Revisiting the calculation of effective free distance of turbo codes

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The expression for the minimum Hamming weight of the output of a constituent convolutional encoder, when its input is a weight-2 sequence is revisited. The new expression particularly facilitates the calculation of the effective free distance of recently proposed schemes, namely non-systematic turbo codes and pseudo-randomly punctured turbo codes.

Introduction: Several authors [1, 2] have agreed that the performance of turbo codes [3] at the error floor region is largely determined by the weight-2 input minimum distance, which corresponds to the minimum Hamming weight among all codeword sequences generated by input sequences of weight two. If a turbo code T consists of N parallel concatenated convolutional codes separated by uniform interleavers, its weight-2 input minimum distance d_2^T, which is also referred to as the *effective free distance* of T, can be written as [4, 5]

$$d_2^T = \sum_{k=1}^{N} d_2^{(k)} \qquad (1)$$

where $d_2^{(k)}$ is the weight-2 input minimum distance of the kth constituent code.

Bounds on the weight-2 input minimum distance d_2 of a convolutional code as well as exact expressions are provided in [1, 4, 6]. Nevertheless, the exact expressions are accurate only when either the impulse response of the code is known [6] or the structure of the code meets particular criteria [1, 4]. Recently, Banerjee *et al.* [5] demonstrated that non-systematic turbo codes using quick-look-in (QLI) convolutional codes as constituent codes, can achieve lower error floors than those of conventional systematic turbo codes. Unfortunately QLI codes do not always meet the conditions of [1, 4], hence the corresponding expressions cannot be used to determine their weight-2 input minimum distances. In this Letter we relax the conditions of [1, 4] and present expressions which allow the accurate calculation of d_2 for a wider set of convolutional codes.

Preliminaries: Let $(r, 1, \nu)$ represent a rate-$1/r$ convolutional code of memory ν and $\mathbf{G}(D) = [\mathbf{P}^{(1)}(D)/\mathbf{Q}(D), \ldots, \mathbf{P}^{(r)}(D)/\mathbf{Q}(D)]$ be the generator matrix of the recursive encoder for that code, where $\mathbf{P}^{(i)}(D) = p_\nu^{(i)} D^\nu + \ldots + p_1^{(i)} D + p_0^{(i)}$ denotes the ith feed-forward generator polynomial and $\mathbf{Q}(D) = q_\nu D^\nu + \ldots + q_1 D + q_0$ corresponds to the feedback generator polynomial, with coefficients $p_j^{(i)}, q_j \in \{0,1\}$. Note that none of the feed-forward polynomials is equal to $\mathbf{Q}(D)$, while $\mathbf{P}^{(1)}(D)/\mathbf{Q}(D) = 1$ only if the convolutional code is systematic.

It was shown in [1, 4] that the weight-2 input minimum distance of a $(r, 1, \nu)$ recursive convolutional code is given by $d_2 = r(2 + 2^{\nu-1})$ if the code is non-systematic and $d_2 = 2 + (r-1)(2 + 2^{\nu-1})$ if the code is systematic. In both cases, it has been assumed that $\mathbf{Q}(D)$ is a primitive polynomial of order $\nu \geq 2$, i.e. deg $\mathbf{Q}(D) = \nu$, while $\mathbf{P}^{(i)}(D)$ is a monic polynomial with constant term 1, i.e. $p_\nu^{(i)} = p_0^{(i)} = 1$. Consequently, deg $\mathbf{P}^{(i)}(D) =$ deg $\mathbf{Q}(D) = \nu$.

Calculation of d_2 when deg $\mathbf{P}^{(i)}$(D) $\leq$ deg $\mathbf{Q}$(D): As previously, we assume that $\mathbf{Q}(D)$ is a primitive polynomial of order $\nu \geq 2$, since it has been shown that turbo codes using primitive feedback generator polynomials yield an excellent performance [1]. Let $u(t)$ denote the input bit to the encoder at time step t and $r_m(t)$ represent the output of the mth memory element, where $m = 1, \ldots, \nu$. Initially, we focus on the ith non-systematic output of the encoder. The corresponding output bit $y^{(i)}$(t) can be expressed as follows

$$\begin{aligned} y^{(i)}(t) &= p_0^{(i)} u(t) \oplus (p_1^{(i)} \oplus q_1 p_0^{(i)}) r_1(t) \oplus \ldots \\ &\ldots \oplus (p_{\nu-1}^{(i)} \oplus q_{\nu-1} p_0^{(i)}) r_{\nu-1}(t) \oplus (p_\nu^{(i)} \oplus p_0^{(i)}) r_\nu(t) \end{aligned} \qquad (2)$$

where the symbol $\oplus$ denotes the mod-2 addition. We have also adopted the notation $d_{t_1 \to t_2}^{(i)}$ to represent the weight of the sequence generated by the i-th non-systematic output of the encoder during the transition from time step t_1 to time step t_2, i.e.

$$d_{t_1 \to t_2}^{(i)} = \sum_{t=t_1}^{t_2 - 1} y^{(i)}(t) \qquad (3)$$

If L is the period of the primitive feedback polynomial $\mathbf{Q}(D)$, the two nonzero bits of a weight-2 input sequence should be separated by $L-1$ zeroes such that the encoder returns to the zero state [7], i.e. $r_m(t) = 0$ for all m. Let $u(0) = u(L) = 1$, while $u(1) = \ldots = u(L-1) = 0$. Note that the weight-2 input minimum distance of the ith non-systematic output of the encoder is quantified by $d_{0 \to L+1}^{(i)}$. For convenience, we express $d_{0 \to L+1}^{(i)}$ as $d_{0 \to L+1}^{(i)} = d_{0 \to 1}^{(i)} + d_{1 \to L}^{(i)} + d_{L \to L+1}^{(i)}$ and compute each term separately:

- t: $0 \to 1$ – Assuming that the encoder was initialised to the zero state, we obtain $d_{0 \to 1}^{(i)} = y^{(i)}(0) = p_0^{(i)}$ from (2) and (3), since $u(0) = 1$ and $r_1(0) = \ldots = r_\nu(0) = 0$.
- t: $1 \to L$ – Let us first consider the case when t: $1 \to L+1$ and $u(L) = 0$. Owing to the properties of primitive polynomials, the output stream is a pseudo-noise sequence having weight $d_{1 \to L+1}^{(i)} = 2^{\nu-1}$, given that $\mathbf{P}^{(i)}(D) \neq \mathbf{Q}(D)$ [7]. Furthermore, when $t = L$, the encoder is in state 1 [7], i.e. $r_1(L) = \ldots = r_{\nu-1}(L) = 0$ and $r_\nu(L) = 1$. Hence, if $u(L) = 0$ is the input bit, the encoder outputs $y^{(i)}(L) = p_\nu^{(i)} \oplus p_0^{(i)}$, which is also the value of $d_{L \to L+1}^{(i)}$. However, an equivalent and more convenient form of the previous expression for the output weight is $d_{L \to L+1}^{(i)} = (p_\nu^{(i)} - p_0^{(i)})^2$. Consequently, we can compute the target quantity $d_{1 \to L}^{(i)}$ by subtracting $d_{L \to L+1}^{(i)}$ from $d_{1 \to L+1}^{(i)}$ and obtain $d_{1 \to L}^{(i)} = 2^{\nu-1} - (p_\nu^{(i)} - p_0^{(i)})^2$, independently of the value of $u(L)$.
- t: $L \to L+1$ – We established that if $t = L$ then $r_\nu(L) = 1$, while the output of the remaining memory elements is zero. That is when the second nonzero bit, namely $u(L) = 1$, of the weight-2 sequence is input to the encoder the bit forces the encoder to return to the zero state. Using (2) and (3), we find that $d_{L \to L+1}^{(i)} = y^{(i)}(L) = p_\nu^{(i)}$.

Thus, the weight of the ith non-systematic output sequence of the encoder for a weight-2 input sequence can be expressed as

$$\begin{aligned} d_{0 \to L+1}^{(i)} &= d_{0 \to 1}^{(i)} + d_{1 \to L}^{(i)} + d_{L \to L+1}^{(i)} \\ &= p_0^{(i)} + 2^{\nu-1} - (p_\nu^{(i)} - 2p_0^{(i)} p_\nu^{(i)} + p_0^{(i)}) + p_\nu^{(i)} \\ &= 2^{\nu-1} + 2p_0^{(i)} p_\nu^{(i)}, \end{aligned} \qquad (4)$$

using the fact that the value of a binary number, such as $p_j^{(i)}$, does not alter when it is raised to a power (e.g., $(p_j^{(i)})^2 = p_j^{(i)}$). The overall weight-2 input minimum distance of the rate-$1/r$ recursive convolutional encoder can be obtained as follows

$$d_2 = \sum_{i=1}^{r} d_{0 \to L+1}^{(i)} = \begin{cases} r2^{\nu-1} + 2\sum_{i=1}^{r} p_0^{(i)} p_\nu^{(i)}, & \text{if the code is non-systematic} \\ 2 + (r-1)2^{\nu-1} + 2\sum_{i=2}^{r} p_0^{(i)} p_\nu^{(i)}, & \text{if the code is systematic,} \end{cases} \qquad (5)$$

Extension to pseudorandomly punctured codes: Pseudorandom (PR) puncturing, initially introduced in [7], is a method to increase the rate of a constituent recursive systematic convolutional code with generator matrix $\mathbf{G}(D) = [1, \mathbf{P}(D)/\mathbf{Q}(D)]$ from $1/2$ to 1 by periodically eliminating particular bits from its output. Note that $\mathbf{Q}(D)$ should be primitive. It has been shown [8] that a rate-$1/2$ turbo code consisting of a rate-1 PR-punctured convolutional code and a rate-1 non-systematic convolutional code, yields a lower error floor than that of its rate-$1/3$ parent code. Following a similar reasoning as in the precoding section, we can express (the proof has been omitted) the weight-2 input minimum distance of a PR-punctured convolutional code $(1, 1, \nu)$ as

$$d_2 = 2^{\nu-2} + 2p_0 p_\nu. \qquad (6)$$

Conclusion: In this Letter we expressed the weight-2 input minimum distance of a rate-$1/r$ convolutional code as a function of the coefficients of its feed-forward generator polynomials $\mathbf{P}^{(i)}(D)$, with $i = 1, \ldots, r$, for a primitive feedback generator polynomial $\mathbf{Q}(D)$. This expression can be used to accurately compute the effective free distance of both conventional systematic turbo codes as well as non-systematic turbo codes [5, 8] that consist of convolutional codes with deg $\mathbf{P}^{(i)}(D) \leq$ deg $\mathbf{Q}(D)$.

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