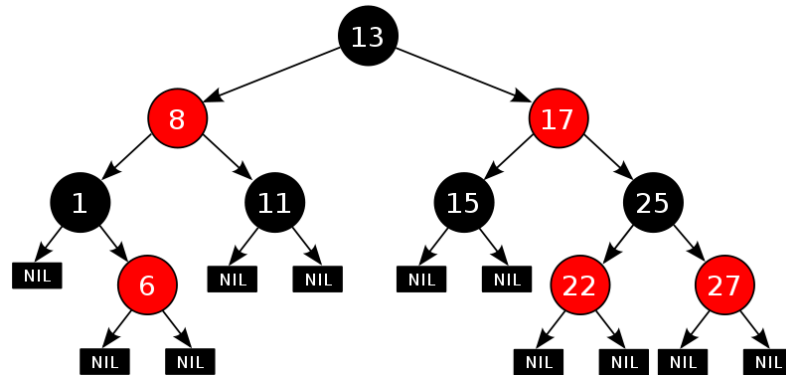


# Algorithms I

## Dr Robert Harle



CST Paper I  
(IA NST CS, PPS CS and CST)  
Easter 2009/10

“Audience participation was good in retrospect but felt like cruel punishment at the time”

“...the last lecture felt like a complete waste of time.”

“I did very much enjoy the last session!”

“the 5 minute breaks were excellent”

“...we wasted time in the middle of the lectures”

“Needs more Blobfish”

“More Blobfish”

“I like Blobfish”

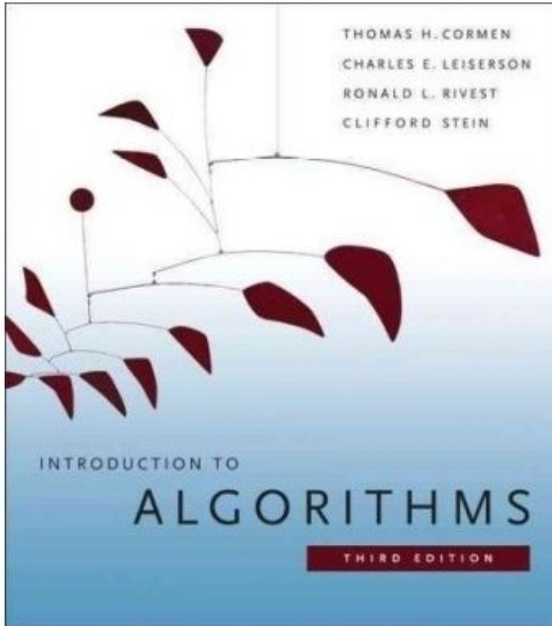
“Blobfish rules!”

“Blobfish Blobfish Blobfish Blobfish...”

# Algorithms I

- This course was developed by **Dr Frank Stajano**, who is on sabbatical this year
- I'm the “substitute teacher” :-)
- Dr Stajano's notes are very good: you have a copy of those as the handout. Those and the course textbook are probably all you need.
- However, I will post an annotated PDF of the notes I make in lectures as we go: check the course web page
- Three Parts
  - **Sorting Algorithms**
  - **Algorithm Design**
  - **Data Structures**

# The CLR(S) Book



- Intro. To Algorithms
  - Cormen, Lieverson, Rivest, (Stein)
- The course is loosely based on this book
  - Definitely read the relevant bits of this book
  - Most libraries should have a copy
  - It contains some good exercises

# Exercises

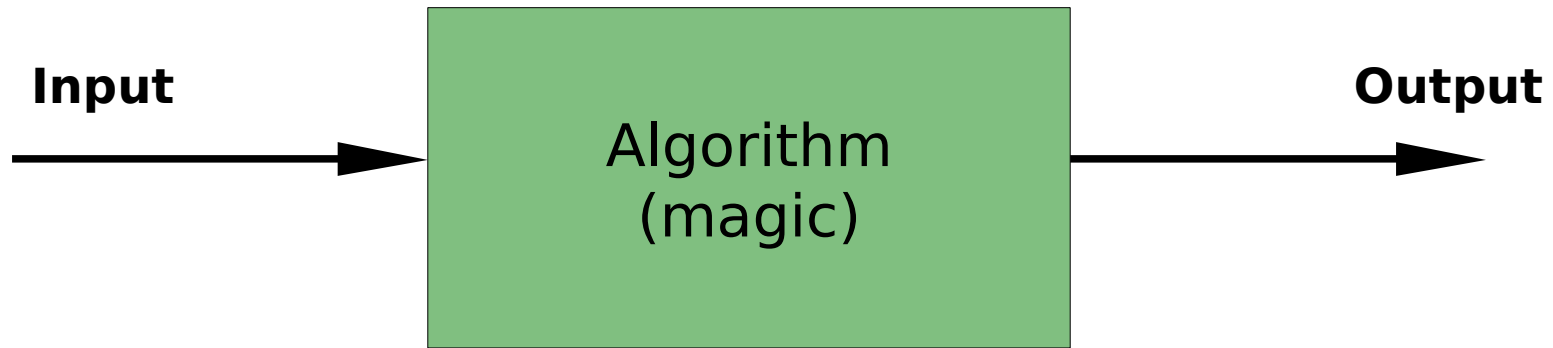
- There are some exercises dispersed throughout the notes
  - They aren't numbered
  - Most are just meant to be done as you read, rather than detailed problems
- There will be **an exercise sheet available as a PDF on the course website** that you may wish to use for supervisions.



# Algorithms

- At its core, CS is really just about puzzle solving. But we aren't just interested in finding a solution (or “algorithm”), we're interested in **finding the best solution** given some definition of 'best'
- Everything else (programming, maths) is just a set of tools that turn out to be useful in supporting our puzzle solving.
- There is no “universal algorithm”; nor will there be.
  - But you can learn a lot from studying how to solve a variety of problems since many problems can be broken down into smaller problems to which established algorithms (or variants of) are appropriate

# Algorithms Optimize Something



- We choose algorithms based on:
  - How soon they give us output (**performance**)
  - How much resource they use (**space**)
  - How good the output is (**quality**)
  - Combinations of the above

# Example: Digital Cameras (JPEG)

- Digital cameras read in a load of pixels and have to convert them into a JPEG image
  - **Performance:** Need to do the conversion quickly so you can take another picture
  - **Space:** Need to do the conversion with minimal space overheads (to keep camera cost and size down)
  - **Quality:** Need to produce a small file that is still a good representation of the original data



# Example: Search Engines

Pages: A B C D E F G H I J K L

## Index

|       |   |   |   |   |   |   |   |  |  |  |  |  |
|-------|---|---|---|---|---|---|---|--|--|--|--|--|
| GET   | A | B | F | H |   |   |   |  |  |  |  |  |
| A     | G | D | K | I | J | B | D |  |  |  |  |  |
| FIRST | G | A |   |   |   |   |   |  |  |  |  |  |
| THIS  | E | F | I | G | A |   |   |  |  |  |  |  |
| YEAR  | C |   |   |   |   |   |   |  |  |  |  |  |

- Algorithms:
  - Look up the search term in the index
  - Optionally combine the results (AND, OR)
  - Arrange the results in some useful order

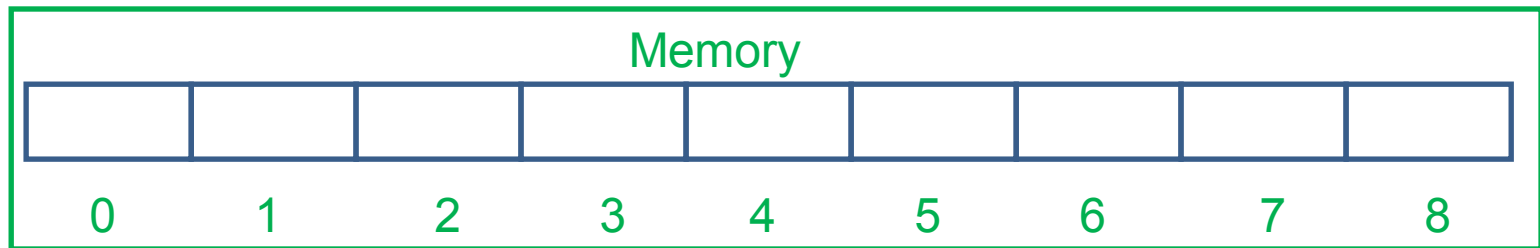
# Part I: Sorting Algorithms

# Why Sorting?

- There is an objective correct result
- Many sorting algorithms are available
  - Some really simple
  - Some more complex
- Sorting (and searching) are needed for most large-scale algorithms
- You have already met some of this in FoCS, but I'll recap anyway (it is revision time after all)
  - Plus you concentrated on sorting **lists** in FoCS: here we look at sorting **arrays**

# Memory Model

- We'll use the simple model from OOP



- Key points:
  - Memory is addressed using numerical addresses and therefore random access
  - We will assume that we never run out of memory
  - We will not worry about the capacity of each memory slot (we'll assume any number can be represented in any slot)

# Insertion Sort

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# Insertion Sort

```
0 def insertSort(a):
1     '''BEHAVIOUR: Run the insertsort algorithm on the integer
2     array a, sorting it in place.
3
4     PRECONDITION: array a contains len(a) integer values.
5
6     POSTCONDITION: array a contains the same integer values as before,
7     but now they are sorted in ascending order.'''
8
9     for k from 0 to len(a)-2:
10        assert(the first k positions are already sorted)
11
12        # Pick up item k+1 (call it a[j]) and let it sink to its correct place
13        j = k+1
14        while j > 0 and a[j-1] > a[j]:
15            swap(a[j-1], a[j])
16            j = j-1
```

# How 'good' is any algorithm?

- It's hard to put numbers to anything since the performance is presumably heavily dependent on the input
- As you know we usually study the limiting behaviour using the **asymptotic notation** you met in FoCS

# Complexity Notations

Big-O:  $0 \leq f(n) \leq k.g(n)$

$\Theta$ :  $0 \leq k_1.g(n) \leq f(n) \leq k_2.g(n)$

$\Omega$ :  $0 \leq k.g(n) \leq f(n)$

For  $n > N$   
 $K, k_1, k_2, N > 0$

# Notes

- $\log_a(x) = \log_b(x)/\log_b(a)$ 
  - So the base of any logarithm in  $g(n)$  is irrelevant
- The value of  $N$  above which the bound holds could be very big
  - i.e. Take care when comparing two complexities for small  $n$ .

# Examples

- Show  $(x+5)\lg(3x^2+7)$  is  $O(x\lg x)$

# Examples

- Show  $n^3+20n$  is  $\Omega(n^2)$

# Examples

- Show  $n^2 - 3n$  is  $\Theta(n^2)$

# Relating to Running Time

- We assume:
  - Any memory access takes unit time
  - Any arithmetic takes unit time
- Thus the running time is linked to the number of operations the algorithm requires.
- Problem: this is often dependent on the input



# Worst, Average and Amortized costs

- **Worst-case**

- Analyse for the worst possible input. This gives you an upper bound for the performance.

- **Average-case**

- Analyse for an 'average' input. Problem here is that the notion of average assumes some probability distribution of inputs, which we rarely have (and which is application specific of course).

- **Amortized analysis**

- Sometimes we have a sequence of operations that occur: in this case we may *amortize* the total cost to run the sequence of operations so we get an average cost per operation. e.g. Garbage collection.

# Insertion Sort Analysis

```
9     for k from 0 to len(a)-2:
10         assert(the first k positions are already sorted)
11
12         # Pick up item k+1 (call it a[j]) and let it sink
13         j = k+1
14         while j > 0 and a[j-1] > a[j]:
15             swap(a[j-1], a[j])
16             j = j-1
```

Is that Optimal?

# $O(n^2)$ Sorting Algorithms

- There are lots of these around. They tend to be easy-ish to think up. Be careful not to reinvent the wheel!
- We're going to look at a few more so that you have been exposed to the common ones and you also get more practice analysing complexity.
- You will find a lot of CS types scoff at these algorithms as being a waste of time. But they have definite advantages:
  - They are usually concise and understandable (means fewer implementation bugs)
  - For small  $n$ , they might be the quickest method!

# Selection Sort: Idea



# Selection Sort: Example

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# Selection Sort

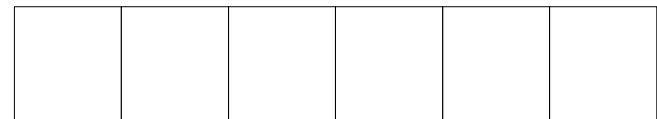
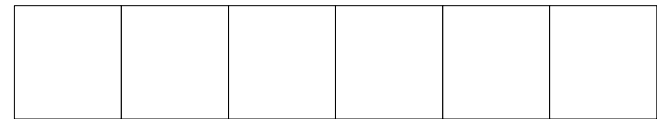
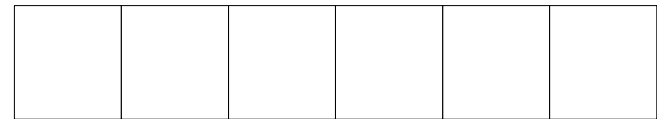
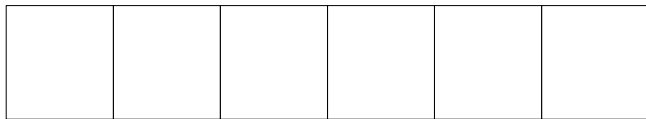
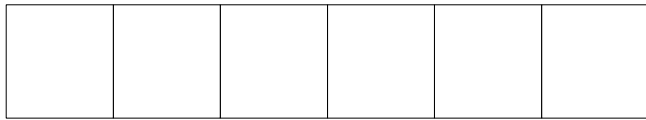
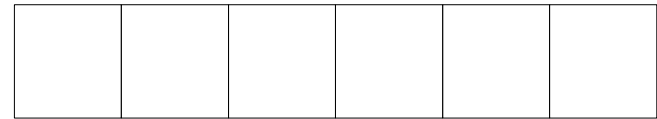
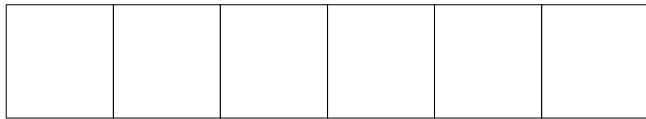
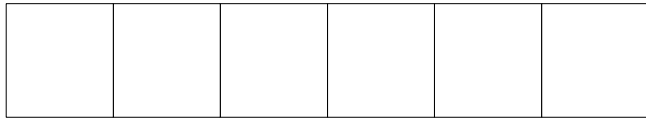
```
9     for k from 0 to len(a)-1:
10         assert(the positions before a[k] are already sorted)
11
12         # Find the smallest element in a[k..end] and swap it into a[k]
13         iMin = k
14         for j from iMin+1 to len(a)-1:
15             if a[j] < a[iMin]:
16                 iMin = j
17         swap(a[k], a[iMin])
```

# Binary Insertion Sort: Idea





# Binary Insertion Sort: Example



# Binary Insertion Sort: Analysis

# Binary Insertion Sort: Analysis

# Bubble Sort: Idea



# Bubble Sort: Example

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# Bubble Sort

```
9     repeat
10         # Go through all the elements once, swapping any that are out of order
11         didSomeSwapsInThisPass = false
12         for k from 0 to len(a)-2:
13             if a[k] > a[k+1]:
14                 swap(a[k], a[k+1])
15                 didSomeSwapsInThisPass = true
16     until didSomeSwapsInThisPass == false
```

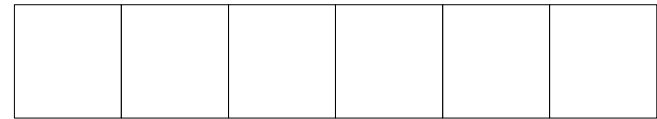
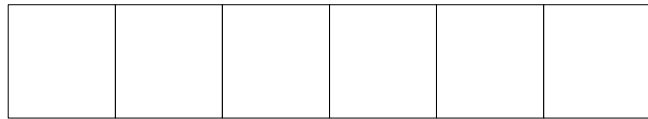
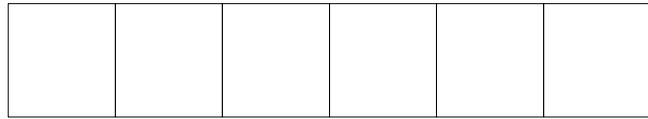
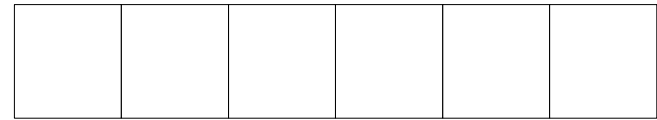
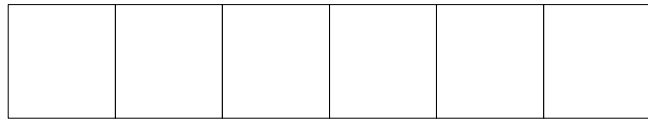
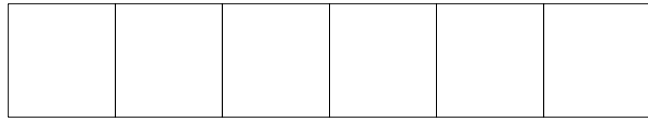
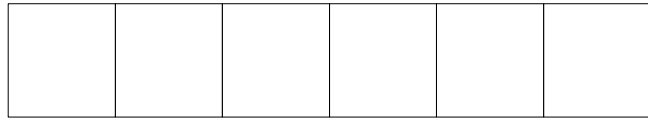
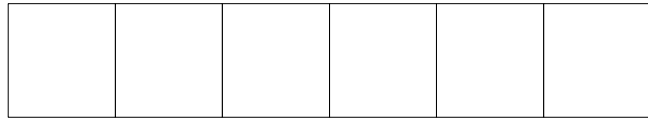
# Better Algorithms

- Can we actually hope to get close to our theoretical  $O(n \log n)$  limit?
- You know we can because you've met mergesort before.
  - In ML it was a lovely short algorithm that did a great job sorting lists
  - It has some drawbacks when we look at arrays but we'll get to that shortly...

# Mergesort: Idea (recap)



# Mergesort: Array Example

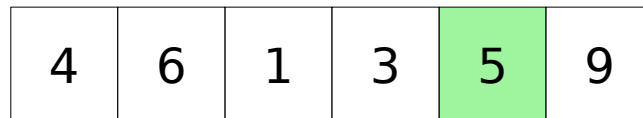


# Mergesort: Analysis

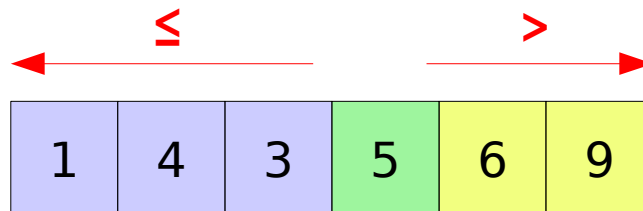
# Mergesort: Analysis

# Quicksort: Idea

- Recursive like mergesort, except it doesn't just slice the array into two
- The basic idea is to pick a **pivot element**
  - Any element will do, although we might get better results if we choose more carefully

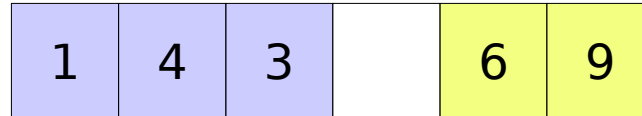


- We then partition the array into those bigger than the pivot and those smaller than the pivot

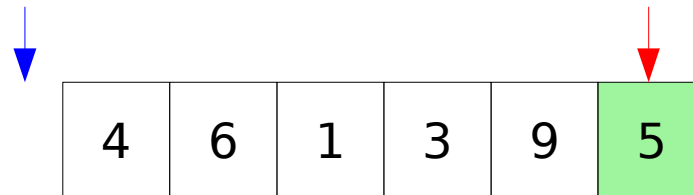


# Quicksort: Idea

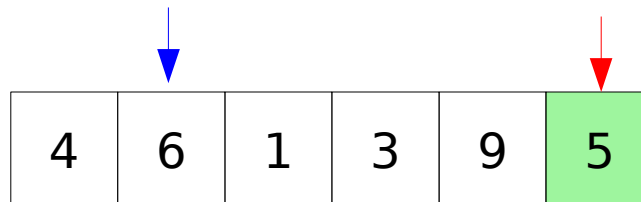
- Now we recursively apply quicksort to the two partitions



- How do we partition?
  - Have two pointers, **L** and **R**

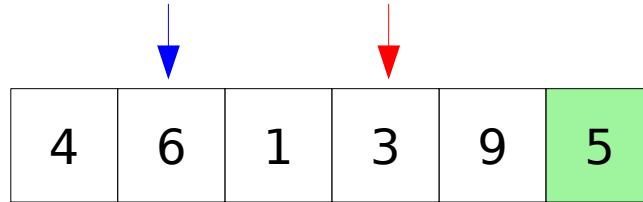


1. Increment L until it points to something bigger than the pivot or  $L==R$

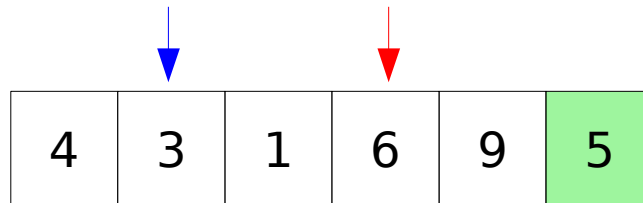


# Quicksort: Idea

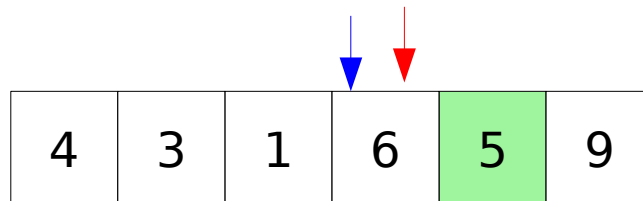
2. Decrement R until it points to something smaller than the pivot or  $L == R$



4. If  $(L \neq R)$  then swap the elements

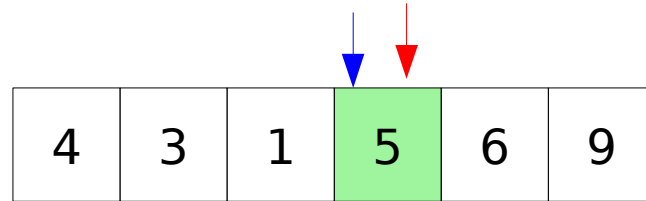


6. If  $(L \neq R)$  go to step 1 else continue



# Quicksort: Idea

5. Swap the pivot into the position R



- Partitioning done!

Beware: Depending on where your pivot is chosen to be, you need to think carefully about what gets swapped where: it's very easy to end up being off by one. You will find lots of subtle variations on the algorithm implementations (all of which work). I recommend you try writing a quicksort that works on any pivot (the one here works just if you choose the last element as the pivot)

# Quicksort: Example

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# Quicksort: Example

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# Quicksort: Example

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# Quicksort: Analysis (Gulp!)

- Best case
  - Magically we manage to always choose the pivot that splits the subarray being sorted into two
  - Then we have exactly what we had for mergesort
  - $f(n) = 2f(n/2) + kn$
  - That was  $O(n \log n)$  :-)

# Quicksort: Analysis (Gulp!)

- Worst case
  - We somehow manage to choose the biggest (or smallest) element as the pivot every time
  - Now we will always recurse on a subarray of size  $(n-1)$
  - $f(n) = f(n-1) + kn$
  - This is  $O(n^2)$  :-)

# Quicksort: Analysis (Gulp!)

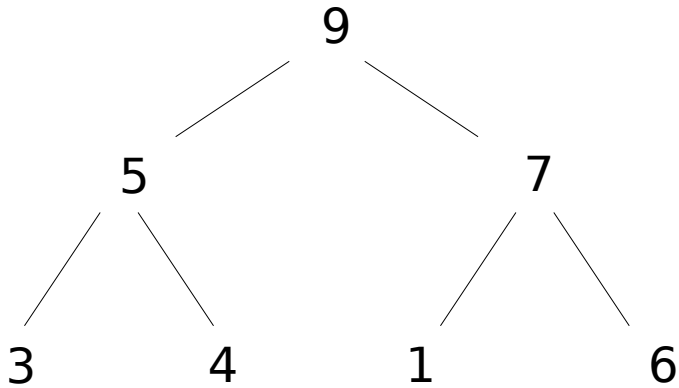
- So why is quicksort **the** choice for sorting?
  - It has a poor worst case
  - But the best case is generally *better* than mergesort (smaller constants in  $O(n \log n)$ ) and the average case is still  $O(n \log n)$
  - And quicksort sorts in place
  - So it comes down to trying to avoid the worst case, which is all about pivot choice

# Order Statistics with Quicksort

# Heapsort

- One last interesting algorithm
- Sorts in place and guarantees  $O(n \log n)$  for any input!
  - Although the constant of proportionality is greater than for quicksort
- Particularly interesting for us because it is based on a data structure called a heap (which we will use later on too)

# Introducing Heaps



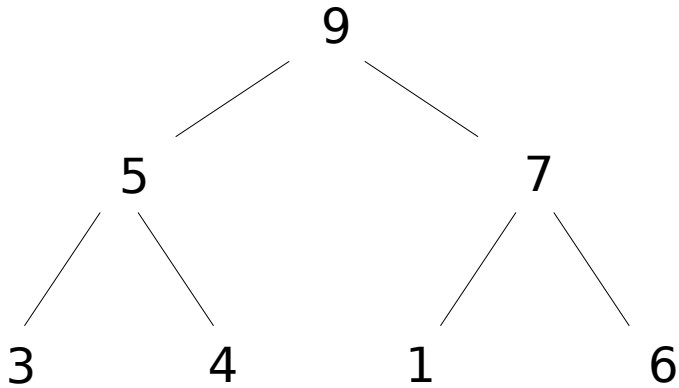
- Consider a simple binary tree (two branches out of each node)
- There is only one rule: the value of the two children must each be less than the value of the parent

## Note:

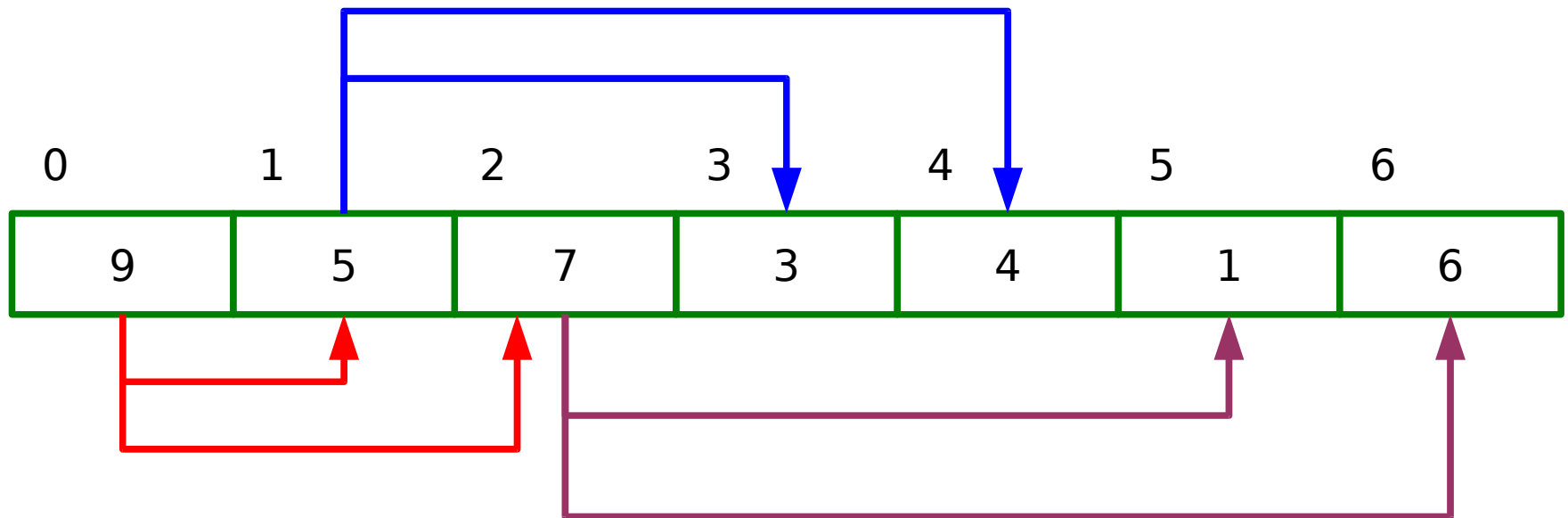
- The root of the tree is always the biggest number
- The root of any subtree is the biggest number in that subtree



# Introducing Heaps



- Now we represent this tree using an array in a certain way:
- The children of the node at  $[i]$  can be found at  $[2i+1]$  and  $[2i+2]$  (array starts at zero)

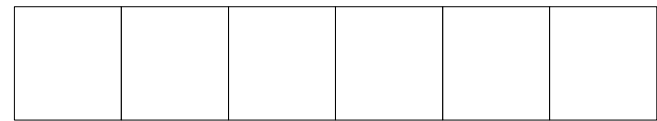
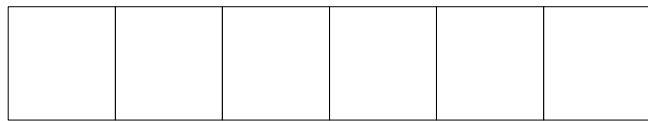
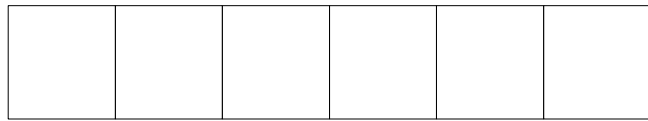
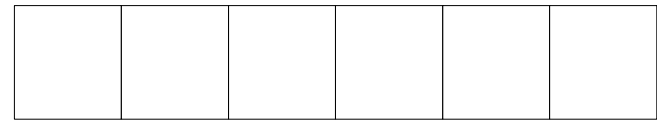
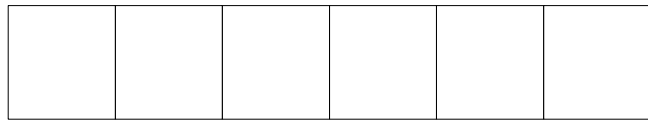
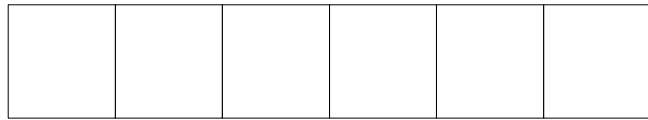
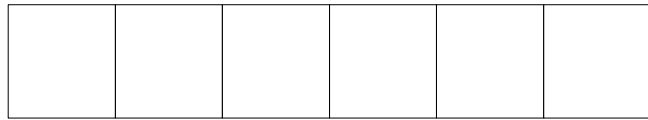
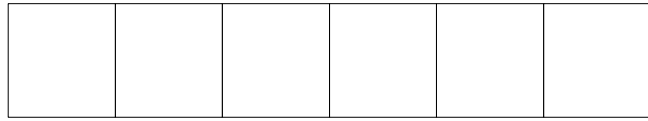


# Heapsort

- Heapsort proceeds as follows:
  1. Make your data into a heap in the array  $[0\dots n]$
  2. Swap the element at the end of the array with the head of the heap
  3. Heapsort the array  $[0\dots n-1]$
  4. Loop to step 2.

# Heapsort: Graph View

# Heapsort: Array View



# Heapsort: Analysis

# Heapsort: Analysis