# **Continuous Mathematics**

## R. J. Gibbens Computer Laboratory

#### Computer Science Tripos, Pt IB & II (G) Diploma in Computer Science University of Cambridge

Michaelmas Term 2004

- Review of analysis
  - → Limits, continuity and differentiability;
  - → Power series & transcendental functions;
  - $\rightarrow$  Taylor series;
  - $\rightarrow$  Complex variables.
- ► Fourier series
  - $\rightarrow$  Introduction & general properties;
  - $\rightarrow$  Examples.
- > Basis functions & decompositions
  - → Expansion basis functions;
  - → Orthogonality, inner products & completeness.
- Representation of signals
  - → Fourier transforms;
  - $\rightarrow$  Wavelets.

- Understand representation in terms of basis functions;
- Be fluent in the use and properties of complex variables;
- Grasp key properties and uses of Fourier analysis and its relation to wavelet analysis.

### **Related courses**

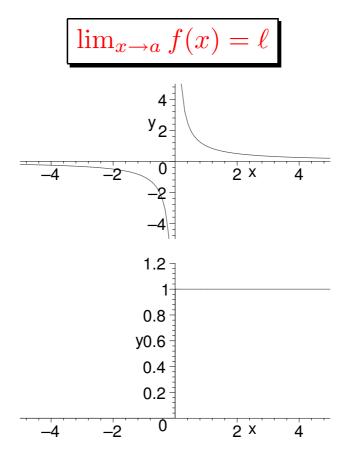
- Computer Graphics & Image Processing;
- Information Theory & Coding;
- Computer Vision;
- Artificial Intelligence I;
- Artificial Intelligence II;
- Quantum Computing;
- Digital Signal Processing.

# Review of analysis

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#### Limit of a function

If we can make the function f(x) arbitrarily close to  $\ell$  by making x close to a then  $\ell$  is the *limit* of f(x) as  $x \to a$ , written



Rigorous definition:  $\forall \epsilon > 0 \ \exists \delta > 0$  such that

 $|f(x) - \ell| < \epsilon$  when  $|x - a| < \delta$ .

#### Continuity

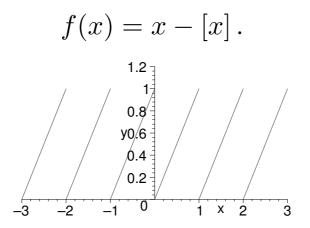
A function, f(x), is said to be *continuous* at x = a if the following three conditions hold

- $\succ \lim_{x \to a} f(x)$  exists;
- > f(x) is defined at x = a, and
- $\succ \lim_{x \to a} f(x) = f(a)$ .

Otherwise, the function is said to be discontinuous at x = a. A function is continuous if it has no points of discontinuity.

At a point of discontinuity, the discontinuity may be *finite* or *infinite*.

Consider the example of

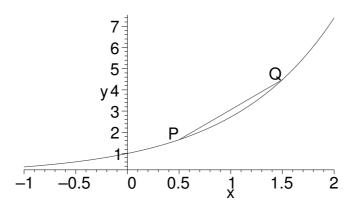


A function, f(x), is *differentiable at* x if as  $\delta x \to 0$ 

$$\frac{df}{dx} \equiv f'(x) \equiv \frac{f(x + \delta x) - f(x)}{\delta x} \to \text{finite limit}.$$

 $\frac{df}{dx}$  (or f'(x)) is known as the *derivative*. A function is *differentiable* if it's derivative exists everywhere.

The existence of the derivative at a point, x, corresponds to there being a *tangent* to the function, f(x), whose gradient is f'(x).



product & quotient rules for differentiation;
 differentiability => continuity.

If the partial sums of a series

$$S_n = a_1 + a_2 + a_3 + \ldots + a_n = \sum_{r=1}^n a_r.$$

converge to a finite limit, *S*, then the infinite series is said to be *convergent*. Otherwise, it is *divergent* (either infinite limit or oscillates).

Example: geometric series

$$\sum_{r=0}^{n} ap^{r} = S_{n} = a(1+p+p^{2}+\dots+p^{n}) = a\frac{1-p^{n+1}}{1-p}$$
  
If  $|p| < 1$  then *convergent*  
and  $S = \lim_{n \to \infty} s_{n} = \frac{a}{1-p}$ . Otherwise,  
*divergent*.

D'Alembert's ratio test says that

 $\lim_{r \to \infty} |a_{r+1}/a_r| = k < 1 \Longrightarrow \text{convergent}$  $\lim_{r \to \infty} |a_{r+1}/a_r| = k > 1 \Longrightarrow \text{divergent}.$ 

Power series are infinite series of the form

$$\sum_{r=0}^{\infty} a_r x^r = a_0 + a_1 x + a_2 x^2 + \dots$$

D'Almbert's ratio test tells us that such power series are convergent if

$$\lim_{r \to \infty} \left| \frac{a_{r+1} x^{r+1}}{a_r x^r} \right| = |x| \lim_{r \to \infty} \left| \frac{a_{r+1}}{a_r} \right| = k < 1.$$

That is, if x lies in the *interval of convergence* 

$$-R < x < R$$

where the *radius of convergence*, R, is given by

$$R = \lim_{r \to \infty} \left| \frac{a_r}{a_{r+1}} \right|$$

The power series could either converge or diverge if |x| = R.

#### **Transcendental functions**

The following functions, members of a class of functions known as *transcendental functions*, are defined within their intervals of convergence by these power series representations

$$\begin{aligned} \sin x &:= x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots \quad \text{all } x \\ \cos x &:= 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots \quad \text{all } x \\ \log_e(1+x) &:= x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \cdots \quad -1 < x \le 1 \\ e^x &:= 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots \quad \text{all } x \\ \sinh x &:= \frac{e^x - e^{-x}}{2} = x + \frac{x^3}{3!} + \frac{x^5}{5!} + \cdots \quad \text{all } x \\ \cosh x &:= \frac{e^x + e^{-x}}{2} = 1 + \frac{x^2}{2!} + \frac{x^4}{4!} + \frac{x^6}{6!} + \cdots \quad \text{all } x \end{aligned}$$

There are convenient properties for the sum, difference, products & composition of power series.

Subject to some important conditions on  $f(\boldsymbol{x})$ 

$$f(a+x) = f(a) + \frac{x}{1!}f'(a) + \frac{x^2}{2!}f''(a) + \dots = \sum_{r=0}^{\infty} \frac{x^r}{r!}f^{(r)}(a)$$

$$f(x) = A_0 + A_1(x-a) + A_2(x-a)^2 + A_3(x-a)^3 + \cdots$$

$$f'(x) = A_1 + 2A_2(x - a) + 3A_3(x - a)^2 + \cdots$$
  

$$f''(x) = 2A_2 + 3 \cdot 2A_3(x - a) + 4 \cdot 3A_4(x - a)^2 + \cdots$$
  

$$f'''(x) = 3!A_3 + 4!A_4(x - a) + \cdots$$
  

$$f^{(n)}(x) = n!A_n + (n + 1)!A_{n+1}(x - a) + \cdots$$

Putting x = a now gives

$$f(a) = A_0$$
  $f'(a) = A_1$   
 $f''(a) = 2!A_2$   $f'''(a) = 3!A_3$   
 $f^{(n)}(a) = n!A_n$ .

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#### **Overview**

- Imaginary number, i;
- > Argand diagram;
- Modulus, argument & complex conjugate;
- > Algebra of imaginary numbers;
- > Euler's equation:

 $e^{i\theta} = \cos\theta + i\sin\theta$ 

We introduce the *imaginary number*,  $i = \sqrt{-1}$  so as to solve a wider class of equations. For example,

 $z^{2} + 1 = 0 \Longrightarrow z = \pm i$  $z^{2} - 2z + 2 = 0 \Longrightarrow z = 1 \pm i.$ 

Note that

$$i^2 = -1$$
,  $i^3 = i^2 i = -i$ ,  $i^4 = (i^2)^2 = 1$ ,

and

$$i^{-1} = \frac{1}{i} = \frac{i}{i^2} = -i, \quad i^{-2} = -1, \quad i^{-3} = \frac{1}{i^3} = \frac{1}{-i} = i.$$

Complex numbers, z, are written

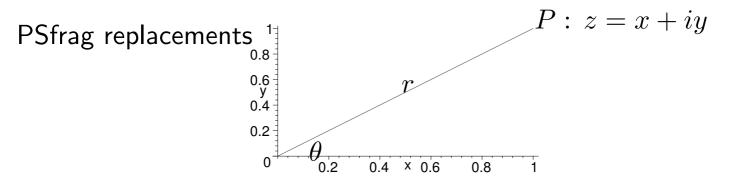
$$z = x + iy$$
 or  $z = (x, y)$ 

#### **Argand diagrams**

The idea is to represent any complex number z = x + iy by the point P : (x, y) in the plane, where x is the *real part* of z and y is the *imaginary part*.

Then using polar coordinates (and for  $z \neq 0$ )

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \\ z &= x + iy = r(\cos \theta + i \sin \theta) \,. \end{aligned}$$



Given

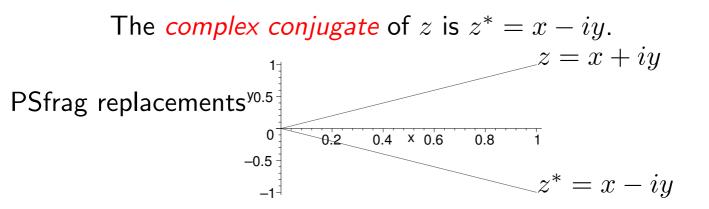
$$z = x + iy = r(\cos\theta + i\sin\theta)$$

define the *modulus* and *argument* of z as

$$|z| = r = \sqrt{x^2 + y^2}$$
  $\arg(z) = \theta$ .

Note that  $\arg(0)$  is *undefined*. Also,  $\theta + 2k\pi$  (k any integer) are also arguments of z. The *Principal value*, written  $\operatorname{Arg}(z)$ , is chosen so that

$$-\pi < \theta \leq \pi$$
 .



If  $z_1 = x_1 + iy_1$  and  $z_2 = x_2 + iy_2$  then the *sum* and *difference* of  $z_1$  and  $z_2$  are defined as

$$z_1 + z_2 = (x_1 + x_2) + i(y_1 + y_2)$$
  
$$z_1 - z_2 = (x_1 - x_2) + i(y_1 - y_2).$$

The *product* of  $z_1$  and  $z_2$  is defined as

$$z_1 z_2 = (x_1 + iy_1)(x_2 + iy_2)$$
  
=  $(x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1).$ 

The *quotient* of two complex numbers is defined analagously

$$\begin{split} \frac{z_2}{z_1} &= \frac{x_2 + iy_2}{x_1 + iy_1} \\ &= \frac{(x_2 + iy_2)(x_1 - iy_1)}{(x_1 + iy_1)(x_1 - iy_1)} \\ &= \frac{x_1x_2 + y_1y_2}{x_1^2 + y_1^2} + i\frac{x_1y_2 - y_1x_2}{x_1^2 + y_1^2} \end{split}$$
provided  $x_1^2 + y_1^2 = |z_1|^2 \neq 0.$ 

Using the power series representations for  $e^z, \sin z$  and  $\cos z$ 

$$e^{z} = 1 + z + \frac{z^{2}}{2!} + \frac{z^{3}}{3!} + \frac{z^{4}}{4!} + \cdots$$
$$\sin z = z - \frac{z^{3}}{3!} + \frac{z^{5}}{5!} - \frac{z^{7}}{7!} + \cdots$$
$$\cos z = 1 - \frac{z^{2}}{2!} + \frac{z^{4}}{4!} - \frac{z^{6}}{6!} + \cdots$$

So, putting  $z = i\theta$ , gives

$$e^{i\theta} = 1 + i\theta + \frac{(i\theta)^2}{2!} + \frac{(i\theta)^3}{3!} + \frac{(i\theta)^4}{4!} + \frac{(i\theta)^5}{5!} + \cdots$$
  
=  $1 + i\theta - \frac{\theta^2}{2!} - i\frac{\theta^3}{3!} + \frac{\theta^4}{4!} + i\frac{\theta^5}{5!} - \cdots$   
=  $\left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \cdots\right) + i\left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \cdots\right)$   
=  $\cos\theta + i\sin\theta$ 

$$e^{i\theta} = \cos\theta + i\sin\theta$$

# Fourier series

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Taylor series allow us to represent certain functions as power series. Such functions must be *continuous* and *infinitely differentiable* within the interval of convergence.

We now consider how functions that may be neither differentiable nor continuous at certain points can be represented by a trigonometric series of the form

$$\frac{a_0}{2} + \sum_{r=1}^{\infty} \left( a_r \cos rx + b_r \sin rx \right)$$

where  $a_0, a_r$  and  $b_r$  are constants for  $r = 1, 2, \ldots$ 

Since this trigonometric series is unchanged by replacing x by  $x + 2k\pi$ , where k is an integer, we can only use it to represent a certain restricted class of functions. We say that a function, f(x), is *periodic* with period p if

$$f(x+p) = f(x)$$

for all x. So, it suffices if we know the value of f(x) for all values in the interval  $0 < x \le p$  of length p.

#### **Examples**

Suppose that f(x) is any integrable function defined on the interval  $-\pi < x \leq \pi$ . Let,

$$a_{0} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) dx,$$
  

$$a_{r} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos rx dx, \qquad r = 1, 2, 3, \dots,$$
  

$$b_{r} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin rx dx, \qquad r = 1, 2, 3, \dots$$

then the resulting series is called the *Fourier series* and the coefficients are the *Fourier coefficients* 

$$\frac{a_0}{2} + \sum_{r=1}^{\infty} \left( a_r \cos rx + b_r \sin rx \right) \,.$$

**Question**: when does the Fourier series for f(x) converge to f(x)?

To answer this question we need to define *Dirichlet's conditions*.

#### **Dirichlet's conditions**

Suppose f(x) is defined arbitrarily in the interval  $-\pi < x \le \pi$  and extended to other values of x by the periodicity condition  $f(x + 2k\pi) = f(x)$  where k is an integer.

The function f(x) satisfies the *Dirichlet's* conditions, if in  $-\pi < x \le \pi$ ,

- f(x) is continuous except for a *finite number* of points of finite discontinuities, and
- has only a *finite number* of maxima and minima.

(Such functions are also called *piecewise regular*.)

Fourier was able to show that a function, f(x), satisfying the Dirichlet conditions has a Fourier series which converges to f(x) at all points in the interval where f(x) is *continuous*.

Moreover, at a point of discontinuity (necessarily finite), say at  $x = x_0$ , the Fourier series converges to the value

$$\frac{1}{2}\lim_{\delta \to 0} \left\{ f(x_0 + \delta) + f(x_0 - \delta) \right\} \,,$$

which is just the mean of the two limiting values of f(x) as x approaches  $x_0$  from the right and left-hand sides. If r and s are positive integers or zero then it follows by simple integration that

$$\int_{-\pi}^{\pi} \cos rx \cos sx \, dx = \begin{cases} 0 & \text{for } r \neq s \\ 2\pi & \text{for } r = s = 0 \\ \pi & \text{for } r = s > 0 \end{cases}$$
$$\int_{-\pi}^{\pi} \sin rx \sin sx \, dx = \begin{cases} 0 & \text{for } r \neq s \\ 0 & \text{for } r = s = 0 \\ \pi & \text{for } r = s > 0 \end{cases}$$
$$\int_{-\pi}^{\pi} \sin rx \cos sx \, dx = 0 \qquad \text{for all } r \text{ and } s$$
$$\int_{-\pi}^{\pi} \cos rx \, dx = \begin{cases} 0 & \text{for } r > 0 \\ 2\pi & \text{for } r = 0 \end{cases}$$
$$\int_{-\pi}^{\pi} \sin rx \, dx = 0 \qquad \text{for all } r .$$

## Derivation of Fourier coefficients, ctd

Using these results and multiplying both sides of

$$f(x) = \frac{a_0}{2} + \sum_{r=1}^{\infty} (a_r \cos rx + b_r \sin rx)$$

by  $\cos sx$  and integrating from  $x = -\pi$  to  $\pi$ yields expressions for  $a_0$  and  $a_r$  (r = 1, 2, 3, ...).

Similarly, multiplying both sides by  $\sin sx$  and integrating from  $x = -\pi$  to  $\pi$  yields expressions for  $b_r$  (r = 1, 2, 3, ...).

Note that we can merge the expressions for  $a_0$ and  $a_r$  into the single formula

$$a_r = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos rx \, dx \,,$$

as r takes values  $r = 0, 1, 2, \ldots$ 

A function f(x) is said to be *even* if for all x

f(x) = f(-x)

So, for example,  $f(x) = \cos(x)$  is an even function.

Similarly, a function  $f(\boldsymbol{x})$  is said to be odd if for all  $\boldsymbol{x}$ 

f(x) = -f(-x)

So, for example,  $f(x) = \sin(x)$  is an odd function.

Suppose that f(x) in the interval  $-\pi < x \le \pi$  is an *even* function then for all r = 1, 2, 3, ...

$$a_{0} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) dx = \frac{2}{\pi} \int_{0}^{\pi} f(x) dx,$$
  

$$a_{r} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos rx dx = \frac{2}{\pi} \int_{0}^{\pi} f(x) \cos rx dx,$$
  

$$b_{r} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin rx dx = 0.$$

Hence, if f(x) is an even function its Fourier series reduces to a series where all the sine terms vanish.

Alternatively, suppose that f(x) in the interval  $-\pi < x \le \pi$  is an *odd* function then for all  $r = 1, 2, 3, \ldots$ 

$$a_{0} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) dx = 0,$$
  

$$a_{r} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos rx dx = 0,$$
  

$$b_{r} = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin rx dx = \frac{2}{\pi} \int_{0}^{\pi} f(x) \sin rx dx.$$

Hence, if f(x) is an odd function its Fourier series reduces to a series where all the cosine terms vanish.

### Change of interval (period)

Instead of using the interval  $-\pi < x \leq \pi$  and a period of  $2\pi$  consider the more general situation of an interval  $-T < x \leq T$  with period 2T.

So suppose that f(x) satisifes the Dirichlet conditions in  $-T < x \le T$  and is defined outside this interval by the periodicity condition f(x + 2Tk) = f(x), where k is an integer. Then, writing  $z = \pi x/T$  gives

$$f(x) = f\left(\frac{Tz}{\pi}\right) = F(z),$$

where now F(z) is a periodic function of z of period  $2\pi$ .

Hence in  $-\pi < z \leq \pi$ 

$$F(z) = \frac{a_0}{2} + \sum_{r=1}^{\infty} \left( a_r \cos rz + b_r \sin rz \right) \,,$$

where

$$a_r = \frac{1}{\pi} \int_{-\pi}^{\pi} F(z) \cos rz \, dz \,, \quad (r = 0, 1, 2, \ldots) \,,$$
$$b_r = \frac{1}{\pi} \int_{-\pi}^{\pi} F(z) \sin rz \, dz \,, \quad (r = 1, 2, 3, \ldots) \,.$$

Thus, putting  $z = \pi x/T$ , gives in  $-T < x \leq T$ 

$$f(x) = \frac{a_0}{2} + \sum_{r=1}^{\infty} \left( a_r \cos \frac{\pi xr}{T} + b_r \sin \frac{\pi xr}{T} \right)$$

where

$$a_r = \frac{1}{T} \int_{-T}^{T} f(x) \cos \frac{\pi x r}{T} dx, \quad (r = 0, 1, 2, ...),$$
$$b_r = \frac{1}{T} \int_{-T}^{T} f(x) \sin \frac{\pi x r}{T} dx, \quad (r = 1, 2, 3, ...).$$

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#### **Compact complex representation**

Using the Euler relation  $e^{i\theta} = \cos\theta + i\sin\theta$ 

$$f(x) = \frac{a_0}{2} + \sum_{r=1}^{\infty} (a_r \cos rx + b_r \sin rx)$$

can be written as

$$f(x) = \sum_{r=-\infty}^{\infty} c_r e^{irx}$$

where for all r > 0

$$c_r = \frac{1}{2} (a_r - ib_r)$$
 and  $c_{-r} = \frac{1}{2} (a_r + ib_r)$ 

and

$$c_0 = \frac{1}{2}a_0.$$

Also, for  $r=0,\pm 1,\pm 2,\ldots$  ,

$$c_r = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) e^{-irx} \, dx \, .$$

# Compact complex representation, ctd

Note that the coefficients,  $c_r$ , are complex numbers and that for each positive integer  $r = 1, 2, 3, \ldots$  we have two coefficients:  $c_r$ and  $c_{-r}$ .

Assuming f(x) is a real-valued function, these two coefficients are complex conjugates, that is,

 $c_{-r} = c_r^* \qquad \text{for } r > 0 \, .$ 

In summary, we have obtained a *represention* of f(x) in terms of a (doubly) infinite series of complex exponential functions

$$f(x) = \sum_{r=-\infty}^{\infty} c_r e^{irx}$$

where

$$c_r = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) e^{-irx} dx.$$

Consider two examples

> square wave

$$f(x) = \begin{cases} -1 & -\pi < x < 0, \\ 1 & 0 < x \le \pi. \end{cases}$$

with period  $2\pi$ , and

sawtooth wave

$$f(x) = x \quad -1 < x \le 1$$

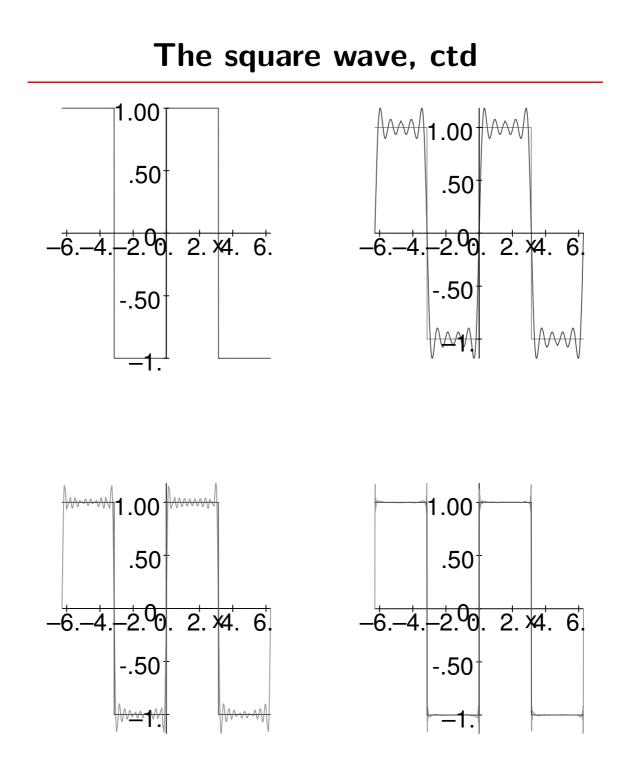
with period 2.

The square wave is an *odd* function so  $a_r = 0$  for all  $r \ge 0$ . The sine terms can be evaluated by

$$b_r = \frac{2}{\pi} \int_0^\pi \sin rx \, dx$$
$$= \frac{2}{r\pi} (1 - \cos r\pi)$$
$$= \begin{cases} \frac{4}{r\pi} & r \text{ odd }, \\ 0 & r \text{ even }. \end{cases}$$

Hence, the Fourier series expansion of the square wave function in  $-\pi < x \leq \pi$  is

$$f(x) = \frac{4}{\pi} \left( \sin x + \frac{\sin 3x}{3} + \frac{\sin 5x}{5} + \cdots \right) \,.$$



Again we have an *odd* function and, using the change of interval relations,

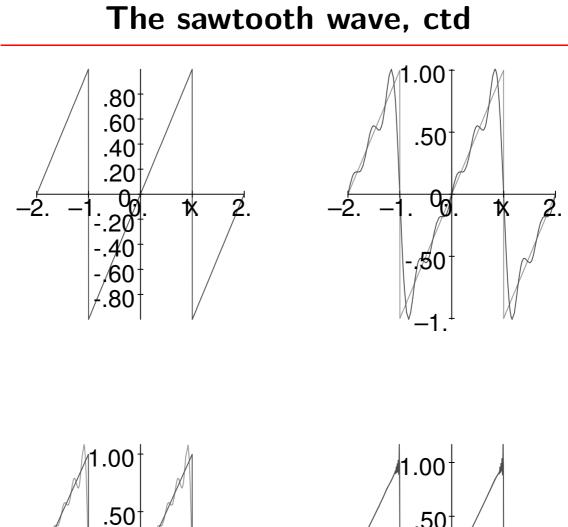
$$b_r = \int_{-1}^{1} x \sin \pi r x \, dx$$
$$= -\frac{2}{\pi r} (-1)^r \, .$$

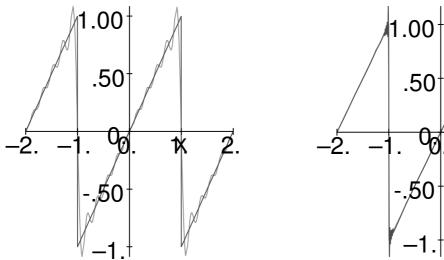
Hence in the interval -1 < x < 1

$$f(x) = x = \frac{2}{\pi} \left( \sin \pi x - \frac{1}{2} \sin 2\pi x + \frac{1}{3} \sin 3\pi x - \cdots \right)$$

At  $x = \pm 1$ , finite discontinuities occur. Hence at these points the series does not represent x but converges to the value

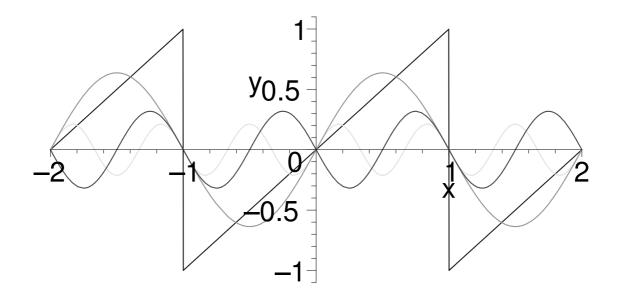
$$\frac{1}{2}\lim_{\delta \to 0} \left\{ f(x_0 + \delta) + f(x_0 - \delta) \right\} = \frac{1}{2} \left\{ 1 + (-1) \right\} = 0.$$





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## Basis functions and decompositions

## Examples of series representation: Taylor's series

Recall, that *Taylor's series* allows us to represent certain functions as

$$f(x) = \sum_{r=0}^{\infty} \frac{(x-a)^r}{r!} f^{(r)}(a)$$

or, equivalently, for some constants  $c_r$ , as the power series

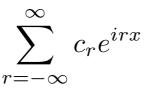
$$\sum_{r=0}^{\infty} c_r x^r$$

For example,

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots$$

## Examples of series representation: Fourier series

*Fourier series* allows us to represent certain periodic functions by the series



that is, using Euler's equation, in terms of the functions

 $1, \cos x, \sin x, \cos 2x, \sin 2x, \cos 3x, \sin 3x, \ldots$ 

For example, the periodic sawtooth function in the interval -1 < x < 1 has the Fourier series

$$\frac{2}{\pi}\left(\sin\pi x - \frac{1}{2}\sin 2\pi x + \frac{1}{3}\sin 3\pi x - \cdots\right) \,.$$

#### Basis functions: general approach

The Taylor and Fourier series are just two examples of a general approach where we seek to represent a given function f(x) in terms of linear combinations

$$f(x) = \sum_{k} c_k \Psi_k(x)$$

of certain other functions,  $\Psi_k(x)$ , called the *expansion basis functions*.

For example, with the Fourier series the basis functions are the complex exponentials

$$\Psi_k(x) = e^{i\mu_k x}$$

where  $k = 0, \pm 1, \pm 2, ...$  and the *frequency* of the kth basis function  $\Psi_k(x)$  is  $\mu_k = k$ .

Note that changing the period from  $2\pi$  to 2T has the effect of changing the frequency of the kth basis function to  $\mu_k = \pi k/T$ .

## Basis functions: application to systems analysis

This approach proves to be very useful because it allows us to choose some universal set of functions (the basis functions) and then represent many other functions in terms of just a set of numerical coefficients (the constants,  $c_k$ ).

In the analysis of systems a major benefit of doing this is that knowledge of how members of the chosen universal set of basis functions behave in the system gives us knowledge about how arbitrary input functions will be treated by the system.

For periodic functions we only need to derive the response when the input is in one of the relatively simple forms:  $\cos(rx)$  or  $\sin(rx)$ , for integer choices of r.

A set of basis functions is called *orthogonal* if they satisfy the rule that the integral of the conjugate product of any two distinct basis functions equals zero, that is,

$$\int_{-T}^{T} \Psi_k^*(x) \Psi_j(x) \, dx = 0 \quad (k \neq j)$$

where the integral is taken over one period,  $-T < x \leq T$ .

We will later consider the case of *aperiodic* functions corresponding to letting  $T \to \infty$  so that the orthogonality condition then becomes

$$\int_{-\infty}^{\infty} \Psi_k^*(x) \Psi_j(x) \, dx = 0 \quad (k \neq j) \, .$$

We call such integrals, *inner products*, and use the angle bracket notation

$$<\Psi_k(x), \Psi_j(x)>:=\int_{-\infty}^{\infty}\Psi_k^*(x)\Psi_j(x)\,dx$$
.

The analogous notion for vectors is the *scalar product*,

 $\mathbf{x}\cdot\mathbf{y}$ 

between two vectors  $\mathbf{x}$  and  $\mathbf{y}$  — a notion which is closely related to notions of *length*, *distance* and *projection* in Euclidean space.

Consider  $\Psi_k(x) = e^{ikx}$  then  $\Psi_k^*(x) = e^{-ikx}$  and so the inner product  $< \Psi_k(x), \Psi_j(x) >$  is given by

$$\begin{aligned} \int_{-\pi}^{\pi} \Psi_{k}^{*}(x)\Psi_{j}(x) \, dx \\ &= \int_{-\pi}^{\pi} e^{-ikx} e^{ijx} \, dx \\ &= \int_{-\pi}^{\pi} e^{i(j-k)x} \, dx \\ &= \int_{-\pi}^{\pi} \left(\cos((j-k)x) + i\sin((j-k)x) \, dx \right) \\ &= \begin{cases} 0 \quad (k \neq j) \\ 2\pi \quad (k = j) \end{cases} \end{aligned}$$

So, we see that the basis functions  $e^{ikx}$  are indeed orthogonal with period  $2\pi$ .

#### **Orthonormal basis functions**

If, in addition to orthogonality, the set of basis functions satisfy the property that the inner product of every basis function with itself is equal to one, that is,

$$\langle \Psi_j(x), \Psi_j(x) \rangle = \int_{-\infty}^{\infty} \Psi_j^*(x) \Psi_j(x) dx = 1$$

then the set of basis functions is said to be *orthonormal*.

That is,

$$<\Psi_k(x), \Psi_j(x)>= \begin{cases} 0 & (k \neq j) \\ 1 & (k=j) . \end{cases}$$

Given a set of orthogonal basis functions we can make them orthonormal just by scaling each of them by a suitable factor.

#### **Derivation of expansion coefficients**

Consider a function represented in terms of orthonormal basis functions

$$f(x) = \sum_{k} c_k \Psi_k(x) \,.$$

Question: How do we determine the  $c_k$ ? Consider, for any k,

$$<\Psi_k(x), f(x) > = \int_{-T}^T \Psi_k^*(x) f(x) \, dx$$
$$= \int_{-T}^T \Psi_k^*(x) \sum_j c_j \Psi_j(x) \, dx$$
$$= \sum_j c_j \int_{-T}^T \Psi_k^*(x) \Psi_j(x) \, dx$$
$$= \sum_j c_j < \Psi_k(x), \ \Psi_j(x) >$$
$$= c_k$$

### **Completeness of basis functions**

We say that a set of basis functions is *complete* when all functions of interest can be represented by an expansion of the form

$$\sum_k c_k \Psi(x) \, .$$

In other words, the space of basis functions spans the required set of functions.

More rigorously, we can say that a set of basis functions is complete if no nontrivial function of interest, f(x), is orthogonal to *all* the basis functions  $\Psi_k(x)$ . That is,

$$\langle f(x), \Psi_k(x) \rangle = 0$$
 for all  $k$ 

implies that f is the trivial function f(x) = 0 for all x.

Suppose that the functions  $\Psi_k(x)$  form orthonormal basis functions.

- ➤ One way to think of the coefficients, c<sub>k</sub>, is that they measure the projection of the some function f(x) along the "coordinate" given by basis function Ψ<sub>k</sub>(x).
- The set of basis functions of the form e<sup>ikx</sup> (k = 0, ±1, ±2,...) can be shown to be complete for the space of piecewise regular functions with period 2π.
- Each function e<sup>ikx</sup> gives one "coordinate" which together are sufficient to represent any such piecewise regular function.

# Representation of signals

#### Fourier transforms: motivation

Fourier series allow us to represent a class of periodic functions on the interval  $-T < x \leq T$ . We now look at the representation of *aperiodic* functions over the infinite range  $-\infty < x < \infty$ .

Consider the Fourier series

$$f(x) = \sum_{k} c_k e^{i\mu_k x}$$

and, informally, take the limit to add up over all possible frequencies  $-\infty < \mu < \infty$  to yield the integral representation for f(x)

$$f(x) = \int_{-\infty}^{\infty} F(\mu) e^{i\mu x} \, d\mu \,.$$

The orthogonality relations for complex exponentials then gives us that

$$F(\mu) = \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x) e^{-i\mu x} dx.$$

The function  $F(\mu)$  is known as the *Fourier transform* of f(x).

Whereas, the expression

$$f(x) = \int_{-\infty}^{\infty} F(\mu) e^{i\mu x} \, d\mu$$

allows us to invert the transform,  $F(\mu)$ , and return to the original function f(x).

Beware: there are other conventions for the choice of basis functions which lead to minor variants of these definitions, the position of the  $2\pi$ 's is critical!

## **Properties of the Fourier transform**

The Fourier transform  $F(\mu)$  of a function f(x)tells us about the contribution to f made by the complex exponential  $e^{i\mu x}$  at frequency  $\mu$ .

The transformation can be thought of as taking us from the time (or space) domain, x, to a representation in the frequency domain,  $\mu$ .

There are a number of helpful properties of Fourier transforms according to the following operations of

> shift;

- scale (or dilation);
- differentiation;
- convolution.

Suppose we shift the original function f(x) by some displacement  $\alpha$ . What happens to the Fourier transform?

Taking the Fourier transform of  $f(x-\alpha)$  gives

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} f(x-\alpha) e^{-i\mu x} dx$$
$$= \frac{e^{-i\mu\alpha}}{2\pi} \int_{-\infty}^{\infty} f(u) e^{-i\mu u} du$$
$$= e^{-i\mu\alpha} F(\mu)$$

Thus the Fourier transform of the shifted function  $f(x - \alpha)$  is obtained by multiplication of the original Fourier transform by the factor  $e^{-i\mu\alpha}$ .

The scale (or dilation) property tells us what happens when we consider  $f(\alpha x)$  instead of f(x) (for  $\alpha \neq 0$ ).

The Fourier transform of  $f(\alpha x)$  is given by

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} f(\alpha x) e^{-i\mu x} dx$$

$$= \begin{cases} \frac{1}{2\pi\alpha} \int_{-\infty}^{\infty} f(u) e^{-i(\mu/\alpha)u} du & (\alpha > 0) \\ \frac{1}{2\pi\alpha} \int_{\infty}^{-\infty} f(u) e^{-i(\mu/\alpha)u} du & (\alpha < 0) \end{cases}$$

$$= \frac{1}{|\alpha|} F\left(\frac{\mu}{\alpha}\right).$$

Suppose f(x) is a differentiable function. What does the Fourier transform of f'(x) look like? Informally, we have that

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} f'(x) e^{-i\mu x} dx$$
  
=  $\frac{1}{2\pi} \left[ e^{-i\mu x} f(x) \right]_{x=-\infty}^{x=\infty} + \frac{i\mu}{2\pi} \int_{-\infty}^{\infty} f(x) e^{-i\mu x} dx$   
=  $i\mu F(\mu)$ .

Using integration by parts as well as assuming a regularity condition that  $f(x) \to 0$  as  $x \to \pm \infty$ .

For higher order derivatives we have that

$$\left(\frac{d}{dx}\right)^m f(x)$$
 has Fourier transform  $(i\mu)^m F(\mu)$ 

where m is the order of the derivative.

The *convolution* of two functions f(x) and g(x) is given by

$$h(x) = (f * g)(x) = \frac{1}{2\pi} \int_{\alpha = -\infty}^{\alpha = \infty} f(\alpha)g(x - \alpha) \, d\alpha \, .$$

Thus the convolution is a way of combining two functions which in a sense uses one to *"blur"* the other, making all possible relative shifts between two functions when computing the integral of their product.

Convolution is an extremely important operation in systems theory because it describes how any linear system f(t) acts on any input g(t) to generate the corresponding output h(t). The output is just given by the convolution of the input with the characteristic system response function, so that,

$$h(t) = f(t) * g(t) \,.$$

#### Fourier transforms and convolutions

Consider the Fourier transform of f \* g given by

$$\frac{1}{2\pi} \int_{x=-\infty}^{x=\infty} \frac{1}{2\pi} \int_{\alpha=-\infty}^{\alpha=\infty} f(\alpha)g(x-\alpha)e^{-i\mu x} d\alpha dx$$
$$= \frac{1}{2\pi} \int_{\alpha=-\infty}^{\alpha=\infty} \int_{x=-\infty}^{x=\infty} f(\alpha)e^{-i\mu \alpha}\frac{g(x-\alpha)e^{-i\mu(x-\alpha)}}{2\pi} dx d\alpha$$
$$= \frac{1}{2\pi} \int_{\alpha=-\infty}^{\alpha=\infty} f(\alpha)e^{-i\mu \alpha}G(\mu) d\alpha$$
$$= F(\mu)G(\mu).$$

Here f(x) and g(x) have Fourier transforms  $F(\mu)$  and  $G(\mu)$ , respectively.

#### Wavelets

*Wavelets* are a further method of representing functions which have received much interest in applied fields over the last several decades.

The approach fits into the general scheme of expansion using basis functions. Here we expand the functions f(x) in terms of a doubly-infinite series

$$f(x) = \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} d_{jk} \Psi_{jk}(x)$$

where  $\Psi_{jk}(x)$  are the basis functions.

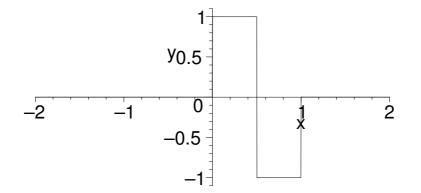
The basis functions arise from *shifting* and *scaling* operations applied to a single function,  $\Psi(x)$ , known as the *mother wavelet*.

The basis functions are given for integers  $j \mbox{ and } k$  by

$$\Psi_{jk}(x) = \Psi(2^j x - k)$$

A common example is the *Haar wavelet* whose mother function is both *localised* and *oscillatory* defined by

$$\Psi(x) = \begin{cases} 1 & \text{if } 0 \le x < \frac{1}{2} \ ,\\ -1 & \text{if } \frac{1}{2} \le x < 1 \ ,\\ 0 & \text{otherwise} \ . \end{cases}$$



#### Wavelet dilations and translations

The Haar mother wavelet oscillates and has a width (or scale) of one. The *dyadic dilates* of  $\Psi(x)$ , namely,

...,  $\Psi(2^{-2}x), \Psi(2^{-1}x), \Psi(x), \Psi(2x), \Psi(2^{2}x), \dots$ 

have widths

$$\dots, 2^2, 2^1, 1, 2^{-1}, 2^{-2}, \dots$$

respectively. Since the dilate  $\Psi(2^j x)$  has width  $2^{-j}$ , its translates

$$\Psi(2^{j}x-k) = \Psi(2^{j}(x-k2^{-j})), \quad k = 0, \pm 1, \pm 2, \dots$$

will cover the whole x-axis. The collection of coefficients  $d_{jk}$  are termed the *discrete wavelet transform* of the function f(x).

How should we intrepret the values  $d_{jk}$ ?

Since the Haar basis function  $\Psi(2^j x - k)$  vanishes except when

 $0 \le 2^j x - k < 1 \,, \quad \text{that is} \quad k 2^{-j} \le x < (k + 1) 2^{-j}$ 

we see that  $d_{jk}$  gives us information about the behaviour of f near the point  $x = k2^{-j}$  measured on the scale of  $2^{-j}$ .

For example, the coefficients  $d_{-10,k}$ ,  $k = 0, \pm 1, \pm 2, \ldots$  correspond to variations of fthat take place over intervals of length  $2^{10} = 1024$  while the coefficients  $d_{10,k}$   $k = 0, \pm 1, \pm 2, \ldots$  correspond to fluctuations of fover intervals of length  $2^{-10}$ .

These observations help explain how the discrete wavelet transform can be an exceptionally efficient scheme for representing functions.

## **Comparison with Fourier analysis**

Some of the practical motivations underlying the use of expansion basis functions such as Fourier analysis or wavelet analysis are

- improved understanding,
- denoising signals, and
- ➤ data compression.

By representation of signals or functions in other forms these tasks become easier.

The approach taken with Fourier analysis represents signals in terms of trigonometric functions and as such is particularly suited to situations where the signal is relatively smooth and is not of limited extent.

## Properties of naturally arising data

Much naturally arising data has been found to be better represented using wavelets which are better able to cope with discontinuities and where the signal is of local extent. Generally, the efficiency of the representation depends on the types of signal involved. If your signal contains

- discontinuities (in both the signal and its derivatives), or
- varying frequency behaviour

then wavelets are likely to represent the signal more efficiently than is possible with Fourier analysis.

#### Other classes of wavelets

One of the most useful features of wavelets is the ease with which a scientist can select the basis functions adapted for the given problem.

In fact, the Haar mother wavelet is perhaps the simplest of a very wide class of possible wavelet systems used in practice today.

Many applied fields have started to make use of wavelets including astronomy, acoustics, signal and image processing, neurophysiology, music, magnetic resonance imaging, speach discrimination, optics, fractals, turbulence, earthquake prediction, radar, human vision, etc. Suppose we have sampled N uniformly spaced function evaluations,  $f(0), f(1), \ldots, f(N-1)$ , say. The complex exponentials  $e^{i\mu n}$ , as functions of n, have period N if

$$e^{i\mu(n+N)} = e^{i\mu n}, \quad n = 0, \pm 1, \pm 2, \dots$$

So that,

$$e^{i\mu N} = 1$$

that is,  $\mu = k2\pi/N$ , for integer k.

Furthermore, when m is an integer

$$e^{i2\pi kn/N} = e^{i2\pi (k+mN)n/N}$$

so the parameters

$$\mu = \frac{k2\pi}{N}, \frac{(k\pm N)2\pi}{N}, \frac{(k\pm 2N)2\pi}{N}, \dots$$

all give the same function.

So there are just N distinct complex exponentials with period N, namely,

$$e^{ik2\pi/N}, \quad k = 0, 1, \dots, N-1.$$

Hence, we can write each f(n) as

$$f(n) = \sum_{k=0}^{N-1} F(k) e^{ik2\pi n/N} \quad n = 0, \pm 1, \pm 2, \dots$$

The corresponding expression for the coefficients F(k) turns out to be

$$F(k) = \frac{1}{N} \sum_{n=0}^{N-1} f(n) e^{-ik2\pi n/N} \quad k = 0, 1, \dots, N-1.$$

The quantities, F(k), are known as the *Discrete* Fourier Transform (DFT) of f.

### **Application to image compression**

The basic steps of the JPEG compression algorithm can be summarized as follows.

Take blocks of  $8 \times 8$  pixels (each pixel is encoded as 24 bits) and then use a discrete Fourier transform (in fact, the related discrete cosine transform is used) to produce  $8 \times 8 = 64$  separate frequency coefficients, per block.

Next use quantization factors (involving 64 tunable parameters) to compress each frequency coefficient block by block.

Store the resulting (integer) values with runlength encoding, etc.

This is a lossy form of compression but the idea is that when we invert the transformation and re-assemble the image the eye is not sensitive to the losses.

## **FBI** fingerprint database

Each of the FBI's fingerprint cards when digitized amounts to about 10Mb of data. They have 200 million such cards!

These cards must be both stored as well as transmitted so compression is very important.

A wavelet-based approach called *Wavelet Scalar Quantization* compression was developed by Los Alamos Labs and NIST in the US.

Reference

http://www.c3.lanl.gov/~brislawn/FBI/FBI.html