

EmotionSense: Designing a Mobile Sensing System for Social Psychology Research



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Joint work with Kiran K. Rachuri, Cecilia Mascolo,
Jason Peter Rentfrow, Chris Longworth and Andrius Aucinas

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Motivation

- Long-standing questions about *emotional states* in social psychology: influence of the environment, location, interactions, etc.
- Classic methods of investigation:
 - Self-reports
 - Lab-based studies
 - Wearable devices



EmotionSense

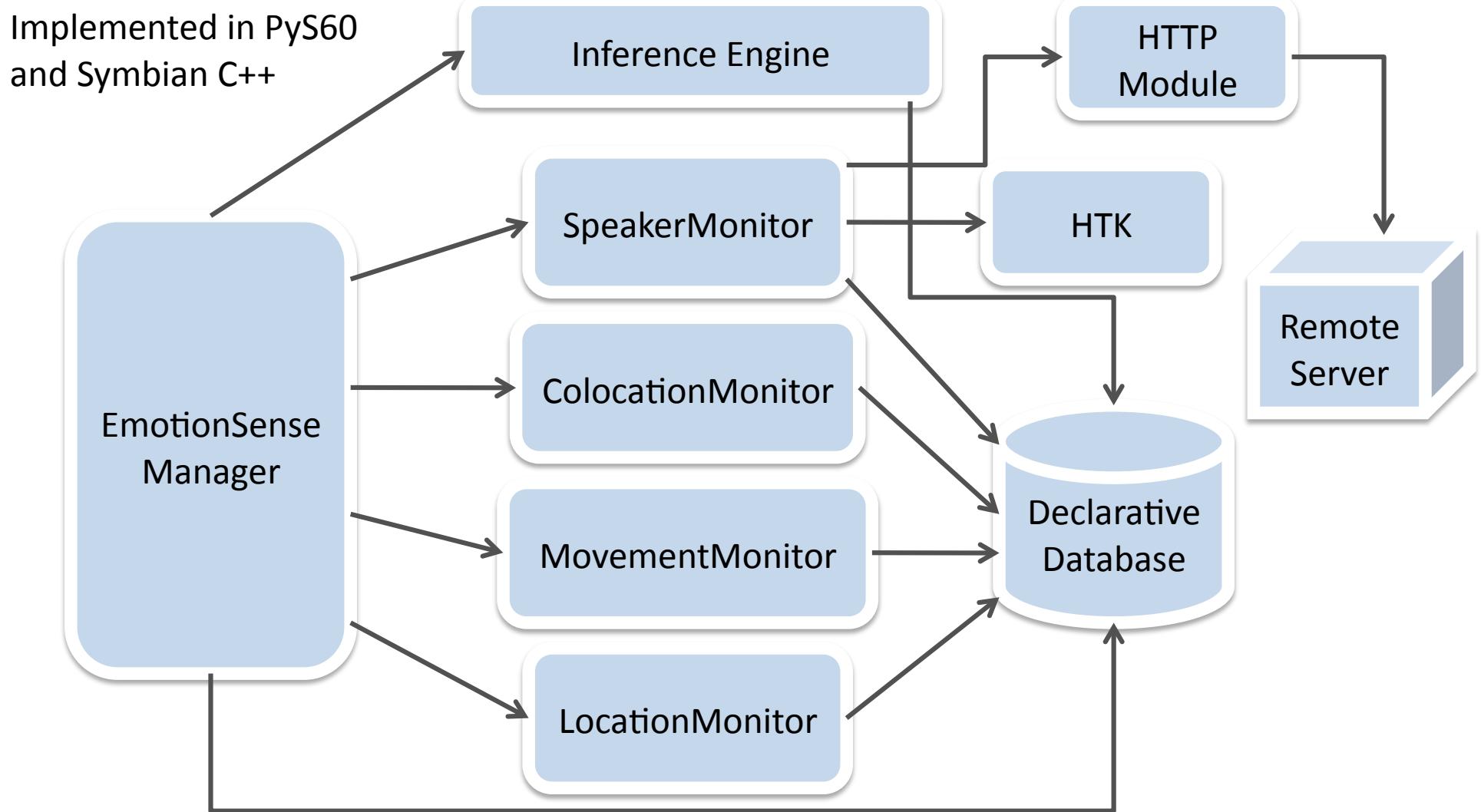


- *Unobtrusive* mobile platform for experimental social psychology
- Automatic inference of:
 - Interactions (proximity and speech dynamics)
 - Speaker recognition
 - Emotion recognition

[Kiran K. Rachuri, Mirco Musolesi, Cecilia Mascolo, Jason Peter Rentfrow, Chris Longworth and Andrius Aucinas. EmotionSense: A Mobile Phones based Adaptive Platform for Experimental Social Psychology Research. In *Proceedings of 12th ACM International Conference on Ubiquitous Computing (UbiComp'10)*. Copenhagen, Denmark. September 2010]

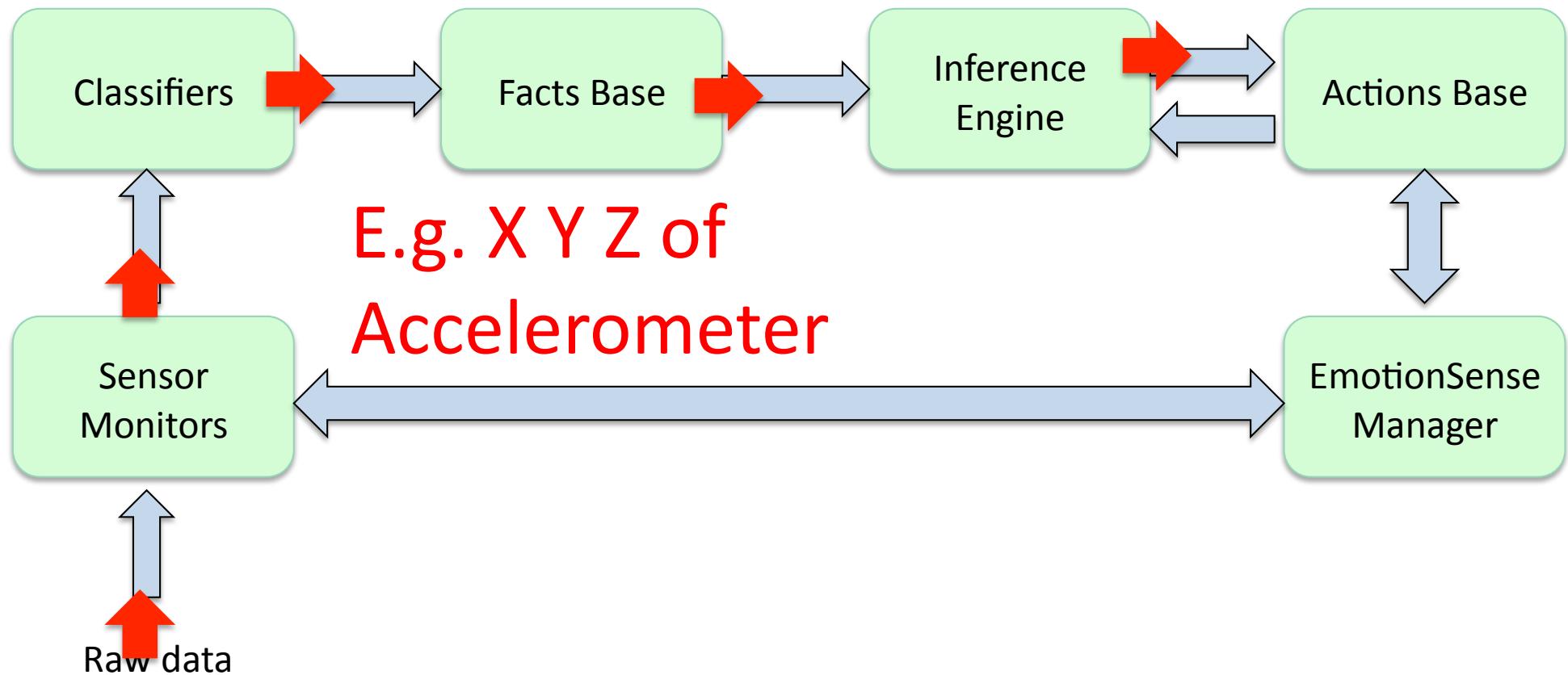
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EmotionSense - Architecture



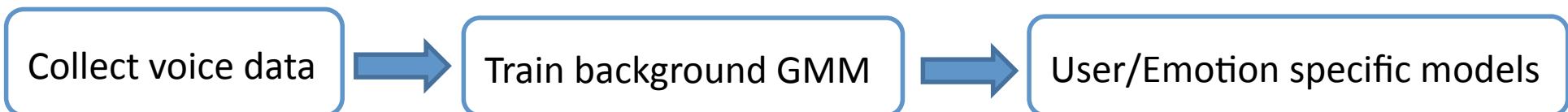
EmotionSense – Flow of Data

E.g. fact(*activity*, *location*, *SamplingInterval*, 2)
E.g. fact(*Moving*, *True*)



Emotion & Speech Recognition

Training Procedure



At Runtime **Speaker Recognition**: Participants voice data
Emotion Recognition: from library



GMM: Gaussian Mixture Model

PLP: Perceptual Liner Prediction

Hcopy, HERest: Tools of Hidden markov ToolKit (HTK)

[1] <http://htk.eng.cam.ac.uk>

[2] M. Liberman, K. Davis, M. Grossman, N. Martey, and J. Bell.
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Emotional prosody speech and transcripts, 2002.

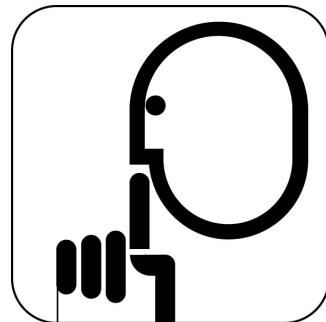
Emotion Categories

- Clustering of emotions **Why?**
(a) Used by psychologists (b) Improves accuracy

Broad Emotion	Narrow Emotion
Happy	Elation, Interest, Happy
Sad	Sadness
Fear	Panic
Anger	Disgust, Dominant, Hot anger
Neutral	Neutral normal, Neutral conversation, Neutral distant, Neutral tete, Boredom, Passive

Speaker Recognition - Optimisations

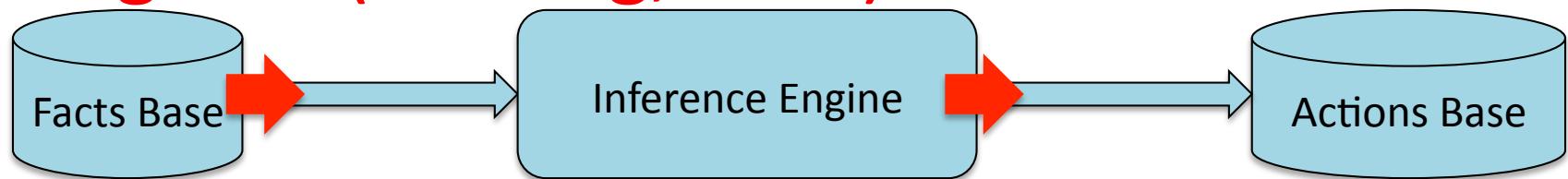
- Silence detection
 - train an additional GMM using silence audio
- Comparisons driven by co-location information
 - A recorded audio sequence is compared only with co-located users
 - This improves speaker recognition accuracy and saves energy





Adaptation Framework

E.g. fact(MovEng, fact(action, GPS, ON))

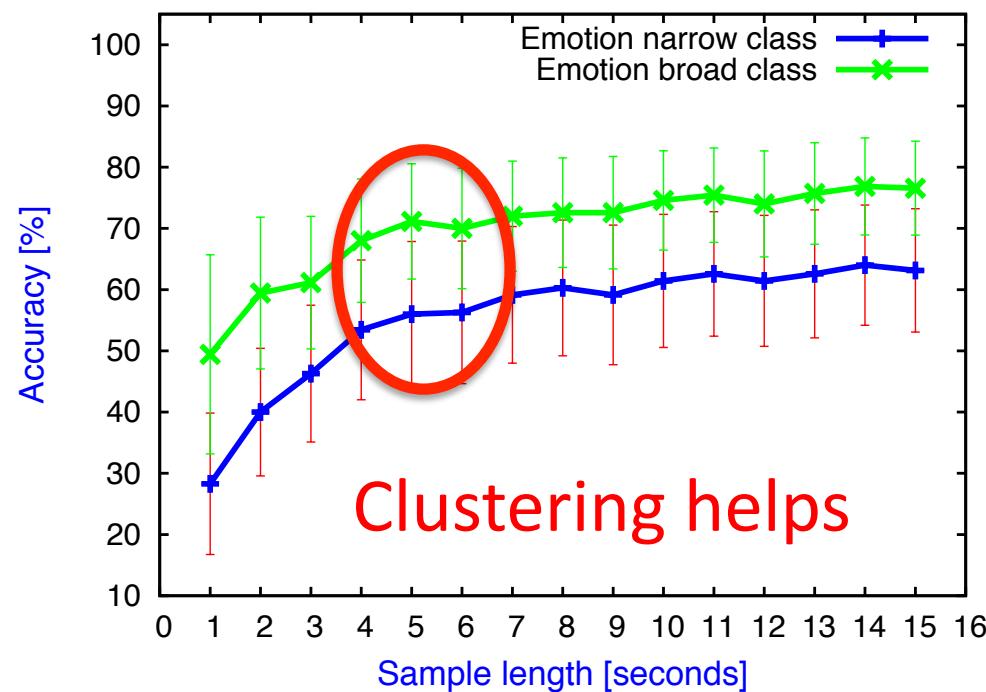


- Implemented using Pyke, a knowledge based inference engine
[<http://pyke.sourceforge.net/>]

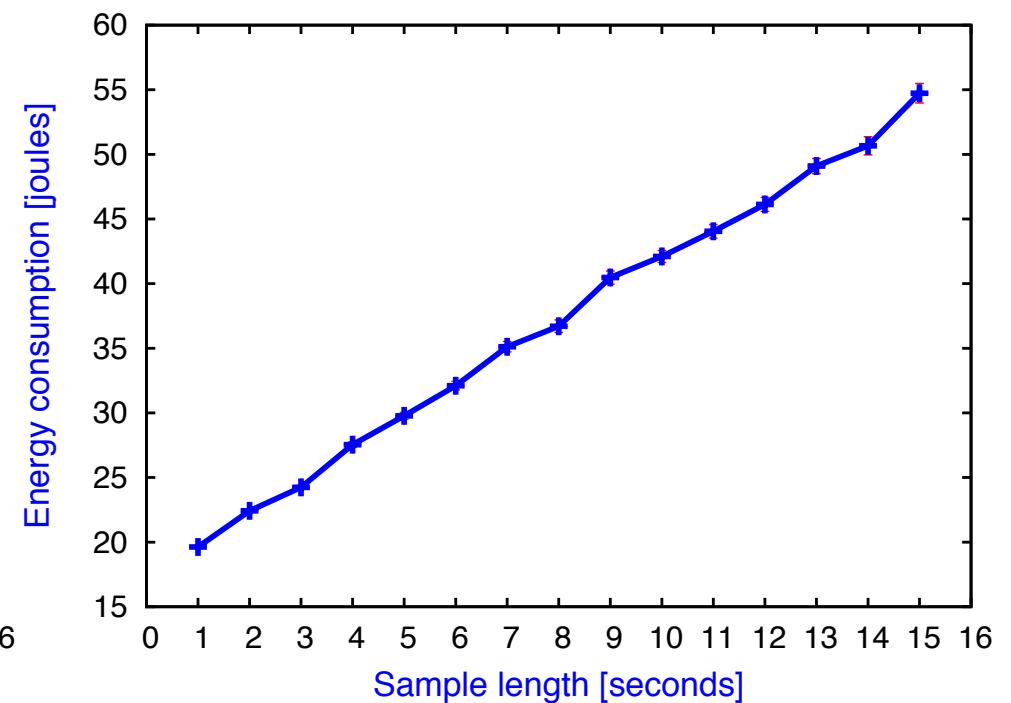
Activate GPS only when user is moving

```
set_location_sampling_interval
foreach
    facts.fact($factName, $value)
    check $factName == 'Activity'
    facts.fact($actionName, $currentInterval)
    check $actionName == 'LocationInterval'
    $interval = update($value, $currentInterval)
assert
    facts.fact('action', 'LocationInterval', $interval)
```

Emotion Recognition - Benchmarks



Accuracy



Energy consumption

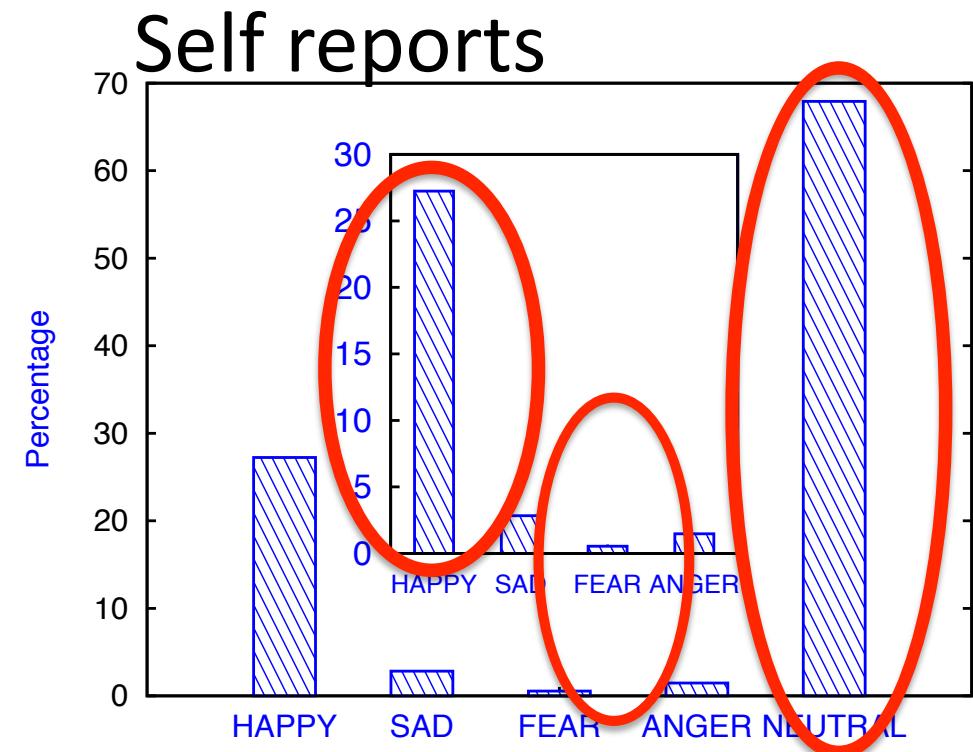
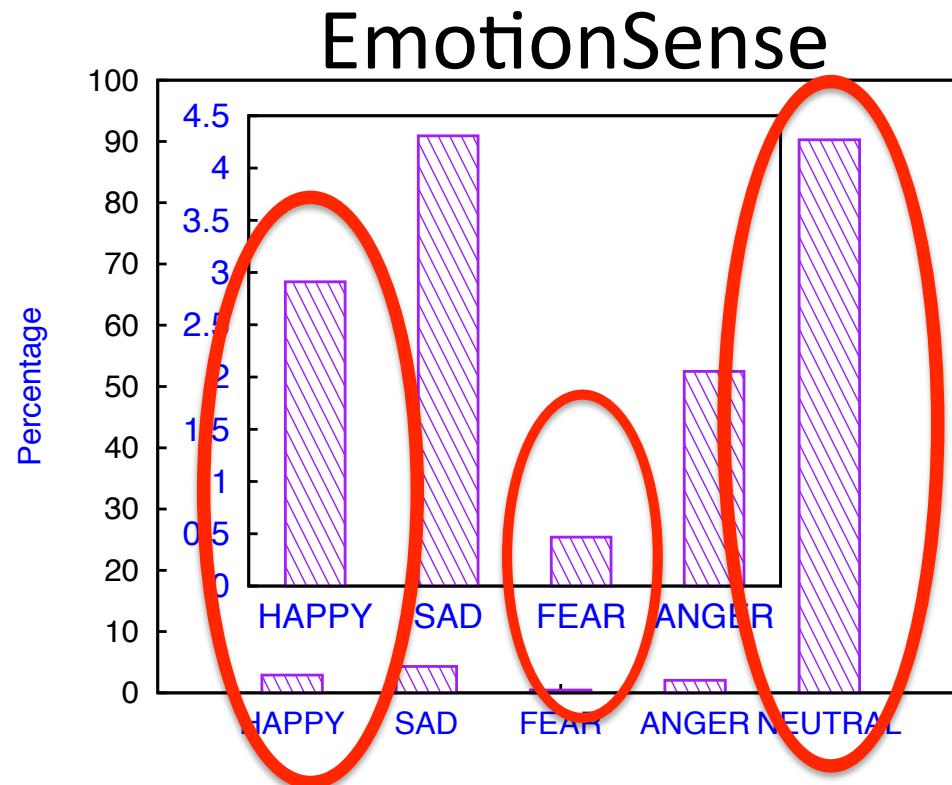
Social Psychology Experiment

- Nokia 6210 Navigator mobile phones
- 18 participants, 10 days
- Users filled in daily diary questionnaire
- Voice data is discarded immediately
- All computation performed locally on phone



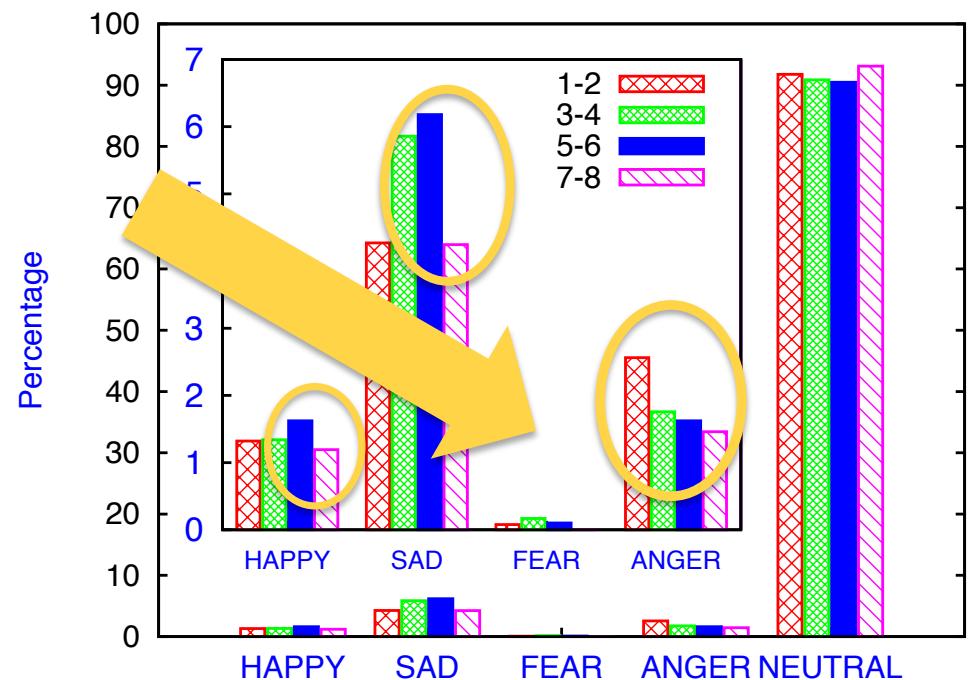
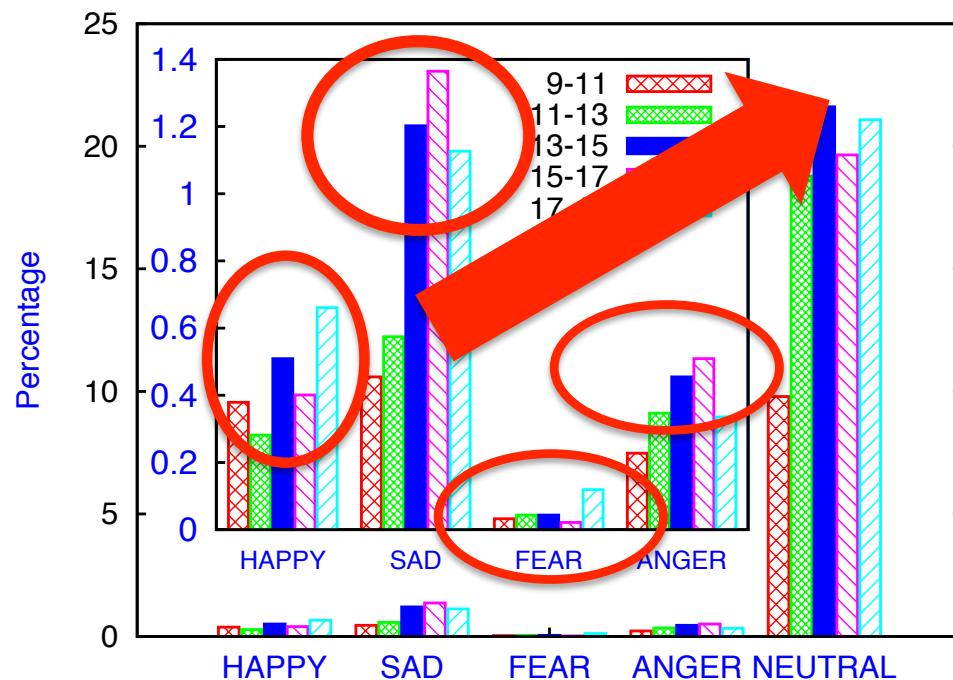
Social Psychology Experiment - Results

Emotion distribution similarity



Users indicated "happy" emotion to represent their mental state, and not necessarily verbal expression

Social Psychology Experiment - Results



Correlation with time of day and co-location

Questions?

EmotionSense Project webpage:

<http://www.cl.cam.ac.uk/research/srg/netos/emotionsense/>



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