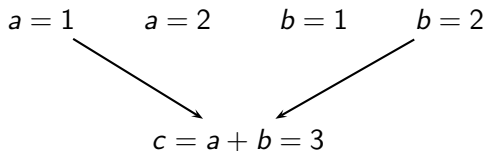
Possible combinations due to merging

 $a = 1$ $a = 2$ $b = 1$ $b = 2$ 

Why is Constant Propagation Non-Distributive?



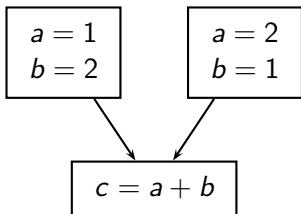
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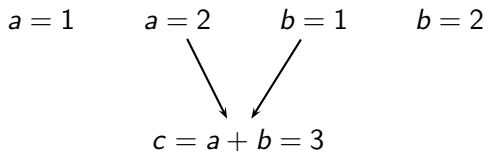
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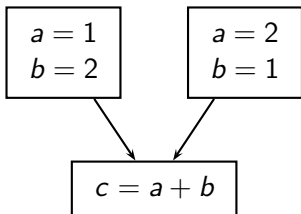
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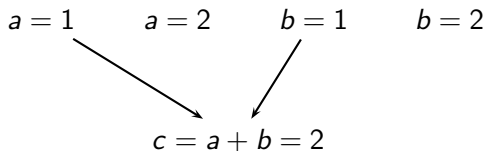
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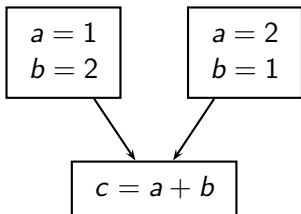
Possible combinations due to merging



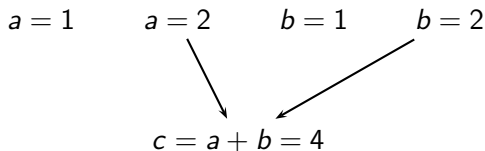
- Wrong combination.
- Mutually exclusive information.
- No execution path along which this information holds.



Why is Constant Propagation Non-Distributive?



Possible combinations due to merging



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Part 3

Solutions of Data Flow Analysis

Solutions of Data Flow Analysis: An Outline of Our Discussion

- MoP and MFP assignments and their relationship
- Existence of MoP assignment
 - ▶ Boundedness of flow functions
- Existence and Computability of MFP assignment
 - ▶ Flow functions Vs. function computed by data flow equations
- Safety of MFP solution



Solutions of Data Flow Analysis

- An assignment A associates data flow values with program points. $A \sqsubseteq B$ if for all program points p , $A(p) \sqsubseteq B(p)$
- Performing data flow analysis

Given

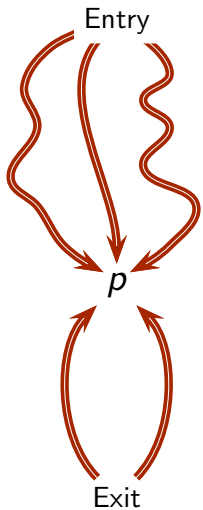
- ▶ A set of flow functions, a lattice, and merge operation
- ▶ A program flow graph with a mapping from nodes to flow functions

Find out

- ▶ An assignment A which is as exhaustive as possible and is safe



Meet Over Paths (MoP) Assignment



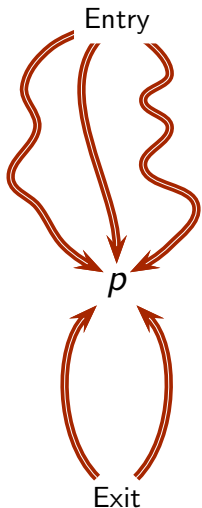
- The largest safe approximation of the information reaching a program point along all **information flow paths**.

$$MoP(p) = \prod_{\rho \in Paths(p)} f_{\rho}(BI)$$

- f_{ρ} represents the compositions of flow functions along ρ .
- BI refers to the relevant information from the calling context.
- All execution paths are considered potentially executable by ignoring the results of conditionals.



Meet Over Paths (MoP) Assignment



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- ▶ f_{ρ} represents the compositions of flow functions along ρ .
 - ▶ BI refers to the relevant information from the calling context.
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- Any $Info(p) \sqsubseteq MoP(p)$ is safe.



Maximum Fixed Point (MFP) Assignment

- Difficulties in computing MoP assignment



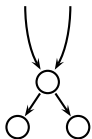
Maximum Fixed Point (MFP) Assignment

- Difficulties in computing MoP assignment
 - ▶ In the presence of cycles there are infinite paths
If all paths need to be traversed \Rightarrow Undecidability



Maximum Fixed Point (MFP) Assignment

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If all paths need to be traversed \Rightarrow **Undecidability**
 - ▶ Even if a program is acyclic, every conditional multiplies the number of paths by two
If all paths need to be traversed \Rightarrow **Intractability**



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- Why not merge information at intermediate points?
 - ▶ Merging is safe but may lead to imprecision.
 - ▶ Computes fixed point solutions of data flow equations.



Maximum Fixed Point (MFP) Assignment

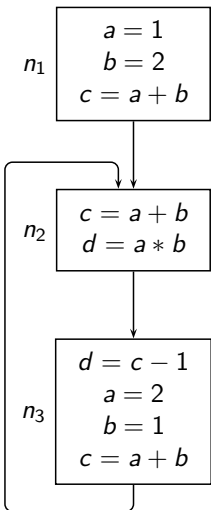
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Path based specification

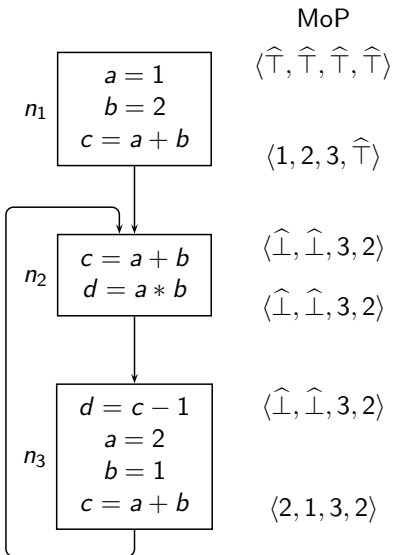
Edge based specifications



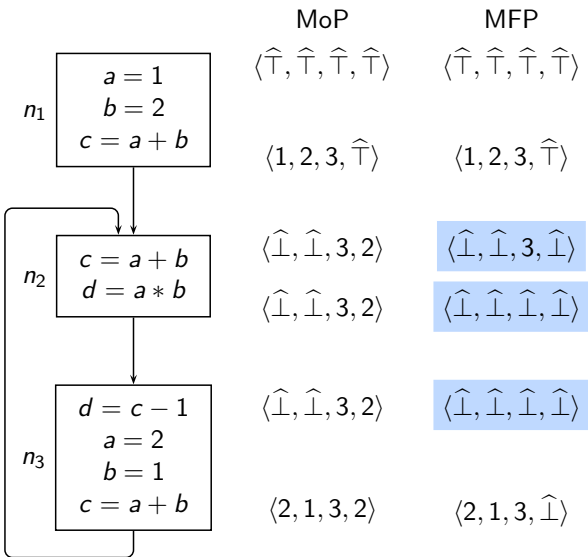
Assignments for Constant Propagation Example



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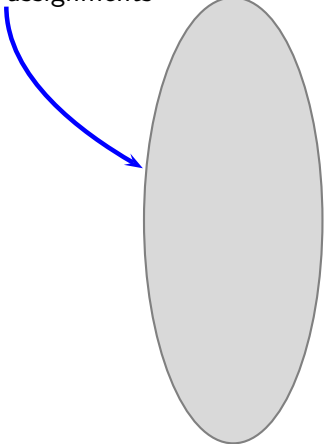


Assignments for Constant Propagation Example

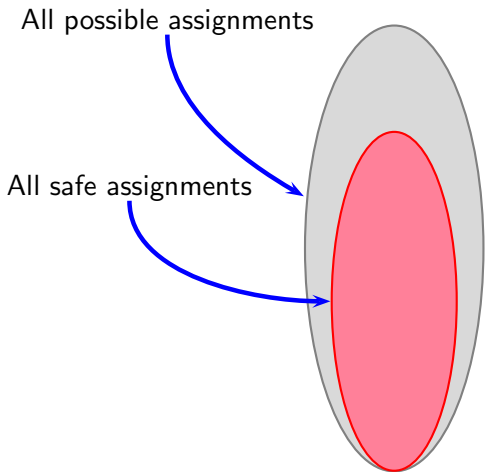


Possible Assignments as Solutions of Data Flow Analyses

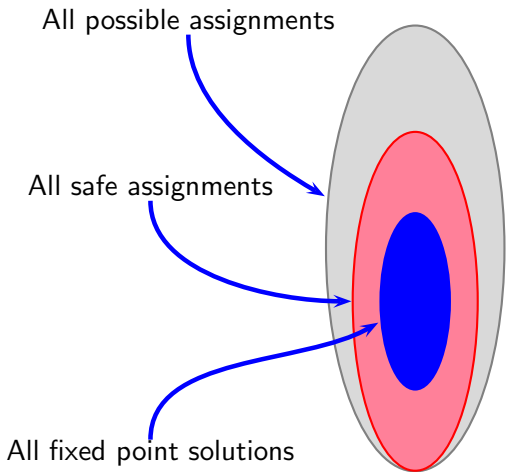
All possible assignments



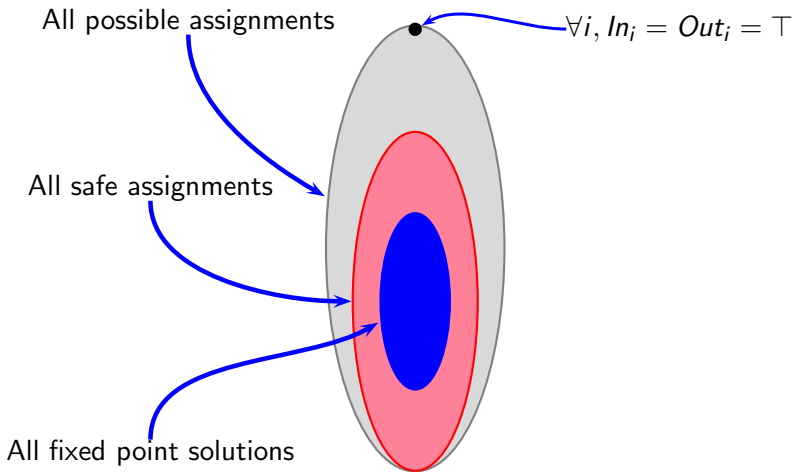
Possible Assignments as Solutions of Data Flow Analyses



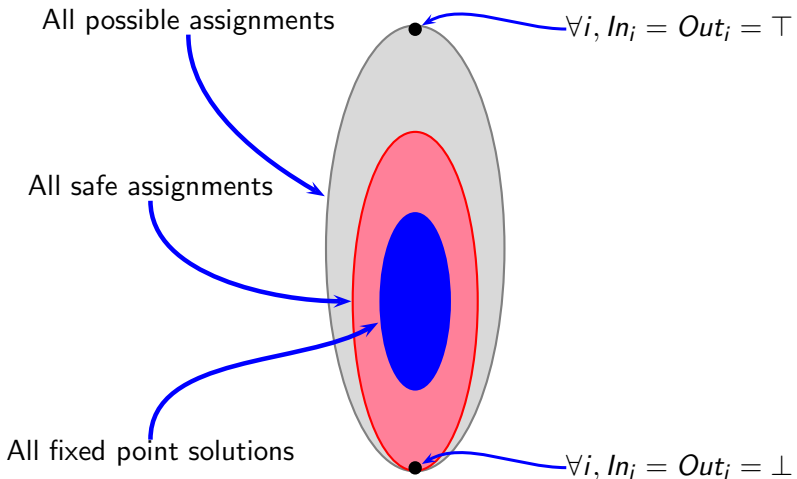
Possible Assignments as Solutions of Data Flow Analyses



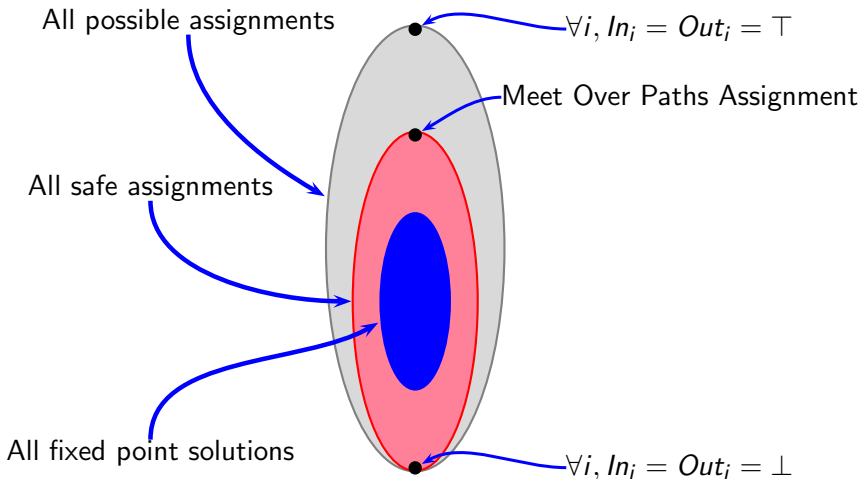
Possible Assignments as Solutions of Data Flow Analyses



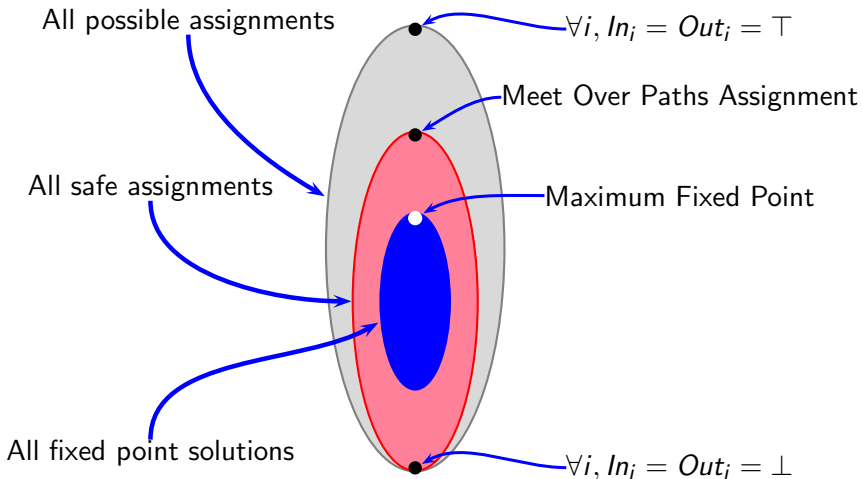
Possible Assignments as Solutions of Data Flow Analyses



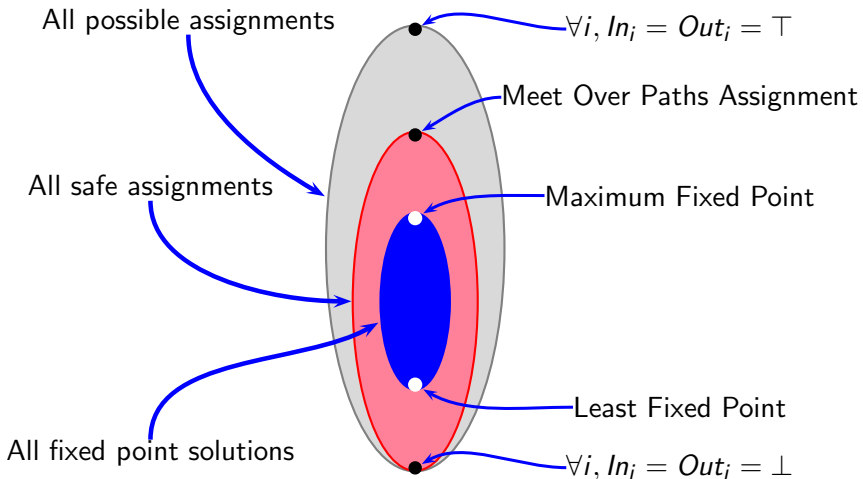
Possible Assignments as Solutions of Data Flow Analyses



Possible Assignments as Solutions of Data Flow Analyses

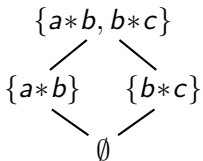


Possible Assignments as Solutions of Data Flow Analyses



Available Expr. Analysis Framework with Two Expressions

Lattice

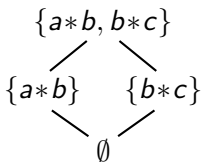


| Constant Functions | | Dependent Functions | |
|--------------------|----------------|---------------------|------------------|
| f | $f(x)$ | f | $f(x)$ |
| f_{\top} | $\{a*b, b*c\}$ | f_{id} | x |
| f_{\perp} | \emptyset | f_c | $x \cup \{a*b\}$ |
| f_a | $\{a*b\}$ | f_d | $x \cup \{b*c\}$ |
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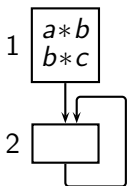
Available Expr. Analysis Framework with Two Expressions

Lattice



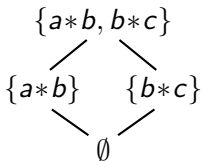
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Program



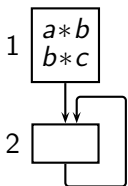
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Lattice



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Program

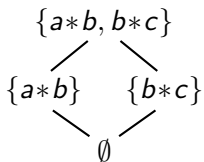


| Flow Functions | |
|----------------|---------------|
| Node | Flow Function |
| 1 | f_{\top} |
| 2 | f_{id} |



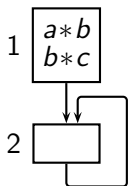
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Lattice



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Program



| Flow Functions | |
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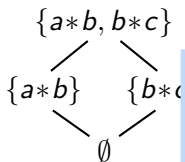
Some Possible Assignments

| | A_1 | A_2 | A_3 | A_4 | A_5 | A_6 |
|---------|-------|-------|-------|-------|-------|-------|
| In_1 | 00 | 00 | 00 | 00 | 00 | 00 |
| Out_1 | 11 | 00 | 11 | 11 | 11 | 11 |
| In_2 | 11 | 00 | 00 | 10 | 01 | 01 |
| Out_2 | 11 | 00 | 00 | 10 | 01 | 10 |



Available Expr. Analysis Framework with Two Expressions

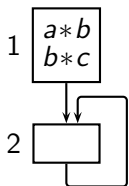
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| f_f | \emptyset | f_f | $x - \{b*c\}$ |

- Maximum fixed point assignment
- Initialization for round robin iterative method: 11

Program



| Flow Functions | |
|----------------|---------------|
| Node | Flow Function |
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| 2 | f_{id} |

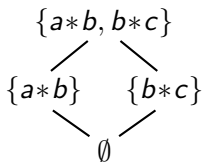
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Available Expr. Analysis Framework with Two Expressions

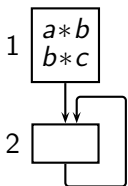
Lattice



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| | | f_e | $x - \{a*b\}$ |
| | | f_f | $x - \{b*c\}$ |

- Not a fixed point assignment

Program



| Flow Functions | |
|----------------|---------------|
| Node | Flow Function |
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| 2 | f_{id} |

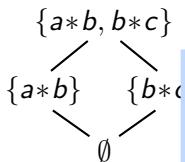
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|---------|-------|-------|-------|-------|-------|-------|
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Available Expr. Analysis Framework with Two Expressions

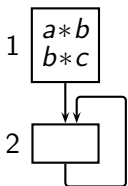
Lattice



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| f_f | \emptyset | f_f | $x - \{b*c\}$ |

- Minimum fixed point assignment
- Initialization for round robin iterative method: 00

Program



| Flow Functions | |
|----------------|---------------|
| Node | Flow Function |
| 1 | f_{\top} |
| 2 | f_{id} |

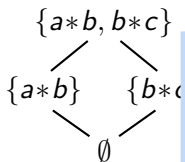
Some Possible Assignments

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Available Expr. Analysis Framework with Two Expressions

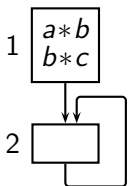
Lattice



| Constant Functions | | Dependent Functions | |
|--------------------|----------------|---------------------|------------------|
| f | $f(x)$ | f | $f(x)$ |
| f_{\top} | $\{a*b, b*c\}$ | f_{id} | x |
| c | | | $x \cup \{a*b\}$ |
| d | | | $x \cup \{b*c\}$ |
| e | | | $x - \{a*b\}$ |
| f | | | $x - \{b*c\}$ |

- Fixed point assignment which is neither maximum nor minimum
- Initialization for round robin iterative method: 10

Program



| Flow Functions | |
|----------------|---------------|
| Node | Flow Function |
| 1 | f_{\top} |
| 2 | f_{id} |

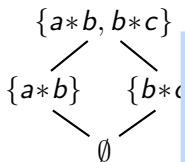
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| In_1 | 00 | 00 | 00 | 00 | 00 | 00 |
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| Out_2 | 11 | 00 | 00 | 10 | 01 | 10 |



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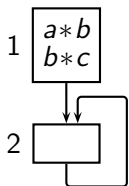
Lattice



| Constant Functions | | Dependent Functions | |
|--------------------|------------------|---------------------|------------------|
| f | $f(x)$ | f | $f(x)$ |
| f_{\top} | $\{a*b, b*c\}$ | f_{id} | x |
| c | $x \cup \{a*b\}$ | d | $x \cup \{b*c\}$ |
| e | $x - \{a*b\}$ | f | $x - \{b*c\}$ |

- Fixed point assignment which is neither maximum nor minimum
- Initialization for round robin iterative method: 01

Program



| Flow Functions | |
|----------------|---------------|
| Node | Flow Function |
| 1 | f_{\top} |
| 2 | f_{id} |

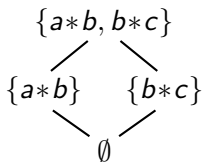
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Available Expr. Analysis Framework with Two Expressions

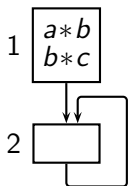
Lattice



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| | | f_d | $x \cup \{b*c\}$ |
| | | f_e | $x - \{a*b\}$ |
| | | f_f | $x - \{b*c\}$ |

- Not a fixed point assignment

Program



| Flow Functions | |
|----------------|---------------|
| Node | Flow Function |
| 1 | f_{\top} |
| 2 | f_{id} |

Some Possible Assignments

| | A_1 | A_2 | A_3 | A_4 | A_5 | A_6 |
|---------|-------|-------|-------|-------|-------|-------|
| In_1 | 00 | 00 | 00 | 00 | 00 | 00 |
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Part 4

Performing Data Flow Analysis

Performing Data Flow Analysis

- Algorithms for computing MFP solution
- Complexity of data flow analysis
- Factor affecting the complexity of data flow analysis



Iterative Methods of Performing Data Flow Analysis

Successive recomputation after conservative initialization (\top)

- *Round Robin*. Repeated traversals over nodes in a fixed order

Termination : After values stabilise

- + Simplest to understand and implement
- May perform unnecessary computations



Iterative Methods of Performing Data Flow Analysis

Successive recomputation after conservative initialization (\top)

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Our examples use this method.



Iterative Methods of Performing Data Flow Analysis

Successive recomputation after conservative initialization (\top)

- *Round Robin*. Repeated traversals over nodes in a fixed order

Termination : After values stabilise

- + Simplest to understand and implement
- May perform unnecessary computations

Our examples use this method.

- *Work List*. Dynamic list of nodes which need recomputation

Termination : When the list becomes empty

- + Demand driven. Avoid unnecessary computations.
- Overheads of maintaining work list.



Elimination Methods of Performing Data Flow Analysis

Delayed computations of dependent data flow values of dependent nodes.

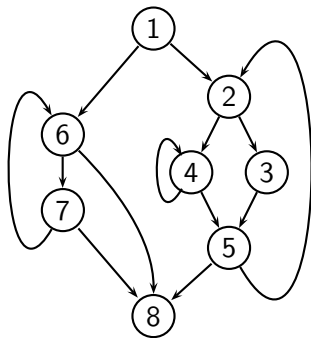
Find suitable single-entry regions.

- *Interval Based Analysis*. Uses graph partitioning.
- T_1, T_2 *Based Analysis*. Uses graph parsing.



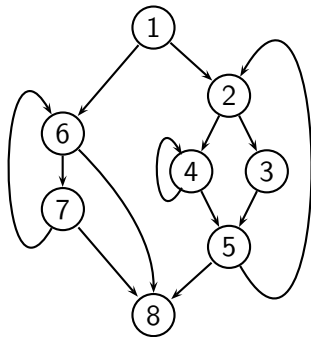
Classification of Edges in a Graph

Graph G

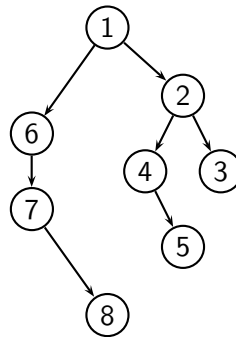


Classification of Edges in a Graph

Graph G

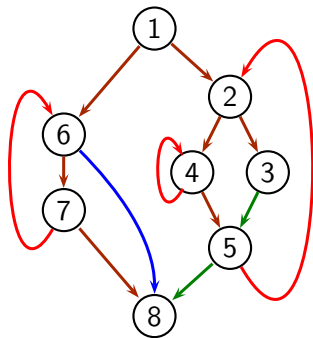


A depth first spanning tree of G



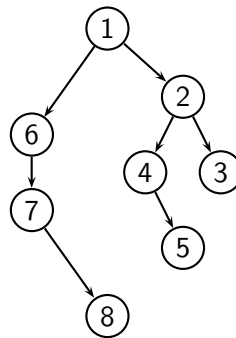
Classification of Edges in a Graph

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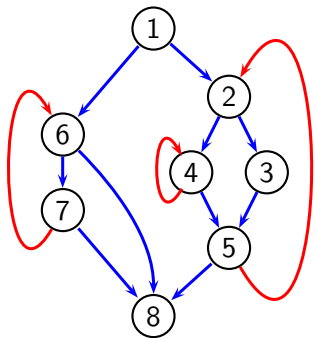
- Back edges →
- Forward edges →
- Tree edges →
- Cross edges →

A depth first spanning tree of G



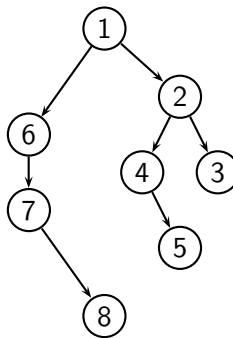
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 Forward edges →

A depth first spanning tree of G

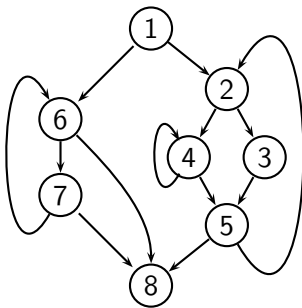
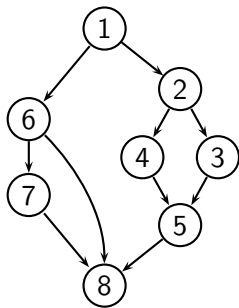


For data flow analysis, we club *tree*, *forward*, and *cross* edges into *forward* edges. Thus we have just forward or back edges in a control flow graph



Reverse Post Order Traversal

- A reverse post order (rpo) is a topological sort of the graph obtained after removing back edges

Graph G  G' obtained after removing back edges of G 

- Some possible RPOs for G are: $(1, 2, 3, 4, 5, 6, 7, 8)$, $(1, 6, 7, 2, 3, 4, 5, 8)$, $(1, 6, 2, 7, 4, 3, 5, 8)$, and $(1, 2, 6, 7, 3, 4, 5, 8)$



Round Robin Iterative Algorithm

```
1   $ln_0 = B_I$ 
2  for all  $j \neq 0$  do
3       $ln_j = \top$ 
4       $change = true$ 
5      while  $change$  do
6          {  $change = false$ 
7              for  $j = 1$  to  $N - 1$  do
8                  {  $temp = \prod_{p \in pred(j)} f_p(ln_p)$ 
9                      if  $temp \neq ln_j$  then
10                         {  $ln_j = temp$ 
11                              $change = true$ 
12                         }
13                     }
14 }
```



Round Robin Iterative Algorithm

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```

- Computation of Out_j has been left implicit
- Works fine for unidirectional frameworks



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- \top is the identity of \sqcap (line 3)
- Reverse postorder (rpo) traversal for efficiency (line 7)



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14 }

```

- Computation of Out_j has been left implicit
Works fine for unidirectional frameworks
- \top is the identity of \sqcap (line 3)
- Reverse postorder (rpo) traversal for efficiency (line 7)
- rpo traversal AND no loops \Rightarrow no need of initialization



Complexity of Round Robin Iterative Algorithm

- Unidirectional bit vector frameworks
 - ▶ Construct a spanning tree T of G to identify postorder traversal
 - ▶ Traverse G in reverse postorder for forward problems and
Traverse G in postorder for backward problems
 - ▶ Depth $d(G, T)$: Maximum number of back edges in any acyclic path

| Task | Number of iterations |
|--|----------------------|
| First computation of In and Out | 1 |
| Convergence (until $change$ remains true) | $d(G, T)$ |
| Verifying convergence ($change$ becomes false) | 1 |



Complexity of Round Robin Iterative Algorithm

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| First computation of In and Out | 1 |
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| Verifying convergence ($change$ becomes false) | 1 |

- What about bidirectional bit vector frameworks?



Complexity of Round Robin Iterative Algorithm

- Unidirectional bit vector frameworks
 - ▶ Construct a spanning tree T of G to identify postorder traversal
 - ▶ Traverse G in reverse postorder for forward problems and
Traverse G in postorder for backward problems
 - ▶ Depth $d(G, T)$: Maximum number of back edges in any acyclic path

| Task | Number of iterations |
|--|----------------------|
| First computation of In and Out | 1 |
| Convergence (until $change$ remains true) | $d(G, T)$ |
| Verifying convergence ($change$ becomes false) | 1 |

- What about bidirectional bit vector frameworks?
- What about other frameworks?



Example C Program with $d(G,T) = 2$

```
1 void fun(int m, int n)
2 {
3     int i,j,a,b,c;
4     c=a+b;
5     i=0;
6     while(i<m)
7     {
8         j=0;
9         while(j<n)
10        {
11            a=i+j;
12            j=j+1;
13        }
14        i=i+1;
15    }
16 }
```

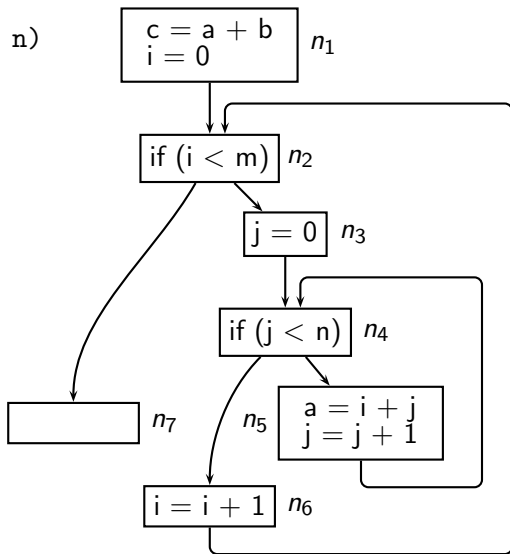


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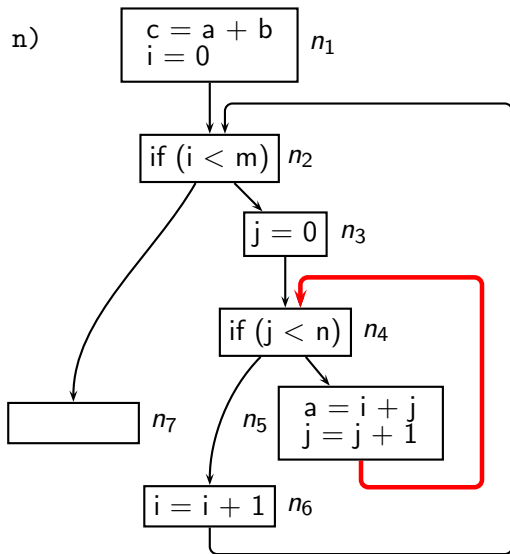


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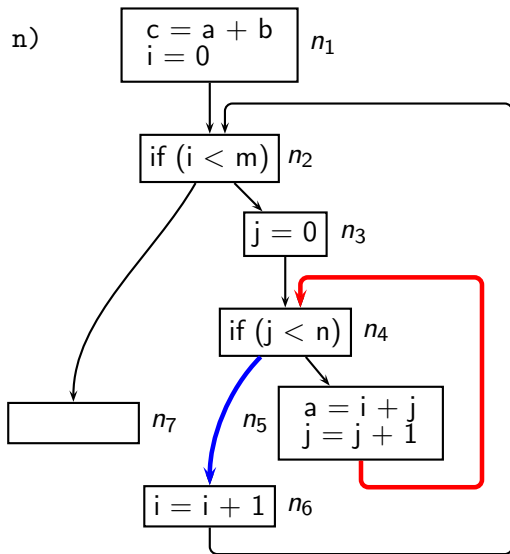


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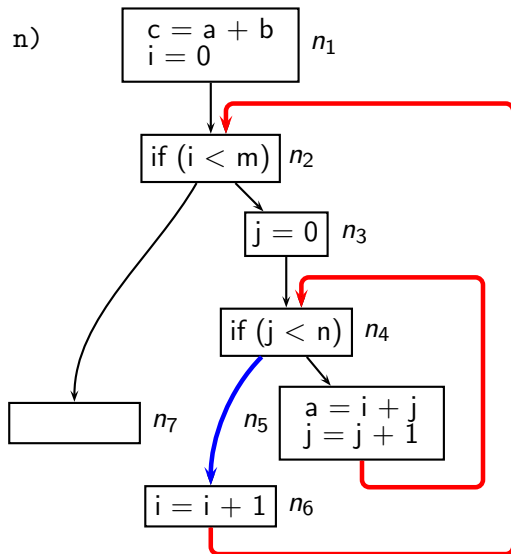


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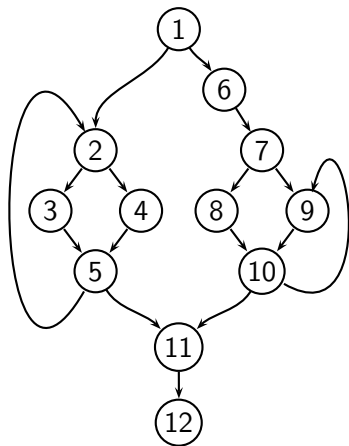


3 + 1 iterations for available expressions analysis



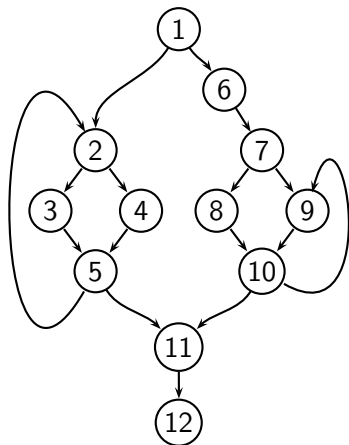
Complexity of Bidirectional Bit Vector Frameworks

Example: Consider the following CFG for PRE



Complexity of Bidirectional Bit Vector Frameworks

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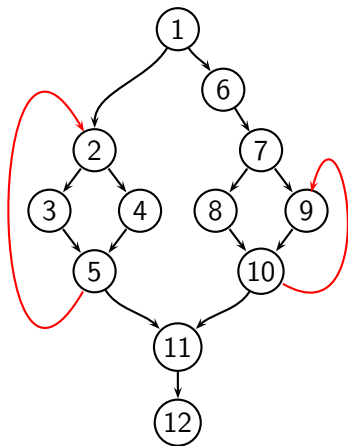


- Node numbers are in reverse post order



Complexity of Bidirectional Bit Vector Frameworks

Example: Consider the following CFG for PRE

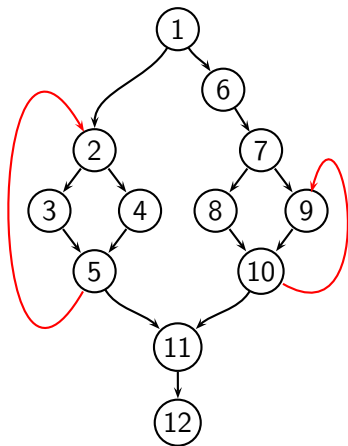


- Node numbers are in reverse post order
- Back edges in the graph are $n_5 \rightarrow n_2$ and $n_{10} \rightarrow n_9$.



Complexity of Bidirectional Bit Vector Frameworks

Example: Consider the following CFG for PRE

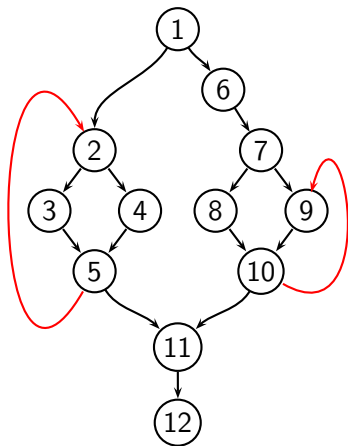


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- $d(G, T) = 1$



Complexity of Bidirectional Bit Vector Frameworks

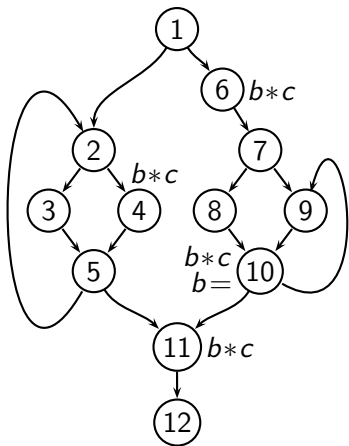
Example: Consider the following CFG for PRE



- Node numbers are in reverse post order
- Back edges in the graph are $n_5 \rightarrow n_2$ and $n_{10} \rightarrow n_9$.
- $d(G, T) = 1$
- Actual iterations : 5



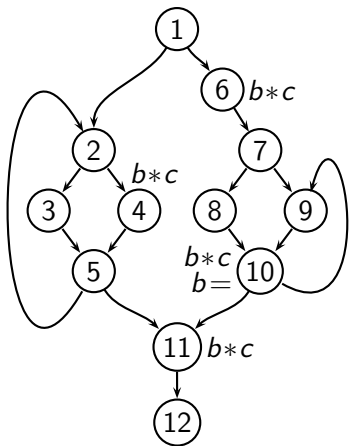
Complexity of Bidirectional Bit Vector Frameworks



| | Pairs of <i>Out, In</i> Values | | | | | | | |
|----|--------------------------------|--------------------------|-----|-----|-----|-----|----------------------------------|--|
| | Initia- lization | Changes in Iterations | | | | | Final values & transformation | |
| | | #1 | #2 | #3 | #4 | #5 | | |
| | 0,1 | 0,1 | 0,1 | 0,1 | 0,1 | 0,1 | 0,1 | |
| 12 | 0,1 | | | | | | | |
| 11 | 1,1 | | | | | | | |
| 10 | 1,1 | | | | | | | |
| 9 | 1,1 | | | | | | | |
| 8 | 1,1 | | | | | | | |
| 7 | 1,1 | | | | | | | |
| 6 | 1,1 | | | | | | | |
| 5 | 1,1 | | | | | | | |
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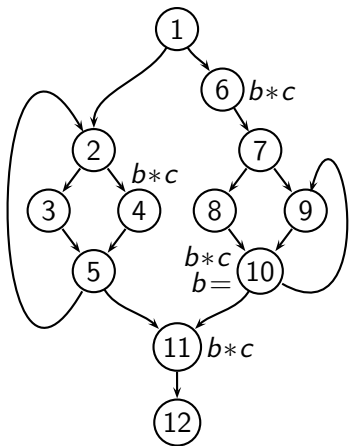
Complexity of Bidirectional Bit Vector Frameworks



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| 1 | 1,1 | 0,0 | | | | | |



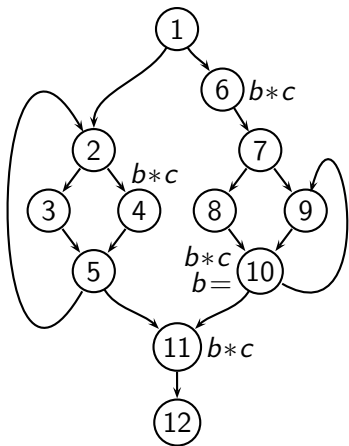
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| 2 | 1,1 | | 1,0 | | | | | |
| 1 | 1,1 | 0,0 | | | | | | |



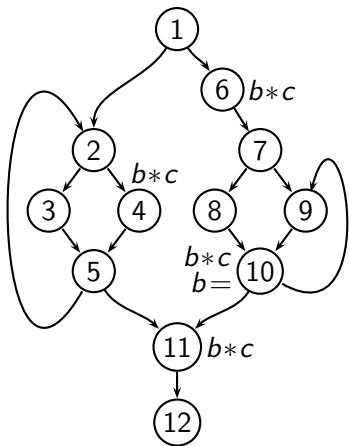
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| 5 | 1,1 | | | 0,0 | | | | |
| 4 | 1,1 | | | 0,1 | | | | |
| 3 | 1,1 | | | 0,0 | | | | |
| 2 | 1,1 | | 1,0 | 0,0 | | | | |
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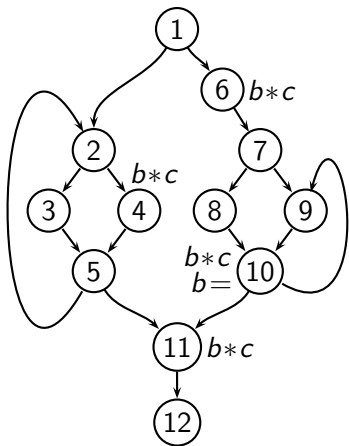
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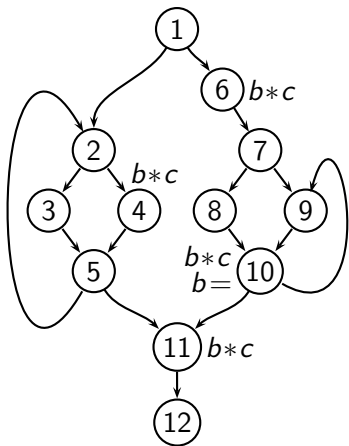
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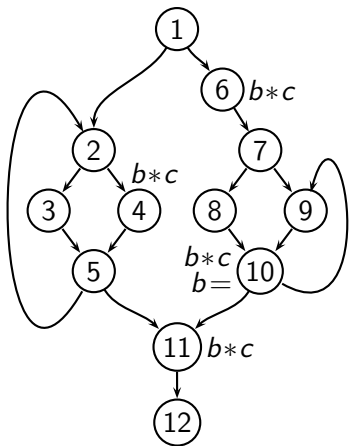
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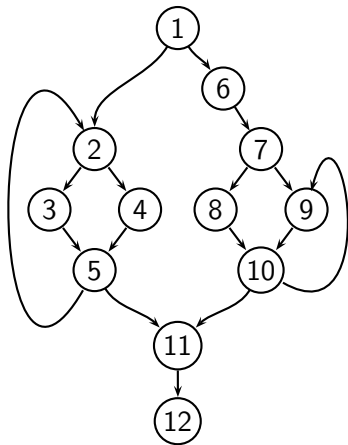
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| 12 | 0,1 | 0,0 | | | | | 0,0 | |
| 11 | 1,1 | 0,1 | | | 0,0 | | 0,0 | |
| 10 | 1,1 | | | | 0,1 | | 0,1 | Delete |
| 9 | 1,1 | | | | 1,0 | | 1,0 | Insert |
| 8 | 1,1 | | | | | 1,0 | 1,0 | Insert |
| 7 | 1,1 | | | | 0,0 | | 0,0 | |
| 6 | 1,1 | 1,0 | | | 0,0 | | 0,0 | |
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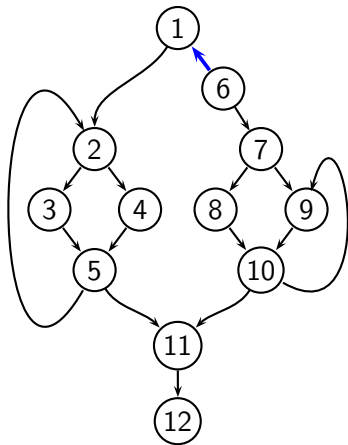
An Example of Information Flow in Our PRE Analysis



- $Pavln_6$ becomes 0 in the first iteration
- This causes many all other values to become 0
- Here we see a particular sequence of changes
- Incorporating the effect of this sequence of changes requires 5 iterations
- Number of iterations is not related to depth (which is 1 for this graph)



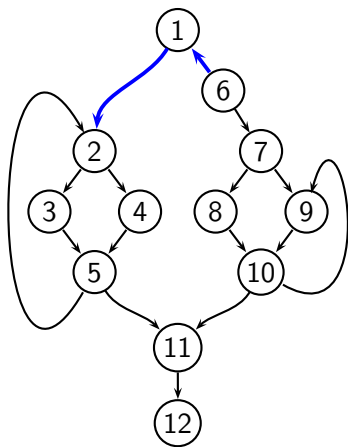
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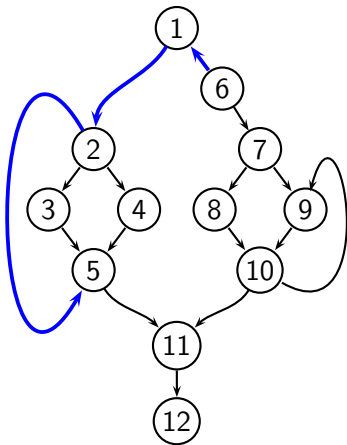
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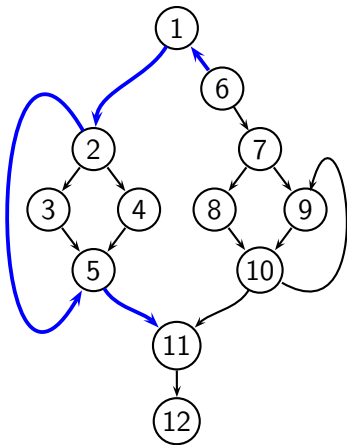
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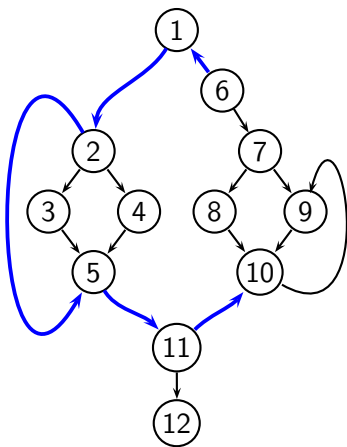
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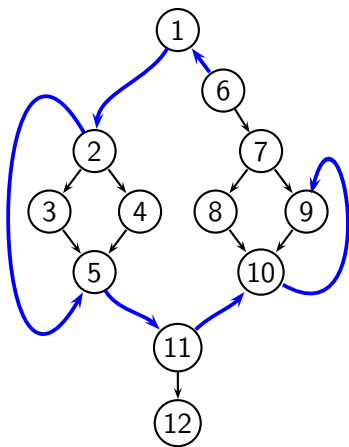
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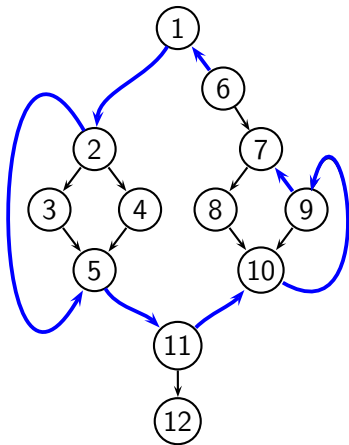
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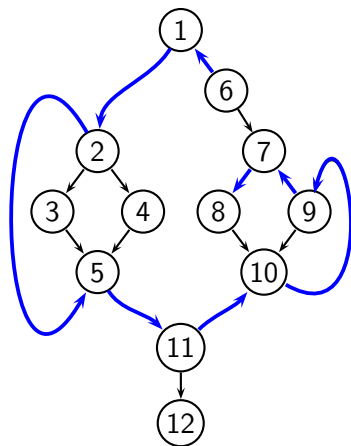
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Information Flow and Information Flow Paths

- Default value at each program point: \top
- *Information flow path*



Information Flow and Information Flow Paths

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Sequence of adjacent program points



Information Flow and Information Flow Paths

- Default value at each program point: \top
- *Information flow path*

Sequence of adjacent program points
along which data flow values change



Information Flow and Information Flow Paths

- Default value at each program point: \top
- *Information flow path*
 - Sequence of adjacent program points along which data flow values change
- A change in the data flow at a program point could be
 - ▶ *Generation of information*
Change from \top to a non- \top due to local effect (i.e. $f(\top) \neq \top$)
 - ▶ *Propagation of information*
Change from x to y such that $y \sqsubseteq x$ due to global effect

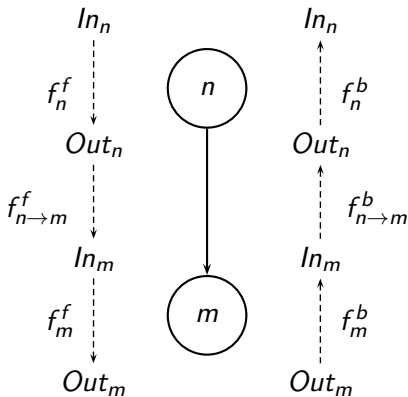


Information Flow and Information Flow Paths

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 - ▶ *Propagation of information*
Change from x to y such that $y \sqsubseteq x$ due to global effect
- Information flow path (ifp) need not be a graph theoretic path

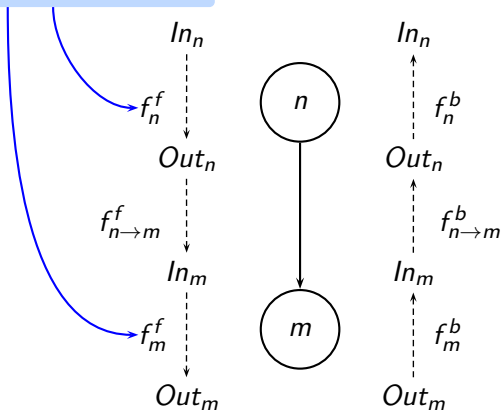


Edge and Node Flow Functions



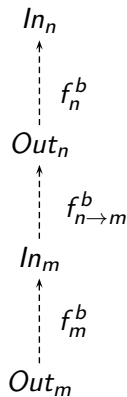
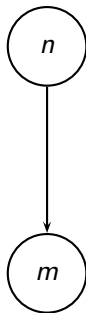
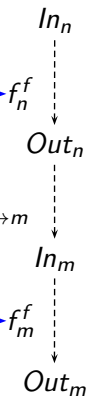
Edge and Node Flow Functions

Forward Node Flow Function



Edge and Node Flow Functions

Forward Node Flow Function

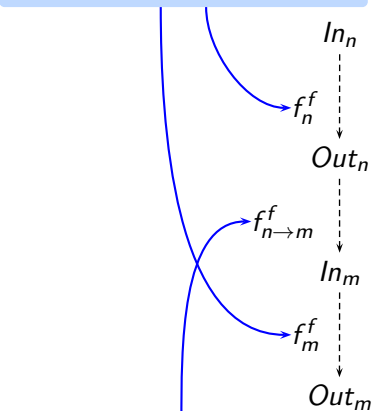


Forward Edge Flow Function



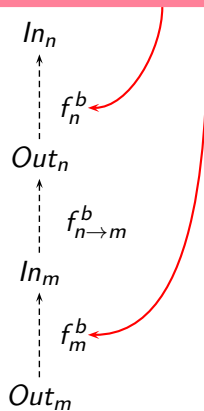
Edge and Node Flow Functions

Forward Node Flow Function



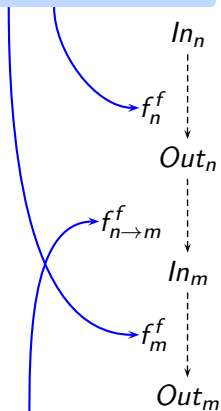
Forward Edge Flow Function

Backward Node Flow Function



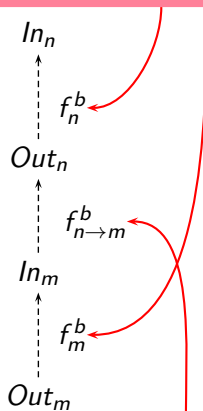
Edge and Node Flow Functions

Forward Node Flow Function



Forward Edge Flow Function

Backward Node Flow Function



Backward Edge Flow Function



General Data Flow Equations

$$\begin{aligned}
 In_n &= \begin{cases} BI_{Start} \sqcap f_n^b(Out_n) & n = Start \\ \left(\prod_{m \in pred(n)} f_{m \rightarrow n}^f(Out_m) \right) \sqcap f_n^b(Out_n) & \text{otherwise} \end{cases} \\
 Out_n &= \begin{cases} BI_{End} \sqcap f_n^f(In_n) & n = End \\ \left(\prod_{m \in succ(n)} f_{m \rightarrow n}^b(In_m) \right) \sqcap f_n^f(In_n) & \text{otherwise} \end{cases}
 \end{aligned}$$

- Edge flow functions are typically identity

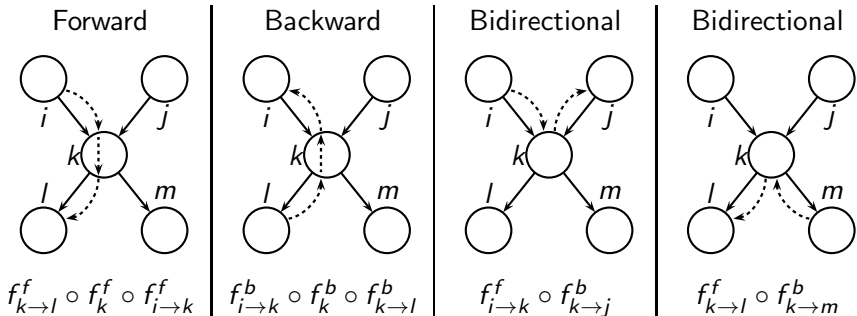
$$\forall x \in L, f(x) = x$$

- If particular flows are absent, the corresponding flow functions are

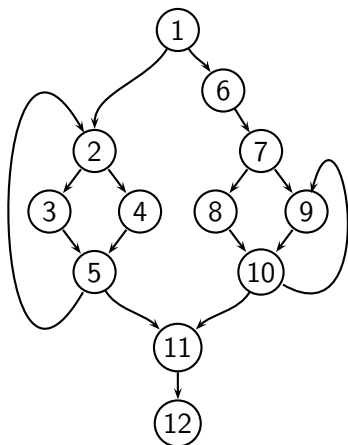
$$\forall x \in L, f(x) = \top$$



Modelling Information Flows Using Edge and Node Flow Functions



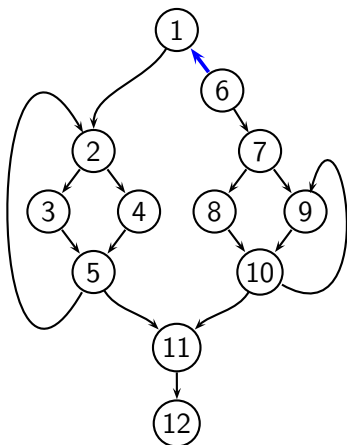
Information Flow Paths in PRE



- Information could flow along arbitrary paths



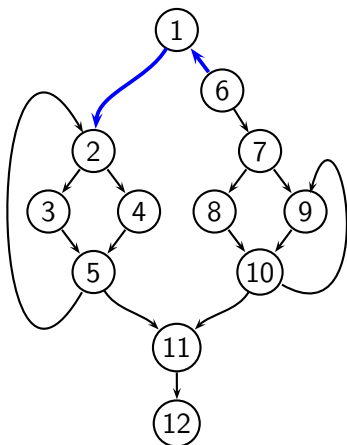
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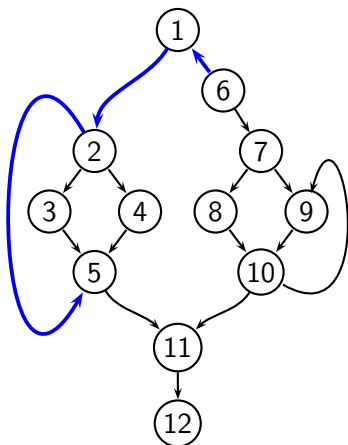
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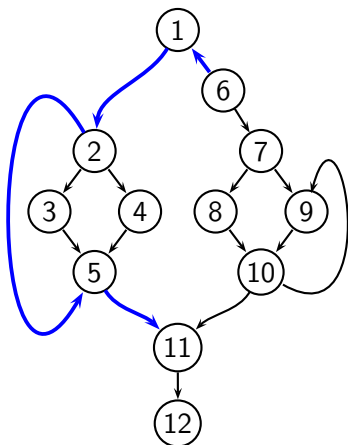
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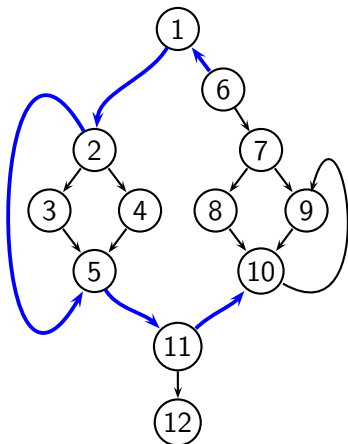
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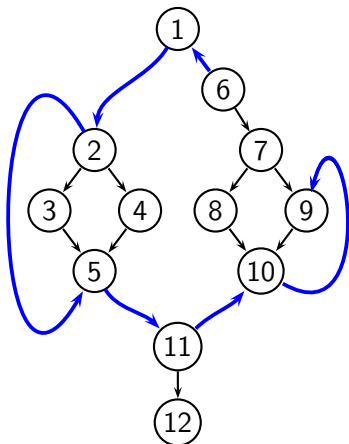
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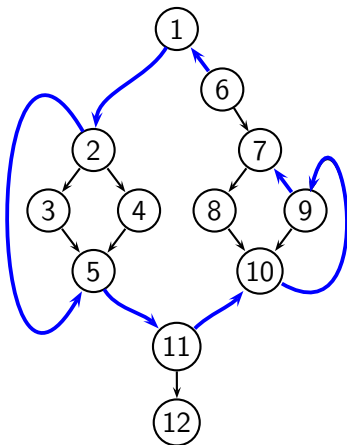
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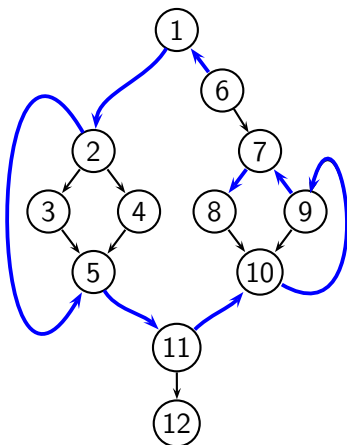
Information Flow Paths in PRE



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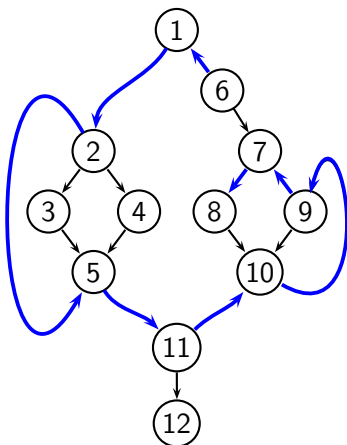
Information Flow Paths in PRE



- Information could flow along arbitrary paths
- Theoretically predicted number : 144



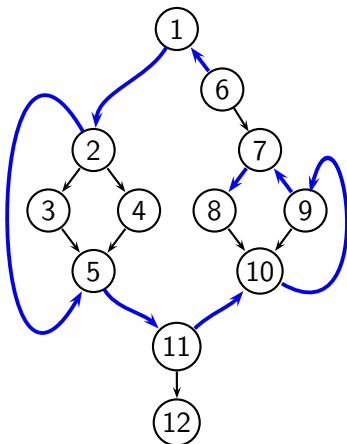
Information Flow Paths in PRE



- Information could flow along arbitrary paths
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- Actual iterations : 5



Information Flow Paths in PRE



- Information could flow along arbitrary paths
- Theoretically predicted number : 144
- Actual iterations : 5
- Not related to depth (1)

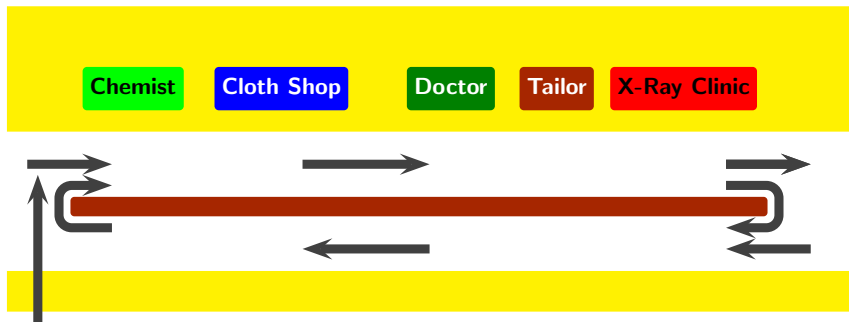


Lacuna with PRE Complexity

- Lacuna with PRE : Complexity $O(n^2)$ traversals.
Practical graphs may have upto 50 nodes.
 - ▶ Predicted number of traversals : 2,500.
 - ▶ Practical number of traversals : ≤ 5 .
- No explanation for about 14 years despite dozens of efforts.
- Not much experimentation with performing advanced optimizations involving bidirectional dependency.



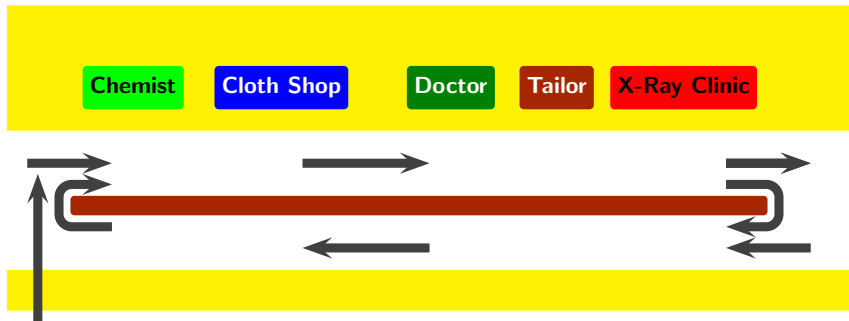
Complexity of Round Robin Iterative Method



- Buy OTC (Over-The-Counter) medicine. No U-Turn 1 Trip



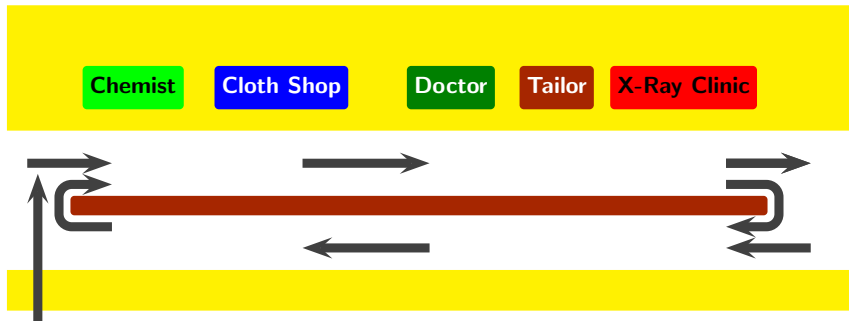
Complexity of Round Robin Iterative Method



- Buy OTC (Over-The-Counter) medicine. No U-Turn 1 Trip
- Buy cloth. Give it to the tailor for stitching. No U-Turn 1 Trip



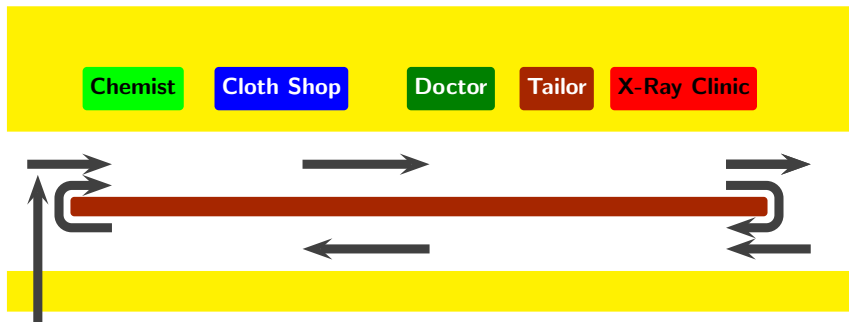
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- Buy medicine with doctor's prescription. 1 U-Turn 2 Trips



Complexity of Round Robin Iterative Method



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- Buy cloth. Give it to the tailor for stitching. No U-Turn 1 Trip
- Buy medicine with doctor's prescription. 1 U-Turn 2 Trips
- Buy medicine with doctor's prescription. 2 U-Turns 3 Trips

The diagnosis requires X-Ray.



Information Flow Paths and Width of a Graph

- A traversal $u \rightarrow v$ in an ifp is
 - ▶ *Compatible* if u is visited *before* v in the chosen graph traversal
 - ▶ *Incompatible* if u is visited *after* v in the chosen graph traversal



Information Flow Paths and Width of a Graph

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- Width of a program flow graph with respect to a data flow framework

Maximum number of incompatible traversals in any ifp, no part of which is bypassed



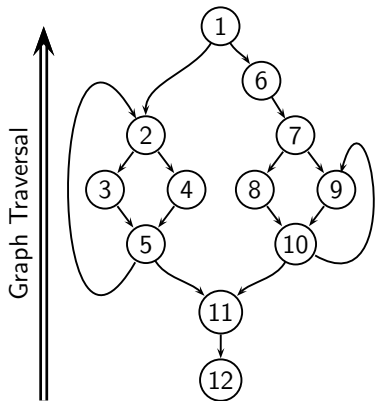
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Maximum number of incompatible traversals in any ifp, no part of which is bypassed
- Width + 1 iterations are sufficient to converge on MFP solution (1 additional iteration may be required for verifying convergence)



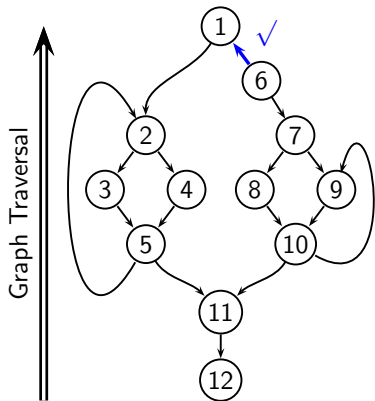
Complexity of Bidirectional Bit Vector Frameworks



- Every “incompatible” edge traversal
⇒ **One additional graph traversal**



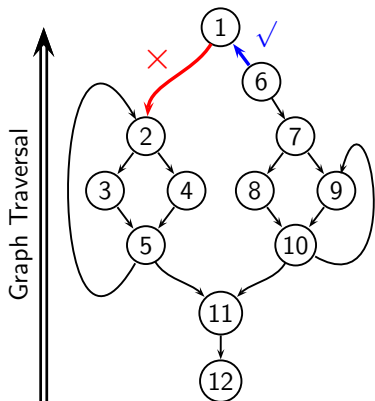
Complexity of Bidirectional Bit Vector Frameworks



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⇒ **One additional graph traversal**
- Max. Incompatible edge traversals
= *Width* of the graph = **0?**
- Maximum number of traversals =
1 + Max. incompatible edge traversals



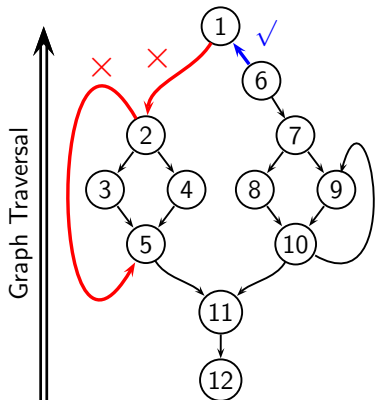
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- Max. Incompatible edge traversals
= *Width* of the graph = **1?**
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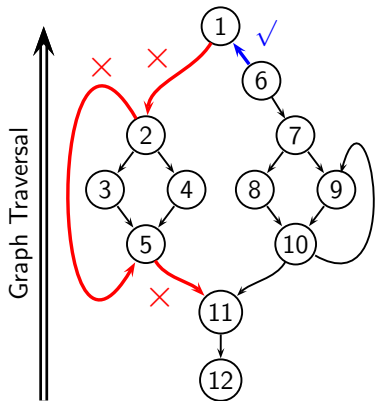
Complexity of Bidirectional Bit Vector Frameworks



- Every “incompatible” edge traversal
 \Rightarrow **One additional graph traversal**
- Max. Incompatible edge traversals
 $=$ *Width* of the graph = **2?**
- Maximum number of traversals =
 $1 +$ Max. incompatible edge traversals



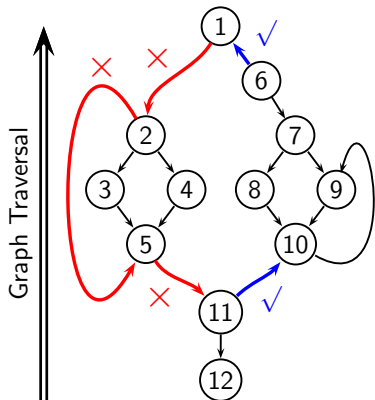
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 $=$ *Width* of the graph = **3?**
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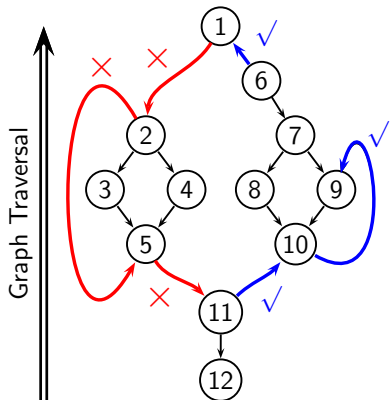
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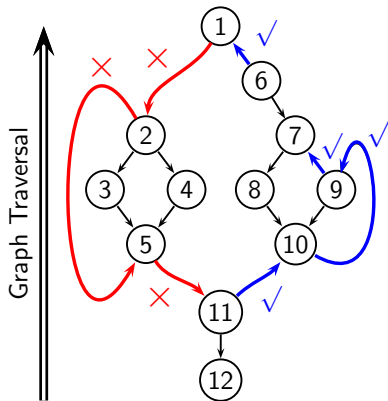
Complexity of Bidirectional Bit Vector Frameworks



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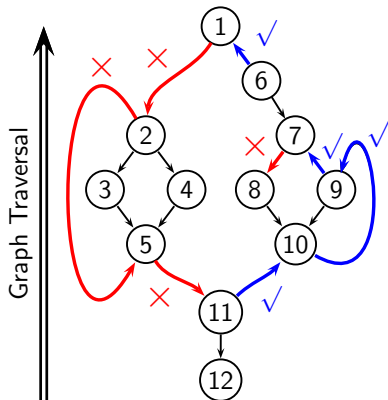
Complexity of Bidirectional Bit Vector Frameworks



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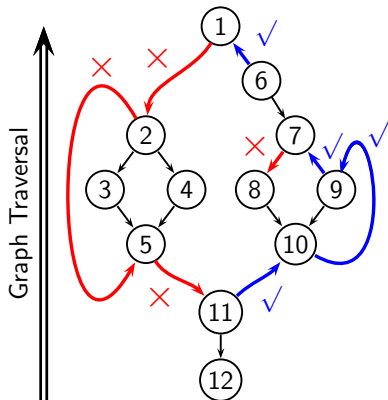
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- Maximum number of traversals = $1 + \text{Max. incompatible edge traversals}$



Complexity of Bidirectional Bit Vector Frameworks



- Every “incompatible” edge traversal \Rightarrow **One additional graph traversal**
- Max. Incompatible edge traversals = *Width* of the graph = **4**
- Maximum number of traversals = $1 + 4 = 5$



Width Subsumes Depth

- Depth is applicable only to unidirectional data flow frameworks
- Width is applicable to both unidirectional and bidirectional frameworks
- For a given graph, $\text{Width} \leq \text{Depth}$
Width provides a tighter bound

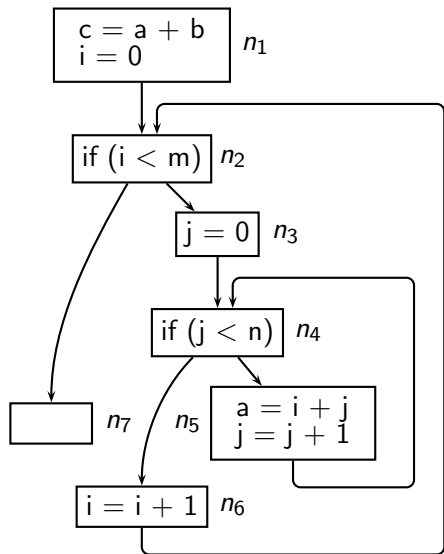


Comparison Between Width and Depth

- Depth is purely a graph theoretic property whereas width depends on control flow graph as well as the data framework
- Comparison between width and depth is meaningful only
 - ▶ For unidirectional frameworks
 - ▶ When the direction of traversal for computing width is the natural direction of traversal
- Since width excludes bypassed path segments, width can be smaller than depth



Width and Depth

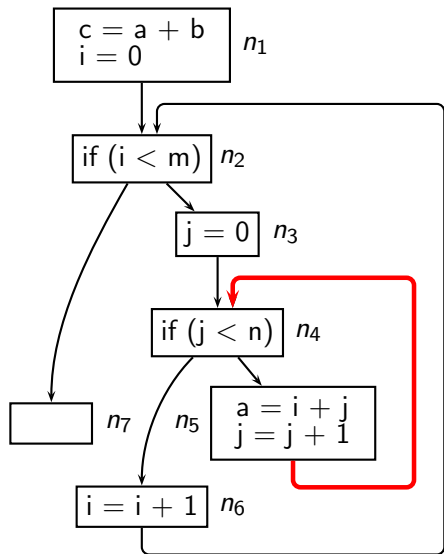


Assuming reverse postorder traversal for available expressions analysis

- Depth = 2



Width and Depth

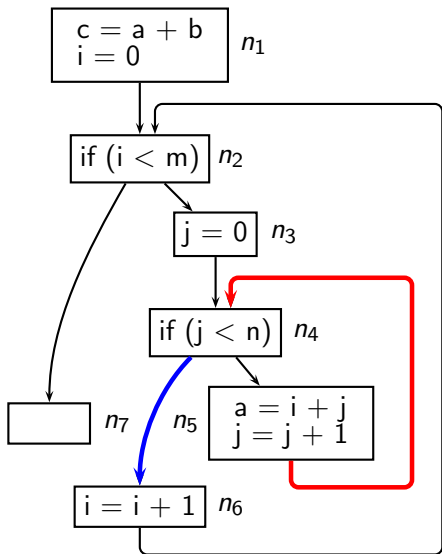


Assuming reverse postorder traversal for available expressions analysis

- Depth = 2
- Information generation point n_5 kills expression “ $a + b$ ”



Width and Depth

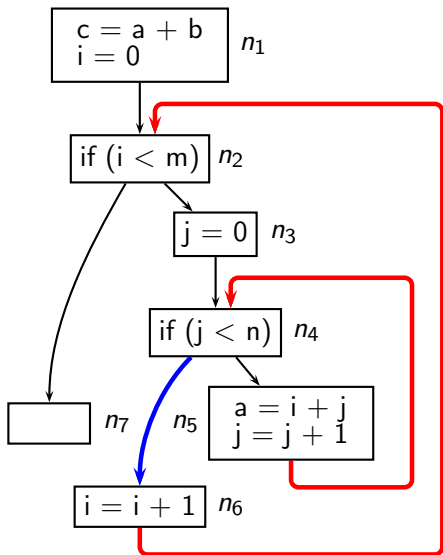


Assuming reverse postorder traversal for available expressions analysis

- Depth = 2
- Information generation point n_5 kills expression “a + b”
- Information propagation path $n_5 \rightarrow n_4 \rightarrow n_6 \rightarrow n_2$
No *Gen* or *Kill* for “a + b” along this path



Width and Depth

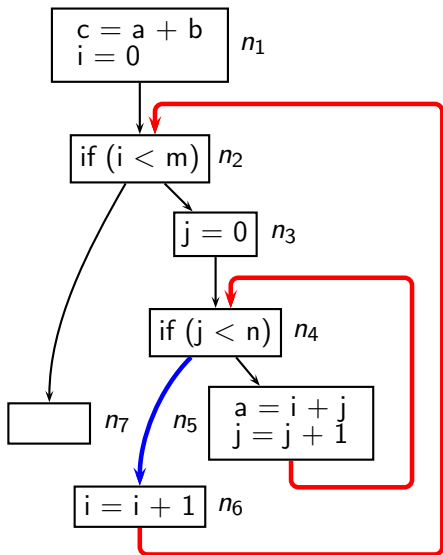


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Width and Depth

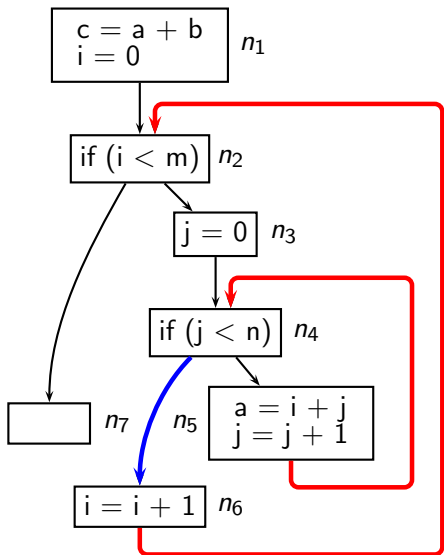


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- What about “j + 1”?



Width and Depth

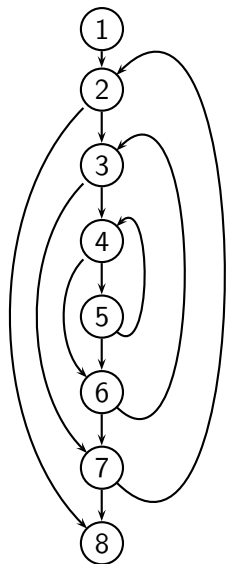


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No *Gen* or *Kill* for “a + b” along this path
- Width = 2
- What about “j + 1”?
- Not available on entry to the loop



Width and Depth

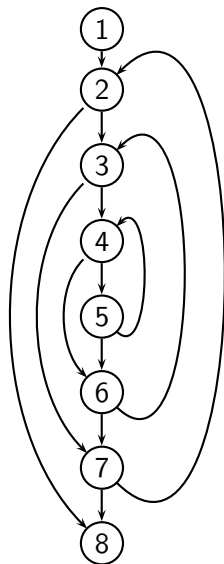


Structures resulting from repeat-until loops with premature exits

- Depth = 3



Width and Depth

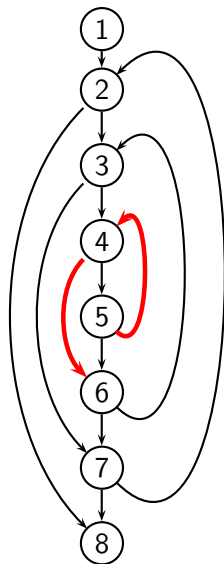


Structures resulting from repeat-until loops with premature exits

- Depth = 3
- However, any unidirectional bit vector is guaranteed to converge in $2 + 1$ iterations



Width and Depth

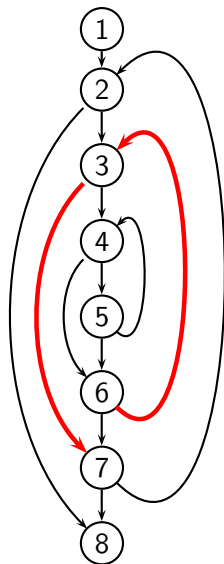


Structures resulting from repeat-until loops with premature exits

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- ifp $5 \rightarrow 4 \rightarrow 6$ is bypassed by the edge $5 \rightarrow 6$



Width and Depth

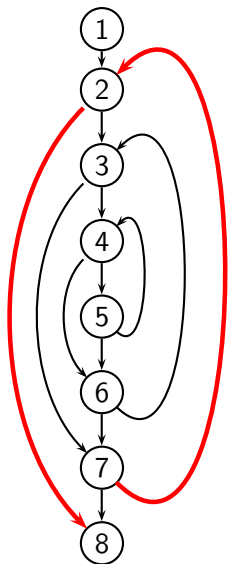


Structures resulting from repeat-until loops with premature exits

- Depth = 3
- However, any unidirectional bit vector is guaranteed to converge in $2 + 1$ iterations
- ifp $5 \rightarrow 4 \rightarrow 6$ is bypassed by the edge $5 \rightarrow 6$
- ifp $6 \rightarrow 3 \rightarrow 6$ is bypassed by the edge $6 \rightarrow 7$



Width and Depth

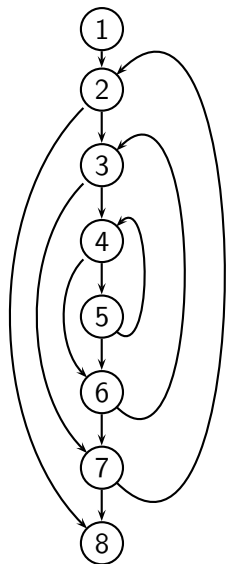


Structures resulting from repeat-until loops with premature exits

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- However, any unidirectional bit vector is guaranteed to converge in $2 + 1$ iterations
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- ifp $7 \rightarrow 2 \rightarrow 8$ is bypassed by the edge $7 \rightarrow 8$



Width and Depth

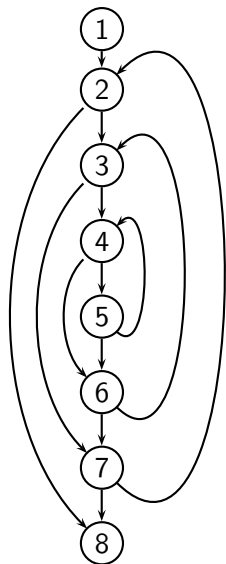


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- For forward unidirectional frameworks, width is 1



Width and Depth



Structures resulting from repeat-until loops with premature exits

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- ifp $6 \rightarrow 3 \rightarrow 6$ is bypassed by the edge $6 \rightarrow 7$
- ifp $7 \rightarrow 2 \rightarrow 8$ is bypassed by the edge $7 \rightarrow 8$
- For forward unidirectional frameworks, width is 1
- Splitting the bypassing edges and inserting nodes along those edges increases the width



Work List Based Iterative Algorithm

Directly traverses information flow paths

```
1   $ln_0 = BI$ 
2  for all  $j \neq 0$  do
3  {  $ln_j = \top$ 
4    Add  $j$  to LIST
5  }
6  while LIST is not empty do
7  { Let  $j$  be the first node in LIST. Remove it from LIST
8     $temp = \prod_{p \in pred(j)} f_p(ln_p)$ 
9    if  $temp \neq ln_j$  then
10   {  $ln_j = temp$ 
11     Add all successors of  $j$  to LIST
12   }
13 }
```



Tutorial Problem

Perform work list based iterative analysis for earlier examples. Assume that the work list follows FIFO (First in First Out) policy.

Show the trace of the analysis in the following format:

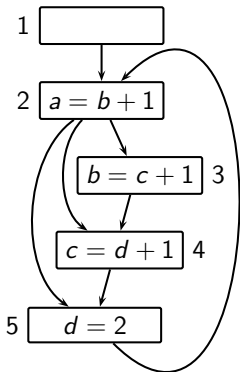
| Step No. | Program Point Selected | Remaining Work list | Data Flow Value | Program Point(s) Added | Resulting Work list |
|----------|------------------------|---------------------|-----------------|------------------------|---------------------|
|----------|------------------------|---------------------|-----------------|------------------------|---------------------|



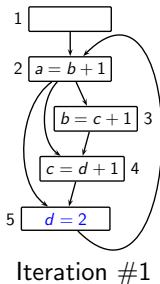
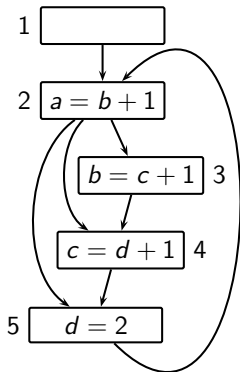
Part 5

Precise Modelling of General Flows

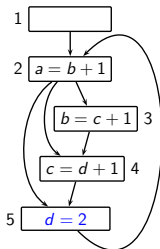
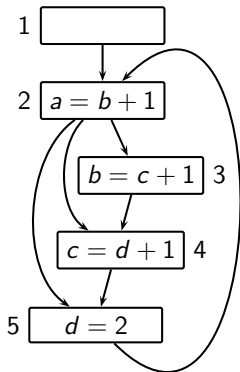
Complexity of Constant Propagation?



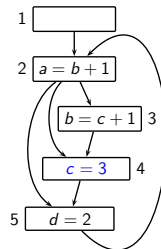
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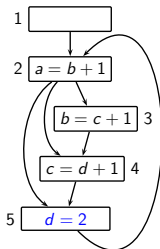
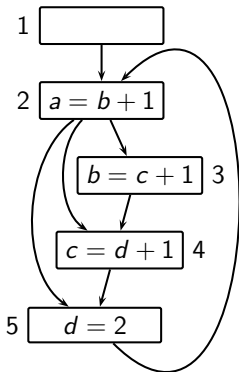
Iteration #1



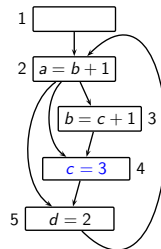
Iteration #2



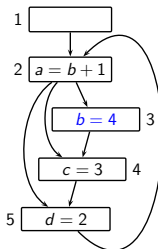
Complexity of Constant Propagation?



Iteration #1



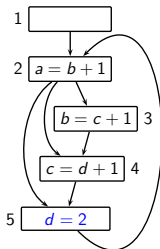
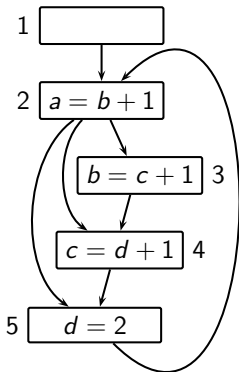
Iteration #2



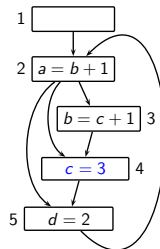
Iteration #3



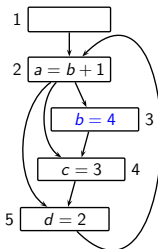
Complexity of Constant Propagation?



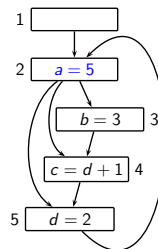
Iteration #1



Iteration #2



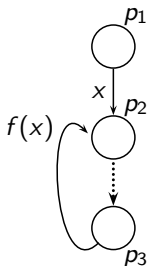
Iteration #3



Iteration #4



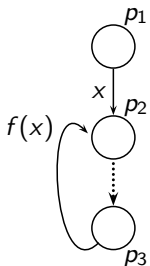
Loop Closures of Flow Functions



| Paths Terminating at p_2 | Data Flow Value |
|--|-----------------------|
| p_1, p_2 | x |
| p_1, p_2, p_3, p_2 | $f(x)$ |
| $p_1, p_2, p_3, p_2, p_3, p_2$ | $f(f(x)) = f^2(x)$ |
| $p_1, p_2, p_3, p_2, p_3, p_2, p_3, p_2$ | $f(f(f(x))) = f^3(x)$ |
| ... | ... |



Loop Closures of Flow Functions



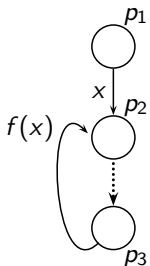
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- For static analysis we need to summarize the value at p_2 by a value which is safe after **any** iteration.

$$f^*(x) = x \sqcap f(x) \sqcap f^2(x) \sqcap f^3(x) \sqcap f^4(x) \sqcap \dots$$



Loop Closures of Flow Functions



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- For static analysis we need to summarize the value at p_2 by a value which is safe after **any** iteration.

$$f^*(x) = x \sqcap f(x) \sqcap f^2(x) \sqcap f^3(x) \sqcap f^4(x) \sqcap \dots$$

- f^* is called the **loop closure** of f .



Loop Closures in Bit Vector Frameworks

- Flow functions in bit vector frameworks have constant *Gen* and *Kill*

$$f^*(x) = x \sqcap f(x) \sqcap f^2(x) \sqcap f^3(x) \sqcap \dots$$

$$f^2(x) = f(\text{Gen} \cup (x - \text{Kill}))$$

$$= \text{Gen} \cup ((\text{Gen} \cup (x - \text{Kill})) - \text{Kill})$$

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- Loop Closures of Bit Vector Frameworks are 2-bounded.*



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- Loop Closures of Bit Vector Frameworks are 2-bounded.*
- Intuition: Since *Gen* and *Kill* are constant, same things are generated or killed in every application of *f*.
Multiple applications of *f* are not required unless the input value changes.



Larger Values of Loop Closure Bounds

- Fast Frameworks \equiv 2-bounded frameworks (eg. bit vector frameworks)

Both these conditions must be satisfied

- ▶ *Separability*

Data flow values of different entities are independent

- ▶ *Constant or Identity Flow Functions*

Flow functions for an entity are either constant or identity

- Non-fast frameworks

At least one of the above conditions is violated



Separability

$f : L \mapsto L$ is $\langle \hat{h}_1, \hat{h}_2, \dots, \hat{h}_m \rangle$ where \hat{h}_i computes the value of \hat{x}_i



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Separable

Non-Separable

Example: All bit vector frameworks

Example: Constant Propagation



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Separable

$\langle \hat{x}_1, \hat{x}_2, \dots, \hat{x}_m \rangle$



f



$\langle \hat{y}_1, \hat{y}_2, \dots, \hat{y}_m \rangle$

Non-Separable

$\langle \hat{x}_1, \hat{x}_2, \dots, \hat{x}_m \rangle$



f



$\langle \hat{y}_1, \hat{y}_2, \dots, \hat{y}_m \rangle$

Example: All bit vector frameworks

Example: Constant Propagation

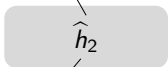


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Separable

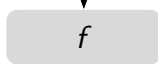
$\langle \hat{x}_1, \hat{x}_2, \dots, \hat{x}_m \rangle$



$\langle \hat{y}_1, \hat{y}_2, \dots, \hat{y}_m \rangle$

Non-Separable

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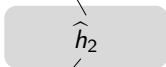


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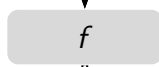


$\langle \hat{y}_1, \hat{y}_2, \dots, \hat{y}_m \rangle$

$\hat{h} : \hat{L} \mapsto \hat{L}$

Non-Separable

$\langle \hat{x}_1, \hat{x}_2, \dots, \hat{x}_m \rangle$



$\langle \hat{y}_1, \hat{y}_2, \dots, \hat{y}_m \rangle$

Example: All bit vector frameworks

Example: Constant Propagation

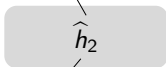


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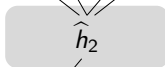
$\langle \hat{x}_1, \hat{x}_2, \dots, \hat{x}_m \rangle$



$\langle \hat{y}_1, \hat{y}_2, \dots, \hat{y}_m \rangle$

Non-Separable

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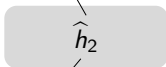


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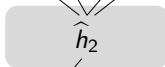


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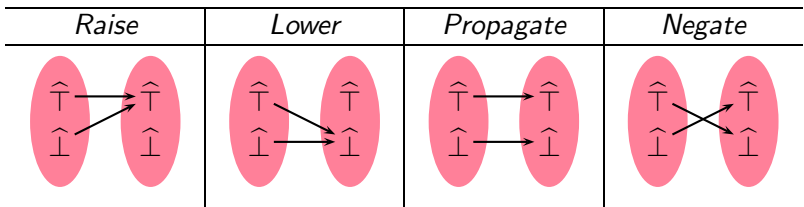
Example: All bit vector frameworks

Example: Constant Propagation



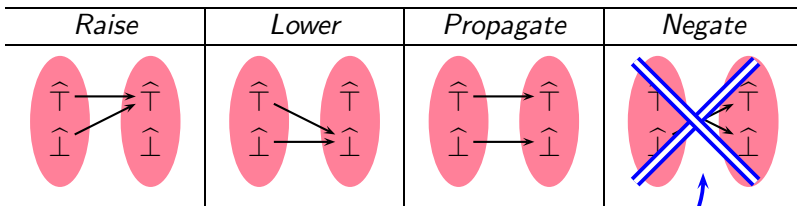
Separability of Bit Vector Frameworks

- \hat{L} is $\{0, 1\}$, L is $\{0, 1\}^m$
- $\hat{\Pi}$ is either boolean AND or boolean OR
- $\hat{\top}$ and $\hat{\perp}$ are 0 or 1 depending on $\hat{\Pi}$.
- \hat{h} is a *bit function* and could be one of the following:



Separability of Bit Vector Frameworks

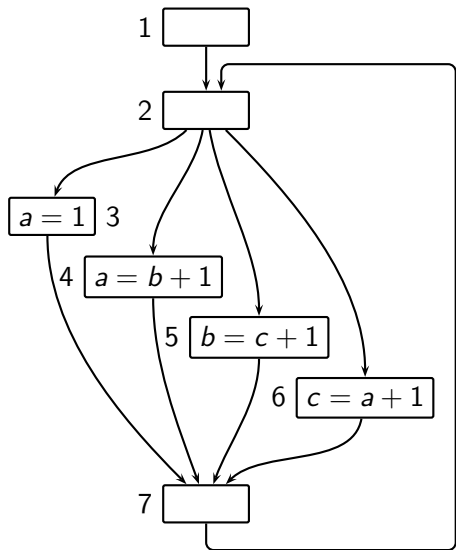
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Non-monotonicity



Boundedness of Constant Propagation

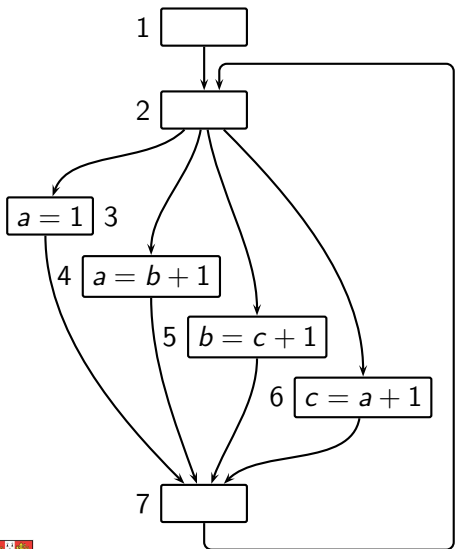


Boundedness of Constant Propagation

Summary flow function:

(data flow value at node 7)

$$f(\langle v_a, v_b, v_c \rangle) = \langle 1 \sqcap (v_b + 1), \\ (v_c + 1), \\ (v_a + 1) \rangle$$



Boundedness of Constant Propagation

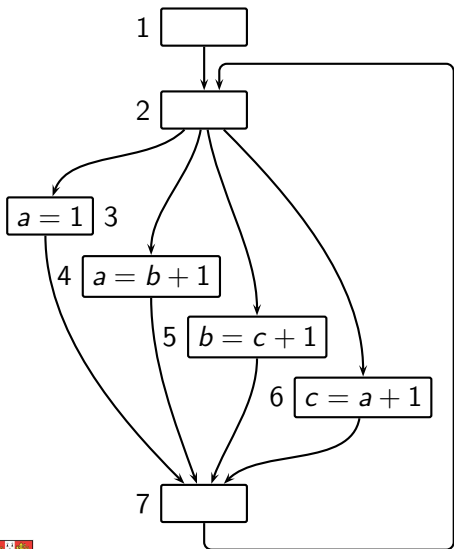
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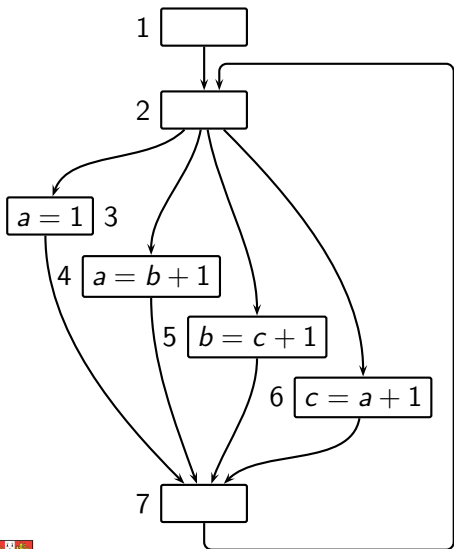
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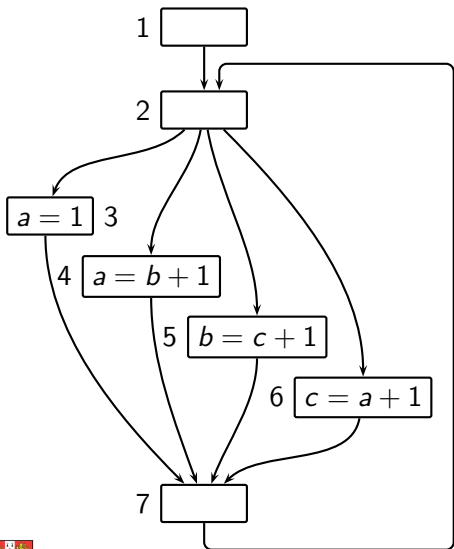
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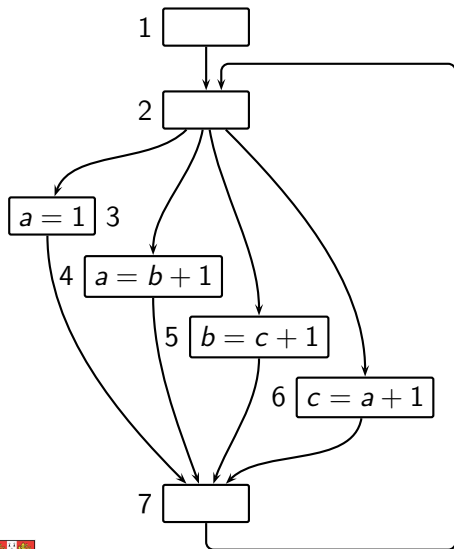
$$f^3(\top) = \langle 1, 3, 2 \rangle$$



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$$f^3(\top) = \langle 1, 3, 2 \rangle$$

$$f^4(\top) = \langle \hat{\perp}, 3, 2 \rangle$$

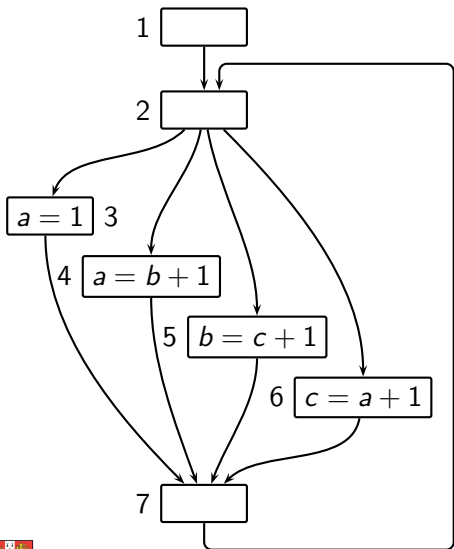


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$$f^5(\top) = \langle \perp, 3, \perp \rangle$$

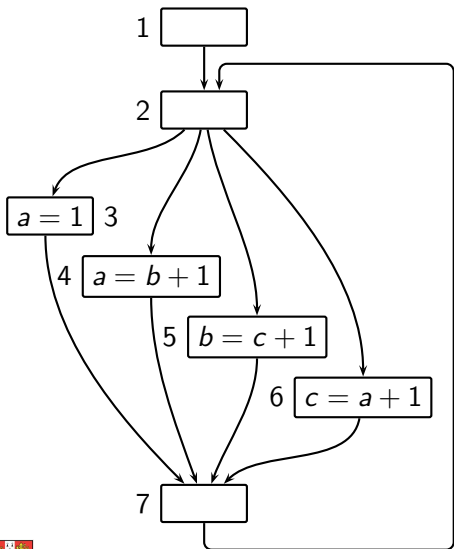


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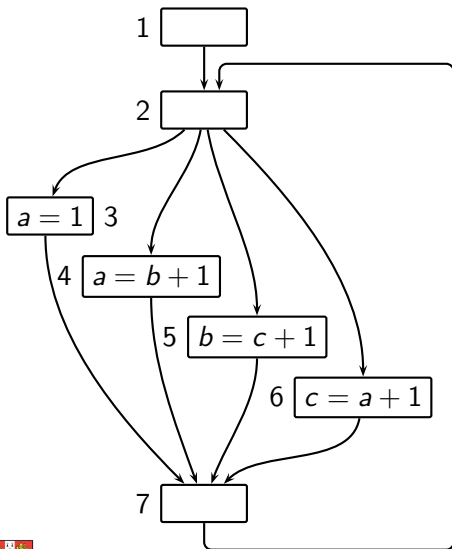
$$f^6(\top) = \langle \perp, \perp, \perp \rangle$$



Boundedness of Constant Propagation

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(data flow value at node 7)



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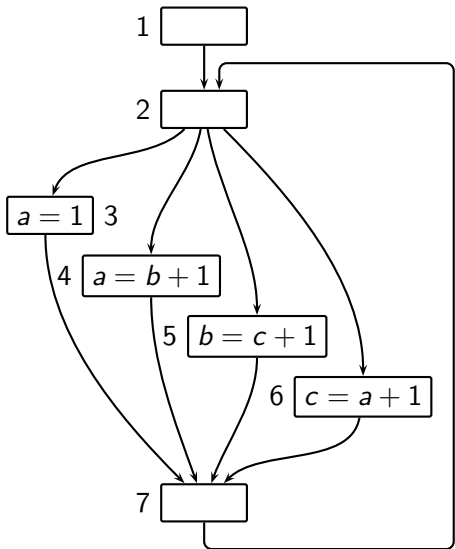
$$f^5(\top) = \langle \perp, 3, \perp \rangle$$

$$f^6(\top) = \langle \perp, \perp, \perp \rangle$$

$$f^7(\top) = \langle \perp, \perp, \perp \rangle$$



Boundedness of Constant Propagation



$$f^*(\top) = \bigcap_{i=0}^6 f^i(\top)$$



Boundedness of Constant Propagation

The moral of the story:

- The data flow value of every variable could change twice



Boundedness of Constant Propagation

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Boundedness of Constant Propagation

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Boundedness of Constant Propagation

The moral of the story:

- The data flow value of every variable could change twice
- In the worst case, only one change may happen in every step of a function application
- Maximum number of steps: $2 \times |\mathbb{V}\text{ar}|$
- Boundedness parameter k is $(2 \times |\mathbb{V}\text{ar}|) + 1$



Modelling Flow Functions for General Flows

- General flow functions can be written as

$$f_n(X) = (X - Kill_n(X)) \cup Gen_n(X)$$

where *Gen* and *Kill* have constant and dependent parts

$$Gen_n(X) = ConstGen_n \cup DepGen_n(X)$$

$$Kill_n(X) = ConstKill_n \cup DepKill_n(X)$$



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$$Kill_n(X) = ConstKill_n \cup DepKill_n(X)$$

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 - ▶ dependence across different entities as well as
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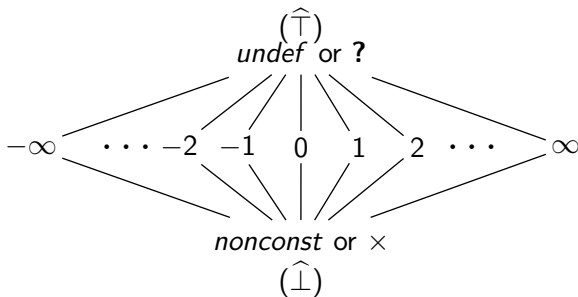
$$Kill_n(X) = ConstKill_n \cup DepKill_n(X)$$

- The dependent parts take care of
 - ▶ dependence across different entities as well as
 - ▶ dependence on the value of the same entity in the argument X
- Bit vector frameworks are a special case

$$DepGen_n(X) = DepKill_n(X) = \emptyset$$



Component Lattice for Integer Constant Propagation



- Overall lattice L is the product of \hat{L} for all variables.
- \sqcap and $\hat{\sqcap}$ get defined by \sqsubseteq and $\hat{\sqsubseteq}$.

| | | | |
|-----------------------------|-----------------------------|-----------------------------|---|
| $\hat{\sqcap}$ | $\langle v, ? \rangle$ | $\langle v, \times \rangle$ | $\langle v, c_1 \rangle$ |
| $\langle v, ? \rangle$ | $\langle v, ? \rangle$ | $\langle v, \times \rangle$ | $\langle v, c_1 \rangle$ |
| $\langle v, \times \rangle$ | $\langle v, \times \rangle$ | $\langle v, \times \rangle$ | $\langle v, \times \rangle$ |
| $\langle v, c_2 \rangle$ | $\langle v, c_2 \rangle$ | $\langle v, \times \rangle$ | If $c_1 = c_2$ then $\langle v, c_1 \rangle$ else $\langle v, \times \rangle$ |



Flow Functions for Constant Propagation

- Flow function for $r = a_1 * a_2$

| | | | |
|-------------------------------|-----------------------------|-------------------------------|----------------------------------|
| <i>mult</i> | $\langle a_1, ? \rangle$ | $\langle a_1, \times \rangle$ | $\langle a_1, c_1 \rangle$ |
| $\langle a_2, ? \rangle$ | $\langle r, ? \rangle$ | $\langle r, \times \rangle$ | $\langle r, ? \rangle$ |
| $\langle a_2, \times \rangle$ | $\langle r, \times \rangle$ | $\langle r, \times \rangle$ | $\langle r, \times \rangle$ |
| $\langle a_2, c_2 \rangle$ | $\langle r, ? \rangle$ | $\langle r, \times \rangle$ | $\langle r, (c_1 * c_2) \rangle$ |



Defining Data Flow Equations for Constant Propagation

| | $ConstGen_n$ | $DepGen_n(X)$ | $ConstKill_n$ | $DepKill_n(X)$ |
|------------------------------------|---------------------------------|-------------------------------------|---------------|--|
| $v = c,$ $c \in \mathbb{C}onst$ | $\{\langle v, c \rangle\}$ | \emptyset | \emptyset | $\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$ |
| $v = e,$ $e \in \mathbb{E}xpr$ | \emptyset | $\{\langle v, eval(e, X) \rangle\}$ | \emptyset | $\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$ |
| $read(v)$ | $\{\langle v, \times \rangle\}$ | \emptyset | \emptyset | $\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$ |
| <i>other</i> | \emptyset | \emptyset | \emptyset | \emptyset |



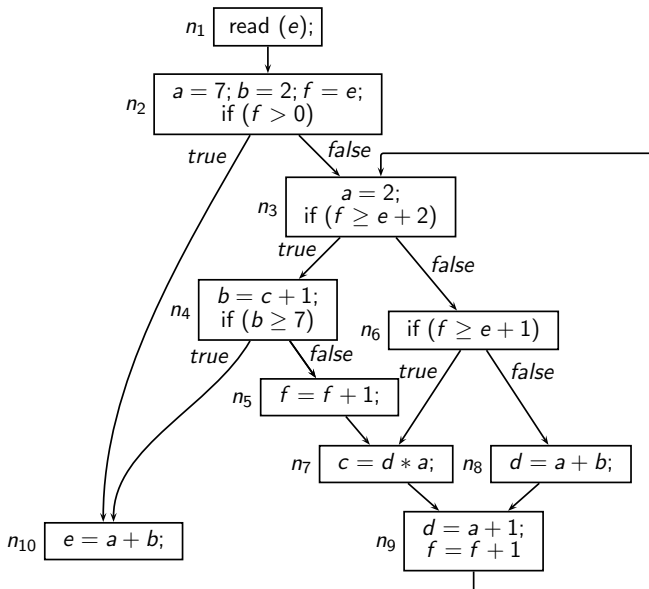
Defining Data Flow Equations for Constant Propagation

| | $ConstGen_n$ | $DepGen_n(X)$ | $ConstKill_n$ | $DepKill_n(X)$ |
|----------------------------------|---------------------------------|--|---------------|--|
| $v = c,$ $c \in \text{Const}$ | $\{\langle v, c \rangle\}$ | \emptyset | \emptyset | $\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$ |
| $v = e,$ $e \in \text{Expr}$ | \emptyset | $\{\langle v, \text{eval}(e, X) \rangle\}$ | \emptyset | $\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$ |
| $\text{read}(v)$ | $\{\langle v, \times \rangle\}$ | \emptyset | \emptyset | $\{\langle v, d \rangle \mid \langle v, d \rangle \in X\}$ |
| <i>other</i> | \emptyset | \emptyset | \emptyset | \emptyset |

| $\text{eval}(a_1 \text{ op } a_2, X)$ | | | |
|---------------------------------------|--------------------------------|-------------------------------------|----------------------------------|
| | $\langle a_1, ? \rangle \in X$ | $\langle a_1, \times \rangle \in X$ | $\langle a_1, c_1 \rangle \in X$ |
| $\langle a_2, ? \rangle \in X$ | ? | \times | ? |
| $\langle a_2, \times \rangle \in X$ | \times | \times | \times |
| $\langle a_2, c_2 \rangle \in X$ | ? | \times | $c_1 \text{ op } c_2$ |



Example Program for Constant Propagation



Result of Constant Propagation

| | Iteration #1 | Changes in iteration #2 | Changes in iteration #3 | Changes in iteration #4 |
|----------------|---|---|--|--|
| In_{n_1} | $\hat{\top}, \hat{\top}, \hat{\top}, \hat{\top}, \hat{\top}, \hat{\top}$ | | | |
| Out_{n_1} | $\hat{\top}, \hat{\top}, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\top}$ | | | |
| In_{n_2} | $\hat{\top}, \hat{\top}, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\top}$ | | | |
| Out_{n_2} | $7, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | | | |
| In_{n_3} | $7, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $\hat{\perp}, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $\hat{\perp}, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $\hat{\perp}, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ |
| Out_{n_3} | $2, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ |
| In_{n_4} | $2, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ |
| Out_{n_4} | $2, \hat{\top}, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, \hat{\top}, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 7, 6, 3, \hat{\perp}, \hat{\perp}$ | |
| In_{n_5} | $2, \hat{\top}, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, \hat{\top}, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 7, 6, 3, \hat{\perp}, \hat{\perp}$ | |
| Out_{n_5} | $2, \hat{\top}, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, \hat{\top}, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 7, 6, 3, \hat{\perp}, \hat{\perp}$ | |
| In_{n_6} | $2, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ |
| Out_{n_6} | $2, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ |
| In_{n_7} | $2, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ | |
| Out_{n_7} | $2, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ | |
| In_{n_8} | $2, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $2, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ |
| Out_{n_8} | $2, 2, \hat{\top}, 4, \hat{\perp}, \hat{\perp}$ | $2, 2, \hat{\top}, 4, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 4, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, \hat{\perp}, \hat{\perp}, \hat{\perp}$ |
| In_{n_9} | $2, 2, \hat{\top}, 4, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, \hat{\perp}, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, \hat{\perp}, \hat{\perp}, \hat{\perp}$ | |
| Out_{n_9} | $2, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $2, 2, 6, 3, \hat{\perp}, \hat{\perp}$ | $2, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ | |
| $In_{n_{10}}$ | $\hat{\perp}, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $\hat{\perp}, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $\hat{\perp}, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ | |
| $Out_{n_{10}}$ | $\hat{\perp}, 2, \hat{\top}, \hat{\top}, \hat{\perp}, \hat{\perp}$ | $\hat{\perp}, 2, \hat{\top}, 3, \hat{\perp}, \hat{\perp}$ | $\hat{\perp}, \hat{\perp}, 6, 3, \hat{\perp}, \hat{\perp}$ | |



Monotonicity of Constant Propagation

- Flow function $f_n(X) = (X - Kill_n(X)) \cup Gen_n(X)$ where

$$Gen_n(X) = ConstGen_n \cup DepGen_n(X)$$

$$Kill_n(X) = ConstKill_n \cup DepKill_n(X)$$

- $ConstGen_n$ and $ConstKill_n$ are trivially monotonic
- To show $X_1 \sqsubseteq X_2 \Rightarrow DepGen_n(X_1) \sqsubseteq DepGen_n(X_2)$
we need to show that $X_1 \sqsubseteq X_2 \Rightarrow eval(e, X_1) \sqsubseteq eval(e, X_2)$.
This follows from definition of $eval(e, X)$.
- To show $X_1 \sqsubseteq X_2 \Rightarrow (X_1 - DepKill_n(X_1)) \sqsubseteq (X_2 - DepKill_n(X_2))$
observe that $DepKill_n$ removes the pair corresponding to the variable modified in statement n . Data flow values of other variables remain unaffected.

