BioInformatics 2009-2010 12 lectures -- Pietro Lio', pl219

Bioinformatics is focused on developing algorithms to be used in biological and medical researches. Molecular biologists generate massive amounts of information that can only be efficiently analyzed with computers.

Computer science could provide the abstraction needed for consolidating knowledge of biomolecular systems.

Both DNA sequence and protein structure research have adopted good abstractions: 'DNA-as-string' (a mathematical string is a finite sequence of symbols) and 'protein-as-three-dimensional-labelled-graph', respectively.

1

BioInformatics

Content

- Working with sequence data
 - Algorithms focusing on strings (lect 1-4)
 - Algorithms on Trees (lect 5-7)
 - Information theory and DNA (lect 8)
 - Applications of Hidden Markov models (lect 9)
- working with microarray data
 - Algorithms for Clustering (lect 10)
 - Algorithms for Genetic Networks (lect 11)
 - Algorithms for System Biology (lect 12)
 - These algorithms are useful in life sciences and are also used in other fields such as economic and social sciences.

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DNA SEQUENCES AS STRINGS

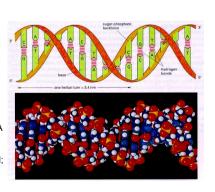
DNA: 4-letter alphabet, A (adenine), T (thymine), C (cytosine) and G (guanine). In the double helix A pairs with T, C with G; RNA: same as DNA but T -> U (uracil) 3 letters (triplet – a codon) code for one amino acid in a protein.

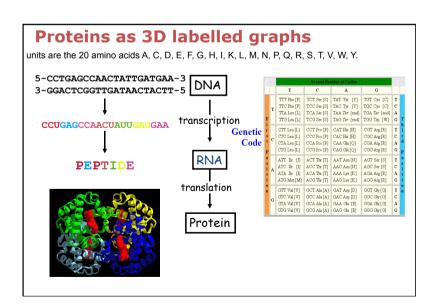


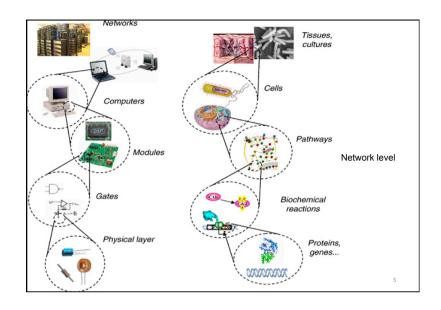
CCUGAGCCAACUAUUGAUGAA

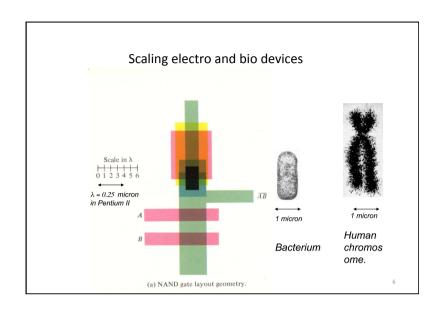
Gene: hereditary information located on the chromosomes and consisting of DNA (say 1000 bases);

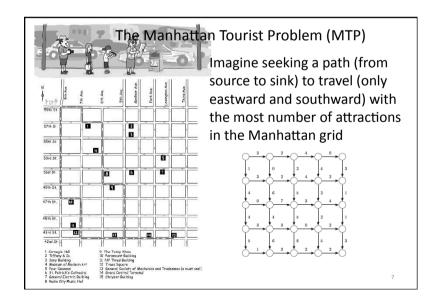
Genome: an organism's genetic material; human genome= 46 pieces (chromosomes) with overall length 3 x 10⁹ base.

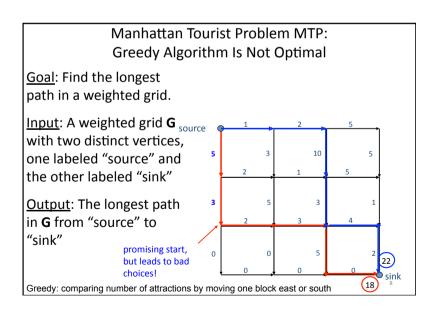






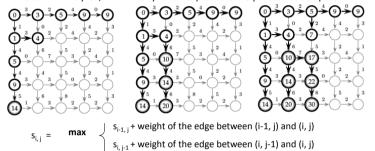






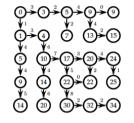
Computing the score for a point (i,j) by the recurrence relation:

- Calculate optimal path score for each vertex in the graph
- Each vertex's score is the maximum of the prior vertices score plus the weight of the respective edge in between
- The only hitch is that one must decide on the order in which visit the vertices; By the time the vertex x is analyzed, the values sy for all its predecessors y should be computed.



The running time is **n** x m for a n by m grid

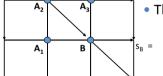
MTP: Dynamic Programming



 $\begin{array}{lll} \text{MANHATTANTOURIST}(\overset{1}{\mathbf{w}},\overset{1}{\mathbf{w}},n,m) \\ 1 & s_{0,0} \leftarrow 0 \\ 2 & \text{for } i \leftarrow 1 & \text{to } n \\ 3 & s_{i,0} \leftarrow s_{i-1,0} + \overset{1}{w}_{i,0} \\ 4 & \text{for } j - 1 & \text{to } m \\ 5 & s_{0,j} \leftarrow s_{0,j-1} + \overset{1}{w}_{0,j} \\ 6 & \text{for } i - 1 & \text{to } m \\ 7 & \text{for } j \leftarrow 1 & \text{to } m \\ 8 & s_{i,j} \leftarrow \max \left\{ \begin{array}{ll} s_{i-1,j} + \overset{1}{w}_{i,j} \\ s_{i,j-1} + \overset{1}{w}_{i,j} \\ \end{array} \right. \\ 9 & \text{return } s_{n,m} \end{array}$

MANHATTANTOURIST computes the length of the longest path in the grid, but does not give the path itself. Lines 1 through 5 set up the initial conditions on the matrix s, and line 8 correspondsto the recurrence that allows us to fill in later table entries based on earlier ones. Most of the dynamic programming algorithms we will develop in the context of DNA sequence comparison will look just like MANHATTANTOURIST with only minor changes. Many problems in bioinformatics can be solved efficiently by the application of the dynamic programming technique, once they are cast as traveling in a Manhattan-like grid.

Manhattan Is Not A Perfect Grid



• The score at point B is given by:

max of s_{A1} + weight of the edge (A₁, B) s_{A2} + weight of the edge (A₂, B)

 $s_{\Delta 3}$ + weight of the edge (A₃, B)

Computing the score for point \mathbf{x} is given by the recurrence relation:

$$s_x =$$
 max s_y + weight of vertex (y, x) where $y \in Predecessors(x)$

Predecessors (x) – set of vertices that have edges leading to x

•The running time for a graph G(V, E) (V is the set of all vertices and E is the set of all edges) is O(E) since each edge is evaluated once

Alignment: 2 row representation

Given 2 DNA sequences **v** and **w**:

v: ATGTTAT m=7 w: ATCGTAC n=7

Alignment: 2 * k matrix (k > m, n)

letters of **v**letters of **w**



Longest Common Subsequence (LCS) —the simplest form of sequence alignment — allows only insertions and deletions (no mismatches). In the LCS Problem, we scored 1 for matches and 0 for indels; in real analysis we consider penalising indels and mismatches with negative scores.

Given two sequences

$$\mathbf{v} = v_1 v_2...v_m$$
 and $\mathbf{w} = w_1 w_2...w_n$

The LCS of v and w is a sequence of positions in

$$v: 1 \le i_1 < i_2 < ... < i_t \le m$$

and a sequence of positions in

w:
$$1 \le j_1 < j_2 < ... < j_t \le n$$

such that i_t -th letter of ${m v}$ equals to j_t -th letter of ${m w}$ and ${m t}$ is maximal

LCS: Example

i coords: 0 1 2 2 3 3 4 5 6 7 8

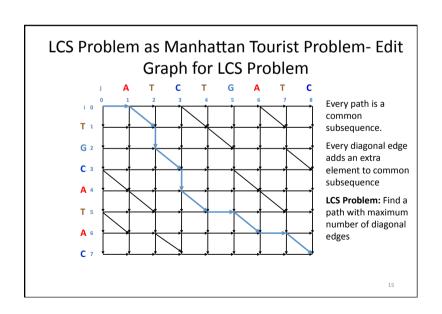
elements of v
elements of w
j coords: 0 0 1 2 3 4 5 5 6 7

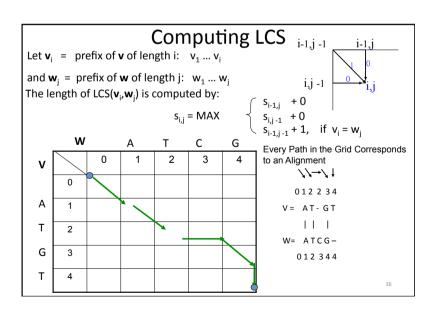
(0,0) \Rightarrow (1,0) \Rightarrow (2,1) \Rightarrow (2,2) \Rightarrow (3,3) \Rightarrow (3,4) \Rightarrow (4,5) \Rightarrow (5,5) \Rightarrow (6,6) \Rightarrow (7,6) \Rightarrow (8,7)

Matches shown in red

positions in v: 2 < 3 < 4 < 6 < 8
positions in w: 1 < 3 < 5 < 6 < 7

Every common subsequence is a path in 2-D grid





The Edit distance between two strings is the minimum number of operations (insertions, deletions, and substitutions) to transform one string into the other

Hamming distance always compares i th letter of \mathbf{v} with i th letter of \mathbf{w} $\mathbf{v} = \underset{|\mathbf{v}|}{\mathsf{ATATATAT}} \underbrace{\mathsf{Just one shift}}_{\mathsf{Make it all line up}} \mathbf{v} = \underbrace{\mathsf{TATATATAT}}_{\mathsf{V}} \mathbf{v} = \underbrace{\mathsf{TATATATAT}}_{\mathsf{V}}$

Hamming distance:

d(v, w)=8
Computing Hamming distance
is a trivial task

Edit distance:

d(v, w)=2 Computing edit distance is a non-trivial task

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Edit Distance: Example

TGCATAT → ATCCGAT in 4 steps

TGCATAT \rightarrow (insert A at front) ATGCATAT \rightarrow (delete 6th T)

 $ATGCATA \rightarrow (substitute G for 5^{th} A)$

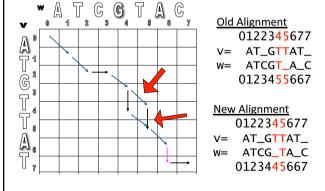
 $ATGCGTA \rightarrow (substitute C for 3^{rd} G)$

ATCCGAT (Done)

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Alignment as a Path in the Edit Graph

Two similar alignments; the score is 5 for both the alignment paths.



, ,

Alignment: Dynamic Programming

$$\begin{vmatrix} s_{i,j} = \\ max \end{vmatrix} \begin{cases} s_{i-1, j-1} + 1 \text{ if } v_i = w_j \\ s_{i-1, j} + 0 \\ s_{i, j-1} + 0 \end{cases}$$

This recurrence corresponds to the Manhattan Tourist problem (three incoming edges into a vertex) with all horizontal and vertical edges weighted by zero.

LCS Algorithm

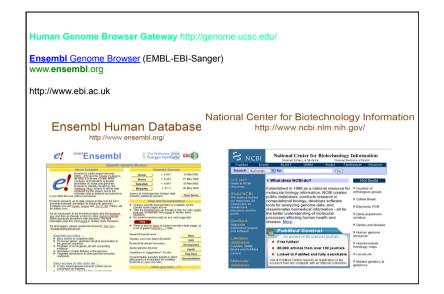
```
LCS(\mathbf{v}, \mathbf{w})
                                                                                         PRINTLCS(\mathbf{b}, \mathbf{v}, i, j)
           s_{t,0} \leftarrow 0
                                                                                          1 if i = 0 or i = 0
3 for j \leftarrow 1 to m
                                                                                                    return
          s_{0,j} \leftarrow 0
                                                                                          3 if b<sub>1.1</sub> = " \"
5 for i \leftarrow 1 to n
                                                                                                    PRINTLCS(\mathbf{b}, \mathbf{v}, i-1, j-1)
            for j \leftarrow 1 to m
                                        s_{i-1,j-1} + 1, if v_i = w_j
                                                                                                           PRINTLCS(b, \mathbf{v}, i-1, j)
                                           if s_{i,j} = s_{i-1,j}
                                  "
\leftarrow" if s_{i,j} = s_{i,j-1}
                                                                                                          PRINTLCS(b, \mathbf{v}, i, j - 1)
                                  ", if s_{i,j} = s_{i-1,j-1} + 1
 9 return (s_{n,m}, \mathbf{b})
```

The above recursive program prints out the longest common subsequence using the information stored in b. The initial invocation that prints the solution to the problem is PRINTLCS(b, v, n,m).

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Fasta Format

>gi|18089116|gb|BC020718.1| Homo sapiens I factor AAATTTCAAAAGAATACCTGGAGTGGAAAAGAGTTCTCAGCAGAGACAAAGACCCCGAACACCTCCAACA $\tt TGAAGCTTCTTCATGTTTTTCTGTTGCTTCCACTTAAGGTTTTTGCAAGGTCACTTATACATC$ ${\tt TCAAGAGGATCTGGTGGAGAAAAAGTGCTTAGCAAAAAAATATACTCACCTCTCCTGCGATAAAGTCTTC}$ TGCCAGCCATGGCAGAGATGCATTGAGGGCACCTGTGTTTGTAAACTACCGTATCAGTGCCCAAAGAATG ${\tt GCACTGCAGTGTGCAACTAACAGGAGAGCTTCCCAACATACTGTCAACAAAAGAGTTTGGAATGTCT}$ CATGGAAATACAGATTCAGAGGGAATAGTTGAAGTAAAACTTGTGGACCAAGATAAGACAATGTTCATAT ${\tt GCAAAAGCAGCTGGAGCATGAGGGAAGCCAACGTGGCCTTGACCTTGGGTTTCAACAAGGTGCTGA}$ TACTCAAAGAAGGTTTAAGTTGTCTGATCTCTCTATAAATTCCACTGAATGTCTACATGTGCATTGCCGA ${\tt GGATTAGAGACCAGTTTGGCTGAATGTACTTTTACTAAGAGAAGAACTATGGGTTACCAGGATTTCGCTG}$ ATGTGGTTTGTTATACACAGAAAGCAGATTCTCCAATGGATGACTTCTTTCAGTGTGTGAATGGGAAATA CATTTCTCAGATGAAAGCCTGTGATGGTATCAATGATTGTGGAGACCAAAGTGATGAACTGTGTTGTAAA $\tt GCATGCCAAGGCAAAGGCTTCCATTGCAAATCGGGTGTTTGCATTCCAAGCCAGTATCAATGCAATGGTG$ $\tt AGGTGGACTGCATTACAGGGGAAGATGAAGTTGGCTGTGCAGGCTTTGCATCTGTGGCTCAAGAAGAAAC$ AGAAATTTTGACTGCTGACATGGATGCAGAAAGAAGACGGATAAAATCATTATTACCTAAACTATCTTGT $\tt GGAGTTAAAAACAGAATGCACATTCGAAGGAAACGAATTGTGGGAGGAAAGCGAGCACAACTGGGAAAAA$ $\tt TGAAGCAAATCTCATTGGATATTTTTAAAGGTCTCCACAGAGTTTATGCCATATTGGAATTTTGTTGTAT$



```
1: BC020718. Reports Homo sapiens | fa...[gi:18089116] Links
                             1249 bp mRNA linear PRI 06-OCT-2003
LOCUS BC020718
DEFINITION Homo sapiens I factor (complement), mRNA (cDNA clone MGC:22501
VERSION BC020718.1 GI:18089116
KEYWORDS MGC.
SOURCE Homo sapiens (human)
FEATURES Location/Qualifier
                                                                              GenBank Format
                  Location/Qualifiers
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            QCNGEVDCITGEDEVGCAGFASVAQEETEILTADMDAERRRIKSLLPKLSCGVKNRMH
            IRRKRIVGGKRAQLGKMKQISLDIFKGLHRVYAILEFCCIILK"
                                                                                                                      24
```

- BioJava www.biojava.org
- BioPerl www.bioperl.org (till now the dominant language in bioinformatics; loosely typed)
- BioPython www.biopython.org
- BioCorba www.biocorba.org (can be used to tying it all together; strongly typed)
- C++ www.ncbi.nlm.nih.gov/IEB/ToolBox/CPP DOC/

BioInformatics 2: sequence alignment

AGGCTATCACCTGACCTCCAGGCCGATGCCC TAGCTATCACGACCGCGGTCGATTTGCCCGAC

-AGGCTATCACCTGACCTCCAGGCCGA--TGCCC---TAG-CTATCAC--GACCGC--GGTCGATTTGCCCGAC

Definition

Given two strings $x = x_1x_2...x_M$, $y = y_1y_2...y_N$,

an alignment is an assignment of gaps to positions 0,..., N in x, and 0,..., N in y, so as to line up each letter in one sequence with either a letter, or a gap in the other sequence

F[i,j-1]

F[i,j]

F[i-1,j-1]

F[I-1,j]

F[i-1,j-1] F[i,j-1] Notice three possible cases: $F(i,j) = F(i-1, j-1) + \cdots$

- 1. x_i aligns to y_i \mathbf{x}_{1} \mathbf{x}_{i-1} \mathbf{x}_{i}
 - y_1, \dots, y_{j-1}, y_j
- 2. x_i aligns to a gap X_1, \dots, X_{i-1}, X_i y₁.....y_i -
- F(i,j) = F(i-1, j) d
- 3. y_i aligns to a gap X₁.....X_i
 - y_1, \dots, y_{j-1}, y_j F(i,j) = F(i, j-1) - d

How do we know which case is correct?

Inductive assumption:

F(i, j-1), F(i-1, j), F(i-1, j-1) are optimal

Then,

 $F(x_i, y_i) = m$, if $x_i = y_i$; -s, if not Where

- The Global Alignment Problem tries to find the longest path between vertices (0,0) and (n,m) in the edit graph.
 - Local alignment \ Global alignment
- The Local Alignment Problem tries to find the longest path among paths between **arbitrary vertices** (i,j) and (i',j') in the edit graph.
- Global Alignment

```
T--cc-c-agt--tatgt-caggggacacg-a-gcatgcaga-gac
AATTGCCGCC-GTCGT-T-TTCAG----CA-GTTATG-T-CAGAT--C
```

 Local Alignment—better alignment to find conserved segment

tccCAGTTATGTCAGgggacacgagcatgcagagac

aattqccqccqtcqttttcaqCAGTTATGTCAGatc

The Needleman-Wunsch Algorithm (Global alignment)

Initialization. F(0, 0) = 0

 $= -j \times d$ F(0, j) $F(i, 0) = -i \times d$

Main Iteration, Filling-in partial alignments

For each | | = 1.....N F(i, j-1) – d $F(i-1, j-1) + s(x_i, y_i)$ [case 3] Ptr(i,j) LEFT if [case 2] DIAG if [case 3]

Termination. F(M, N) is the optimal score, and from Ptr(M, N) can trace back optimal alignment

Complexity: Space: O(mn); Time: O(mn) Filling the matrix O(mn) Backtrace O(m+n)

The Overlap Detection variant

Maybe it is OK to have an unlimited # of gaps in the beginning and end:

----CTATCACCTGACCTCCAGGCCGATGCCCCTTCCGGC GCGAGTTCATCTATCAC--GACCGC--GGTCG------



Changes:

- 1. Initialization For all i, j, F(i, 0) = 0
- Termination

F(0, j) = 0

max_i F(i, N) $F_{OPT} = \max \max_{i} F(M, j)$ The local alignment: Smith-Waterman algorithm

Idea: Ignore badly aligning regions: Modifications to

Needleman-Wunsch

e.g. x = aaaacccccgggg y = cccgggaaccaacc

Initialization: F(0, j) = F(i, 0) = 0

Iteration: F(i, j) = max

$$\begin{cases} 0 \\ F(i-1,j)-d \\ F(i,j-1)-d \\ F(i-1,j-1)+d \end{cases}$$

F(i, j - 1) - d
F(i - 1, j - 1) +
$$s(x_i, y_j)$$

Termination:

1. If we want the best local alignment...

$$F_{OPT} = max_{i,i} F(i, j)$$

2. If we want all local alignments scoring > t

For all i, j find F(i, j) > t, and trace back

Alignment with gaps

Current model: a gap of length n incurs penalty $n\times d$ Gaps usually occur in bunches so we use a convex gap penalty function:



for all n, $\gamma(n + 1) - \gamma(n) \le \gamma(n) - \gamma(n - 1)$

Initialization: same Iteration:

$$F(i, j) = \max \begin{cases} F(i-1, j-1) + s(x_i, y_j) \\ \max_{k=0...i-1} F(k,j) - \gamma(i-k) \\ \max_{k=0...i-1} F(i,k) - \gamma(j-k) \end{cases}$$

Termination: same

Running Time: O(N²M) (assume N>M)

Space: O(NM)

A compromise: affine gaps

To compute optimal alignment, at position i,j, need to "remember" best score if gap is open and best score if gap is not open

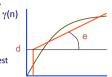
F(i, j):score of alignment $x_1...x_i$ to $y_1...y_i$ if x_i aligns to y_i G(i, j):score if x_i, or y_i, aligns to a gap

Initialization:
$$F(i, 0) = d + (i - 1) \times e$$

 $F(0, i) = d + (i - 1) \times e$

Iteration: $F(i-1, j-1) + s(x_i, y_i)$ F(i, j) = maxF(i - 1, j) - d

G(i, j) = max



 $F(0, j) = d + (j - 1) \times e$

 $G(i-1, j-1) + s(x_i, y_i)$ F(i, j-1) - dG(i, j-1) - eG(i - 1, j) - e

Termination: same

Banded DP

Assume we know that x and y are very similar; If the optimal alignment of x and y has few gaps, then the path of the alignment will be close to the diagonal

Assumption: # gaps(x, y) < k(N)(say N>M)

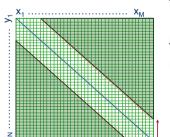
$$X_i$$
| implies | $i - j$ | $< k(N)$
 Y_j



Note that for diagonals, i-j = constant.

Time, Space: $O(N \times k(N)) \ll O(N^2)$

Banded Dynamic Programming



k(N)

Initialization: F(i,0), F(0,j) undefined for i, j > k

Iteration:

For i = 1...M For j = max(1, i - k)...min(N, i+k)

$$F(i, j) = \max \begin{cases} F(i - 1, j - 1) + s(x_i, y_j) \\ F(i, j - 1) - d, \text{ if } j > i - k(N) \\ F(i - 1, j) - d, \text{ if } j < i + k(N) \end{cases}$$

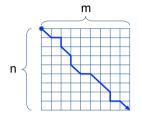
Termination: same

Easy to extend to the affine gap case

Computing Alignment Path Requires Quadratic Memory

Alignment Path

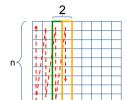
- Space complexity for computing alignment path for sequences of length n and m is O(nm)
- We need to keep all backtracking references in memory to reconstruct the path (backtracking)

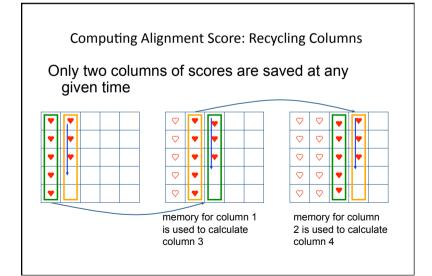


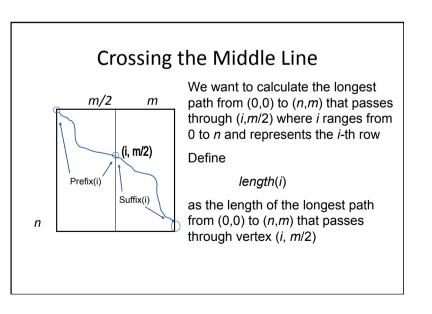
Computing Alignment Score with Linear Memory

Alignment Score

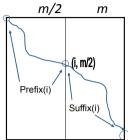
- Space complexity of computing just the score itself is O(n)
- We only need the previous column to calculate the current column, and we can then throw away that previous column once we're done using it







Crossing the Middle Line

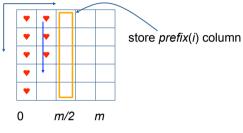


Define (*mid*,*m*/2) as the vertex where the longest path crosses the middle column.

 $length(mid) = optimal length = max_{0 \le i \le n} length(i)$

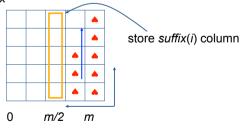
Computing Prefix(i)

- prefix(i) is the length of the longest path from (0,0) to (i,m/2)
- Compute prefix(i) by dynamic programming in the left half of the matrix



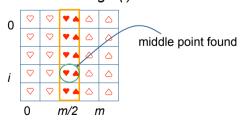
Computing Suffix(i)

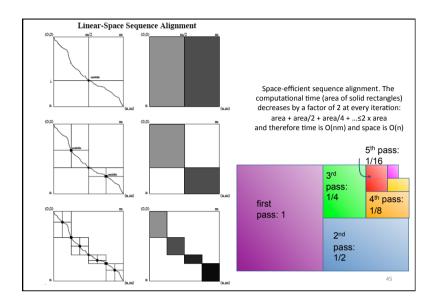
- suffix(i) is the length of the longest path from (i,m/2) to (n,m)
- suffix(i) is the length of the longest path from (n,m) to (i,m/2) with all edges reversed
- Compute suffix(i) by dynamic programming in the right half of the "reversed" matrix



Length(i) = Prefix(i) + Suffix(i)

- Add prefix(i) and suffix(i) to compute length(i):
 length(i)=prefix(i) + suffix(i)
- You now have a middle vertex of the maximum path (i,m/2) as maximum of length(i)





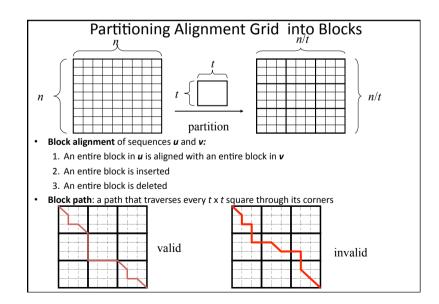
BioInformatics 3: can we align Sequences in Subquadratic Time?

- Partition the n x n grid into blocks of size t x t
- We are comparing two sequences, each of size n, and each sequence is sectioned off into chunks, each of length t
- Sequence $\mathbf{u} = u_1 ... u_n$ becomes

$$|u_1...u_t| |u_{t+1}...u_{2t}| ... |u_{n-t+1}...u_n|$$

and sequence $\mathbf{v} = v_1 ... v_n$ becomes

$$|v_1...v_t| |v_{t+1}...v_{2t}| ... |v_{n-t+1}...v_n|$$



Block Alignment Problem

- Goal: Find the longest block path through an edit graph
- <u>Input</u>: Two sequences, **u** and **v** partitioned into blocks of size *t*. This is equivalent to an *n* x *n* edit graph partitioned into *t* x *t* subgrids
- <u>Output</u>: The block alignment of u and v with the maximum score (longest block path through the edit graph)

Constructing Alignments within Blocks

- To solve: compute alignment score $\beta_{i,j}$ for each pair of blocks $|u_{(i-1)^*t+1}...u_{i^*t}|$ and $|v_{(j-1)^*t+1}...v_{j^*t}|$
- How many blocks are there per sequence?
 (n/t) blocks of size t
- How many pairs of blocks for aligning the two sequences?
 (n/t) x (n/t)
- For each block pair, solve a mini-alignment problem of size t x t

Constructing Alignments within Blocks **Note The Problems of the Problems of

Block Alignment: Dynamic Programming

• Let $s_{i,j}$ denote the optimal block alignment score between the first i blocks of \boldsymbol{u} and first j blocks of \boldsymbol{v}

$$s_{i,j} = \max \begin{cases} s_{i-I,j} - \sigma_{\text{block}} \\ s_{i,j-I} - \sigma_{\text{block}} \\ s_{i-I,j-I} - \beta_{i,j} \end{cases}$$

 $\sigma_{\rm block}$ is the penalty for inserting or deleting an entire block

 $\beta_{i,j}$ is score of pair of blocks in row i and column j.

Block Alignment Runtime

- Indices i,j range from 0 to n/t
- Running time of algorithm is

$$O([n/t]*[n/t]) = O(n^2/t^2)$$

if we don't count the time to compute each β_{ij}

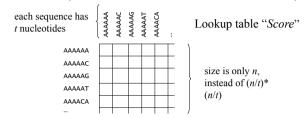
- Computing all $\beta_{i,j}$ requires solving (n/t)*(n/t) mini block alignments, each of size (t*t)
- Computing all $\beta_{i,j}$ takes time $O([n/t]*[n/t]*t*t) = O(n^2)$
- This is the same as dynamic programming
- How do we speed this up?

Four Russians Technique

(Arlazarov, Dinic, Kronrod, Faradzev)

- Let t = log(n), where t is block size, n is sequence size.
- Instead of having (n/t)*(n/t) mini-alignments, construct $4^t \times 4^t$ mini-alignments for all pairs of strings of t nucleotides (huge size), and put in a lookup table.
- However, size of lookup table is not really that huge if t is small. Let $t = (\log n)/4$. Then $4^t \times 4^t = n$

Look-up Table for Four Russians Technique



The new lookup table *Score* is indexed by a pair of *t*-nucleotide strings, so

$$s_{i,j} = \max \begin{cases} s_{i-1,j} - \sigma_{block} \\ s_{i,j-1} - \sigma_{block} \\ s_{i-1,j-1} - Score(i^{th} block of v, j^{th} block of u) \end{cases}$$

Four Russians Speedup Runtime

- Since computing the lookup table *Score* of size n takes O(n) time, the running time is mainly limited by the (n/t)*(n/t) accesses to the lookup table
- Each access takes O(logn) time
- Overall running time: O([n²/t²]*logn)
- Since *t* = log*n*, substitute in:
- O($[n^2/{\log n}]^2 | \log n$) \geq O($n^2/{\log n}$)

So Far...

- We can divide up the grid into blocks and run dynamic programming only on the corners of these blocks
- In order to speed up the mini-alignment calculations to under n², we create a lookup table of size n, which consists of all scores for all tnucleotide pairs
- Running time goes from quadratic, $O(n^2)$, to subquadratic: $O(n^2/\log n)$

Four Russians Speedup for LCS

 Unlike the block partitioned graph, the LCS path does not have to pass through the vertices of the blocks.





block alignment

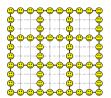
longest common subsequence

Block Alignment vs. LCS

- In block alignment, we only care about the corners of the blocks.
- In LCS, we care about all points on the edges of the blocks, because those are points that the path can traverse.
- Recall, each sequence is of length n, each block is of size t, so each sequence has (n/t) blocks.



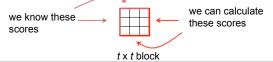




LCS alignment has O(n^2/t) points of interest

Traversing Blocks for LCS

- Given alignment scores s_{i,*} in the first row and scores s_{*,j} in the first column of a t x t mini square, compute alignment scores in the last row and column of the minisquare.
- To compute the last row and the last column score, we use these 4 variables:
 - alignment scores s_i,* in the first row
- alignment scores s*, in the first column
- substring of sequence u in this block (4^t possibilities)
- substring of sequence v in this block (4^t possibilities
- If we used this to compute the grid, it would take quadratic, $O(n^2)$ time, but we want to do better.



Four Russians Speedup

- Build a lookup table for all possible values of the four variables:
 - 1. all possible scores for the first row s_{*i}
 - 2. all possible scores for the first column s*,
 - 3. substring of sequence u in this block (4^t possibilities)
 - 4. substring of sequence v in this block (4^t possibilities)
- For each quadruple we store the value of the score for the last row and last column.
- This will be a huge table, but we can eliminate alignments scores that don't make sense

Reducing Table Size

- Alignment scores in LCS are monotonically increasing, and adjacent elements can't differ by more than 1
- Example: 0,1,2,2,3,4 is ok; 0,1,2,4,5,8, is not because 2 and 4 differ by more than 1 (and so do 5 and 8)
- Therefore, we only need to store quadruples whose scores are monotonically increasing and differ by at most 1

Efficient Encoding of Alignment Scores

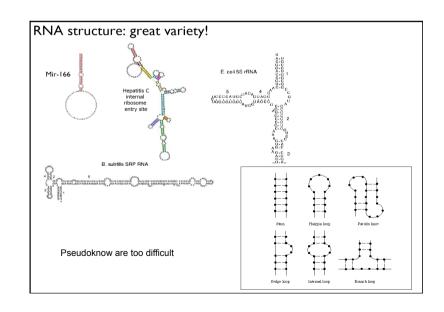
• Instead of recording numbers that correspond to the index in the sequences *u* and *v*, we can use binary to encode the differences between the alignment scores

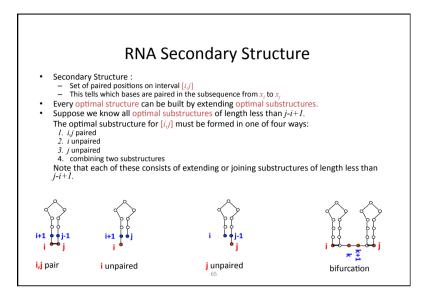
$/\Box$	0	1	L	2		2	3	3	4	ļ	original encoding
		1	1	L	0		1	:	1		binary encoding

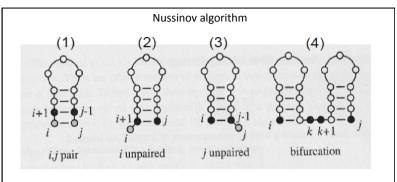
Reducing Lookup Table Size

- 2^t possible scores (t = size of blocks)
- 4^t possible strings
 - -Lookup table size is $(2^t * 2^t)*(4^t * 4^t) = 2^{6t}$
- Let $t = (\log n)/4$;
 - -Table size is: $2^{6((\log n)/4)} = n^{(6/4)} = n^{(3/2)}$
- Time = O($[n^2/t^2]*log n$)
- O($[n^2/\{\log n\}^2] * \log n$) \geq O($n^2/\log n$)

Summary: We take advantage of the fact that for each block of t = log(n), we can pre-compute all possible scores and store them in a lookup table of size $n^{(3/2)}$. We used the Four Russian speedup to go from a quadratic running time for LCS to subquadratic running time: $O(n^2/logn)$.





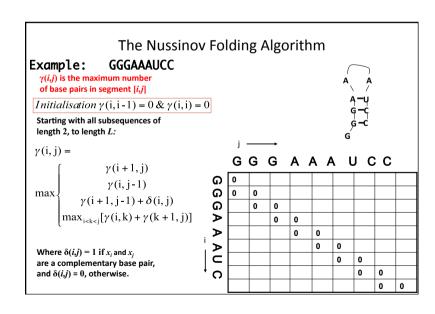


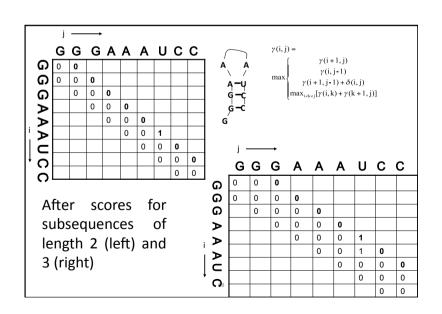
Objective: To find the secondary structure with the maximal number of base pairs under the pseudo-knot exclusion constraint.

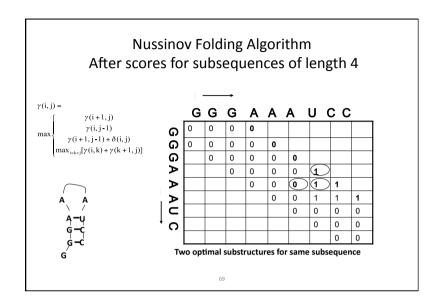
Principle: Recursive procedure (dynamic programming algorithm). Scoring function: sum of base-pair scores, no penalties for loops Optimal score computed from the optimal scores of subsequences.

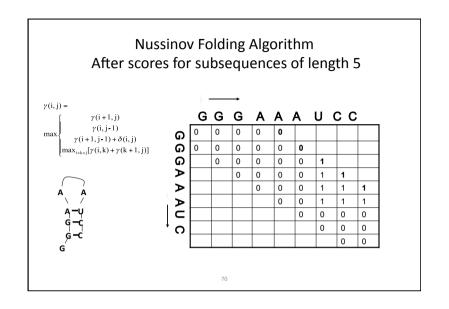
Filling-stage. Scores for subsequences are recursively computed from and recorded in a quadratic table.

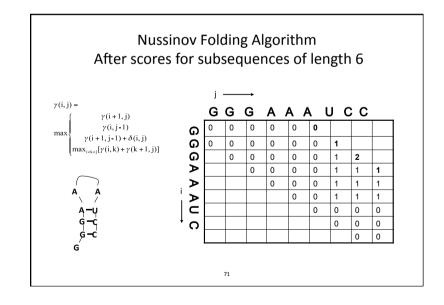
Trace-back: Reconstruction of filling steps indicates optimal structure Time-complexity: O(N³)

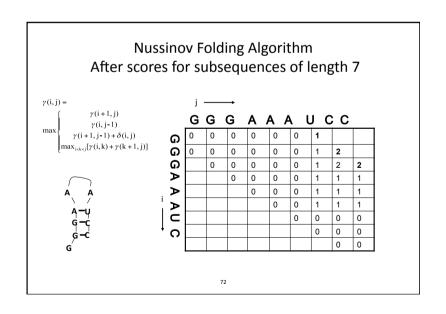


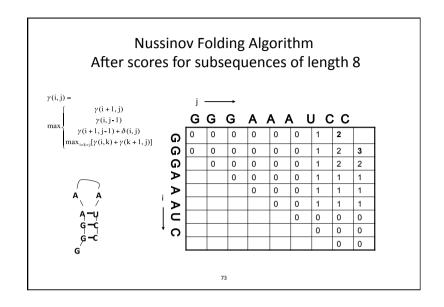


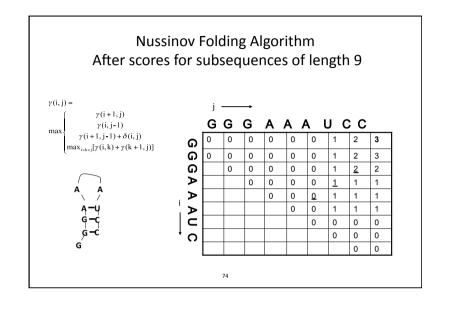


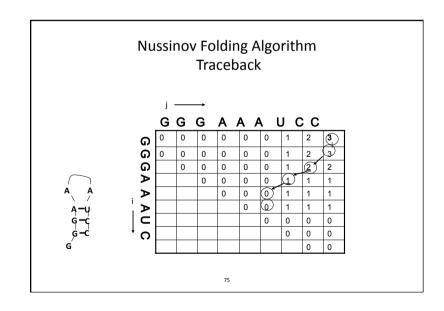


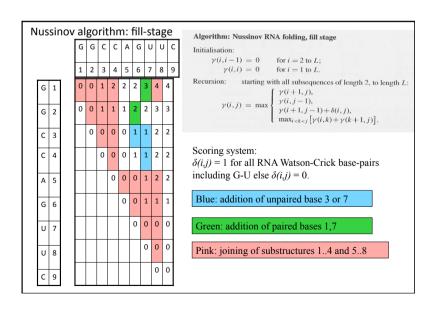


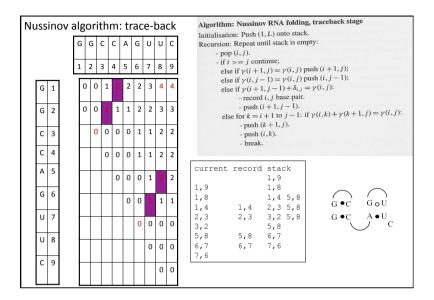








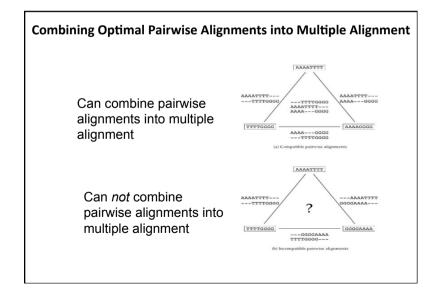




BioInformatics 4 Multiple Alignment: Running Time For N sequences, there are 2^N-1 ways

• For N sequences, there are $2^{N}-1$ ways to extend an alignment; for 3 sequences of length n, the run time is $7n^3$; $O(n^3)$

- For k sequences, build a k-dimensional Manhattan, with run time $(2^k-1)(n^k)$; $O(2^kn^k)$
- Conclusion: dynamic programming approach for alignment between two sequences is easily extended to k sequences but it is impractical due to exponential running time



Progressive Alignment

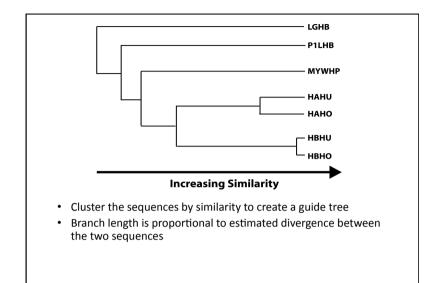
- 1) Align each sequence against each other giving a similarity matrix; Similarity = exact matches / sequence length (percent identity)
- 2) Create Guide Tree using the similarity matrix; Guide tree roughly reflects evolutionary relations
- 3) Progressive Alignment guided by the tree

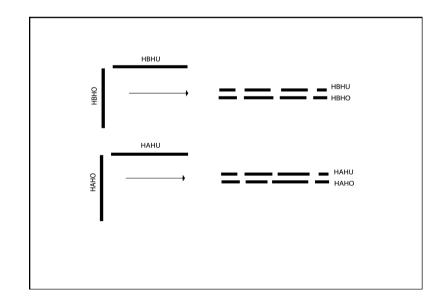
$$v_1$$
 v_2 v_3 v_4 v_2 v_4 v_2 v_4 v_5 v_6 v_7 v_8 v_8 v_9 v_9

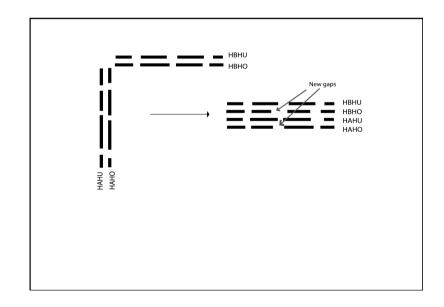
How does it work?

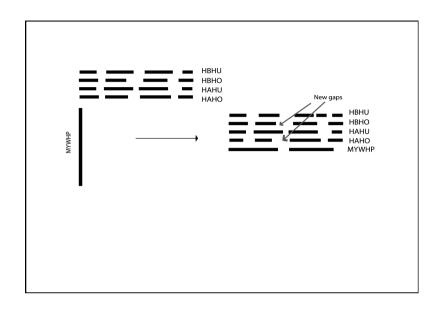
- Starting with a group of 7 sequences from different species
- Do pairwise alignments between all 7 sequences
- Score given for similarity, higher score indicates more similar

	нано	HBHU	НАНО	HBH	MYWHP	P1LHB	LGHB
HAHU							
нвни	21.1						
нано	32.9	19.7					
нвно	20.7	39.0	20.4				
MYWHP	11.0	9.8	10.3	9.7			
P1LHB	9.3	8.6	9.6	8.4	7.0		
LGHB	7.1	7.3	7.5	7.4	7.3	4.3	









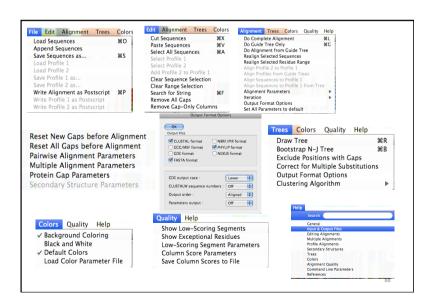
Sum of Pairs Score(SP-Score)

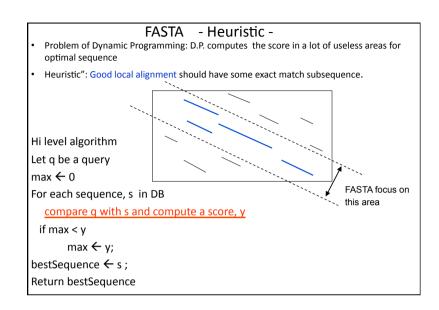
- Consider pairwise alignment of sequences a_i and a_j imposed by a multiple alignment of k sequences
- Denote the score of this suboptimal (not necessarily optimal) pairwise alignment as $s^*(a_{\nu}, a_{i})$
- Sum up the pairwise scores for a multiple alignment:

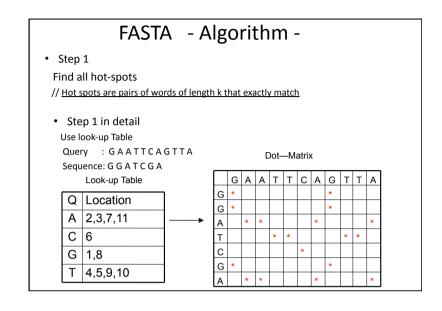
$$s(a_1,...,a_k) = \Sigma_{i,j} s^*(a_i, a_j)$$

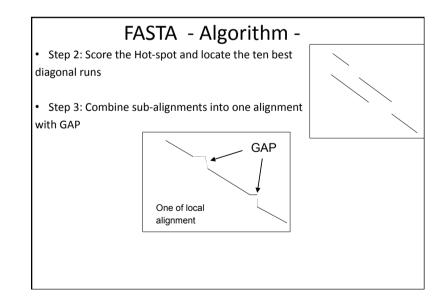
Given a1,a2,a3,a4:
 $s(a1...a4) = \Sigma s^*(ai,aj) = s^*(a1,a2) + s^*(a1,a3) + s^*(a1,a4) + s^*(a2,a3) + s^*(a2,a4) + s^*(a3,a4)$

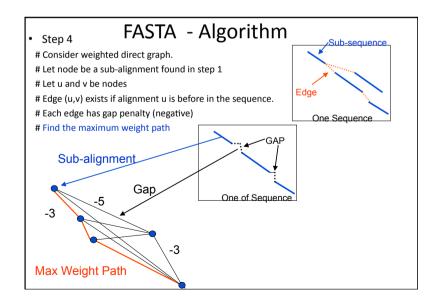












FASTA - Algorithm -

Step 5

Use the dynamic programming in restricted area around the best-score alignment to find out the higher-score alignment larger than the best-score alignment

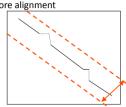
Width of this band is a parameter

Summary of the algorithm

1: Find all hot-spots

 $\ensuremath{/\!/}$ Hot spots is pairs of words of length k that exactly match.

- 2: Score each Hot-spot and locate the ten best diagonal runs.
- 3: Combine sub-alignments into one alignment.
- 4: Score each alignment with gap penalty and pick up the best-score alignment.
- 5: Use the dynamic programming in restricted area around the best-score alignment to find out the alignment greater than the best-score alignment.



Step 1 and 2 // select the best 10 diagonal runs Let n be a sequence from DB O(n) because Step 1 just uses look up table O(n) << O(mn) m,n = 100 to 200 # Step 3 and 4 // compute the MAX Weight Path Let r be the number of sub-alignments. (r = 10) O(r²) < O(m*n) # Step 5 // compute partial D.P. Depends on the restricted area < O(mn)

FASTA - Complexity -

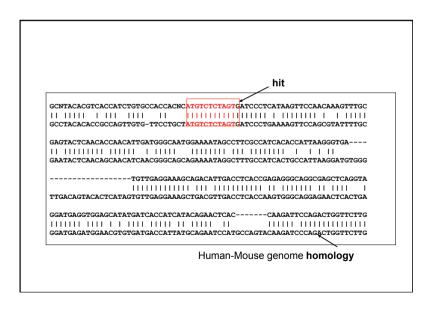
BLAST Basic Local Alignment Search Tool

• Heuristic but evaluating the result statistically.

Homologous sequence are likely to contain a short high scoring word pair, a hit.

BLAST tries to extend it on the both sides to get optimal sequence.

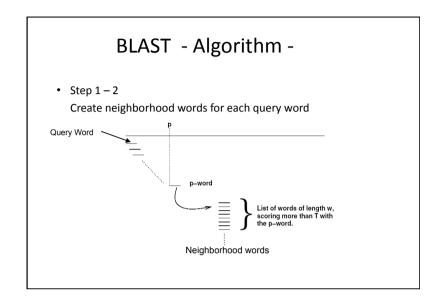




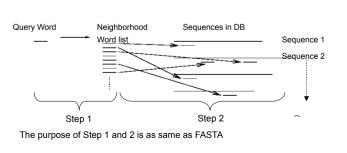
BLAST - Algorithm -

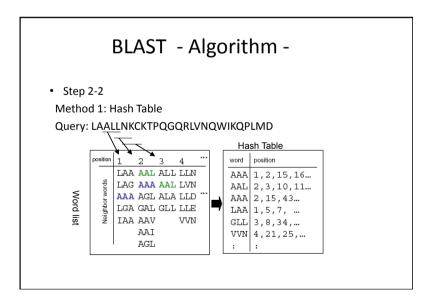
Step 1: preprocessing Query
 Compile the short-hit scoring word list from query.
 The length of query word, w, is 3 for protein search, 11 for DNA.
 Threshold T is 13

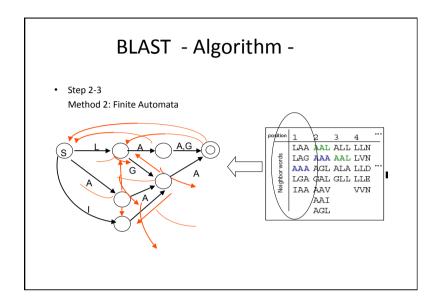












BLAST - Algorithm -

Step 3 (Search optimal alignment)
 Let S be a score of hit-word

For each hit-word, extend ungapped alignment in both directions.

Step 4 (Evaluate the alignment statistically)
 Stop extension when E-value (depending on score S) become less than threshold. The hit-word is called High Scoring Segment Pair. BLAST return it



E-value = the number of HSPs having score S (or higher) expected to occur only by chance.

→ Smaller E-value, more significant in statistics Bigger E-value , by chance

BLAST - Algorithm -

• Step 3 -2

Definition of E-Value

The expected number of HSP with the score at least \$ is:

$$E = K*n*m*e^{-\lambda S}$$

K, λ is constant depending on model

n, m are the length of query and sequence

The probability of finding at least one such HSP is:

$$P = 1 - e^{E}$$

→ If a word is hit by chance (E-value is bigger),

P become smaller.

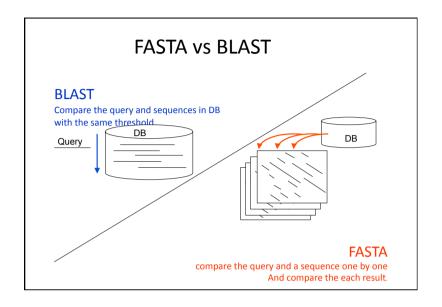
BLAST - Running Time -

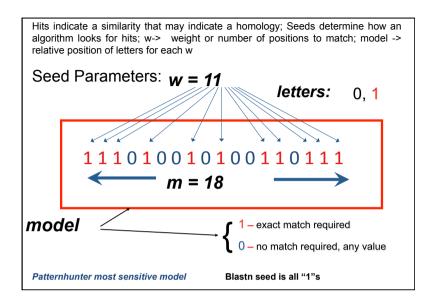
• Running Time on a Pentium 4

The length of Query : 153

DB size : 5997 sequences

Algorithm	Running Time				
D.P	16.989 [s]				
FASTA	0.618 [s]				
BLAST	0.118 [s]				





A spaced seed is formed by two words, one from each input sequence, that match at positions specified by a fixed pattern – a word over symbols # and _ interpreted as a match and a don't care symbol respectively. For example, pattern ##_# specifies that the first, second and fourth positions must match and the third one may contain a mismatch.

PatternHunter was the first method that used carefully designed spaced seeds to improve the sensitivity of DNA local alignment. Spaced seeds have been shown to improve the efficiency of *lossless* filtration for approximate pattern matching, namely for the problem of detecting all matches of a string of length m with q possible substitution errors (an (m, q)-problem). Other software use some specific spaced seeds and random spaced seeds

BLAST uses

"consecutive seeds"

• In BLAST, we often use the consecutive model with weight 11.

 However, it fails to find the alignment in the two sequence.

Dilemma: Sensitivity vs Speed

Similarity

How similar it is between two sequences?

Usually mean that the probability of the same symbol appear in anywhere of two sequences.

Sensitivity

The probability to find a local alignment.

needs shorter seeds

too many random hits, slow computation

Speed – needs longer seeds, lose distant homologies

Specificity

In all local alignments, how many alignments are homologous

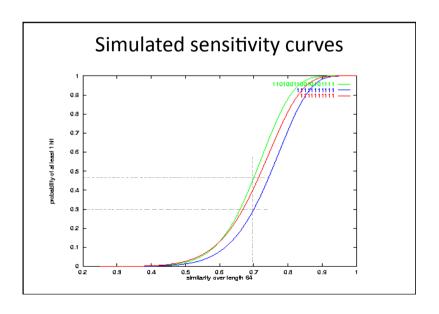
PatternHunter uses "non-consecutive seed"

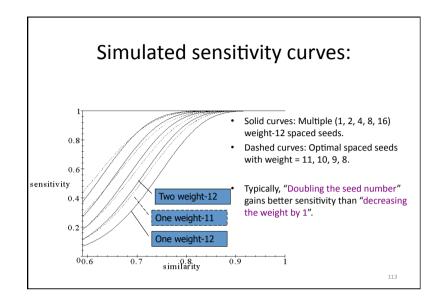
• In PatternHunter, we often use the spaced model with weight 11 and length 18.

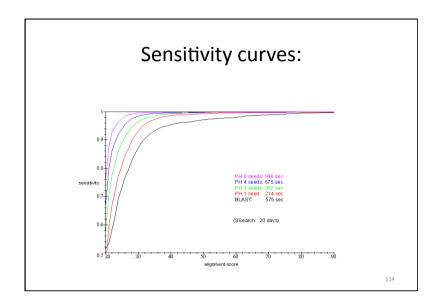
- · Higher hit probability
- Lower expected number of random hits

A trivial comparison between spaced and consecutive seed

- Consider 111 and 1101.
- To fail seed 111, we can use
 - 110110110110...
 - 66.66% similarity
- But we can prove, seed 1101 will hit every region with 61% similarity for sufficient long region.







Proof

- Suppose there is a length 100 region which is not hit by 1101.
- We can break the region into blocks of 1^a0^b. Besides the last block, the other blocks have the following few cases:
 - -10^{b} for b>=1
 - 110^b for b>=2
 - 1110^b for b>=2
- In each block, similarity <= 3/5.
- The last block has at most 3 matches.
- So, in total there are at most 61 matches in 100 positions. The similarity is <=61%.

Formalize

• Given i.i.d. sequence (homology region) with Pr(1) =p and Pr(0)=1-p for each bit:

110011101110110101111011011111011101 111*1**1*11**111

- Which seed is more likely to hit this region:
 - BLAST seed: 11111111111
 - Spaced seed: 111*1**1*11*111

Expect Less, Get More

 Lemma: The expected number of hits of a weight W length M seed model within a length L region with homology level p is

 $(L-M+1)p^{W}$ Proof. E(#hits) = $\sum_{i=1,...,L-M+1} p^{W}$

- Example: In a region of length 64 with p=0.7
 - Pr(BLAST seed hits)=0.3E(# of hits by BLAST seed)=1.07
 - Pr(optimal spaced seed hits)=0.466, 50% more
 E(# of hits by spaced seed)=0.93, 14% less

Why Is Spaced Seed Better?

A wrong, but intuitive, proof: seed s, interval I, similarity p

E(#hits) = Pr(s hits) E(#hits | s hits)

Thus:

Pr(s hits) = Lpw / E(#hits | s hits)

For optimized spaced seed, E(#hits | s hits)
111*1**1*11*111 Non overlap Prob

111*1**1*11*111 6 p⁶
111*1**1*11*111 6 p⁶
111*1**1*11*111 6 p⁶
111*1**1*11*111 7 p⁷

....

- For spaced seed: the divisor is $1+p^6+p^6+p^6+p^7+...$
- For BLAST seed: the divisor is bigger: $1+p+p^2+p^3+...$

Observations of spaced seeds

- Seed models with different shapes can detect different homologies.
- Two consequences:
 - Some models may detect more homologies than others
 - · More sensitive homology search
 - PatternHunter I
 - Can use several seed models simultaneously to hit more homologies
 - Approaching 100% sensitive homology search
 - PatternHunter II

Example of a hit using a spaced seed:

BLAST: redundant hits

TTGACCTCACC? ||||||||||? TTGACCTCACC? 11111111111

This results in > 1 hit and creates clusters of redundant hits

■ PatternHunter

CAA?A??A?C??TA?TGG? |||?|??|?|?||?||? CAA?A??A?C??TA?TGG? 111010010100110111 111010010100110111

This results in very few redundant hits

Why is PH better?

BLAST may also miss a hit

GAGTACTCAACACCAACATTAGTGGGCAATGGAAAAT GAATACTCAACAGCAACATCAATGGGCAGCAGAAAAT

9 matches

In this example, despite a clear homology, there is no sequence of continuous matches longer than length 9. BLAST uses a length 11 and because of this, BLAST does not recognize this as a hit!

Resolving this would require reducing the seed length to 9, which would have a damaging effect on speed

PatternHunter II:

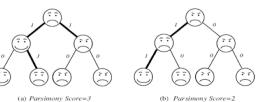
-- Smith-Waterman Sensitivity, BLAST Speed (Li, Ma, Kisman, Tromp, J. Bioinfo Comput, Biol, 2004)

- The biggest problem for BLAST was low sensitivity (and low speed). Massive parallel machines are built to do S-W exhaustive dynamic programming.
- Spaced seeds give PH a *unique* opportunity of using several optimal seeds to achieve optimal sensitivity, this was not possible by BLAST technology.
- PH II has with multiple optimal seeds.
- PH II approaches Smith-Waterman sensitivity, and 3000 times faster.

BioInformatics 5 Molecular Evolution: Fitch and Sankoff Algorithms Terminal Nodes Branches or Lineages Ancestral Node or ROOT of **Internal Nodes** the Tree rooted ((A,(B,C)),(D,E)) = The above phylogeny as nested parentheses

Parsimony Approach

- Applies Occam's razor principle to identify the simplest explanation for the data
- Assumes observed character differences resulted from the fewest possible mutations
- Seeks the tree that yields lowest possible parsimony score - sum of cost of all mutations found in the tree



(a) Parsimony Score=3

Small Parsimony

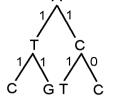
- Input: Tree T with each leaf labeled by an m-character string.
- <u>Output</u>: Labeling of internal vertices of the tree *T* minimizing the parsimony score.
- We can assume that every leaf is labeled by a single character, because the characters in the string are independent.

Weighted Small Parsimony Problem

- Input: Tree T with each leaf labeled by elements of a k-letter alphabet and a $k \times k$ scoring matrix (δ_{ii})
- Output: Labeling of internal vertices of the tree *T* minimizing the weighted parsimony score.
- For Small Parsimony problem, the scoring matrix is based on Hamming distance dH(v, w) = 0 if v=w; dH(v, w) = 1 otherwise

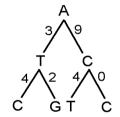
125

Unweighted vs. Weighted A A A A A B B C Small F



	Α	Т	G	С
Α	0	1	1	1
Т	1	0	1	1
G	1	1	0	1
O	1	1	1	0

Small Parsimony Score: 5



	Α	Т	G	С
Α	0	3	4	9
Т	3	0	2	4
G	4	2	0	4
С	9	4	4	0

Weighted Parsimony Score: 22

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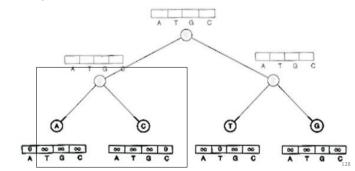
Sankoff Algorithm: Dynamic Programming

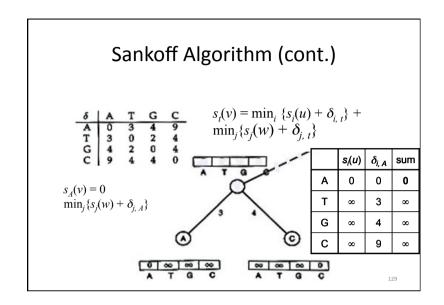
- Calculate and keep track of a score for every possible label at each vertex
 - $-s_t(v)$ = minimum parsimony score of the **subtree** rooted at vertex v if v has character t
- The score at each vertex is based on scores of its children:
 - $-s_t(parent) = \min_i \{s_i(left child) + \delta_{i,t}\} + \min_i \{s_i(left child) + \delta_{i,t}\}$

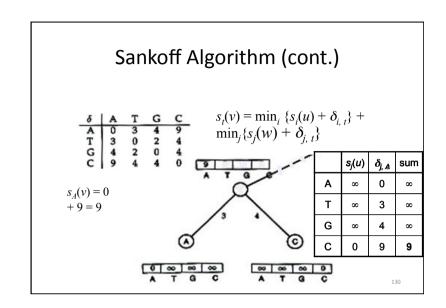
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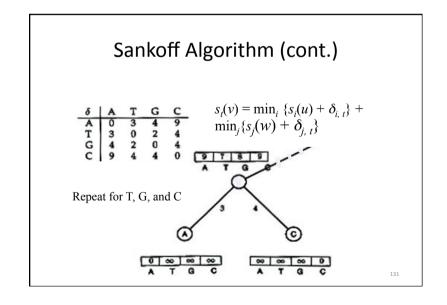
Sankoff Algorithm (cont.)

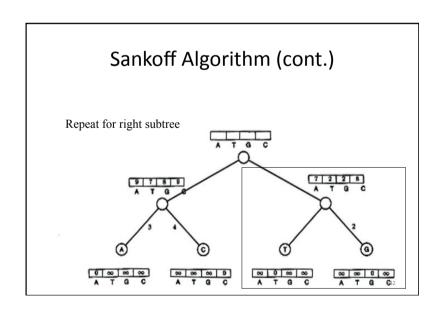
- · Begin at leaves:
 - If leaf has the character in question, score is 0
 - Else, score is ∞

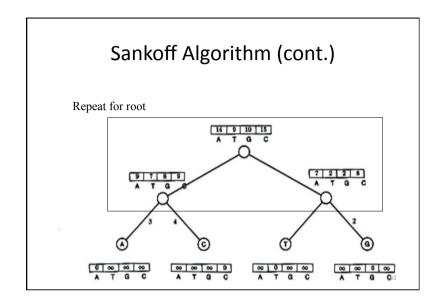


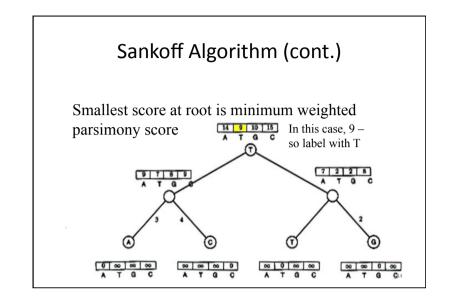


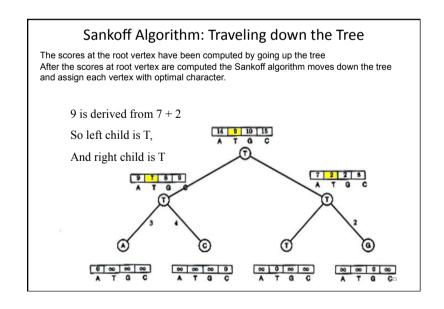


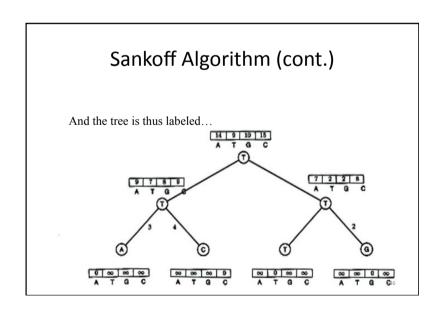








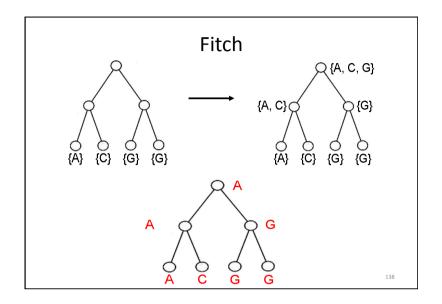




Fitch Algorithm

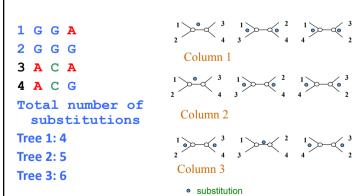
- · Solves Small Parsimony problem;
- Dynamic programming in essence;
- Assign a set of possible letters to every vertex, traversing the tree from leaves to root
- Each node's set is the combination of its children's sets (leaves contain their label)
 - E.g. if the node we are looking at has a left child labeled {A, C} and a right child labeled {A, T}, the node will be given the set {A}
- 2) Assign labels to each vertex, traversing the tree from root to leaves
- Assign root arbitrarily from its set of letters
- For all other vertices, if its parent's label is in its set of letters, assign it its parent's label
- Else, choose an arbitrary letter from its set as its label

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Parsimony Example

Say we have an alignment of 4 DNA sequences of 3 bases each



Sankoff vs. Fitch

- The Sankoff algorithm gives the same set of optimal labels as the Fitch algorithm
- For Sankoff algorithm, character t is *optimal* for vertex v if $s_t(v) = \min_{1 \le i \le k} s_i(v)$
 - Denote the set of optimal letters at vertex v as S(v)
 - If S(left child) and S(right child) overlap, S(parent) is the intersection
 - Else it's the union of s(left child) and s(right child)
 - · This is also the Fitch recurrence
- Complexity:
- Fitch: O(mnk); Sankoff: O(mnk²)
- m characters, n leaves, k possible values for a character

Large Parsimony Problem

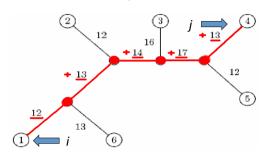
- <u>Input:</u> An n x m matrix M describing n species, each represented by an m-character string
- Output: A tree T with n leaves labeled by the n rows of matrix M, and a labeling of the internal vertices such that the parsimony score is minimized over all possible trees and all possible labelings of internal vertices
- Possible search space is huge, especially as n increases
- (2n 3)!! possible rooted trees
- (2n 5)!! possible unrooted trees
- Problem is NP-complete; Exhaustive search only possible w/ small n(< 10)

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BioInformatics 6

Distance in Trees

 $d_{ii}(T)$ – tree distance between i and j



$$d_{1.4} = 12 + 13 + 14 + 17 + 13 = 69$$

1.12

Edit Distance vs. Tree Distance

- Given *n* sequences, we can compute the *n* x *n* **distance matrix** D_{ii}
- D_{ij} may be defined as the edit distance between a gene in species i and species j, where the gene of interest is sequenced for all n species.

 D_{ii} – edit distance between i and j

· Note the difference with

 $d_{ii}(T)$ – tree distance between i and j

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Fitting Distance Matrix

- Given n sequences, we can compute the n x n distance matrix D_{ii}
- Evolution of these sequences is described by a tree that we don't know.
- We need an algorithm to construct a tree that best fits the distance matrix D_{ii}

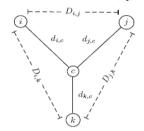
Lengths of path in an (unknown) tree T

• Fitting means $D_{ij} = d_{ij}(T)$

Edit distance between species (known)

Reconstructing a 3 Leaved Tree

- Tree reconstruction for any 3x3 matrix is straightforward
- We have 3 leaves i, j, k and a center vertex c



Observe:

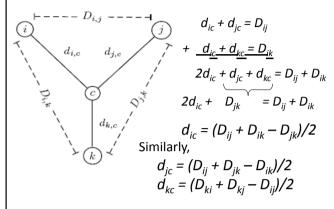
$$d_{ic} + d_{jc} = D_{ij}$$

$$d_{ic} + d_{kc} = D_{ik}$$

$$d_{jc} + d_{kc} = D_{jk}$$

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Reconstructing a 3 Leaved Tree (cont'd)



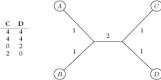
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Trees with > 3 Leaves

- A tree with *n* leaves has 2*n*-3 edges
- This means fitting a given tree to a distance matrix
 D requires solving a system of "n choose 2" equations with 2n-3 variables
- This is not always possible to solve for n > 3

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Additive Distance Matrices



NON-ADDITIVE otherwise



?

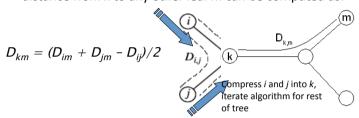
Distance Based Phylogeny Problem

- <u>Goal</u>: Reconstruct an evolutionary tree from a distance matrix
- Input: n x n distance matrix D_{ii}
- Output: weighted tree T with n leaves fitting D
- If *D* is additive, this problem has a solution and there is a simple algorithm to solve it

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Using Neighboring Leaves to Construct the Tree

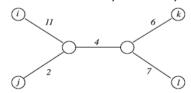
- Find *neighboring leaves i* and *j* with parent *k*
- Remove the rows and columns of i and i
- Add a new row and column corresponding to *k*, where the distance from *k* to any other leaf *m* can be computed as:



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Finding Neighboring Leaves

- · Closest leaves aren't necessarily neighbors
- *i* and *j* are neighbors, but $(d_{ii} = 13) > (d_{ik} = 12)$



 Finding a pair of neighboring leaves is a nontrivial problem!

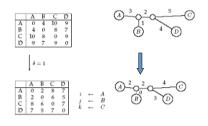
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Degenerate Triples

- A degenerate triple is a set of three distinct elements 1<=i,j,k<=n where D_{ij}
 + D_{ik} = D_{ik}
- Element j in a degenerate triple i,j,k lies on the path from i to k (or is attached to this path by an edge of length 0).
- If distance matrix D has a degenerate triple i,j,k then j can be "removed" from D thus reducing the size of the problem.
- If distance matrix D does not have a degenerate triple i,j,k, one can "create" a degenerative triple in D by shortening all hanging edges (in the tree).

Shortening Hanging Edges to Produce Degenerate Triples

• Shorten all "hanging" edges (edges that connect leaves) until a degenerate triple is found



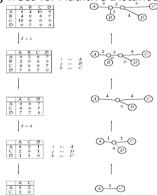
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Finding Degenerate Triples

- If there is no degenerate triple, all hanging edges are reduced by the same amount δ , so that all pair-wise distances in the matrix are reduced by 2δ .
- Eventually this process collapses one of the leaves (when δ = length of shortest hanging edge), forming a degenerate triple i,j,k and reducing the size of the distance matrix D.
- The attachment point for *j* can be recovered in the reverse transformations by saving *D_{ij}* for each collapsed leaf.

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Reconstructing Trees for Additive Distance Matrices



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AdditivePhylogeny Algorithm

- 1. AdditivePhylogeny(*D*)
- 2. **if** D is a 2×2 matrix
- T = tree of a single edge of length $D_{1,2}$
- 4. return T
- 5. **if** D is non-degenerate
- 6. δ = trimming parameter of matrix D
- 7. **for** all $1 \le i \ne j \le n$
- 8. $D_{ij} = D_{ij} 2\delta$
- 9. else
- 10. $\delta = 0$

AdditivePhylogeny (cont'd)

- 1. Find a triple *i*, *j*, *k* in *D* such that $D_{ii} + D_{ik} = D_{ik}$
- $2. x = D_{ii}$
- 3. Remove j^{th} row and j^{th} column from D
- 4. T = AdditivePhylogeny(D)
- 5. Add a new vertex *v* to *T* at distance *x* from *i* to *k*
- 6. Add j back to T by creating an edge (v,j) of length 0
- 7. **for** every leaf / in T
- 8. **if** distance from I to v in the tree $\neq D_{I,i}$
- 9. output "matrix is not additive"
- 10. return
- 11. Extend all "hanging" edges by length δ
- 12. **return** *T*

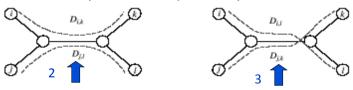
The Four Point Condition

- AdditivePhylogeny provides a way to check if distance matrix D is additive
- An even more efficient additivity check is the "four-point condition"
- Let $1 \le i,j,k,l \le n$ be four distinct leaves in a tree

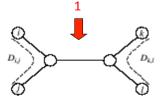
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The Four Point Condition (cont'd)

Compute: 1. $D_{ij} + D_{kl}$, 2. $D_{ik} + D_{jl}$, 3. $D_{il} + D_{jk}$



2 and 3 represent the same number: the length of all edges + the middle edge (it is counted twice)



1 represents a smaller number: the length of all edges – the middle edge

The Four Point Condition: Theorem

- The four point condition for the quartet *i,j,k,l* is satisfied if two of these sums are the same, with the third sum smaller than these first two
- Theorem: An n x n matrix D is additive if and only if the four point condition holds for every quartet 1 ≤ i, j, k, l ≤ n

Least Squares Distance Phylogeny Problem

• If the distance matrix *D* is NOT additive, then we look for a tree *T* that approximates *D* the best:

Squared Error: $\sum_{i,j} (d_{ij}(T) - D_{ij})^2$

- Squared Error is a measure of the quality of the fit between distance matrix and the tree: we want to minimize it.
- Least Squares Distance Phylogeny Problem: finding the best approximation tree T for a non-additive matrix D (NP-hard).

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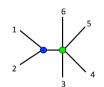
Neighbor Joining Algorithm

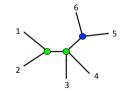
- In 1987 Naruya Saitou and Masatoshi Nei developed a neighbor joining algorithm for phylogenetic tree reconstruction
- Finds a pair of leaves that are close to each other but far from other leaves: implicitly finds a pair of neighboring leaves
- Advantages: works well for additive and other non-additive matrices, it does not have the flawed molecular clock assumption (see UPGMA).

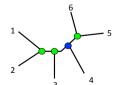
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Neighbor Joining Algorithm







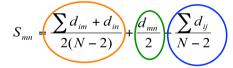


- Sequences chosen to give best least-squares estimate of branch length
- Begin with star topology no neighbors have been joined

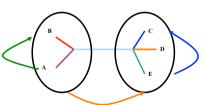
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Neighbor Joining

- · Tree modified by joining pairs of sequences
- Pair is chosen by calculating sum of branch lengths, S, for the corresponding tree (joining m and n; i are the other nodes); d_{ij} are the distance matrix values.



(If A and B are joined):



Neighbour Joining Algorithm

- Identify i,j as neighbours if their "distance" is the shortest.
- Combine i,j into a new node u.
- Update the distance matrix.
- Distance of u from the rest of the tree is calculated
- If only 3 nodes are left finish.

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Let's define a new parameter called r. This r is computed for each node represented in the current matrix.

$$r_i = \sum_{k=1}^N d_{ik}$$

(i represents the node for which we are computing r now)

Next, we define a rate corrected matrix (M), in which the elements are defined by:

$$M_{ii} = d_{ii} - (r_i + r_i) / (N-2)$$

And this is now our new parameter; i and j represent numbers of nodes. At each stage, we look for the i and j which give us the minimal $M_{ij}\cdot$

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Why does using S_{ii} give us $O(n^5)$ complexity?

- 1. If N represents the number of leaves at each stage, we compute $S_{12}, S_{13}, S_{14}, ... S_{23}, ... S_{(N-1,N)}$, which about N^2 computations.
- We have N stages (we start off with a matrix of N x N, and at each stage the matrix is reduced by 1) → so we've reached N x N² = N³.
- 3. Each S_{ij} we compute, requires us to sum over all of the elements in the matrix once again, N^2 computations, so now we've reached $N \times N^2 \times N^2 = N^5$

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Why does M_{ij} give us complexity of $O(N^3)$?

In M_{ii} we only have to evaluate r_i and r_i each round. This can

be achieved in O(1), if we compute these terms *once* at the

beginning of the round.

Thus, if we return to the list that built the complexity of Sii,

Stage 1 and 2 remain with the same complexity \rightarrow O(N³).

Stage 3 is reduced to O(1), and thus we get a total of O(N³).

UPGMA: Unweighted Pair Group Method with Arithmetic Mean

- UPGMA is a clustering algorithm that:
 - computes the distance between clusters using average pairwise distance
 - assigns a *height* to every vertex in the tree, effectively assuming the presence of a molecular clock and dating every vertex
 - The algorithm produces an ultrametric tree: the distance from the root to any leaf is the same (this corresponds to a constant molecular clock: leaves in the tree are assumed to accumulate mutations (and thus evolve) at the same rate.

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Clustering in UPGMA

Given two disjoint clusters C_p , C_j of sequences,

$$d_{ij} = \frac{1}{|C_i| \times |C_i|} \sum_{\{p \in C_i, q \in C_j\}} d_{pq}$$

Note that if $C_k = C_i \cup C_j$, then distance to another cluster C_i is:

$$d_{kl} = \frac{d_{il} |C_i| + d_{jl} |C_j|}{|C_i| + |C_j|}$$

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UPGMA Algorithm

Initialization:

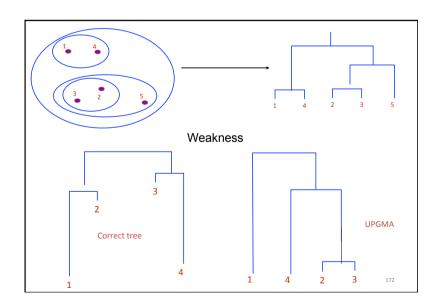
Assign each x_i to its own cluster C_i Define one leaf per sequence, each at height 0

Iteration:

Find two clusters C_i and C_j such that d_{ij} is min Let $C_k = C_i \cup C_j$ Add a vertex connecting C_i , C_j and place it at height $d_{ij}/2$ Delete C_i and C_i

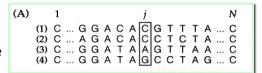
Termination:

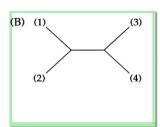
When a single cluster remains

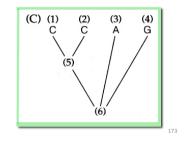


BioInformatics 7: Likelihood for a tree

Aligned sequences for 4 taxa; What is the prob that this tree generated the data?







Calculating L for a tree

- Root the tree at any internal node (models are time-reversible)
- Assumption of independence allows to calculate L for each site separately
- · Then combine the likelihoods into a total value at the end
- To calculate L for some site j, we must consider all possible scenarios by which the tip sequences could have evolved; Specifically, the root (6) may have had A, C, T, or G.
- For each of these possibilities, the other internal node (5) also might have possessed any of the 4 nucleotides

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Calculating L for a tree

• Thus, there are 4x4=16 possibilities to consider

(D)
$$L_{(j)} = \operatorname{Prob} \begin{pmatrix} C & C & A & G \\ A & A & A \end{pmatrix} + \operatorname{Prob} \begin{pmatrix} C & C & A & G \\ C & A & G \end{pmatrix}$$

$$+ \qquad \dots \qquad + \operatorname{Prob} \begin{pmatrix} C & C & A & G \\ G & A & G \\ C & A & G \end{pmatrix}$$

$$+ \qquad \dots \qquad + \operatorname{Prob} \begin{pmatrix} C & C & A & G \\ G & A & G \\ C & A & G \end{pmatrix}$$

Calculating L for a tree

- Calculate the probability of each and sum them to obtain the total probability for site j
- Assume that the changes along each branch are independent (Markov model)
- Thus, the Pr of any single scenario is equal to the product of the Pr of the changes required by that scenario

(E)
$$L = L_{(1)} \cdot L_{(2)} \cdot \dots \cdot L_{(N)} = \prod_{j=1}^{N} L_{(j)}$$

Calculating L for a tree

- Because the Probability of any single observation is an extremely small number, we evaluate the log of the likelihood instead
- Probabilities are accumulated as the sum of logs of the single-site likelihoods

(F)
$$\ln L = \ln L_{(1)} + \ln L_{(2)} + ... + \ln L_{(N)} = \sum_{j=1}^{N} \ln L_{(j)}$$

Typical assumptions of ML substitution models

The probability of any change is independent of the prior history of the site (a Markov Model) Substitution probabilities do not change with time or over the tree (a homogeneous Markov process)

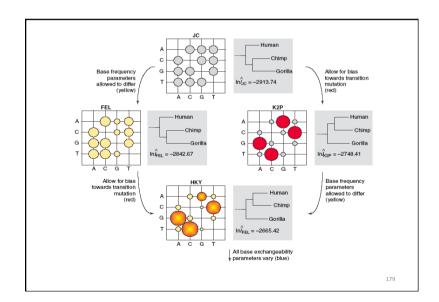
Change is time reversible e.g. the rate of change of A to T is the same as T to A

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Typical assumptions of ML substitution models

- The probability of any change is independent of the prior history of the site (a Markov Model)
- Substitution probabilities do not change with time or over the tree (a homogeneous Markov process)
- Change is time reversible e.g. the rate of change of A to T is the same as T to A

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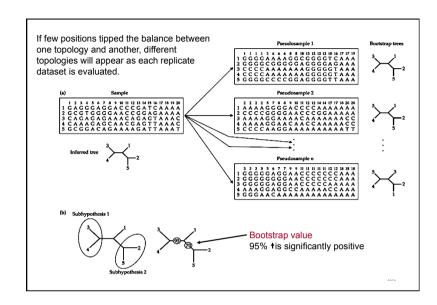


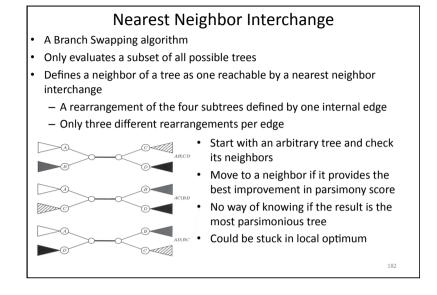
Bootstrapping to get the best trees

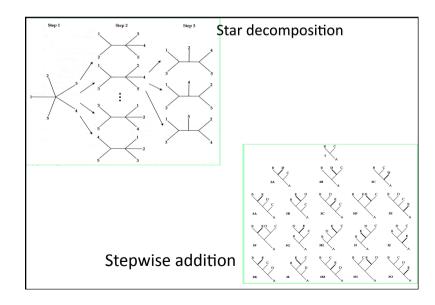
Main outline of algorithm:

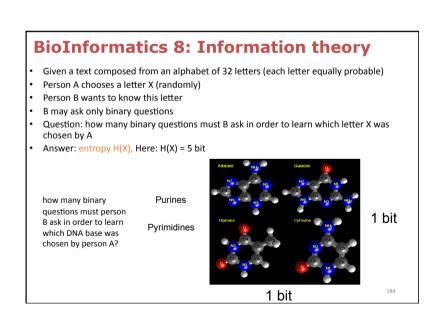
- 1. Select random columns from a multiple alignment one column can then appear several times
- 2. Build a phylogenetic tree based on the random sample from (1)
- 3. Repeat (1), (2) many (say, 1000) times
- 4. Output the tree that is constructed most frequently

Jackknifing: Similar to bootstrapping; Generates a number of randomized data sets that are sampled without replacements -> each data set is smaller than the original









Conditional entropy

- Given a text composed from an alphabet of 32 letters (each letter equally probable)
- Person A chooses a letter X (randomly)
- · Person B wants to know this letter
- · B may ask only binary questions
- · A may tell B the letter Y preceding X
- Question: how many binary questions must B ask in order to learn which letter X was chosen by A
- Answer: conditional entropy H(X|Y); H(X|Y) <= H(X)
- In worst case namely if B ignores all "information" in Y about X B needs H(X) binary questions
- Under no circumstances should B need more than H(X) binary questions
- Knowledge of Y cannot increase the number of binary questions

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Mutual information

Compare two situations:

- I: learn X without knowing Y
- II: learn X with knowing Y
- How many binary questions in case of I? → H(X)
- How many binary questions in case of II? → H(X|Y)
- Question: How many binary questions could B save in case of II?
- Question: How many binary questions could B save by knowing Y?
- Answer: I(X;Y) = H(X) H(X|Y) where I(X;Y) = information in Y about X
- H(X|Y) <= H(X) → I(X;Y) >= 0
- Example 1: random sequence composed of A, C, G, T (equally probable)
- H(X) = 2 bit; H(X|Y) = 2 bit; I(X;Y) = H(X) H(X|Y) = 0 bit
- Example 2: deterministic sequence ... ACGT ACGT ACGT ACGT ...
- H(X) = 2 bit; H(X|Y) = 0 bit; I(X;Y) = H(X) H(X|Y) = 2 bit

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Identifying Motifs and generating Motif Logo

- Genes are turned on or off by regulatory proteins;
- These proteins bind to a short DNA sequence called a motif (TFBS)
- So finding the same motif in multiple genes' regulatory regions suggests a regulatory relationship amongst those genes
- Motifs can mutate on non important bases
- The five motifs in five different genes have mutations in position 3 and 5
- Representations called motif logos illustrate the conserved and variable regions of a motif



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Information Content of a DNA Motif

Information at position j: $I_i = H_{before} - H_{after}$

Motif probabilities: p_k (k = A, C, G, T)

Background probabilities: $\mathbf{q}_{k} = \frac{1}{4}$ (k = A, C, G, T)

$$I_{j} = -\sum_{k=1}^{4} q_{k} \log_{2} q_{k} - \sum_{k=1}^{4} p_{k} \log_{2} p_{k} = 2 - H_{j}$$

$$I_{\text{motif}} = \sum_{j=1}^{w} I_j = 2w - H_{\text{motif}}$$
 (motif of width w bases)

Log base 2 gives entropy/information in 'bits'

Sequence Logos http://weblogo.berkeley.edu/

Entropy estimation of alignment

• Define frequencies for the occurrence of each letter in each column of multiple alignment

$$\begin{array}{ll} p_{A} = 1, \, p_{T} = p_{G} = p_{C} = 0 \; (1^{st} \; column) & \text{AAA} \\ p_{A} = 0.75, \, p_{T} = 0.25, \, p_{G} = p_{C} = 0 \; (2^{nd} \; column) & \text{AAA} \\ p_{A} = 0.50, \, p_{T} = 0.25, \, p_{C} = 0.25 \; p_{G} = 0 \; (3^{rd} \; column) & \text{ATC} \end{array}$$

· Compute entropy of each column

$$-\sum_{X=A,T,G,C} p_X \log p_X$$

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Multiple Alignment: Entropy Score

Best case

$$entropy \begin{pmatrix} A \\ A \\ A \\ A \end{pmatrix} = 0$$

Worst case

entropy
$$\begin{pmatrix} A \\ T \\ G \\ C \end{pmatrix} = -\sum \frac{1}{4} \log \frac{1}{4} = -4(\frac{1}{4}*-2) = 2$$

Entropy for a multiple alignment is the sum of entropies of its columns:

 Σ over all columns Σ $_{X=A,T,G,C}$ $p_X \log p_X$

Information Content

- In a positional weight matrix , PWM, convert frequencies to probabilities
- PWM W: $W_{\beta k}$ = frequency of base β at position k
- q_{β} = frequency of base β by chance
- Information content of W:

$$\sum_{k} \sum_{\beta \in \{A,C,G,T\}} W_{\beta k} \log \frac{W_{\beta k}}{q_{\beta}}$$

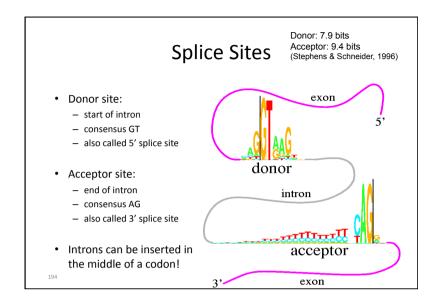
- If $W_{\beta k}$ is always equal to q_{β} , i.e., if W is similar to random sequence, information content of W is 0.
- If W is different from q, information content is high.

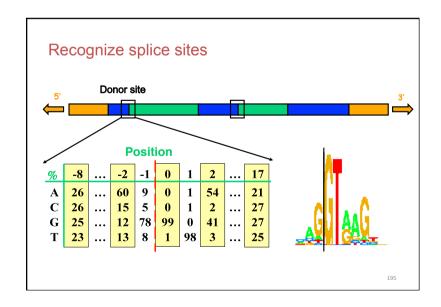
Entropy of an Alignment: Example

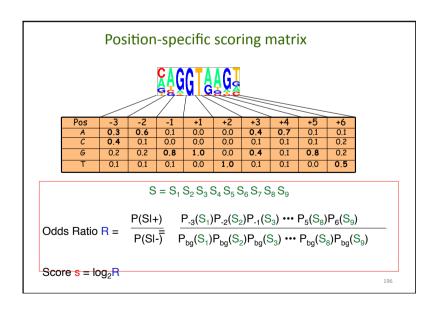
column entropy: $-(p_A \log p_A + p_C \log p_C + p_C \log p_C + p_T \log p_T)$

A	Α	Α	l
Α	С	С	
Α	С	G	
Α	С	Т	

- •Column 1 = -[1*log(1) + 0*log0 + 0*log0 + 0*log0] = 0
- •Column 2 = -[(\frac{1}{4})*log(\frac{1}{4}) + (\frac{3}{4})*log(\frac{3}{4}) + 0*log0 + 0*log0] = -[(\frac{1}{4})*(-2) + (\frac{3}{4})*(-.415)] = +0.811
- •Column 3 = -[($^{1}/_{4}$)*log($^{1}/_{4}$)+($^{1}/_{4}$)*log($^{1}/_{4}$)+($^{1}/_{4}$)*log($^{1}/_{4}$)+($^{1}/_{4}$)*log($^{1}/_{4}$)] = 4* -[($^{1}/_{4}$)*(-2)] = +2.0
- •Alignment Entropy = 0 + 0.811 + 2.0 = +2.811







Motifs: Profiles and Consensus

ACGTACGT

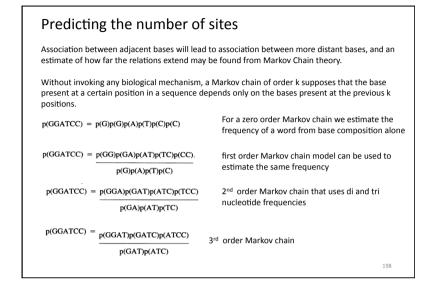
Consensus

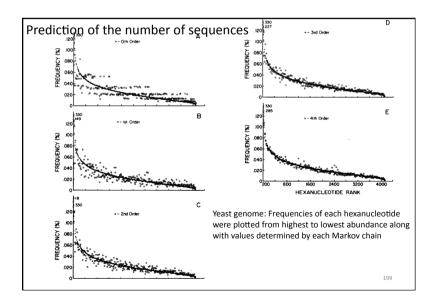
• Line up the patterns by their start indexes

$$\mathbf{s} = (s_1, s_2, ..., s_t)$$

- Construct matrix profile with frequencies of each nucleotide in columns
- Consensus nucleotide in each position has the highest score in column
- Think of consensus as an "ancestor" motif, from which mutated motifs emerged
- The distance between a real motif and the consensus sequence is generally less than that for two real motifs

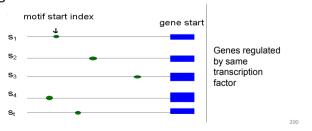
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Gibbs Sampling

- Gibbs Sampling is an iterative procedure that discards one *l*-mer after each iteration and replaces it with a new one.
- Gibbs Sampling proceeds slowly and chooses new *l*-mers at random increasing the odds that it will converge to the correct solution.



How Gibbs Sampling Works

- 1) Randomly choose starting positions $\mathbf{s} = (s_1, ..., s_t)$ and form the set of *I*-mers associated with these starting positions.
- 2) Randomly choose one of the t sequences.
- 3) Create a profile \mathbf{p} from the other t -1 sequences.
- 4) For each position in the removed sequence, calculate the probability that the *I*-mer starting at that position was generated by **p**.
- 5) Choose a new starting position for the removed sequence based on the probabilities calculated in step 4.

Gibbs Sampling – Motif Positions

 \triangleright For each position, r, in the omitted sequence, s_t , calculate

i.e. the probability of motif to background score \triangleright New motif location in s_t is choosen according to these

weights. That is, instead of giving each position in the

sequence equal weight so that each position has a $\frac{1}{L}$

chance of being selected, the chance of being selected is

proportional to the weight. Large weight (meaning higher

chance of the motif begin positioned there) gives large

 $\frac{\prod_{k=r}^{r+W-1}\prod_{i=1}^{4}\rho_{i,k-r+1}^{/(s_{t,k}=i)}}{\prod_{k=r}^{r+W-1}\prod_{i=1}^{4}\rho_{i0}^{/(s_{t,k}=i)}}$

a weight:

chance of selection.

6) Repeat steps 2-5 until there is no improvement

Input:

t = 5 sequences, motif length I = 8

GTAAACAATATTTATAGC

AAAATTTACCTCGCAAGG

CCGTACTGTCAAGCGTGG

1) Randomly choose starting positions, $\mathbf{s} = (s_1, s_2, s_3, s_4, s_5)$ in the 5 sequences:

S₁=7GTAAACAATATTTATAGC

S₂=11 AAAATTTACCTTAGAAGG

S₃=9CCGTACTGTCAAGCGTGG

s₁=4 TGAGTAAACGACGTCCCA

S₅=1TACTTAACACCCTGTCAA

Gibbs Sampling

Gibbs Sampling Algorithm

TGAGTAAACGACGTCCCA

TACTTAACACCCTGTCAA

Gibbs Sampling: an Example 2) Choose one of the sequences at random:

Sequence 2: AAAATTTACCTTAGAAGG

3) Create profile **p** from *l*-mers in remaining 4 sequences:

1	Α	Α	Т	Α	Т	Т	Т	Α
3	Т	С	Α	Α	G	С	G	Т
4	G	Т	Α	Α	Α	С	G	Α
5	Т	Α	С	Т	Т	Α	Α	С
Α	1/4	2/4	2/4	3/4	1/4	1/4	1/4	2/4
С	0	1/4	1/4	0	0	2/4	0	1/4
Т	2/4	1/4	1/4	1/4	2/4	1/4	1/4	1/4
G	1/4	0	0	0	1/4	0	3/4	0
Consensus String	Т	Α	Α	Α	Т	С	G	Α

Gibbs Sampling: an Example

4) Calculate the prob(b/P) for every possible 8-mer in the removed sequence:

Strings Highlighted in Red	prob(a P)
AAAATTTACCTTAGAAGG	.000732
A AAATTTAC CTTAGAAGG	.000122
AA AATTTACC TTAGAAGG	0
AAA <mark>ATTTACCT</mark> TAGAAGG	0
AAAATTTACCTTAGAAGG	0
AAAAT TTACCTTA GAAGG	0
AAAATT TACCTTAG AAGG	0
AAAATTT ACCTTAGA AGG	.000183
AAAATTTA CCTTAGAA GG	0
AAAATTTAC CTTAGAAG G	0
AAAATTTACC TTAGAAGG	0

- 5) Create a distribution of probabilities of *I*-mers $prob(\mathbf{b}/\mathbf{P})$, and randomly select a new starting position based on this distribution.
- a) To create this distribution, divide each probability prob(b/P) by the lowest probability:

Starting Position 1: $prob(AAAATTTA \mid P) = .000732 / .000122 = 6$ Starting Position 2: prob(AAATTTAC | P) = .000122 / .000122 = 1 Starting Position 8: prob(ACCTTAGA | P) = .000183 / .000122 = 1.5 Ratio = 6:1:1.5

b) Define probabilities of starting positions according to computed ratios

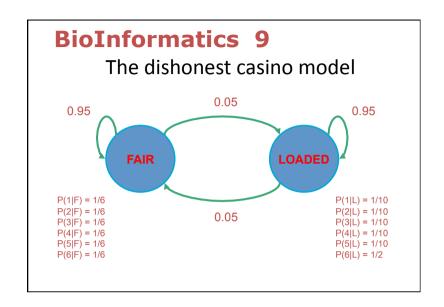
Probability (Selecting Starting Position 1): 6/(6+1+1.5)= 0.706 Probability (Selecting Starting Position 2): 1/(6+1+1.5)= 0.118 Probability (Selecting Starting Position 8): 1.5/(6+1+1.5)=0.176 Gibbs Sampling: an Example

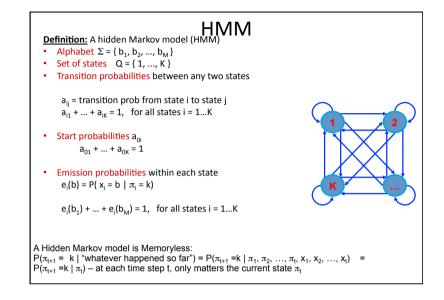
c) Select the start position according to computed ratios:

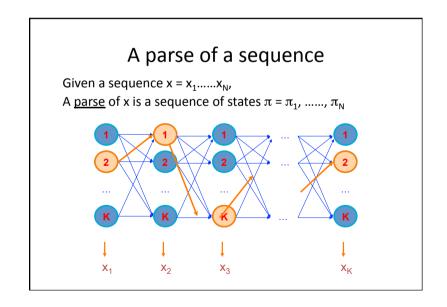
P(selecting starting position 1): .706 P(selecting starting position 2): .118

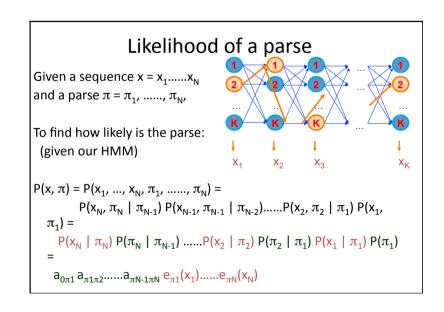
P(selecting starting position 8): .176

6) We iterate the procedure again with the above starting positions until we cannot improve the score any more.









The three main questions on HMMs

1. Evaluation

GIVEN a HMM M, and a sequence x, FIND Prob[x | M]

2. Decoding

GIVEN a HMM M. and a sequence x,

the sequence π of states that maximizes P[x, π | M] FIND

3. Learning

GIVEN a HMM M, with unspecified transition/emission probs., and a sequence x,

parameters $\theta = (e_i(.), a_{ii})$ that maximize P[x | θ] FIND

Let's not be confused by notation

P[x | M]: The probability that sequence x was generated by the model: The model is: architecture (#states, etc)

+ parameters $\theta = a_{ii}$, $e_i(.)$

So, P[x | θ], and P[x] are the same, when the architecture, and the entire model, respectively, are implied

Similarly, P[x, π | M] and P[x, π] are the same

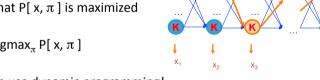
In the LEARNING problem we always write P[x | θ] to emphasize that we are seeking the θ that maximizes P[x | θ]

Decoding

GIVEN $x = x_1 x_2 \dots x_N$

We want to find $\pi = \pi_1,, \pi_N$, such that P[x, π] is maximized

$$\pi^* = \operatorname{argmax}_{\pi} P[x, \pi]$$



We can use dynamic programming!

$$\begin{split} \text{Let V}_{k}(i) &= \text{max}_{\{\pi 1, \dots, i-1\}} \, P[x_{1} ... x_{i-1}, \, \pi_{1}, \, ..., \, \pi_{i-1}, \, x_{i}, \, \pi_{i} = k] \\ &= \text{Probability of most likely sequence of states ending at} \\ &\quad \text{state } \pi_{i} = k \end{split}$$

Decoding – main idea

Given that for all states k, and for a fixed position i,

$$V_k(i) = \max_{\{\pi_1,...,i-1\}} P[x_1...x_{i-1}, \pi_1, ..., \pi_{i-1}, x_i, \pi_i = k]$$

What is V_ν(i+1)?

From definition,

$$V_{l}(i+1) = \max_{\{\pi_{1},...,i\}} P[x_{1}...x_{i}, \pi_{1}, ..., \pi_{i}, x_{i+1}, \pi_{i+1} = l]$$

$$= \max_{\{\pi_1,...,i\}} P(x_{i+1}, \pi_{i+1} = I \mid x_1,...,x_i, \pi_1,...,\pi_i) P[x_1,...,x_i, \pi_1,...,\pi_i]$$

$$= \max_{\{\pi_1,...,i\}} P(x_{i+1}, \pi_{i+1} = I \mid \pi_i) P[x_1,..., \pi_{i-1}, \pi_1, ..., \pi_{i-1}, x_i, \pi_i]$$

=
$$\max_{k} P(x_{i+1}, \pi_{i+1} = I \mid \pi_i = k) \max_{\{\pi_1, ..., i-1\}} P[x_1 ... x_{i-1}, \pi_1, ..., \pi_{i-1}, x_i, \pi_i = k] = e_i(x_{i+1}) \max_{k} a_{kl} V_k(i)$$

The Viterbi Algorithm

Input: $x = x_1 x_N$

Initialization:

$$V_0(0) = 1$$
 (0 is the imaginary first position) $V_{\nu}(0) = 0$, for all $k > 0$

Iteration:

$$\frac{V_{i}(i)}{e_{i}(x_{i}) \times \max_{k} a_{kj} V_{k}(i-1)}$$

$$Ptr_i(i) = argmax_k a_{ki} V_k(i-1)$$

Termination:

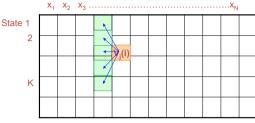
$$P(x, \pi^*) = \max_k V_k(N)$$

Traceback:

$$\pi_N^* = \operatorname{argmax}_k V_k(N)$$

 $\pi_{i-1}^* = \operatorname{Ptr}_{\pi_i}(i)$

The Viterbi Algorithm



Similar to "aligning" a set of states to a sequence Time: O(K²N) Space: O(KN)

Underflows are a significant problem

$$P[x_1,...,x_i, \pi_1, ..., \pi_i] = a_{0\pi 1} a_{\pi 1\pi 2}.....a_{\pi i} e_{\pi 1}(x_1).....e_{\pi i}(x_i)$$

These numbers become extremely small – underflow

Solution: Take the logs of all values

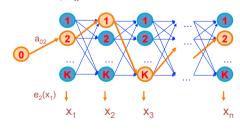
$$V_l(i) = \log e_k(x_i) + \max_k [V_k(i-1) + \log a_{kl}]$$

Generating a sequence by the model

Given a HMM, we can generate a sequence of length n as follows:

Start at state π_1 according to prob $a_{0\pi 1}$

- 1. Emit letter x_1 according to prob $e_{\pi_1}(x_1)$
- 2. Go to state π_2 according to prob $a_{\pi^1\pi^2}$
- 3. ... until emitting x_n



A couple of questions

Given a sequence x,

- What is the probability that x was generated by the model?
- Given a position i, what is the most likely state that emitted x_i?

Example: the dishonest casino

Say x = 12341623162616364616234161221341

Most likely path: $\pi = FF.....F$

However: marked letters more likely to be L than unmarked letters

Evaluation

We will develop algorithms that allow us to compute:

P(x) Probability of x given the model

 $P(x_i...x_i)$ Probability of a substring of x given the model

 $P(\pi_1 = k \mid x)$ Probability that the ith state is k, given x

A more refined measure of which states x may be in

The Forward Algorithm

We want to calculate

P(x) = probability of x, given the HMM

Sum over all possible ways of generating x:

$$P(x) = \sum_{\pi} P(x, \pi) = \sum_{\pi} P(x \mid \pi) P(\pi)$$

To avoid summing over an exponential number of paths π , define

$$f_k(i) = P(x_1...x_i, \pi_i = k)$$
 (the forward probability)

The Forward Algorithm – derivation

Define the forward probability:

$$f_{I}(i) = P(x_{1}...x_{i}, \pi_{i} = I)$$

=
$$\sum_{\pi_1...\pi_{i-1}} P(x_1...x_{i-1}, \pi_1, ..., \pi_{i-1}, \pi_i = I) e_I(x_i)$$

$$= \sum_{k} \sum_{\pi_1...\pi_{i-2}} P(x_1...x_{i-1}, \pi_1, ..., \pi_{i-2}, \pi_{i-1} = k) \ a_{kl} \ e_l(x_i)$$

=
$$e_i(x_i) \sum_k f_k(i-1) a_{ki}$$

The Forward Algorithm

We can compute $f_k(i)$ for all k, i, using dynamic programming! **Initialization:**

$$f_0(0) = 1$$

$$f_k(0) = 0$$
, for all $k > 0$

Iteration:

$$f_{i}(i) = e_{i}(x_{i}) \sum_{k} f_{k}(i-1) a_{ki}$$

Termination:

$$P(x) = \sum_{k} f_{k}(N) a_{k0}$$

Where, a_{k0} is the probability that the terminating state is k (usually = a_{nk})

Relation between Forward and Viterbi

VITERBI

FORWARD

Initialization:

$$V_0(0) = 1$$

$$f_0(0) = 1$$

$$V_k(0) = 0$$
, for all $k > 0$

$$f_k(0) = 0$$
, for all $k > 0$

Iteration:

$$V_i(i) = e_i(x_i) \max_k V_k(i-1) a_{ki}$$

$$f_{i}(i) = e_{i}(x_{i}) \sum_{k} f_{k}(i-1) a_{ki}$$

Termination:

$$P(x, \pi^*) = \max_{\nu} V_{\nu}(N)$$

$$P(x) = \sum_{k} f_{k}(N) a_{k0}$$

Motivation for the Backward Algorithm

We want to compute

$$P(\pi_i = k \mid x),$$

the probability distribution on the ith position, given x

We start by computing

$$P(\pi_{i} = k, x) = P(x_{1}...x_{i}, \pi_{i} = k, x_{i+1}...x_{N})$$

$$= P(x_{1}...x_{i}, \pi_{i} = k) P(x_{i+1}...x_{N} | x_{1}...x_{i}, \pi_{i} = k)$$

$$= P(x_{1}...x_{i}, \pi_{i} = k) P(x_{i+1}...x_{N} | \pi_{i} = k)$$
Forward f.(i)

The Backward Algorithm – derivation

Define the backward probability:

$$\begin{split} b_k(i) &= P(x_{i+1}...x_N \mid \pi_i = k) \\ &= \sum_{\pi i + 1...\pi N} P(x_{i+1}, x_{i+2}, \, ..., \, x_N, \, \pi_{i+1}, \, ..., \, \pi_N \mid \pi_i = k) \\ &= \sum_{l} \sum_{\pi i + 1...\pi N} P(x_{i+1}, x_{i+2}, \, ..., \, x_N, \, \pi_{i+1} = l, \, \pi_{i+2}, \, ..., \, \pi_N \mid \pi_i = k) \\ &= \sum_{l} e_l(x_{i+1}) \, a_{kl} \sum_{\pi i + 1...\pi N} P(x_{i+2}, \, ..., \, x_N, \, \pi_{i+2}, \, ..., \, \pi_N \mid \pi_{i+1} = l) \\ &= \sum_{l} e_l(x_{i+1}) \, a_{kl} \, b_l(i+1) \end{split}$$

The Backward Algorithm

We can compute $b_k(i)$ for all k, i, using dynamic programming

Initialization:

$$b_k(N) = a_{k0}$$
, for all k

What is the running time, and space required, for Forward, and Backward?

Iteration:

$$b_k(i) = \sum_i e_i(x_{i+1}) a_{ki} b_i(i+1)$$

Termination:

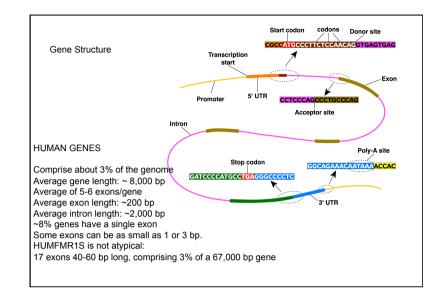
$$P(x) = \sum_{i} a_{0i} e_{i}(x_{1}) b_{i}(1)$$

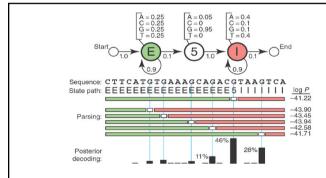
Assume we are given a DNA sequence that begins in an exon, contains one splice site and ends in an intron. The problem is to identify where the switch from exon to intron occurred.

For us to guess intelligently, the sequences of exons, splice sites and introns must have different statistical properties.

Let's imagine some simple differences: say that exons have a uniform base composition on average (25% each base), introns are A+T rich (say, 40% each for A/T, 10% each for C/G), and the 5'SS consensus nucleotide is almost always a G (say, 95% G and 5% A).

Starting from this information, we can draw an HMM that invokes three states, one for each of the three labels we might assign to a nucleotide: E (exon), 5 (5'SS) and I (intron).





Each state has its own emission probabilities (shown above the states), which model the base composition of exons, introns and the consensus G at the 5'SS.

Each state also has transition probabilities (arrows), the probabilities of moving from this state to a new state.

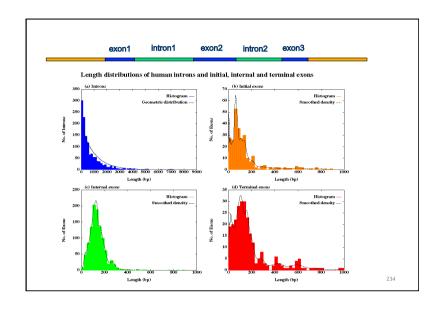
The transition probabilities describe the linear order in which we expect the states to occur: one or more Es, one 5, one or more Is.

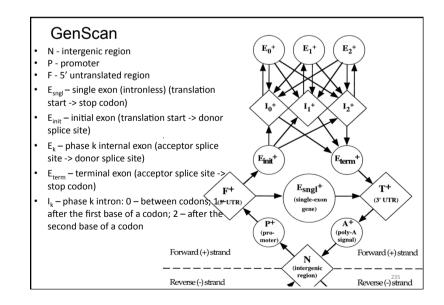
How confident are we that the fifth G is the right choice?

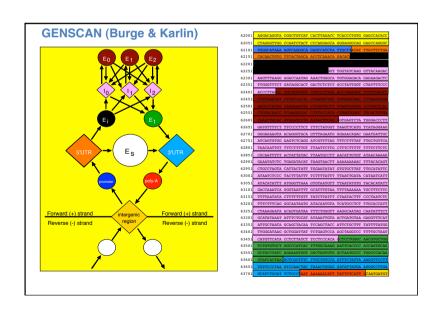
Our confidence will depend on posterior decoding.

Posterior decoding uses two dynamic programming algorithms called Forward and Backward, which have some similarity with Viterbi, but they sum over possible paths instead of choosing the best.

Genescan model Duration of states – length distributions of - Exons (coding) Introns (non coding) Signals at state transitions ATG Codon for gene start - Stop Codon TAG/TGA/TAA Exon/Intron and Intron/Exon Splice Sites Emissions Coding potential and frame at exons - Intron emissions scored by scored by scored by signal sensor content sensor signal sensor CGA**GT**CGATATAC... CGT**ATG**CTAGCTAGCGCAT signal sensor signal sensor-







Assessing performance: Sensitivity and Specificity

- Testing of predictions is performed on sequences where the gene structure is known
- Sensitivity is the fraction of known genes (or bases or exons) correctly predicted: Sn=N_{True Positives} /N_{All True}
 - "Am I finding the things that I'm supposed to find?
- Specificity is the fraction of predicted genes (or bases or exons) that correspond to true genes: Sp=N_{True Positives} /N_{All Positives}
 - "What fraction of my predictions are true?
- · In general, increasing one decreases the other

	Accuracy per nucleotide			Accuracy per exon				
Method	Sn	Sp	AC	Sn	Sp	(Sn+Sp)/ 2	ME	WE
GENSCAN	0.93	0.93	0.91	0.78	0.81	0.8	0.09	0.05
FGENEH	0.77	0.85	0.78	0.61	0.61	0.61	0.15	0.11
GeneID	0.63	0.81	0.67	0.44	0.45	0.45	0.28	0.24
GeneParser2	0.66	0.79	0.66	0.35	0.39	0.37	0.29	0.17
GenLang	0.72	0.75	0.69	0.5	0.49	0.5	0.21	0.21
GRAILII	0.72	0.84	0.75	0.36	0.41	0.38	0.25	0.1
SORFIND	0.71	0.85	0.73	0.42	0.47	0.45	0.24	0.14
Ynound	0.61	0.82	0.68	0.15	0.17	0.16	0.32	0.13

Sn = Sensitivity Sp = Specificity

Ac = Approximate Correlation ME = Missing Exons

WE = Wrong Exons

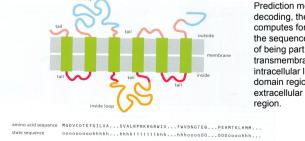
wrong Exons

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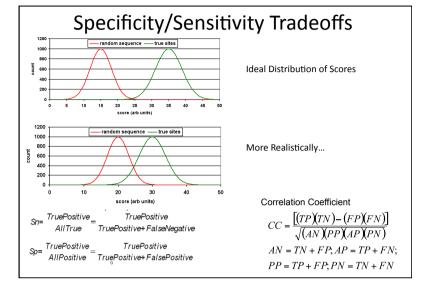
TMHMM: Prediction of transmembrane topology of protein sequence Model consists of submodels for:

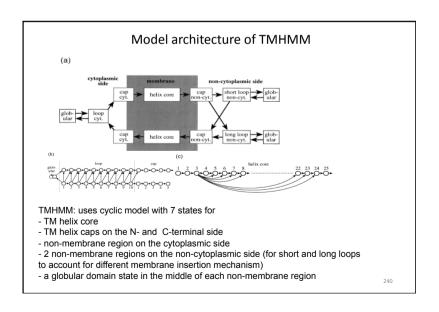
- helix core and cap regions (cytoplasmic and extracellular)
- cytoplasmic and extracellular loop regions
- globular domain regions

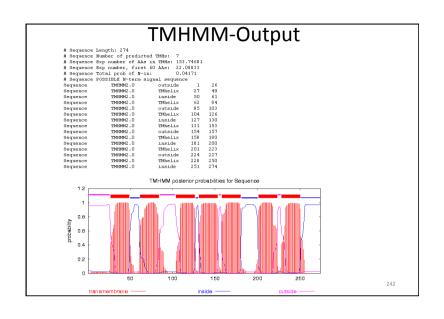
Trained form 160 proteins with experimentally determined transmembrane helices.

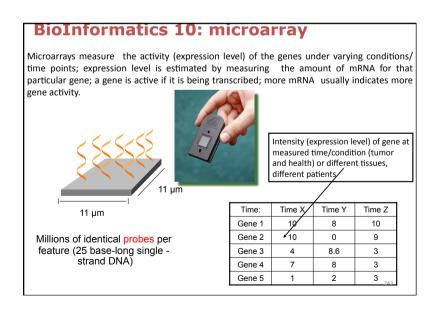


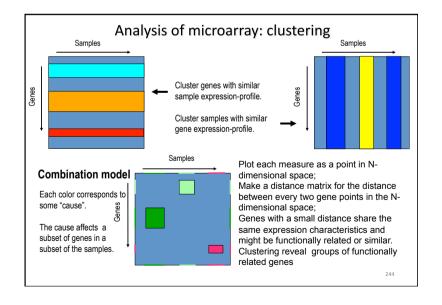
Prediction method: Posterior decoding, the program computes for each residue of the sequence the probability of being part if a transmembrane helix, an intracellular loop or globular domain region, or an extracellular loop or domain region.

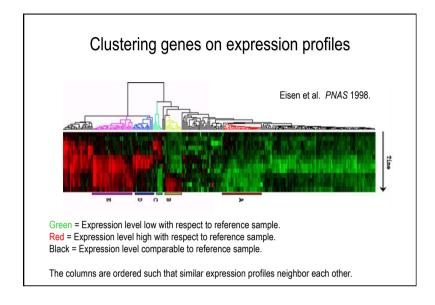












K-Means Clustering Problem: Formulation

- Input: A set, V, consisting of n points and a parameter k
- Output: A set X consisting of k points (cluster centers)
 that minimizes the squared error distortion d(V,X) over
 all possible choices of X

1-Means Clustering Problem: an Easy Case

- **Input**: A set, **V**, consisting of *n* points
- Output: A single points x (cluster center) that minimizes the squared error distortion d(V,x) over all possible choices of x
- 1-Means Clustering problem is easy.

However, it becomes very difficult (NP-complete) for more than one center. An efficient *heuristic* method for K-Means clustering is the Lloyd algorithm

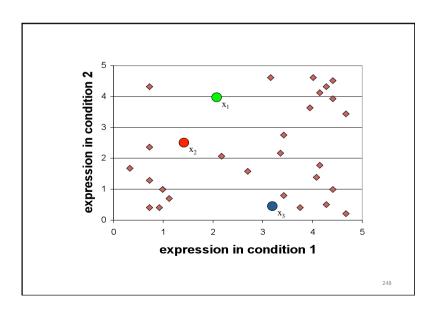
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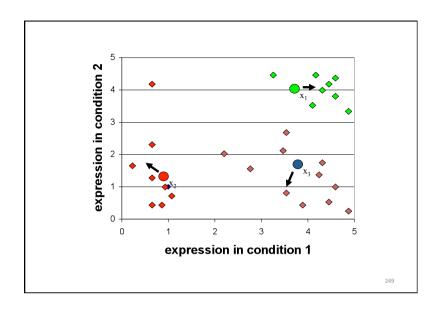
K-Means Clustering: Lloyd Algorithm

- Lloyd Algorithm
- 2. Arbitrarily assign the *k* cluster centers
- 3. while the cluster centers keep changing
- 4. Assign each data point to the cluster C_i corresponding to the closest cluster representative (center) $(1 \le i \le k)$
- 5. After the assignment of all data points, compute new cluster representatives according to the center of gravity of each cluster, that is, the new cluster representative is

 $\Sigma v \setminus |C|$ for all v in C for every cluster C

*This may lead to merely a locally optimal clustering.





Conservative K-Means Algorithm

- Lloyd algorithm is fast but in each iteration it moves many data points, not necessarily causing better convergence.
- A more conservative method would be to move one point at a time only if it improves the overall **clustering cost**
 - The smaller the clustering cost of a partition of data points is the better that clustering is
 - Different methods (e.g., the squared error distortion) can be used to measure this clustering cost

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K-Means "Greedy" Algorithm

```
ProgressiveGreedyK-Means(k)
Select an arbitrary partition P into k clusters
2.
3.
     while forever
       bestChange ← 0
        for every cluster C
6.
           for every element i not in C
7.
            if moving i to cluster C reduces its clustering cost
               if (\cos t(P) - \cos t(P_{i \to C}) > bestChange

bestChange \leftarrow \cos t(P) - \cos t(P_{i \to C})
8.
9.
10.
                 i* ← 1
                C^* \leftarrow C
11.
        if bestChange > 0
12.
13.
           Change partition P by moving i^* to C^*
14.
       else
15.
          return P
```

Squared Error Distortion

 Given a data point v and a set of points X, define the distance from v to X

d(v, X)

as the (Eucledian) distance from v to the *closest* point from X.

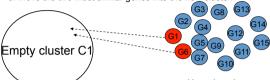
Given a set of n data points V={v₁...v_n} and a set of k points X, define the Squared Error Distortion

$$d(V,X) = \sum d(v_i, X)^2 / n$$
 $1 \le i \le n$

Clustering Affinity Search Technique (CAST)-1

Affinity = a measure of similarity between a gene, and all the genes in a cluster. Threshold affinity = user-specified criterion for retaining a gene in a cluster, defined as %age of maximum affinity at that point

- Create a new empty cluster C1.
- 2. Set initial affinity of all genes to zero
- 3. Move the two most similar genes into the new cluster.



4. Update the affinities of all the genes (new affinity of a gene = its previous affinity + its similarity to the gene(s) newly added to the cluster C1)

ADD GENES

5. While there exists an unassigned gene whose affinity to the cluster C1 exceeds the user-specified threshold affinity, pick the unassigned gene whose affinity is the highest, and add it to cluster C1. Update the affinities of all the genes accordingly.

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REMOVE GENES:

CAST - 2

6. When there are no more unassigned high-affinity genes, check to see if cluster C1 contains any elements whose affinity is lower than the current threshold. If so, remove the lowest-affinity gene from C1. Update the affinities of all genes by subtracting from each gene's affinity, its similarity to the removed gene.

7. Repeat step 6 while C1 contains a low-affinity gene



Unassigned genes

- 8. Repeat steps 5-7 as long as changes occur to the cluster C1.
- 9. Form a new cluster with the genes that were not assigned to cluster C1, repeating steps 1-8.
- 10. Keep forming new clusters following steps 1-9, until all genes have been assigned to a cluster

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Markov clustering algorithm

We take a random walk on the graph described by the similarity matrix, but after each step we weaken the links between distant nodes and strengthen the links between nearby nodes.

Unlike most clustering algorithms, the MCL does not require the number of expected clusters to be specified beforehand.

The basic idea underlying the algorithm is that dense clusters correspond to regions with a larger number of paths.

A random walk has a higher probability to stay inside the cluster than to leave it soon. The crucial point lies in boosting this effect by an iterative alternation of expansion and inflation steps.

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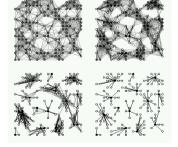
The algorithm iterates three steps.

Given a network with n vertexes, it takes the corresponding $n \times n$ adjacency matrix A and normalises each column to obtain a stochastic matrix M. It takes the k_{th} power M^k of this matrix (expansion) and then the r_{th} power $m^r(_{ij})$ of every element (inflation).

The expansion parameter k is often taken equal to 2, while the granularity of the clustering is controlled by tuning the inflation

parameter r.

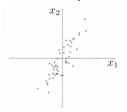
Graphic from van Dongen, 2000

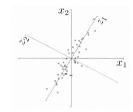


Principle Components Analysis (PCA)

A sample of n observations in the 2-D space $X=(X_1,X_2)$

Goal: to account for the variation in a sample in as few variables as possible, to some accuracy





- the 1^{st} PC Z_1 is a minimum distance fit to a line X in space
- the 2^{nd} PC Z_2 is a minimum distance fit to a line in the plane perpendicular to the 1^{st} PC

PCAs are a series of linear least squares fits to a sample, each orthogonal to all the previous.

PCA - Steps

Input: a dataset $S = \{s^1,...,s^n\}, s^i = \langle s_1^i,...,s_d^i \rangle$

- · Subtract the mean from each dimension
- Compute the covariance matrix $\boldsymbol{\Sigma}$ for the d dimensions
 - The covariance of two variables X and Y:

$$cov(X,Y) = \sum_{i=1}^{n} \frac{(X_i - \overline{X}) \cdot (Y_i - \overline{Y})}{(n-1)}$$

– The covariance matrix: $\sum (X,Y) = \sum (Y,X) = \cos(X,Y)$

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Principle Components Analysis (PCA)

- PCA seeks for a linear projection that best describes the data in a least mean squares sense
- Finds a set of principle components (PCs)
 - A PC defines a projection that encapsulates the maximum amount of variation in a dataset
 - Each PC is orthogonal to all other PCs
- Reduce dimensionality by picking the most informative PCs
 - Namely, for reducing from dimension d to dimension d', pick the d' most informative PCs

PCA - Steps (cont.)

- Compute the eigenvectors and eigenvalues of the covariance matrix
- Choose the most informative PCs, construct a feature vector
 - Eigenvectors with highest eigenvalues carry the most information
 - Feature vector is simply the combination of all eigenvectors chosen

FeatureVector =
$$(eig_1, eig_2, ..., eig_{d'})$$

• Transform dataset to the new axis system $- \text{ For s} \in \mathbb{S} \colon \quad s' = Feature Vector^T \times s = \begin{bmatrix} eig_1 \\ eig_2 \\ \vdots \\ eig_{d'} \end{bmatrix} \times \begin{bmatrix} s_1 \\ s_2 \\ \vdots \\ s_d \end{bmatrix}$

When Things Get Messy...

- PCA is fine when initial dimension is not too big
 - Space and time complexity are of O(d²) size of covariance matrix
- Otherwise we have a problem...
 - E.g. when d=10⁴ \Rightarrow time/space complexity is O(10⁸)...
- Luckily an alternative exists: SVD

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Eigengenes, Eigenarrays and SVD

- The idea:
 - Use the singular value decomposition (SVD) theorem for transforming the dataset from the gene/array space to the eigengene/eigenarray space
- Eigengenes, eigenarrays and eigenvalues:
 - Each dimension is represented by an eigengene/ eigenarray/eigenvalue triplet
 - Eigenvalues are used for ranking dimensions

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Singular Value Decomposition (SVD)

• Theorem: if E is a real M by N matrix, then there exist orthogonal matrices

$$U = [u^1, ..., u^M] \in \Re^{MxM}$$
 and $V = [v^1, ..., v^N] \in \Re^{NxN}$

s.t.

$$E = U \cdot W \cdot V^T$$

Where

$$W = diag(\sigma_1, ..., \sigma_n)$$

and

$$\sigma_1 \ge \sigma_2 \ge ... \ge \sigma_n \ge 0, \qquad p = \min(m, n)$$

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SVD

- σ_i is the ith singular value of E.
 u_i and v_i are the ith left singular vector and right singular vector of E, respectively.
- · It holds that

$$E \cdot v^{i} = \sigma_{i} \cdot u^{i}$$

$$E^{T} \cdot u^{i} = \sigma_{i} \cdot v^{i}$$

$$i = 1 : \min(M, N)$$

· Efficient algorithms for calculating the SVD exist

Orthogonality of Decomposition

$$\begin{split} E &= U \cdot W \cdot V^T \\ V &= \begin{bmatrix} v^1, ..., v^N \end{bmatrix}, \qquad v^i &= \left\langle v^i_1, ..., v^i_N \right\rangle \\ U &= \begin{bmatrix} u^1, ..., u^M \end{bmatrix}, \qquad u^i &= \left\langle u^1_1, ..., u^1_M \right\rangle \\ W &= diag(\sigma_1, ..., \sigma_p) \end{split}$$

$$\begin{bmatrix} e_{11} & e_{12} & \cdots & e_{1N} \\ e_{21} & \ddots & & & \vdots \\ \vdots & & & \vdots \\ e_{M1} & & \cdots & e_{MN} \end{bmatrix} = \begin{bmatrix} u_1^1 & u_1^2 & \cdots & u_1^M \\ u_2^1 & \ddots & & & \vdots \\ u_M^1 & & \cdots & u_M^M \end{bmatrix} \times \begin{bmatrix} \sigma_{11} & 0 & \cdots & 0 \\ 0 & \sigma_{22} & & & \vdots \\ \vdots & & \ddots & & \vdots \\ 0 & & & \cdots & 0 \end{bmatrix} \times \begin{bmatrix} v_1^1 & v_2^1 & \cdots & v_N^1 \\ v_1^2 & \ddots & & \vdots \\ \vdots & & \ddots & \vdots \\ v_1^N & \cdots & \cdots & v_N^N \end{bmatrix}$$

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Orthogonality of Decomposition

$$U \cdot W = \begin{bmatrix} \sigma_{11} u_1^1 & \sigma_{22} u_1^2 & \cdots & \sigma_{MM} u_1^M & \cdots & 0 \\ \sigma_{11} u_2^1 & \sigma_{22} u_2^2 & & & & \vdots \\ \vdots & \vdots & \ddots & & & \vdots \\ \sigma_{11} u_M^1 & & \sigma_{MM} u_M^M & \cdots & 0 \end{bmatrix} \qquad V^T = \begin{bmatrix} v_1^1 & v_2^1 & \cdots & v_N^1 \\ v_1^2 & \ddots & & \vdots \\ \vdots & & \ddots & \vdots \\ v_1^N & \cdots & \cdots & v_N^N \end{bmatrix}$$

$$U \cdot W \cdot V^T = \begin{bmatrix} e_{11} & e_{12} & \cdots & e_{1N} \\ e_{21} & \ddots & & \vdots \\ \vdots & & & \vdots \\ e_{M1} & & \cdots & e_{MN} \end{bmatrix} \qquad e_{ij} = \sum_{k=1}^p \sigma_k \cdot u_i^k \cdot v_j^k$$

$$\Rightarrow E = \sum_{k=1}^{p} \sigma_k \cdot u^k \cdot v^{k^T}$$

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SVD and Microarray analysis

- Reduction from the N genes x M arrays to p eigengenes x p eigenarrays space
 - W is the eigenexpression matrix
 - U represents the expression of genes over eigenarrays
 - V represents the expression of eigengenes over arrays
- · The "fraction of eigenexpression":

$$p_i = \sigma_i / \sum_{k=1}^p \sigma_k^2$$

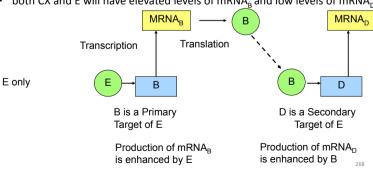
· "Shannon entropy" of the dataset:

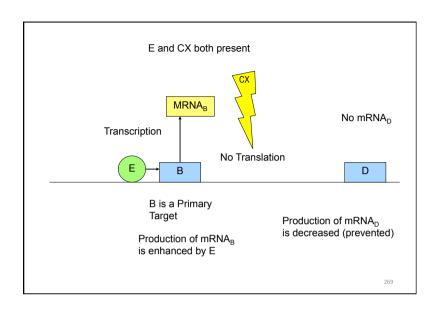
$$0 \le d = \frac{-1}{\log(p)} \sum_{k=1}^{p} p_k \log(p_k) \le 1$$

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BioInformatics 11: genetic networks

- assume that there are two related genes, B and D
- neither is expressed initially, but E causes B to be expressed and this in turn causes D to be expressed
- the addition of CX by itself may not affect expression of either B or D
- both CX and E will have elevated levels of mRNA_R and low levels of mRNA_D



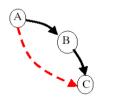


- in the presence of both CX and E we see increased expression of mRNA_B but not of mRNA_D
- this will be one of the principles we can use to differentiate between primary targets of E (such as B) and secondary targets of E (such as D)

	Genes				
		$mRNA_B$	$mRNA_D$		
Conditions	Nothing	Low	Low		
	Е	High	High		
	CX	Low(?)	Low (?)		
	E and CX	High	Low		

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How to reconstruct a large genetic network from n gene perturbations in fewer than n² steps



Direct:

A⇒B

 $B \Rightarrow C$

Indirect

 $A \Rightarrow C$

- How can we distinguish between direct and indirect relationships in a network based on microarray data?
- · Additional Assumption needed
- Next: minimize # relationships

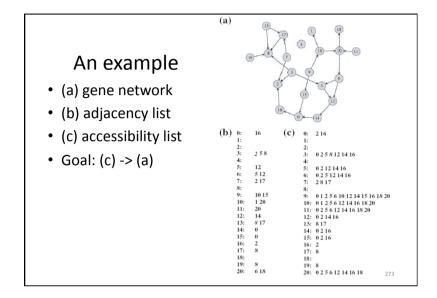
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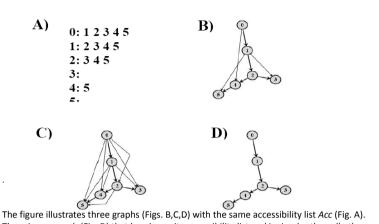
Perturbation Static Graph Model

- Motivation: perturb a gene network one gene at a time and use the effected genes in order to discriminate direct vs. indirect gene-gene relationships
- Perturbations: gene knockouts, over-expression, etc.

Method:

- 1. For each gene \mathcal{S}_i , compare the control experiment to perturbed experiment and identify the differentially expressed genes
- 2. Use the most parsimonious graph that yields the graph of 1. as its reachable graph

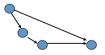




The figure illustrates three graphs (Figs. B,C,D) with the same accessibility list Acc (Fig. A). There is one graph (Fig. D) that has Acc as its accessibility list and is simpler than all other graphs, in the sense that it has fewer edges. Let's call Gpars the most parsimonious network compatible with Acc.

Algorithm

- Step1: Graphs without cycles only (acyclic directed graph)
- Step2: Graphs with cycles
- Step 1: Shortcut:



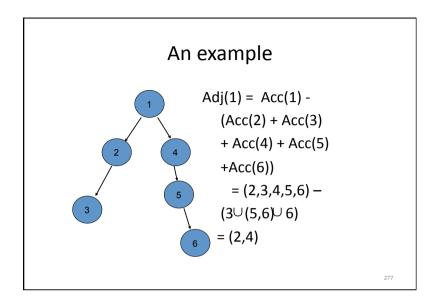
 A shortcut-free graph compatible with an accessibility list is a unique graph with the fewest edges among all graphs compatible with the accessibility list, i.e, a shortcut-free graph is the most parsimonious graph.

Step1

• A theorem: Let Acc(G) be the accessibility list and Adj (G) be the adjacency list at an acyclic directed graph, its mos@parsimonious graph, and V() the set of all nodes of . Then the following identity holds

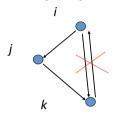
$$\forall i \in V(G_{pars})$$
 $Adj(i) = Acc(i) \setminus \bigcup_{j \in Acc(i)} Acc(j)$

In words, for each node i the adjacency list Adj(i) of the most parsimonious genetic network is equal to the accessibility list Acc(i) after removal of all nodes that are accessible from any node in Acc(i).



Step 1

 A Corollary: Let i, j, and k be any three pairwise different nodes of an acyclic directed shortcut-free graph G. If j is accessible from i, then no node k accessible from j is adjacent to i.

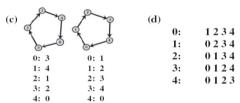


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The algorithm of step 1 for all nodes i of G

```
for all nodes i of G
                      Adj(i)=Acc(i)
           for all nodes i of G
                      if node i has not been visited
                                 call PRUNE_ACC(i)
                      end if
           PRUNE_ACC(i)
                      for all nodes j \in Acc(i)
                                 if Acc(j) = \emptyset
10
                                            declare j as visited.
11
12
                                            call PRUNE_ACC(j)
13
                                 end if
14
                      for all nodes j \in Acc(i)
15
                                 for all nodes k \in Adj(j)
16
                                            if k \in Acc(i)
                                                       delete k from Adj(i)
17
18
19
           declare node i as visited
           end PRUNE_ACC(i)
```

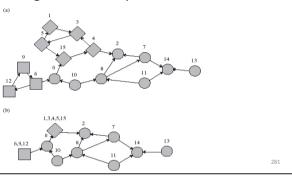
Step 2: How about graphs with cycles?



- Two different cycles have the same accessibility list
- Perturbations of any gene in the cycle influences the activity of all other genes in the same cycle.
- Can't decide a unique graph if cycle happens
- Not an algorithmic but an experimental limitation

The algorithm of step 2

 Basic idea: Shrink each cycles (strongly connected components) into one node and apply the algorithm of step 1.



The algorithm of step 2

- A corollary: Let i and j (i ≠ j) be two nodes of a directed graph G. i and j are in the same component iff i∈Acc(j) and j∈Acc(i).
- A graph after shrinking all the cycles into nodes is called a condensation graph.

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The algorithm of step 2

```
for all nodes i of G
               if component[i] has not been defined
                      create new node x of G^*
                      component[i]=x
                      for all nodes j \in Acc(i)
                                     component[j]=x
               end if
       for all nodes i of G*
               Acc_{G^{q}}(i)=\emptyset
11
12
       for all nodes i of G
13
               for all nodes j \in Acc(i)
14
                      if component[i] \neq component[j]
15
                             if component[j]∉AccG*(component[i])
                                     add component[j] to Accg*(component[i])
17
                             end if
```

Missing genes and messy data

- Some genes are difficult to perturb
- Problem: some information is missing for certain genes. How well does the algorithm perform in such cases?
- Simulation: Randomly generate graphs with prespecified nodes and edges. Then eliminate prespecified fraction of nodes from the accessibility list. Apply the algorithm to both graphs without elimination and with elimination.

Limitation of the algorithm

- Unable to resolve cycled graphs
- Require more data than conventional methods using gene expression correlations.
- There are many networks consistent with the given accessibility list. The algorithm construct the most parsimonious one.
- The same problem was proposed around 1980 which is called "transitive reduction".
- The transitive reduction of a directed graph G is the directed graph G' with the smallest number of edges such for every path between vertices in G, G' has a path between those vertices.
- An O(V) algorithm for computing transitive reduction of a planar acyclic digraph was proposed by Sukhamay Kundu. (V is the number of nodes in G)

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BioInformatics lecture 12

System Biology

- 1. Large scale integration of information on molecules, genes, cell, tissue, organ, organism, health
- 2. Markup language
 - -- development of SBML (Systems Biology Markup Language) for representing biochemical networks and CellML for electrophysiology, mechanics, energetics and general pathway. SBML is an XML-based markup language for describing the biochemical network models that arise in Systems Biology.
- 3. Computational models
 - -- development of models that are "anatomically based" and "biophysically based" to link gene, protein, cell, tissue ,organ and whole body systems physiology.

Methodologies: differential equations and stochastic algorithms

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The Gillespie algorithm

A **reaction rate** w_i is associated to each reaction step. These probabilites are related to the kinetics constants.

Initial number of molecules of each species are specified.

The **time interval** is computed stochastically according the reation rates.

At each time interval, the **reaction** that occurs is chosen randomly according to the probabilities w_i and both the number of molecules and the reaction rates are updated.

$$4 \xrightarrow{w_1} E$$

$$B+C \xrightarrow{w_2} D$$

$$D \xrightarrow{w_3} E + F$$

••

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Gillespie algorithm

Probability that reaction *r* occurs

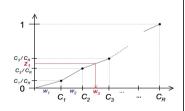
$$P_r = \frac{w_r}{\sum_{i=1}^R w_i}$$

Reaction r occurs if

$$P_{r-1} < z_1 \le P_{r-1} + P_r$$

Time step to the next reaction

$$\Delta t = \frac{1}{\sum_{i=1}^R w_i} ln \frac{1}{z_2}$$



Gillespie D.T. (1977) Exact stochastic simulation of coupled chemical reactions. *J. Phys. Chem.* 81: 2340-2361.

Gillespie D.T., (1976) A General Method for Numerically Simulating the Stochastic Time Evolution of Coupled Chemical Reactions. *J. Comp. Phys.*, 22: 403-434.

Gillespie algorithm

In practice...

- 1. Calculate the transition probability w_i and the variables X_i (A,B,C etc).
- 2. Generate z_1 and z_2 and calculate the reaction that occurs as well as the time till this reaction occurs.
- 3. Increase t by Δt and adjust X to take into account the occurrence of the reaction that just occured.

